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Abstract: This work is focused on designing and implementing a decimation filter specifically intended for use in hearing aid applications. The filter utilizes distributed arithmetic (DA) and is described in this brief. Our proposal involves the development of a reconfigurable finite impulse response (FIR) filter, which utilizes both offset binary code (OBC) and binary distributed arithmetic (DA) techniques. Additionally, we utilize canonic signed digit (CSD) representation to develop decimation filters, which include the CIC filter, half band filter, and corrector filter. In this work, we have implemented a decimation filter using Matlab Simulink. We have utilized Xilinx Vivado 19.2 to execute the FIR filters, binary DA filters, and OBC DA-based filters. Our focus is on implementing these filters using VLSI architecture, in order to achieve low power consumption, reduced latency, less area, and fast speed.

Keywords: FIR filters, CIC filters, VLSI architecture, Verilog.

I. INTRODUCTION

Due to their ability to require less hardware and process data faster, digital filters are becoming increasingly common in wireless and audio applications. While only about 5% of the world's population with hearing loss use hearing aids, designing and implementing a high-speed, low-power decimation filter using VLSI architecture can be challenging. Achieving the necessary performance characteristics requires careful consideration of several important factors, including filter architecture and digital filter design methodologies. Once these factors have been addressed, the next step is to implement the filters using VLSI technology. By balancing all of these factors, it is possible to achieve the necessary performance characteristics for a range of hearing aid applications. There are two main categories of hearing aids. They are analogue hearing aids and digital hearing aids. The input signal is converted to an electrical signal by analogue

Manuscript received on 26 March 2023 | Revised Manuscript received on 05 April 2023 | Manuscript Accepted on 15 May 2023 | Manuscript published on 30 May 2023.

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hearing aids. In contrast, digital hearing aids convert the incoming signal to binary numerical information. Because they are more adaptable and self-adjusting, digital hearing aids are generally preferred over analogue ones. Normal human hearing ranges from 20Hz to a maximum of 20KHz. The human ear often responds more reliably to auditory signals in the 1KHz to 4KHz frequency range. The block diagram of a hearing aid is displayed in Fig.1. Preamplifier, A/D converter, digital decimation filter, and D/A converter are all included in the block diagram. The proposed architecture in this work is created to minimize the amount of hardware needed, the amount of power used, and the latency. Using CSD representation, a half band FIR filter and a corrector FIR filter are developed and created.



Fig.1. Block diagram of hearing aid

II. DECIMATION FILTER

Decimation is the conversion of a signal's sample frequency to a lower sampling frequency. Down sampling is another name for it. A decimation filter [1], which is a sort of digital filter, lowers a signal's sampling rate by a factor of m, where m is an integer. Decimation filters are frequently used in hearing aid applications to lower the signal's data rate, which can help to increase battery life and lower the device's overall power usage. Fig.2. shows the block diagram of a digital decimation filter. The five-stage comb filter, half band FIR filter, and corrector FIR filter make up the bulk of the digital decimation filter (divide by 16). Comb filters have an input frequency of 1.28MHz and an output frequency of 80KHz. They are used as inputs for half-band FIR filters, which create an output frequency of 40KHz, and corrector FIR filters, which produce an output frequency of 4KHz.

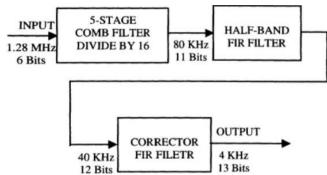


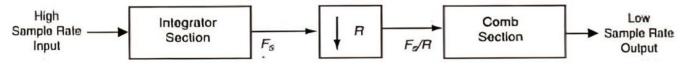
Fig. 2 (Frequency response of half band filter)

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Retrieval Number: 100.1/ijrte.A75640512123 DOI: 10.35940/ijrte.A7564.0512123 Journal Website: www.ijrte.org

The initial block of a digital decimation filter is called a CIC (Cascade Integrated Comb), and it is made up of an integrator section and a comb section. The comb carries out differentiation on the signal, while the integrator carries out signal integration. Electronic equipment use CIC filters for a variety of purposes, including frequency selection and extensive sampling. Unlike to conventional digital filters, CIC filters do not require multipliers or coefficient storage components. Hence, operating at a fast rate of speed can be effective. Fig.3. is the block diagram of CIC filter. The second block of the digital decimation filter is the half band

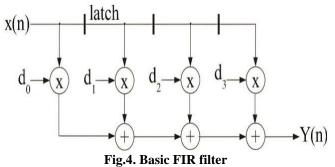
FIR filter. Half band FIR filter receives the CIC's decreased frequency and processes it. A half-band filter is a low pass filter that decreases the maximum bandwidth of sampled data by a factor of 2. As a result, the frequency is further decreased before being transmitted to the corrector filter. The third block in the digital decimation filter is the corrector FIR filter. Unwanted signals are eliminated using the corrector FIR filter. The corrector filter receives the lowered frequency from the half band FIR filter and outputs it at 4KHz. Canonical signed digit architecture was used in the construction of these half band and corrector filters[5].



