

Landau Modeling of Dynamical Nucleation of Martensite at Grain Boundaries under Local Stress

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Abstract

The dynamical nucleation of martensite in polycrystals is simulated by means of Lagrange-Rayleigh dynamics with Landau energetics, which is capable of obtaining the local stress as a result of the interplay of the potential of transformation and external loadings. By monitoring the spatio-temporal distribution of the strain in response to the local stress, we demonstrate that the postcursors, high angle grain boundaries and triple junctions act as favorable heterogeneous nucleation sites corresponding to different loading and cooling conditions, and predict the phase diagram of the nucleation mode of martensite.

Key word: ferroelastic martensite; martensitic transformation; Landau model; polycrystals; phase diagram of nucleation sites;

1. Introduction

A preference for heterogeneous nucleation in Martensitic Transformations (MT) has been evidenced by a wide body of experimental explorations on steels [1-3], shape-memory alloys [4-6], ceramics [7-8], etc. The heterogeneous processes of nucleation and subsequent growth at various defects present distinct microstructure [9-10], diverse transformation pathways [11-12], and hence give rise to different properties of materials [13-14]. To understand the mechanisms underlying the observed phenomena, different models of martensitic nucleation have been developed for different defects like dislocations [15-21] and grain boundaries [22-31] in perspectives of thermodynamics, kinetics and crystal lattice dynamics. These models are at least

1 classified into two categories considering the classical and non-classical nucleation
2 paths [32-33]. The models describing classical nucleation paths believe that the
3 embryos of martensites are formed via the dislocation dissociation mechanism and
4 thereafter increase in size by motions of interfaces. During these processes, the nuclei
5 have a fixed structure and/or the same composition as those of fully formed martensite
6 variants. This is the case such that the driving force and kinetics of martensitic
7 nucleation can be discerned by evaluating the time evolution of individual energy
8 contributions from misfit elastic energy, chemical energy in bulk
9 (composition-dependent lattice stability) and surface energy. Pioneered by Cohen [15],
10 Kaufman [16], Christian [17], and consolidated by Olson [18, 32-35] *et al.*, the model
11 for classical paths has been developed into a self-consistent and unified interpretation
12 to heterogeneous martensitic nucleation on a basis of dislocation theories,
13 thermodynamics and crystallography of martensitic transformation, and it has been
14 widely applied to the martensite nucleation in steels and a few shape memory alloys,
15 where the dislocation plays the primary role.

16 In contrast, the models for non-classical martensitic nucleation paths describe a
17 continuous change in structure and/or composition in a finite temperature region.
18 Among the most prominent is the dynamical nucleation model [36], where the
19 Landau-type free energy, incorporating physical nonlinearity describing the symmetry
20 breaking in MT and nonlocal terms accounting for the long-range interactions of elastic
21 oscillators, is formulated in a frame of Lagrangian-Rayleigh (LR) or Bales-Gooding
22 (BG) [37-38] dynamics to present a physics scenario of ‘elastic solitary wave’ for
23 martensitic nucleation [37-45]. Different from the classical models, the dynamical
24 nucleation method is able to investigate the complete process of martensitic interface
25 motion and interpret the phenomena at early stage of MT such as the formation of
26 tweeds, dynamical twinning, autocatalysis, etc. Thus, it is helpful and has persistently
27 been used in studying the homogeneous coherent nucleation of improper and weak
28 proper MTs in shape memory alloys, which arise from lattice softening and/or weak
29 distortion near the critical point. Meanwhile, further uses of the model towards
30 studying heterogeneous nucleation in weak proper MT have been performed. The

