

# Report on Himawari-8 from JMA

Japan Meteorological Agency

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# Contents

- Introduction to Himawari-8
- Calibration and Validation for IR Bands
- Image Navigation and Registration (INR)
  - Ground processing system updates of 9 March 2016
- L3 SST and Cloud Mask





# Contents

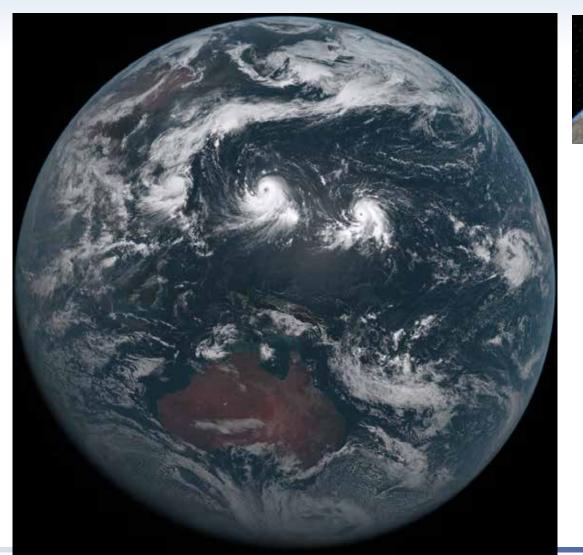
### • Introduction to Himawari-8

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# Himawari-8 started operation at 02 UTC on 7 July 2015.



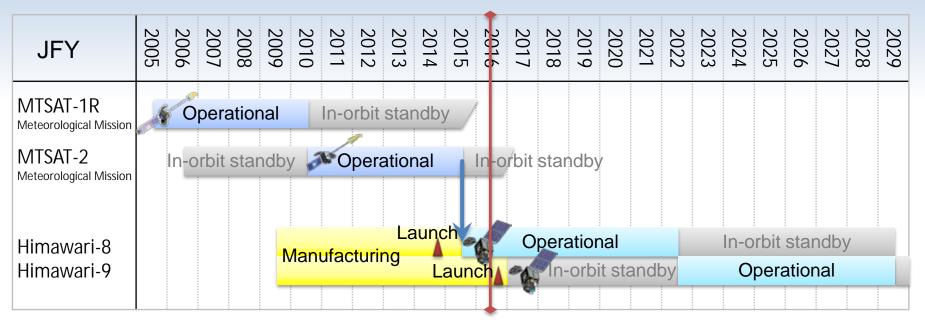






02:00 UTC on July 2013 hington, D.C. 2016

# Himawari-8/9 timeline



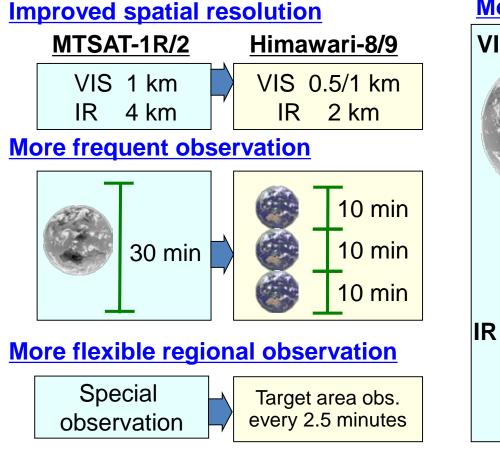
n Himawari-8 was launched on 7 October 2014.
 n Himawari-8 started operation on 7 July 2015, replacing MTSAT-2.

n MTSAT -2 observation parallel to Himawari-8 operation terminated at 00 UTC on 24 March 2016.
 n Himawari-9 is scheduled for launch in 2016.

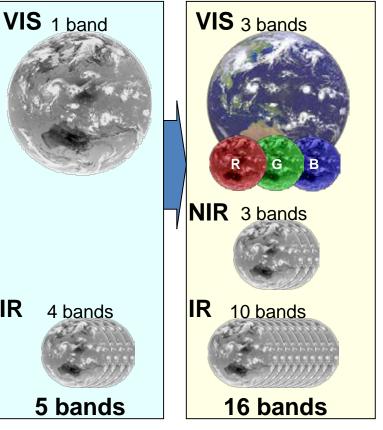


# AHI (Advanced Himawari Imager)

Himawari-8 multispectral observation with higher spatial/temporal resolution provides more information on atmosphere/ocean/land than MTSAT.



