

# Using Near-Real-Time DORIS Data for Validating Real-Time GNSS Ionospheric Maps

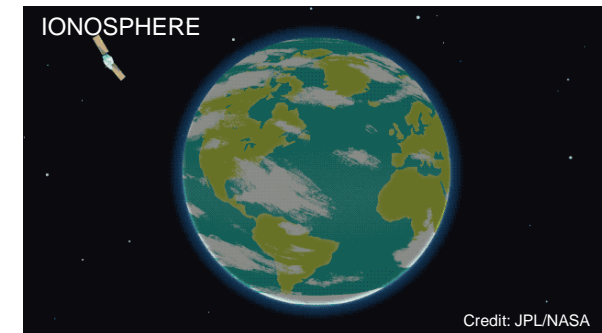
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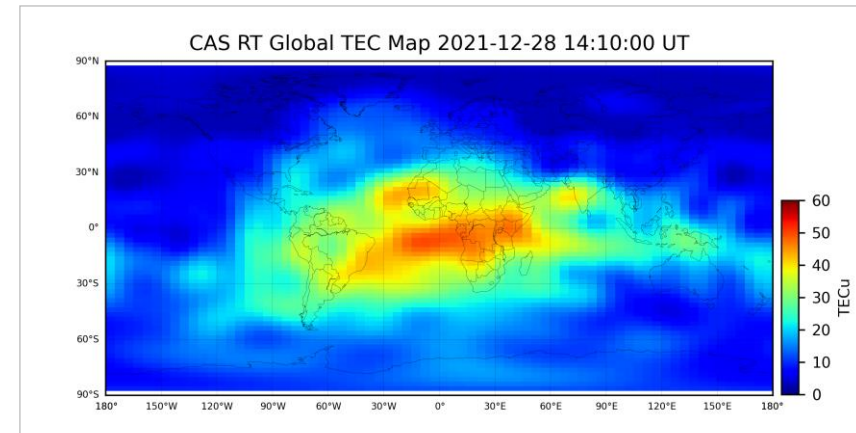
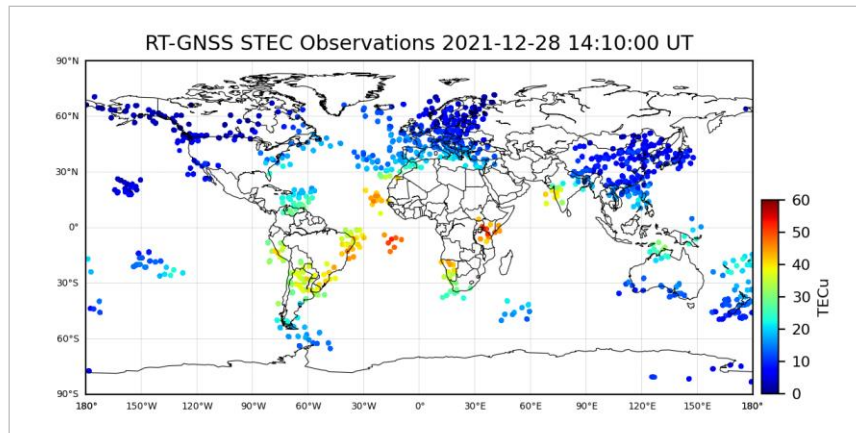
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- ▶ Background and Motivation
- ▶ GNSS and DORIS dSTECh assessments
  - GNSS derived dSTECh observables
  - DORIS derived dSTECh observables
- ▶ Data sets and analysis results
- ▶ Summary and conclusions



## Generation of Real-Time Global Ionospheric Maps (RT-GIMs)

- ▶ Regional and global real-time GNSS data streams (1 Hz), containing multi-frequency (L1/L2/L5) and multi-constellation (G/R/E/C) GNSS measurements, are available for RT-GIM computation.
- ▶ Within the International GNSS Service (IGS), RT-GIMs are routinely generated by 4 Analysis Centers (ACs): CAS, CNES, UPC and WHU.
- ▶ The IGS combined RT-GIMs are independently generated by CAS and UPC since January 2022.
- ▶ RT-GIMs are widely used in ionospheric space weather and precise GNSS positioning applications.



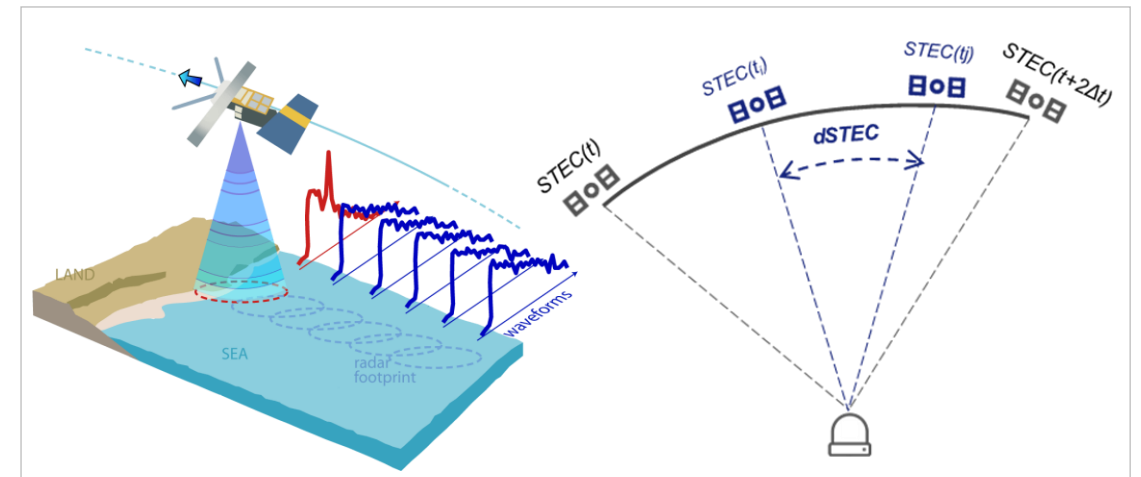
## Validation of Real-Time Global Ionospheric Maps (RT-GIMs)

