# The effect of rotation on rapidly sheared homogeneous turbulence and passive scalar transport. Linear theory and DNS 

By G. BRETHOUWER<br>Department of Mechanics, KTH, SE-100 44 Stockholm, Sweden<br>geert@mech.kth.se

(Received ?? and in revised form ??)
The effect of rotation on a homogeneous turbulent shear flow has been studied by means of a series of direct numerical simulations with different rotation numbers. The evolution of passive scalar fields with mean gradients in each of the three orthogonal directions in the flow was investigated in order to elucidate the effect of rotation on turbulent scalar transport. Conditions of the near-wall region of a boundary layer were approached by using a rapid shear and therefore, comparisons could be made with with rapid distortion theory based on the linearized equations of the flow and scalar transport. Reynolds stresses, pressure-strain correlations and two-point velocity correlations were computed and turbulent structures were visualized. It is shown that rotation has a strong influence on the time development of the turbulent kinetic energy, the anisotropy of the flow and on the turbulent structures. Furthermore, rotation significantly affects turbulent scalar transport. The transport rate of the scalar and the direction of the scalar flux vector show large variations with different rotation numbers and a strong alignment was observed between the scalar flux and the principal axes of the Reynolds stress tensor. The ratio of the turbulent and scalar time scales is influenced by rotation as well. The predictions of the linear theory of the turbulent one-point statistics and the scalar flux agreed fairly well with DNS results based on the full non-linear governing equations. Nonetheless, some clear and strong non-linear effects are observed in a couple of cases which significantly influence the development of the turbulence and scalar transport.

## 1. Introduction

Flows of gases and liquids often take place in a rotating system. The so-called Coriolis force in this rotating system acts on the fluid and this gives rise to complicated but interesting phenomena. Flow patterns can alter due to the influence of rotation and also the turbulent characteristics change if there is rotation, which is proven by several experimental and numerical studies (see Bech \& Anderson 1997 and references therein). It is more than likely that the alteration of the turbulence by rotation in its turn will affect the transport and dispersion of scalars, for example pollutants, heat and reacting species. For practical situations it is of considerable importance to know how rotation affects turbulent flows and how rotation affects transport and dispersion of scalars in turbulent flows.

In recent years the modelling of rotating turbulent flows or flows with streamline curvature received considerable attention, see for instance the studies of Speziale, Younis \& Berger (2000), Poroseva et al. (2002), Wallin \& Johansson (2002) and Gatski \& Wallin
(2004), but an accurate description of rotational effects remains even nowadays a difficult subject.

Salhi \& Cambon (1997) and Salhi (2002) studied the most basic case with both shear and rotation, namely homogeneous turbulent shear flow in a rotating frame. They used linear rapid distortion theory (RDT) to investigate the influence of the rotation on the development of the flow. Assuming a linear shear flow with shear rate $S$, and a rotation around the spanwise axis, with angular velocity $\Omega$, Salhi \& Cambon showed that maximum destabilization of the flow occurs at $R=2 \Omega / S=-1 / 2$. (For convenience we take $U_{i}=S x_{3} \delta_{i 1}$ as we do later in the article.) Moreover, they analysed the influence of pressure on the turbulence development and compared the results of RDT with large-eddy simulation (LES) of rotating homogeneous shear flow performed by Bardina, Ferziger \& Reynolds (1983) and found a reasonable agreement. In contrast to a pressure-less analysis, RDT reveals a difference between the cases $R$ and $-1-R$ regarding the growth of the kinetic energy. Salhi (2002) presents analytical solutions for the RDT equations and some statistical quantities.

Lee, Kim \& Moin (1990) studied homogeneous turbulent shear flow with a high shear rate but without rotation through direct numerical simulations (DNS). The value of the non-dimensional shear number $S K / \varepsilon$, where $K$ is the turbulent kinetic energy and $\varepsilon$ is the energy dissipation, was approximately 17 in their simulations. This is of the same order as the value of the non-dimensional shear number in the buffer region of a turbulent boundary layer. Lee et al. observed in the rapidly sheared homogeneous flow streaky turbulent structures, similar to the structures found in turbulent boundary layers and concluded that a high shear rate is the most important requirement for the generation of turbulent streaks and not the presence of a wall. In their study the RDT predictions of the anisotropy of the Reynolds stresses agreed well with the DNS data at these high shear rates. RDT was also able to describe the development of the turbulent structures, showing the importance of linear effects for the dynamics of rapidly sheared homogeneous turbulent flows.

Passive scalar transport in non-rotating shear flows received considerable attention during the last decades. Tavoularis \& Corrsin (1981) and Rogers, Mansour \& Reynolds (1989) investigated passive scalar mixing with a uniform mean scalar gradient in homogeneous turbulent shear flow. In the case of a scalar field with a mean gradient in the transverse direction, they observed a much larger scalar flux in the flow direction than in the transverse direction leading to a strong misalignment between the scalar flux vector and the mean scalar gradient. Consequently, gradient-diffusion models are not the most appropriate models to describe the turbulent scalar flux in homogeneous shear flow because they assume alignment between the scalar flux and the mean gradient. An alternative modelling approach, algebraic scalar flux modelling, has in the case of homogeneous and other turbulent shear flows considerable more success in predicting the correct scalar flux (Rogers et al., 1989; Abe et al., 1996; Wikström, Wallin \& Johansson, 2000; Högström et al., 2001).

Detailed studies of scalar transport in rotating shear flows are, nevertheless, rare. Recently, Nagano \& Hattori (2003) and Wu \& Kasagi (2004) studied through DNS scalar transport in a rotating turbulent channel flow at a low Reynolds number. The correlation between the wall-normal velocity fluctuations and scalar fluctuations changes with varying rotation numbers according to this study. Further detailed investigations of the influence of rotation on turbulent scalar transport are lacking.

In this paper a study is presented of homogeneous turbulent shear flow with a passive scalar field in a rotating frame at different rotation numbers. Direct numerical simulations (DNS) and linear theory are used in this investigation. A linear and steady mean scalar


Figure 1. Sketch of the mean velocity profile, coordinate system and the direction of rotation.
gradient is imposed and high shear rates are used with the aim of approximating the conditions in a turbulent boundary close to the wall. The main objective of the study is to clarify the following points: How are the development of turbulence and, in particular, the anisotropy and the turbulent structures affected by rotation? What is the influence of rotation on turbulent scalar transport? To find an answer to these questions results on scalar fluctuations, scalar-velocity correlations and scalar dissipation will be presented. Furthermore, how important are linear processes for the development of turbulence and for scalar mixing in a rapidly sheared turbulent flow and can a linear model explain the influence of rotation on turbulence and scalar mixing? To investigate these aspects detailed comparisons between linear theory and the DNS data will be made.

## 2. Geometry and governing equations

The governing equations of the incompressible homogeneous turbulent shear flow in a rotating frame are

$$
\begin{gather*}
\boldsymbol{\nabla} \cdot \boldsymbol{u}=0  \tag{2.1}\\
\frac{\partial \boldsymbol{u}}{\partial t}+\boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u}+S x_{3} \frac{\partial \boldsymbol{u}}{\partial x_{1}}+S u_{3} \boldsymbol{e}_{1}+2 \boldsymbol{\Omega} \times \boldsymbol{u}=-\nabla p+\nu \nabla^{2} \boldsymbol{u} \tag{2.2}
\end{gather*}
$$

where $\boldsymbol{u}$ is the fluctuating velocity, $\boldsymbol{\nabla} p$ is the sum of the pressure gradient and the centrifugal force, both divided by the fluid density, $\nu$ is the viscosity, $S=\partial \bar{U}_{1} / \partial x_{3}$ is the imposed linear mean velocity gradient, $\boldsymbol{\Omega}$ is the rotation vector and $\boldsymbol{e}_{i}$ is the unit vector in the $x_{i}$-direction. The last term on the left hand side of the equation represents the Coriolis force. In the present case the frame is rotating around the spanwise axis and thus $\Omega=\Omega e_{2}$ with $\Omega$ the angular velocity of the frame. The mean velocity profile, coordinate system and direction of rotation are sketched in figure 1.

Using these equations we can derive the Reynolds stress evolution equations

$$
\begin{gather*}
\frac{\partial{\bar{u} u_{1}}^{\partial t}=-2 \bar{u}_{1} u_{3} S(1+R)+\Pi_{11}-\varepsilon_{11}}{\frac{\partial \bar{u}_{2} u_{2}}{\partial t}=\Pi_{22}-\varepsilon_{22}}  \tag{2.3}\\
\frac{\partial \bar{u}_{3} u_{3}}{\partial t}=2{\overline{u_{1} u_{3}} S R+\Pi_{33}-\varepsilon_{33}}_{\partial \bar{u}_{1} u_{3}}^{\partial t}=\bar{u}_{1} u_{1} S R-\bar{u}_{3} u_{3} S(1+R)+\Pi_{13}-\varepsilon_{13} \tag{2.4}
\end{gather*}
$$

where $\Pi_{i j}$ and $\varepsilon_{i j}$ denote the usual pressure-strain correlation and dissipation rate, respectively, and $R=2 \Omega / S$. The pressure-strain correlation redistributes the energy between the different fluctuating velocity components and can be split into a slow part, related to non-linear processes, and a rapid part, related to the large-scale distortion of the flow. The Poisson equation for the rapid and slow part of the pressure, respectively satisfy in our case

$$
\begin{align*}
\nabla^{2} p^{(r)}= & (-2 S-2 \Omega) \frac{\partial u_{3}}{\partial x_{1}}+2 \Omega \frac{\partial u_{1}}{\partial x_{3}}  \tag{2.7}\\
& \nabla^{2} p^{(s)}=-\frac{\partial u_{i}}{\partial x_{j}} \frac{\partial u_{j}}{\partial x_{i}} \tag{2.8}
\end{align*}
$$

In Appendix A the stability of rotating homogeneous shear flow is analysed using the Reynolds stress equations without the pressure-strain correlations and dissipation terms. This is a drastic simplification but nevertheless, the analysis gives a reasonable qualitative picture of the stability as a function of the rotation number. The conclusions of the analysis is that $(i)$ the turbulent kinetic energy grows algebraically if $R=0$ or $R=-1$, (ii) the flow is destabilized by rotation if $-1<R<0$ with an exponentially growing kinetic energy and with at maximum destabilization at $R=-1 / 2$, (iii) the Reynolds stresses have an oscillating behaviour and the turbulence is stabilized by rotation if $R<-1$ or $R>0$.

Using equation 2.2 we can derive for the fluctuating vorticity $\boldsymbol{\omega}$ the following equation

$$
\begin{equation*}
\frac{\partial \omega_{i}}{\partial t}+u_{k} \frac{\partial \omega_{i}}{\partial x_{k}}+S x_{3} \frac{\partial \omega_{i}}{\partial x_{1}}=\omega_{k} \frac{\partial u_{i}}{\partial x_{k}}+\nu \nabla^{2} \omega_{i}+S \omega_{3} \delta_{i 1}+S(1+R) \frac{\partial u_{i}}{\partial x_{2}} \tag{2.9}
\end{equation*}
$$

The second and third term on the left hand side of the equation are the advection by the fluctuating and mean velocity. The first term on the right hand side is the non-linear production of vorticity, the third and last term are the linear production of vorticity.

In the homogeneous turbulent shear flow we study the turbulent transport of a passive scalar with an imposed mean and linear scalar gradient $\boldsymbol{G}$. The transport equation for the fluctuation of the passive scalar $\theta$, which does not have an influence on the velocity field, is given by

$$
\begin{equation*}
\frac{\partial \theta}{\partial t}+\boldsymbol{u} \cdot \boldsymbol{\nabla} \theta+S x_{3} \frac{\partial \theta}{\partial x_{1}}+\boldsymbol{G} \cdot \boldsymbol{u}=\kappa \nabla^{2} \theta \tag{2.10}
\end{equation*}
$$

where $\kappa$ is the molecular diffusivity of the scalar. The last term on the left hand is a production term of scalar fluctuations. The effect of rotation does not directly enter the scalar equation, but scalar transport is nevertheless, affected by rotation because of the alteration of the velocity field by rotation. This can be noticed when the transport equation for the mean turbulent scalar flux is considered, which for the present rotating homogeneous shear flow reads

$$
\begin{equation*}
\frac{\partial \overline{u_{i} \theta}}{\partial t}=-\overline{u_{i} u_{j}} G_{j}-\overline{u_{3} \theta} S \delta_{i 1}+2 \epsilon_{i j 2} \overline{u_{j} \theta} \Omega+\Pi_{\theta i}-\varepsilon_{\theta i} \tag{2.11}
\end{equation*}
$$

Here, the first and second term on the right hand side are production terms due to mean gradients, $\Pi_{\theta i}$ the pressure-gradient correlation and $\varepsilon_{\theta i}$ the viscous and diffusive destruction term, see e.g. Wikström et al., 2000. The third term is a direct consequence of the rotation and affects in the present case the scalar flux in the streamwise and transverse directions. This is, however, not the only term influenced by rotation. Reynolds stresses and the pressure field are also affected by rotation, as we will see later, and therefore the first and fourth term on the right hand side can change as well.

## 3. Direct numerical simulations

The governing equations of the three-dimensional turbulent flow and scalar transport given by equations (2.2) and (2.10) respectively, are solved with a pseudo-spectral method with periodic boundary conditions on the computational domain. The aliasing errors are reduced by a combination of phase shifting and truncation. Only after $S t=10$ at $R=0$, series $B$, the aliasing errors were completely removed by employing the $2 / 3$ rule. A fourthorder or a low-storage third-order Runge-Kutta scheme is used for the time advancement of the non-linear terms and the linear viscous and diffusive terms are integrated exactly in Fourier wave-number space. In order to be able use periodic boundary conditions in all three directions, a coordinate transformation has been employed and consequently the numerical grid is moving with the mean flow field. To avoid too large deformations of the grid it is remeshed with regular time intervals at times $(m+1 / 2)\left(L_{x_{1}} / L_{x_{3}}\right) S^{-1} \quad(m=$ $0,1,2, \ldots$ ) where $L_{x_{i}}$ is the size of the domain in the $x_{i}$-direction. The same procedure has been used by Rogers et al. (1989). During the remeshing some information is lost, especially at high wave numbers, but this was in general quite small in the present simulations. The loss of kinetic energy was in fact negligible. The loss of energy dissipation was more serious but, for example, in the run without system rotation series $B$ the decrease of energy dissipation during remeshing was not larger than $1.5 \%$. Statistics were computed when the coordinate system was non-skewed.

