

ITKWidgets

Interactive widgets to visualize images, point sets,
and 3D geometry on the web.

Matt McCormick @ Kitware

March 2nd, 2023

Software Development Panel: Web Visualization Frameworks

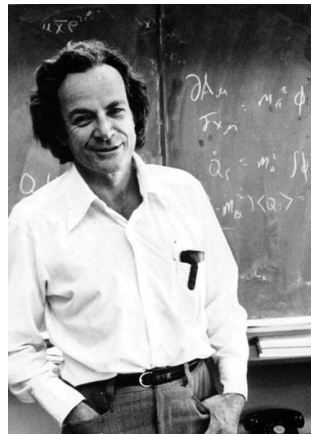


Scientific Computing and Imaging Institute, University of Utah

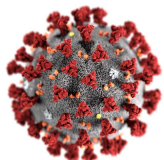
Thank You

- Scientific Computing and Imaging Institute
University of Utah
- National Institute of General Medical Sciences of the
National Institutes of Health: R24 GM136986

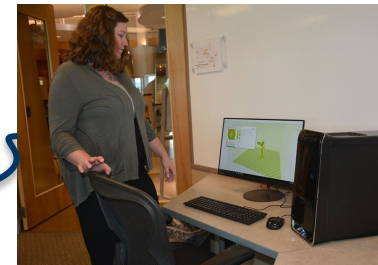
Where are our research components located?



1
Researcher



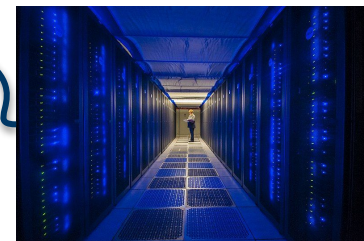
2
Image Acquisition System



3
Laboratory Workstation



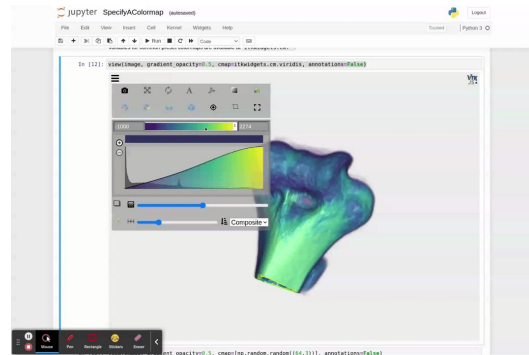
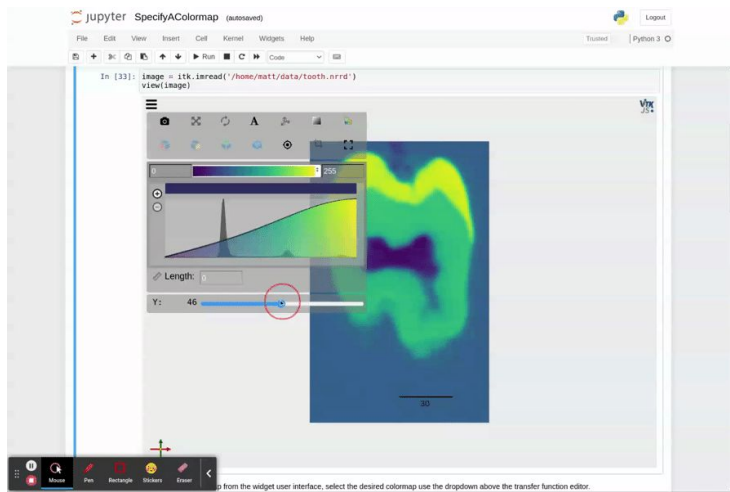
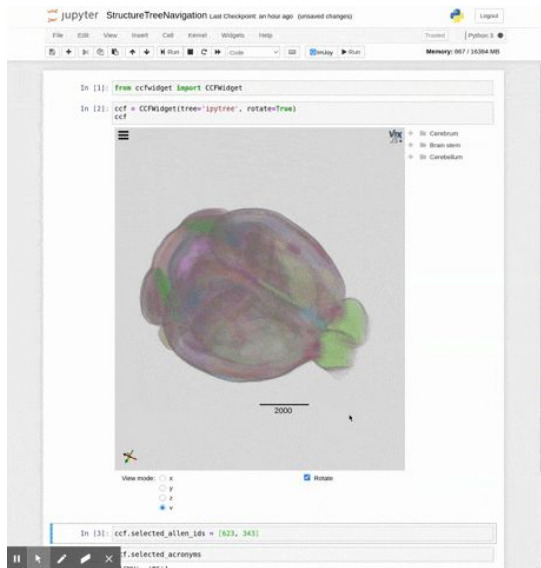
4
High Performance Computing Cluster



5
Cloud Computing Cluster

What is itkwidgets? (<https://itkwidgets.readthedocs.io/>)

Interactive widgets to visualize images, point sets, and 3D geometry on the web.

