
Mapping global dynamics of benchmark creation and saturation in artificial intelligence

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Supplementary Information

Suppl. Figure 1: Global SOTA improvement map for computer vision. Anchors (vertical dashes) and only multiple dot trajectories shown in the plot.

Suppl. Figure 2: Global SOTA improvement map with single gain result for NLP.

Suppl. Figure 3: Global SOTA improvement map with single gain result for computer vision.

Suppl. Figure 4: Global SOTA improvement map with aggregated superclasses for NLP.

Suppl. Figure 5: Global SOTA improvement map with aggregated superclasses for computer vision.

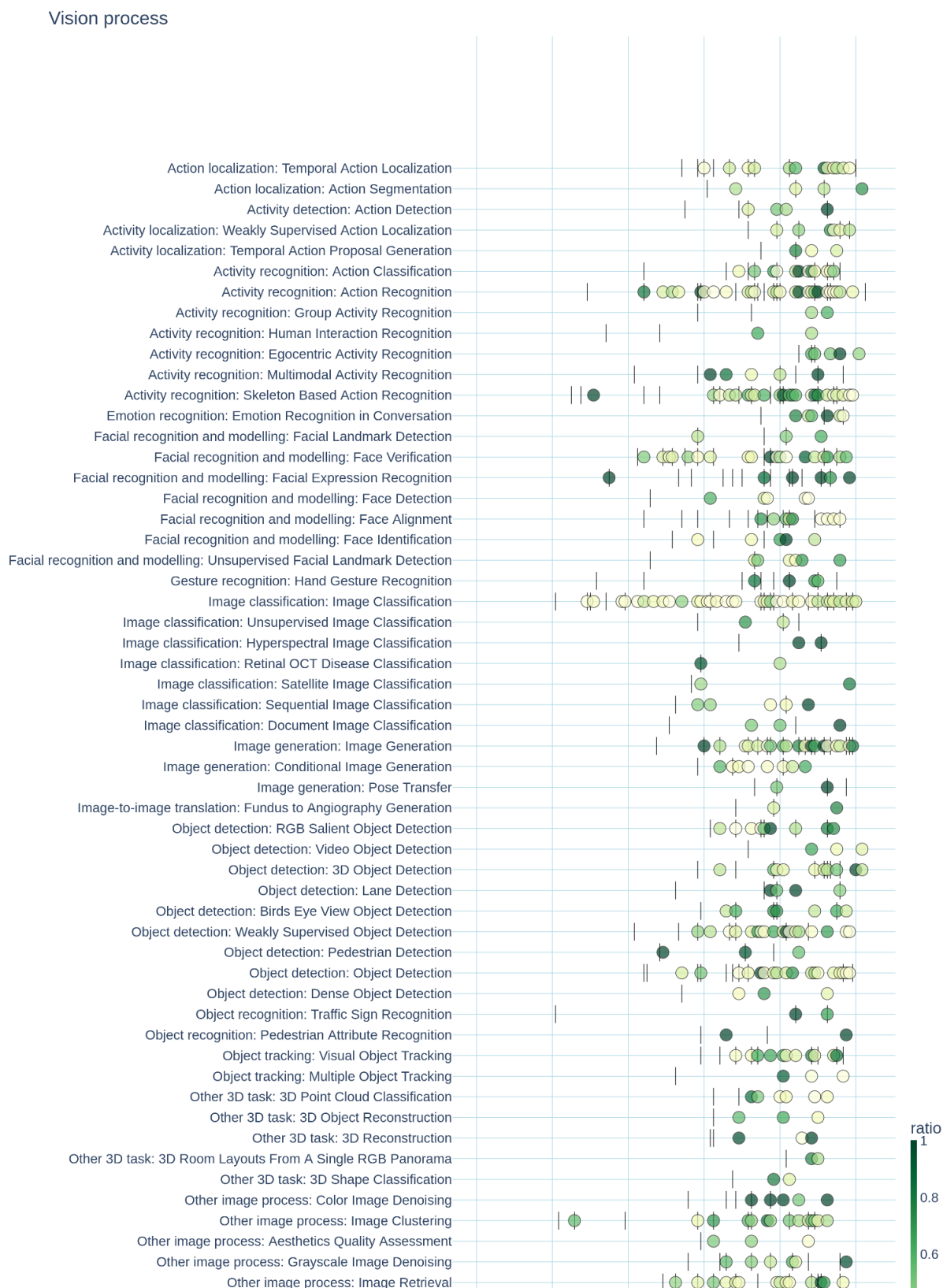
Suppl. Figure 6: AI benchmark lifecycle map for computer vision.