The numerical code has been thoroughly validated by comparing it with an independently written code. The two codes produced essentially the same results for the velocity and scalar field and the small differences could be attributed to the different time integration methods used. Also one of the cases of Rogers, Moin \& Reynolds (1986), case $C 128 U$, has been repeated and the major results concerning velocity and scalar statistics could be reproduced.

The initial approximately isotropic velocity field for the present simulations has been obtained from a DNS of decaying isotropic turbulence and has a Taylor Reynolds number of $R e_{\lambda}=u^{\prime} \lambda / \nu=32$ where $u^{\prime}$ is the root mean square ( rms ) of the velocity fluctuations and $\lambda$ the Taylor length scale.

Five cases with different rotation numbers have been simulated: $R=2 \Omega / S=0$ (pure shear), $R=-1 / 2, R=-1$ (zero absolute mean vorticity), $R=-3 / 2$ and $R=1 / 2$. The numerical parameters used in the simulations are listed in table 1. Each case has been simulated twice (series $A$ and series $B$ ), with different number of grid points and domain sizes, in order to investigate if the results are significantly affected by the finite size of the domain, remeshing and resolution.

The conditions in a turbulent boundary layer close to the wall were approximated by choosing an appropriate shear rate. Figure $2(a)$ presents the non-dimensional shear number $S K / \varepsilon$ obtained from DNS data of turbulent channel flow at $R e_{\tau}=590$ (Moser et al., 1999) and a zero-pressure gradient turbulent boundary layer (Komminaho \& Skote 2002) as a function of the distance to the wall. According to these simulations $S K / \varepsilon$ has a high value in the buffer layer with a maximum value between 16 to 18 at about $y^{+}=10$. This is also approximately the position where the production rate of turbulent kinetic energy has its highest value as shown in figure $2(b)$. In order to approximate the conditions in the important part of the boundary layer where most of the kinetic energy is produced we have set the initial value of non-dimensional shear number $S K / \varepsilon$ in all simulations to 18. Note that this value is much larger than the asymptotic non-dimensional shear number in a homogeneous turbulent shear flow which is believed to be close to 6 (Tavoularis \& Karnik, 1989) and the equilibrium state will therefore not be reached in the present numerical simulations. Hence, it is natural that the non-dimensional shear number does

| $R=2 \Omega / S$ | $L_{x_{2}}$ | $S$ | $N_{1} \times N_{2} \times N_{3}$ | $\ell$ | $L$ | $k_{\max } \eta$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Series $A$ |  |  |  |  |  |  |
| 0 | $3.11 \pi$ | 51.8 | $576 \times 448 \times 288$ | 0.288 | 0.284 | 1.60 |
| $-1 / 2$ | $3.11 \pi$ | 51.8 | $576 \times 448 \times 288$ | 0.288 | 0.284 | 1.60 |
| -1 | $2.5 \pi$ | 47.46 | $512 \times 320 \times 256$ | 0.295 | 0.296 | 1.49 |
| $-3 / 2$ | $2.5 \pi$ | 47.46 | $512 \times 320 \times 256$ | 0.295 | 0.296 | 1.49 |
| $1 / 2$ | $3 \pi$ | 46.6 | $512 \times 384 \times 256$ | 0.298 | 0.299 | 1.50 |
| Series $B$ |  |  |  |  |  |  |
| 0 | $3 \pi$ | 75.5 | $768 \times 640 \times 512$ | 0.194 | 0.235 | 1.47 |
| $-1 / 2$ | $3 \pi$ | 75.5 | $768 \times 640 \times 512$ | 0.194 | 0.235 | 1.47 |
| -1 | $3 \pi$ | 75.5 | $640 \times 480 \times 384$ | 0.194 | 0.235 | 1.47 |
| $-3 / 2$ | $3 \pi$ | 94.2 | $576 \times 440 \times 352$ | 0.172 | 0.214 | 1.17 |
| $1 / 2$ | $3 \pi$ | 94.2 | $576 \times 440 \times 352$ | 0.172 | 0.214 | 1.17 |

Table 1. Overview of the numerical parameters that have been used. Only the size of the domain in the spanwise direction and $L_{x_{2}}$ has been varied. The size of the computational domain in the streamwise and transverse direction, equal to $4 \pi$ and $2 \pi$ respectively, has been kept constant in all simulations. $N_{i}$ is the number of nodes in the $x_{i}$-direction, $\ell$ is the longitudinal integral length scale and $L=u^{\prime 3} / \varepsilon$ of the initial isotropic velocity field, $k_{\text {max }} \eta$ is the largest resolved wave number times the Kolmogorov length scale at $t=0$.


Figure 2. (a) $S K / \varepsilon$ and (b) production of turbulent kinetic energy normalized with wall units as a function of the non-dimensional distance to the wall $y^{+}$in terms of wall units. Solid line: channel flow data (Moser et al., 1999); dashed line: boundary layer data (Komminaho \& Skote 2002).
not stay constant during the simulations but varies. At $R=0, R=-1 / 2$ and $R=-1$ the minimum value reached by $S K / \varepsilon$ up to the non-dimensional time $S t=8$, was 13 . After $S t=8, S K / \varepsilon$ decreased slightly to 11.8 at $R=0$. At $R=-3 / 2$ and $R=1 / 2$, $S K / \varepsilon$ reached lower values but stayed above 8.9.

In series $A$, transport equations for three passive scalars are solved together with the flow equations. The three scalars all have a Schmidt number of $\nu / \kappa=0.7$ and have a mean scalar gradient in the $x_{1}, x_{2}$ and $x_{3}$-direction, respectively. The evolution for any mean scalar gradient is a simple superposition of these three passive scalar fields. In series $B$, only the evolution of one scalar field with a mean gradient in the $x_{3}$-direction has been simulated. The initial scalar fields are without scalar fluctuations but the mean gradient acts as a source of fluctuations.

During the simulations the turbulent length scales grow and eventually become too
large for the finite domain we use in the DNS. In order to be sure that the DNS results are not depending on the size of the physical domain we have carefully followed the development of the two-point velocity correlations during the computations and stopped the simulations as soon as the correlations did not properly approach zero for increasing separation distances.

While the largest scales tend to grow, the Kolmogorov length scale $\eta$ becomes in general smaller during the simulations which makes higher demands on the grid spacing. In series $A, k_{\max } \eta$, were $k_{\max }$ is the largest resolved wave number, was always equal or larger than 1.0 during the simulations, except in the $R=-1 / 2$ case, series $A$, where $k_{\max } \eta=0.93$ at the end of the simulations at $S t=6$. To save computation time a coarser grid was used in series $B$ at $R=0$ and $R=-1 / 2$ initially, but in the last part of the simulations the resolution was increased to the values reported in table 1. During the simulations $k_{\max } \eta$ was, however, always smaller than one.

## 4. Linearized equations

If the shear or rotation rate is high enough, the Navier-Stokes equations and the transport equation of the scalar can be approximated by their linearized forms. The assumption of linearity is the main idea behind rapid distortion theory (RDT).

The necessary requirement for the applicability of RDT on the flow field in the present case is that in equation (2.2) the non-linear term is much smaller than either the linear term due to mean shear or the term due to rotation. Using a characteristic eddy size $l$ and eddy velocity $u$, the order of the non-linear term can be estimated as

$$
|\boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u}|=\mathcal{O}\left(u^{2} / l\right)
$$

and the linear mean shear and rotation term can be estimated as

$$
\left|S u_{3} \boldsymbol{e}_{1}\right|=\mathcal{O}(S u), \quad|2 \boldsymbol{\Omega} \times \boldsymbol{u}|=\mathcal{O}(\Omega u)
$$

respectively. The energy containing scales can be approximated by $u \simeq K^{1 / 2}$ and $l \simeq$ $K^{3 / 2} / \varepsilon$ and hence, the necessary condition for the applicability of RDT becomes either $S K / \varepsilon \gg 1$ or $\Omega K / \varepsilon \gg 1$. In other words, the time scale of the turbulence must be much larger than the time scale of shear or rotation and this condition is satisfied in all present simulations, at least for the large scales. We can thus expect a reasonable prediction of RDT of the large-scale turbulence characteristics such as the anisotropy. For the smaller turbulent scales the time scale is shorter and the applicability of RDT is questionable. Furthermore, we must stress that the condition $S K / \varepsilon \gg 1$ or $\Omega K / \varepsilon \gg 1$ is a necessary condition, but not always a sufficient condition, as we will notice later in this paper.

For the scalar the necessary condition for the applicability of RDT is that the second advection term in equation (2.10) is much smaller than the fourth term due to the mean scalar gradient. These terms can be estimated as

$$
|\boldsymbol{u} \cdot \boldsymbol{\nabla} \theta|=\mathcal{O}\left(u \theta^{\prime} / l\right)
$$

and

$$
|\boldsymbol{G} \cdot u|=\mathcal{O}(G u)
$$

respectively, where $\theta^{\prime}$ is the root mean square of the scalar fluctuations. The condition for RDT becomes then $\left(G K^{3 / 2}\right) /\left(\theta^{\prime} \varepsilon\right) \gg 1$. In section 5 we will observe that $\left(\theta^{\prime} / G\right) /(u / S)$ is $\mathcal{O}(1)$ or larger after short distortion times. Assuming that the ratio is $\mathcal{O}(1)$ the condition for the scalar becomes $S K / \varepsilon \gg 1$, which is in fact the same as for the flow field. In case $\left(\theta^{\prime} / G\right) /(u / S)$ is not $\mathcal{O}(1)$ but larger, the condition $S K / \varepsilon \gg 1$ is not necessarily
sufficient and the more severe demand $\left(G K^{3 / 2}\right) /\left(\theta^{\prime} \varepsilon\right) \gg 1$ applies. The condition for the applicability of RDT for scalar transport seems therefore more restrictive than for the flow field.

In case of homogeneous flows the governing equations for the flow and scalar field can be transformed to Fourier space with the definitions

$$
\begin{equation*}
u_{i}=\sum_{\boldsymbol{k}} \hat{u}_{i}(\boldsymbol{k}, t) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{x}} \quad(i=1,2,3) \tag{4.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\theta=\sum_{\boldsymbol{k}} \hat{\theta}(\boldsymbol{k}, t) \mathrm{e}^{\mathrm{i} \boldsymbol{k} \cdot \boldsymbol{x}} \tag{4.2}
\end{equation*}
$$

After the linearization, elimination of the pressure using the continuity equation and transformation to a coordinate system moving with the mean flow, the RDT equations for the homogeneous shear flow read

$$
\begin{equation*}
\left(\frac{\mathrm{d}}{\mathrm{~d} S t}+\nu \frac{k^{2}}{S}\right) \hat{u}_{i}=-\underbrace{\left[\left(\delta_{i 1}-2 \frac{k_{i} k_{1}}{k^{2}}\right) \delta_{j 3}-2 \frac{\Omega}{S}\left(\epsilon_{i j 2}-\frac{k_{i} k_{n}}{k^{2}} \epsilon_{n j 2}\right)\right]}_{\mathcal{L}_{i j}} \hat{u}_{j} \tag{4.3}
\end{equation*}
$$

and for the scalar fluctuation with a mean gradient

$$
\begin{equation*}
\left(\frac{\mathrm{d}}{\mathrm{~d} S t}+\kappa \frac{k^{2}}{S}\right) \hat{\theta}=-\frac{G_{i}}{S} \hat{u}_{i} \tag{4.4}
\end{equation*}
$$

where the time $t^{*}$ is scaled with the shear rate and $\epsilon_{i j k}$ is the permutation tensor. The wave numbers evolve according to

$$
\begin{equation*}
\frac{\mathrm{d} k_{i}}{\mathrm{~d} S t}=-k_{1} \delta_{i 3} \tag{4.5}
\end{equation*}
$$

The viscous and diffusive terms are not neglected in the present analysis, but have been taken into account in the RDT computations.

To compute the Reynolds stresses, scalar fluxes and other mean statistical moments the Fourier coefficients of the velocity and scalar have to be integrated in wave number space. However, in the present study the viscous and diffusive terms are retained and therefore, an initial turbulent energy spectrum has to be specified. For the scalar field no initial spectrum has to be specified because the fluctuations are initially zero, similar to the initial conditions of the DNS. The following form is assumed for the initial energy spectrum

$$
\begin{equation*}
E\left(k^{\prime}\right)=C k^{2} \exp \left(-2 k^{\prime} l\right) \tag{4.6}
\end{equation*}
$$

where $C$ is a constant and $l$ some characteristic turbulent length scale. The shape of this spectrum agrees fairly well with the DNS data, but it has been observed that the anisotropy of the flow and other statistics are not critically dependent on the exact form of the initial energy spectrum.

Using the spectrum defined by (4.6) it can be shown that the initial non-dimensional shear number is $S K / \varepsilon=\frac{1}{6} S^{*}$ where $S^{*}=S l^{2} / \nu$. The evolution of the flow and scalar field according to the RDT equations is completely determined through the choice of $S^{*}$ and the rotation number $R$. Here $S^{*}=108$ is taken which implies $S K / \varepsilon=18$ and hence, the initial value of the non-dimensional shear number in the DNS and the RDT computations are the same. After the specification of the energy spectrum, $S^{*}$ and $R$ the Fourier coefficients of the velocity and the scalar can be integrated in time and the development of the Reynolds stresses, pressure-strain correlations, scalar fluxes and scalar


Figure 3. Time development of the turbulent kinetic energy $K$ according to DNS (symbols) and RDT (lines). The time $t$ is made non-dimensional with the shear rate $S$ and $K$ is scaled with its initial value. $(\nabla,-\cdots-\cdots-), R=1 / 2$; $(\square,-\longrightarrow), R=0 ;(\mathrm{O},---), R=-1 / 2$; $(\triangle, \cdots), R=-1 ;(\diamond,-\cdots \cdot-), R=-3 / 2$. The gray filled symbols are DNS results from series $A$ and the white filled from series $B$. Sometimes they are not distinguishable because the symbols overlap each other.
variances can be calculated. More details of the computational procedure are given in Appendix B.