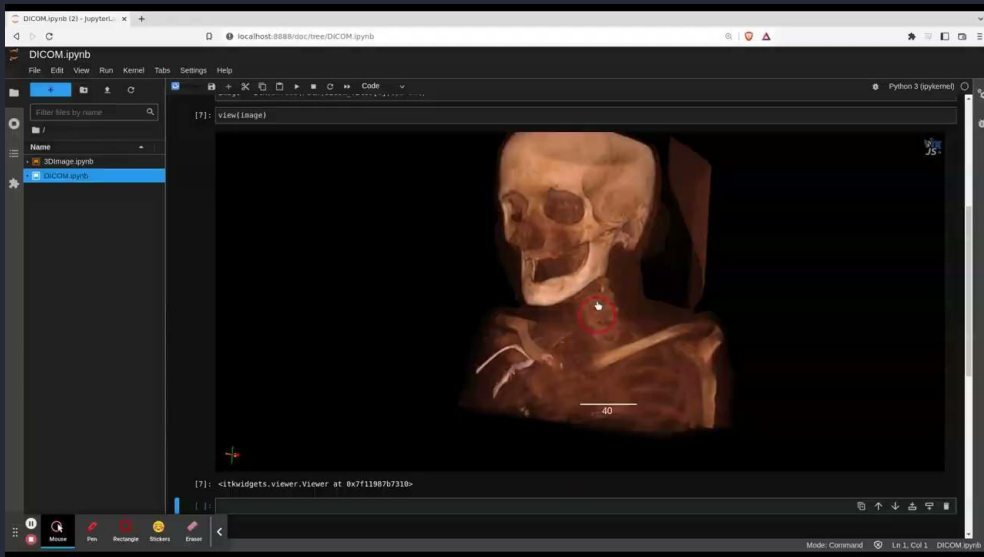




itkwidgets

Cinematic Volume Rendering Integrated with your AI Research and Applications

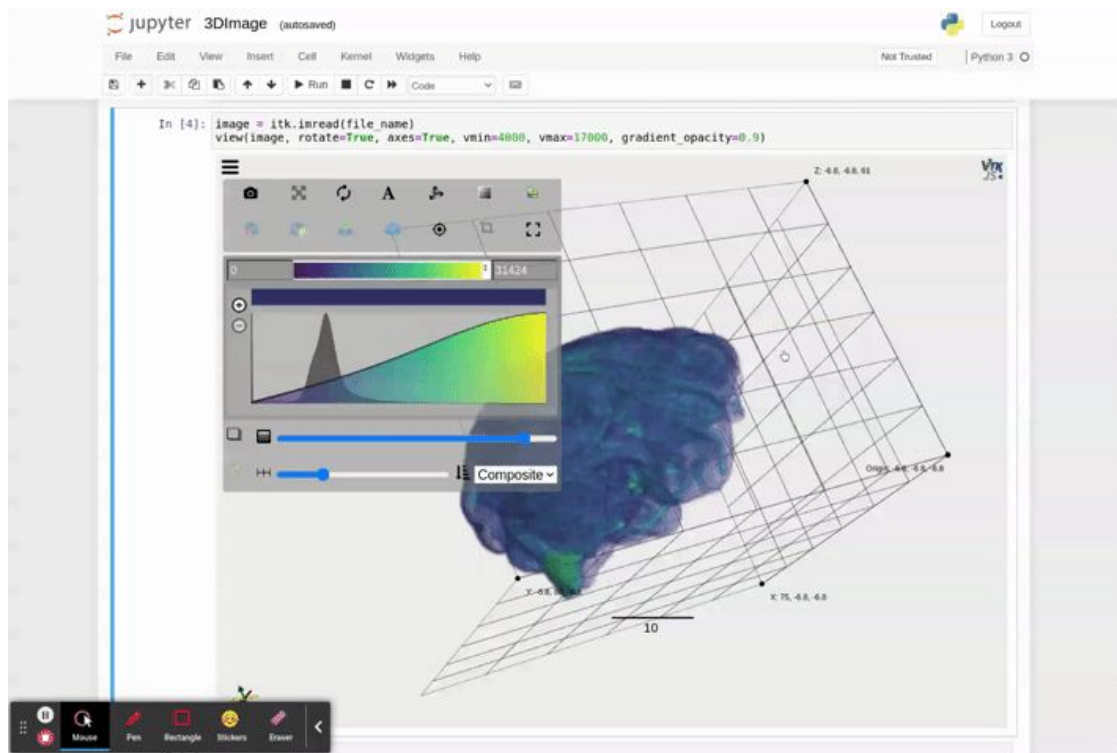
- Runs in Jupyter, JupyterLab, JupyterLite, Google CoLab, AWS Sagemaker, and Python standalone (WIP)
- Works with MONAI, PyTorch, TensorFlow, etc.
- Advanced cinematic volume rendering of medical data
- Integrated overlay of AI results
- Open and reproducible