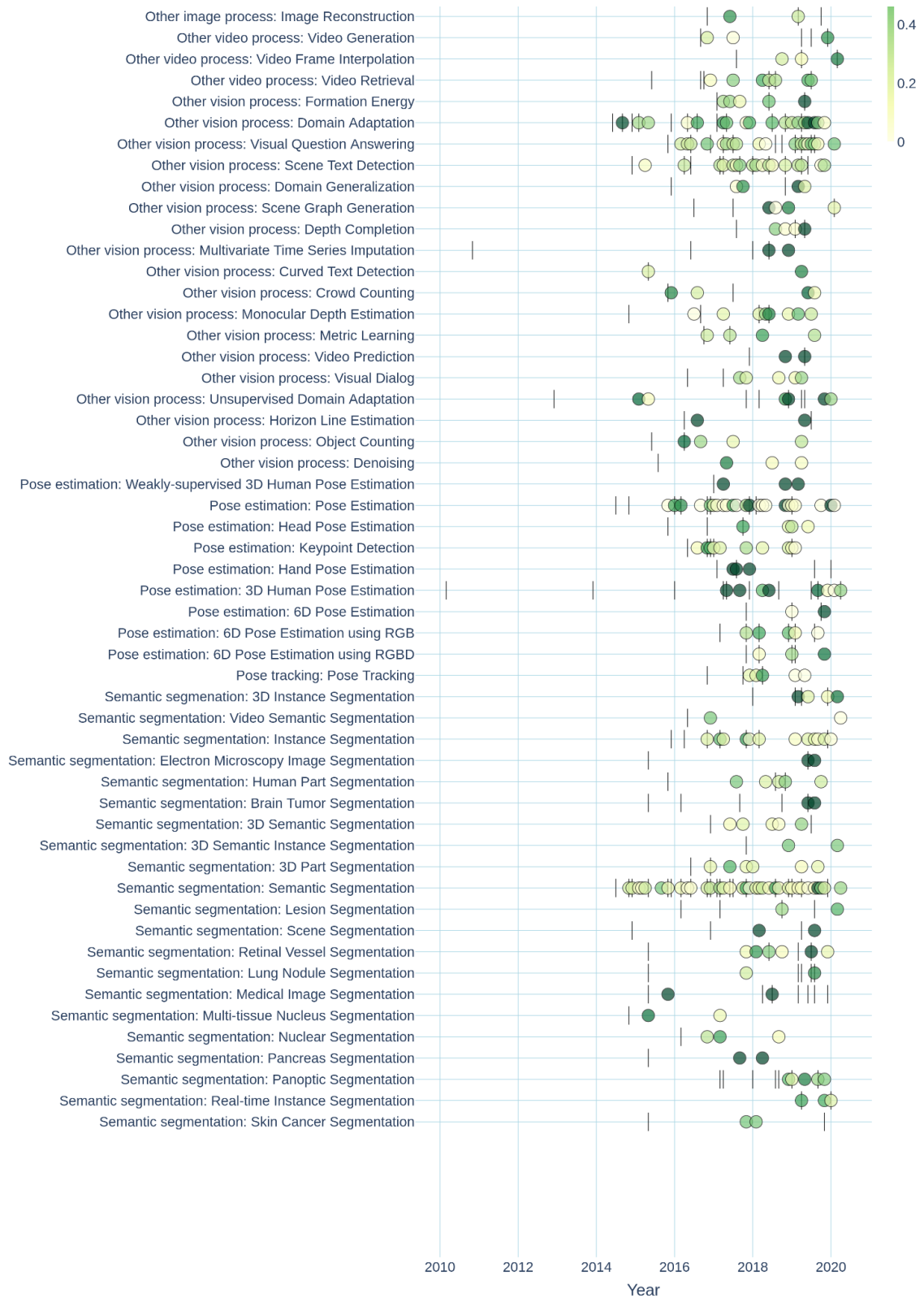
Suppl. Figure 7: Number of active benchmarks vs. number of benchmarks reporting novel SOTA results over time for computer vision tasks.

