

Optimal Placement of DG with Battery Energy Storage in Distribution Network for Power loss Minimization using Combined Dispatch & Combined PLS Strategy

Bharat Singh, Satyaveer Singh Rawat

Abstract: This paper presents a novel application of General Algebraic Modelling System (GAMS) and MATLAB interfacing for optimal location and placement of DG with battery. The main contribution of this paper is: (i) optimal placement of DG based on combined-Power Loss Sensitivity (PLS) method, (ii) optimal placement of battery energy storage using combined dispatch strategy, (iii) optimal size of DGs and Battery have been carried out in such a way to minimize the total power loss without violating the constraints using MINLP solver in GAMS. (iv) Two types of DGs have been considered for analysis and the impact of DG with and without battery placement on total power loss and voltage improvement. Voltage profile, real and reactive power flow pattern, total power loss, computational time, fuel cost, total installation cost, total cost, State of Charge (SOC) status of battery and power obtain by DG with the battery has been determined. The result shows the importance of DG with battery size and location. The results are obtained on IEEE-33bus radial distribution test system and compare with another existing method also.

Keywords: Distribution Generation, Battery Storage, radial distribution system, Renewable Energy Sources, Power loss minimization.

I.INTRODUCTION

The renewable energy sources based generation has become integral part of the power system network. The distributed generation (DGs) with renewable sources and its penetration into the distribution network has introduced lot of challenges to the distribution network operator for better management and planning. In this context, the distribution system analysis need to be analyzed with DGs. The storage devices have become part of the AC/DC micro grids with the renewable sources to meet out the deviations in the power requirement during their intermittency. Therefore, there is utmost need to analyze such hybrid power system for optimal dispatch strategy satisfying the criteria of loss minimization. In this paper work, we have considered a 33bus radial distribution for analysis that consists of batteries and diesel generators. Each generating unit is first mathematically modeled. For simplicity, current modeling is used, in which the output and input of each generating unit are expressed in terms of current.

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A lot of literature has been done for the placement of renewable-based Distribution Generation (DGs). The loss sensitivity factor (LSF) method is presented in [1] for the location and sizing of DGs. A research based on the single variable and multi-variable approach using Particle Swarm Optimization (PSO) algorithm to find out the best location and optimal size of DG represented in [2]. The MINLP approach has been used for location of DGs in [3]. The multi-source has represented better reliability then single source energy system in [4]. Dufo-Lopez et al. [5] has represented the multi-objective genetic algorithm for cost calculation of hybrid energy sources along with battery energy storage. The DGs placement have also been used for the voltage enhancement using PSO algorithm [6]. In many of the research paper the PSO algorithm was implemented [7] -[8].

The power flow has been solved using direct approach by Teng.j et.al [9]. The battery storage has not considered with DG using power Loss [10]. The GA technique has used for multi-objective function by k. Vinod Kumar et.al [11] to obtain the DGs position. In the above literature the battery storage has not been taken into account with DG [6]-[11].

The power loss minimization has become another issue for the placement of DGs along with the battery storage. In this context the total power loss minimization with installation of DGs has been done in [12].

The optimal position of battery storage has become essential task for the Microgrid (MG) operator. The installation of battery storage has been done using the dispatch strategy represented in [13]. The cycling and load following battery dispatch strategy has considered with solar energy for cost based analysis in [14]. The cost based energy storage system has also been done for energy management system in [15], [16] [17] and [18].

In this paper work, the DG size and location with and without storage device has been determined. First, the candidate bus for DG placement based on the sensitivity approach, the MINLP technique was used to determine the size of DG. The combined power loss sensitivity approach and the combined dispatch strategy have been used for location of DGs and battery storage respectively. Whereas the MINLP used of the sizing of DGs and battery storage.



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The MATLAB and GAMS interfacing has been utilized for obtaining the optimal solution. On the other hand, the battery energy storage device has been integrated with DG in such a way to meet out the power mismatch.

In this paper the two cases are taken: in first case- DGs at unity, 0.9 lagging and combined load power factor have been considered. The combined-PLS is computed for distribution network with and without DGs. The dynamic load also consider on the basis of 24 hours changing in nature. In the second case- the DG with battery storage has been consider. The battery storage with dispatch strategy [13] is used to obtain the location of the energy storage device.

