

A Non-Inverting Soft Switching Buck-Boost Converter (Closed Loop) and It's Performance Against Various Converters



R. Senthil kumar, N. Vishaal Balaji, N. Venkatesh, J.Ajay

Abstract: A Non-inverting soft switching buck-boost Converter is presented. One of the major hurdles that every converters face is switching losses. This loss is associated with the switches that are used to build the converters. To overcome this, magnetic coupling effect has been introduced to the proposed converter. This magnetic coupling effect helps the converter to obtain an adjustable soft switching range. Theoretically, it has been said that soft switching results in zero switching losses. That way, the losses due to switching can be neglected and that helps in improving the overall efficiency. In the paper, we have proposed a soft switching non inverting buck-boost converter and compared its performance characteristics with various other converters.

Keywords: Coupling, Inductor, Capacitor, zero voltage switching, Soft switching, Hard switching, Power converters, DC-DC, Coupled Inductor, Non-inverting, Buck-Boost Converter, Zeta Converter

I. INTRODUCTION

A converter used in electrical applications converts the electrical power from any one form to another. The converters are classified into different types, based on the type of the power given as input and the converted output. They are DC-AC, DC-DC, AC-AC and AC-DC. Let us mainly focus on the DC-DC converter. The DC-DC converter, converts a fixed DC input to a variable DC voltage. It has applications ranging from very low levels of power like small batteries to extremely high-power applications like in power systems. They have been efficient and better alternatives compared to vibrators, which were used to convert the input power to AC and later given to a transformer for stepping down voltage and then fed to rectifier to get a DC output. And for high power applications, generators of the desired output voltage were used to give the DC output. This conversion was very inefficient as there was a very high loss of power in the circuit. So, power switches were used to build these converters. They were comparatively better and viable alternatives to the earlier methods of power conversion. Although these are very efficient compared to the olden techniques, they are also not perfect. As the switching frequency increases it is important to reduce the loss that take place in the converter.

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This loss is called as switching loss. Switching losses are associated with the switches used and they occur due to the transition of the switches from one state to another state. To avoid switching losses in converters, we use a technique called soft switching[1]. To understand soft switching, we need to understand about hard switching. As we know, a transistor is a three-terminal device with a simple logic – the flow of electricity in the third pin allows the passage of current between the other two terminals. So, the transistor is in either on or off state. The transition from on to off state or the reverse is not instantaneous, but consumes a very short time. In this transition period, some energy is wasted which are switching losses. These amount to a higher percentage of losses in power converters converters[3]. Switches that operate on larger voltages have larger losses. These losses have an effect on the overall efficiency of the converter[4]. Switching losses occur when the voltage and current waveforms intersect (Refer fig.). Soft switching reduces this loss by either reducing the voltage or current to zero, so that the power loss is virtually zero as power is tantamount to the product of voltage past the switch and the current[2]. Depending on which parameter is to be reduced to zero, soft switching is classified into two types:

- 1) zero voltage switching
- 2) zero current switching.

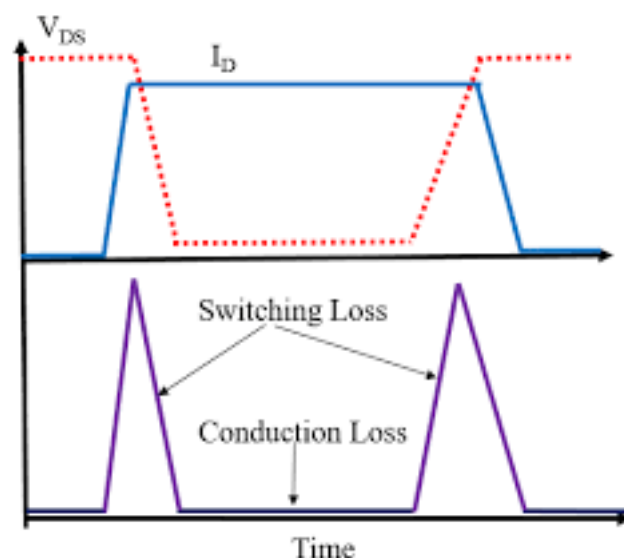


Fig. 1. Soft Switching

$$P_{\text{loss}} = V \cdot I$$

Soft switching improves the overall efficiency of the converter.

To achieve this, an external circuit is used. This circuit helps in overlapping the voltage and current waveforms. There are two types: self resonance and forced resonance. A self oscillating circuit is used in case of self resonance. With precise timing of the transistor commutation, results a narrow offset in current and voltage waveforms. Forced resonance uses various inputs to calculate the timing required to force a resonance to offset the current and voltage waveforms. Soft switching is further classified into three types based on the circuits used for obtaining it.

