Sampling Errors in Satellite Derived Sea Surface Temperature Associated with Climate Data Records

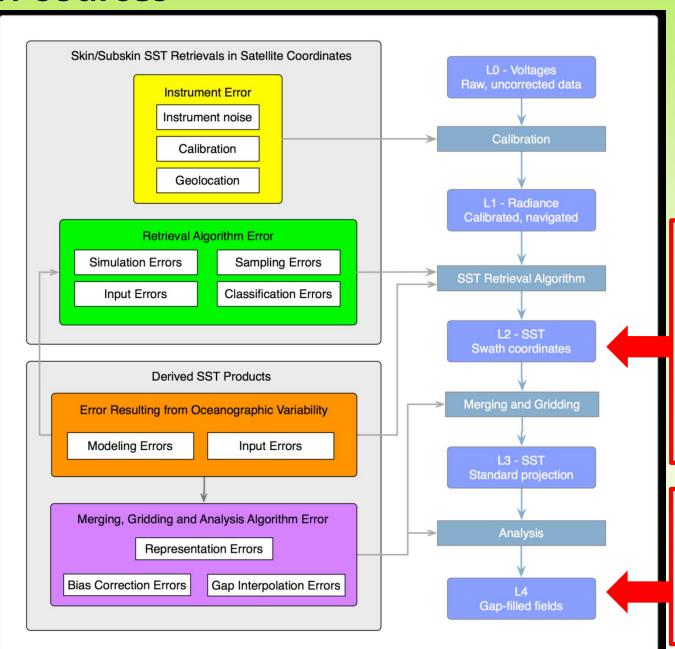
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Error sources



Sea Surface Temperature Error Budget: ISSTST White Paper.

L2 is where the uncertainties in the SST retrievals are derived by comparison with independent measurements.

to initialize climate models, and in other climate studies.

Motivation

Uncertainties in satellite-derived SSTs are usually derived at Level 2 (swath data), but climate analysis and model input generally use Level 4 fields

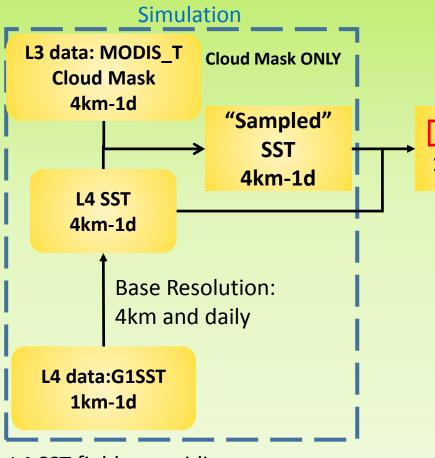
Additional sources of uncertainty in Level 4 include:

- ✓ Clouds cause significant undersampling; typically only ~10% of all pixels pass cloud screening
- ✓ Gaps between swaths for some IR sensors cause undersampling



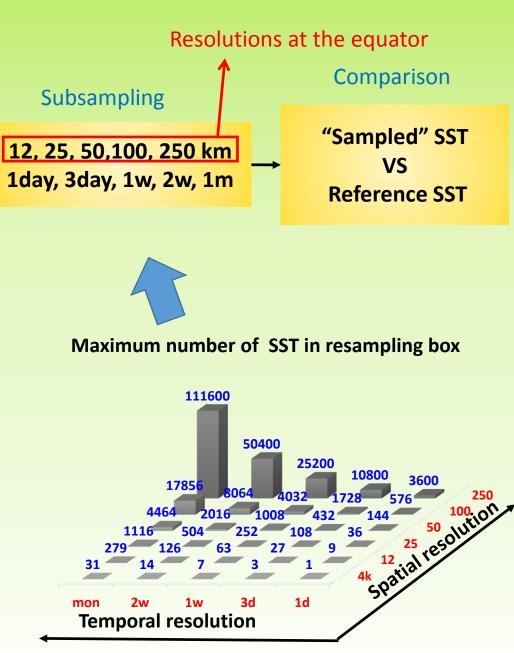


Data and Methods



L4 SST fields, providing a complete SST field, are sampled through real MODIS cloud mask

Time: 2010.12.26 – 2011.01.25



Error Quantification Framework

Point to Point statistics:

Base resolution
$$R_0 = 4km$$

$$R = [4,12,25,50,100,250 \ km]$$

$$T = [1d,3d,1w,2w,mon]$$

$$N_t = T$$
 Sampled number of SST
$$N_r = \frac{R}{R_0} \times \frac{R}{R_0}$$

$$N_t = T$$

$$N_t = [0,1,2,3 \dots N_t]$$

$$Gap\ Fraction = 1.0 - \frac{n_r \times n_t}{N_r \times N_t} \quad (0 \le Gap_F \le 1)$$