High definition images of all figures are available here:

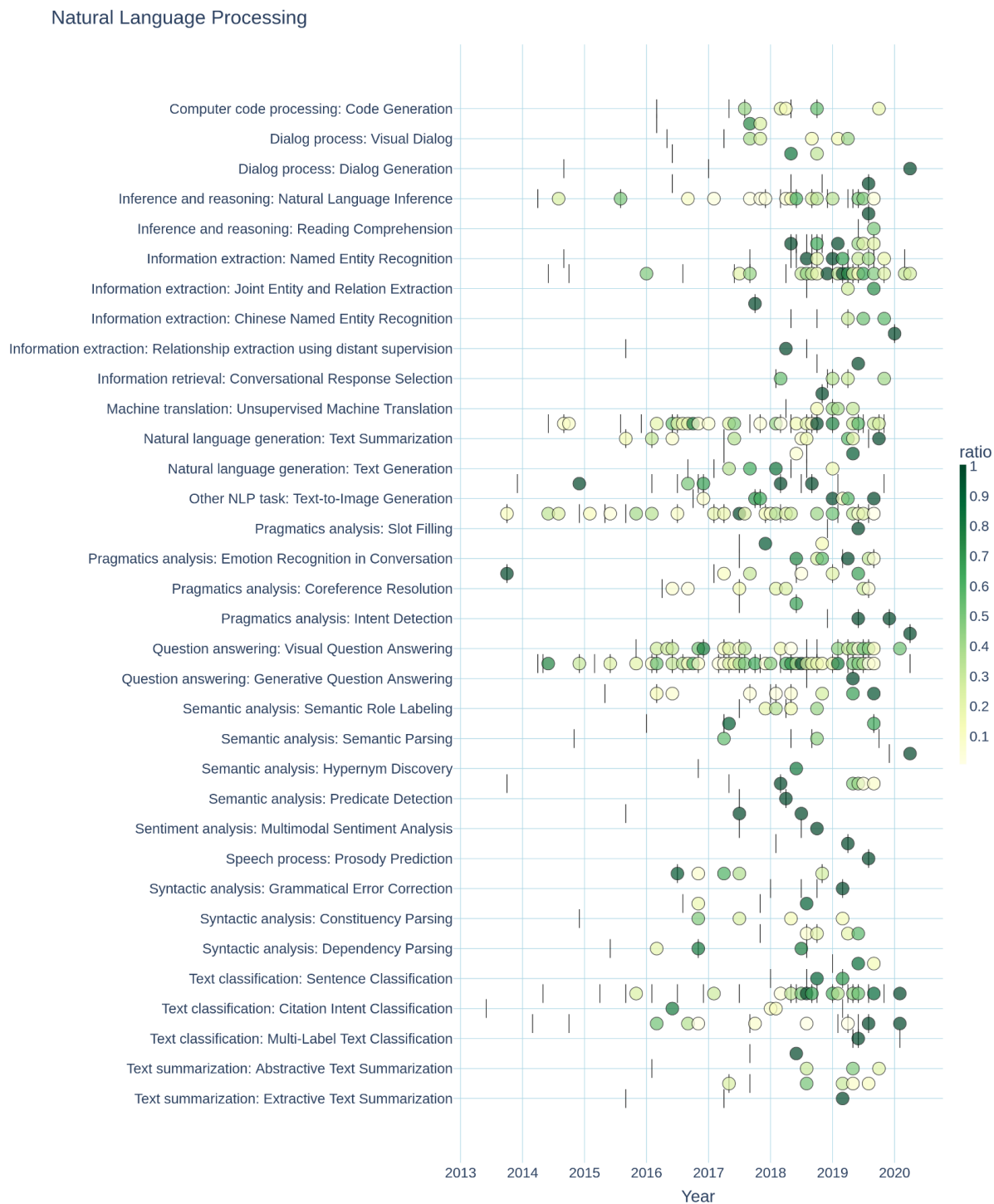
https://drive.google.com/drive/folders/1OlU13253wzxVIbEMGHcB_duGIoHlVCO1?usp=sharing