II.PROBLEM FORMULATION AND MATHEMATICAL MODEL

The main objective of this paper is to obtain the optimal size and location of DGs with and without battery storage for power loss minimization. The single objective problem of this paper has been solved in two part as follows;

In first part, the position of DG's and battery storage has been obtained.

- The location of DGs is obtained using the combined power loss sensitivity (PLS) in MATLAB [12].
- The position of battery energy storage is obtained using the Combined dispatch strategy in MATLAB [13]. In second part of this paper;
 - The sizing of DGs and battery storage have been determined at the obtained location of first part using MINLP in GAMS.

GAMS is designed for modeling linear, nonlinear and mixed integer optimization problems.

In this paperwork, the IEEE 33 bus test system has been carried out. The time-varying ZIP load has been taken into account for the analysis. The impact of battery energy storage with and without renewable energy sources has also been analysed. The unit commitment problem has been formulated, including piecewise cost segment, ramp rate, minimum uptime and downtime constraints. The problem is solved by MINLP solver in GAMS. The data interpretation has been done with the interfacing of MATLAB and GAMS software.

A. Mathematical Modelling

In this section the mathematical modelling of Solar, Wind Turbine, Fuel Cell, Micro-Turbine and battery storage has been represented as follows;

1) Radial Distribution System

The IEEE -33 bus test system has been carried out for the analysis, with 24 hours load variation, Distribution Generator (DG) and batteries. The schematic representation of the radial distribution power system is shown in Fig.1.

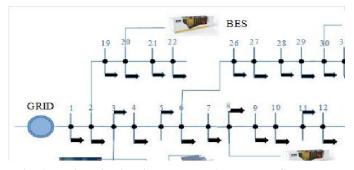


Fig. 1 Radial Distribution system with Energy Sources

2) Battery Model

The battery storage works as backup storage. It can either be charged or dis-charged according to the dispatch strategy [20]. The state of charge has been cal-culated for each battery. The maximum value depends on the nominal capacity while the minimum value on its Depth of Discharge (DOD).

$$SOC_{min} = N_{batt}C_{nb}(1 - DOD_{max_bat})$$

$$SOC_{max} = N_{batt} * C_{nb}$$
 (2)

$$SOC(k + \Delta k) = SOC(k). (1 - \delta_k) + \left(P_{ch}.\eta_{ch} - P_{dis}.\frac{1}{\eta_{dis}}\right). \Delta k$$
 (3)

Constraints:

$$SOC_i^{min}(k) \le SOC_i(k) \le SOC_i^{max}(k)$$
 (4)

$$P_{ch_min_i}^k \le P_{ch_i}^k \le P_{ch_max_i}^k$$

$$P_{dis_min_i}^{k} \le P_{dis_i}^{k} \le P_{dis_max_i}^{k} \tag{51}$$

where, N_{batt} is the no of battery, C_{nb} is the nominal capacity of the battery, $\delta_{-}k$ is the depth of discharge at the kth time, $P_{ch_i}^{k}$ and $P_{dis_i}^{k}$ is the charging and discharging power of battery at the kth time respectively. $\eta_{-}ch$ and $\eta_{-}dis$ is the charging and discharging efficiency of the battery respectively.

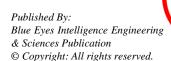
3) Solar Photovoltaic Model

The solar PV is renewable based green energy source, in Fig.2 the output curve is shown, The solar model of PV has been represented as follows;

$$P_{solar}(I_{\beta}) = N_{PV} \cdot P_{rated}^{PV} \frac{G}{G0} \cdot \{1 - T_c(T_A - 25)\} \cdot \eta_{inv} \eta_{rl}$$
(6)

where, P_{solar} is the output power, P_{rated}^{PV} rated power of PV, and N_{PV} is the total number of solar panel [19]. G and G0 are solar irradiation and slandered solar irradiation in $(\frac{watt}{m^2})$.