"Sampled" SST:
$$SST = \frac{1}{n_r \times n_t} \sum_{i=1}^{n_r} \sum_{j=1}^{n_t} SST_0^{rf}$$
 Reference SST at base resolution Reference SST:
$$SST^{rf} = \frac{1}{N_r \times N_t} \sum_{i=1}^{N_r} \sum_{j=1}^{N_t} SST_0^{rf}$$

ROSENSTIEL Difference:
$$Diff = SST - SST^{rf}$$



Geographic statistics:

$N_x = Num \ of \ grids \ in \ longitude$

$$n_x = Num \ of \ samples \dots$$

$$N_{v} = Num \ of \ grids \ in \ latitude$$

$$n_{v} = Num \ of \ samples \dots$$

$$\widehat{SST} = \frac{1}{\sum_{i=1}^{n_x} \sum_{j=1}^{n_y} \cos(lat_j)} \sum_{i=1}^{n_x} \sum_{j=1}^{n_y} SST \times \cos(lat_j)$$

$$\widehat{SST}^{rf} = \frac{1}{\sum_{i=1}^{N_x} \sum_{j=1}^{N_y} \cos(lat_j)} \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} SST^{rf} \times \cos(lat_j)$$

$$\widehat{Diff} = \frac{1}{\sum_{i=1}^{n_x} \sum_{j=1}^{n_y} \cos(lat_j)} \sum_{i=1}^{n_x} \sum_{j=1}^{n_y} (SST - SST^{rf}) \times \cos(lat_j)$$

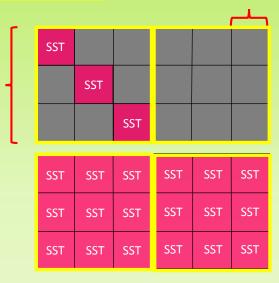
....."Global Mean of Difference"

"
$$\widehat{SST} - \widehat{SST}^{rf}$$
"

....."Difference of Global Mean"

$$RMSE = \sqrt{\frac{1}{\sum_{i=1}^{n_x} \sum_{j=1}^{n_y} \cos(lat_j)} \sum_{i=1}^{n_x} \sum_{j=1}^{n_y} Diff^2 \times \cos(lat_j)}$$

4 grid cells at 12km:



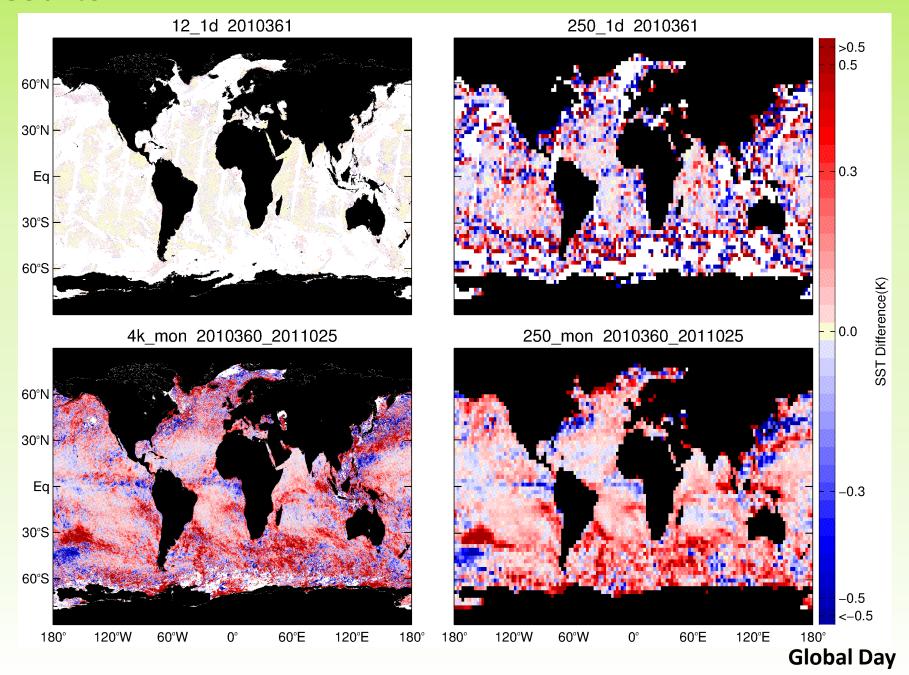
4km

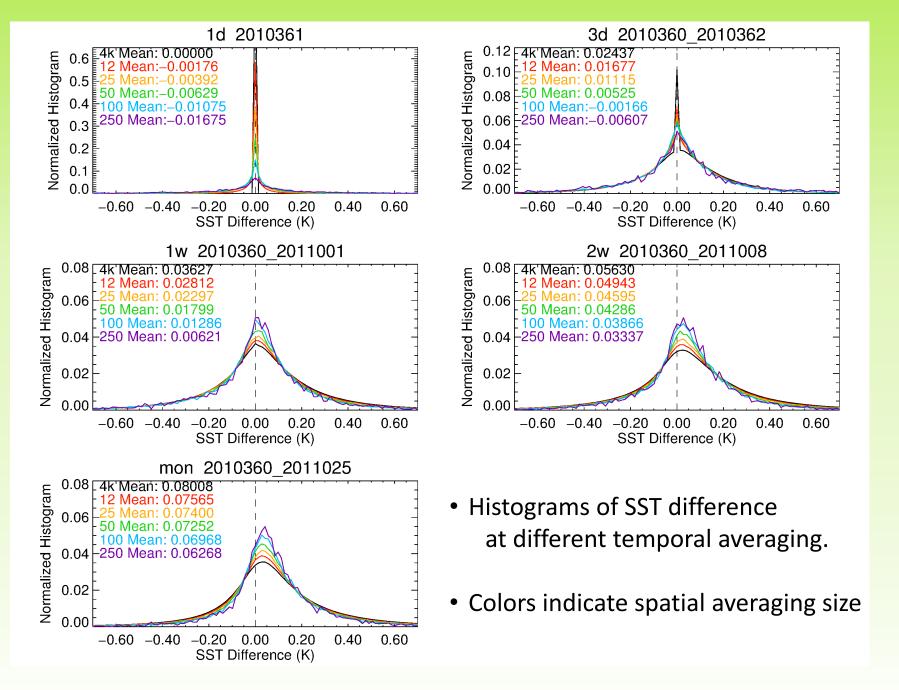
At each grid cell of 12km, the gap fraction is 6/9, 9/9, 0/9, 0/9. But the global Gap fraction would be 1/4.

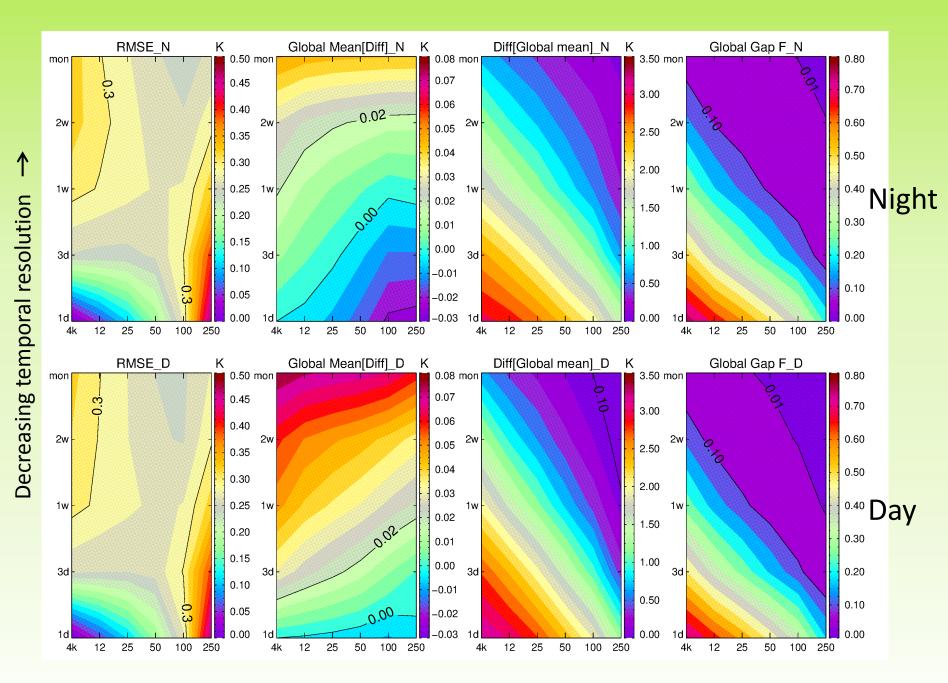
Global Gap Fraction

$$= 1.0 - \frac{\sum_{i=1}^{n_x} \sum_{j=1}^{n_y} \cos(lat_j)}{\sum_{i=1}^{N_x} \sum_{j=1}^{N_y} \cos(lat_j)}$$