### More spectral bands





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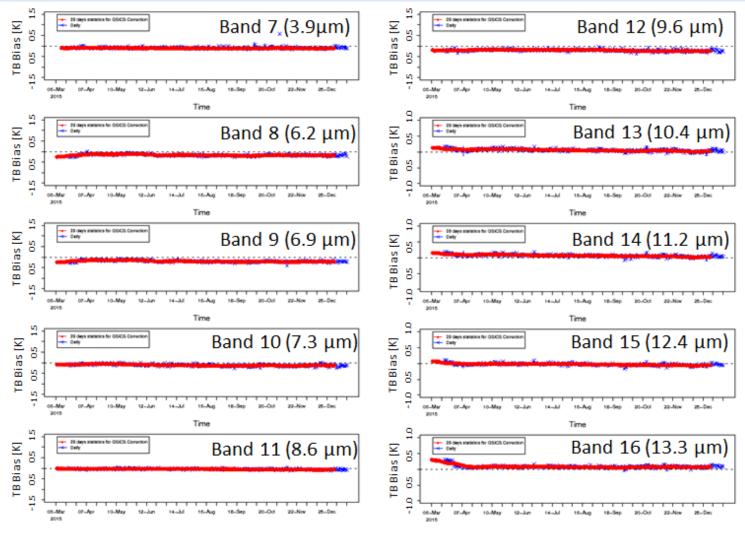
### Calibration and Validation for IR Bands

### On-board calibration

- A black body is provided as an on-board calibration source.
  Hot reference: Black body observation is performed every 10 minutes.
  Cold reference: Deep space viewing is conducted for every swath of full-disk observation.
- Inter-calibration for IR Bands
  - JMA has developed an infrared calibration method under the GSICS (Global Space-based Inter-Calibration System) framework.
  - AHI data are compared with data from hyper-spectral infrared sounders such as IASI/Metop and AIRS/Aqua.
  - Statistical parameters derived from GSICS inter-calibration work are available on MSC's GSICS calibration monitoring website. (http://www.data.jma.go.jp/mscweb/data/monitoring/calibration.html)



#### TB biases for IR bands: very stable – less than 0.2K for standard scenes



 $\times$  Daily value  $\times$  29 days of statistics

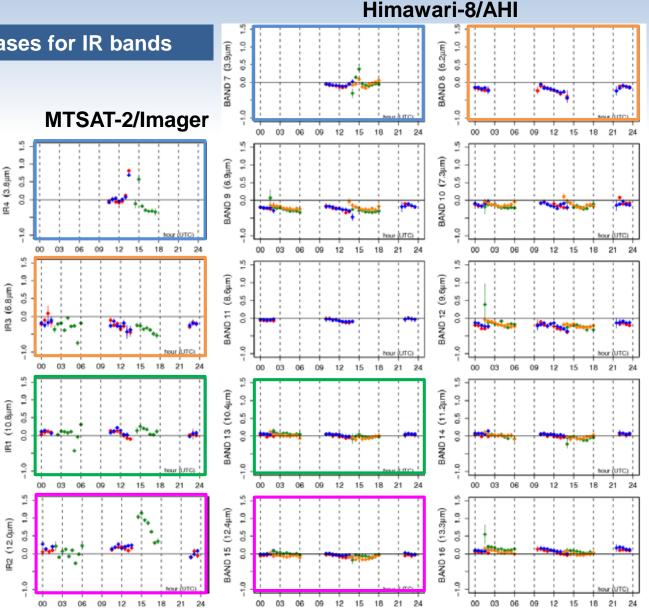


#### Time dependence of TB biases for IR bands

- Monthly statistics for February 2016
- <u>No significant diurnal</u> <u>variation in Himawari-8</u>
- Root cause of small variations in Himawari-8 is under investigation

Reference sensors: Metop-A/IASI Metop-B/IASI Aqua/AIRS S-NPP/CrIS

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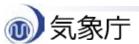




### Himawari-8 Ground Processing System Updates of 9 March 2016

- 1. Improvement of the <u>band-to-band co-registration process</u> for IR bands *relative misalignment between sensor bands*
- 2. Improvement of the <u>resampling</u> process
- 3. Implementation of a <u>coherent noise reduction process</u>
- 4. Bug fix for HSD header information

The updates significantly improved Himawari-8 image quality





#### Ground Processing System Update – Band-to-band Co-registration Process for IR Bands

- Old process for estimation of co-registration correction:
  - ü Based on co-registration errors from pattern matching during in-orbit testing
  - Ü VNIR and Band 7 (3.9μm): optimized using <u>AHI temperature data</u>
  - ü IR except Band 7: constant
- New process applied to IR bands 7, 8, 9, 10, 11, 12 and 15:
  - **ü** Based on <u>co-registration errors of previous full-disk observing cycle w/o optimization</u>
  - **ü** Change of pattern matching method and bug fix for domain determination.
  - ü Significant error reduction (e.g., ~0.2km -> ~0.02km for band 15)
    - The new process would also be applied to other bands in the future.