For $S c \neq 1$ the computation of the scalar variance and scalar flux becomes complicated. Rogers et al. $(1986,1989)$ observed a rather small difference between turbulent scalar transport at $S c=0.7$ and $S c=1$ in their DNS of homogeneous shear flow and therefore we take $S c=1$ in the RDT computations instead of the value $S c=0.7$ which is used in the DNS.

## 5. Results of the DNS and RDT

In this section the results of the DNS and the predictions of RDT are presented. The flow field is first analysed. One-point statistics and the anisotropy of the turbulence are considered and the turbulent structures are studied by means of two-point velocity correlations and visualizations. Then the turbulent transport of the scalars and the mixing time scales are investigated.

### 5.1. Flow field

### 5.1.1. Development of the turbulent kinetic energy and anisotropy

The time development of the turbulent kinetic energy for the five different rotation numbers is presented in figure 3. RDT predictions and DNS results from series $A$ and series $B$, which give similar results, are displayed in the figure. Both DNS and RDT show a strong influence of rotation on the stability of the flow. In figure 4 only the DNS results of series $B$ at $R=0,-1 / 2$ and -1 are plotted together with exponential and linear fits. The case $R=-1 / 2$ is the most unstable case, in agreement with previous findings (Salhi


Figure 4. Time development of the turbulent kinetic energy $K$ according DNS, series $B .-$ (thick line) $R=0 ;---, R=-1 / 2 ; \cdots, R=-1$. The thin solid lines are fitted exponential functions at $R=0(\exp (0.178 S t))$ and $R=-1 / 2(\exp (0.56 S t))$ and a linear fit at $R=-1$.
\& Cambon, 1997) and the analysis presented in Appendix A. The kinetic energy has a very fast exponential growth according to figure 4 at larger $S t$ values. An exponential growth of the kinetic energy is also observed in the DNS results at $R=0$ at larger $S t$ values, but the RDT results do not show this behaviour. Consequently, there is a quite large discrepancy between the DNS and RDT results for $S t>6$ which also, but to a lesser extent, can be observed at $R=-1$ for $S t>8$. In the other cases there is a reasonable to good correspondence between DNS and RDT. At $R=-1$ the kinetic energy is growing approximately linearly according the DNS as can be seen in figure 4. Bardina et al. (1983) observed in their LES for $R=-1$ an approximately constant kinetic energy and this difference is likely to be a consequence of the lower non-dimensional shear number used in their study. In the other two cases, $R=-3 / 2$ and $R=1 / 2$, the kinetic energy first increases very slightly but then decreases slowly according to DNS and RDT which implies a stabilizing influence of rotation on the turbulence (Salhi 2002). We observe also in figure 3 a clear difference between the cases $R$ and $-1-R$, i.e. between $R=0$ and $R=-1$ and between $R=1 / 2$ and $R=-3 / 2$ caused by the influence of the pressure, confirming the analysis of Salhi \& Cambon (1997).

The next point of attention is the anisotropy of the turbulence. Figure 5 shows the development of the streamwise velocity fluctuation in terms of the Reynolds stress anisotropy component $b_{13}$ where $b_{i j}=\overline{u_{i} u_{j}} /(2 K)-\delta_{i j} / 3$. At $R=-1 / 2, b_{13}$ reaches very large negative values implying a strong correlation between the streamwise and transverse velocity fluctuations. The velocity cross-correlation $\overline{u_{1} u_{3}} / u_{1}^{\prime} u_{3}^{\prime}$ is as large as -0.86 at $S t=6 \mathrm{ac}-$ cording to the DNS. At $R=0$ and $R=-1, b_{13}$ at first sharply decreases but then increases again and it becomes approximately constant at larger $S t$ values. The DNS corresponds well to the RDT predictions till $S t=4$ at $R=0$, but thereafter $b_{13}$ is significantly larger negative in the DNS. The pressure-less analysis presented in appendix A predicts oscillations of $\bar{u}_{1} u_{3}$ with a period of 3.6 at $R=-3 / 2$ and $R=1 / 2$ and this behaviour can also be observed in the DNS and RDT results. Moreover, $b_{13}$ becomes positive according to RDT and DNS implying an energy transfer from the turbulence to the mean flow.

The figures 6,7 and 8 show the development of $b_{11}, b_{22}$ and $b_{33}$, respectively. In the pure shear case $R=0$ the production term of $\bar{u}_{1} u_{1}$ is positive and there is no production of


Figure 5. Time development of the Reynolds stress anisotropy component $b_{13}$. Symbols and lines as in figure 3.


Figure 6. Time development of the Reynolds stress anisotropy component $b_{11}$. Symbols and lines as in figure 3.
$\bar{u}_{3} u_{3}$. At $R=-1 / 2$, however, both Reynolds stresses have a positive production term due to rotation and at $R=-1$, only ${\overline{u_{3}} u_{3} \text { has a production term as can be seen in equations }}_{\text {a }}$ (2.3) and (2.5). In accordance with this, at $R=0$ the streamwise velocity fluctuations are large and $b_{11}$ is positive, but at $R=-1 / 2, b_{11}$ and $b_{33}$ are approximately equal and at $R=-1, b_{33}$ is positive and $b_{11}$ negative signifying strong transverse and weak streamwise velocity fluctuations. RDT shows at $R=0$ a monotic increase and decrease of $b_{11}$ and $b_{33}$, respectively, but in the DNS the non-linear effects are strong enough to reduce the anisotropy at larger $S t$ values as we see in figure 6 and 8 leading to significant differences with the RDT predictions. The anisotropy of the turbulence, however, is still much larger than in a homogeneous shear flow at the equilibrium state (Tavoularis \& Corrsin 1981). At $R=1 / 2$ and $R=-3 / 2, b_{11}$ and $b_{33}$ follow initially the same trend as at $R=0$ and $R=-1$, respectively, but then start to oscillate with a decaying amplitude.

The spanwise velocity fluctuations are only influenced by rotation through the pressurestrain correlation and the dissipation term according to equation (2.4). Weak oscillations of $b_{22}$ are observed in figure 7 at $R=1 / 2$ and $R=-3 / 2$ and negative values at $R=0$ and $R=-1 / 2$ at larger $S t$ values.

Similar trends regarding the anisotropy development of the turbulence at $R=0,-1 / 2$ and -1 in rotating homogeneous shear flow but at a lower non-dimensional shear rate have been observed by Bardina et al. (1983) and Salhi \& Cambon (1997).

In order to get a better understanding of the influence of rotation on the anisotropy of the turbulence it is worthwhile to consider the principal angle of the Reynolds stress tensor, defined here as

$$
\begin{equation*}
\alpha_{u}=\frac{1}{2} \tan ^{-1}\left[2{\overline{u_{1} u_{3}}}_{3} /\left({\overline{u_{1} u_{1}}}_{1}-{\overline{u_{3} u_{3}}}_{3}\right)\right] \tag{5.1}
\end{equation*}
$$

The definition is such that $\alpha_{u}$ is the angle of the principal axis corresponding to the largest eigenvalue, i.e. largest principal Reynolds stress, with the $x_{1}$-axis. The angles for the five cases obtained form DNS and RDT are plotted in figure 9 . It can be shown that for a positive production rate of kinetic energy the requirement is $-90^{\circ}<\alpha_{u}<0^{\circ}$. For the non-rotating case $\alpha_{u}=-13^{\circ}$ according to the DNS at $S t=12$ compared to the value $\alpha_{u}=-19^{\circ}$ found in experiments which where conducted at a lower non-dimensional shear number (Ferchichi \& Tavoularis, 2002). At $R=-1 / 2$ and $R=-1, \alpha_{u}$ is very


Figure 7. Time development of the Reynolds stress anisotropy component $b_{22}$. Symbols and lines as in figure 3.


Figure 8. Time development of the Reynolds stress anisotropy component $b_{33}$. Symbols and lines as in figure 3.


Figure 9. Time development of $\alpha_{u}$. Symbols and lines as in figure 3.
close to $-45^{\circ}$ and $-90^{\circ}$, respectively, at larger $S t$ values which is related to decrease of $\bar{u}_{1} u_{1}$ production and the increase of ${\overline{u_{3}} u_{3} \text { production due to rotation. A simple displaced }}_{\text {a }}$ particle analysis predicts $\alpha_{u}=0^{\circ},-45^{\circ}$ and $-90^{\circ}$ for $R=0,-1 / 2$ and -1 , respectively (Tritton, 1992), quite close to the DNS values. At $R=1 / 2, \alpha_{u}$ approaches a value around $0^{\circ}$ and at $R=-3 / 2, \alpha_{u}$ decreases below $-90^{\circ}$ and starts to oscillate.

The pressure-strain correlations are considered to get a more complete understanding of development of the turbulent anisotropy and the importance of non-linear effects. In the following part the rapid and the slow pressure-strain correlations are denoted by $\Pi_{i j}^{r}$ and $\Pi_{i j}^{s}$, respectively. The slow part of $\Pi_{i j}$ is related to the non-linear part of the source term in the Poisson equation of the pressure, and is therefore not included in the RDT. The pressure-strain correlations presented in the figures are all scaled with $S K$.

In figure $10, \Pi_{11}^{r}$ and $\Pi_{11}^{s}$ are presented. In all cases, except at $R=-3 / 2, \Pi_{11}^{r}$ is a sink term in the Reynolds stress equation for $\bar{u}_{1} u_{1}$ and thus redistributes the streamwise kinetic energy to the other directions. At $R=0$ there is a considerable difference between the RDT predictions of $\Pi_{11}^{r}$ and the DNS results whereas in the other cases there is a fair agreement. The DNS shows a decrease of $\Pi_{11}^{r}$ after $S t=8$ at $R=0$, in contrast to


Figure 10. (a) Time development of $\Pi_{11}^{r} /(S K)$. Symbols and lines as in figure 3. (b) Time development of $\Pi_{11}^{s} /(S K)$. Only DNS data are displayed. Symbols as in figure 3.


Figure 11. (a) Time development of $\Pi_{33}^{r} /(S K)$. Symbols and lines as in figure 3. (b) Time development of $\Pi_{33}^{s} /(S K)$. Only DNS data are displayed. Symbols as in figure 3.
the RDT predictions. At $R=0$ and $R=-1 / 2, \Pi_{11}^{s}$ is a sink term and gives a significant contribution to the energy redistribution at larger $S t$ values. While at $R=0, \Pi_{11}^{s}$ is a sink term, it is a source term at $R=-1$. Because $\Pi_{11}^{r}$ becomes very small at $R=-1$ the sum of the slow and rapid part of the pressure-strain correlation becomes positive at larger $S t$ values and thus the streamwise velocity fluctuations gain energy.

In figure 11, $\Pi_{33}^{r}$ and $\Pi_{33}^{s}$ are presented. At $R=-1 / 2$ and $-1, \Pi_{33}^{r}$ is a large sink term but this is opposed by a positive production term as discussed before and, as a result, the transverse velocity fluctuations still grow. At $R=0, \Pi_{33}^{s}$ is much larger than $\Pi_{33}^{r}$ at larger $S t$ and the sum becomes a source term. At $R=-3 / 2, \Pi_{33}^{r}$ becomes a source term after about $S t=2$ for the transverse velocity fluctuations. This does not result in an increase of $\bar{u}_{3} u_{3}$ because after $S t=2$ the production of $\bar{u}_{3} u_{3}$ becomes negative.

In figure $12, \Pi_{13}^{r}$ and $\Pi_{13}^{s}$ are displayed. At $R=0, \Pi_{13}^{r}$ is initially large but then decreases rapidly whereas $\Pi_{13}^{s}$ increases and is larger than $\Pi_{13}^{r}$ for $S t>5$. At $R=-1 / 2$, $\Pi_{13}^{S}$ is also positive and gives a significant contribution at larger $S t$ values, but in the other three remaining cases $\Pi_{13}^{s}$ gives a very small contribution to the total pressurestrain correlation.

The RDT predictions of the development of the kinetic energy, anisotropy and pressure-


Figure 12. (a) Time development of $\Pi_{13}^{r} /(S K)$. Symbols and lines as in figure 3. (b) Time development of $\Pi_{13}^{s} /(S K)$. Only DNS data are displayed. Symbols as in figure 3.


Figure 13. Time development of $(a) K$ and $(b) \varepsilon$ at $R=0$ series $B(-)$ and $R=-1$ series $B(\cdots \cdots)$ and the corresponding simulations without the non-linear terms at $R=0(---)$ and at $R=-1(-\cdot-\cdot-)$.
strain correlations correspond in general well with the DNS at $R=1 / 2$ and $R=-3 / 2$. The non-linear effects in terms of $\Pi_{i j}^{s}$ appear to be weak in these two cases and seem to be strongly damped by the rotation. At $R=-1 / 2$ and $R=-1$ the non-linear effects are noticeable, for instance in the development of the anisotropy, but the most clear non-linear effects are observed at $R=0$, although the non-dimensional shear rate was high during the simulation period. However, a similar result was obtained by Kim (1989) who found that the slow pressure fluctuations have the same magnitude as the rapid pressure fluctuations in the rapidly sheared layer near the wall in a turbulent channel flow, contrary to common belief. In the DNS in the present study, all the slow pressure-strain correlations, except for the spanwise direction, are larger than the rapid pressure-strain correlations for $S t>7$.