Supplementary Figure 1: Global SOTA improvement map for computer vision. Anchors (vertical dashes) and only multiple dot trajectories shown in the plot.



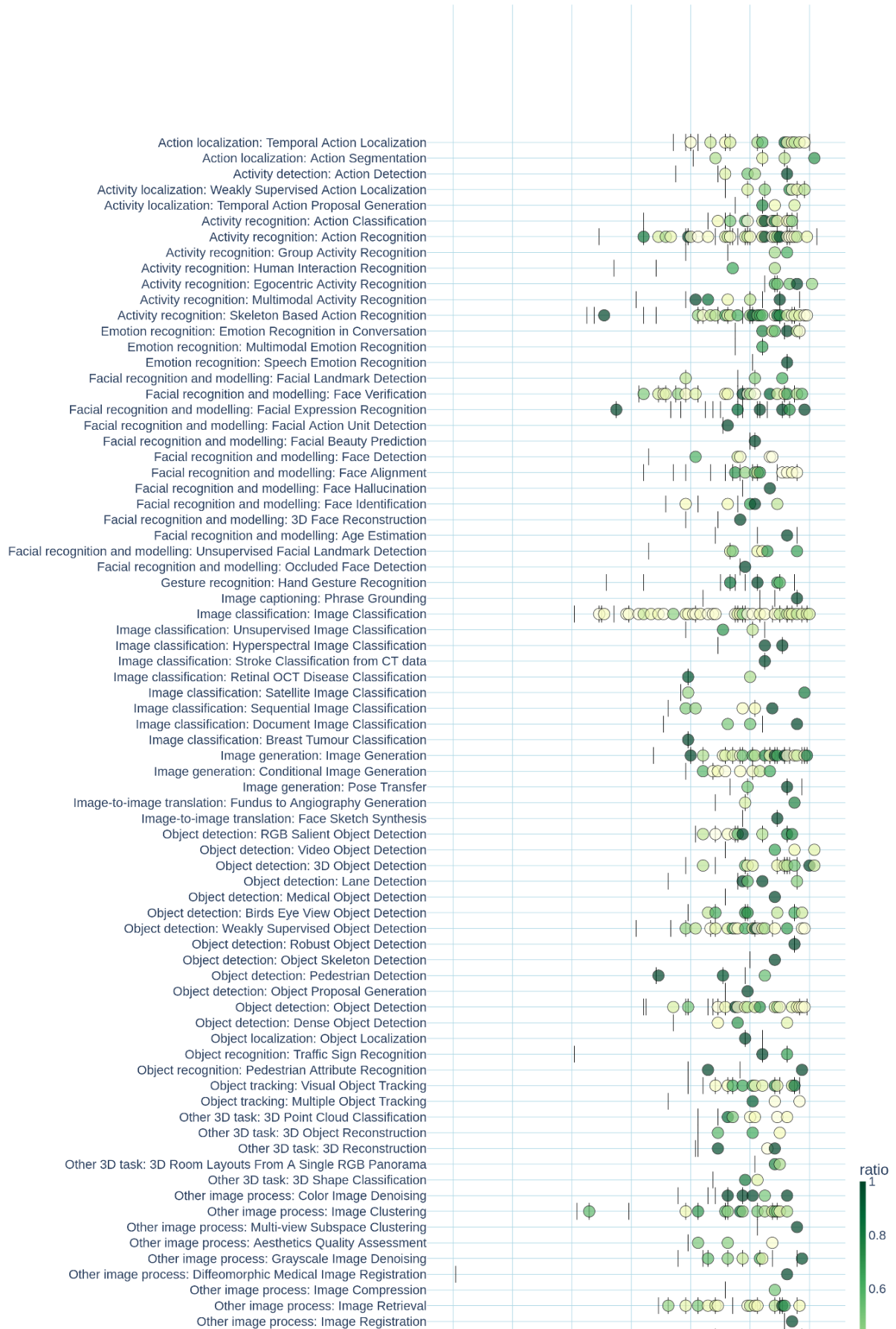


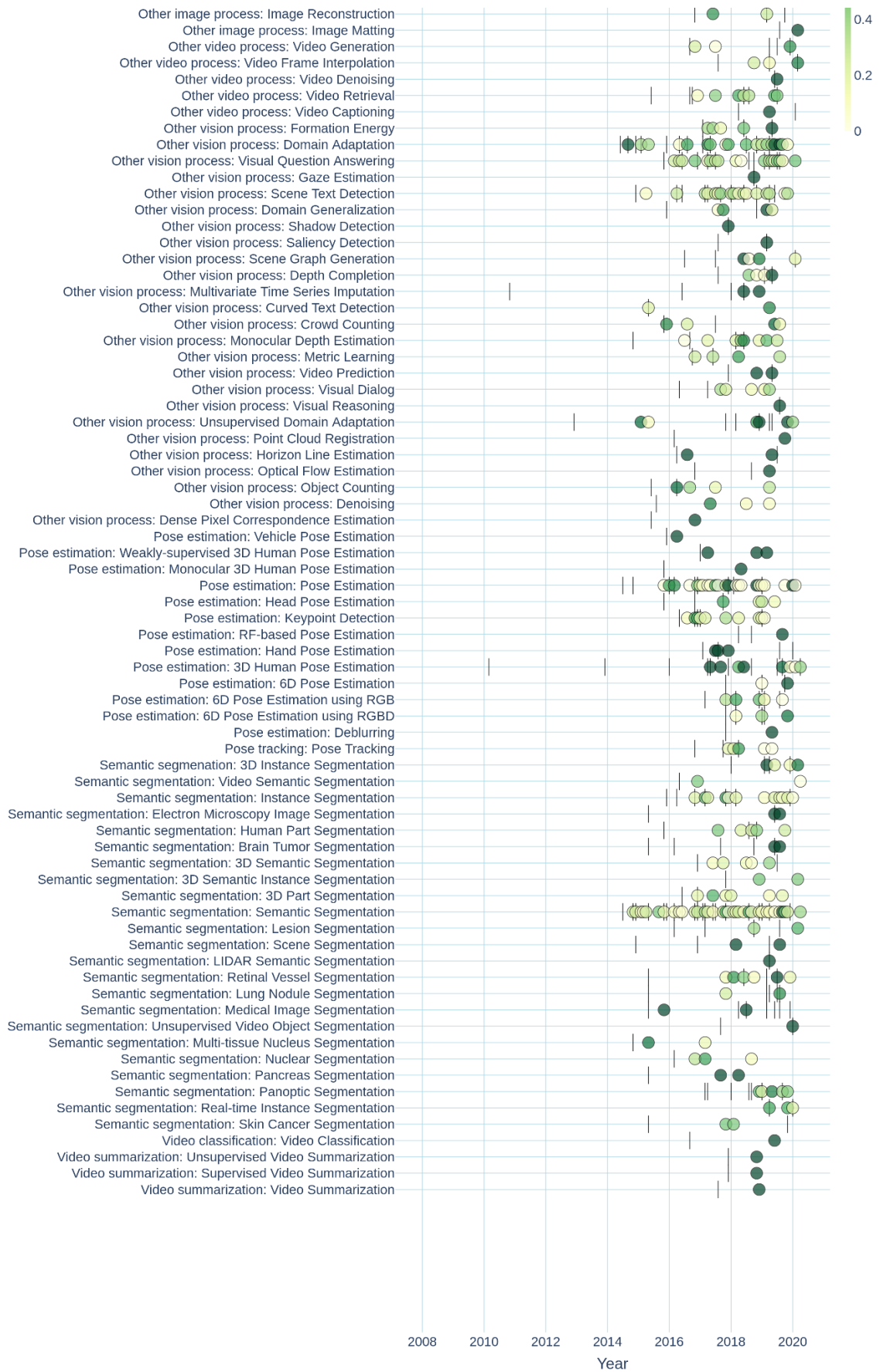
Suppl. Figure 2: Global SOTA improvement map with single gain result for NLP.



