

Level up your HPC skills

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HPC architecture



Some terminology

- MPI (*Message Passing Interface*) software library facilitating parallelism across multiple, potentially heterogeneous computational resources.
- **OpenMP**: software library facilitating shared-memory parallelism (e.g. within a single server or computer).
- **Process**: basic unit of parallelism employed by MPI. Processes operate as independent, persistent instances of a given program and do not share resources.
- **Thread**: basic unit of parallelism employed by OpenMP. Threads can be conceptually created and destroyed at will and share all resources on a machine.



HPC cluster architecture - CPUs





Schematic of AMD Zen3 node. Credit: Pawsey Supercomputing Centre



HPC cluster architectures

- Modern clusters are becoming increasingly heterogeneous (even for CPUs)
- Thread/core count per node can be misleading
 - Non-uniform performance
 - Threads on a single socket often share e.g. I/O bus bandwidth saturation!
- Modern HPC processors are really multiple smaller processors that happen share a chip
- Memory hierarchies are also getting deep
 - Non-uniform memory access
 - Deep shared caches
- *Where* your code executes (e.g. MPI ranks, OpenMP threads) can make a big difference for performance



HPC performance – profile your code

- Can't know if you're doing the right thing if you don't measure
- We're scientists: treat optimising and deploying code like an experiment
 - Collect data
 - Analyse performance patterns
 - Form a hypothesis for how to improve
 - Collect data to test hypothesis
- Can be as simple as checking walltime when job's done (scheduler will usually do this for you)
- Large codes like LAMMPS, CP2K sometimes have this built in
- Dedicated profiling tools available on most clusters ask your helpdesk or see the list at the end of these slides



Strong scaling – Amdahl's law





HPC performance - MPI

- MPI performance determined by two main hardware factors:
 - 1. Network latency
 - 2. Network bandwidth
- Relative importance varies between apps
 - o "Speed" can refer to either of these, or both. Be clear about your needs
- Network congestion affects both, can't control this as a user
- You *can* control where processes are placed
 - Need to be aware of network topology for maximum performance



HPC network topology - intra-node

- MPI messages between processes on the same node use *shared memory*
 - Message passing performance dependent on memory access
- Modern CPU architecture has Non-Uniform Memory Access (NUMA):



- = low-latency
- = higher-latency



HPC network topology – inter-node

- Fast network interconnects put the "super" in "supercomputer"
- Multi-node latency very sensitive to *network topology* and process placement
- Many different topologies, differ between clusters
- Learn what your cluster uses and how to optimise for it
- E.g. Setonix and Gadi use *Dragonfly* and *Dragonfly*+ topologies, respectively







Fat Tree

Torus

Dragonfly



Source: Mellanox Technologies Inc.



Example: Dragonfly topology

- Processing elements (PE, e.g. nodes) organised into groups
- Groups are *all-to-all* connected to each other:
 - One "external" switch per group
 - Few "long links"
- PEs within a group connected by different subtopology (e.g. tree or torus)
- Latency (almost) constant for messages within groups, much worse for messages between groups



Graph of dragonfly topology. Source: https://commons.wikimedia.org/wiki/ File:Dragonfly-topology.svg



Job schedulers

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The lay of the land

- Multi-tenant clusters need some way to allocate and manage jobs/resources
- SLURM or PBS/Torque/SGE most common on HPC clusters
 - Typically focused on relatively homogeneous compute jobs (e.g large DFT jobs) batch processing
 - Provide fine-grained control of resource placement/topology
 - Lots of monitoring/reporting (even profiling) tools
- Traditional schedulers poorly suited to multi-stage heterogeneous workflows
 - Data-intensive ML or bioinformatics pipelines are especially tricky
- New set of *workflow managers* gaining adoption:
 - Nextflow
 - Flux
 - Snakemake



SLURM

- Used by Setonix, UQ's Bunya
- Good support for heterogeneous architectures (e.g. GPUs, highly-nonuniform nodes, future weird stuff?)
- Extensive monitoring and logging capabilities
- UQ Research Computing Centre has a cool tool to generate SLURM script templates: <u>https://shiny.rcc.uq.edu.au/SLURM/</u>





SLURM – resource management

SLURM concept	Logical interpretation
NTASKS	MPI Ranks
CPUS	Physical CPU core
CPUS_PER_TASK	CPUs per MPI process (for e.g. MPI+OpenMP)
NODES	Physical compute node
SOCKETS	Physical socket/chiplet
GRES	Generic consumable resource (e.g. GPU)



SLURM – submitting

- Manage process/thread placement with srun
- Modern HPC processors are really multiple smaller processors that share a chip
- Memory access/messaging across boundaries (even within a node) is *slow*
- Lots of cores, so resource contention is also
 important
- HPC administrators will typically set good defaults for *most* jobs, not necessarily good for *your* job





SLURM - submitting jobs

srun --distribution={block|cyclic|arbitrary|plane}:{block|cyclic|arbitrary|plane}

- First option distribution of tasks to nodes, second controls distribution *within* nodes
- Example 1: MPI-only, processes only talk to "nearby" processes (e.g. neighbour list MD)
 - Scheduling adjacent processes on the same node/socket = optimise communication

srun --nodes 4 --tasks-per-node=128 --distribution=block:blockImp [...]