In order to study the importance of the non-linear effects on the development of the turbulence at $R=0$ and $R=-1$ in more detail, simulations have been performed with the same initial velocity field, the same code and the same numerical parameters as the cases $R=0$ and $R=-1$ in series $B$, but with the non-linear terms explicitly set to zero. The results of this linear simulation are compared with the cases $R=0$ and


Figure 14. Time development of (a) $\bar{u} 3 u_{3}$ at $R=0$ and $\bar{u}_{1} u_{1}$ at $R=-1$ and (b) $\bar{u}_{1} u_{3}$ at $R=0$ and $R=-1$ in the linear and non-linear simulation. Lines as in figure 13.
$R=-1$ in series $B$. The results of the linear simulation should correspond well to the RDT predictions, which they do, but we wanted to be sure to have the same influence of finite domain size, domain deformation and remeshing in the linear and non-linear simulations. The differences between the two simulations are thus solely the result of non-linear contributions. Although the dissipation of kinetic energy is significant larger for $S t>6$ as can be seen in figure 13 (b) due to the non-linear effects, the growth of $K$ at $R=0$ is faster in the non-linear simulation than in the linear for $S t>6$ because of a larger production term as will be discussed later. The growth of $K$ at $R=0$ in the non-linear simulation at larger $S t$ values can be approximated by $\exp (0.178 S t)$ whereas in the linear simulations it is approximately linear. The growth rate at $R=0$ in the DNS, which is at $S t=12$ still far from equilibrium conditions, is faster than in the experiments close to equilibrium conditions of Tavoularis \& Corrsin (1981). In the latter study the growth rate can be approximated by $\exp (0.122 S t)$ when the centreline mean velocity in the experiments is taken as the advection velocity. Rogers (1991) proves that in the long time limit $K$ grows linearly in a non-viscous RDT at $R=0$. In a viscous RDT as in the present study the growth rate is less than linear at large times, but up to $S t=12$ it is close to linear in the linear simulation presented in figure 13. At $R=-1$ the differences between the linear and non-linear simulations are not as large but also in this case $K$ is larger in the non-linear simulations at larger $S t$ values.

The largest difference between the non-linear and linear simulation at $R=0$ occurs in the development of $\overline{\bar{u}_{3} u_{3}}$, which is presented in figure $14(a)$. According to non-viscous RDT (Rogers 1991) and viscous RDT $\bar{u}_{3} \bar{u}_{3}$ decays monotonically at $R=0$ and this happens also in the linear simulation. In the non-linear DNS, however, $\overline{u_{3} u_{3}}$ grows for $S t>3$ and at $S t=12$ there is a large difference between $\bar{u}_{3} u_{3}$, a factor of 20 , in the linear and non-linear simulation. Already in an early stage of the simulations, at $S t=3$, a difference between the linear and non-linear simulation can be noticed, which is surprising in view of the high shear rate. The difference between the development of $\bar{u}_{3} u_{3}$ in the linear and non-linear simulation is a consequence of $\Pi_{33}^{s}$ which gives a positive contribution to the growth of the transverse velocity fluctuations, as has been shown in figure 11. At $R=-1, \bar{u}_{1} u_{1}$ grows for $S t>7$ in the non-linear simulation whereas in the linear simulation it monotonically decays. At $S t=14, \bar{u}_{1} \bar{u}_{1}$ it is almost a factor of 5 larger in the non-linear simulation. In this case the difference is due to the positive contribution of $\Pi_{11}^{s}$ to the growth of the velocity fluctuations.


Figure 15. The two-point correlations (a) $\rho\left[u_{1}\right](\boldsymbol{r})$ and (b) $\rho\left[u_{3}\right](\boldsymbol{r})$ at $R=0$ and $S t=12$, series $B$, for separation vectors in the $\left(x_{1}, x_{3}\right)$-plane. Here $u_{1}$ is almost parallel to the principal axis of the Reynolds stress tensor and $u_{3}$ perpendicular.



Figure 16. The two-point correlations (a) $\rho[u](\boldsymbol{r})$ and (b) $\rho[w](\boldsymbol{r})$ at $R=-1 / 2$ and $S t=6$, series $A$, for separation vectors in the ( $x_{1}, x_{3}$ )-plane. Here $u=u_{1} \cos \alpha_{u}+u_{3} \sin \alpha_{u}$, $w=-u_{1} \sin \alpha_{u}+u_{3} \cos \alpha_{u}$ and $\alpha_{u}=-45^{\circ}$. Thus $u$ is the strongest fluctuating velocity component and is parallel to the principal axis of the Reynolds stress tensor and $w$ perpendicular.

Figure $14(b)$ presents the development of $\bar{u}_{1} u_{3}$ in the linear and non-linear simulation. Rogers has proven that $\bar{u}_{1} u_{3}$ becomes constant in a non-viscous RDT at large times at $R=0$. Non-viscous RDT computations strongly indicate the same asymptotic behaviour of ${\bar{u} u_{1}}_{3}$ at $R=-1$ but in a viscous RDT $\bar{u}_{1} u_{3}$ decays at large times, In figure $14(b)$ we can observe a growing discrepancy between the linear and non-linear simulation for $S t>4$. At the end of the simulations at $R=0$ and $R=-1, \bar{u}_{1} u_{3}$ is larger in the nonlinear simulation than in the linear simulation and this explains the faster growth of the kinetic energy in the non-linear DNS. The reason for the larger magnitude of ${\overline{u_{1}} u_{3} \text { is not }}^{\text {D }}$ due to $\Pi_{13}^{s}$ because at $R=0$ it opposes the development of negative $\bar{u}_{1} u_{3}$ correlations and at $R=-1$ it is very small, but it is the larger $\bar{u}_{3} u_{3}$ and $\bar{u}_{1} u_{1}$ correlation in the non-linear simulations at $R=0$ and $R=-1$, respectively.

### 5.1.2. Turbulent structures

It is known that a high shear rate causes elongated streamwise structures in homogeneous shear flow which bear close similarities with the structures encountered in wallbounded shear flows (Lee et al., 1990). Quantitative information about turbulent length scales can be obtained from two-point velocity correlations (no summation of repeated indices)

$$
\begin{equation*}
\rho\left[u_{i}\right](\boldsymbol{r})=\overline{u_{i}(\boldsymbol{x}) u_{i}(\boldsymbol{x}+\boldsymbol{r})} / \overline{u_{i} u_{i}} \tag{5.2}
\end{equation*}
$$



Figure 17. The two-point correlations (a) $\rho\left[u_{3}\right](\boldsymbol{r})$ and (b) $\rho\left[u_{1}\right](\boldsymbol{r})$ at $R=-1$ and $S t=14$, series $B$, for separation vectors in the $\left(x_{1}, x_{3}\right)$-plane. Here $u_{3}$ is almost parallel to the principal axis of the Reynolds stress tensor and $u_{1}$ perpendicular.

Two-point velocity correlations with the separation distance vector $\boldsymbol{r}$ in the ( $x_{1}, x_{3}$ )plane have been extracted from the DNS at different rotation numbers and at the end of the simulations so that the elongation of the structures is most pronounced. Figure $15(a)$ presents $\rho\left[u_{1}\right](\boldsymbol{r})$ at $R=0$, figure $16(a)$ presents $\rho\left[u_{i}\right](\boldsymbol{r})$ at $R=-1 / 2$ where $u_{i}$ is the velocity component in the $\left(x_{1}, x_{3}\right)$-plane with an angle of $-45^{\circ}$ to the flow direction and figure $17(a)$ presents $\rho\left[u_{3}\right](\boldsymbol{r})$ at $R=-1$. These velocity components are all approximately parallel to the principal axis of the Reynolds stress tensor corresponding to Reynolds stress with highest fluctuation intensity. The direction of this particular principal axis has been displayed in figure 9 . The figures show the typical long correlation length in a direction almost parallel to the flow direction of these velocity components parallel or almost parallel to the principal axis of the Reynolds stress tensor. A closer examination reveals that the longest correlation length appears at an angle of approximately $10^{\circ}$ with the flow direction with little variation of the angle at different rotation numbers.

Figure $15(b)$ presents $\rho\left[u_{3}\right](\boldsymbol{r})$ at $R=0$, figure $16(b)$ presents $\rho\left[u_{i}\right](\boldsymbol{r})$ at $R=-1 / 2$ where $u_{i}$ is the velocity component in the $\left(x_{1}, x_{3}\right)$-plane with an angle of $45^{\circ}$ to the flow direction and figure $17(b)$ presents $\rho\left[u_{1}\right](\boldsymbol{r})$ at $R=-1$. These velocity components are perpendicular to the velocity components whose two-point correlations are plotted in figure $15(a), 16(a)$ and $17(a)$, respectively. They are thus almost parallel to the principal axis of the Reynolds stress tensor corresponding to the Reynolds stress with the lowest fluctuation intensity. The velocity components in this direction have a much shorter correlation length as can be seen in the figures $15(b), 16(b)$ and $17(b)$. At $R=0,-1 / 2$ and -1 the velocity components with a high turbulence intensity have thus a long correlation length and the velocity components with a low turbulence intensity a short correlation length.

RDT significantly underpredicted the intensity of the transverse velocity fluctuations at $R=0$ and the streamwise velocity fluctuations at $R=-1$ because there was a considerable energy transfer due to the slow pressure-strain correlations as we have observed before. In these cases RDT overpredicts the correlation length in comparison with the DNS (results are omitted here). This shows that in the DNS mainly the transverse velocity fluctuations with higher wave numbers at $R=0$ and the streamwise velocity fluctuations with higher wave numbers at $R=-1$ gain energy by non-linear processes which leads to shorter correlation lengths than in the RDT simulations.

In the two stabilized cases, $R=-3 / 2$ and $R=1 / 2$, the two-point velocity correla-


Figure 18. The instantaneous velocity in a $\left(x, x_{2}\right)$-plane where $x$ is at $10^{\circ}$ with the flow direction. (a) streamwise velocity at $R=0$ and $S t=8 ;(b)$ streamwise velocity at $R=0$ and $S t=8$ for the RDT (the other plots are all obtained from DNS); (c) velocity component $u$ (see the caption of figure 16 for the definition of $u$ ) at $R=-1 / 2$ and $S t=6 ;(d)$ transverse velocity at $R=-1$ and $S t=10 ;(e)$ transverse velocity at $R=-3 / 2$ and $S t=6 ;(f)$ streamwise velocity at $R=1 / 2$ and $S t=6$.
tions do not reveal clear elongated structures in the flow direction and are therefore not presented here.

According to the two-point velocity correlation we might expect to see streaky velocity structures at $R=0, R=-1 / 2$ and $R=-1$. These are indeed observed in instantaneous
plots of the fluctuating velocity presented in figure $18(a),(c)$ and $(d)$ in a plane with an angle of $10^{\circ}$ with the flow direction. In the plots elongated turbulent structures in the flow direction can be observed of low and high speed flow. Note that at $R=0$ an instantaneous plot of the streamwise fluctuating velocity is shown but at $R=-1 / 2$ and $R=-1$ an instantaneous plot of $u$ (see the caption of figure 16 for the definition) and the transverse fluctuating velocity is shown, respectively. At $R=-1$ an instantaneous plot of the streamwise fluctuating velocity does not show any streaky structures, as can be expected from the two-point correlation presented in figure 17.

The turbulent structures found at $R=0$ are similar to the structures observed by Lee et al. (1990) in a rapidly sheared non-rotating homogeneous shear flow. Lee et al. remarked that these structures resemble the streaky streamwise structures in the nearwall region of a turbulent channel flow. We have also performed a simulation with the same parameters and initial velocity field as the $R=0$ case but without the non-linear terms. This simulation thus represents a RDT calculation and a plot of the streamwise velocity fluctuations is shown $18(b)$. Streamwise streaks are also observable in this case which shows that linear processes can generate the streaks, an observation that is in agreement with Kim \& Lim (2000), but the velocity field is much smoother than in the case with the non-linear terms included (see figure 18 a) because the small scales do not gain energy by non-linear instabilities and are damped by viscous effects.

Alvelius \& Johansson (1999) performed DNS of turbulent channel flow with spanwise rotation. In the simulations there was a large region in the middle of the channel where the absolute mean vorticity was approximately zero which corresponds to the $R=-1$ case considered here. It is interesting to note that Alvelius \& Johansson observed long streamwise structures with a positive wall-normal velocity in this middle region of the rotating channel flow. This observation corresponds well with the results shown in figure 18 (d).

The figures $18(e)$ and $(f)$ present instantaneous plots of the transverse and streamwise fluctuating velocity at $R=-3 / 2$ and $R=1 / 2$, respectively, in a plane with an angle of $10^{\circ}$ with the flow direction. These velocity components are also approximately aligned with the principal axis of the Reynolds stress tensor. At $R=1 / 2$ the instantaneous streamwise velocity structures are somewhat stretched in the flow direction but there are no such distinctive elongated structures as in the cases $R=0, R=-1 / 2$ and $R=-1$. Turbulent structures are even less clear at $R=-3 / 2$. The most coherent large scale turbulent structures are thus in our study found in the cases where the kinetic energy is growing.

To quantify the formation of streaky structures in homogeneous shear flows, Lee et al. (1990) and Salhi \& Cambon (1997) used the eddy elongation parameter $L^{*}=\ell_{1} / \ell_{2}$. In case of the streamwise velocity fluctuations we use $\ell_{1}=L_{1}^{1}$ and $\ell_{2}=2 L_{1}^{2}$ for the streamwise and spanwise length scales, respectively, similar as Lee et al. (1990). The length scales are obtained by integrating the two-point correlations (5.2)

$$
\begin{equation*}
L_{j}^{i}=\int_{0}^{\infty} \rho\left[u_{j}\right]\left(\boldsymbol{r}+x \boldsymbol{e}_{i}\right) d x \tag{5.3}
\end{equation*}
$$

Lee et al. suggested $L^{*}>8$ as criterium for streaky structures.
Figure 19 (a) shows $L^{*}$ extracted from the DNS at the different rotation numbers. Analytical expressions for $L^{*}$ obtained from inviscid RDT are presented by Salhi \& Cambon (1997). At $R=0, L^{*}$ seems to approach an asymptotic value close to the criterium for streaky structures whereas in RDT $L^{*}$ monotonically increases (Salhi \& Cambon). An explanation is the decrease of $L_{1}^{2}$ in the RDT whereas in the DNS it is approximately constant after some time. The streak spacing or $L_{1}^{2}$ in the DNS seems

Figure 19. The elongation parameter for the streamwise velocity component $(a)$ and for the transverse velocity component $(b) .(-), R=0 ;(---), R=-1 / 2 ;(\cdots), R=-1 ;(-\cdots-)$, $R=1 / 2 ;(--), R=-3 / 2$.