### ► Self-consistency check

- **GNSS-derived STEC**: *code smoothing* or *precise point positioning* (PPP) derived, S/R DCB removed.
- **GNSS-derived dSTEC**: carrier phase geometry-free combination derived, differential STEC b.w.t. two epochs along individual continuous arcs, low level of observation noises.
- GNSS derived STEC and dSTEC are available in real-time (few seconds in time latency).

### ► External-consistency check

- Altimetry-derived VTECs, available over the oceanic regions.
- Fully independent to GNSS measurements.
- Near-real-time altimetry VTECs provided by **Jason-3** (~3 hours in latency)



## Using DORIS Data to Validate GNSS-generated RT-GIMs

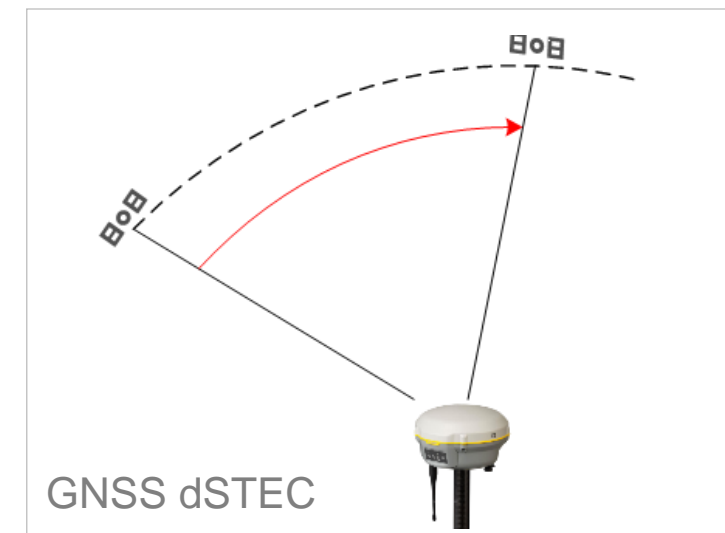
- ▶ **DORIS data: valuable and external data sources to examine the Earth's ionosphere.**
- ▶ **Homogeneous distribution of DORIS ground beacons**, covering continental and oceanic regions.
- ▶ DORIS data are **available from 8 satellites**: CRYOSAT-2, HY-2C, HY-2D, Jason-3, SARAL, Sentinel-3A, Sentinel-3B and Sentinel-6A
- ▶ The **relative frequency ratio** between two frequencies of DORIS is **about 5**, more sensitive to detect the ionospheric information and less prone to measurement noises.
- ▶ The standardization of DORIS data formats, i.e., **RINEX DORIS 3.0**, similar to the existing GNSS RINEX format.
- ▶ The **decreasing time latency** in obtaining DORIS data (2-3 hours for Jason-3 DORIS data).
- ▶ **“NRT DORIS DATA WG”** established in IDS since 2018.



## GNSS dSTEC analysis

- ▶ GNSS dSTEC: differential phase STEC along a continuous arc referring to the highest satellite elevation (Hernández-Pajares et al. 2017).
- ▶ dual-frequency carrier phase measurements used to form the geometry-free linear combination.
- ▶ avoiding the negative effects of amplified pseudorange noises as well as the intra-day variation of receiver biases in code-smoothing technique derived STEC/VTEC.
- ▶ providing a slant but not vertical assessment of different ionospheric models (containing mapping errors)

$$dSTEC_{GNSS}(t) = 40.3 \times (f_1^{-2} - f_2^{-2}) \times [L_I(t) - L_I(t_{E_{\max}})]$$

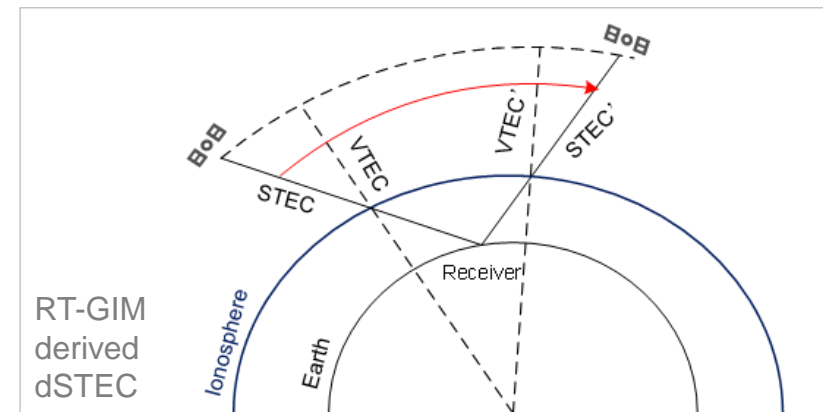
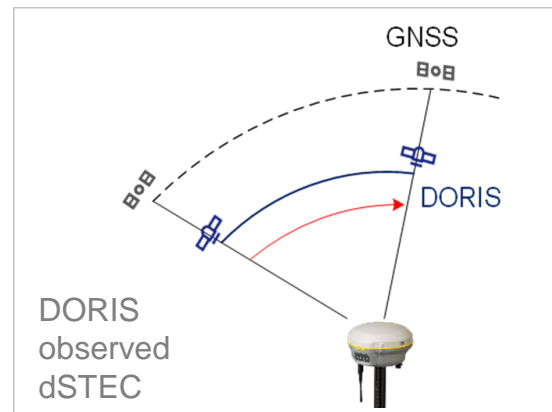
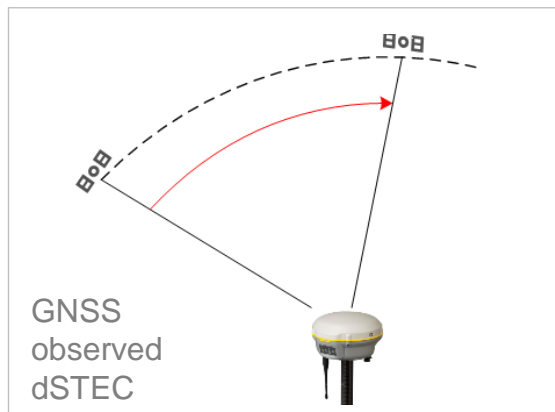


