

Facilitating the Use of the MODIS Aqua L2 SST Dataset

Peter Cornillon

Graduate School of Oceanography, University of Rhode Island, Narragansett, RI 02882, USA

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Outline

- 1 Motivation
- 2 The Problems And Their Solutions
- 3 Putting it All Together
- 4 Summary

SST Fronts and Gradients

- Features associated with SST fronts are of significant interest in oceanography.

They are important:

- In the up-scale and down-scale flux of energy in the upper ocean.
- As boundaries of water masses.
- In a broad range of biological processes.
- ...
- I study features with SST fronts identified with JF Cayula's edge detection algorithm
 - A population-based algorithm operating on 32×32 pixel regions.
- And with gradients obtained from the Sobel Gradient operator
 - Operating on a 3×3 pixel kernel.
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 - L2 data preserve the spatial relationship of pixels.
 - Higher levels of processing do not.
- I'm interested in applying these algorithms to long, global, high-resolution SST datasets.
- But such datasets (L2, global) can be hard to use for a number of reasons.

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The Dataset

- The longest, global, 1 km datasets are those obtained from MODIS.
- The primary MODIS L2 SST datasets available in GHRSSST format are the R19 version:
GHRSSST Level 2P Global Sea Surface Skin Temperature from the MODIS on the NASA Aqua/Terra satellite
- These datasets
 - Were processed by the OBPG at NASA's GSFC
 - Using the retrieval algorithm developed by the Remote Sensing Group at the UMiami.
- The Aqua dataset consists of
 - Approximately 2 million 5-minute granules.
 - From mid-2002 to present.
 - Global coverage approximately twice daily.
 - Spatial resolution approximately 1 km at nadir.
 - 10 detectors per mirror rotation.

OBPG - Ocean Biology Processing Group
GSFC - NASA's Goddard Space Flight Center

5-minute granule corresponds to the data collected by the data in 5 minutes.

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- Three basic problem areas related to fronts & gradients with the MODIS R19 datasets:
 - Granularization
 - Bow-Tie Effect
 - Quality Mask
 - Reference Temperature
 - High Gradient Regions
 - There are other issues with the quality flags
e.g., low quality pixels flagged as good
but I will not address these issues here.

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Granularization – The Problem

- MODIS orbits are divided into 5-minute granules.
- The Cayula-Cornillon edge detection algorithm operates on 32×32 pixel regions.
 - These regions are referred to as windows.
 - It begins by locating frontal candidates in the window based on pixel populations.
 - It then drops to the pixel level and contour follows gradients from the candidates.
- For these reasons matching fronts between granules is problematic.
 - It requires a minimal overlap between adjacent granules of one window.
 - Which means overlapping the granules before working on them.
 - Following location of fronts, frontal segments must be joined across the granule seams.
 - Which means that 80% is not enough.

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 - Fronts may extend beyond the window edges!
- For these reasons matching fronts between granules is problematic.
 - It requires a minimal overlap between adjacent granules of one window.
 - Which means overlapping the granules before applying the algorithm.
 - Following location of fronts, frontal segments must be joined across the granule seams.
 - A segment that is not in a window.

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 - It requires a minimal overlap between adjacent granules of one window.
 - Window seams are visible in the granules before and after the seam.
 - Following location of fronts, frontal segments must be joined across the granule seams.
 - Granules that do not overlap are problematic.

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 - It requires a minimal overlap between adjacent granules of one window.
 - Small overlaps necessitate the granules being smaller on them.
 - Following location of fronts, frontal segments must be joined across the granule seams.
 - This is not the case for the Cayula-Cornillon algorithm.

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 - This means overlapping the granules to solve the problem.
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 - If there are no overlaps between granules there is a problem on them.
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 - It requires a minimal overlap between adjacent granules of one window.
 - Which means augmenting the granules before working on them.
 - Following location of fronts, frontal segments must be joined across the granule seams.
 - It turns out that this is not straightforward.