Band-to-band co-registration errors w.r.t. band 13 (10.4 µm) observation

BAND	01	02	03	04	05	06				
BEFORE	0.1977	0.1996	0.3144	0.2074	0.4048	0.1979	Units in IR pixel size (1pixel = 2km at SSP)			
AFTER	0.2171	0.2157	0.3408	0.2297	0.4044	0.1925				
BAND	07	08	09	10	11	12	13	14	15	16
BEFORE	0.1162	0.1284	0.2159	0.2256	0.2756	0.1803	-	0.1168	0.1130	0.0159
AFTER	0.0134	0.0084	0.0091	0.0104	0.0115	0.0098	-	0.1194	0.0081	0.0159

• BEFORE and AFTER: averages of all full-disk data for 4-8 and 10-14 March 2016

• VIS/NIR bands: daytime averages (21:00-08:50 UTC)





#### Ground Processing System Update – Resampling Process

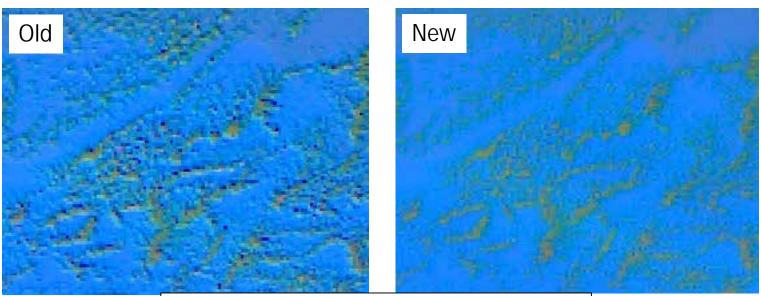
### Old process

ü Unnatural spotted pixels in band-to-band differential imagery at the edge of cloudsü Caused by inadequate resampling and large band-to-band co-registration errors

• New process (refined resampling parameters)

**ü** Band-to-band radiance inconsistency significantly reduced.

**ü** New band-to-band co-registration process also contributes to this improvement



Dust RGB image at 00:10 UTC on 9 December 2015 Color composite: 12.4-10.4µm, 10.4-8.6µm, 10.4µm





# Contents

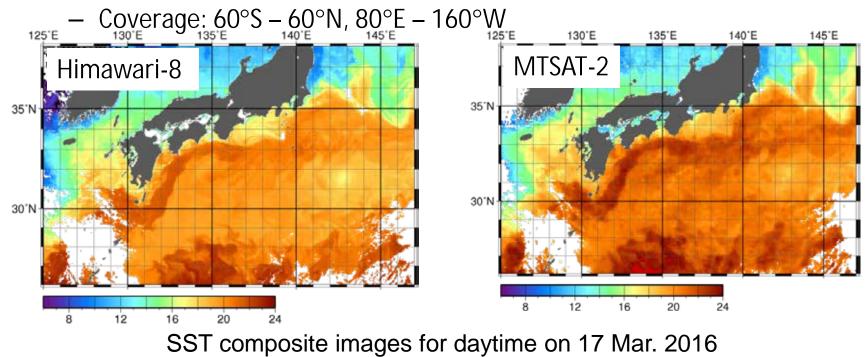
- Introduction to Himawari-8
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# Himawari-8 L3 SST

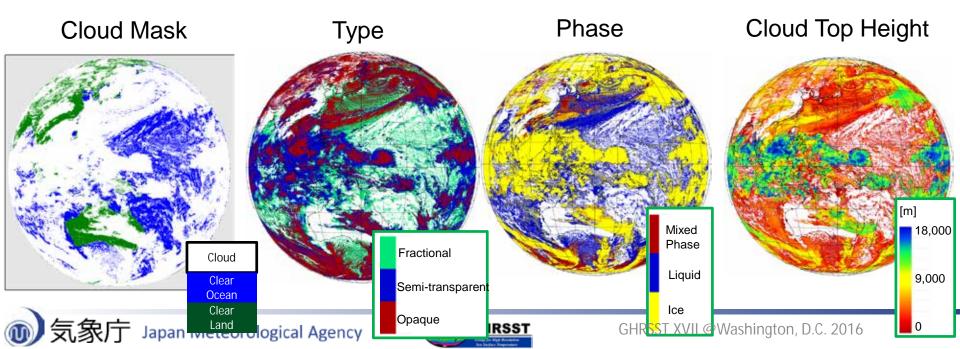
- JMA's Meteorological Satellite Center produces Himawari-8 L3 SST data
- Same SST retrieval algorithm as used by JAXA based on a quasi-physical algorithm (Kurihara et al. 2016)
- $-\,$  Band 11 (8.6µm), Band 13 (10.4µm) and Band 14 (11.2µm)
- Cloud mask based on JMA's Fundamental Cloud Product for Himawari-8
- <u>Hourly</u>, 0.02° horizontal resolution (0.04° for MTSAT-2)