The Fig.2 shows solar PV output for 24 hours. T_A is the ambient temperature and Tc is the temperature coefficient of the maximum power of PV. η_-inv and η_-rl represent the efficiency of the inverter and the relative efficiency of the PV modules respectively.





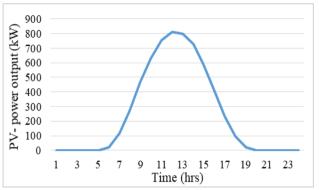


Fig.2 Solar power output curve for 24 hrs

Wind Turbine Generator

In this paper, the liner model of wind power output has been taken into account. In Fig.3 the output curve of wind turbine is shown.

$$\begin{split} P_{wind} &= \{P_{rated}\left(\frac{(v-v_{in})^2}{(v_r-v_{in})^2}\right) \; ; \; v_{in} \leq v \leq \\ v_r \; P_{rated} \; ; \qquad \qquad v_r \leq v \leq v_{out} \; 0 \qquad ; \qquad v > \\ v_{out} \; and \; v < v_{cut} \end{split}$$

where, P_{rated} is the rated Wind Turbine power, P_{wind} is the Wind-Turbine power output v_{in} is cut in the velocity of Wind Turbine, v_{out} is cut out Wind Turbine velocity

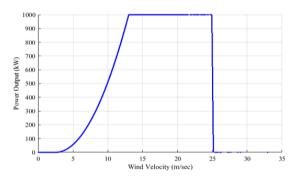


Fig. 3 Wind Turbine power output curve

5) **Combined Power Loss Sensitivity Method** (CPLS).

This method [10] considers both active and reactive power loss for the formulation of sensitivity factors. The bus with highest sensitivity factor for which normalized sensitivity value is less than 0.0015 is chosen as the location for placement DG. The formulation for sensitivity factors are as follows:

$$\frac{\partial P_{loss}^{k}}{\partial Q_{i}^{k}} = \frac{2Q_{l}^{k}R_{l}}{(V_{i}^{k})^{2}}; \frac{\partial P_{loss}^{k}}{\partial P_{i}^{k}} = \frac{2P_{i}^{k}R_{l}}{(V_{i}^{k})^{2}}$$

$$\frac{\partial Q_{loss}^{k}}{\partial Q_{i}^{k}} = \frac{2Q_{l}^{k}X_{l}}{(V_{i}^{k})^{2}}; \frac{\partial Q_{loss}^{k}}{\partial P_{i}^{k}} = \frac{2P_{i}^{k}X_{l}}{(V_{i}^{k})^{2}}$$
(9)

$$\frac{\partial Q_{loss}^k}{\partial Q_l^k} = \frac{2Q_l^k X_l}{(V_l^k)^2}; \frac{\partial Q_{loss}^k}{\partial P_l^k} = \frac{2P_l^k X_l}{(V_l^k)^2}$$
(9)

combined loss sensitivity with respect to reactive power is given by

$$\frac{\partial S_{loss}^{k}}{\partial P_{i}^{k}} = \frac{\partial P_{loss}^{k}}{\partial P_{i}^{k}} + j \frac{\partial Q_{loss}^{k}}{\partial P_{i}^{k}}$$

$$\frac{\partial S_{loss}^{k}}{\partial Q_{i}^{k}} = \frac{\partial P_{loss}^{k}}{\partial Q_{i}^{k}} + j \frac{\partial Q_{loss}^{k}}{\partial Q_{i}^{k}}$$
(11)

$$\frac{\partial S_{loss}^{k}}{\partial o_{i}^{k}} = \frac{\partial P_{loss}^{k}}{\partial o_{i}^{k}} + j \frac{\partial Q_{loss}^{k}}{\partial o_{i}^{k}} \tag{11}$$

Distribution ZIP load model

In this paper, the time-varying ZIP load model is represented. The constant impedance, constant current and constant power load model for residential, commercial and industrial loads has been carried out for the analysis.