Granularization – The Problem

- MODIS orbits are divided into 5-minute granules.
- The Cayula-Cornillon edge detection algorithm operates on 32×32 pixel regions.
 - These regions are referred to as windows.
 - It begins by locating frontal candidates in the window based on pixel populations.
 - It then drops to the pixel level and contour follows gradients from the candidates.
 - Fronts may extend beyond the window edges!
- For these reasons matching fronts between granules is problematic.
 - It requires a minimal overlap between adjacent granules of one window.
 - Which means augmenting the granules before working on them.
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Granularization – The Solution

- Granules are merged into complete orbits.
- Orbits are started with the nadir pixel nearest 78°S on the descending part of the orbit.
 - Choosing this latitude minimizes the ocean area where orbits begin.
i.e., it reduces the seam problem at the beginning/end of an orbit.
- Orbits overlap by 100 pixels.
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This is only an issue for a small portion of the Southern Ocean.

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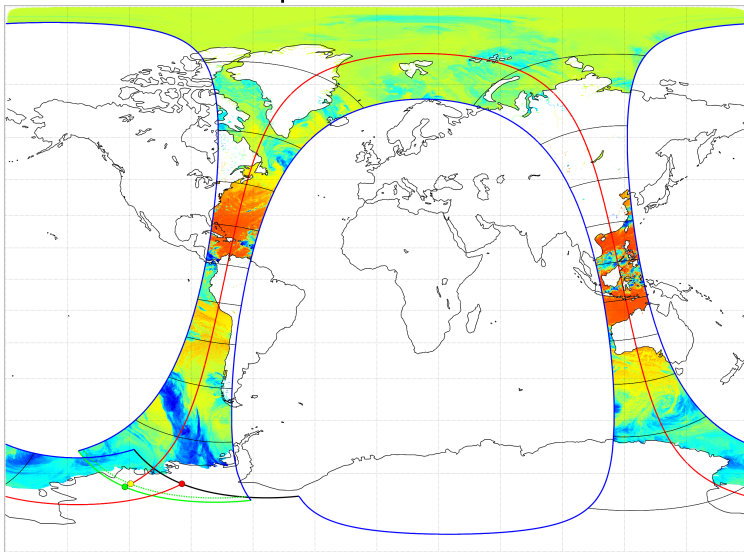
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Granularization – The Solution – 20 Granules \Rightarrow 1 orbit

MODIS Aqual L2 SST 05h15 19 June 2010



Bow-Tie Effect – The Problem

- As the distance from nadir increases the size & shape of pixels on a scan line changes:
 - The along-scan size of a pixel increases substantially
 - The along-track size of a pixel increases slightly
- For a single detector scanner (e.g., AVHRR) this is not a major problem:
 - The along-scan separation of pixels increases away from nadir with adjacent along-scan pixels touching.
 - The along-track separation of pixels is independent of distance from nadir with some overlap of adjacent along-track pixels.
- For multi-detector scanners this is a problem.
 - The along-scan properties remain the same, however
 - The along-track separation of pixels depends on position in the detector group.
 - The detector group consists of 10 detectors for AVHRR.
 - This effect becomes significant less than 1/2 way from nadir to the swath edge!