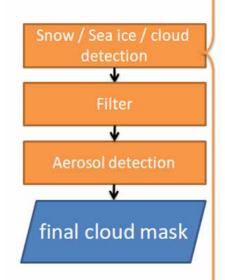
# Fundamental Cloud Product (FCP)

- Parameters: Cloud Mask, Type, Phase, and Top Height
- FCP is used for retrieval of other products within JMA/MSC
- Algorithm is based on NWC-SAF and NOAA/NESDIS
- HSD-pixel basis (2km)
- Algorithm documents published in March 2016 Imai and Yoshida (2016), http://www.data.jma.go.jp/mscweb/technotes/msctechrep61-1.pdf

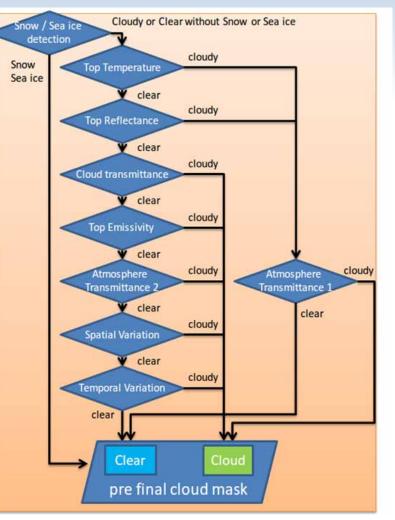


### **Cloud Mask Algorithm**

### Clear/Cloudy status is determined from a variety of threshold tests.



Thresholds are modified using offsets determined from comparison with a MODIS cloud mask product

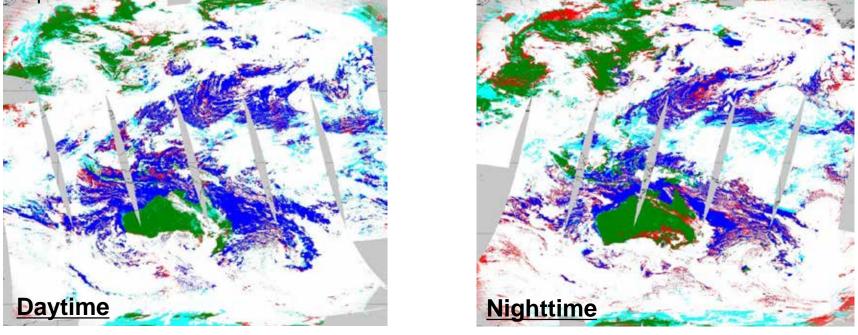




# **Cloud Mask Validation**

Comparison with MODIS product

The FCP cloud mask hit rate compared with that of the MODIS product (MYD35\_L2, C6) was about 85% for the two weeks leading up to 4 Sep. 2015. The daytime hit rate was slightly higher than the corresponding nighttime figure. Although false detections of cloud (cyan) was observed in the tropical region, this was corrected via offset adjustment on 6 Sep. 2015.



Clear(sea) Clear(land) AHI: Cloudy AHI: Clear MODIS: Clear MODIS: Cloudy Cloudy

Yoshida et al., An Introduction of Himawari-8 Cloud Products, Poster Presentation at the Sixth AOMSUC Conference, November 2015, Tokyo. [Available online at MSC website]

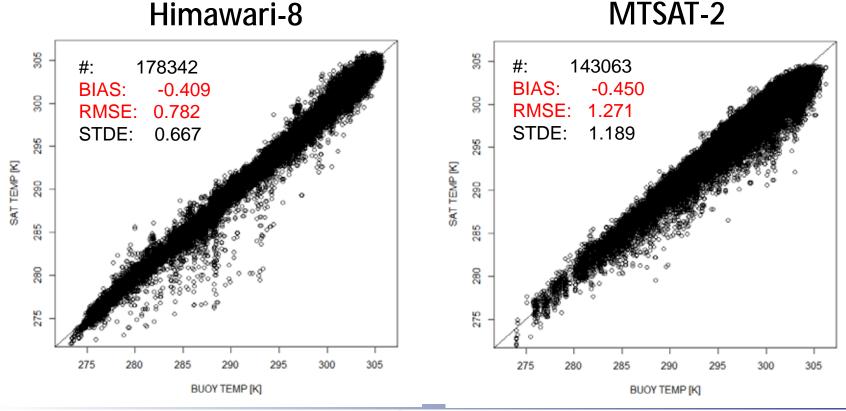


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### Himawari-8 SST Validation (March 2016)

- Match-up of satellite and buoy SSTs with time differences within 1.25 hours and spatial distances of less than 10km from March 1 to 31 (until March 24 for MTSAT-2).
- Himawari-8 SST data were superior to those of MTSAT-2.