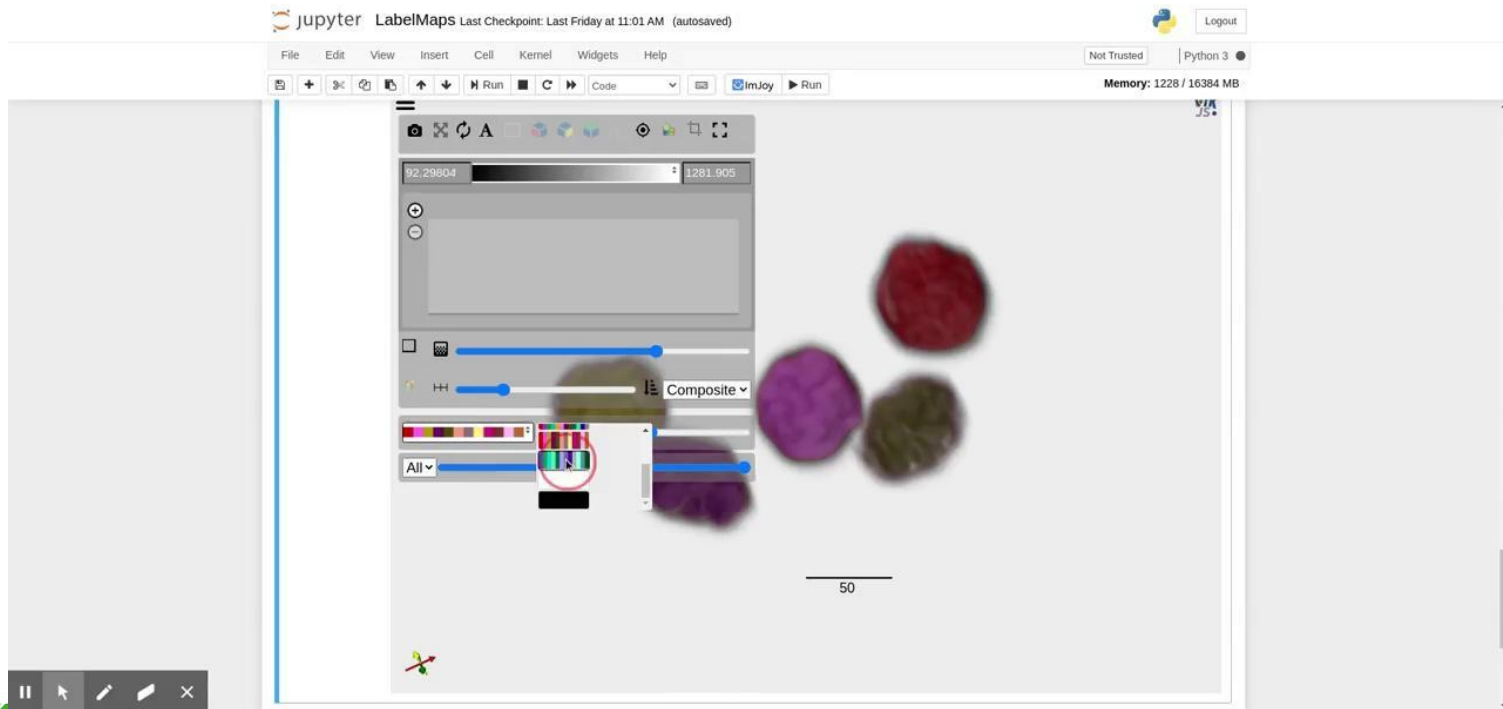
For more information:

<https://itkwidgets.readthedocs.io>

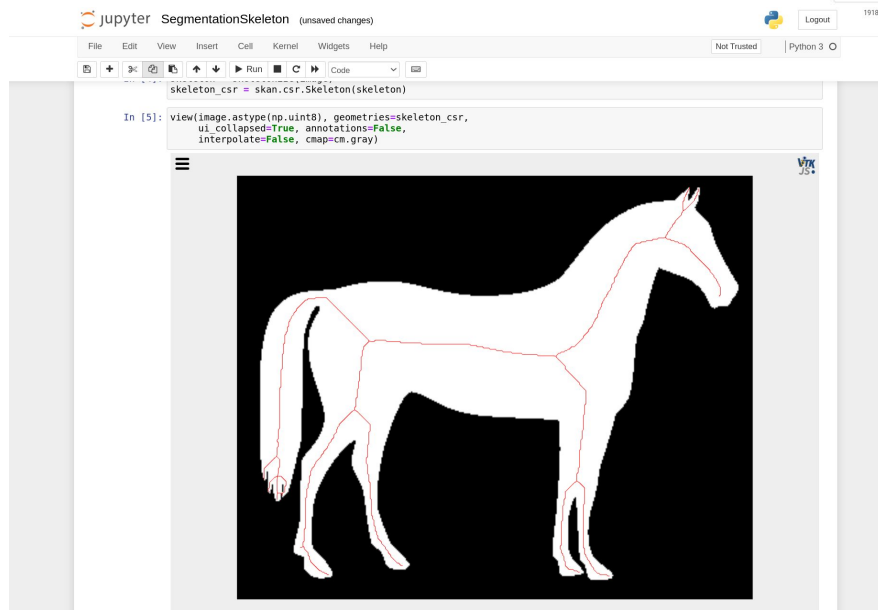
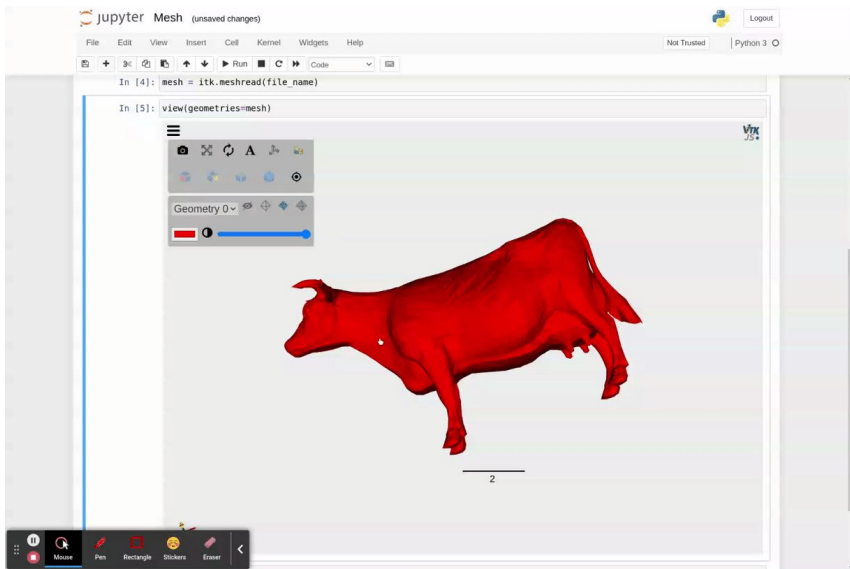
2D and 3D images