- Example 2: MPI+OpenMP, MPI ranks talk to to "nearby" processes, one process per socket
 - Schedule nearby processes on adjacent nodes, spread out processes within nodes to minimise contention between threads

srun --nodes=4 --ntasks-per-node=8 --cpus-per-task=16 --distribution=block:cyclic

• As always, experiment and profile!



SLUM – monitoring and reporting

- sinfo information about node status and partition occupancy
- squeue what's the status of my jobs in the queue?
- sprio what's my job's priority? Why isn't it running yet?

\$ sinfo -O Partition,NodeList,Nodes,Gres,CPUs

PARTITION	NODELIST	NODES	GRES	CPUS
debug*	bun[006-067]	62	(null)	192
general	bun[006-067]	62	(null)	192
ai	bun[003-005]	3	gpu:a100:3	256
gpu	bun[001-002]	2	gpu:mi210:2	192
gpu	bun068	1	gpu:a100:2	192



SLURM - monitoring and reporting

- sstat what's the status of my (running) job?
 CPU usage, memory usage, I/O patterns
- sacct as above, but for historical jobs. Can specify ranges. Useful for coarse-grained profiling, keeping track of which jobs have finished/failed

\$ sstat --format=JobID,AveCPU,MinCPU,AveVMSize -j 965786 JobID AveCPU MinCPU AveVMSize

965786 00:01:59 00:01:57 117936K

\$ sacct -o jobid,jobname,NNodes,NCPUS,elapsed -S now-30days --user=\$USER JobID JobName NNodes NCPUS Elapsed

909263	cp2k-256	1	8	00:24:33
966144	build-lammps	1	256	00:00:35



SLURM – monitoring and reporting

- sreport generate nice reports from SLURM job data for a range of jobs
 - Very useful when estimating resource requirements for grant applications

sreport cluster UserUtilizationByAccount -t Hours start=2022-01-01 Users=\$USER

Cluster/User/Account Utilization 1 Jan 2022 - Ystday 23:59 (36201600 secs) Usage reported in CPU Hours ------Cluster Login Proper Name Account Used Energy ------setonix ekahl Emily Kahl fc8 8577 0



SLURM – monitoring and reporting

- seff generate detailed report about a *single* job, including CPU and memory efficiency
 - Important to gauge how well you're using the cluster
 - Want to aim for as close to 100% utilisation as possible
 - Sometimes number of cores can be misleading – figure to the right reports 4 cores, but that counts virtual cores which are unused and not included in job accounting (re-scale by 2 to get the physical cores): more info from Pawsey <u>here</u>

Example CP2K job:
\$ seff 1026815
Job ID: 1026815
Cluster: setonix
User/Group:ekahl/ekahl
State: COMPLETED (exit code 0)
Nodes: 1
Cores per node: 4
CPU Utilized: 01:23:52
CPU Efficiency: 49.39% of 02:49:48 core-walltime
Job Wall-clock time: 00:42:27
Memory Utilized: 188.32 MB (estimated maximum)
Memory Efficiency: 62.77% of 300.00 MB (300.00 MB/node)



PBS

- Scheduler used by Gadi, many older clusters
- Less rich support for thread/process placement than SLURM
- Have to use OpenMP environment variables and mpirun to control job placement/affinity
- Usually don't need these with SLURM (use srun instead)

OMP_NUM_THREADS	Number of OpenMP threads
OMP_PROC_BIND	Pin threads to CPU cores
OMP_PLACES	How to distribute threads on a node
mpirunmap-by	How to distribute MPI ranks



High performance storage



POSIX filesystems

- UNIX-like systems use the POSIX standard
- Everything is a file, files live in a hierarchical directory structure
- /home, /scratch on clusters
- Directories spread across multiple disks/servers on clusters, but still have a single namespace: distributed file system, e.g. Lustre
- Familiar, convenient, works the same on every machine
- Doesn't scale well for very large data abstractions are expensive!
- Strong limits on *number* of files searching through metadata gets slow
- Usually have quotas on storage and number of files



Image credit: RedHat, Inc.



