



## Radial Velocity Challenge at the AIUC

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## **AIUC Instrumentation**



#### **PUCHEROS**



#### ESO 1m, La Silla Observatory

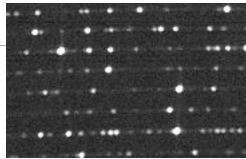
#### MOONS

**FIDEOS** 



## PUCHEROS & FIDEOS

Table 1. Main characteristic of PUCHEROS	
<b>Spectral resolution</b> $\lambda/\Delta\lambda$ (average)	18000
Spectral coverage (single shot)	390 – 730 nm –
Orders	42
Aperture on sky (diameter)	4.2 arcsec
Detector	FLI-PL1001E 1K, 1K x 1K, 24μm
Limiting mag. (1 h, S/N= 20)	V= 8
Total efficiency	< 5%
Calibration Method	Individual Thorium-Argon Lamp



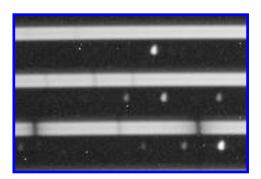
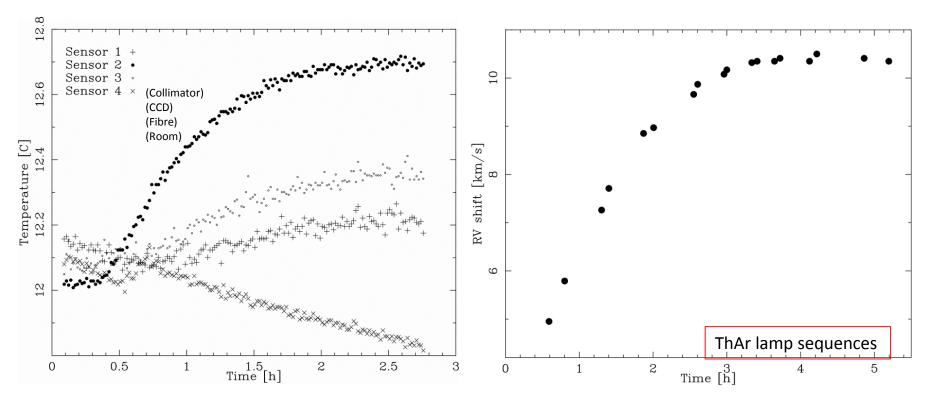


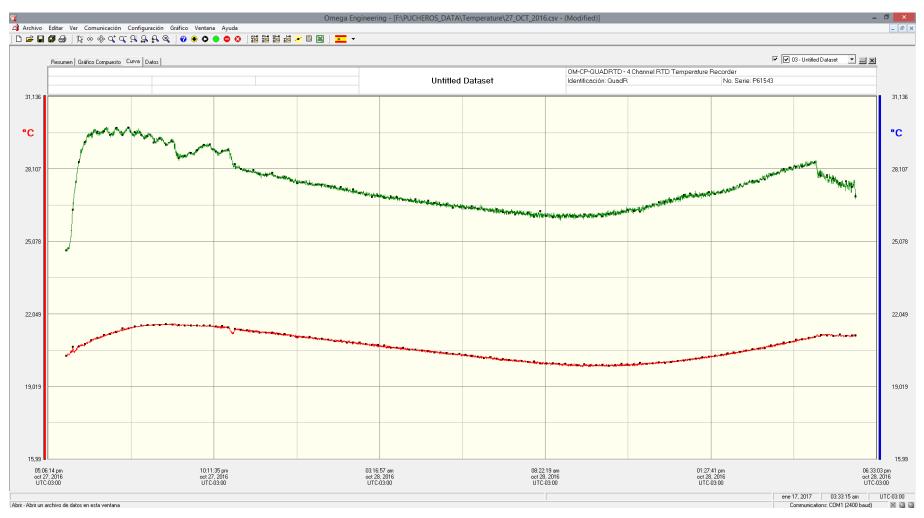
Table 2. Main characteristic of FIDEOS	
Spectral resolution $\lambda/\Delta\lambda$ (average)	43000
Spectral coverage (single shot)	400 – 700 nm
Orders	52
Aperture on sky (diameter)	1.87 arcsec
Detector	FLI-PL230, 2K x 2K, 15μm
Limiting mag. (1 h, S/N= 20)	V= 12
Total efficiency	~10%
Calibration Method	Simultaneous Thorium-Argon Lamp