Label images



Meshes, geometry



Point sets

Jupyter NumPyArrayPointSet (unsaved changes) Logout

File Edit View Insert Cell Kernel Widgets Help Trusted Python 2.0

```
In [1]: import numpy as np
        from itkwidgets import view

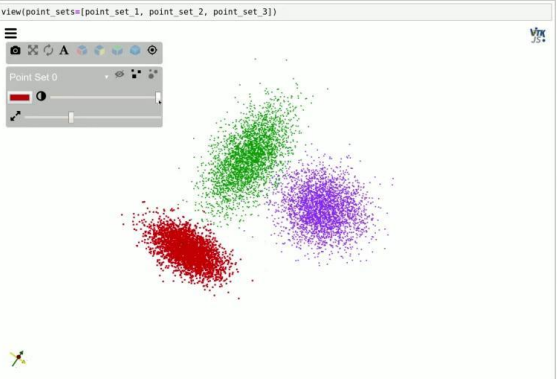
In [2]: number_of_points = 3000

        gaussian_1_mean = [0.0, 0.0, 0.0]
        gaussian_1_cov = [[1.0, 0.0, 0.0], [0.0, 2.0, 0.0], [0.0, 0.0, 0.5]]
        point_set_1 = np.random.multivariate_normal(gaussian_1_mean, gaussian_1_cov,
            number_of_points)

        gaussian_2_mean = [4.0, 6.0, 7.0]
        gaussian_2_cov = [[2.0, 0.0, 0.0], [0.0, 2.0, 0.0], [0.0, 0.0, 1.5]]
        point_set_2 = np.random.multivariate_normal(gaussian_2_mean, gaussian_2_cov,
            number_of_points)

        gaussian_3_mean = [4.0, 0.0, 7.0]
        gaussian_3_cov = [[4.0, 0.0, 0.0], [0.0, 1.0, 0.0], [0.0, 0.0, 3.5]]
        point_set_3 = np.random.multivariate_normal(gaussian_3_mean, gaussian_3_cov,
            number_of_points)

In [3]: view(point_sets=[point_set_1, point_set_2, point_set_3])
```



In [1]:

Jupyter pyvistaLIDAR (autosaved) Logout

File Edit View Insert Cell Kernel Widgets Help Trusted Python 2.0

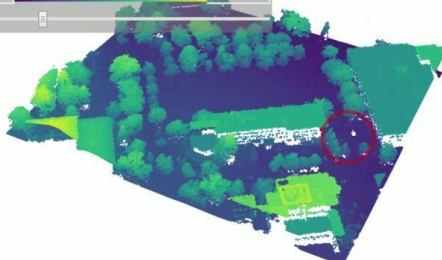
```
from itkwidgets import view

In [2]: point_set = examples.download_lidar()
        point_set

Out[2]:
```