## DORIS dSTEC analysis

- ▶ The calculation of DORIS dSTEC is very similar to that of GNSS dSTEC, generated based on dual-frequency DORIS carrier phase measurements.
- ▶ Containing dSTEC information to the height of LEO satellites, e.g. ~1,300 km for Jason-3.

$$dSTEC_{DORIS}(t) = 40.3 \times (f_1^{-2} - f_2^{-2}) \times [L_I(t) - L_I(t_{E_{max}}) - (\Delta D(t) - \Delta D(t_{E_{max}}))] ]$$

$\Delta D$  denotes the geometry correction (or the PCO correction)





## Precision analysis of DORIS/GNSS observed dSTEC

- ▶ Ignoring the correlation b.w.t. L1/L2 carrier phase measurements, the theoretical precision of DORIS or GNSS dSTEC can be estimated by

$$\begin{cases} \sigma_{dSTEC}^2 = 2\mu^2 \sigma_{L_1}^2 \\ \sigma_{LI}^2 \approx \sigma_{L_1}^2 + \sigma_{L_2}^2 \end{cases}$$

$\sigma_{LI}$  denotes the precision of geometry-free linear combination of dual-frequency DORIS/GNSS phase measurements

- ▶ The precision of DORIS observed dSTEC reaches 0.028 TECu ( $\sigma_{L_1}=1.5$  mm and  $\sigma_{L_2}=7.5$  mm)
- ▶ The precision of GNSS observed dSTEC is about 0.25 TECu ( $\sigma_{L_1}=\sigma_{L_2}=2.0$  mm)
- ▶ The precision of derived dSTEC **benefits from the larger frequency difference** (i.e.,  $f_1 - f_2$ )
- ▶ Overall, the theoretical precision of DORIS dSTEC is about 10 times better than GNSS dSTEC



## Overview of RT-GIMs provided by different ACs

AC	Caster	Mountpoint	Interval
CAS	products.igs-ip.net:2101	SSRC00CAS1 ( <i>IGS-SSR</i> )	60s
CNES	products.igs-ip.net:2101	SSRC00CNE1 ( <i>IGS-SSR</i> )	60s
UPC	products.igs-ip.net:2101	IONO00UPC1 ( <i>IGS-SSR</i> )	15s
WHU	58.49.94.212:2101	IONO00WHU0 ( <i>RTCM-SSR</i> )	60s
UPC-combined	products.igs-ip.net:2101	IONO00IGS0 ( <i>IGS-SSR</i> )	15s
CAS-combined	products.igs-ip.net:2101	IONO01IGS0 ( <i>RTCM-SSR</i> ) IONO01IGS0 ( <i>IGS-SSR</i> )	60s

### NRT DORIS Data and Associated NRT Ephemeris Data

- ▶ Link to Jason-3 NRT DORIS RINEX data

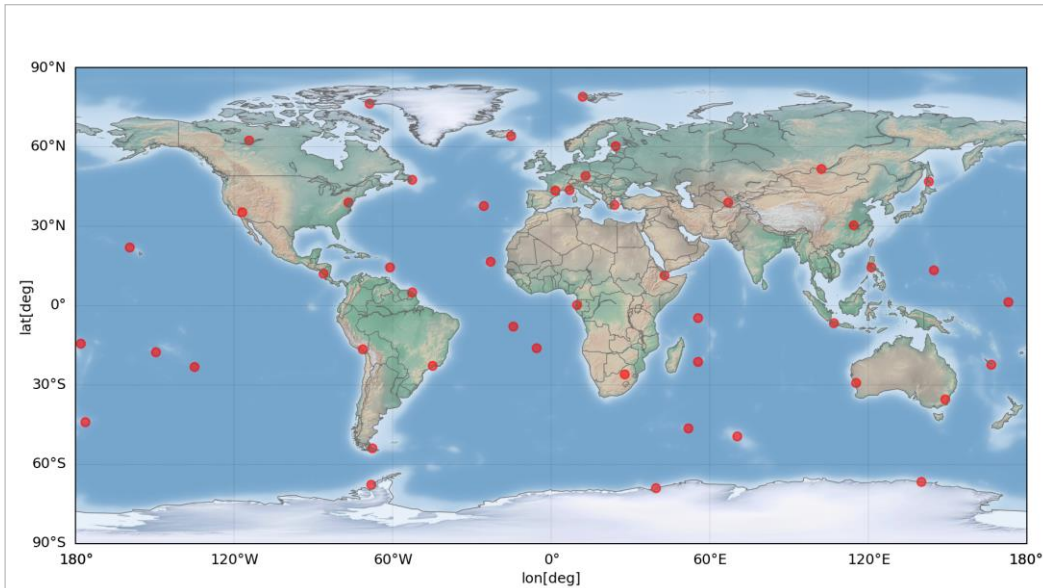
<ftp://doris.ign.fr/pub/doris/data/ja3/NRT/>