## **PUCHEROS Stability**



Temperature measured in four points of PUCHEROS versus time. Sensors 1, 2 and 3 are located on the optical bench, respectively, at the position of the collimator mirror, CCD camera and fibre optics. Sensor 4 is on the external surface of the enclosure. The effect of turning on the CCD is clearly observable in the temperature measured by sensor 2. (Vanzi et al. 2012)

### **Temperatures on PUCHEROS**



The temperature of the instrument is dominated by environmental conditions and shutter effects. Environmental temperature (green) and instrument (red).

# Improvement of FIDEOS respect to PUCHEROS

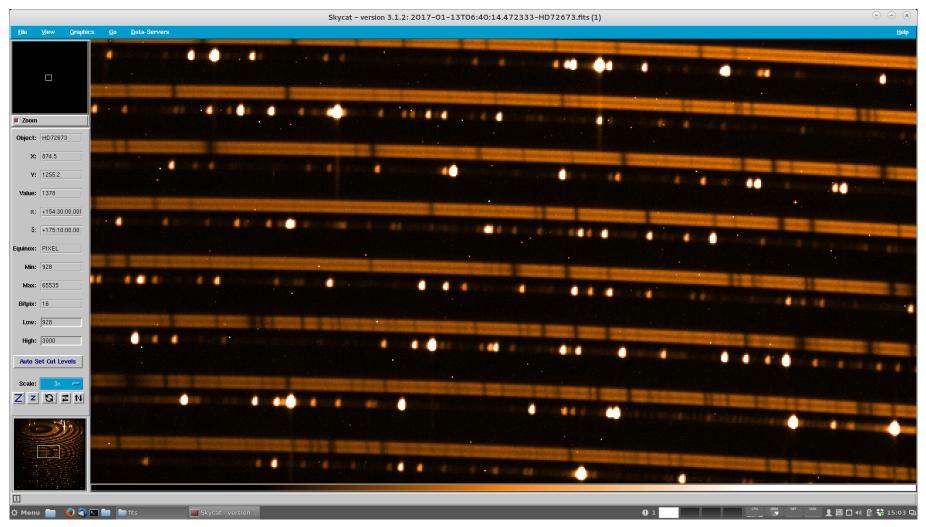
Simultaneous Calibration Th-Ar.

Temperature control.

Heat extraction liquid cooling (chiller) vs air flow.

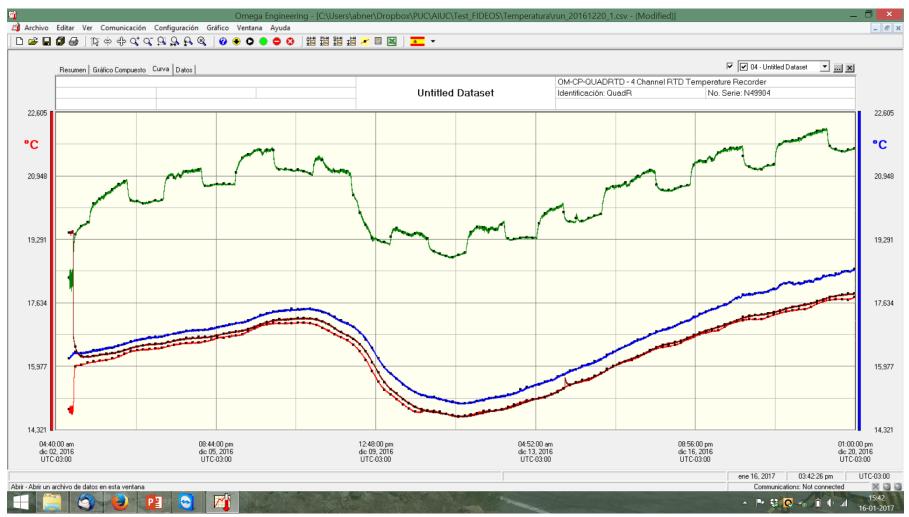
Octagonal fiber.