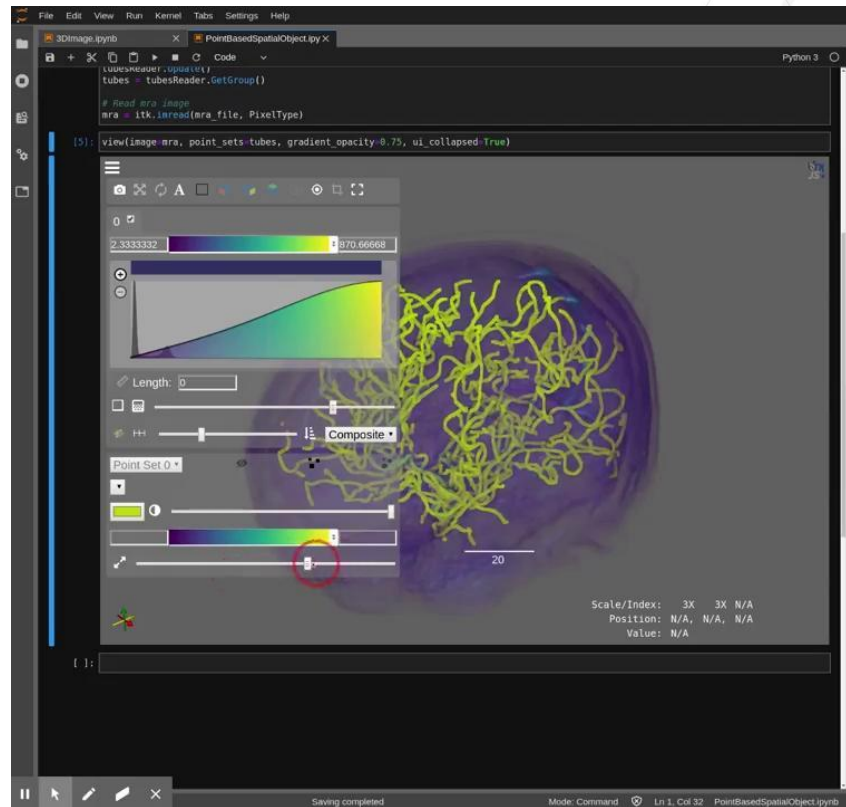
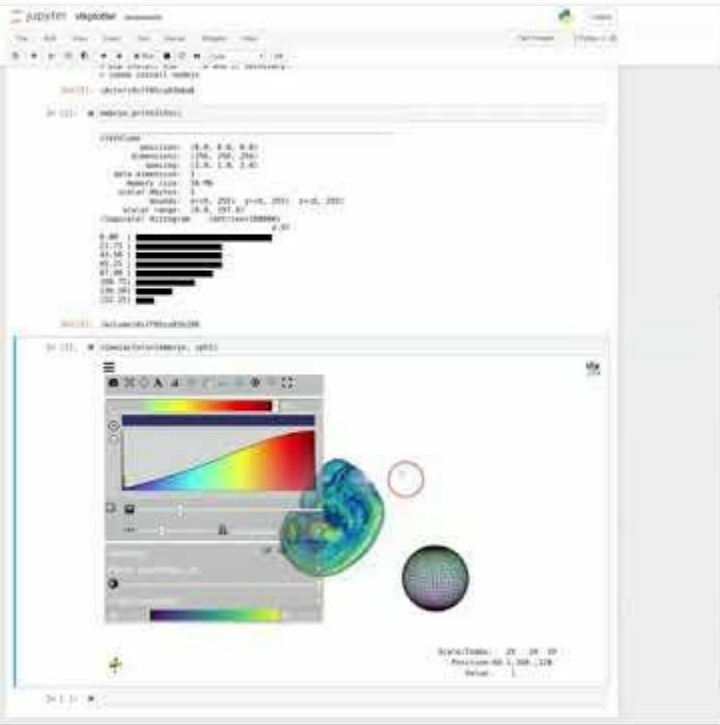
Header		Data Arrays					
PolyData		Information					
N Cells	3392091						
N Points	3392091						
X Bounds	4.809e+05, 4.811e+05	Name	Field	Type	N Comp	Min	Max
Y Bounds	4.400e+06, 4.400e+06	Elevation	Points	float64	1	1.754e+03	1.787e+03
Z Bounds	1.754e+03, 1.787e+03						
N Arrays	1						

```
In [3]: view(point_sets=point_set)
```



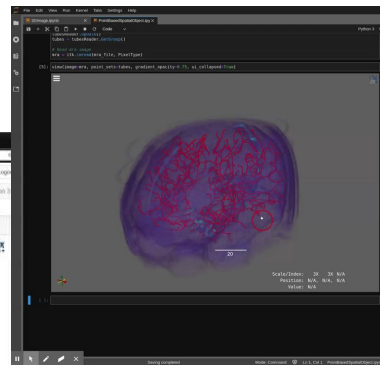
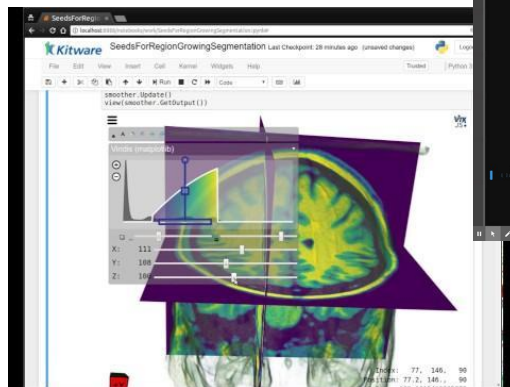
In [3]:

Combine data

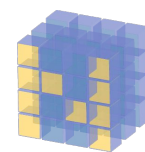


How does it work?