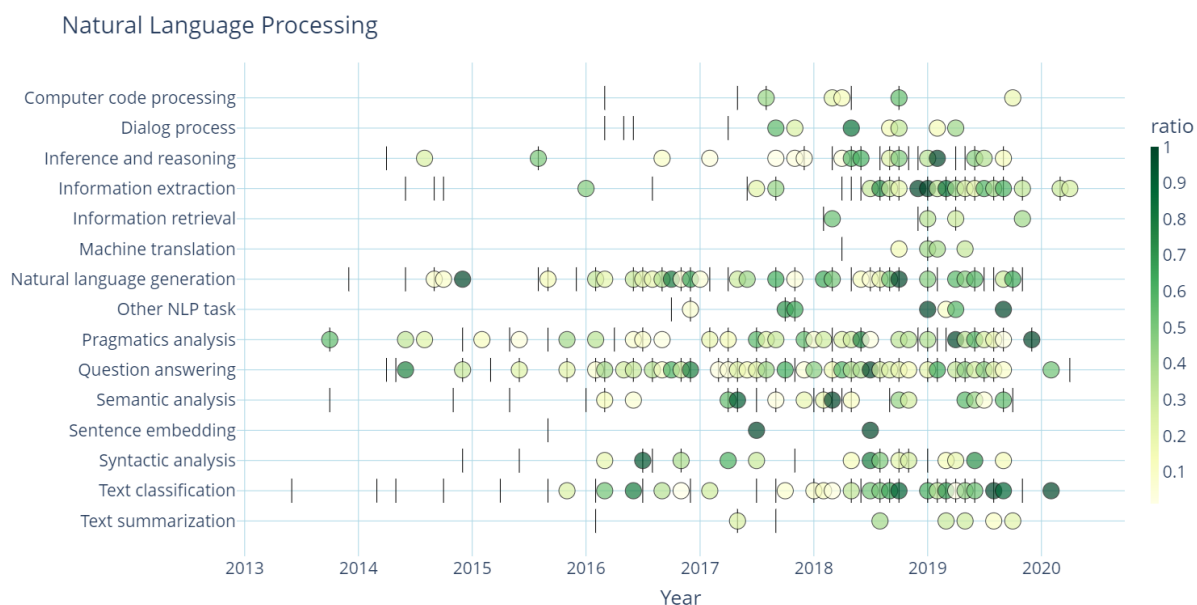
Suppl. Figure 3: Global SOTA improvement map with single gain result for computer vision.