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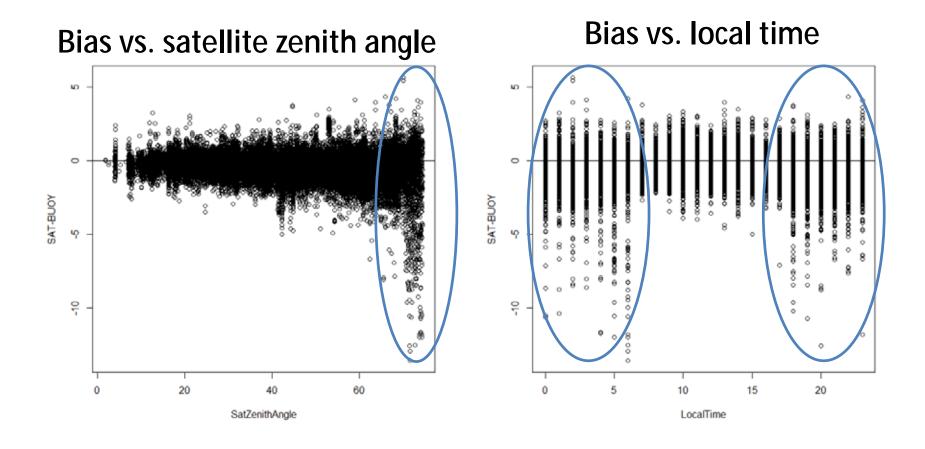
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MTSAT-2

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### Himawari-8 SST Validation (March 2016)

Large negative bias for satellite zenith angles exceeding 70 degrees and for night time

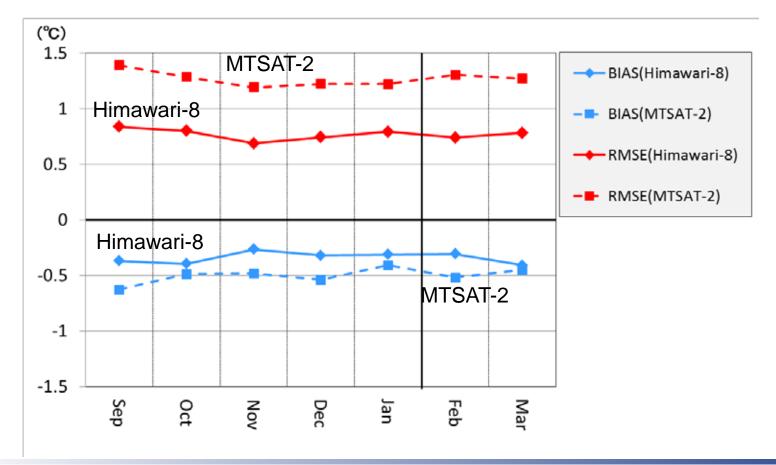






### Himawari-8 SST Validation (Monthly Statistics)

Bias: -0.3 ~ -0.4°C, RMSE: 0.7 ~ 0.8°C for Himawari-8 Bias: -0.4 ~ -0.6°C, RMSE: 1.2 ~ 1.4°C for MTSAT-2 The results show significant improvement over those from MTSAT-2.

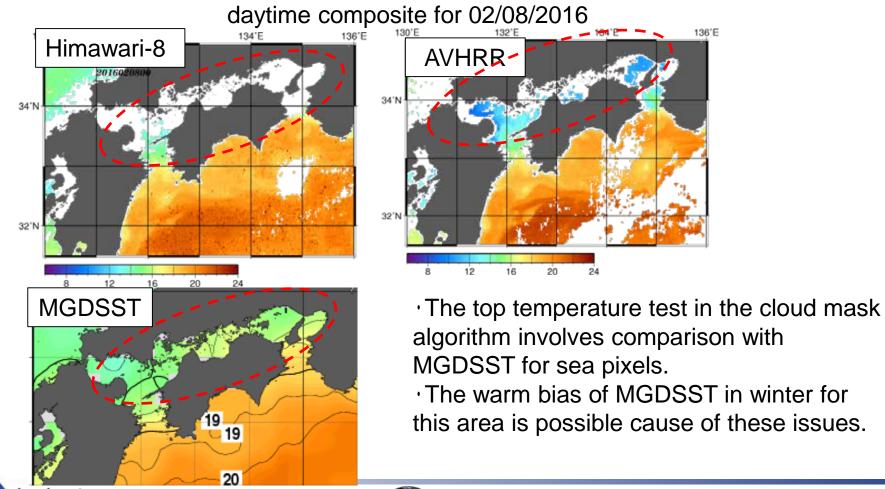




### **Problems with Cloud Screening**

·Cloud is often falsely detected over the Seto Inland Sea, especially in winter (see the figures below).

·Cloud is sometimes falsely detected in areas with large SST gradients.