Python on HPC

- Python packages can be very bad for HPC filesystem performance
 - e.g. Conda, pip
- Small, isolated packages probably okay
- Recursive dependencies can create LOTS of tiny files really bad for Lustre performance
- Easy to exhaust quota on "number of files" (inodes)
- Try not to install python environments on the clusters
- Use containers where possible image acts as a single file on disk but expands into a filesystem in memory
- Good resource/tutorial: <u>https://pawseysc.github.io/singularity-containers/</u>
- (pip|conda)install--dry-run is your friend!



Some Useful Tools and Resources



Observability tools

NOTE: These tools may not be available on all HPC systems. All of these are command-line tools and their output may require some interpretation.

- Istopo: print information about the topology of the node (CPU cores, memory regions, network bus, etc).
 Sub-program distributed with <u>hwloc</u> (itself a sub-project of OpenMPI). Will need to run via a batch or interactive job to see details of compute nodes
- Iscpu: print detailed information about the CPU on the current node. Will also need to run via a batch or interactive job to see details of compute nodes
- LIKWID: set of tools for reporting and managing hardware and HPC resources (e.g. MPI). Some tools are more for system administrators, but some can be installed without superuser privileges. Link
- sinfo: SLURM tool to print information about nodes and partitions, including some information on hardware configuration



Profilers

- gprof: old-school, kinda rough, limited support for parallelism, built into GNU compilers and available everywhere: <u>https://support.pawsey.org.au/documentation/display/US/Profiling+with+gprof</u>
- Caliper: extremely fine-grained information, supports MPI/OpenMP/CUDA, open-source, requires source-code modifications: <u>https://software.llnl.gov/Caliper/index.html</u>
- Arm Forge: Very fine-grained metrics, tracing (can view program performance as a time-series), really good GUI, works with MPI/OpenMP/CUDA, proprietary, available on Gadi: <u>https://opus.nci.org.au/display/Help/Arm+HPC+Tools</u>
- Cray PAT/perftools: decent coverage of diagnostics, optional GUI, proprietary, available on Setonix (documentation)
- Intel VTune: good coverage of low-level diagnostics and tracing, good support for OpenMP, installed on Gadi, proprietary but costs \$0: <u>https://www.intel.com/content/www/us/en/developer/tools/oneapi/vtune-profiler.html</u>
- HPCToolkit: fine-grained metrics and profiling, works with MPI/OpenMP and CUDA, open-source and widely available, somewhat complicated workflow: <u>http://hpctoolkit.org/</u>
- TAU: good support for profiling and tracing with MPI and OpenMP, optional GUI, opensource: <u>https://www.cs.uoregon.edu/research/tau/home.php</u>



Debuggers

- Can start and stop program execution and inspect program's state almost arbitrarily
- GDB is a superpower!
- Available almost anywhere
- Almost arbitrary control and observability for CPU-based programs.
- Terminal based, but TUI exists
- Good tutorial at <u>Dive Into Systems</u>
- NVIDIA/AMD have GPU-aware debuggers with GDB-like interface: cuda-gdb/rocm-gdb
- Distributed, MPI-aware debugging is hard, few available tools:
- Arm DDT (proprietary) on Gadi: <u>https://opus.nci.org.au/display/Help/Arm+HPC+Tools</u>
- gdb4hpc (Cray proprietary) on Setonix
- TotalView, available on Gadi: https://opus.nci.org.au/display/Help/TotalView



Good resources

- CTCMS tutorials and guide (suggestions and contributions welcome!): <u>https://ctcms-uq.github.io/</u>
- UQ RCC docs: <u>https://github.com/UQ-RCC/hpc-docs</u>
- NCI's Gadi user guide: https://opus.nci.org.au/display/Help/Gadi+User+Guide
- Pawsey's Setonix user guide: <u>https://support.pawsey.org.au/documentation/display/US/Setonix+User+Guide</u>
- Victor Eijkhout, *The Art of HPC* (series of textbooks and guides)
- Paul E McKenney, <u>Is Parallel Programming Hard, And, If So, What Can You Do About It?</u> (textbook)
- Brendan Gregg's <u>website</u> and <u>and book</u> on performance engineering
- Julia Evans, <u>The Pocket Guide to Debugging</u>



Thank you!

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Object storage

- Qualitatively different from POSIX filesystems
- Stores unstructured data no folders, no hierarchy
- Scales better than POSIX for very large data sets
- Objects stored in buckets unique ID + rich metadata for search
- Splits reads/writes from namespace manipulation
- Pull data -> read/modify -> push data
- Good for data which is read more often than it's written (e.g. molecular geometry files)
- Used by Pawsey (Acacia), commercial cloud services (e.g. Amazon S3) - get used to it!



Image credit: RedHat, Inc.