- ▶ Link to Jason-3 NRT ephemeris data

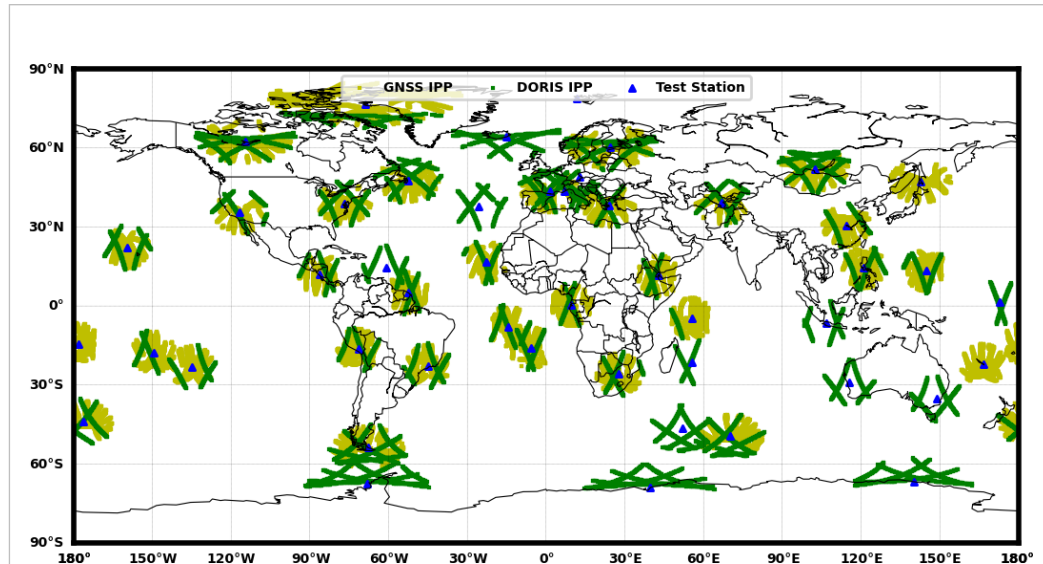
<ftp://doris.ign.fr/pub/doris/products/orbits/ssa/ja3/NRT/>

## The selected 48 DORIS beacons and co-located GNSS stations

- ▶ NRT DORIS data from Jason-3 altimetry used for DORIS dSTEC analysis
- ▶ GPS and GLONASS observations of the IGS network used for GNSS dSTEC analysis

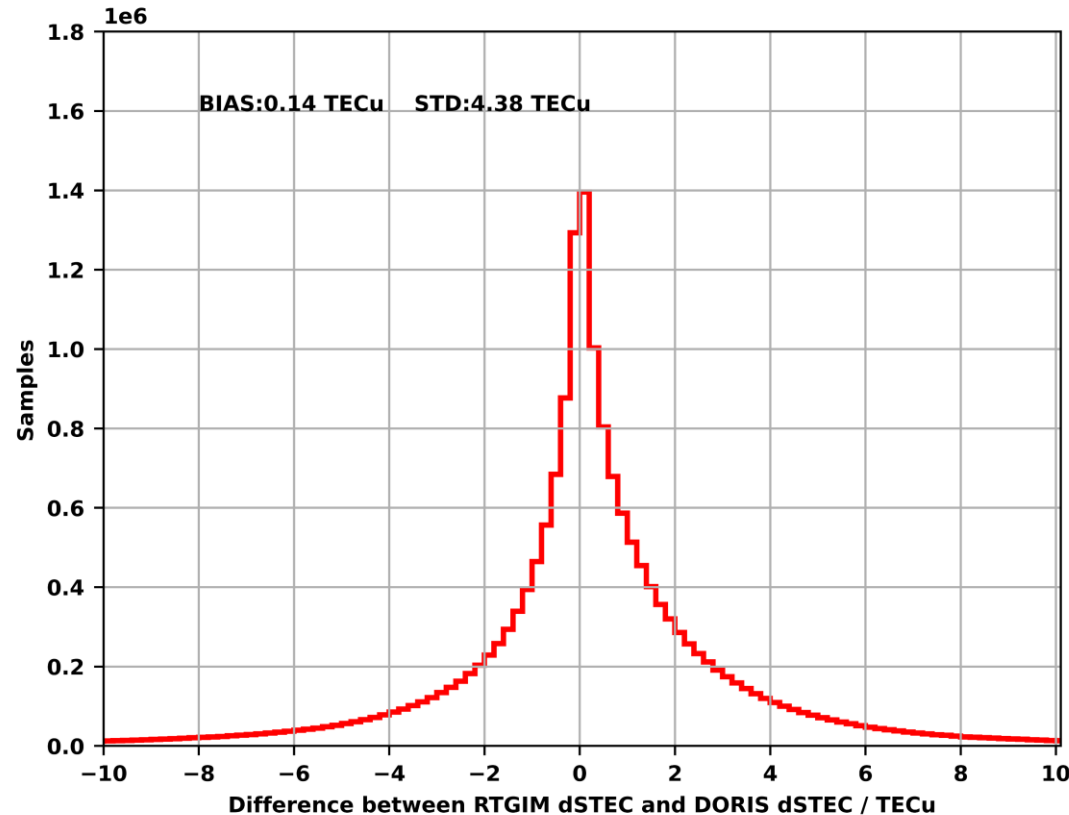


Distribution of the selected DORIS beacons



DORIS (green) and GNSS (yellow) derived ionospheric information (UT 00-02, DoY 098, 2022)