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# Summary

Introduction

- ü Himawari-8 started operation in July 2015
- ü AHI: more spectral bands (16 bands), double the spatial resolution
  - (4 2km for IR), more frequent observation
- **p** Calibration and Validation for IR Bands
  - ü Brightness temperature biases: very stable less than 0.2K for standard scenes, no significant diurnal variation
- **p** Image Navigation and Registration (INR)
  - ü Ground processing system updates of 9 March 2016
    - significant improvement in image quality
- E L3 SST and Cloud Mask
  - ü Same SST retrieval algorithm as used by JAXA; different cloud mask method (using JMA's Fundamental Cloud Product)
  - ü Hourly, 0.02° horizontal resolution
  - **ü** Himawari-8 SST vs. buoys: Bias: -0.3 -0.4°C; RMSE: 0.7 0.8°C



# BACKUP





### Introduction

- Himawari-8 started operation on 7 July 2015
- AHI (Advanced Himawari Imager) on Himawari-8: new generation GEO imager
  - ü 3 VIS, 3 NIR and 10 IR bands
  - ü Full disk observing cycle: 10 min., rapid scanning within 2.5 min. / 30 sec. intervals

Himawari-8/AHI				GOES	-R/ABI	MTSAT-2/IMAGER		
Band	Wave	Spatial	Bit depth	Wave	Spatial	Wave	Spatial	
	length	resolution	ысцерти	length	resolution	length	resolution	
1	0.47 µm	1km	11	0.47 µm	1km			
2	0.51 µm	1km	11					
3	0.64 µm	0.5km	11	0.64 µm	0.5km	0.68 µm	1km	
4	0.86 µm	1km	11	0.86 µm	1km			
				1.38 µm	2km			
5	1.6 µm	2km	11	1.61 µm	1km			
6	2.3 µm	2km	11	2.26 µm	2km			
7	3.9 µm	2km	14	3.90 µm	2km	3.7 µm	4km	
8	6.2 µm	2km	11	6.15 µm	2km	6.8 µm	4km	
9	6.9 µm	2km	11	7.00 µm	2km			
10	7.3 µm	2km	12	7.40 µm	2km			
11	8.6 µm	2km	12	8.50 µm	2km			
12	9.6 µm	2km	12	9.70 µm	2km			
13	10.4 µm	2km	12	10.3 µm	2km	10.8 µm	4km	
14	11.2 µm	2km	12	11.2 µm	2km			
15	12.4 µm	2km	12	12.3 µm	2km	12.0 µm	4km	
16	13.3 µm	2km	11	13.3 µm	2km			





#### Inter-calibration and Vicarious Calibration for VIS/NIR Bands

- A) Ray-matching with reference to S-NPP/VIIRS
- B) Comparison with simulated TOA radiance based on a radiative transfer model
- C) Comparison with deep convective cloud measurements by Aqua/MODIS
- D) Comparison with simulated lunar irradiance using GIRO (GSICS

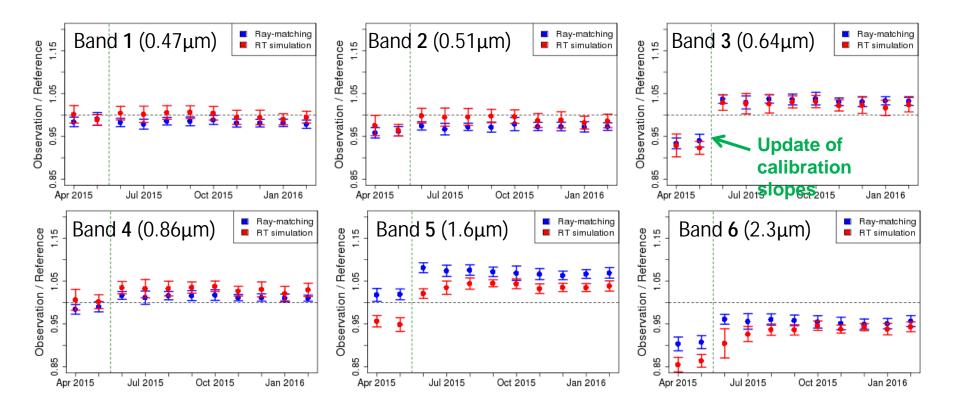
Implementation of the ROLO model) <u>C) and D) are under implementation</u>





#### Validation of VNIR calibration slopes using RT simulation and Ray-matching approach

Improvement of accuracy after updating calibration slopes based on SD observation
 # +6.1% bias for band 5, -4.3 % bias for band 6 based on ray-matching validation
 Root cause is under investigation

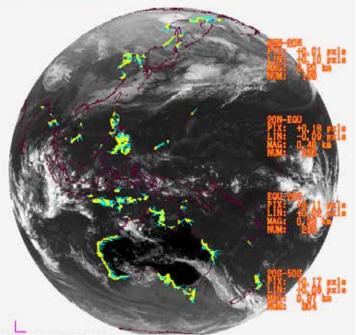


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### Image Navigation and Registration (INR)