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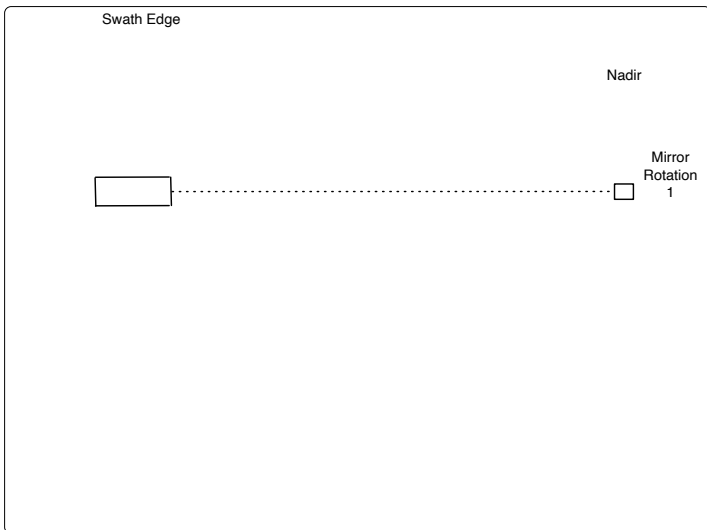
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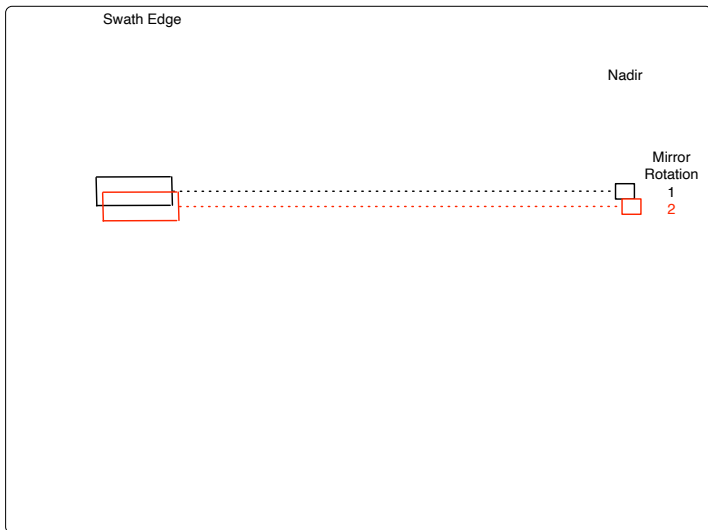
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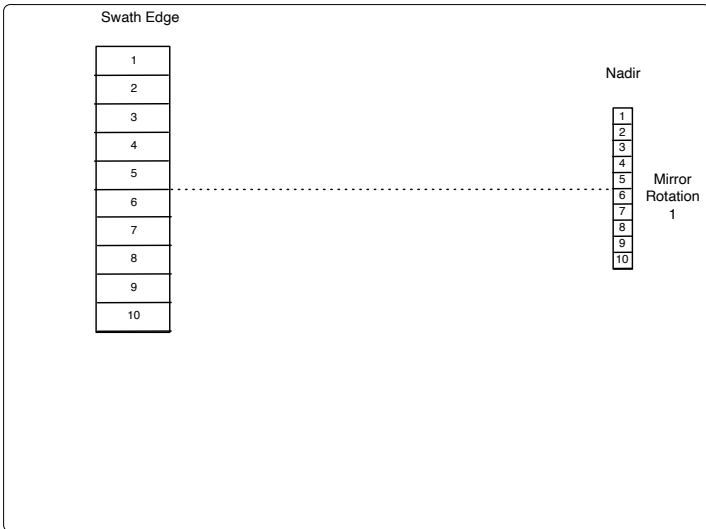
Bow-Tie Effect - Graphically - Single Detector 1st Mirror Rotation



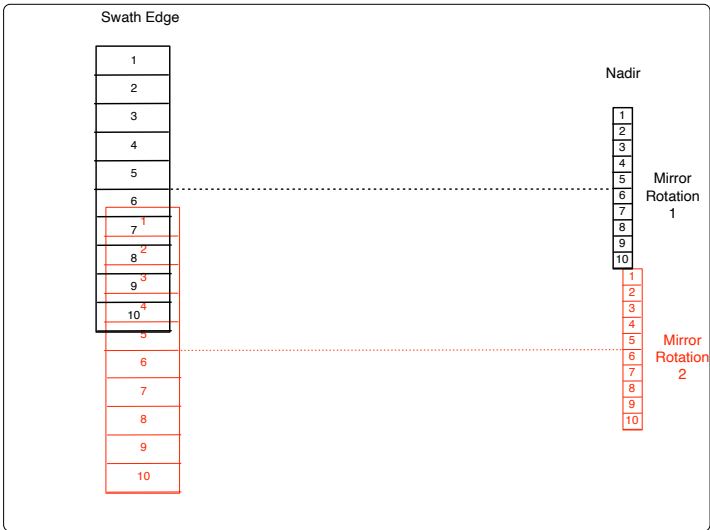
Bow-Tie Effect - Graphically - Single Detector 1st & 2nd Mirror Rotation