### Example of spectrum with FIDEOS



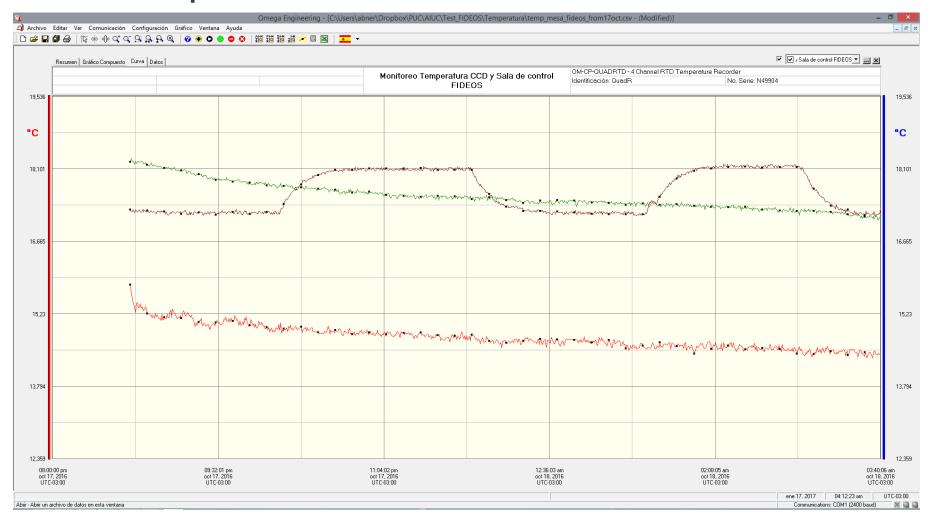
Simultaneous calibration with ThAr lamp and image slicer.

#### Monitoring temperatures



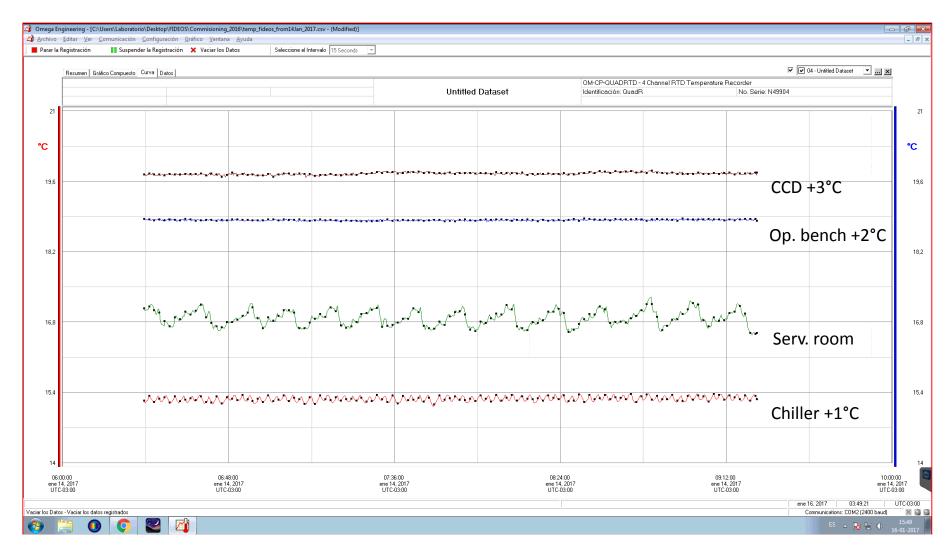
Temperatures on FIDEOS without control. Day and night cycle is observed. Service room (instrument next door) (green); Instrument (blue); CCD (brown) and Chiller (red).