- 1) Passive auxiliary circuit based soft switching
- 2) Auxiliary circuit based soft switching
- 3) Non-auxiliary circuit based soft switching

Since using non-auxiliary circuit based soft switching results in large current ripples it is avoided. Passive auxiliary circuit based switching does not allow bidirectional soft-switching. Auxiliary circuit switching results in reducing the switching losses but additional control and driver circuits have to be used resulting in complexity of the circuit. In this paper, using coupled inductor a non-inverting soft switching buck-boost converter (closed loop) is presented and its performance characteristics are compared with other converters.

II. OPERATION

The converter operation can be explained by splitting it into several stages.

Stage 1: All the switches are switched off. `Capacitors charge during this phase.

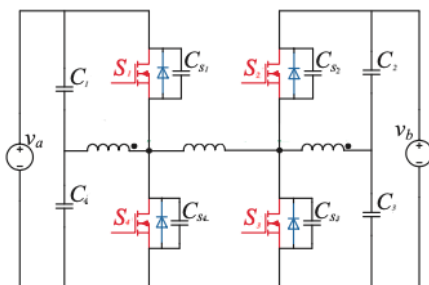
Stage 2: The diodes connected across the switches s2 and s4 will be turned on. In this phase the voltage across vs2 and vs4 will be approaching zero

Stage 3: Now switches s2 and s4 are turned on.

Stage 4: All the four switches are turned off in this phase.

Stage 5: Diodes across s1 and s3 are turned on like stage 2, therefore voltage across the switches s1 and s3 approaches to zero.

Stage 6: Switches s1 and s3 are turned on similar to stage 3. During this stage, power is stocked in the Inductor (L) .



$$i_{s1} = v_a DT(1-D)(1-D+kD) / 2Lr(1-k^2) > i_b$$

$$i_{s2} = v_a DT(1-D)(k+D-kD) / 2Lr(1-k^2) > i_b$$

$$v_o = v_{in} * D / (1-D)$$

The above equations are the conditions for achieving soft switching[6] . Where,

Va = Voltage from source A.

Vb = Voltage from source B.

D = Duty Cycle

Lr = Auxiliary Inductor

M = kLr = Mutual Inductance

V_o = Output Voltage

V_{in} = Input Voltage

III. SIMULATION

Non-inverting soft switching buck-boost converter with closed loop. Proposed converter's circuit diagram is shown in fig. 2. Simulated results of the proposed converter are also provided below. Simulated results includes voltage across the switches (refer fig.2.1), capacitor currents (refer fig.2.2) and inductor currents (refer fig.2.3).

A. Non-Inverting Buck-Boost Converter

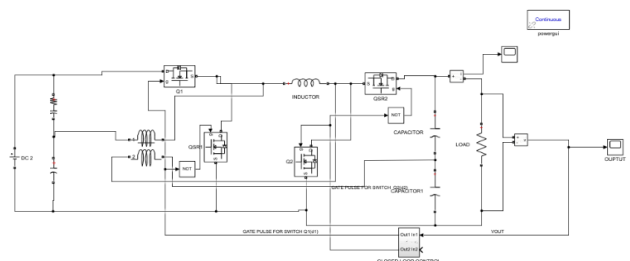


Fig. 2. Proposed circuit diagram

Values of the components:

Input voltage – 12 V

Main inductor – 780nH

Auxiliary inductor – 50mH

Resistor – 100 ohms

Capacitor – 4.7 uF, 1 F

Simulated result:

