

```

1 function fe2dx_nr_fast_test ( )
2 %*****80
3 %
4 %% FE2DX_NR_FAST_TEST tests the FE2DX_NR_FAST code.
5 %
6 % Discussion:
7 %
8 % This function sets all parameter values and initial condition information
9 % necessary to execute the "fast" version of the fe2dx_nr algorithm.
10 %
11 % Licensing:
12 %
13 % Copyright (C) 2014 Marcus R. Garvie.
14 % See 'mycopyright.txt' for details.
15 %
16 % Modified:
17 %
18 % 28 April 2014
19 %
20 % Author:
21 %
22 % Marcus R. Garvie.
23 %
24 % Reference:
25 %
26 % Marcus R Garvie, John Burkardt, Jeff Morgan,
27 % Simple Finite Element Methods for Approximating Predator-Prey Dynamics
28 % in Two Dimensions using MATLAB,
29 % Submitted to Bulletin of Mathematical Biology, 2014.
30 %
31 timestamp ( );
32 fprintf ( 1, '\n' );
33 fprintf ( 1, 'FE2DX_NR_FAST_TEST:\n' );
34 fprintf ( 1, ' Test the FE2DX_NR_FAST function, which\n' );
35 fprintf ( 1, ' applies Neumann and Robin boundary conditions as it\n' );
36 fprintf ( 1, ' approximates a solution to a predator-prey system.\n' );
37 %
38 % Set the parameters.
39 %
40 alpha = 0.4;
41 beta = 2.0;
42 gamma = 0.6;
43 delta = 1.0;
44 %
45 % Use T=150.0 for normal run.
46 % Use T=0.50 for a "quick" run that might take 15 minutes of computing.
47 %
48 T = 0.50;
49 delt = 1.0 / 384.0;
50 k1 = 0.01;
51 k2 = 0.01;
52 t = tic;
53 fe2dx_nr_fast ( alpha, beta, gamma, delta, T, delt, @u0f, @v0f, k1, ...
54 k2, @g2uf, @g2vf );
55 t = toc ( t );

```

```

56   fprintf ( 1, ' Execution took %10.2g minutes \n', t / 60.0 );
57 %
58 % Terminate.
59 %
60   fprintf ( 1, '\n' );
61   fprintf ( 1, 'FE2DX_NR_FAST_TEST:\n' );
62   fprintf ( 1, ' Normal end of execution.\n' );
63   fprintf ( 1, '\n' );
64   timestamp ( );
65   return
66 end
67 function value = u0f ( x, y )
68 %*****80
69 %
70 %% U0F evaluates the initial condition for U.
71 %
72 % Licensing:
73 %
74 % Copyright (C) 2014 Marcus R. Garvie.
75 % See 'mycopyright.txt' for details.
76 %
77 % Modified:
78 %
79 % 26 April 2014
80 %
81 % Author:
82 %
83 % Marcus R. Garvie.
84 %
85 % Parameters:
86 %
87 % Input, real X, Y, a location in the region.
88 %
89 % Output, real VALUE, the initial condition for U at (X,Y).
90 %
91 value = 6.0 / 35.0 - 2.0E-07 * ( x - 0.1 * y - 225.0 ) * ( x - 0.1 * y - 675.0 );
92 return
93 end
94 function value = v0f ( x, y )
95 %*****80
96 %
97 %% V0F evaluates the initial condition for V.
98 %
99 % Licensing:
100 %
101 % Copyright (C) 2014 Marcus R. Garvie.
102 % See 'mycopyright.txt' for details.
103 %
104 % Modified:
105 %
106 % 26 April 2014
107 %
108 % Author:
109 %
110 % Marcus R. Garvie.
111 %
112 % Parameters:

```

```

113 %
114 %      Input, real X, Y, a location in the region.
115 %
116 %      Output, real VALUE, the initial condition for V at (X,Y).
117 %
118     value = 116.0 / 245.0 - 3.0E-05 * ( x - 450.0 ) - 1.2E-04 * ( y - 150.0 );
119     return
120 end
121 function value = g2uf ( x, y, t )
122 %*****80
123 %
124 %% G2UF evaluates the Neumann boundary condition for U.
125 %
126 % Licensing:
127 %
128 %      Copyright (C) 2014 Marcus R. Garvie.
129 %      See 'mycopyright.txt' for details.
130 %
131 % Modified:
132 %
133 %      28 April 2014
134 %
135 % Author:
136 %
137 %      Marcus R. Garvie.
138 %
139 % Parameters:
140 %
141 %      Input, real X, Y, a location on the boundary.
142 %
143 %      Input, real T, the time.
144 %
145 %      Output, real VALUE, the prescribed value for dU/dn at (X,Y,T).
146 %
147     value = 0.0;
148     return
149 end
150 function value = g2vf ( x, y, t )
151 %*****80
152 %
153 %% G2VF evaluates the Neumann boundary condition for V.
154 %
155 % Licensing:
156 %
157 %      Copyright (C) 2014 Marcus R. Garvie.
158 %      See 'mycopyright.txt' for details.
159 %
160 % Modified:
161 %
162 %      28 April 2014
163 %
164 % Author:
165 %
166 %      Marcus R. Garvie.
167 %
168 % Parameters:
169 %

```

```
170 % Input, real X, Y, a location on the boundary.  
171 %  
172 % Input, real T, the time.  
173 %  
174 % Output, real VALUE, the prescribed value for dV/dn at (X,Y,T).  
175 %  
176 value = 0.0;  
177 return  
178 end
```

.....

Published with MATLAB® R2013b