- Orbit determination: based on ranging data
- Satellite attitude determination involves the use of star trackers and gyros
  ü Refined using landmark analysis based on pattern matching for coastlines
- Residual image navigation error in Himawari Standard Data (L1B equiv. data) is validated using landmark analysis



#### AN OF VECTOR MAGNITUDES(px1s): 0,15(=0,3 km) AN VECTOR(px1s): FIX +0,13, 11N +0,02, MAG 0,13(=0,3 km), # OF SAMPLES: 1012



01/15 03:00:21 UTC

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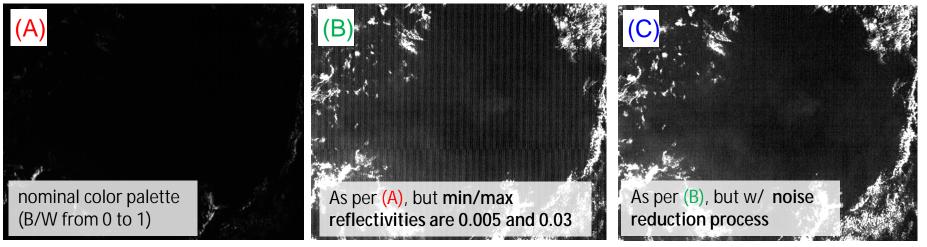
#### Image navigation error

- Usually less than 0.5 IR pixels (approx. 1 km at SSP)
- The error occasionally/provisionally becomes larger in the <u>next full-disk observing cycle</u> after <u>station keeping maneuver</u> and the timing of <u>satellite eclipse</u>
- Root cause: under-investigation

#### **Ground Processing System Update – Coherent Noise Reduction Process**

- AHI sensor configuration creates coherent noise:
  - ü Stripes perpendicular to the scan direction over low-radiance areas
  - ü E.g. cloud-free ocean in VIS/NIR, deep convective cloud in IR and deep space in all bands
- Noise reduction module was applied to bands 1, 2, 4, 5, 6, 10, 11, 12, 13, 14 and 15
  - ü Noise reduction parameters: based on deep-space observation and the Fourier transform
  - ü significant reduction of striping
  - ü The module was applied for band 7 on 18 June 2015

Band 4 (0.86  $\mu m)$  reflectivity at 00:20 UTC on 25 November 2015

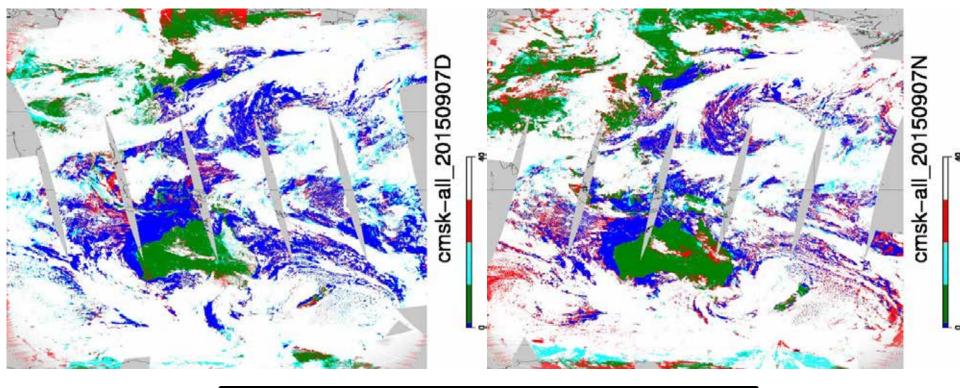




# Validation of Cloud Mask

### Comparison with MODIS product

7 Sep. 2015



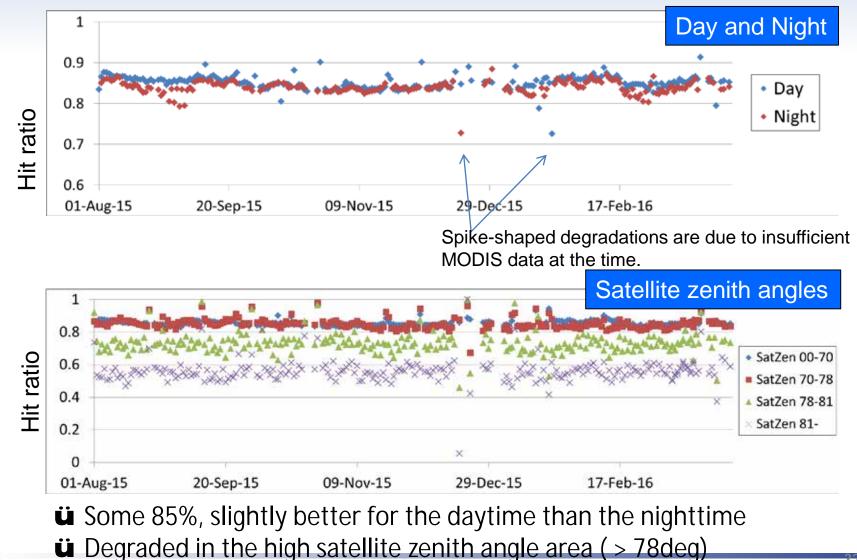
Clear(sea) Clear(land) AHI: Cloudy AHI: Clear MODIS: Clear MODIS: Cloudy Cloudy Cloudy