1 fundamental physical picture of heterogeneous dynamical nucleation model is depicted
2 as follows: The interaction of the defects with the material allows a spatiotemporally
3 varying potential of phase transformation and gives rise to local stress field in the
4 correct tensor expression and magnitude to exert influence on MT [46]. Clapp *et al.* [39]
5 incorporated for the first time the Ginzburg-Landau (GL) phenomenological theory to
6 determine the ‘spinodal’ strains during martensite nucleation by introducing the
7 interaction of a single ‘misfit’ planar defect with the host. They denominated this type
8 of nucleation as ‘localized soft mode’. Later, the initial concept of heterogeneous
9 dynamical nucleation was further consolidated with the efforts of Cao [40-41], Reid
10 [36, 43-45], Chu [47], van Zyl [48-49] and Gröger [50] *et al.* Based on the dynamical
11 twinning [37], Reid *et al.* [43] extensively analyzed the dynamical nucleation with a
12 predefined local strain field (as an analog of heterogeneous nucleus) along with
13 generalized boundary conditions. Their results demonstrated that the variation of
14 morphology in MT, e.g. the presence of twin or single-domain martensite, depends on
15 the quenching temperature and dissipation, while it is independent of the boundary
16 conditions. Afterwards, van Zyl [48-49] *et al.* inferred that the surface nucleation, a
17 mode by which the intrinsic inhomogeneous strain field coupled with the boundaries
18 leads to a lower saddle point on the transformation energy surface, would always be
19 preferred over homogeneous bulk nucleation. Cao [40-41] introduced a planar defect
20 with a predefined stress field (instead of aforementioned predefined strain field) and
21 ascertained the critical stresses and the effective temperature for the onset of MT in the
22 square-to-rectangular ferroelastic materials. A similar formalism of heterogeneous
23 nucleation was also presented by Gooding *et al.* [42], yet the latter focused on the
24 concentration of the local strain at the defect arising from undercooling. It was further
25 applied by Reid *et al.* [45] to the Eshelby’s inclusion problem where the functional
26 forms or the values of the local stress field due to the presence of the inclusion become
27 available.

28 Other than the aforementioned works which focus on the MT induced by the single
29 planar defect with a predefined stress or strain, few works of heterogeneous dynamical
30 nucleation have been applied to grain boundary with more complicated geometry of

1 defects. It is in comparison with the great achievements of modern phase-field methods
2 on this topic [22-31]. The phase-field models have advantages to represent the perfect
3 martensitic microstructure by taking a mutually advantageous conjunction of interface
4 motion and clarified energy contributions in models for classical paths and the
5 continuously varying order parameters in models for non-classical paths, which as a
6 whole describe a hybrid transformation path. However, the over-damped dynamics in
7 phase field method encounters difficulties in accounting for the correct dynamic
8 behaviors for the formation of precursors [51] and the near sound velocity of interface
9 propagation in weak proper MT [38]. This is due to the fact that these behaviors are the
10 consequence of competition among inertia, damping and undercooling, as well as the
11 minimization of kinetic energy [38]. The interplaying of these effects in a strained
12 system undergoing weak first-order MT reflects the under-damped dynamics of elastic
13 oscillators [36]. Therefore, the development of the complete dynamical nucleation
14 model in polycrystals remains open. Recently, Ahluwalia *et al.* [52] extended strain
15 based Landau energetics and LR dynamics to investigate the grain size effects on the
16 MT in nano-polycrystalline shape memory alloys, especially when the MT is inhibited
17 around grain boundaries in nano-polycrystals. However, the phenomenon where the
18 alignment of martensite variants rotate at certain angles with respect to the grain
19 orientations in individual grains, generally observed by microscopy, is unnoticeable in
20 their simulated morphology. This is because they adopted global stresses in the
21 dissipative force balance equation which led to the mechanical equilibrium of global
22 stresses rather than local transformation stresses. Therefore, we modified the existing
23 polycrystalline MT model by replacing the global stresses with local transformation
24 stresses and then rewrote them in global variables, i.e. displacement gradients in global
25 coordinates [53]. The updated model is not only consistent with kinematic
26 compatibility in Phenomenological Theory of Martensite Crystallography (PTMC), but
27 also has the ability to explicitly explore the spatiotemporal distribution of local stress
28 during the MT. It also allows us to generalize the conceptual dynamical nucleation
29 theory within our updated model to simulate the heterogeneous martensitic nucleation
30 in polycrystals. The present simulations aim at extending the application of dynamical

1 nucleation model and at gaining an in-depth understanding of the collective
2 (competitive and/or cooperative) effects of the martensitic nucleation and subsequent
3 growth assisted by grain boundaries and external loadings following the non-classical
4 transformation paths. In turn, it allows evaluating the ability of different
5 defects/positions as martensitic nucleation sites originating from the interaction of
6 intrinsic polycrystalline defects with the applied loading in a weak proper MT.