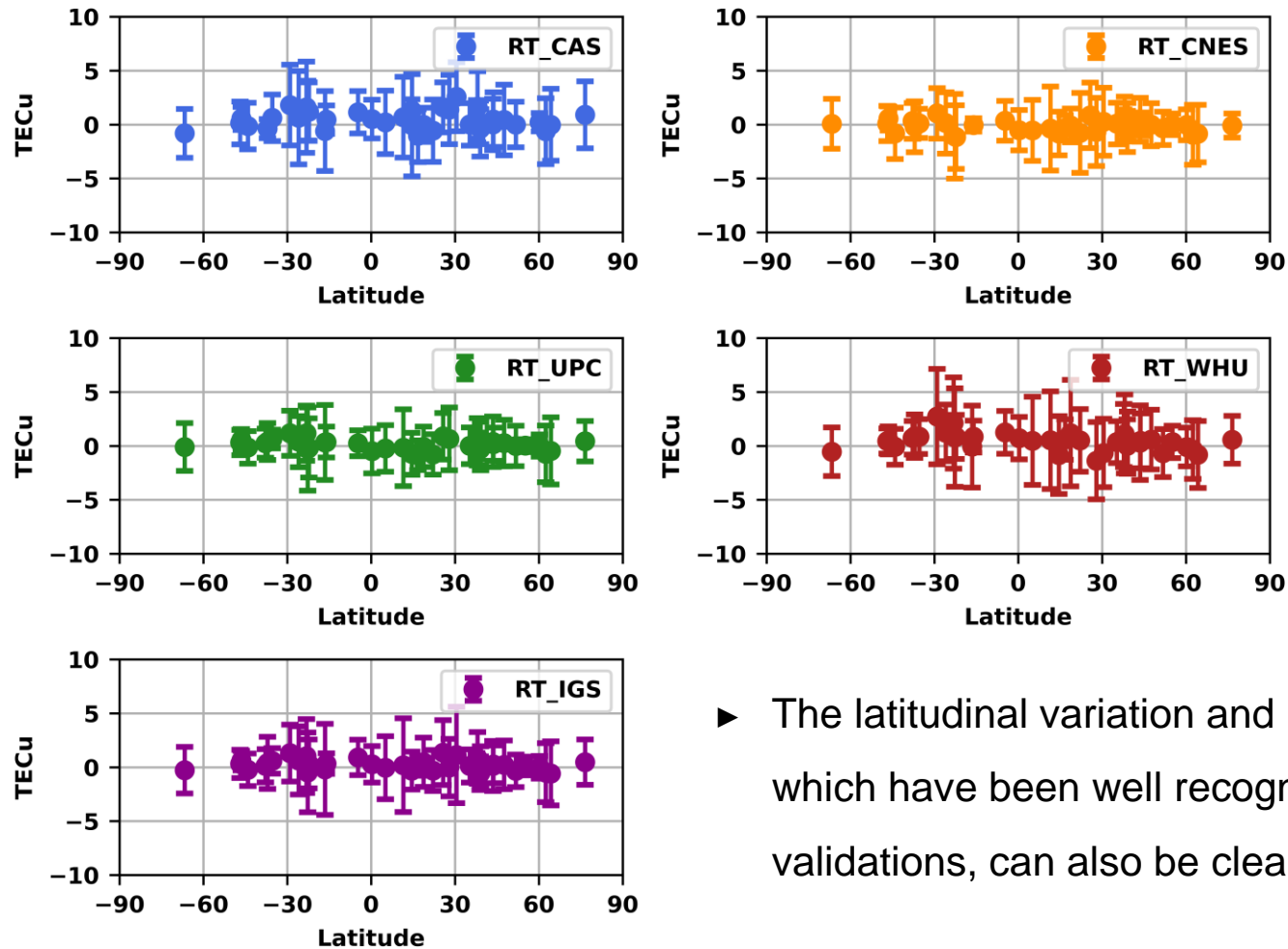
## Consistency b.w.t. RT-GIM derived and DORIS observed dSTECs



- ▶ more than 18,000,000 DORIS dSTEC observables used for the analysis.
- ▶ around 77.1% of the dSTEC differences is below +/- 3.0 TECu.
- ▶ no systematic bias found b.w.t. Jason-3 DORIS observed dSTEC and RT-GIM derived dSTEC.