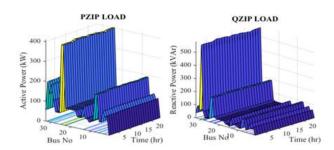


Fig.4 ZIP Load profile

The expressions for zip load model is represented as

$$P_{i,k}^{ZIP} = Pd_i \left[Z_p \left(\frac{V_i^k}{V_{min}^k} \right)^2 + I_p \left(\frac{V_i^k}{V_{min}^k} \right) + P_p \right]$$
 (12)

$$Q_{i,k}^{ZIP} = Qd_i \left[Z_q \left(\frac{v_i^k}{v_{min}^k} \right)^2 + I_q \left(\frac{v_i^k}{v_{min}^k} \right) + P_q \right]$$
 (13)

 $\forall \{Z_i + I_i + P_i = 1\}$, where, Z_i , I_i and P_i are the constant impedance, constant current and constant power load parameter for different type of costumer [20]. Pd_i and Qd_i are the load demand at each bus i. The active and reactive part of ZIP load is shown in Fig.4.

A. B Mathematical model formulation

The following objective function has formulated as: Optimal power flow formulation.

Optimal power flow is formulated by minimizing the total power loss which is given by the equations

Minimize

$$OF = \sqrt{\left[\left(\sum_{i,j=1}^{k} PL_{ij}\right)^{2} + \left(\sum_{i,j=1}^{k} QL_{ij}\right)^{2}\right]}$$

Constraints Equation:

(i). Power balance constraints:

$$\begin{split} P_i^k &= P_{DGi}^k + P_{dis,i}^k - P_{ch,i}^k - P_{i,k}^{ZIP} \\ &= V_i^k \sum_{j=1}^n V_j^k \left(G_{ij}^k \cos \cos \left(\delta_i^k - \delta_j^k \right) + B_{ij}^k \right. \\ &\sin \sin \left(\delta_i^k - \delta_j^k \right) \right) \\ , \ i \in S_B \ \& \ k \in S_T \end{split}$$

$$\begin{array}{l} Q_i^k = Q_{DG,i}^k - Q_{i,k}^{ZIP} = V_i^k \sum_{j=1}^n \quad V_j^k \left(G_{ij}^k \sin \sin \left(\delta_i^k - \delta_j^k \right) - B_{ij}^k \cos \cos \left(\delta_i^k - \delta_j^k \right) \right), \; i \in S_B \ \& \; k \in S_T \end{array}$$

where $\forall i = 1, 2 \dots nb$, $\forall ij = 1, 2 \dots nl$, nb is a number of buses and nl is the total number of line. $\forall k = 1,2....24$ is the set of time. P_i^k is the total active power injected at the ith bus for kth hours. $P_{i,k}^{ZIP}$ is the total active power demand of ZIP Load at ith bus for kth hours. $Q_{i,k}^{ZIP}$ is the total reactive power demand of ZIP Load at ith bus for kth hours.

(ii) DG's power Limits

$$P_{DG,i}^{min} \leq P_{DG,i}^{k} \leq P_{DG,i}^{max}$$

$$Q_{DG,i}^{min} \leq Q_{DG,i}^{k} \leq Q_{DG,i}^{max}$$

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(iii) Limits for voltage and angle



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$$V_i^{min} \le V_i^k \le V_i^{max}, \ i \in S_B$$

$$\delta_i^{min} \le \delta_i^k \le \delta_i^{max} \ \forall i = 1, 2 \dots nb$$

(iv) Line loss limit

$$\begin{split} |Pl^k| &= \left| P_{ij}^k \right| = \left| V_i^k V_j^k \left(G_{ij}^k \cos \cos \left(\delta_i^k - \delta_i^k \right) + B_{ij}^k \cos \cos \left(\delta_i^k - \delta_i^k \right) \right) - (V_i^k)^2 G_{ij}^k \right| \leq Pl_{max}^k, l \in S_L \end{split}$$

where, S_B represent the set of Bus i

(v) Transmission line sending end and receiving end constraints

$$P_{fsmin_{j}}^{k} \leq P_{fs_{j}} \leq P_{fsmax_{j}}^{k}, \ i \in S_{fs}$$

$$Q_{fsmin_i}^k \le Q_{fs_j} \le Q_{fsmax_j}^k, i \in S_{fs}$$

$$P_{frmin_{i}}^{k} \leq P_{fr_{i}} \leq P_{frmax_{i}}^{k}, i \in S_{fr}$$

$$Q_{frmin_i}^k \le Q_{fr_i} \le Q_{frmax_i}^k, i \in S_{fr}$$

where, S_{fs} , S_{fs} represents the set of Bus i for sending and receiving end power flow.

