

Define engineering quantities

E_i Young's modulus along direction i $E_i = \frac{\sigma_{ii}}{\epsilon_{ii}}$

G_{ij} Shear modulus in plane with normal i in direction j $G_{ij} = \frac{\sigma_{ij}}{2 \epsilon_{ij}}$

ν_{ij} Poisson's ratio due to load applied in direction i and measured response in direction j $\nu_{ij} = - \frac{\epsilon_{jj}}{\epsilon_{ii}}$

$i, j \in [x, y, z]$

Implications

$G_{ij} = G_{ji}$ because of symmetry of σ, ϵ

$\left(\frac{\nu_{12}}{E_1} = \frac{\nu_{21}}{E_2} \right)$ because of symmetry of compliance (see below)
note, that $\nu_{12} \neq \nu_{21}$! Distinguish cause and effect!

Orthotropy

$$\sigma^{-1} = \begin{bmatrix} \frac{1}{E_1} & -\frac{\nu_{21}}{E_2} & -\frac{\nu_{31}}{E_3} & & & \\ -\frac{\nu_{12}}{E_1} & \frac{1}{E_2} & -\frac{\nu_{32}}{E_3} & & & \\ -\frac{\nu_{13}}{E_1} & -\frac{\nu_{23}}{E_2} & \frac{1}{E_3} & & & \\ & & & \frac{1}{G_{23}} & & \\ & & & & \frac{1}{G_{31}} & \\ & & & & & \frac{1}{G_{12}} \end{bmatrix}$$

Voigt

$$= \begin{bmatrix} \frac{1}{E_1} & -\frac{\nu_{12}}{E_1} & -\frac{\nu_{13}}{E_1} & & & \\ & \frac{1}{E_2} & -\frac{\nu_{23}}{E_2} & & & \\ & & \frac{1}{E_3} & & & \\ & & & \frac{1}{G_{23}} & & \\ & & & & \frac{1}{G_{13}} & \\ & & & & & \frac{1}{G_{12}} \end{bmatrix}$$

Voigt

sym

nicer

\Rightarrow 9 parameters:

E_1, E_2, E_3

$\nu_{12}, \nu_{13}, \nu_{23}$

G_{12}, G_{13}, G_{23}

unused (dependent):

$$\nu_{21} = \frac{E_2}{E_1} \nu_{12}$$

$$\nu_{31} = \frac{E_3}{E_1} \nu_{13}$$

$$\nu_{32} = \frac{E_3}{E_2} \nu_{23}$$

Bounds:

$$E_m > 0 \quad m \in [1, 2, 3]$$

$$G_n > 0 \quad n \in [12, 13, 23]$$

Transversal Isotropy

Special case of Orthotropy with

bindings:

$$E_2 = E_3$$

\Rightarrow

$$E_1$$

$$E_{11}$$

$$G_{12} = G_{13}$$

$$E_2$$

$$E_3, E_{\perp}$$

$$v_{12} = v_{13}$$

$$G_{12}$$

$$G_{13}, G_{11}, G_{21}, G_{31}$$

$$\left[v_{23} = \frac{E_2}{2G_{23}} - 1 \right]$$

$$G_{23}$$

$$G_{\perp}, G_{32}, G_{in\ plane}$$

or

$$v_{23}$$

$$v_{32} \text{ due to isotropy in plane}$$

$$v_{12}$$

$$v_{13}$$

\Rightarrow Transversal Isotropic = Orthotropic (

Preferred, primary args

$$E_1 = \textcircled{E_1}$$

$$E_2 = \textcircled{E_2}$$

$$E_3 = E_{11}$$

$$v_{12} = \textcircled{v_{12}}$$

$$\text{or } \frac{E_1}{E_2} v_{21}$$

$$v_{13} = v_{11}$$

"

$$v_{23} = v_{23}$$

$$\text{or } \frac{E_2}{2 \textcircled{G_{23}}} - 1$$

$$G_{12} = \textcircled{G_{12}}$$

$$G_{13} = "$$

$$G_{23} = \frac{E_2}{2(1+v_{23})} \text{ or } G_{23}$$

)

Valid argument combinations:

Combinations of length 5 out of $\{E_1, E_2, G_{23}, G_{12}, v_{12}, v_{21}, v_{23}\}$

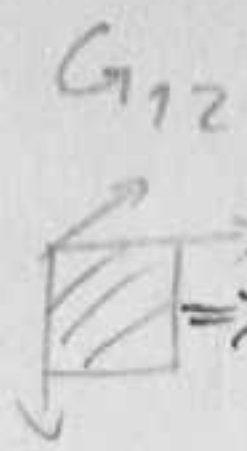
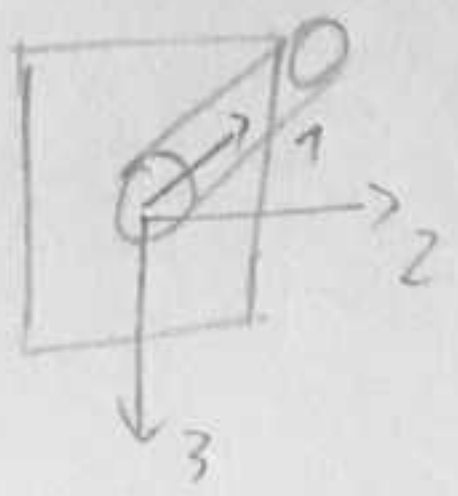
with $[E_1, E_2, G_{12}]$ in combinations

and G_{23} or v_{23} in combinations

and v_{12} or v_{21} in combinations

$$\Rightarrow [E_1, E_2, G_{12}] + \left\{ \begin{array}{l} [G_{23}, v_{12}] \\ [G_{23}, v_{21}] \\ [v_{12}, v_{23}] \\ [v_{21}, v_{23}] \end{array} \right\} \text{ 4 combinations + aliases}$$

Notes on Engineering constants



$G_{ij} = G_{ji}$ because σ, ϵ are symmetric