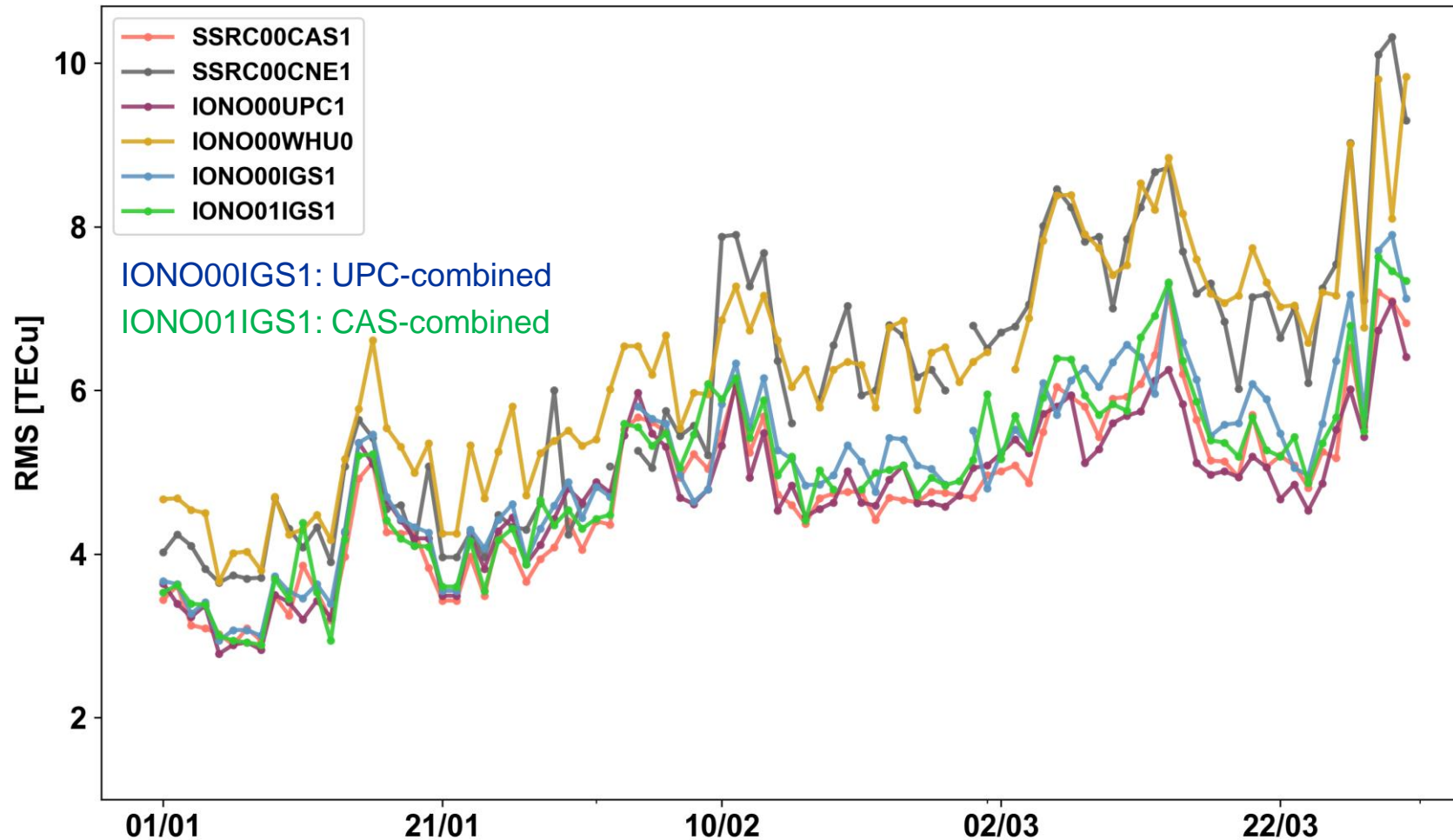
Histogram of differences b.w.t. RT-GIM derived and DORIS observed dSTECs during DOY 001–110, 2022