Decimation Filter
Fig.3. Block diagram of CIC filter

III. DIGITAL FIR FILTER

One of the key building blocks in Digital Signal Processing (DSP) systems is the Finite Impulse Response (FIR) digital filter. FIR filters are commonly used for a variety of signal processing applications due to their linear phase response and ability to achieve high selectivity. However, implementing FIR filters in real-time can be a challenge as the number of Multiply Accumulate (MAC) operations required for each filter increases linearly with filter order. While MAC operations can consume a significant amount of resources, techniques such as pipelining and parallelization can be used to optimize MAC performance and reduce power consumption. Fig.4. shows the architecture of basic FIR filter.



A digital-to-analog (DA) filter is a filter used to tame a digital-to-analog converter's output waveform [2-4]. The analog signal is cleaned up of unwanted high-frequency noise and other abnormalities. Applications that call for high-quality analogue signals, as those in audio instruments and equipment, frequently use DA filters. Although the slowness of DA due to its bit serial structure may appear to be a drawback, its ability to mechanize is a positive feature. The time needed to input K words one at a time in parallel, however, is precisely the same as the time needed to input all K words serially on K simultaneous wires when the number of input words K is proportionate to the number of bits in each input word N. A sign bit timing signal, control signal S is shown in Fig. 5. In the time of the sign bit, S is equal to 1, and 0 otherwise. One clock cycle is thought to be the length of the delay in the accumulator loop. Switch SW is in position 1 for the remainder of the clock cycle and in position 2 for the sign bit time. The completely formed result is available at the accumulator's output when switch SW toggles to position 2 for one clock cycle. Shift register, LUT, adder/shifter, and accumulator units comprise the Modified Binary DA based FIR architecture is shown in Fig.6. The information in the ROM is the same as the information in the binary DA's ROM's upper half [6]. The adder/shifter unit's control line S can be changed to decrease the memory size of the LUT. Thus, as compared to FIR, the memory size of LUT is reduced from 2^{2K} to 2K

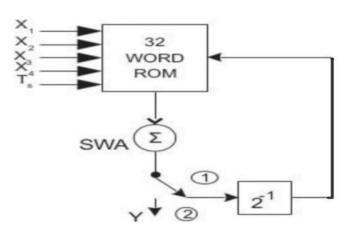


Fig.5. Binary DA

The Oversampling, Bit-stream, Closed-loop Digital-to-Analog (OBC DA) filter is a type of DA filter that achieves high-resolution digital-to-analog conversion through oversampling and a closed-loop feedback system [7-8] is shown in Fig 7. This type of filter is commonly used in applications that require high-quality audio reproduction, such as high-end audio equipment and studio recording systems. Instead of using binary data, OBC DA uses signed data, or (-1, 1) (0, 1). Offset-binary code (OBC) can be utilized to shrink the size of the LUT in this case. As a result, the memory size in OBC DA is lowered from 2K to 2(K-1) [9-12].

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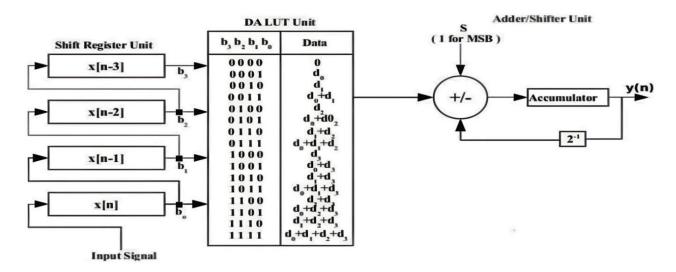


Fig.6. Modified Binary DA

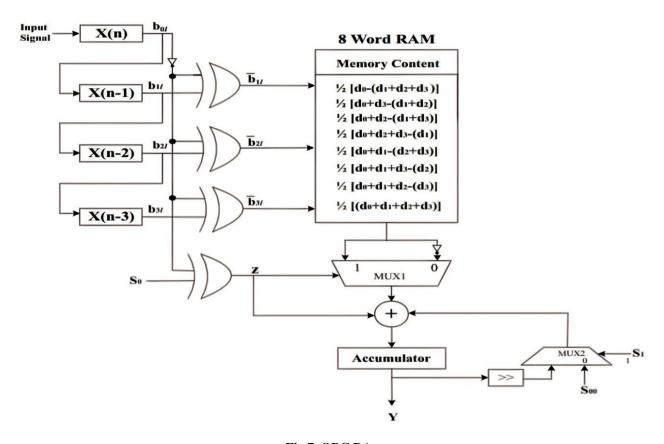


Fig.7. OBC DA

IV. RESULT AND DISCUSSION

In this work, simulations were performed on different FIR filter architectures, and a Verilog hardware description language was written for each architecture. The RTL code was then simulated on Xilinx Vivado to verify the syntax and logic functionality, and synthesis was performed to determine the area, power, and delay. The simulation results showed that the FIR filters were logically matched, and the OBC DA filter had better power efficiency compared to the DA-based filter. The simulation waveforms are shown in Figure 8a, 8b,8c. and the synthesis report for power, area, and delay comparison is presented in Table 1. Finally, a