7 **2. Model and Numerical Implementation**

8 The dynamical nucleation of MT induced by grain boundary in polycrystals can
9 be achieved once the predefined planar defects in Refs. [40-42] are specified as the
10 grain boundaries and triple junctions. The grain boundaries and triple junctions can
11 perceive the applied stress and feel back to couple with Landau transformation
12 potential, which leads to a local stress field and modifies the transformation
13 temperature. Similar to Cao's work on single crystal [40], we assume that 1) the
14 inhomogeneous distribution of stress is produced by defects, specifically in this work,
15 the local stress fields around the grain boundaries and triple junctions, rather than the
16 defects themselves; 2) the interface between austenite and martensite is coherent which
17 is imposed by the compatibility condition; 3) the displacement at grain boundaries is
18 continuous as required by the displacement-based LR dynamics [38]. It is inferred that
19 martensitic nucleation against free surfaces and incoherent grain boundaries is not
20 taken into consideration. It is also noted that we are not intending to obtain various
21 morphologies by tuning the damping parameters as what conventional dynamical
22 nucleation modeling did, rather, we focus on how intrinsic MT potential involving
23 grain boundaries and applied stresses leads to different nucleation modes or sites.

24 There are two critical issues to be addressed in our Landau modeling of the
25 dynamical nucleation in polycrystals: the Landau free energy in the expansion of order
26 parameters and the deterministic dynamic equations. In the single crystal model,
27 non-linear Landau free energy is developed based on the linearized strain tensor with
28 the component $e_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$, where u_i denotes the local displacement, and

1 $u_{i,j} = \partial u_i / \partial x_j$ is the displacement gradient in the intragranular coordinates. The
2 symmetry-adapted linear strains e_k , written as the linear combination of the strain
3 components, are selected as the Order Parameters (OP). Now we consider a MT in
4 polycrystals. The degrees of freedom in a system undergoing MT are the global
5 displacements, U_i , and they should be connected with the OP strains by introducing an
6 additional variable $\theta(\bar{\mathbf{r}}, t)$ describing the grain orientation field. As such, the local
7 strains and symmetry-adapted OP strains are the functional of the global displacement
8 gradients, viz. $e_{ij}(U_{I,J})$ and $e_k(U_{I,J})$. For the sake of clarity, the variables in global
9 coordinates are denoted by capital letters while those in local coordinates by lowercase.
10 The specific expressions of free energy and dynamic equations for the simulation of
11 2D square-to-rectangular martensitic nucleation are detailed as follows.

12 **2.1. Landau free energy**

13 The free energy functional of the system is written as the spatial integral of free
14 energy density f ,

$$15 \quad F = \int f d\bar{\mathbf{r}} = \int d\bar{\mathbf{r}} (f_{elastic} + f_{grain} + f_{load}), \quad \dots\dots(1)$$

16 while f is intuitively defined as the summation of three energy density contributions:
17 the transformation energy density in elasticity $f_{elastic}$, the energy of a polycrystalline
18 microstructure f_{grain} , and the energy due to the applied load f_{load} .

19 In our model, the grain orientation field of polycrystals is described by the
20 conventional phase field method. It defines the spatially distributed grain orientation
21 $\theta[\vec{\eta}_i(\mathbf{r}, t)]$ with respect to a set of arbitrarily selected intragranular coordinates which
22 should serve as the referential global coordinates. The grain orientation field is
23 expressed as

$$\theta(\vec{\eta}, \vec{r}) = \frac{\theta_{\max}}{Q-1} \left[\frac{\sum_{i=1}^Q (i-1) \eta_i(\vec{r}, t)}{\sum_{i=1}^Q \eta_i(\vec{r}, t)} \right], \quad \dots\dots(2)$$

where, $\vec{\eta}(\eta_1, \eta_2, \dots, \eta_Q)$ is a vectorial indicator, by which a given grain orientation corresponds to one component η_i being positive nonzero while the remaining components are equal to zero [52]. The energy contribution f_{grain} quantifies the spatial inhomogeneity in crystal orientation and can be written as