Figure 20. Two-point velocity correlations: (-), $\rho\left[u_{1}\right]\left(x_{2}\right)$ at $R=0$ and $S t=12$, series $B ;(---), \rho[u]\left(x_{2}\right)$ at $R=-1 / 2$ and $S t=6$, series $A$ (see the caption of figure 16 for the definition of $u) ;(\cdots \cdots), \rho\left[u_{3}\right]\left(x_{2}\right)$ at $R=-1$ and $S t=14$, series $B$.
to be determined by $(\nu / S)^{1 / 2}$ as discussed hereafter, but in the RDT this is not the case. Kim \& Lim (2000) concluded from numerical experiments of turbulent channel flow that the non-linear terms are necessary to produce the proper streak spacing and this conclusions seems to be confirmed by the present simulations. At $R=-1 / 2, L^{*}$ grows faster than at $R=0$, but at $R=1 / 2,-1$ and $-3 / 2, L^{*}$ stays approximately constant or oscillates weakly showing the absence of streaky structures. Similar results are obtained by RDT as shown by Salhi \& Cambon (1997).

In figure $19(\mathrm{~b})$ we present $L^{*}=\ell_{1} / \ell_{2}$ where $\ell_{1}=L_{3}^{1}$ and $\ell_{2}=L_{3}^{2}$, i.e. the integral length scales for the transverse velocity component, extracted from the DNS at $R=-1 / 2$ and -1 . ( $L^{*}$ is always defined so that $L^{*}=1$ in isotropic turbulence). In both these cases $L^{*}$ becomes very large revealing strong elongation of the structures in the streamwise direction.

Elongated streaks of alternating high and low speed flow give rise to negative values of the spanwise two-point correlations. The spanwise two-point velocity correlations are plotted in figure 20 for the cases and velocity components that we can observe clear

|  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $R=2 \Omega / S$ | $S t$ | $v_{11}$ | $v_{22}$ | $v_{33}$ | $v_{13}$ |  |
| $1 / 2$ | 6 | 0.151 | 0.076 | -0.227 | 0.117 |  |
| 0 | 8 | -0.019 | 0.084 | -0.064 | 0.111 |  |
| $-1 / 2$ | 6 | 0.249 | -0.156 | -0.093 | 0.267 |  |
| -1 | 10 | 0.542 | -0.277 | -0.265 | 0.167 |  |
| $-3 / 2$ | 6 | 0.466 | -0.187 | -0.279 | 0.125 |  |

TABLE 2. The components of the anisotropy tensor of the vorticity fluctuations at different rotation numbers, extracted from series $A$.
streaks, e.g. $R=0, R=-1 / 2$ and $R=-1$. The mean spacing $\Lambda$ between two high speed or low speed streaks is about twice the separation at which the minimum value of $\rho\left[u_{i}\right]\left(x_{2}\right)$ occurs. If the streak spacing is scaled with the viscous length scale $(\nu / S)^{1 / 2}$, we find $\Lambda=87$ at $R=0$ and $S t=12, \Lambda=89$ at $R=-1 / 2$ and $S t=6$, and $\Lambda=80$ at $R=-1$ and $S t=14$. These values correspond reasonably well with the mean streak spacing of $\Lambda=112$ found in DNS of turbulent channel flow (Moser et al. (1999).

### 5.1.3. Vorticity structures

Rotation affects the small scales of the turbulence as we can see in the equation (2.9) for the vorticity. The influence of vorticity on the small scales and in particular on vortices is studied in this section.

In table 2 the values of the anisotropy tensor components of the mean vorticity fluctuations (thus without the mean vorticity component)

$$
\begin{equation*}
v_{i j}=\frac{\left\langle\omega_{i} \omega_{j}\right\rangle}{\left\langle\omega_{k} \omega_{k}\right\rangle}-\frac{1}{3} \delta_{i j} \tag{5.4}
\end{equation*}
$$

extracted from the DNS, are listed in table 2 for the different rotation numbers. According to the table, $v_{22}$ is the largest component at $R=0$, but it is not much larger than the other components. At $R=-1 / 2, v_{11}$ is the dominating component and this is even more pronounced at $R=-1$ where the vorticity fluctuations of $\omega_{2}$ and $\omega_{3}$ are much smaller than of $\omega_{1}$. This can be understood if we consider the linearized form of the vorticity equation (2.9). At $R=-1$, linear inviscid theory shows that $\omega_{2}$ and $\omega_{3}$ stay constant and $\omega_{1} \sim S t$ because of amplification by mean shear (Cambon et al. 1994). The linear production appears in fact to be dominant at $R=-1$ (results are not presented here).

Figure 21 presents joint probability density functions (PDFs) of the strain rate $\left(2 s_{i j} s_{i j}\right)^{1 / 2}$ and the norm of the vorticity $\left(\omega_{i} \omega_{i}\right)^{1 / 2}$ obtained from the DNS whereby now the mean vorticity is included in $\omega_{2}$ and the mean strain rate is included in $s_{13}$. Points close to the line $s=\omega$ correspond typically to vortex sheets, but also the mean flow gives $s=\omega$.

The joint PDF obtained from the DNS at $R=0$ and at $S t=8$, displayed in figure 21 (a), shows a high probability around the line $s=\omega$, suggesting vortex sheet behaviour, especially at large values of strain and vorticity. At the same time there are regions in the flow with high vorticity and low strain which typically are related to vortices, and regions with high strain and low vorticity related to irrotational straining (Chong et al. 1998). This is even more pronounced at $S t=12$ where more regions are found with high vorticity or high strain (figure 21 b). Results are omitted here, but in a simulation without the non-linear terms and $R=0$, regions with either large strain or large vorticity are absent.

When the rotation number decreases from $R=0$ to $-1 / 2$ and to -1 the vortex sheet behaviour becomes less appearant according to figure $21(a),(c)$ and $(d)$. The probability


Figure 21. The joint PDF of norm of the vorticity including the mean vorticity $\left(\omega_{i} \omega_{i}\right)^{1 / 2}$ (horizontal axis) and the strain $\left(2 s_{i j} s_{i j}\right)^{1 / 2}$ (vertical axis) whereby both are scaled with the rms of the vorticity. The difference between each contour level is one decade and a lighter colour corresponds to a higher probability. (a) $R=0$ and $S t=8$; (b) $R=0$ and $S t=12$; (c) $R=-1 / 2$ and $S t=6 ;(d) R=-1$ and $S t=14 ;(e) R=-3 / 2$ and $S t=6 ;(f) R=1 / 2$ and $S t=6$.
of strain or vorticity dominated regions in the flow is quite large at $R=-1 / 2$. The appearance of vorticity dominated regions, with sometimes extreme values of vorticity, is even more likely at $R=-1$, which indicates the presence of many relative strong vortices.

At $R=-3 / 2$ much less strain or vorticity dominated regions appear than in the former three non-linear cases according to $21(e)$. The strain and vorticity are mostly of the same order indicating the presence of vortex sheets. Similar conclusions can be drawn for the case $R=1 / 2$. The appearance of less strain and vorticity dominated regions is probably related to the less intensive non-linear processes in these two cases.

Further insight into the features of the vorticity field can be obtained by using threedimensional visualizations of vortex structures. There exist a number of techniques to


Figure 22. Vortices identified by isosurfaces of $\left|\lambda_{c i}\right|$ in a domain of size $L_{x_{1}} \times L_{x_{2}} \times L_{x_{3}}=1.5 \pi \times 1 \pi \times 0.5 \pi(a, \mathrm{~b}, \mathrm{c}, \mathrm{d}) . L_{x_{1}} \times L_{x_{2}} \times L_{x_{3}}=2 \pi \times 1.5 \pi \times 0.8 \pi$ (e,f). (a) $R=0$ and $S t=8,\left|\lambda_{c i}\right| / S=1.68 ;(b) R=0$ and $S t=12,\left|\lambda_{c i}\right| / S=2.75$; (c) $R=-1 / 2$ and $S t=6,\left|\lambda_{c i}\right| / S=1.40 ;(d) R=-1$ and $S t=14,\left|\lambda_{c i}\right| / S=2.07 ;(e) R=-3 / 2$ and $S t=6,\left|\lambda_{c i}\right| / S=0.66 ;(f) R=1 / 2$ and $S t=6,\left|\lambda_{c i}\right| / S=0.48$.
identify vortices. We have applied a technique proposed by Zhou et al. (1999) and use the imaginary part of the complex eigenvalue of the velocity gradient tensor $\lambda_{c i}$ to identify the vortices. This quantity is related to the strength of the local swirling motion of the velocity field. For instance, it is zero at places where the velocity field is not locally
circular or swirling, as e.g. in vortex sheets. In the visualizations presented here we show isosurfaces of the imaginary part of the complex eigenvalue of the velocity gradient tensor. This means that only vortices with a swirling strength above a certain threshold value are visualized and vortex sheets or shear layers are not visible in the figures.

The three-dimensional visualizations presented in figure 22 show the vortical structures developed in the DNS. Many elongated, quasi streamwise vortices can be observed in figure $22(a)$ at $R=0$ and $S t=8$ which are approximately aligned with the streaky structures observed in figure 18 (b). Kim \& Lim (2000) observed that in wall-bounded shear flows linear processes can produce streaks but the non-linear terms are essential for the formation of the streamwise vortices. In a simulation without the non-linear terms we could observe streamwise vortices, but these were much weaker than in the simulation with the non-linear terms. Apart form the streamwise vortices some hairpin-like vortical structures can be distinguished in figure $22(a)$ and many short, curved vortex tubes can be seen which are more or less aligned with the spanwise direction. These latter structures could well be parts or remains of hairpin vortices. The vorticity field has a quite different appearance at a later stadium in the DNS at $S t=12$ when the non-linear processes are much stronger, as shown in figure $22(b)$. There are some streamwise vortices but they are not as long and pronounced as at $S t=8$. Instead many relative short vortex tubes can be observed with a more isotropic orientation or with a spanwise orientation. These observations show similarities with the observations of Kida \& Tanaka (1994) who also found that the streamwise vortices disappear and the vorticity field becomes more isotropic at larger $S t$ values in homogeneous shear flow.

Streamwise and spanwise vortex tubes and hairpin-like vortical structures have also been observed by Rogers \& Moin (1987) and Kida \& Tanaka (1994) in non-rotating homogeneous shear flows, but at much lower shear rates. The latter argued that the spanwise vortex tubes are a consequence of a rolling up of vortex sheets through the Kelvin-Helmholtz instability. This is, however, a linear instability process and one would therefore expect to see these spanwise vortex tubes in a simulation without the non-linear terms, if this linear instability mechanism exists, but they are absent in the simulation without the non-linear terms at $R=0$. The spanwise vortical structures in the DNS are thus more likely related to non-linear processes.

In the most unstable case at $R=-1 / 2$ there exist many and intense streamwise vortices as can be observed in figure $22(c)$. They have a slightly steeper angle with the flow direction, approximately $18^{\circ}$, than the streamwise vortices at $R=0$. A few hairpinlike vortical structures can be observed at $R=-1 / 2$ and many curved vortices as well as quasi spanwise vortices. Very elongated and intense streamwise vortex tubes are observed at $R=-1$ in figure $22(d)$. Similar structures were observed by Tanaka et al. (1998) in rotating homogeneous shear flow at $R=-1$ at a lower shear rate. The dominance of the streamwise vortices at $R=-1$ was already indicated by the vorticity anisotropy tensor presented in table 2. To a smaller extent spanwise vortex tubes can be observed and streamwise vortex tubes with a hook-like shape at one of the ends resembling one-sided hairpin vortical structures.

Much weaker and less distinct streamwise vortex structures are observed in the stabilized case $R=-3 / 2$ displayed in figure $22(e)$, but the predominance of streamwise oriented vortex tubes is still obvious. Vortices appear to be even weaker at $R=1 / 2$ which is indicated by the low value of $\left|\lambda_{c i}\right|$ used in figure $22(f)$ to visualize the vortices. At $R=1 / 2$ most of the vortices are not lying in a $\left(x_{1}, x_{3}\right)$-plane as in the other cases, but have a component in the spanwise direction. Due to the strong shear they still have a small angle with the flow direction. Beside these vortices also quite thick and short


Figure 23. PDFs of the fluctuating relative helicity density $h^{\prime}$ conditioned on high streamwise vorticity:,$- R=0$ and $S t=8 ;-\cdot--, R=0$ and $S t=12 ;---, R=-1 / 2$ and $S t=6$; $\cdots \cdots, R=-1$ and $S t=14$.
vortical structures can be observed with a spanwise orientation. Hairpin-like vortical structures seem to be absent in both stabilized cases.

The presence of streamwise vortices is a common feature at $R=-1 / 2,-1$ and 0 in the DNS. The swirling motion of fluid particles in the streamwise vortices is however, quite different at the different rotation numbers. To study this topic in more detail a useful quantity is the relative helicity density fluctuation, which is defined as

$$
\begin{equation*}
h^{\prime}=\frac{\boldsymbol{u} \cdot \boldsymbol{\omega}}{|\boldsymbol{u}||\boldsymbol{\omega}|}=\cos \phi \tag{5.5}
\end{equation*}
$$

where $\phi$ is the angle between the velocity and vorticity vector. Here the mean vorticity is included in $\boldsymbol{\omega}$. The condition $\omega_{1}>1.5 \omega^{\prime}$ is used where $\omega^{\prime}$ is the rms of the vorticity to identify mainly streamwise vortices in the DNS, otherwise the interpretation of the results will be complicated. The condition $\omega_{1}>1.5 \omega^{\prime}$ eliminates the tracing of vortex sheets and the heads of hairpin vortices because they have in general a relatively small streamwise vorticity component. This condition is satisfied in about $1.5 \%$ to $2.5 \%$ of the flow field and visualizations show that this condition indeed traces many of the streamwise vortices.