decimation filter was designed using Matlab Simulink. The black box window was called in Matlab Simulink software, and the Verilog code of our FIR filter was invoked to simulate the decimation filter for down sampling. The simulation results from Matlab Simulink are shown in Figure 9a,9b,9c. Simulation results show that OBC DA has lower power consumption compared to conventional FIR filters, and it has been successfully implemented with Verilog code and verified for down-sampling decimation filter. Therefore, it is being used in hearing aid applications.

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Fig8a. Simulation wave form for FIR Filter

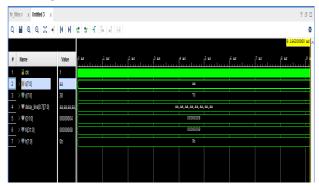


Fig8b. Simulation wave form for DA Filter

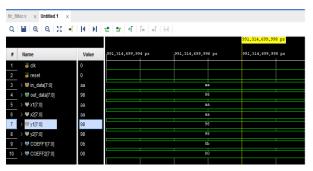


Fig8c. Simulation wave form for OBC DA Filter

Table. 1

14510.1					
S. No	FILTERS	POWER(W)	DELAY (ns)	LUT	
1	DA	10.218	13.218	120	
2	OBC DA	8.368	5.93	21	

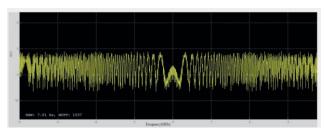


Fig9a. Input signal to decimation filter

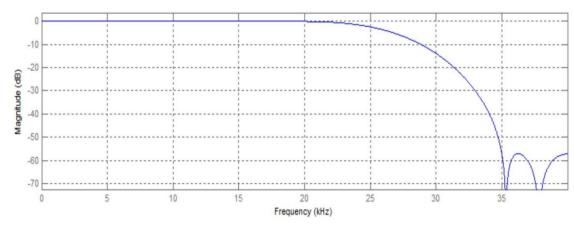


Fig9b. Frequency response of corrector filter

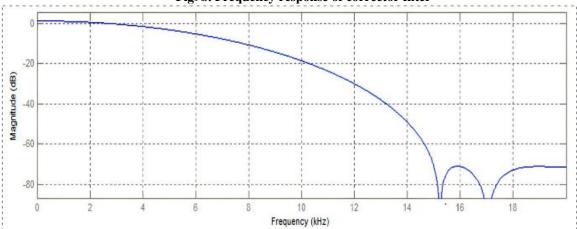


Fig9c. Frequency response of corrector filter

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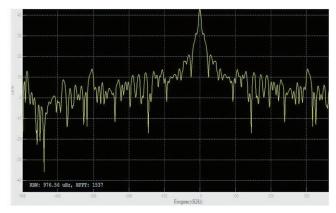


Fig 9d. Frequency response of decimation filter

V. CONCLUSION

In this paper, a reconfigurable CSD-based FIR decimation filter has been proposed for digital hearing aid applications. The power is (mW), delay, and LUT reports for the FIR filter with 8 taps have been presented. The Binary DA and OBC DA FIR filters occupy more area than the conventional FIR filter. The Binary DA architecture consumes more power due to its high LUT requirement and delay. On the other hand, the OBC DA architecture has a comparatively lower LUT requirement and less delay, resulting in increased speed. Moreover, the area of the OBC DA architecture is less than that of the DA architecture due to the reduction in ROM. Therefore, the OBC DA architecture is highly preferred over the DA architecture due to its less power consumption, less delay, and high speed.

DECLARATION

Funding/ Grants/ Financial Support	No, We did not receive.		
Conflicts of Interest/	No conflicts of interest to the		
Competing Interests	best of our knowledge.		
Ethical Approval and Consent to Participate	No, the article does not require ethical approval and consent to participate with evidence		
Availability of Data and	Yes, It is		
Material/ Data Access	relevant.(ieeexplore.ieee.com)		
Statement	and (scholar.google.com)		
Authors Contributions	I K Teja Sri have completed this paper work under the guidance of Dr. S V V Satyanarayana, Assistant Professor in SVEC, Tadepalligudem.		

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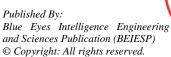
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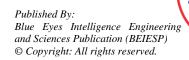
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