$$f_{\text{grain}} = \varpi \left\{ \sum_{i=1}^Q \left[\frac{a_2}{2} \eta_i^2 + \frac{a_3}{3} \eta_i^3 + \frac{a_4}{4} \eta_i^4 \right] + \frac{a_c}{2} \sum_{i=1}^Q \sum_{j \neq i}^Q \eta_i^2 \eta_j^2 + \sum_{i=1}^Q \frac{\kappa_{\text{grain}}}{2} (\nabla \eta_i)^2 \right\}, \quad \dots\dots(3)$$

where, the coefficients are $a_2, a_3 < 0$ and $a_4, a_c > 0$ to ensure a potential with Q degenerate minima, $(\eta_1, 0, \dots, 0)$, $(0, \eta_2, \dots, 0)$, etc. up to $(0, 0, \dots, \eta_Q)$ ($\eta_i > 0$), ϖ is an adjustable parameter to mediate the magnitude of grain boundary energy density. It's worth noting that the polycrystalline structure in our model is simply described by the spatial distribution of different grain orientations, thus the internal stress at grain boundaries are absent in comparison with the real polycrystals.

The elastic transformation energy density f_{elastic} can be further divided into three parts, i.e., local transformation energy density f_{local} , energetic contribution originating from non-OP strains $f_{\text{non-OPs}}$, and gradients of OP strains f_{grad} . The first term f_{local} describes the two degenerated martensite variants due to the symmetry breaking in square-to-rectangular MT, and is expressed in the polynomial expansion of the symmetry-adapted deviatoric strain, e_2 , up to sixth order,

$$f_{\text{local}} = \frac{A_{20}}{2} \left(\frac{T - T_c}{T_m - T_c} \right) e_2^2 + \frac{A_4}{4} e_2^4 + \frac{A_6}{4} e_2^6, \quad \dots\dots(4)$$

where, $A_2 = A_{20} \left(\frac{T - T_c}{T_m - T_c} \right)$ is temperature dependent deviatoric modulus expressed in linear combination of the elastic constants as $A_2 = c_{11}(T) - c_{12}(T)$. A_4 and A_6 are related to higher order nonlinear elastic constants. T_c and T_m are critical point and MT

1 starting temperature, respectively. The OP strain $e_2 = (e_{xx} - e_{yy})/\sqrt{2}$ has to be
 2 rewritten as the derivation of the global displacements in global coordinates, i.e.

$$3 \quad e_2 = [u_{x,x}(U, \theta) - u_{y,y}(U, \theta)]/\sqrt{2} \quad , \quad \dots\dots(5.1)$$

$$4 \quad = [\cos 2\theta(U_{X,X} - U_{Y,Y}) + \sin 2\theta(U_{X,Y} + U_{Y,X})]/\sqrt{2} \quad , \quad \dots\dots(5.2)$$

5 where, θ is the angle of grain orientation, see Eq.(2). There are two non-OPs, i.e.

6 dilatational strain $e_1 = (e_{xx} + e_{yy})/\sqrt{2} = (U_{X,X} + U_{Y,Y})/\sqrt{2}$ and the shear strain

7 $e_3 = (e_{xy} + e_{yx})/2 = -\frac{\sin(2\theta)}{2}(U_{X,X} - U_{Y,Y}) + \frac{\cos(2\theta)}{2}(U_{X,Y} + U_{Y,X})$ to construct the

8 $f_{non-OPs}$ in square-to-rectangular MT as:

$$9 \quad f_{non-OPs} = \frac{A_1}{2}e_1^2 + \frac{A_3}{2}e_3^2 \quad , \quad \dots\dots(6)$$

10 where, $A_1 = c_{11} + c_{12}$ is the bulk modulus in 2D, $A_3 = 4c_{44}$ is the shear modulus in the

11 isotropic approximation. The gradient energy density f_{grad} is the square of the OP strain

12 gradient, i.e.

$$13 \quad f_{grad} = g(\nabla e_2)^2 \quad , \quad \dots\dots(7)$$

14 and g is the gradient coefficient.