Figure 23 presents the probability density functions (PDFs) of $h^{\prime}$ extracted from the DNS at $R=0,-1 / 2$ and -1 for the regions of the flow field where the condition $\omega_{1}>\beta \omega^{\prime}$ with $\beta=1.5$ is satisfied. The conditioned PDFs appear to be rather insensitive to the exact value of the threshold value $\beta$. The figure shows that there is a clear difference between the conditioned PDFs at different rotation numbers. At $R=0$ and $S t=8$ the PDF has peaks at $h^{\prime}= \pm 1$ which indicates that in many streamwise vortices the fluid particles undergo a swirling, helical motion with a large streamwise component. This is likely the reason that the streamwise velocity has a long correlation length and has a streak-like structure at $R=0$. At $S t=12$ the peaks at $h^{\prime}= \pm 1$ have disappeared which is likely related to the more isotropic character of the vortices at larger $S t$ values, but the high probability of large negative or positive values of $h^{\prime}$ still remains.

At $R=-1 / 2$ the fluid particles undergo a swirling motion with a smaller streamwise component than at $R=0$, which is indicated by the flat distribution in the PDF between $h^{\prime}= \pm 0.3$. The conditioned PDF at $R=-1$ has a peak at $h^{\prime}=0$ and this signifies that the streamwise vortices are characterized by swirling motions with a very small streamwise component. Remark that in this case we have seen that the transverse velocity


Figure 24. Time development of the dimensionless parameter (a) $B_{1}$ (only series $A$ ) and (b) $B_{3}$. Symbols and lines as in figure 3.
has a long correlation length in the flow direction and has a streak-like structure and the streamwise velocity a short correlation length, which now can be explained by the small streamwise velocity component in the streamwise vortices.

### 5.2. Scalar field

In this section the evolution of the three passive scalar fields with steady and linear mean scalar gradients in the $x_{1}, x_{2}$ and $x_{3}$-direction is studied by means of the DNS and RDT. The corresponding passive scalar will be denoted by $\theta_{1}, \theta_{2}$ and $\theta_{3}$, respectively.

### 5.2.1. Scalar fluctuations

The dimensionless ratio of scalar versus velocity fluctuations is defined as

$$
\begin{equation*}
B_{\alpha}=\frac{\theta_{\alpha}^{\prime} / G}{q / S} \tag{5.6}
\end{equation*}
$$

where $\theta_{\alpha}^{\prime}$ is the root mean square of the scalar fluctuations and $q^{2}=2 K$. The time development of this relative strength of scalar fluctuations versus velocity fluctuations has been displayed in figure 24 for the five different rotation numbers. Both DNS results and RDT predictions are plotted. Initially, the ratio is zero because there are no scalar fluctuations at $S t=0$, but then it grows because of the presence of the mean scalar gradient. In some cases the relative intensity seems to reach an asymptotic value at the end of the simulations, but the simulation time was in general too short to reach an asymptotic state. This is a difference with the experiments of Tavoularis \& Corrsin (1981) and DNS of Rogers et al. (1989) where the relative intensity reached quite fast an asymptotic value because they used a lower shear rate. Nevertheless, at $R=0, \theta_{1}^{\prime}$ is considerably larger than $\theta_{3}^{\prime}$, in agreement with the DNS of Rogers et al. (1989). The effect of rotation on the relative strength of the scalar fluctuations is significant. In the case with the mean scalar gradient in the $x_{1}$-direction the DNS show that at $R=0$ and $R=1 / 2, B_{1}$ is larger than when the rotation number is negative. as we can see in figure $24(a)$. At $R=-1$ and $R=-3 / 2, B_{3}$ is on the other hand larger than in the other cases. The RDT predictions agree in general quite well with the DNS, but some discrepancies can be noticed at larger $S t$ values.

The change of the structure of the turbulent flow field by rotation influences in its turn the structure of the scalar field. This is observable in figure 25 where visualizations of the instantaneous scalar fluctuations in a plane perpendicular to the flow direction are

The effect of rotation on turbulence and scalar transport


Figure 25. The instantaneous scalar fluctuations in a ( $x_{2}, x_{3}$ )-plane. $\theta_{1}$ at (a) $R=0, S t=8$ and (b) $R=-3 / 2$ and $S t=6 ; \theta_{2}$ at (c) $R=-1 / 2, S t=6$ and (d) $R=1 / 2$ and $S t=6 ; \theta_{3}$ at (e) $R=0, S t=12$ and $(f) R=-1$ and $S t=14$.
presented. Small plume-like structures in the scalar field with a streamwise mean gradient can be observed at $R=0$ (figure $25 a$ ), but these structures are absent at $R=-3 / 2$ (figure $25 b$ ). Plume-like structures are also present in the scalar field with a spanwise mean gradient at $R=-1 / 2$ (figure $25 c$ ), but at $R=1 / 2$ the structures are more


Figure 26. Time development of the scalar flux coefficient $(a) \zeta_{1}^{1}$ and (b) $\zeta_{3}^{1}$. Symbols (only series $A$ ) and lines as in figure 3 .
streak-like and elongated in the spanwise direction. Note the very thin scalar structures at $R=1 / 2$, which are probably caused by intense strain in the $\left(x_{2}, x_{3}\right)$-plane. A possible origin of the plume-like structures can be scalar transport by the streamwise vortices which are more dominantly present at $R=0$ and $R=-1 / 2$ than at $R=-3 / 2$ and $R=1 / 2$ as we have seen before and are therefore probably responsible for a significant part of the scalar transport. At $R=0$ the structures in the scalar field with a transverse mean gradient (figure 25 e ) seem to be smaller than at $R=-1$, where again plume-like structures can be observed (figure $25 f$ ), but is this not surprising because of the presence of many streamwise vortices in this case, as shown before.

### 5.2.2. Turbulent scalar fluxes

The turbulent scalar flux is affected by mean shear and rotation as can be seen in equation (2.11) and does in general not align with the mean scalar gradient (Tavoularis \& Corrsin, 1981), but our knowledge about the effect of rotation on turbulent scalar transport is limited and therefore a detailed analysis presented.

The scalar-velocity correlation coefficient is defined by (no summation of repeated indices)

$$
\begin{equation*}
\zeta_{i}^{\alpha}={\overline{u_{i}}}_{\alpha} / u_{i}^{\prime} \theta_{\alpha}^{\prime} \tag{5.7}
\end{equation*}
$$

where $u_{i}^{\prime}$ and $\theta_{\alpha}^{\prime}$ are the root mean square of the velocity and scalar fluctuation. Figure 26 presents $\zeta_{1}^{1}$ and $\zeta_{3}^{1}$ obtained from DNS and RDT predictions. At $R=0, \zeta_{1}^{1}$ shows a large negative correlation but there is also a small scalar flux component in the transverse direction shown by figure $26(b)$. The decrease of $\zeta_{3}^{1}$ as seen in the DNS is not predicted by RDT. The differences between the RDT predictions and DNS regarding scalar fluxes is caused by differences in velocity fluctuations and the destruction term and the absence of the slow pressure-scalar gradient correlation in the RDT, see equation (2.11). The correlation $\zeta_{1}^{1}$ has at $R=-1 / 2$ a large negative correlation as well, but at $R=-1$, $\zeta_{1}^{1}$ has a relative small negative value at the end of the simulation. This is probably a consequence of the cancellation of the second and third production term on the right-hand-side of equation (2.11) at $R=-1$. The RDT predicts a decrease of $\zeta_{1}^{1}$ but not as rapid as the DNS. Also at $R=1 / 2$ and $R=-3 / 2$ rotation strongly reduces $\zeta_{1}^{1}$. In all cases, except at $R=1 / 2, \zeta_{3}^{1}$ is positive because the production term due to the mean scalar gradient is positive. At $R=1 / 2$ this production term of $\bar{u}_{3}{ }_{1}$ is small because


Figure 27. Time development of the scalar flux coefficient $\zeta_{2}^{2}$. Symbols (only series $A$ ) and lines as in figure 3.


Figure 28. Time development of the scalar flux coefficient $(a) \zeta_{1}^{3}$ and (b) $\zeta_{3}^{3}$. Symbols and lines as in figure 3.
$\bar{u}_{1} u_{3}$ is small, but the third term on the right-hand-side of equation (2.11) is negative leading to a negative $\zeta_{3}^{1}$.

The correlation coefficient $\zeta_{2}^{2}$ is also affected by rotation as we see in figure 27, but not as much as the other scalar-velocity correlations. At $R=-3 / 2$ and $R=1 / 2$ the RDT predictions and the DNS agree quite well, but at the other rotation numbers RDT predicts stronger negative correlations than the DNS.

Figure 28 presents $\zeta_{1}^{3}$ and $\zeta_{3}^{3}$. At $R=0, \zeta_{3}^{3}=-0.41$ at $S t=12$ in the DNS, which is close to $\zeta_{3}^{3}=-0.45$ obtained by Tavoularis \& Corrsin (1981) and Rogers et al. (1986), but in these investigations $\zeta_{1}^{3} \simeq 0.60$, which is considerably smaller than $\zeta_{1}^{3} \simeq 0.86$ we observed at $S t=12$ in the DNS. A higher shear rate gives thus stronger streamwise scalar-velocity correlations. At $R=-1 / 2$ the scalar fluctuations are strongly correlated to the transverse and streamwise velocity fluctuations as shown by the large positive and negative values of $\zeta_{1}^{3}$ and $\zeta_{3}^{3}$, respectively. At $R=-1, \zeta_{3}^{3}$ has also large negative values but $\zeta_{1}^{3} \simeq 0$. This implies that the first product term in the transport equation of $\bar{u}_{1} \bar{\theta}_{3}$ given by $(2.11)$ is balanced by $\Pi_{\theta 1}$ and $\varepsilon_{\theta 1}$ because the second and third term on the right-hand-side cancel each other at $R=-1$. At $R=-3 / 2$, $\zeta_{3}^{3}$ becomes slightly positive at $S t=6$ according to the DNS and RDT predictions, which implies that there is a


Figure 29. Time development of $\alpha_{\theta}$ for the scalar with a (a) streamwise (only series $A$ ) and (b) transverse mean scalar gradient. Symbols and lines as in figure 3.
small counter gradient scalar flux, although it is very small in the DNS. The counter gradient flux is the result of the scalar flux interacting with the rotation which gives a positive contribution in the transport equation (2.11) for $\bar{u}_{3} \theta_{3}$ because $\bar{u}_{1} \theta$ is negative at $R=-3 / 2$. In this case $\zeta_{1}^{3}$ is negative because the sum of the second and third term production term of ${\overline{u_{1}} \theta_{3}}^{0}$ on the right-hand-side of equation (2.11) equals $\frac{1}{2} S \bar{u}_{3}{ }_{3}$ and is negative till $S t=4$ and the first term is small because $\bar{u}_{1} u_{3}$ is small. This is of course a simplified explanation because the pressure-gradient correlation and the destruction terms play also a role.

The RDT predictions in the two stabilized cases, $R=-3 / 2$ and $R=1 / 2$, agree quite well with the DNS, but in the other cases RDT predicts too strong correlations between scalar and transverse velocity fluctuations.

We can gain further insight by studying the direction of the turbulent scalar flux at different rotation numbers. The angle $\alpha_{\theta}$ of the mean turbulent scalar fluxes for the cases with a streamwise or transverse mean scalar gradient is defined as

$$
\begin{equation*}
\alpha_{\theta}=\tan ^{-1}\left(\overline{u_{3} \theta} / \overline{u_{1} \theta}\right) \tag{5.8}
\end{equation*}
$$

and is the inclination angle of the scalar fluxes with the $x_{1}$-axis. The scalar flux for the case with a spanwise mean gradient is always aligned with the mean scalar gradient because ${\overline{u_{1}} \theta_{2}}^{2}{\bar{u} u_{3}}_{2}=0$ due to flow symmetry.

Figure 29 (a) presents the time development of $\alpha_{\theta}$ for the cases with a streamwise mean scalar gradient. Note that in this case $\alpha_{\theta}=0^{\circ}$ implies a scalar flux down the mean gradient. It is obvious that the rotation has a large influence on the direction of the turbulent scalar flux. At $R=1 / 2$ and $R=0$ the scalar flux has a small positive and negative angle with the streamwise axis, respectively, but in the other cases the scalar flux has a large negative angle with the mean scalar gradient. In the case $R=-1$, $\alpha_{\theta}=-79^{\circ}$ at $S t=10$ implying that the scalar flux is almost perpendicular to the mean gradient.

Figure $29(b)$ shows the time development of $\alpha_{\theta}$ for the cases with a transverse mean scalar gradient. At $R=-1, \alpha_{\theta}$ is close to $-90^{\circ}$ during the entire simulation implying a close alignment between the scalar flux and the mean scalar gradient. On the other hand, at $R=-1 / 2$ and especially at $R=0$ and $R=1 / 2$ the scalar flux vector has a large component in the streamwise direction at larger $S t$ values. The case $R=-3 / 2$ has also a large scalar flux component in the streamwise direction at larger $S t$ values, but


Figure 30. Time development of $\alpha_{u}$ (white symbols) and $\alpha_{\theta}$ for $\theta_{1}$ (black symbols) and $\theta_{3}$ (gray symbols), extracted from the DNS. (a) shows the results of the cases ( $\square-\square$ ), $R=0$; $(\mathrm{O}-\mathrm{O}), R=-1 / 2 ;(\triangle \cdots \triangle), R=-1$; and $(b)$ shows the results of the cases $(\nabla-\cdots-\nabla)$, $R=1 / 2 ;(\diamond-\cdot-\diamond), R=-3 / 2$.
the direction of the scalar flux is almost opposite to the direction of the scalar flux at $R=0$. Moreover, the scalar flux has a small counter gradient component in this case as we have observed before. The RDT predictions correspond in all cases well with the DNS and this signifies a large influence of the linear effects on the direction of the scalar transport.

