# Validating Encounter Model Assumptions and Representativeness for the Class B Environment

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**RTCA SC-228** 

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### Correlated Encounters between Aircraft in Terminal Airspace

- Revision A of the DAA MOPS by RTCA SC-228 permits UAS terminal operations in Class C, D, E and G airspaces
- To support MOPS certification, MIT LL developing a statistical model of how aircraft behave near or within terminal airspace, traffic patterns, and runway operations
  - Class C, D, E, G aerodromes with single or multiple runways
  - Ownship assumed to be a fixed-wing landing straight-in or taking off straight-out
  - Intruder can land or takeoff by any means and also merely transit through the airspace
  - Intruder classified as either fixed-wing or rotorcraft
  - Prototype unvalidated model available for Class B airports
  - Out of scope was vertiports and aircraft operating from nearby airports
- An encounter was defined based on the geometry between aircraft and a runway
  - Aircraft within 4 nautical miles laterally and 2000 feet vertically of each other
  - Encounter must be at least 30 seconds in duration (both aircraft tracks exist)\*
  - Both aircraft must be within 8 nautical miles laterally and 5000 feet vertically of a runway

IAP – Instrument Approach Procedure



# **Correlated Terminal Model History**

Attribute	Feature	V1 (06/2020)	V2 (03/2021)	V3 (10/2021†)
Ownship Intent	Landings – Straight In	0	0	✓
	Take offs – Straight Out	×	0	✓
Intruder Intent	Landings – Any	0	0	✓
	Take offs – Any	0	0	✓
	Transit – Any (General)	×	0	0
	Transit - Published Routes	×	×	×
Airspace Class	В	×	×	0
	С	×	0	✓
	D	✓	✓	✓
	Other (E/G)	×	✓	✓
Aerodrome Design	Single Runway	✓	✓	✓
	Multiple Runways	×	×	✓
	Heliports / Vertiports	×	×	×
Technology Transfer	Publicly Available Models <sup>‡</sup>	×	×	$\checkmark$

🗴 No Support 🔘

Prototype feature with update in a future version

 $\checkmark$ 



- 1. Operational Suitability Analysis: validating and informing DO-365 alerting thresholds
  - A. Leverage existing surveillance data sources—TRAMS, RADES, ADS-B—in the Class B terminal environments to generate representative Class B operational suitability encounter set(s)
  - B. Assess alerting performance in Class B using existing alerting requirements/implementations (DAIDALUS), and assess alternatives if needed
- 2. Safety Analysis: validating and informing surveillance performance requirements and safety analysis (e.g., to support TSO/SRM)
  - 1. Validate encounter model assumptions and representativeness for Class B environment
  - 2. Modify encounter model structure and relearn model based on identified extensions (in 2.1.)
  - 3. Perform initial simulation analysis to validate the model use and provide preliminary indication of safety performance

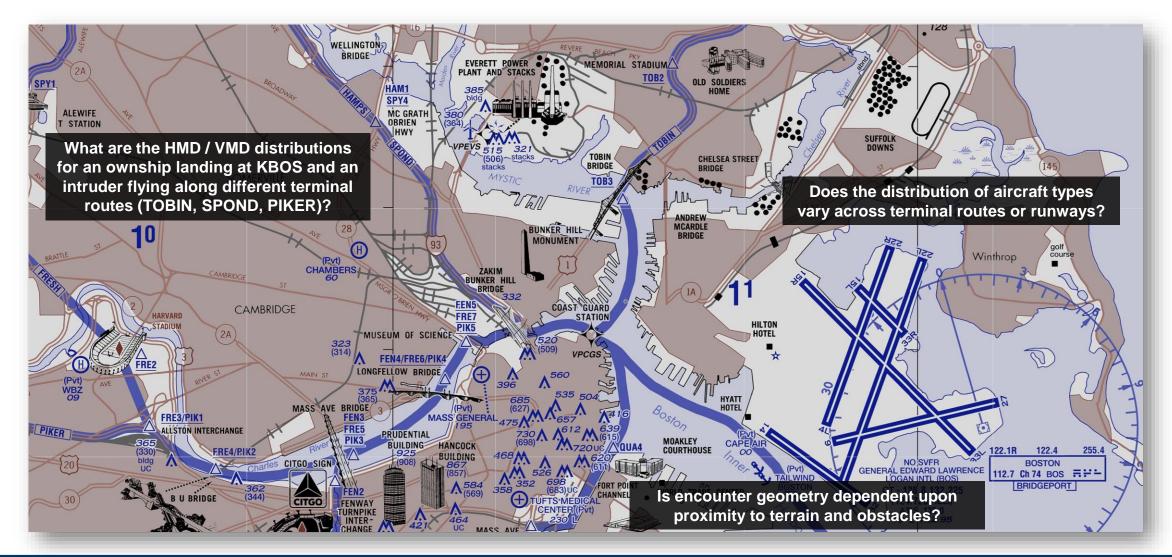
\*Not formally encounter model/set development or needed to directly support the MOPS (could be separate effort). †Represents latest deliverable date; should be accomplished earlier if possible to reduce risk. Note: estimates do not fully consider multi-threat encounters.