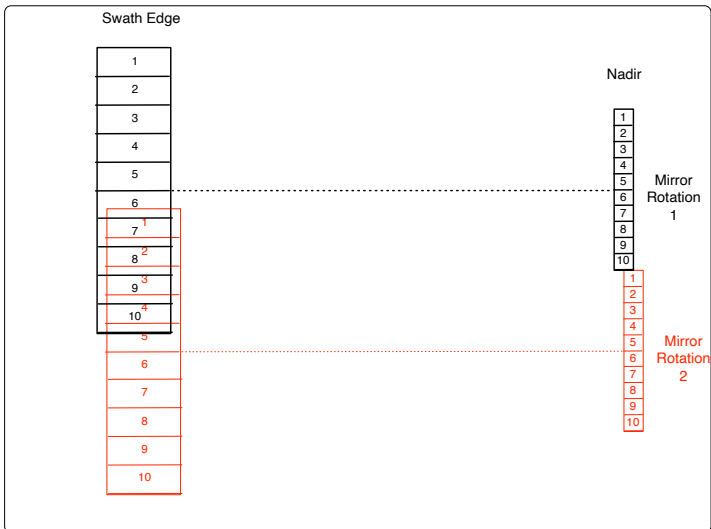
Bow-Tie Effect - Graphically - 10-Detector 1st Mirror Rotation



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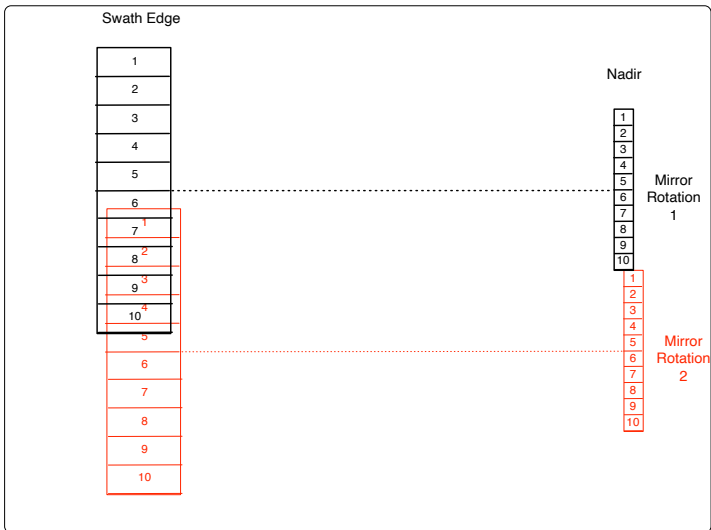


Bow-Tie Effect



This clearly plays havoc on the calculation of along-track gradients.

Bow-Tie Effect



This clearly plays havoc on the calculation of along-track gradients.
 And the problem is not just at nadir.

Bow-Tie Effect – The Solution

- I use Matlab's *griddata* function to regrid the data in the along-track direction. Specifically,
 - At each along-scan pixel location
 - Calculate the separation of the 5th detector in adjacent mirror rotations.
 - Determine the new along-track pixel locations for the 10 detectors.
 - Regrid from the original array to the new array using the *linear interpolation* scheme.
 - This is *very slow*, ≈ 5 minutes per full orbit & there are $\approx 100,000$ orbits.
 - Construct a look-up table based on the *griddata* reconstruction to speed it up.
 - The result allows for an orbit to be regridded in ≈ 7 seconds.