The large variation of the direction of the scalar flux with different rotation numbers is quite remarkable, but some understanding for this large variation can be obtained when the principal angle of the Reynolds stress tensor $\alpha_{u}$ and the inclination angle of the scalar fluxes $\alpha_{\theta}$ are compared. In figure 30 the time development of those two angles, extracted from the DNS, has been displayed. The close connection between the large scale structure of the turbulent flow field and the turbulent transport of scalars is apparent. In all cases, except at $R=-3 / 2$, the turbulent scalar flux rapidly aligns itself with the principal axes of the Reynolds stress tensor. The same observation, but only for a non-rotating homogeneous shear flow, has been made by Rogers et al. (1989). The scalar flux vector is thus in general aligned with the direction of the strongest velocity fluctuations. The exception is the case $R=-3 / 2$ where the scalar flux with the transverse mean gradient is almost perpendicular to the direction of the strongest velocity fluctuations at $S t=6$.

The streamwise vortices observed in the cases $R=0,-1 / 2$ and -1 might also play an important role in the transport of the scalars. This is in fact indicated by the plume-like structure of the scalar field (figure 25). At $R=0$ the streamwise vortices appear to have a large streamwise velocity component, as shown in figure 23 by means of the PDF of the fluctuating relative helicity density, and can therefore induce a large streamwise scalar transport, which is what we observe. At $R=-1$ on the other hand the streamwise vortices have a small streamwise velocity component which can cause a preferential scalar transport in the transverse and spanwise direction rather than in the streamwise direction and this is confirmed by the results of the DNS.

The simplest model for the scalar flux is based on a gradient diffusion assumption

$$
\begin{equation*}
\overline{u_{i} \theta}=-\frac{\nu_{t}}{S c_{t}} G_{i} \tag{5.9}
\end{equation*}
$$

where $\nu_{t}$ is the turbulent viscosity, which is in the present case equal to $-\overline{u_{1} u_{3}} / S$, and $S c_{t}$ is the turbulent Schmidt or Prandtl number. This model predicts a scalar flux down

| $R$ | St | $S c_{t}$ for $\theta_{1}$ |  | $S c_{t}$ for $\theta_{2}$ |  | $S c_{t}$ for $\theta_{3}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | DNS | RDT | DNS | RDT | DNS | RDT |
| 1/2 | 6 | -0.005 | -0.011 | -0.005 | -0.010 | -0.10 | -0.31 |
| 0 | 8 | 0.05 | 0.03 | 0.24 | 0.11 | 0.97 | 0.78 |
| $-1 / 2$ | 6 | 0.42 | 0.38 | 0.82 | 0.63 | 0.54 | 0.47 |
| -1 | 10 | 0.86 | 0.44 | 0.08 | 0.03 | 0.04 | 0.02 |
| -3/2 | 6 | -0.07 | -0.12 | -0.007 | -0.010 | 0.31 | 0.17 |

Table 3. The turbulent Schmidt number $S c_{t}$ for the scalars with a streamwise, spanwise and transverse mean gradient, respectively. Data are obtained from the DNS, series $A$ and RDT.


Figure 31. Time development of (a) $\Upsilon_{1}$ (only series $A$ ), (b) $\Upsilon_{3}$ (gray symbols: series $A$ and white symbols: series $B$ ). Data are obtained from DNS and symbols and lines are as in figure 30.
the mean gradient which is thus inappropriate for the present case. In addition, $S c_{t}$ is assumed to be a constant and of order one but Rogers et al. (1989) showed that $S c_{t}$ strongly depends on the direction of the mean scalar gradient. Table 3, listing $S c_{t}$ computed at the end of the DNS, shows that $S c_{t}$ does not only depend on the direction of the mean scalar gradient, but also strongly on the rotation number. At $R=0$, for instance, $S c_{t}$ for the scalar with transverse mean gradient is of order one in agreement with the value found in other shear flows, but at $R=-1$ it is much smaller. Even negative turbulent Schmidt numbers are observed at $R=-3 / 2$ and $R=1 / 2$ which is not due to counter gradient fluxes but a consequence of negative equivalent turbulent viscosities. The positive Schmidt number for $\theta_{3}$ at $R=-3 / 2$ is due to the counter gradient flux and the negative turbulent viscosity. RDT predictions of $S c_{t}$ are also listed in table 3 and they show quite similar trends regarding the influence of the rotation number as the results obtained from DNS. In a few cases, however, there are significant differences between the predictions of RDT and DNS. For example, at $R=-1$ where the DNS gives a significant larger value for $S c_{t}$ than the RDT in case of a streamwise mean scalar gradient.

### 5.2.3. Time scale ratios

An often used model for the scalar dissipation is the assumption of a constant ratio of turbulence time scale versus scalar time scale $\Upsilon_{\alpha}=(2 K / \varepsilon) /\left(\overline{\theta_{\alpha} \theta_{\alpha}} / \chi\right)$ (no summation of repeated indices), where the scalar dissipation $\chi=\kappa \overline{\left(\partial \theta_{\alpha} / \partial x_{j}\right)\left(\partial \theta_{\alpha} / \partial x_{j}\right)}$ (only summation of the index $j$ ). The time development of this time scale ratio for the scalars with
mean gradients in the streamwise and transverse direction extracted from the DNS, is presented in figure 31. In the DNS of non-rotating homogeneous shear flow of Rogers et $a l$. (1989) the time scale ratio had a value between 1.5 and 2.0, depending on the direction of the mean scalar gradient. In the present case we observe at $R=0$ a variation of the time scale ratio with the mean scalar gradient direction as well, but it does not reach yet an asymptotic value. Of importance is the large variation of the time scale ratios with the rotation number. At $R=-1 / 2$ the time scale ratios reach large values compared to the other cases, especially the scalar with a streamwise mean gradient as can be seen in figure $31(a)$ and (b), and the figures indicate that the time scale ratios may even become larger if the simulations would be proceeded. On the other hand, in the two stabilized cases $R=-3 / 2$ and $R=1 / 2$ the time scale ratios have quite small values compared to the other cases.

## 6. Conclusions

The time development of uniformly sheared homogeneous turbulent flows in a frame rotating around the spanwise axis has been studied by means of a series of direct numerical simulations (DNS). Together with the flow field, the development of passive scalar field with mean gradients in the streamwise, spanwise and transverse direction, respectively, was investigated in order to clarify the influence of rotation on scalar transport. A relatively high shear rate has been applied in the present study with the aim to approximate the conditions of the near-wall region of turbulent boundary layers. It was therefore anticipated that rapid distortion theory (RDT), based on a linearized set of equations, would give a good description of the observed phenomena.

Several cases have been simulated with varying rotation numbers. In the case $R=$ $2 \Omega / S=-1 / 2$ the rotation strongly destabilized the flow resulting in a much more rapid growth of the turbulent velocity fluctuations than in the non-rotating case. In two cases, $R=-3 / 2$ and $R=1 / 2$, the rotation stabilized the flow leading to a decay of the turbulent kinetic energy. The anisotropy of the turbulence was also strongly affected by the rotation. Predictions of RDT agreed in general quite well with the fully non-linear DNS, but a closer examination revealed that, even though the applied shear rate was high, non-linear effects gained in importance during the simulations and sometimes clearly affected the flow. At $R=0$, for instance, the kinetic energy has an exponential growth at larger $S t$ values in the DNS whereas the RDT predicts an approximately linear growth. The importance of the non-linear processes was quite apparent in the development of the slow pressure-strain correlations associated with non-linear processes, which were in a couple of cases of the same order or larger than the rapid pressure-strain correlations associated with linear processes. The strongest non-linear effects were observed at $R=0$ where the transverse velocity fluctuations were much more intense in the DNS than in a simulation without the non-linear terms.

In the non-rotating case the streamwise velocity field had a streak-like structure and the vorticity field showed streamwise vortex tubes and some hairpin-like vortex structures, although it changed later in the DNS because then the long streamwise vortices disappeared and the vorticity field became more isotropic. At earlier times these structures are, indeed, quite similar as in boundary layers. The structures drastically changed, however, under the influence of rotation. In the case of zero absolute mean vorticity $R=-1$ the transverse velocity field and not the streamwise velocity field had a streak-like structure and very elongated streamwise vortex tubes were observed. An examination of the helicity showed a predominant swirling motion in the streamwise vortices with a small
streamwise velocity component at $R=-1$ whereas at $R=0$ the helical motion in the streamwise vortices had a large streamwise component.

The results presented regarding the influence of rotation on passive scalar transport in a homogeneous shear flow show interesting effects of rotation on turbulent scalar transport. Scalar-velocity correlations were significantly affected and could strongly be reduced or enhanced by rotation. The direction of the turbulent scalar flux also showed large variations, depending on the rotation number. It was shown that the scalar flux vector align itself with the direction of the strongest turbulent velocity fluctuations at different rotation numbers. Some of the phenomena, like the influence of rotation on the scalar flux direction, could be fairly well predicted by RDT revealing that linear processes are important for scalar transport in rapidly sheared flows, but the scalarvelocity correlations showed quite large differences in the RDT and DNS in a couple of cases, especially for the transverse scalar-velocity correlation at $R=0,-1 / 2$ and -1 , proving the importance of non-linear processes for scalar transport.

The ratio of turbulent time scale versus scalar time scale, characterizing small-scale mixing, was affected by rotation as well. In the case that rotation destabilized the flow, the ratio of time scales was smaller and at $R=-1 / 2$ larger than at $R=0$.

The statistics of the Reynolds stresses and pressure-strain correlations presented in this study are useful for modelling of turbulent shear flows where rotation or streamline curvature plays a role, or for modelling of rapidly distorted and rotating flows. Scalar transport modelling in rotating turbulent flows has been relatively neglected, although it can be argued that is of relevance in many practical situations. This study has therefore important implications because it has clearly been proven that the effect of rotation on scalar transport is significant and must be taken into account properly. The concept of gradient diffusion fails to describe the variation of the scalar flux direction and neither does the assumption of constant turbulent Schmidt number hold with varying rotation numbers. If one tries to model scalar transport in rotating flows, it is thus recommendable to consider algebraic scalar flux models, because they are in principal able to take into account the influence of rotation. They have only been tested for non-rotating cases so far, but it of interest to investigate their ability to predict turbulent scalar transport in rotating flows.

The author wishes to thank Anshu Dubey and the Astronomy \& Astrophysics department of the University of Chicago for making their numerical code available, and Arne Johansson, Erik Lindborg, Stefan Wallin and professor A. Yoshizawa for the valuable discussions and comments. The financial support from the Swedish Research Council and the Göran Gustafsson Foundation is gratefully acknowledged.

## Appendix A. Analysis of the stability of rotating homogeneous shear flows using the simplified Reynolds stress equations

It is enlightening to consider the simplified Reynolds stress equations because these explain at least in a qualitative manner some of the observed phenomena. A more extensive analysis using the simplified Reynolds stress equations is given by Tritton (1992), see also Leblanc \& Cambon (1997). The simplified Reynolds stress equations read

$$
\begin{gather*}
\frac{\partial{\bar{u} u_{1}}_{1}}{\partial t^{*}}=-2{\overline{u_{1} u_{3}}(1+R)}_{\frac{\partial \bar{u}_{2} u_{2}}{\partial t^{*}}=0}=0 . \tag{A1}
\end{gather*}
$$

$$
\begin{align*}
& \frac{\partial{\bar{u} u_{3}}_{3}}{\partial t^{*}}=2{\overline{u_{1} u_{3}}} R  \tag{A3}\\
& \frac{\partial \overline{u_{1} u_{3}}}{\partial t^{*}}={\overline{u_{1} u_{1}}} R-{\overline{u_{3} u_{3}}}_{3}(1+R) \tag{A4}
\end{align*}
$$

where $t^{*}=S t$. The pressure-strain correlations and the dissipation terms are neglected in this analysis. The equations without the pressure terms show in a quantitative way the role of the Coriolis term regarding the stability of the flow because the spectral modes which are mostly affected by the Coriolis force are the spanwise modes (Leblanc \& Cambon 1997) for which the pressure effects vanishes (Salhi et al. 1997). However, the influence of the pressure is not negligible as seen in the present DNS and RDT and shown by Salhi \& Cambon (1997).

Combining the simplified Reynolds stress equations we can derive for $\bar{u}_{1} u_{3}$ and the turbulent kinetic energy, respectively

$$
\begin{gather*}
\frac{\partial^{2} \bar{u}_{1} u_{3}}{\partial t^{* 2}}=-4{\bar{u} 1_{1} u_{3}}^{(1+R) R}  \tag{A5}\\
\frac{\partial K}{\partial t^{*}}=-\bar{u}_{1} u_{3} \tag{A6}
\end{gather*}
$$

Considering equation (A 5) three different case can be distinguished: $R(R+1)>0$, $R(R+1)=0$ and $R(R+1)<0$.

If $R(R+1)>0$, i.e. $R>0$ or $R<-1$, there is a wave-like solution

$$
\begin{equation*}
\overline{u_{1} u_{3}} \sim \exp \left(2 i \sqrt{R(R+1)} t^{*}\right) \tag{A7}
\end{equation*}
$$

The other Reynolds stress components have then also an oscillatory behaviour. The period of the oscillations is $\pi / \sqrt{R(R+1)}$. For $R=1 / 2$ and $R=-3 / 2$ the period is 3.6.

If $R(R+1)=0$, i.e. $R=0$ or $R=-1$, the solution is given by $\bar{u}_{1} u_{3}=-c_{1} t^{*}-c_{2}$ where $c_{1}, c_{2}$ are constants. The growth of the kinetic energy is then given by $K=$ $\frac{1}{2} c_{1} t^{* 2}+c_{2} t^{*}+K(t *=0)$ and is thus algebraic. If $R=0, \bar{u}_{1} u_{1}$ has an algebraic growth and $\bar{u}_{3} u_{3}$ is constant and if $R=-1$ it is the other way around.