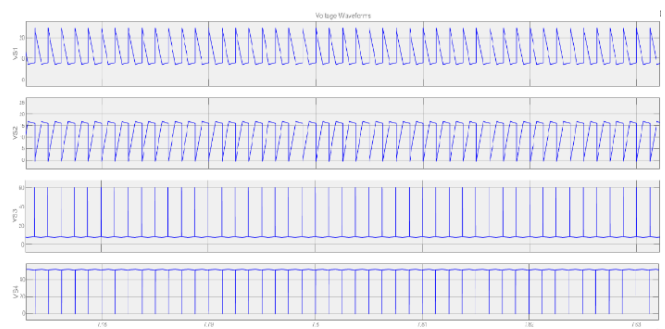


Fig.2.1. Voltages across the switches

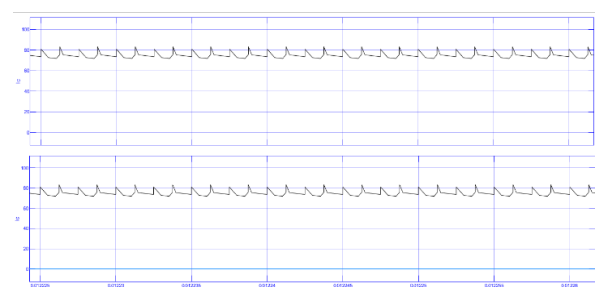


Fig.2.2. Capacitor current

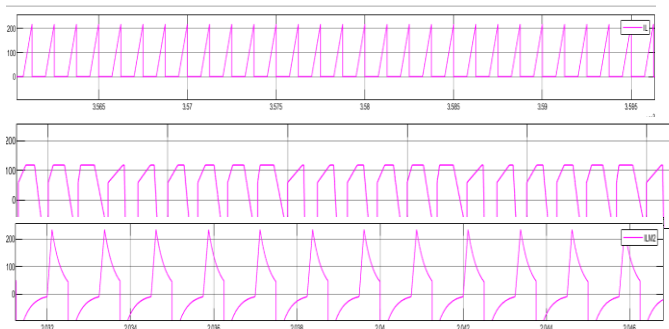


Fig.2.3. Inductor currents

B. Zeta Converter

Zeta converter circuit diagram along with its simulated results are presented below. The parameter values are same as that used in case of non-inverting soft switching buck-boost converter. The simulated results include output voltage (Refer fig.3.1), inductor current (Refer fig. 3.2) and capacitor current (Refer fig. 3.3).

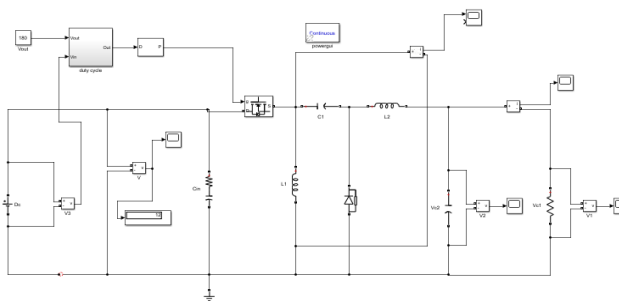


Fig.3. Zeta circuit diagram

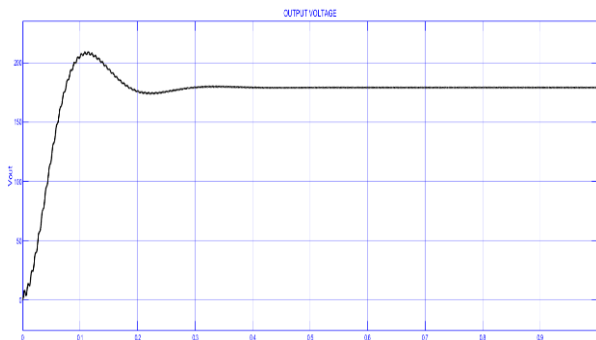


Fig.3.1. Output voltage

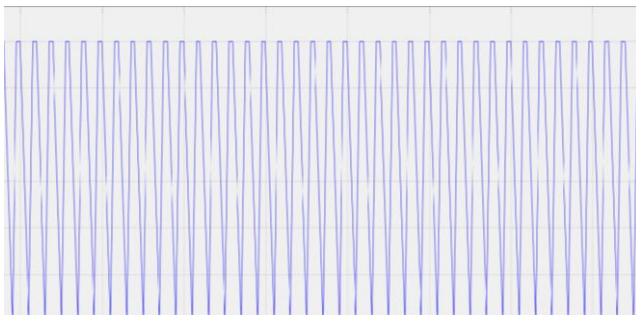


Fig.3.2 Inductor current

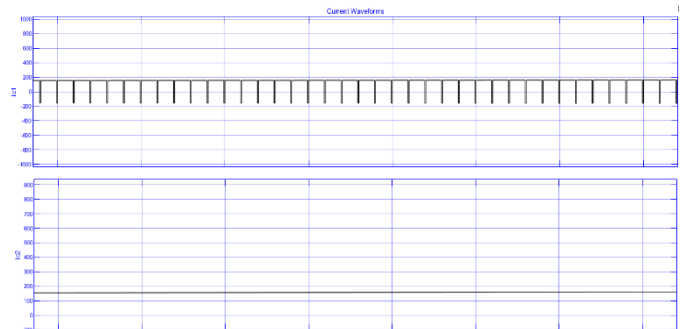


Fig.3.3 Capacitor current

C. Inverting Buck-Boost Converter

Conventional buck-boost converter (Inverting) is considered. The simulated results include output voltage (Refer fig.4.1) and output current (Refer fig. 4.2).