- Does an encounter between a large aircraft landing at a Class B runway and a helicopter flying within a VFR route differ from an encounter between two large aircraft landing at the same airport but different runways?
- What is the likelihood of an encounter with 3 or more aircraft? Is it significantly more likely to occur in Class B airspace than Class D?
- What airspace structures exist besides runway approach and departure corridors?
- Should the model be dependent upon time of day or location (i.e. JFK vs LAX)?



## **Motivating Questions**



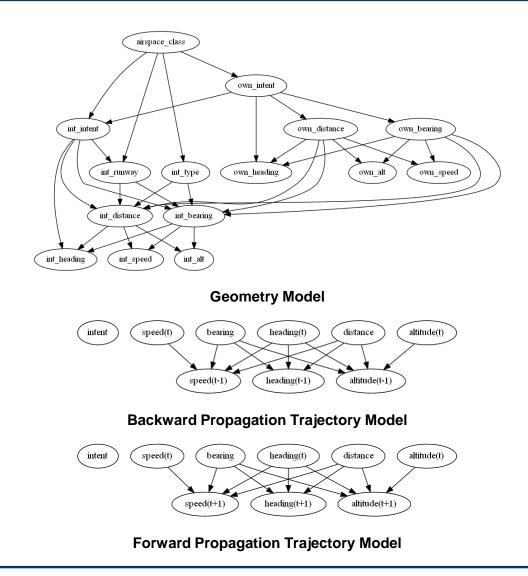
Terminal Model AJW 10/13/21 7 HMD – horizontal miss distance VMD – vertical miss distance VFR – visual flight rules

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## Current Correlated Terminal Model Structure October 2021

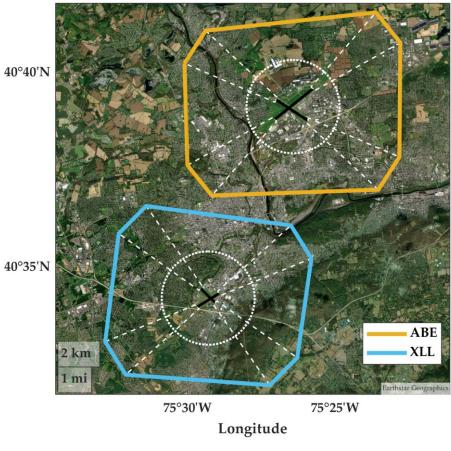
- Correlated terminal model consists of multiple distinct Bayesian Networks
  - Geometry model is a static Bayesian Network that represents the relative geometry of the aircraft with the respect to the runway at CPA
  - Ownship and intruder each have a trajectory model, a dynamic Bayesian network, for the aircraft kinematics
- Rejection sampling of the models used to model ownship to behave similar to UAS defined by RTCA SC-228
- Sampled sets of encounters generated to support RTCA SC-228 SRMD





Latitude

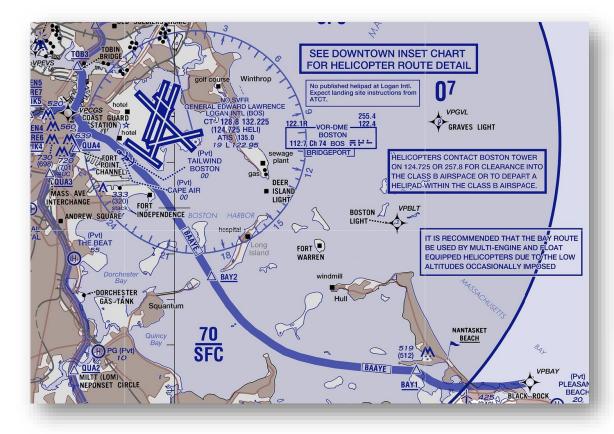
- Track intent determined based on aerodrome bounding polygons and notional approach and departure corridors
- To be classified as taking off or landing, tracks must satisfy duration, vertical rate, and relative heading criteria while in a runway corridor
- Classification algorithm leverages general assumptions about aerodrome and runway design to enable a scalable and efficient means to classify intent
- Algorithm can be extended to consider terminal routes and other well structured navigation corridors



Runways colored in black and the approach trepezoids and traffic patterns colored in white



### **Terminal Routes: Published Guidance**



#### BOSTON TERMINAL AREA ROUTE DESCRIPTIONS AND COORDINATES

#### Bay Route (BAAYE)

Southern end of Nantasket Beach at offshore rocks, cross inlet to Worlds End, via the coastline to the west of Long Island then to the channel to the Coast Guard Station. Note: It is recommended that the Bay Route be used by multi-engine and float equipped helicopters due to the low altitudes occasionally imposed.