If $R(R+1)<0$, e.g. $-1<R<0$, the solution is

$$
\begin{equation*}
{\overline{u_{1} u}}_{3}, K \sim \exp \left(2 \sqrt{-R(R+1)} t^{*}\right) \tag{A8}
\end{equation*}
$$

and the kinetic energy has thus an exponential growth. The fastest growth occurs when $R=-1 / 2$, then $K \sim \exp \left(t^{*}\right)$.

## Appendix B. Some details of the RDT computations

The solution of the set of linear equations (4.3) is

$$
\begin{equation*}
\hat{u}_{i}(\mathbf{k}, t)=\exp \left(-\frac{\nu k^{2}}{S} f(\mathbf{k} / k, S t)\right) A_{i j}(\mathbf{k} / k, t) \hat{u}_{j}\left(\mathbf{k}^{\prime}, t=0\right) \tag{B1}
\end{equation*}
$$

where

$$
f(\mathbf{k} / k, S t)=S t\left(1+\frac{k_{1} k_{3}}{k^{2}} S t+\frac{k_{1}^{2}}{k^{2}} \frac{(S t)^{2}}{3}\right)
$$

The matrix $A_{i j}$ obeys the equation

$$
\begin{equation*}
\frac{\mathrm{d} A_{i j}}{\mathrm{~d} t^{*}}=-\mathcal{L}_{i q} A_{q j} \tag{B2}
\end{equation*}
$$

where $\mathcal{L}_{i j}$ is defined in (4.3). The initial conditions are $A_{i j}\left(\mathbf{k}^{\prime}, t=0\right)=\delta_{i j}-k_{i}^{\prime} k_{j}^{\prime} / k^{\prime 2}$ where $k_{i}^{\prime}=k_{i}(t=0)$ is the initial wave vector.

The time development of the Reynolds stress tensor is now given by

$$
\begin{equation*}
\overline{u_{i} u_{j}}=\int A_{i p} A_{j q}\left(\delta_{p q}-\frac{k_{p}^{\prime} k_{q}^{\prime}}{k^{\prime 2}}\right) \frac{E\left(k^{\prime}\right)}{4 \pi k^{\prime 2}} \exp \left(-2 \frac{\nu k^{2}}{S} f(\mathbf{k} / k, S t)\right) \mathrm{d}^{3} \mathbf{k}^{\prime} \tag{B3}
\end{equation*}
$$

Using a spherical coordinate system $\left(k^{\prime}, \theta, \phi\right)$ for $\mathbf{k}^{\prime}$ and $E\left(k^{\prime}\right)$ given by (4.6), equation (B3) can be rewritten as

$$
\begin{align*}
\overline{u_{i} u_{j}}= & \frac{C}{4 \pi} \int_{0}^{2 \pi} \int_{0}^{\pi} A_{i p} A_{j q}\left(\delta_{p q}-\frac{k_{p}^{\prime} k_{q}^{\prime}}{k^{\prime 2}}\right) \\
& {\left[\int_{0}^{\infty} k^{\prime 2} \exp \left(-2 k^{\prime} l-2 \frac{\nu k^{2}}{S} f(\mathbf{k} / k, S t)\right) \mathrm{d} k^{\prime}\right] \sin \theta \mathrm{d} \theta \mathrm{~d} \phi } \tag{B4}
\end{align*}
$$

The integral between brackets can be solved analytically. The solution is

$$
-\frac{b^{3}}{4 l^{3}}\left(-2 b+\sqrt{\pi}\left(2 b^{2}+1\right) \mathrm{e}^{b^{2}} \operatorname{erfc} b\right), \quad b^{2}=\frac{1}{2} S^{*} \frac{k^{\prime 2}}{k^{2}} f(\mathbf{k} / k, S t)
$$

where erfc $b$ is the complementary error function. The expression for the pressure-strain correlation, which is by definition the rapid pressure-strain correlation, reads

$$
\begin{align*}
\Pi_{i j}= & \frac{C}{4 \pi} \int_{0}^{2 \pi} \int_{0}^{\pi} \frac{1}{k^{2}}\left(\left[(S+\Omega) k_{1} A_{3 q}-\Omega k_{3} A_{1 q}\right]\left(k_{j} A_{i p}+k_{i} A_{j p}\right)\right)\left(\delta_{p q}-\frac{k_{p}^{\prime} k_{q}^{\prime}}{k^{\prime 2}}\right) \\
& {\left[\int_{0}^{\infty} k^{\prime 2} \exp \left(-2 k^{\prime} l-2 \frac{\nu k^{2}}{S} f(\mathbf{k} / k, S t)\right) \mathrm{d} k^{\prime}\right] \sin \theta \mathrm{d} \theta \mathrm{~d} \phi } \tag{B5}
\end{align*}
$$

with the same analytical solution for the integral between brackets as in (B 4).
If there are no initial scalar fluctuations the solution of equation (4.4) for the scalar is

$$
\begin{equation*}
\hat{\theta}_{i}(\mathbf{k}, t)=\exp \left(-\frac{\kappa k^{2}}{S} f(\mathbf{k} / k, S t)\right) B_{j}(\mathbf{k} / k, t) \hat{u}_{j}\left(\mathbf{k}^{\prime}, t=0\right) \tag{B6}
\end{equation*}
$$

where $\theta_{i}$ is the scalar with a mean gradient $\mathbf{G}$ in the $x_{i}$-direction. For $\theta_{i}$ the vector $B_{j}$ is the solution of

$$
\begin{equation*}
\frac{\mathrm{d} B_{j}}{\mathrm{~d} t^{*}}=-\frac{G}{S} A_{i j} \exp \left(-(\nu-\kappa) \frac{k^{2}}{S} f(\mathbf{k} / k, S t)\right) \tag{B7}
\end{equation*}
$$

where $G$ is the norm of the mean scalar gradient.
The scalar flux is now derived from

$$
\begin{equation*}
\overline{u_{j} \theta_{i}}=\int A_{j p} B_{q}\left(\delta_{p q}-\frac{k_{p}^{\prime} k_{q}^{\prime}}{k^{\prime 2}}\right) \frac{E\left(k^{\prime}\right)}{4 \pi k^{\prime 2}} \exp \left(-(\nu+\kappa) \frac{k^{2}}{S} f(\mathbf{k} / k, S t)\right) \mathrm{d}^{3} \mathbf{k}^{\prime} \tag{B8}
\end{equation*}
$$

and the scalar variance from

$$
\begin{equation*}
\overline{\theta_{i}^{2}}=\int B_{p} B_{q}\left(\delta_{p q}-\frac{k_{p}^{\prime} k_{q}^{\prime}}{k^{\prime 2}}\right) \frac{E\left(k^{\prime}\right)}{4 \pi k^{\prime 2}} \exp \left(-2 \frac{\kappa k^{2}}{S} f(\mathbf{k} / k, S t)\right) \mathrm{d}^{3} \mathbf{k}^{\prime} \tag{B9}
\end{equation*}
$$

The integrals in (B 8) and (B 9) can then be simplified in the same way as in (B 4) if $S c=1$.

For the time integration of (B 2) and (B 7), the spatial integration of (B 4), (B 5), (B 8) and (B 9) and for the computation of erfc $b$ optimized numerical libraries have been used.

Analytical solutions for (4.3) and (4.4) for homogeneous shear flow without rotation are presented in Rogers (1991). In that article also short-time and long-time approximations of the Reynolds stresses, scalar fluxes and scalar variances are presented for the case without viscosity and diffusivity.

## REFERENCES

Abe, K., Kondoh, T., Nagano, Y. 1996 A two-equation heat transfer model reflecting secondmoments closures for wall and free turbulent flows. Int. J. Heat Fluid Flow 17, pp. 228-237.
Alvelius, K., Johansson, A.V. 1999 Direct numerical simulations of rotating channel flow at various Reynolds numbers and rotation numbers. In Alvelius, K. PhD-thesis, Department of Mechanics, KTH, Stockholm, Sweden.
Bardina, J., Ferziger, J.H., Reynolds, W.C. 1983 Improved turbulence models based on large-eddy simulation of homogeneous incompressible turbulent flow. Tech. Rep. TF-19. Stanford University.
Bech, K.H., Andersson, H.I. 1997 Turbulent plane Couette flow subject to strong system rotation. J. Fluid Mech. 347, pp. 289-314.
Cambon, C., Benoit, J.-P., Shao, L., Jacquin, L. 1994 Stability analysis and large-eddy simulation of rotating turbulence with organized eddies. J. Fluid Mech. 278, pp. 175-200.
Chong, M.S., Soria, J., Perry, A.E., Chacin, J., Cantwell, B.J., Na, Y. 1998 Turbulent structures of wall-bounded shear flows found using DNS data. J. Fluid Mech. 357, pp. 225-247.
Ferchichi, M., Tavoularis, S. 2002 Scalar probability density function and fine structure in uniformly sheared turbulence. J. Fluid Mech. 461, pp. 155-182.
Gatski, T.B., Wallin, S. 2004 Extending the weak-equilibrium condition for algebraic Reynolds stress models to rotating and curved flows. J. Fluid Mech. 518, pp. 147-155.
Högström, C.M., Wallin, S., Johansson, A.V. 2001 Passive scalar flux modelling for CFD. In Proc. of Turbulence and Shear Flow Phenomena II, Stockholm, June 27-29.
Kida, S., Tanaka, M. 1994 Dynamics of vortical structures in a homogeneous shear flow. J. Fluid Mech. 274, pp. 43-68.
Kim, J. 1989 On the structure of pressure fluctuations in simulated turbulent channel flow. $J$. Fluid Mech. 205, pp. 421-451.
Kim, J., Lim, J. 2000 A linear process in wall-bounded turbulent shear flows. Phys. Fluids 12, pp. 1885-1888.
Komminaho, J., Skote, M. 2002 Reynolds stress budgets in Couette and boundary layer flows. Flow, Turbul. Combust. 68 pp. 167-192.
Leblanc, S., Cambon, C. 1997 On the three-dimensional instabilities of plane flows subjected to Coriolis force. Phys. Fluids 9, pp. 1307-1316.
Lee, M.J., Kim, J., Moin, P. 1990 Structure of turbulence at high shear rate. J. Fluid Mech. 216, pp. 561-583.
Moser, R.D., Kim, J., Mansour, N.N. 1999 Direct numerical simulation of turbulent channel flow up to $R e_{\tau}=590$. Phys. Fluids 11, pp. 943-945.
Nagano, Y., Hattori, H. 2003 Direct numerical simulation and modelling of spanwise rotating channel flow with heat transfer. J. Turbulence 4, 010
Poroseva, S.V., Kassinos, S.C., Langer, C.A., Reynolds, W.C. 2002 Structure-based turbulence model: Application to a rotating pipe flow. Phys. Fluids 14, pp. 1523-1532.
Rogers, M.M. 1991 The structure of a passive scalar field with a uniform mean gradient in rapidly sheared homogeneous turbulent flow. Phys. Fluids 3, pp. 144-154.
Rogers, M.M., Mansour, N.N., Reynolds, W.C. 1989 An algebraic model for the turbulent flux of a passive scalar. J. Fluid Mech. 203, pp. 77-101.
Rogers, M.M., Moin, P. 1987 The structure of the vorticity field in homogeneous turbulent flows. J. Fluid Mech. 176, pp. 33-66.
Rogers, M.M., Moin, P., Reynolds, W.C. 1986 The structure and modelling of the hydrodynamic and passive scalar fields in homogeneous turbulent shear flow. Dept. Mech. Engng Rep. TF-25. Stanford University. Stanford. California.
Salhi, A. 2002 Similarities between rotation and stratification effects on homogeneous shear flow. Theor. Comp. Fluid Dyn. 15, pp. 339-358.
Salhi, A., Cambon, C. 1997 An analysis of rotating shear flow using linear theory and DNS and LES results. J. Fluid Mech. 347, pp. 171-195.
Salhi, A., Cambon, C., Speziale, C.G. 1997 linear stability analysis of plane quadratic flows in a rotating frame with applications to modeling. Phys. Fluids 9, pp. 2300-2309.

Speziale, C.G., Younis, B.A., Berger, S.A. 2000 Analysis and modeling of turbulent flow in an axially rotating pipe. J. Fluid Mech. 407, pp. 1-26.
Tanaka, M., Yanase, S., Kida, S., Kawahara, G. 1998 Vortical structures in rotating uniformly sheared turbulence. Flow, Turbul. Combust. 60 pp. 301-332.
Tavoularis, S., Corrsin, S. 1981 Experiments in nearly homogeneous turbulent shear flow with a uniform mean temperature gradient. Part 1. J. Fluid Mech. 104, pp. 311-347.
Tavoularis, S., Karnik, U. 1989 Further experiments on the evolution of turbulent stresses and scales in uniformly sheared turbulence. J. Fluid Mech. 204, pp. 457-478.
Tritton, D.J. 1992 Stabilization and destabilization of turbulent shear flow in a rotating fluid. J. Fluid Mech. 241, pp. 503-523.

Wallin, S., Johansson, A.V. 2002 Modelling streamline curvature effects in explicit algebraic Reynolds stress models. Int. J. Heat Fluid Flow 23, pp. 721-730.
Wikström, P.M., Wallin, S., Johansson, A.V. 2000 Derivation and investigation of a new explicit algebraic model for the passive scalar flux. Phys. Fluids 12, pp. 688-702.
Wu, H., Kasagi, N. 2004 Turbulent heat transfer in a channel flow with arbitrary directional system rotation. Int. J. Heat Mass Transf. 47, pp. 4579-4591.
Zhou, J., Adrain, R.J., Balachandar, S., Kendall, T.M. 1999 Mechanisms for generating coherent packets of hairpin vortices in channel flow. J. Fluid Mech. 387, pp. 353-396.