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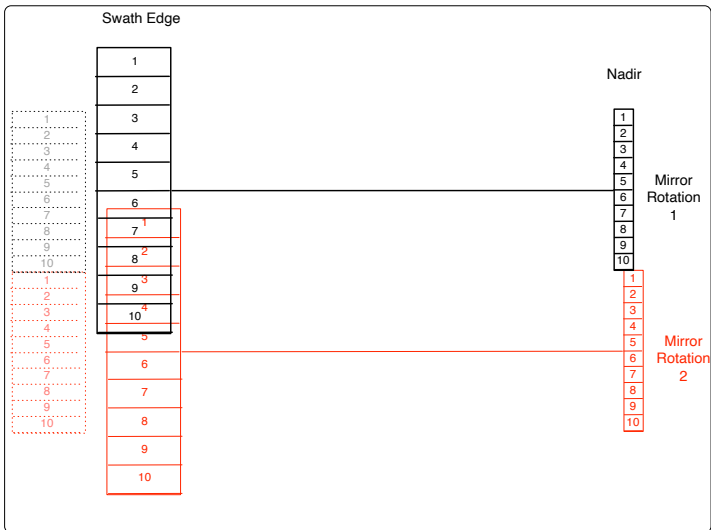
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Bow-Tie Effect – Graphically



Quality Mask

- The quality of each pixel is flagged from 0 to 5 based on a variety of criteria.
- One of the criteria is based on the difference between the retrieved SST and a reference SST.
 - This threshold is exceeded in regions of high dynamic variability and large changes in SST.

Quality Mask

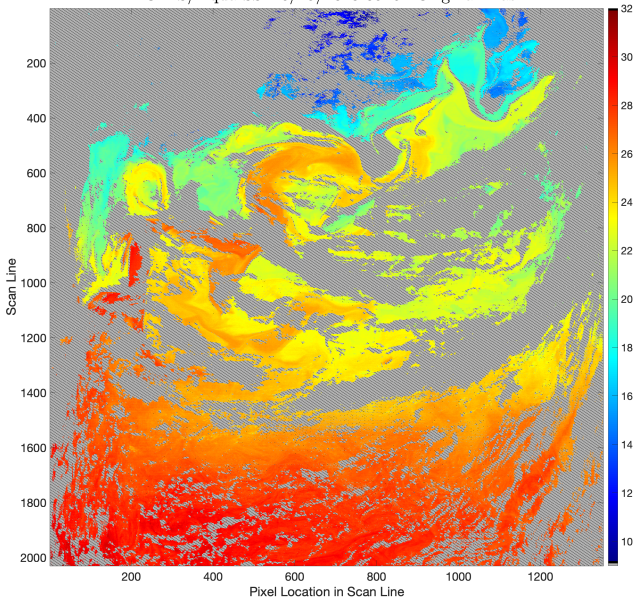
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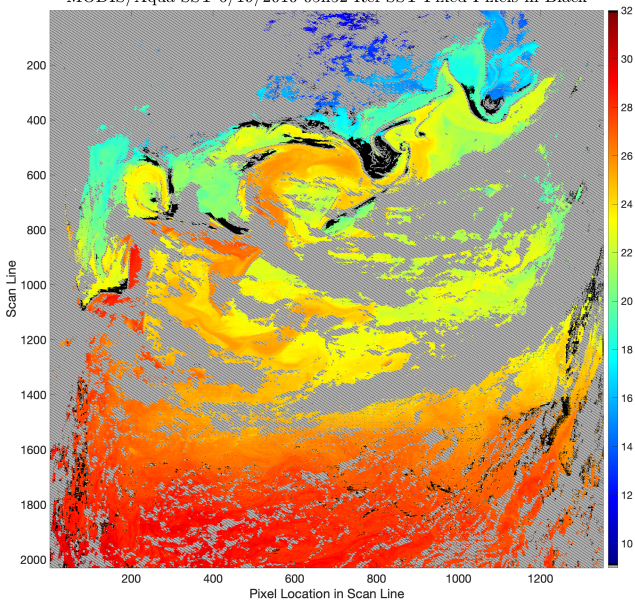
Quality Mask