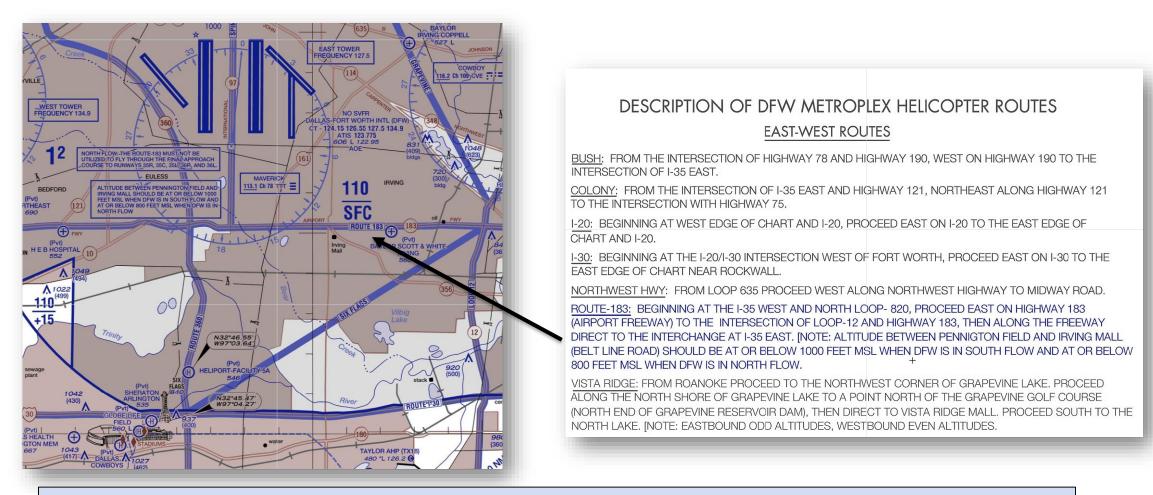
1442 10.17	W70°49.48'
N42°16.43'	W70°52.87'
N42°18.50'	W70°58.90′
N42°22.08'	W71°03.13'
	N42°16.43' N42°18.50'

#### Terminal route information can be sourced from aeronautical charts or the 28 Day National Airspace System Resource (NASR) System Subscription

Terminal Model - 10 AJW 10/13/21 https://skyvector.com/?II=42.37990830005483,-71.05046523957584&chart=205&zoom=2 https://www.faa.gov/air\_traffic/flight\_info/aeronav/Aero\_Data/NASR\_Subscription/



### **Terminal Routes: Features of Interest** Identifying Ad-Hoc Routes and Supplementing FAA Guidance



Terminal routes also based on long linear infrastructure, whose information can be sourced from general open source maps, such as OpenStreetMap or Natural Earth Data



- The Class B terminal environment consists of a wide variety of different operations
  - Large passenger transport
  - General aviation VFR
  - Local commercial / business (i.e. helicopter tours)
  - On-demand (i.e. private jets)
- The frequency of operations will vary temporally
  - General aviation primarily flies during the day
  - Air shuttle services operate hourly
- Need to characterize encounter rate given intent and time of day. Hypothesize that it is more likely for two passenger transports to encounter each other at 23:00 local than a passenger transport and general aviation





Oct. 2021 -Feb. 2022

Spring 2022

Summer - Fall

2022

- In addition to the existing approach and departure corridors, define terminal routes based on published guidance and features of interest
- Using existing training data, characterize the frequency that each route is utilized and the potential operation frequency within each route
- Update model structure to include additional intents, such as "VFR route"
- Update model structure to include time of day and evaluate if inclusion sufficiently influences the observed distributions
- Train independent models for different Class B airspaces and determine if location
  - should be a model dependency
- Prototype encounters with 3 or more aircraft by potentially updating model structure or sampling trajectories based on route frequency
  - Investigate support for vertiports and heliports
- Release updated model and determine if additional model iteration required

Terminal Model - 13 AJW 10/13/21

Focus of initial funded tasking from October 2021 – February 2022





### **Questions?**

Feedback?

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### Boston Downtown Helicopter Insert Scale 1:50,000