Built on:



Supports:



PYTORCH

NumPy

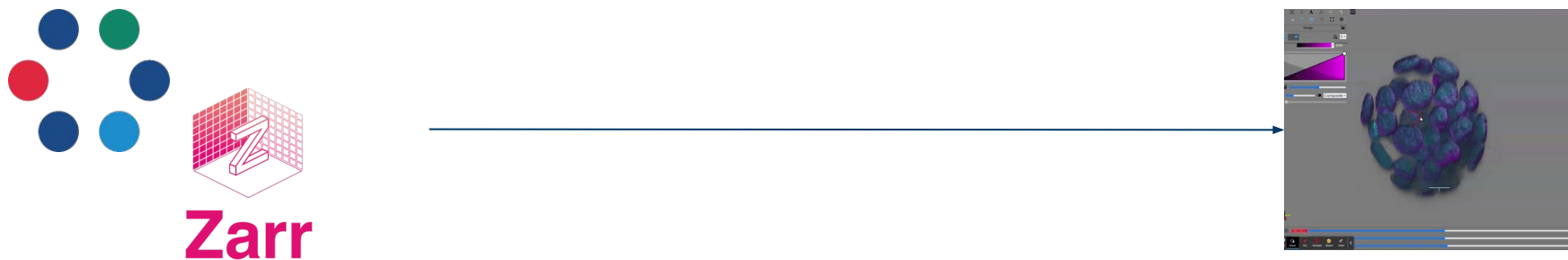


OpenCV



Amazon SageMaker

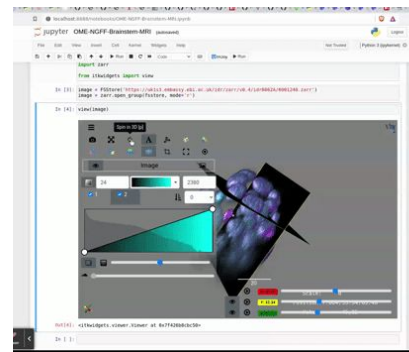
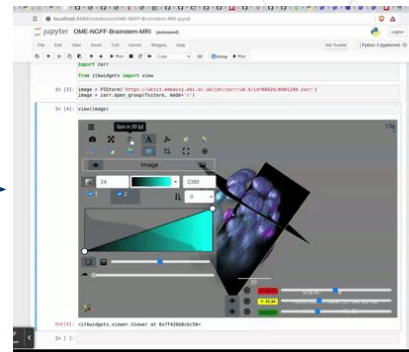
Client-side: Use directly or generate with WebAssembly



Server-side: Use directly or generate with Python

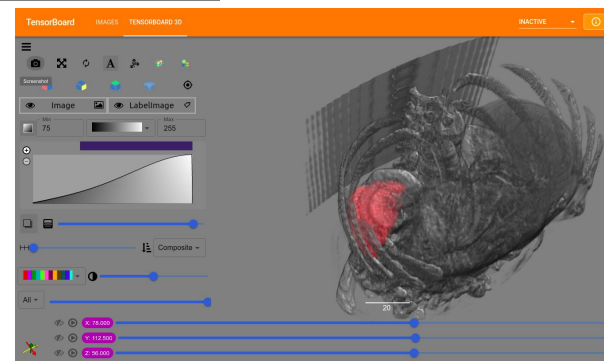
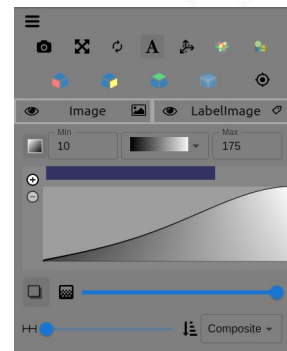
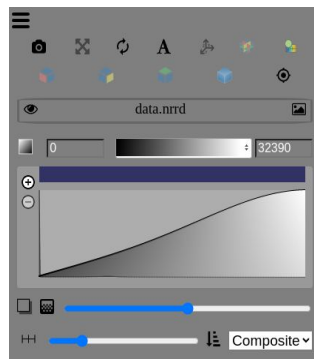


Zarr



A meta-viewer component for custom research applications (alpha)

- Customizable frontends
 - Vanilla HTML, Vue, React, etc.
 - Complete custom UI or only relevant features from examples
- Customizable renderers (WIP)
 - Editor overlays
 - Server side, e.g. 3D Slicer



Open source

- <https://github.com/InsightSoftwareConsortium/itkwidgets>
- <https://github.com/InsightSoftwareConsortium/itk-wasm>
- <https://github.com/Kitware/itk-vtk-viewer>
- <https://github.com/Kitware/vtk-js>

Reproduce these slides!

- ◆ [Brainstem serverless](#)
- ◆ [Brainstem Jupyter](#)
- ◆ [Load local images](#)

Questions?

Matt McCormick

Thank You

- Scientific Computing and Imaging Institute
University of Utah
- National Institute of General Medical Sciences of the
National Institutes of Health: R24 GM136986