MODIS/Aqua SST 6/19/2010 05h52 Original Mask



Quality Mask – Reference Temperature – The Problem

MODIS/Aqua SST 6/19/2010 05h52 Ref SST Fixed Pixels in Black



Quality Mask – Reference Temperature – The Solution

- The OBPG granules include a variable of the results for each of the threshold tests: *flags_sst*
 - This field is *not* included in the PO.DAAC version of the files ← an additional problem.
- Construct global, monthly $5^\circ \times 5^\circ$ grids of maximum Δ SST.
 - From nighttime fields for 2002-2019 generate 128×128 pixel regions > 95% clear.
 - This defines the 90% range of values in the “good” pixels.
 - For each monthly, $5^\circ \times 5^\circ$ grid location determine the 90% range of maximum Δ SST.
- Replace the quality flag based on

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Quality Mask – Reference Temperature – The Solution

- The OBPG granules include a variable of the results for each of the threshold tests: *flags_sst*
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- Construct global, monthly $5^\circ \times 5^\circ$ grids of maximum Δ SST.
 - From nighttime fields for 2002-2019 generate 128×128 pixel regions $> 95\%$ clear.
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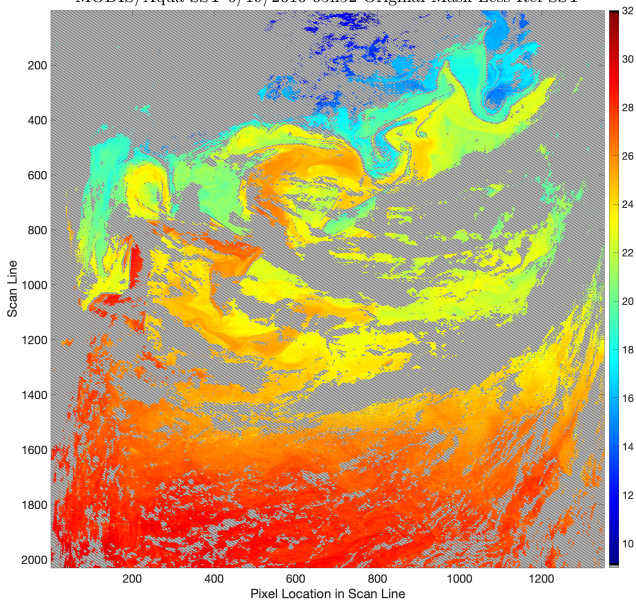
- Another criterion is based on the range of brightness temperatures in a 3×3 pixel square.
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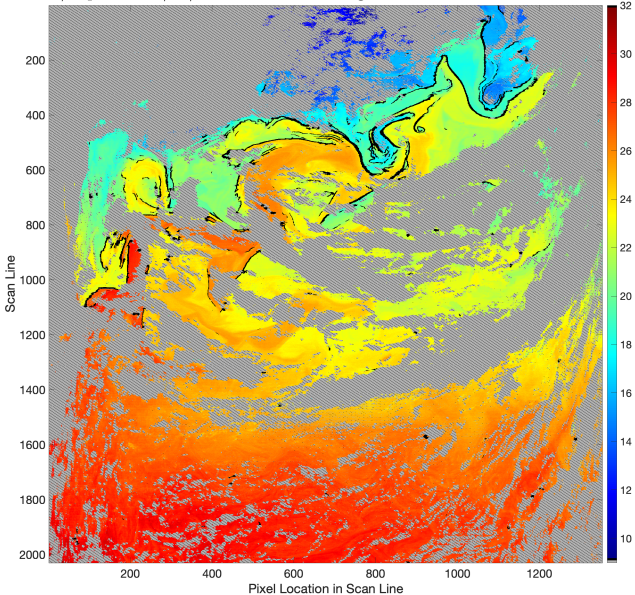
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MODIS/Aqua SST 6/19/2010 05h52 Original Mask Less Ref SST