## Consistency b.w.t. RT-GIM derived and DORIS observed dSTECs

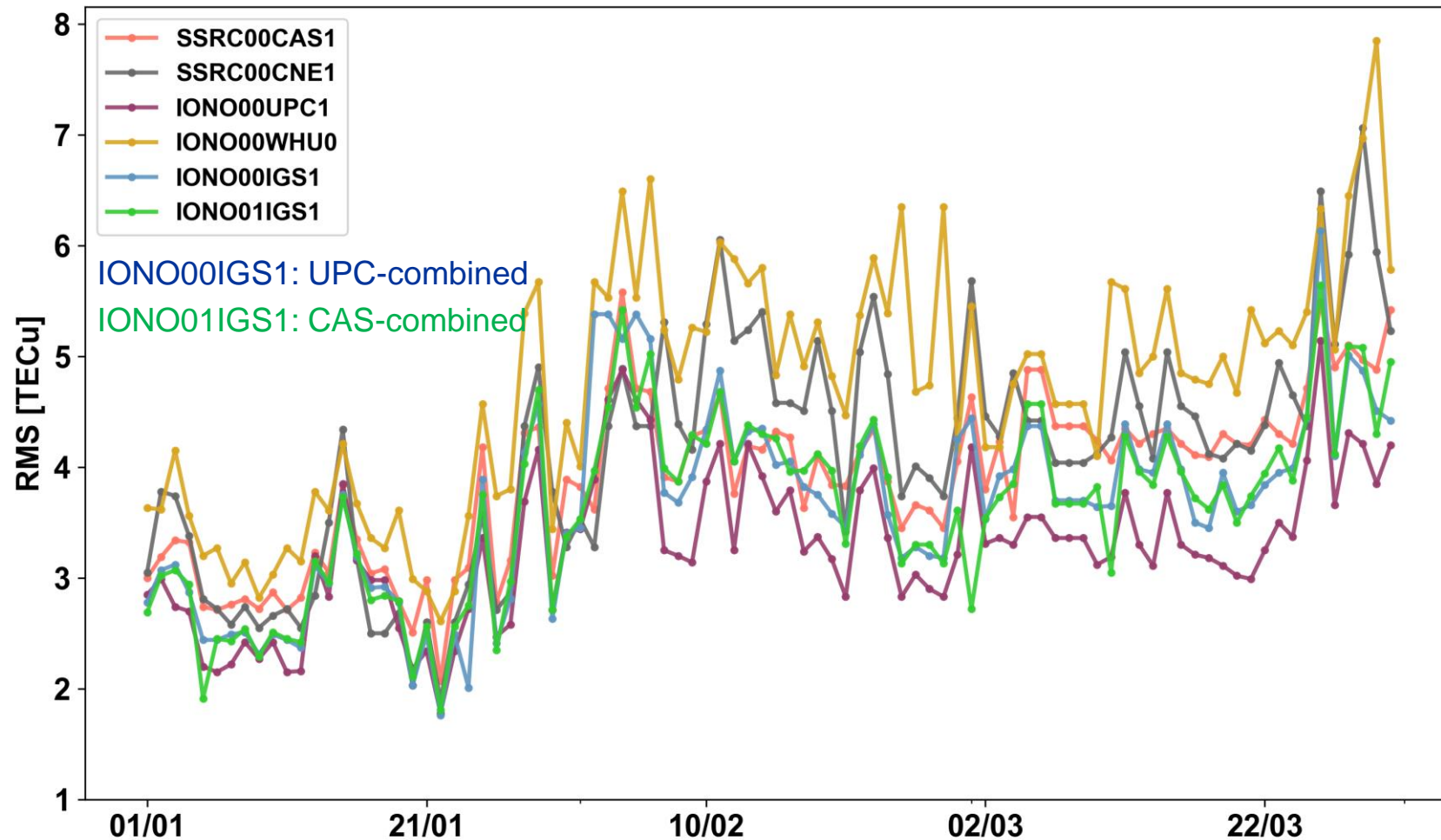


- ▶ The latitudinal variation and hemispheric asymmetry of RT-GIM errors, which have been well recognized in GPS-dSTEC or altimetry-VTEC validations, can also be clearly observed in DORIS dSTEC assessment.