### **Temperatures FIDEOS**



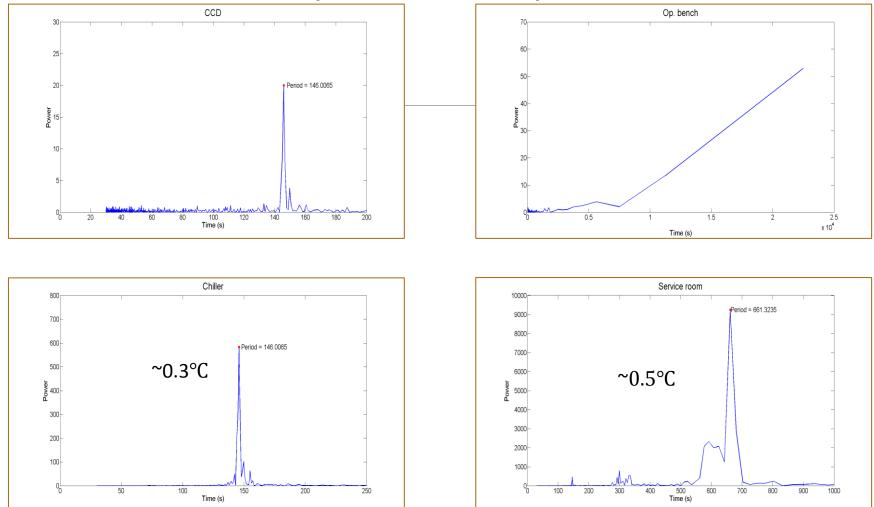
Temperatures on FIDEOS. Upper (brown line) it is observed electronic heating (CCD) when exposures are taken.

## Thermalized condition



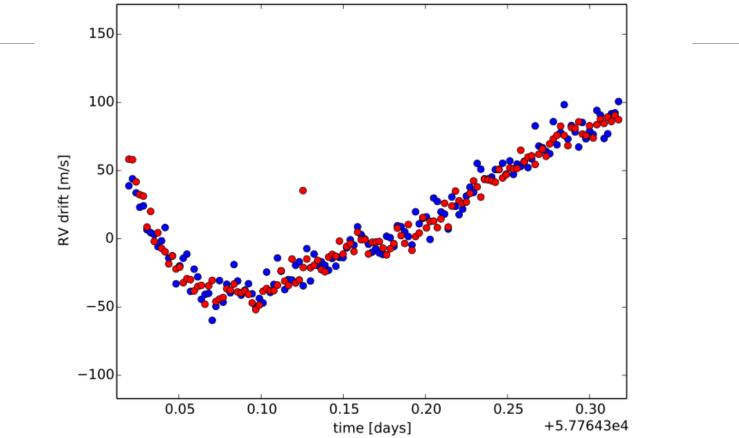
After thermal control it is observed minimal changes in the temperature of CCD and instrument (op. bench).

#### Fourier analysis of temperatures



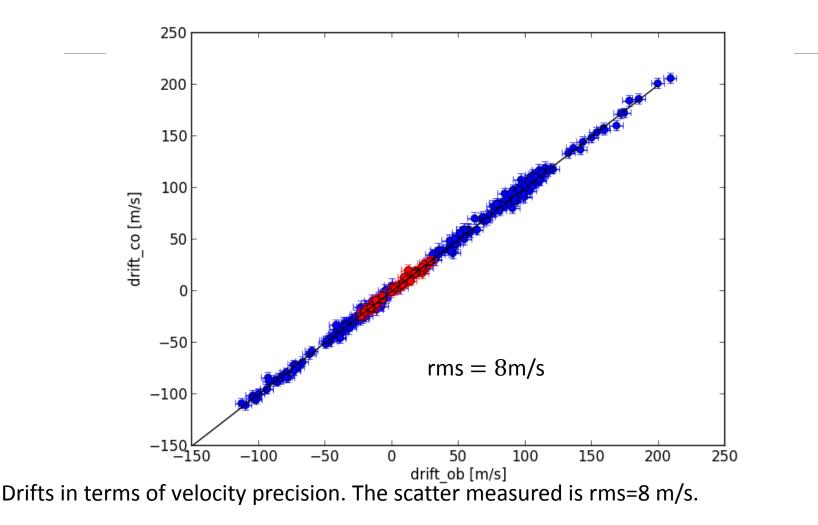
Upper right: The CCD present a thermal cycle of 0.1 °C which correspond to the cooling cycle (bottom right). Upper left: The instrument (op. bench) do not present any dependency with the thermal cycle of the service room neither the Chiller cycle.