1.1 **Dispatch Strategy**

In this model, the DG and storage device as a battery have been with an objective to minimize the total power loss and cost of the system. In order to maximize the reliability and yet maintain the cost along with minimum power loss, different dispatch strategies like as Load following strategy, Cycle charging strategy or combined strategy can be used [5], [13]. In this paper the combined strategy is implemented for the location of energy storage device as batteries.

III.ALGORITHM USED

The various steps involved in finding the optimal location and sizing of DGs with and without batteries in such a way to minimize the total power losses in distribution system summarized as:

Step 1: Read the system data for IEEE 33-bus radial distribution system.

Step 2: Run the load flow program for the 24-hour load data and obtain the base case for total power losses.

Step 3: Obtain the PLS at each node for 24 hours based on the distribution load flow. Select the node having the highest PLS factor for the position of DGs.

Step 4: Obtain the position of batteries at each node for 24 hours using dispatch strategy [13], in the form of a matrix (bus, hours). Save the position set of battery storage to obtain the size at each node.

Step 5: Transfer the all control parameter from MATLAB to GAMS using interfacing.

Step 6: Solve the optimal load flow for optimal size of DGs with and without batteries, calculate the SOC using MINLP solver to minimize the total power loss.

Step 7: Transfer the objective variables form GAMS to MATLAB.

Step 8: Print the results.

Retrieval Number: E1007069520/2020©BEIESP DOI: 10.35940/ijeat.E1007.069520 Journal Website: www.ijeat.org The flow chart (1) shown in Fig.5.

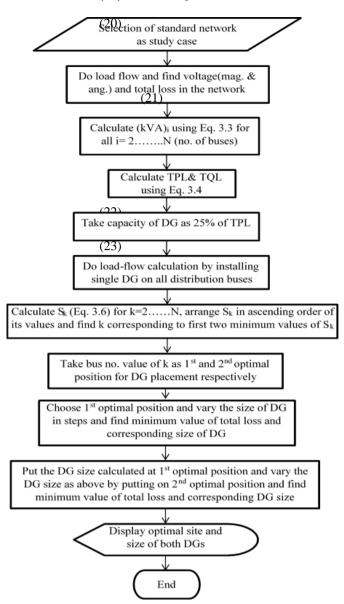


Fig. 5. Flow chart for the algorithm used

IV.SYSTEM DATA

The system data are given in this paper represented as follows;

A. Load data and Market price data

The ZIP load data [35] for the residential, commercial, and industrial consumers are given in Table I.

Table- I: Cost coefficients of ZIP load for various customers

customers						
Type	Zp	Ip	Pp	Zq	Iq	Pq
Residential	0.414	0.136	0.450	0.160	0.375	0.465
Commercial	0.860	-0.160	0.300	0.60	0.660	-0.260
Industrial	0	0	1	0	0	1

The percentage of load demand in residential, commercial and industrial are shown in Table II.

Table- II: Percentage of demand for various

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customers and market price

Time	Res	Com	Indu.	Market
				Price
t1	0.66	0.17	0.17	0.11
t2	0.63	0.17	0.20	0.10
t3	0.60	0.18	0.22	0.11
t4	0.58	0.20	0.22	0.09
t5	0.60	0.23	0.17	0.11
t6	0.55	0.15	0.30	0.11
t7	0.30	0.14	0.56	0.13
t8	0.11	0.32	0.57	0.15
t9	0.10	0.34	0.56	0.26
t10	0.11	0.33	0.56	0.30
t11	0.12	0.37	0.51	0.35
t12	0.17	0.46	0.37	0.40
t13	0.14	0.37	0.49	0.50
t14	0.14	0.39	0.47	0.40
t15	0.15	0.46	0.39	0.30
t16	0.18	0.41	0.41	0.30
t17	0.20	0.44	0.36	0.40
t18	0.33	0.47	0.20	0.50
t19	0.60	0.30	0.10	0.30
t20	0.70	0.23	0.06	0.26
t21	0.74	0.19	0.07	0.15
t22	0.76	0.15	0.09	0.13
t23	0.75	0.15	0.10	0.10
t24	0.71	0.16	0.13	0.11