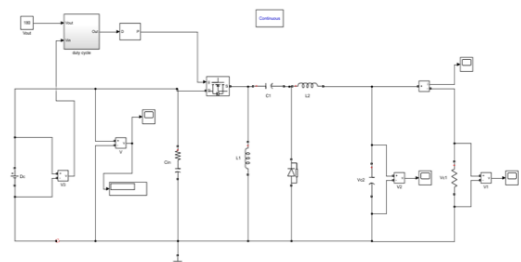


Fig. 4. Inverting buck-boost converter circuit

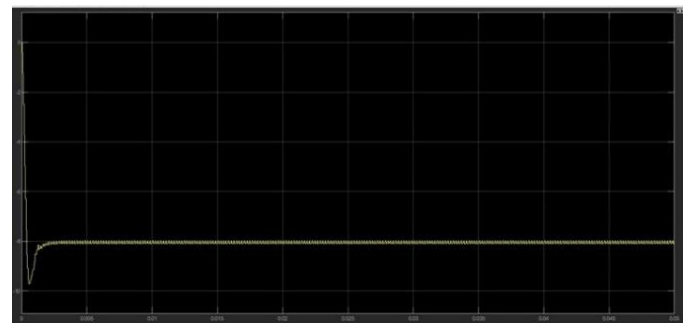


Fig. 4.1. Output voltage of inverting Buck-Boost converter

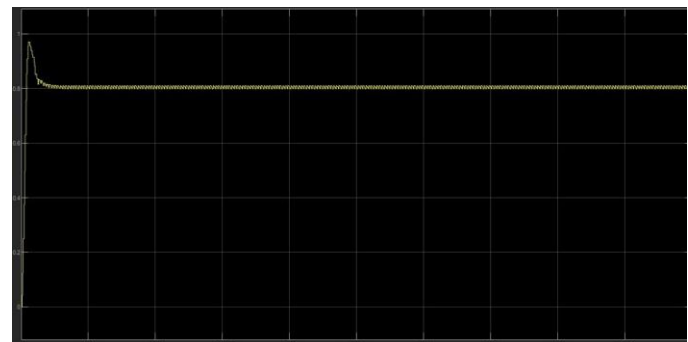


Fig. 4.2. Output Current

D. Simulated Results

S. No	Converter	Input Voltage	Output Voltage
1	Proposed Converter	12V	120V
2	Zeta Converter	12V	140V
3	Inverting Buck-Boost Converter	12V	20V (Negative polarity)

IV. HARDWARE

A. Overall Block Diagram:

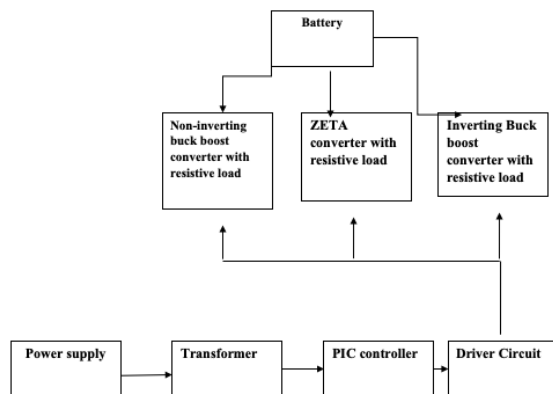


Fig. 4.3 Block Diagram

The hardware consists of three converters connected to the control and driver circuit. The converters are Non-inverting soft switching buck-boost converter (proposed), zeta converter, inverting buck-boost converter. As the supply is given to the control and driver circuit, the proposed converter operates in boost mode. The hardware consists of 3 switches where the first switch can be used for making the proposed converter operate in buck mode. Second switch is used for operating zeta converter. And the third switch is used for operating inverting buck-boost converter. The input voltage and the output voltage can be measured through the connectors provided. Harmonic analyser, power analyser and Digital Oscilloscope can be used for measuring the current and voltage harmonics.

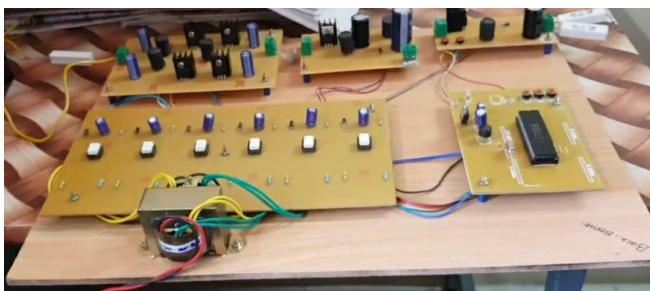


Fig. 4.4 Hardware Prototype

B. Circuit Description:

S.NO	Component Name	Specifications	Ratings
1	Mosfet	IRF840	-
2	Diode	IN4007	-

3	Opto Coupler	TLP250	-
4	Capacitor	μF	250
5	Resistor	Ω	
6	PIC	16F778A	5V
7	Transformer		12/5V
8	Battery	AT12-1.3	12V-1.3A

V. CONCLUSION

A Non-Inverting soft switching Buck-Boost converter is presented. Performance of the proposed converter in both open loop and closed loop were analysed. A comparison between the proposed converter and various other converters were carried out. Closed loop results were more precise and stable than the open loop. General performance analysis of the proposed converter was carried out along with various other converters like zeta converter, inverting buck-boost converter. The output voltage, stability of various converters were verified by building an experimental prototype.

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