# Cloud Mask comparison with MODIS

The FCP Cloud Mask has been compared with the MODIS cloud product (MYD03, C6)



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# Hit Ratio Definition

		Actual cloud mask		
		Clear	Cloudy	
CMP	Clear	А	В	
	Cloudy	С	D	

Hit ratio = (A + D) / (A + B + C + D)

Clear hit ratio = A / (A + B)

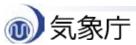
Cloudy hit ratio D / (C + D)





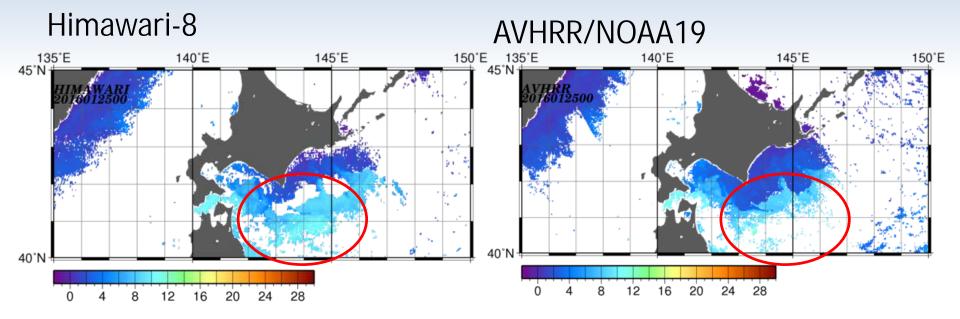
Table 9 Hit ratios of the CMP algorithm for MSG/SEVIRI data compared with those of the Aqua/MODIS product for each season (winter: 28 December 2011 – 10 January 2012; spring: 28 March – 10 April 2012; summer: 27 June – 10 July 2012; autumn: 27 September – 10 October 2012)

	Winter	Spring	Summer	Autumn	All
All region	0.86	0.85	0.85	0.85	0.85
Sea	0.86	0.85	0.85	0.86	0.85
Snow/Ice	0.86	0.81	0.72	0.86	0.81
Sand	0.87	0.86	0.86	0.89	0.87
Vegetation	0.86	0.84	0.83	0.83	0.84
Others	0.80	0.82	0.86	0.84	0.84

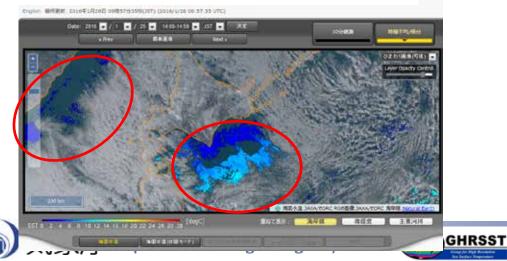




### Problems with cloud-screening for SST



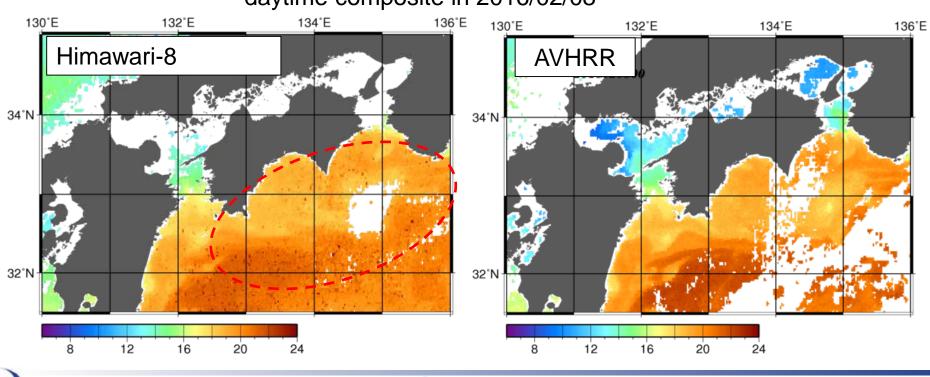
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### issue of unnatural spotted pixels -A case of SST -

- Unnatural spotted pixels are seen in the maximum-value composite image for HIMAWARI SST.
- New resampling and band-to-band co-registration process may reduce these unnatural spotted pixels.



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daytime composite in 2016/02/08

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