B. Solar and Wind Turbine cost data

Table- IV: The input data for the energy sources

14010	Acquisit ion cost	Operation and	Replacem ent	Lifes pan	Rating
	(\$)	Maintenance Cost (\$/year/kW)	Cost (\$/Lifeti me)	(year)	
PV module	2400	18	2.85 @ 25 year of life time	25	800 (kW)
Wind Turbine (1MW)	3724.5	31	3009.5	20	1000 (kW)
Battery Storage	600	20	4.64 @ 1.45 year		100 (kWh)

The input data used in this paper has shown in Table- IV. The cost estimation data for the PV-based DG and wind-based DG have been taken from the National Renewable Energy Laboratory (NREL) [21], [22] & [23]. The data for battery, regulators and investors are taken from the literature [24].

The **Si-mono PV modules (ET –Solar maker)** of PV module has been taken for the analysis in this paper.

V.RESULTS AND DISCUSSION

The energy storage system incorporated with Distribution Generation in radial distribution system under consideration has been designed by GAMS optimization tool. To demonstrate the proposed optimized algorithm by GAMS and MATLAB interfacing has been tested on IEEE-33 bus test system. In this algorithm, the optimization has been done by using GAMS optimization tool in such a way to minimize the total power loss, planning the optimum location and sizing of DGs.

In this context the DG of type-1 and Type-3 has been considered for analysis. In DG Type-1, operating at unity power factor and capable of injecting real power to the distribution system. Whereas the DG type-3 operating at

lagging power factor and capable of injecting real and reactive power to the distribution system.

In this section two cases has been taken as follows;

- Case-1: DGs without energy storage has been considered.
- Case-2: DGs with energy storage has been considered.

In Case-1 single as well as multiple DGs has been taken into account. In Case-2; the single and multiple DGs with type-1 and Type-3 has been considered for analyzing the impact of battery energy storage also.

A. Result for combined power loss sensitivity

The combined power loss sensitivity approach is used to calculate the location of DGs and thus the corresponding size of DGs is obtained as explain in section II. From Fig.6 the highest PLS obtained is for at bus number 8, 24, and 25 as is shown. The criterion for selection of the optimal placement of DGs is set if PLS is greater than 0.0015, due to this bus no 20 and 31 are also be selected.

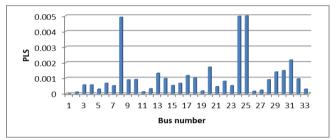


Fig. 6. PLS profile for 33-bus radial distribution system

B. Case 1

The single DG of Type-1 at 8th bus and obtained size is 2521.8 kW, whereas the multiple DGs located at bus number 8, 24 and 25. The obtained size of multiple DGs are 1424.9, 448.84 and 420.22 kW at bus number 8th, 24th, and 25th respectively. The size of DGs Type-3 without battery storage has been shown in Fig.7 the location for the multiple DG of Type-3 located at bus number 8, 20, 24, 25 and 31. The active and reactive power rating required for DGs has also shown.

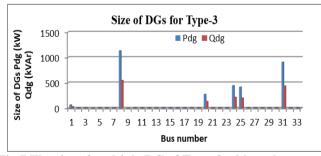


Fig.7 The size of multiple DG of Type-3 without battery storage

The Fig.7 shows the real and reactive power for DGs of type-3.

The optimal location and placement for DGs type-3

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shown in Table-V, the selection criteria is based on PLS. The higher value of PLS indicates the higher losses in the system, for selection of single DG the losses are larger, and it has been decreasing simultaneously with increasing the number of DGs. for DGs of Type-3

C. Case 2: DGs with battery storage

The second part of this paper is to the analysis of Battery energy storage with DGs to share the real power injection as well as to minimize the total power loss. The location and sizing of the battery energy storage are based on the combined load cycling method [20].