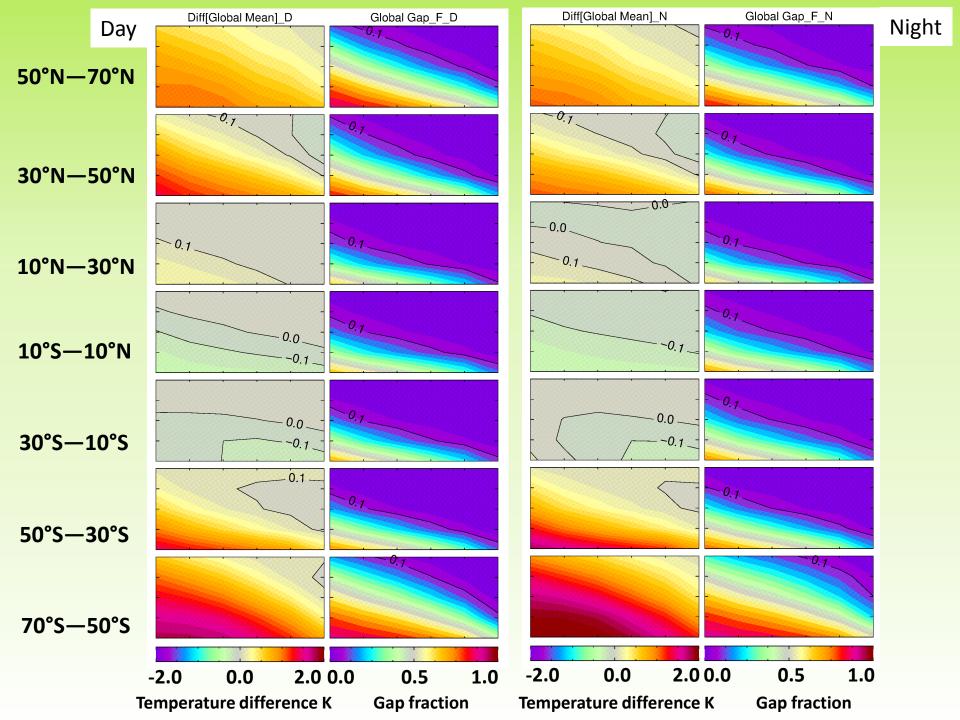
Results

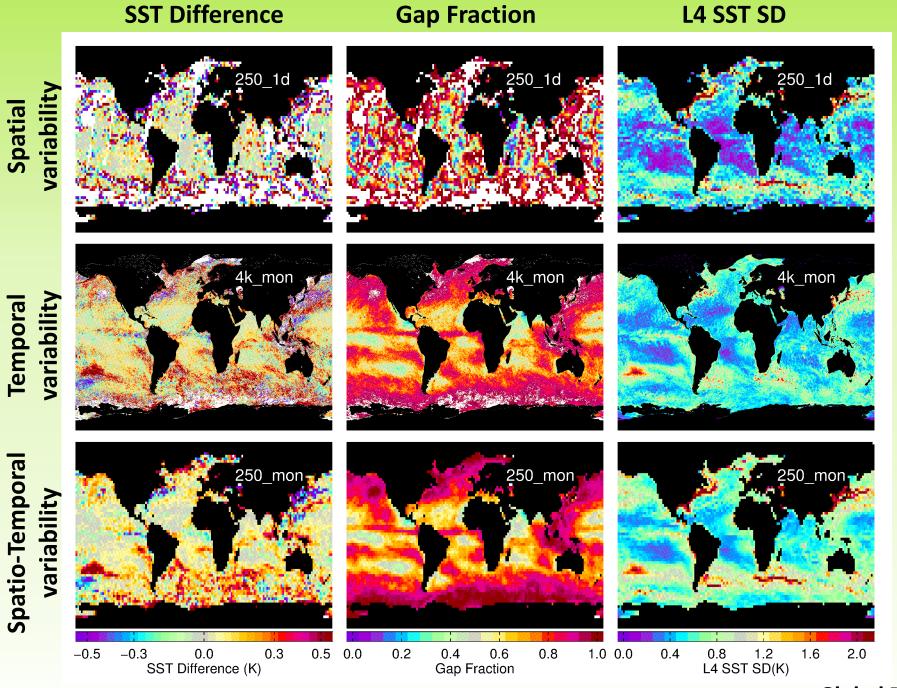






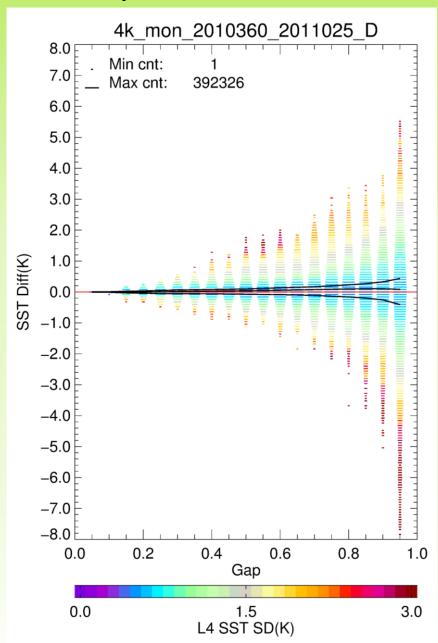
Decreasing spatial resolution →

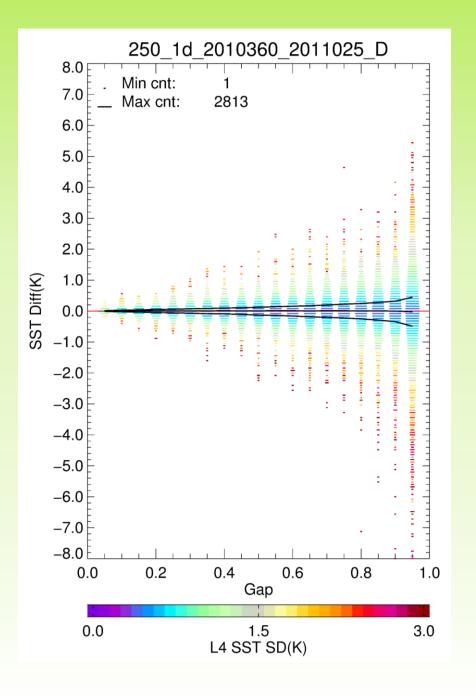




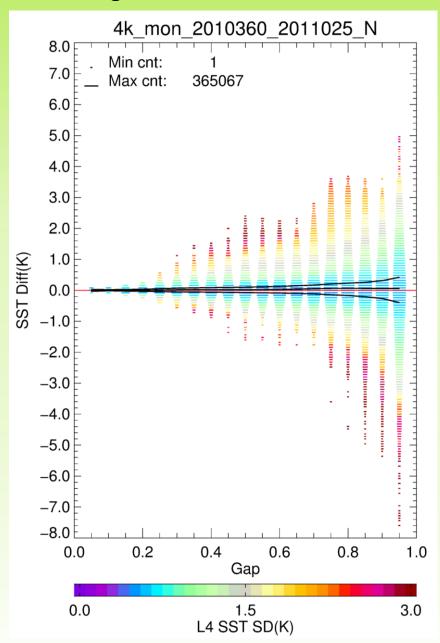
Global Day

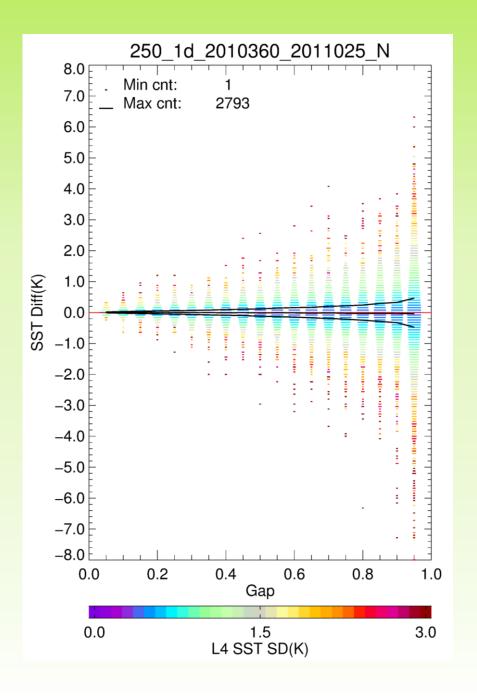
Global Day





Global Night





Summary

- Sampling errors caused by clouds are large and can not be neglected when interpreting L4 fields.
- For sampling error less than 0.1K, only L4 fields with 100-mon, 250-2w, or 250-mon should be used.
- Spatial distribution of errors over global ocean is complex. And some areas are prone to larger errors than others.
- Real L4 fields have additional errors accumulated at the production of each Level, including those due to satellite retrieval errors, aerosols and unresolved clouds ...
- The method of gap filling in real L4 fields introduces further complications.



Future Work

- Compare different seasons
- Use Aqua MODIS for a different time of day
- Regional analyses
- AATSR added issue of narrow swath
- VIIRS no gap between swaths......