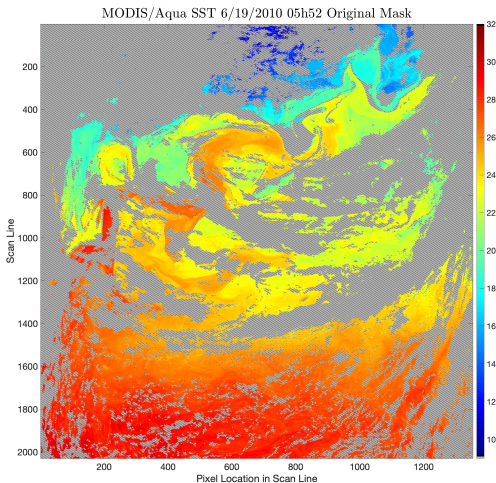
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MODIS/Aqua SST 6/19/2010 05h52 Fixed High Gradient Pixels in Black Ref Fixed



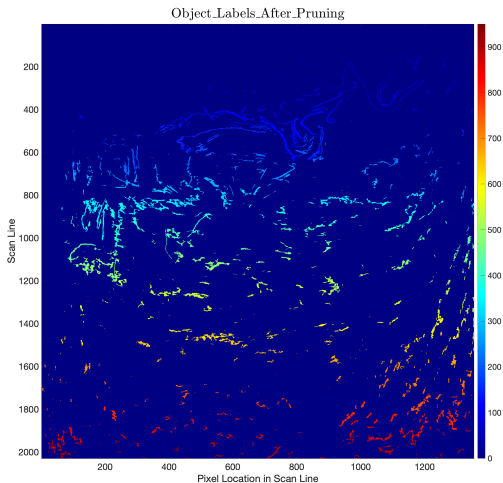
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 - ⇒ flag object as good or bad.



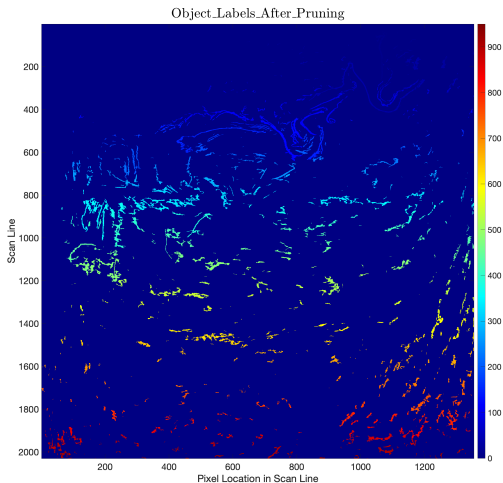
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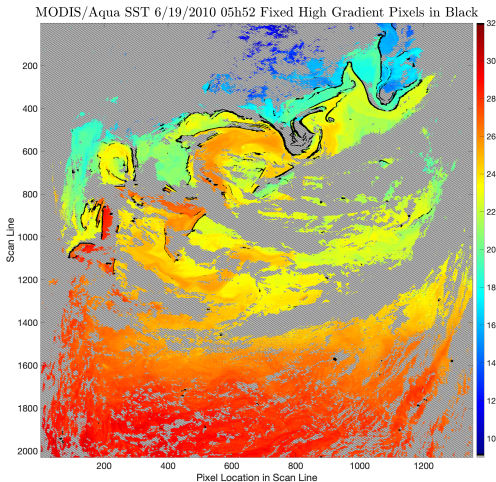
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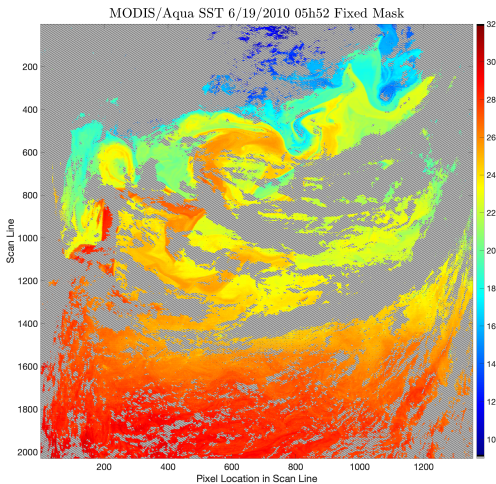
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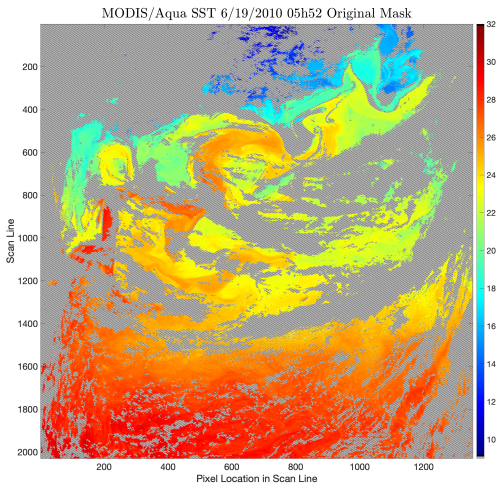
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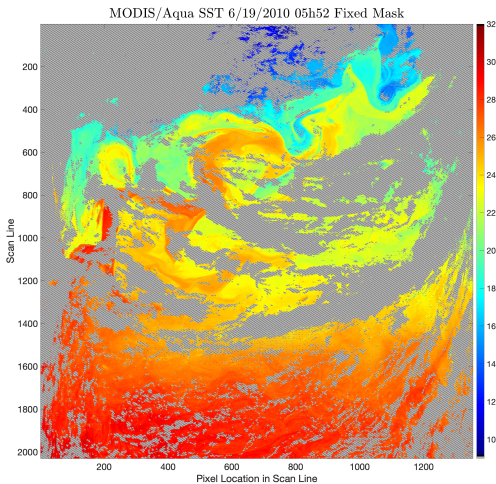
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- 1 Motivation
- 2 The Problems And Their Solutions
- 3 Putting it All Together**
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The Basic Processing Steps