1). Size of DGs type-1 with Battery energy storage

Fig.8 shows the size and location of DG for 24 hours load along with the battery. The position of multiple DGs Type-1 with battery energy storage (BES) is 8, 20, 24, 25 and 31 based on the highest value of PLS.

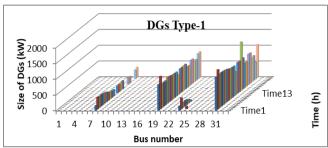


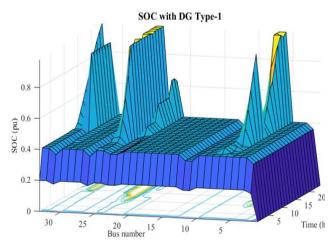
Fig. 1. DGs Type-1 profile for 24 hours load 33-bus radial distribution system

In Table V shows the result for the optimal size and placement of DG with battery.

The size of single DG with battery storage obtained is 1684.3 kW at 25th bus. The size of battery storage obtained is 13.8 kWh. the required data for battery storage is given in section-IV.

Table V. Result for DG with Battery storage

Method	Optimal	Optimal DGs Size (kW)
	Location	
	25	[1684.3]
Propose	7, 8, 24, 25	[1350.2, 1499.4
d		446.73, 418.68]
	8, 20, 24, 25	[523.22, 1843.5,
	31	139.14 9.2789, 2333.5]



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Fig. 2. State of charge profile for 24 hours load 33-bus radial distribution system

The lower limit of SOC value is 0.4 in per unit (pu) of (base value of 100) is taken and the maximum value is 1 pu when the battery is fully charged. At the minimum value of SOC battery get charged to maintain the SOC up to 90-100 %, beyond 40% the battery is fully discharged and it stops supplying the real power. The SOC has been calculated for the battery size of 13.8 kWh battery. The Lithium-ion battery has been taken in to account for the analysis.

2). The size of DG type -3 with battery storage

The best location of DGs Type -3 with battery storage are selected at bus number 8, 20 and 24. At bus number 8 the highest active power supplied by the diesel generator is in 5th and 23rd hours. Among all the DGs, largest amount of power shared by DG at bus number 20 for 23rd hrs.

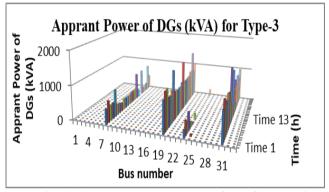


Fig. 10. Apparent power output for DGs Type-3 profile for 24 hours load 33-bus radial distribution system

The size of DGs Type-3 with battery storage obtained are 1200 kVA at 20th bus, 600 kVA at 8th bus and 1000 kVA at 31st bus. The apparent power of DG is shared simultaneously higher at bus number 31, and at 7th hour the reactive power demand is higher

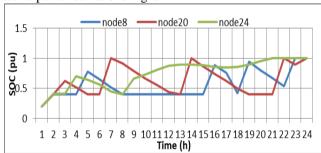


Fig. 11. Result and comparison for SOC at node 8, 20, 24 for DG type 3

Fig.... shows the location of battery storage obtained at bus number 8, 20 and 24th. The SOC at bus number 8, 20 and 24 for 24th hours load duration. In Fig.12 the minimum SOC is maintained at 40% for safely utilization of battery power. Once diesel generator placed at 8th bus, the load has been shared by the DG, therefor battery remains fully-charged so it represents the highest value of SOC at that time. On the other hand, the SOC at the remaining bus is

less, at that time of instant the battery get discharge.

In the Fig.13 the SOC profile shown at bus number

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File shown at bus number

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8 20 and 24, the DGs placed at the bus no 8, 20 and 24. The blue line indicates the SOC at bus no 8, the battery is charging from 4th to 5th hours and then discharge from 5th to 8th hours as per the load demand. Whereas the red line indicates the battery status at the bus no 20, the battery get initially charge up-to 3rd hour the discharge from 3rd to 5th hour simultaneously.