Compared to **GNSS dSTEC** – 01/01-31/03, 2022

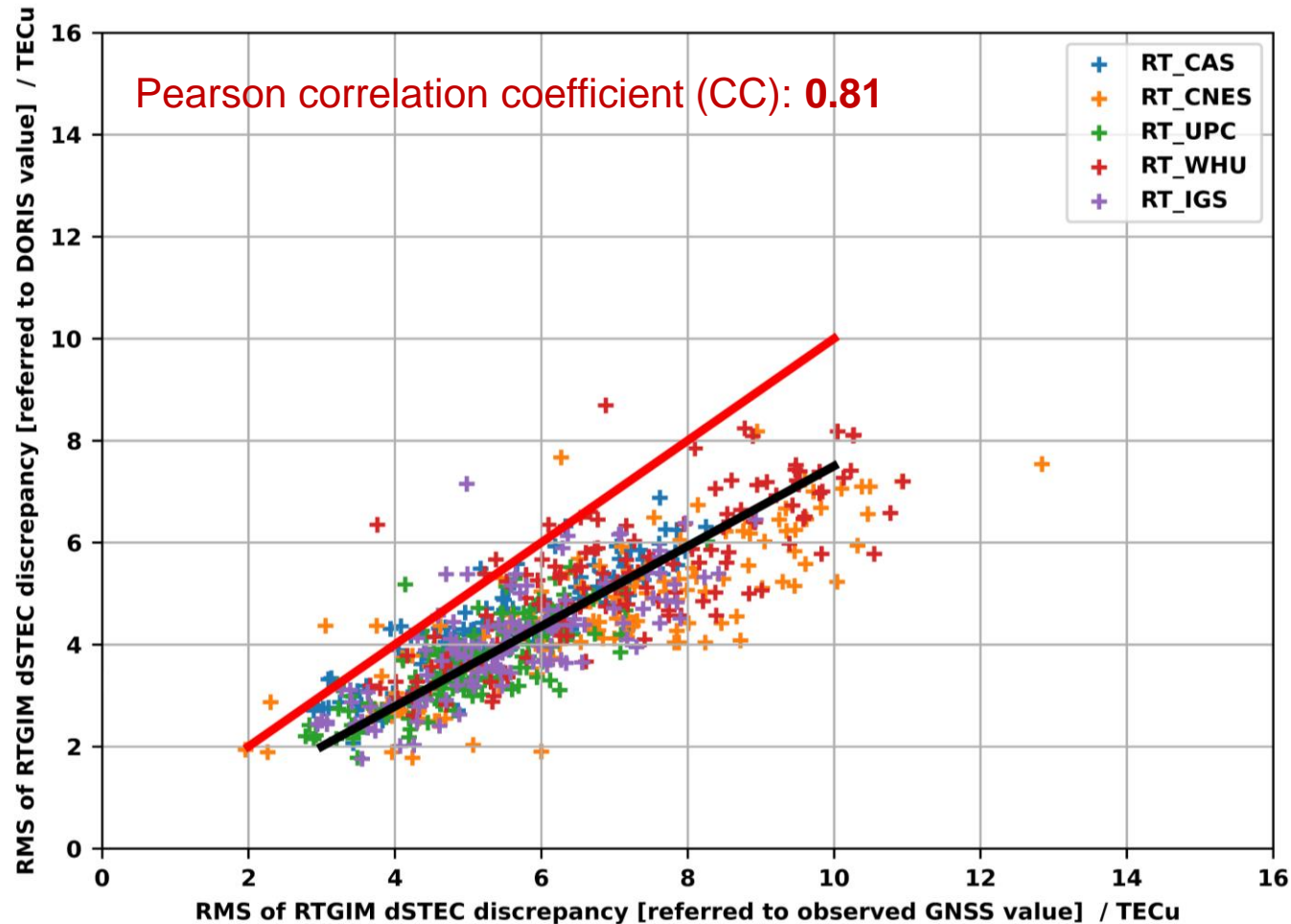


Compared to **Jason-3 DORIS dSTEC** – 01/01-31/03, 2022

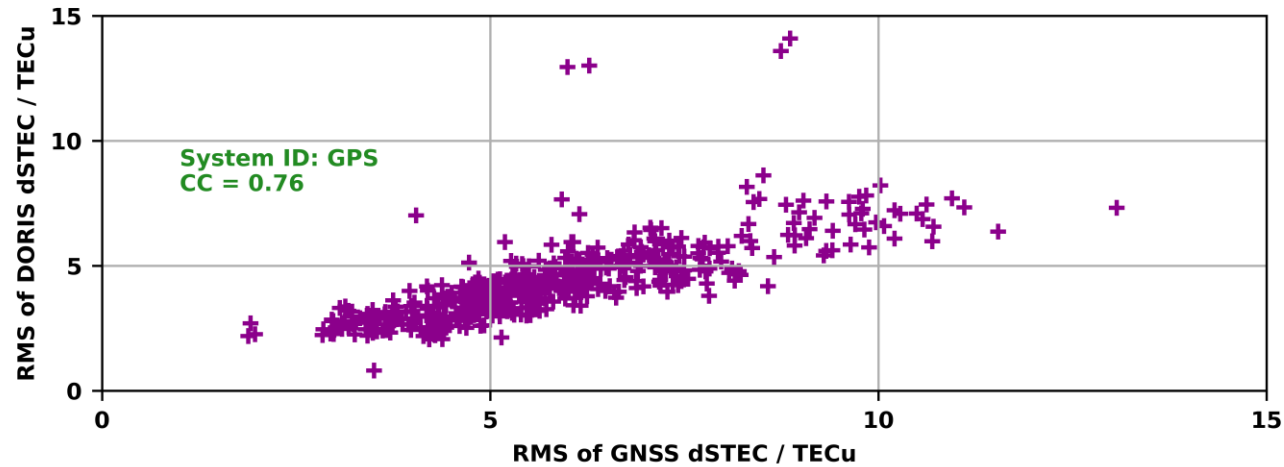




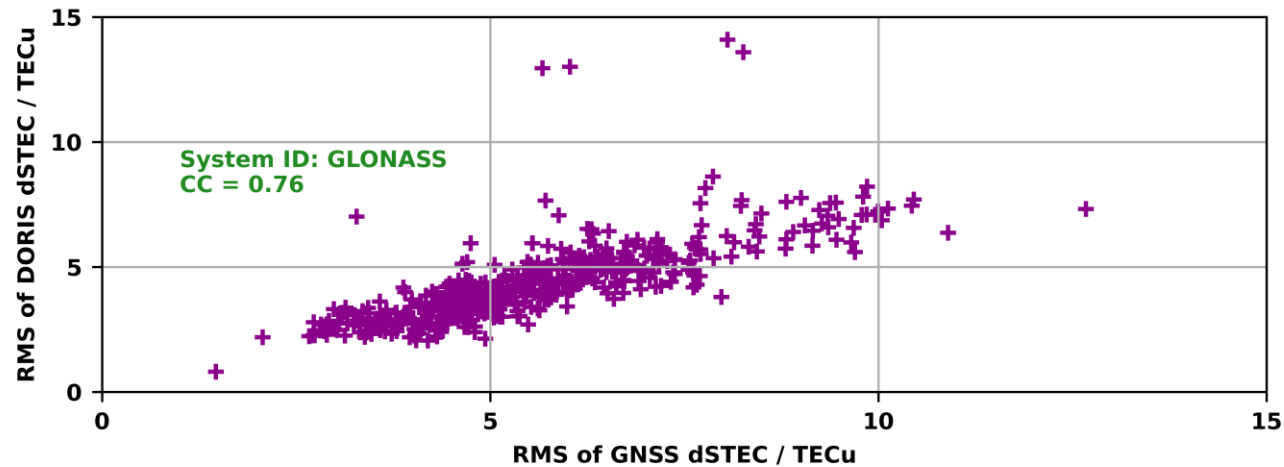
## Consistency b.w.t. DORIS (Jason-3) and GNSS (G/R) dSTE<sub>C</sub> assessments



## Consistency b.w.t. DORIS (Jason-3) and GNSS (G/R) dSTEC assessments



- ▶ **no significant dependence** on the GNSS data used
- ▶ require further verification with the use of Galileo and BeiDou observation data



- ▶ The concept of **DORIS dSTEC assessment is proposed**, which is the extension of the existing GNSS dSTEC validation method.
- ▶ Benefiting from the large relative frequency ratio between DORIS L1/L2 frequencies, **the precision of DORIS dSTEC reaches 0.028 TECu**, which is about 10 times better than that of GNSS L1/L2 dSTEC.
- ▶ Using more than 18,000,000 DORIS dSTEC observables, the bias and STD is 0.14 and 4.38 TECu between RT-GIM derived dSTEC and DORIS observed dSTEC and **no systematical bias is found**.
- ▶ The overall **correlation coefficient is 0.81** for the validation result using DORIS and GNSS dSTEC.
- ▶ To ensure a better consistency between DORIS and GNSS dSTEC assessments, the dSTEC analysis is suggested to be **performed with higher satellite elevation cutoff angle, e.g., 45°**.
- ▶ DORIS dSTEC assessment can be **used an independent way** to validate the quality of those ground GPS/GNSS generated ionospheric models.



# Thanks for your attention

In case of any questions, please feel free to contact  
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