- 1 Assemble granules into complete orbits beginning at descending 78°S .
- 2 Regrid to address the bow-tie effect.
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 - Quality mask will be modified to fix high gradient and reference SST problems.
 - Gradients will be calculated.
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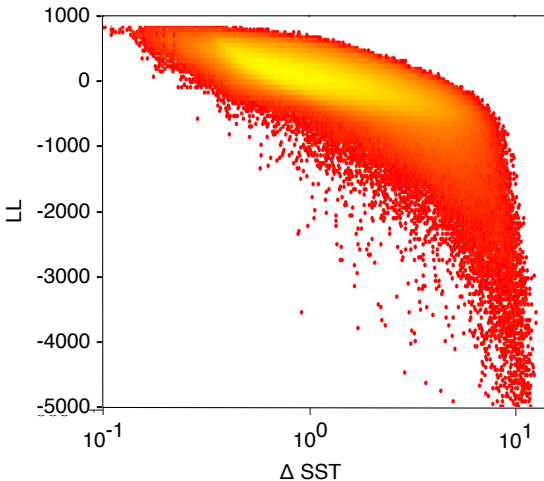
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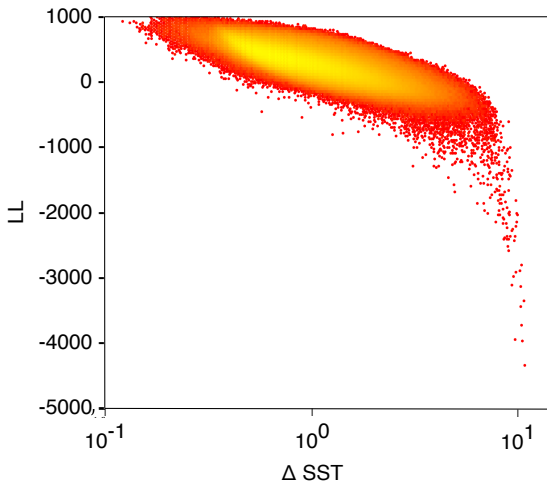


Quality Mask – The Problem – An Aside 95% Clear



Courtesy J.X. Prochaska. Also see: Madolyn Kelm's poster/ S1 highlights: *Using Deep Supervised Learning to Explore and Identify Patterns within Sea Surface Temperature Data*

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