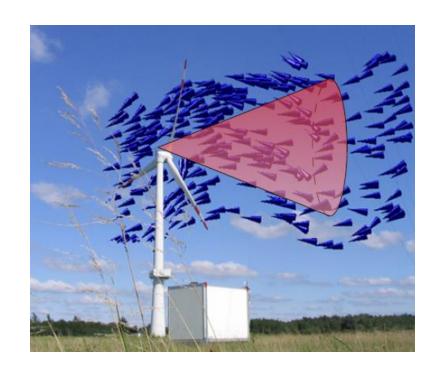




Motivation for Lidar Assisted Control



- > wind is changing over space and time
- > conventional control reacts after impact
- > lidar technology provides wind preview
- > better control performance is expected



- ➤ Biggest market: one lidar for every wind turbine!
- ➤ Development over the last years showed: It's not a wonder weapon, quite complex, but still promising!
- ➤ Main idea for working group: make application easy!



Key facts about your working group

Objectives

- Push the technology by transparency and Open Source Tools
- Recommended Practices on Lidar-Assisted Control

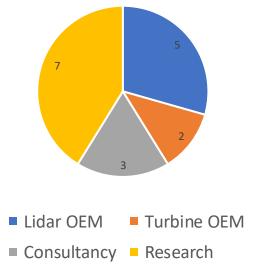
Approach

- Monthly conference calls
- Work together on code and documents
- Webinars

Participants:

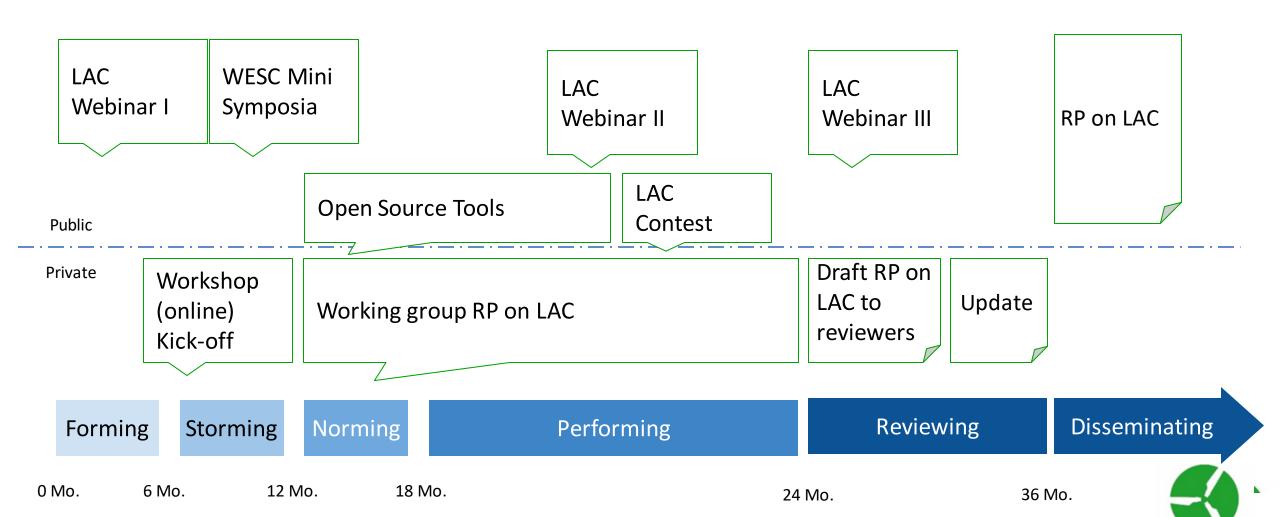
- 17 active members
- From 7 countries (China, Denmark, France, Germany, Italy, Japan, UK)
- 12 more in mailing list