Vision process





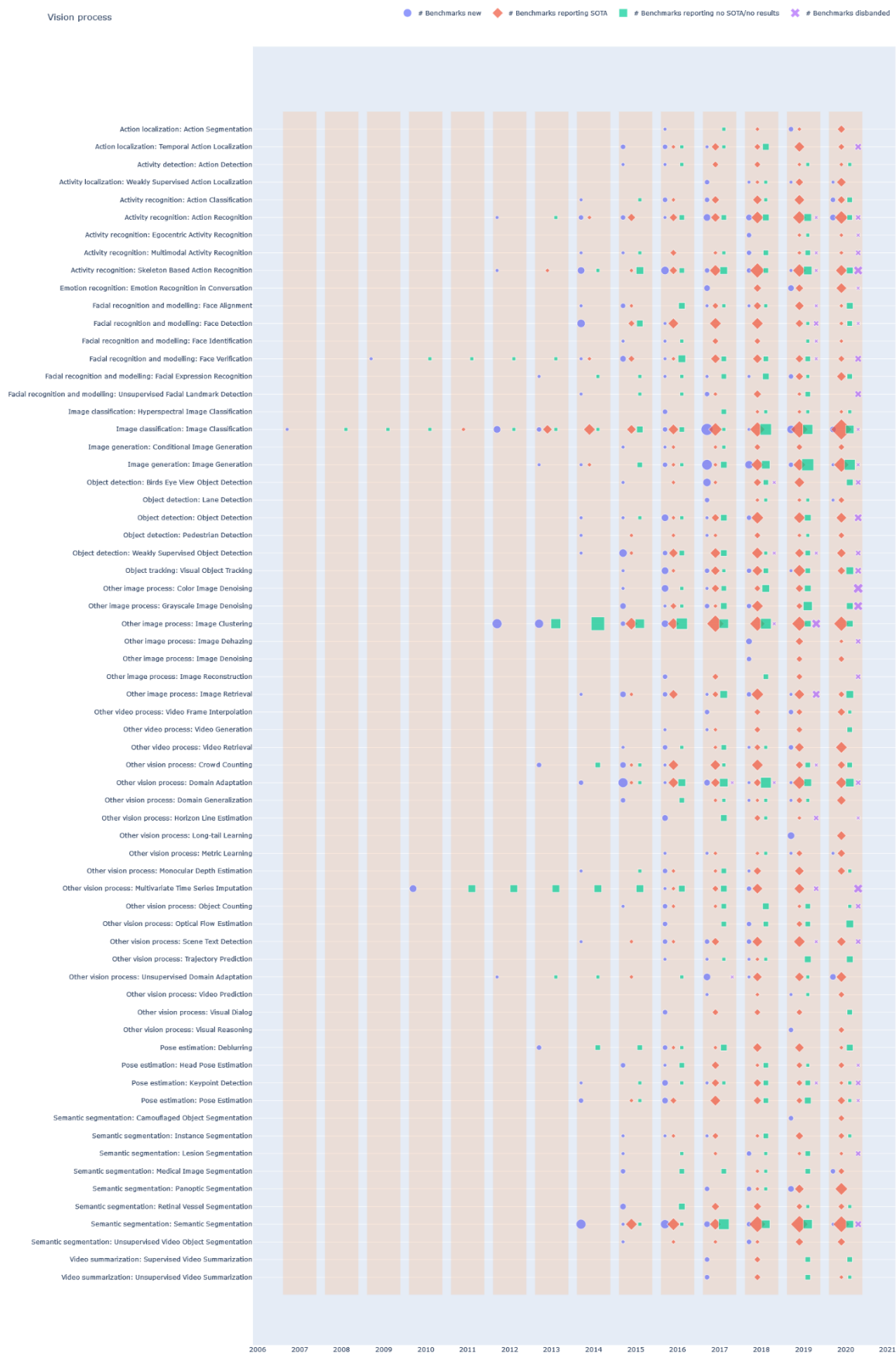
Suppl. Figure 4: Global SOTA improvement map with aggregated superclasses for NLP.



Supplementary Figure 5: *Global SOTA improvement map for computer vision with aggregated superclasses.*



Supplementary Figure 6: AI benchmark lifecycle map for computer vision.



Supplementary Figure 7: Number of active benchmarks vs. number of benchmarks reporting novel SOTA results over time for computer vision tasks.