Table VI Result for DG with battery storage system

	DG + Battery	
	DC to 1	DC town 2
	DG type-1	DG type-3
Installation	6978.1 €	6978.1 €
cost of		
DG+ Battery		
+ Regulator		
Total Cost	14925 €	6.2407e+05 €

D. Comparison with other method

The size of DG without battery storage has been shown in Table-VII. The purposed method has been compared with existing method in Table-VII

Table-VII. Result of comparison of existing method and purposed method with DG.

and purposed method with DG.						
Method	Optimal	Optimal	Losses (kW)			
	Locatio	DGs Size	Without	With		
	n	(kW)	DG	DG		
PSO [2]	6	2590	211.20	110.10		
ELF [25]	6	2600	211.20	111.10		
NM [10]	6	2494.80	210.98	111.14		
CPLS	8	1800	210.98	111.14		
[10]						
	8	[2521.8]	210.98	110.63		
Proposed	8 24 25	[1424.9	210.98	79.356		
		448.84				
		420.22]				

In this context, the power loss has been reduced to 110.63 kW with single DG and 79.356 kW with multiple DG installation respectively. Therefore, power loss has been reduced to 47.59 % with direct approach by using single DG. The power loss has reduced to 62.38% with direct approach by using multiple DGs.

At bus number 25 the size of DG is 684.3 kW, but the losses are higher in this case, on the other hand at bus number 7, 8, 24 and 25 the losses are reduced.

E. Voltage profile

The 33-bus radial distribution system using the direct approach for the comparison of direct approach method [14] without DGs and proposed method with DGs for voltage profile shown in Fig 5. The voltage profile has been improved considerably in the proposed method.

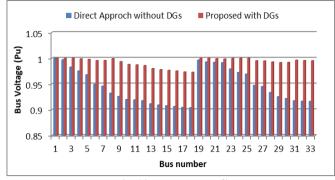


Fig.12 Voltage Profile

The comparison of voltage, the angle at each bus, total power loss and execution time using the direct approach and proposed approach with DGs is given in Table-III. The voltage magnitude in per unit, angle in radian, power loss in kW unit is given in the Table-III. With the proposed approach, the losses are very low and the execution time has reduced drastically compared to the direct approach in [14].

VI.CONCLUSION

This paper has presented a novel application of GAMS software to perform the dispatch strategy with optimal location of DG along with battery energy storage device. The two-phase scheme has been proposed for DG and battery allocation in the distribution system. In the first phase, the candidate nodes are selected as the optimal DG location along with battery position and second phase, optimal DG with battery size are computed. The two techniques are used. In first, combined power loss sensitivity (CPLS) has been used for optimal DG location and second, the combined dispatch strategy has been used for placement of the battery. Also, the MINLP solver of GAMS has been used for optimal sizing of DG with battery. The results have been obtaining with and without considering the battery, the PLS limit is changed for finding the optimal location and minimum power loss. The proposed method is tested on IEEE 33-bus test system. In terms of voltage profile and total power loss reduction, the purposed method has superior results than existing methods.

LIST OF SYMBOL

P_{solar}	Solar output power	P_{wind}	Wind output power
S_{DG}	Set of DG location	nb	Total number of buses
δ_i	Voltage angle at bus i	v_{in}	Cut in velocity of wind,



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V	Rated Voltage	v_{out}	cut out velocity of wind,
N_{PV}	Total number of the solar panel	SOC_{min}	minimum state of charge
i	Index for bus	SOC _{max}	maximum state of chare
k	Index for time	N_{batt}	total number of battery
$P_{dis_i^k}^{}$	Discharge power for i th bus at k th time	DOD _{max _bat}	maximum depth of discharge of battery
$P_{ch_i}^{k}$	Charge power for i th bus at k th time	А, В	Fuel curve constant
L_{cc}	Cycle charging coefficient	P_{NGen}	Rated power of Diesel Generator
$Pd_{net_Load}^{k}_{i}$	Net DC load for i th bus at k th time	$pf_{deg_{\dot{i}}}$	Power factor of Diesel Generator

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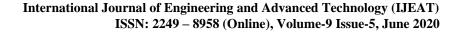
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