## Drifts of Science vs Comparison



Drifts of the spectral lines from the ThAr lamp sequences. Red and blue dots are the observed (science) fiber and the comparison fiber (simultaneous calibration).

## Drifts of Science vs Comparison



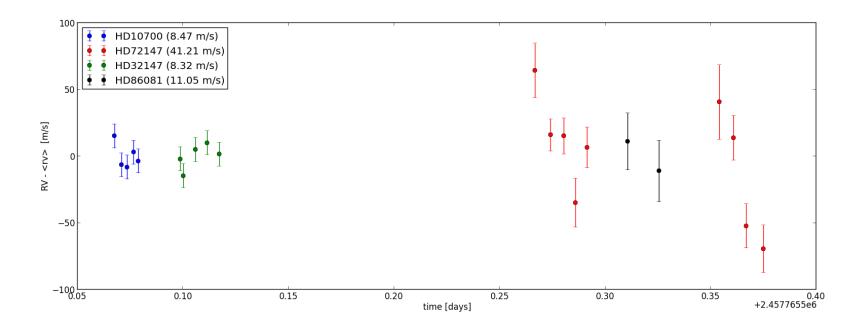
## FIDEOS Calibration plan

• ThAr + ThAr

• Flat + Flat

Simultaneous





Few spectra of RV standars. HD10700 and HD32147 show a RV dispersion of ~8 m/s in agreement with the expected.

## Comparison with theoretical expectation

$$\sigma(m/s) = \frac{C}{R^{3/2}\sqrt{B(A)} S/N}$$
<sup>(1)</sup>

C calibrated with HARPS.

R = 45000

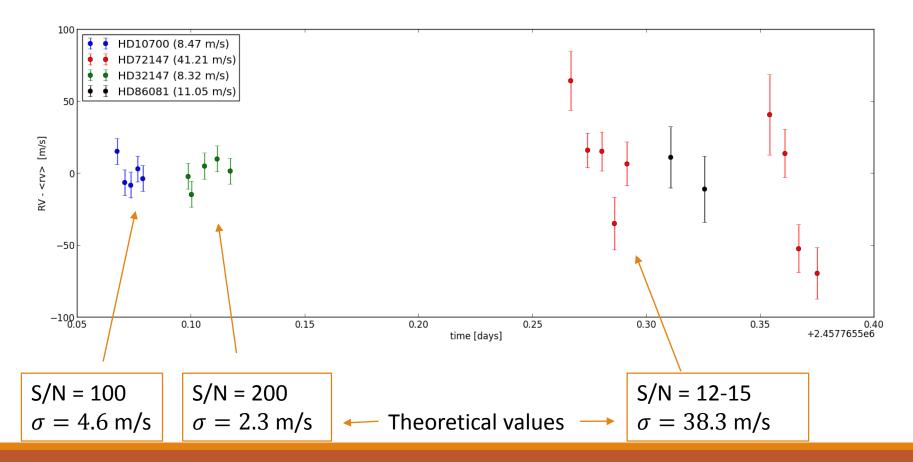
*B* = 3000

*S/N = 100* 

#### $\sigma$ = 4.6 m/s

Reference value for RV precision expected on FIDEOS for a S/N  $\sim$  100.

## Radial Velocity results



## What next?

• To improve the temperature control.

Seasonal change in the temperature and electronic heating are observed yet.

• To improve and stabilize guiding.

This help us to improve the efficiency of the system.

• To explore alternative wavelength reference (Etalon, Iodine).

## Summary

- PUCHEROS was the first step in the development of spectrographs at the AIUC.
- FIDEOS has been intended to be RV precision better than 10 m/s with a simultaneous ThAr calibration lamp.
- Important improvement in the stability and RV precision has been done during the commissioning of FIDEOS.
- Early results indicate that we are capable to achieve RV precision ~8 m/s or even better. Now we are working to get similar results in long term RV stability.