LAC Working Group



iea wind

Highlight 1: Lunch Seminar





Slides can be found at Zenodo: https://doi.org/10.5281/zenodo.7683412



Highlight 2: Mini Symposia at the WESC



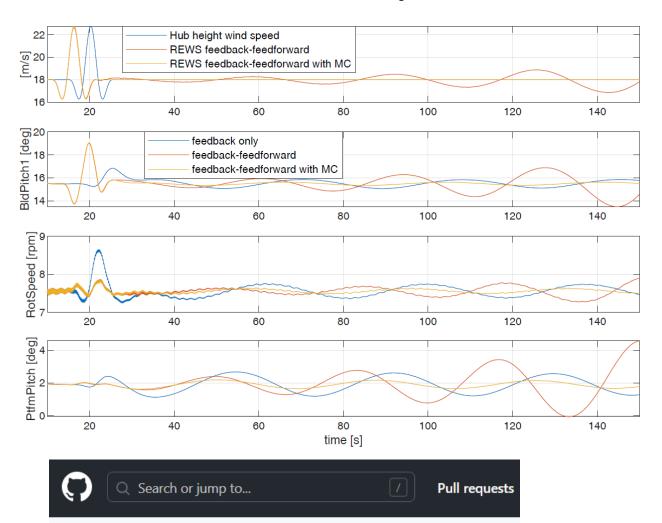
Details see presentation of Eric Simley from Day 1



4.6 Mini Symposia: IEA Wind Task 52: Lidar-Assisted Control, Turbulence Estimation, and Digitalization



Highlight 3: Open Source LAC Tools



☐ IEAWindTask52 / LidarAssistedControl (Public)

- Open Source code of
 - Very detailed lidar simulator
 - Modified feedback controller (ROSCO)
 - Lidar data processing
 - Feedforward controller
 - 4 Examples with coherent and turbulent wind
- Published at GitHub and presented at ACC 2023





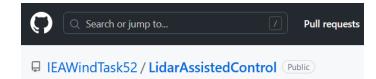






Plans for next 12 months

- 2. Webinar: Ideas are very welcome!
- Organize workshop with Task 44: Wind Farm Flow Control
- Open Source tools
 - Extend it to make it more useful for a broader audience



measurements

Control inputs

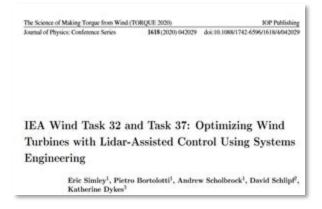
- Main motivation: improved transparency of performance for different methods
- Contest
 - Objective: benchmarking, increase motivation for LAC (industry and research)
 - Different Categories: bottom fixed / floating wind
 - Common cost function as evaluation

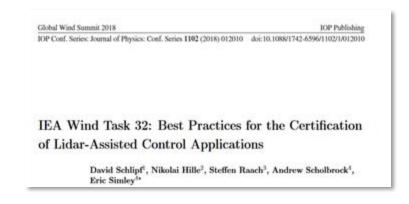
$$L(x(t), u(t)) = Q_1 \qquad (\Omega(t) - \Omega_{rated})^2 + Q_2 \qquad (P_{el}(t) - P_{rated})^2 + Q_3 \qquad \dot{x}_T^2(t) + R_1(v_0(t)) \qquad \dot{\theta}^2(t) + R_2 \qquad \dot{M}_g^2(t)$$

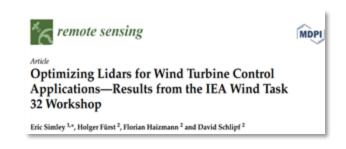


Plans for next 12 months

- "Recommended Practices" on LAC
 - Building up on existing documents
 - Define scope content
 - Define connection other documents (load standards, measurement standards)
 - First in person meeting / workshop









Strategy and context

How does your working group address the overall theme of the task

"Large-Scale Deployment of Wind Lidar"?

- Tools and RP help to address complex task of LAC!
- Transparency about potential foster decisions for developers!



Let's work together on getting a lidar on every wind turbine!