15 Since we are interested in a simple uniaxial stress in this work, the free energy

16 contribution due to the applied stress σ_{app} yields

$$17 \quad f_{app} = -\sigma_{app}e_{xx} \quad , \quad \dots\dots(8)$$

18 Thus, the free energy is finally expressed in global coordinates as

$$19 \quad F = \int d\vec{r} \left[\frac{A_1}{2}e_1^2(\vec{r}, \theta) + \frac{A_2}{2}\left(\frac{T-T_c}{T_m-T_c}\right)e_2^2(\vec{r}, \theta) + \frac{A_4}{4}e_2^4(\vec{r}, \theta) + \frac{A_6}{6}e_2^6(\vec{r}, \theta) + \frac{A_3}{2}e_3^2(\vec{r}, \theta) \right. \\ \left. + g(\nabla e_2(\vec{r}, \theta))^2 + f_{grains}(\theta) - \sigma_{app}e_{xx}(\vec{r}, \theta) \right] \quad \dots\dots(9)$$

20 **2.2. Dynamic equations**

21 The evolution of grain orientation and displacement fields are treated differently

22 in this work. The time dependent Ginzburg-Landau equation

$$23 \quad \frac{\partial \vec{\eta}(\vec{r}, t)}{\partial t} = -L_\eta \frac{\delta f_{grain}}{\delta \vec{\eta}(\vec{r}, t)} \quad \dots\dots(10)$$

1 is used to describe the evolution of the order parameter field $\vec{\eta}(\vec{r}, t)$ of the grain
 2 orientations with L_η as kinetic coefficient for interface mobility.

3 When the spatiotemporal evolution of displacement and strain fields is considered,
 4 a variation method of Lagrange mechanics is utilized. We incorporate the kinetic
 5 energy density $T = \rho \dot{\mathbf{U}}^2 / 2$ and the free energy density f to construct the Lagrangian
 6 $\mathcal{L} = \int_V d\mathbf{r} \{T - f\}$. By taking the variation of the Lagrangian with respect to the
 7 displacement \mathbf{U} and velocity $\dot{\mathbf{U}}$ and explicitly substituting the Lagrangian into the
 8 Lagrange-Rayleigh equations $\frac{d}{dt} \frac{\delta \mathcal{L}}{\delta \dot{U}_i} - \frac{\delta \mathcal{L}}{\delta U_i} = -\frac{\delta \mathcal{R}}{\delta \dot{U}_i}$, the Lagrange-Rayleigh equations
 9 yield the general equations of motion

$$10 \quad \rho \ddot{U}_i = \frac{\partial}{\partial X_j} \left\{ \frac{\partial f}{\partial e_k} \frac{\partial e_k}{\partial e_{pq}} \frac{\partial e_{pq}}{\partial U_{i,j}} - \nabla \cdot \frac{\partial f}{\partial \nabla e_k} \frac{\partial \nabla e_k}{\partial e_{pq}} \frac{\partial e_{pq}}{\partial U_{i,j}} + \frac{\partial R}{\partial \dot{e}_k} \frac{\partial \dot{e}_k}{\partial \dot{e}_{pq}} \frac{\partial \dot{e}_{pq}}{\partial \dot{U}_{i,j}} \right\}, \quad \dots\dots(11)$$

11 where, ρ is density; \mathcal{R} and R are Rayleigh dissipation and dissipation density, written
 12 as the functional of strain rates to describe the friction in the system. If the isotropic
 13 approximation is adopted for the Rayleigh dissipation density with viscosity γ , and the
 14 local stress expressed in global coordinates is defined as

$$15 \quad \sigma_{ij} = \frac{\delta F}{\delta U_{i,j}} = \frac{\partial f}{\partial e_k} \frac{\partial e_k}{\partial e_{pq}} \frac{\partial e_{pq}}{\partial U_{i,j}} - \nabla \cdot \frac{\partial f}{\partial \nabla e_k} \frac{\partial \nabla e_k}{\partial e_{pq}} \frac{\partial e_{pq}}{\partial U_{i,j}}, \quad \dots\dots(12)$$

16 the dynamics of displacement fields is given by dissipative force balance equations

$$17 \quad \rho \ddot{U}_i = \frac{\partial \sigma_{ij}}{\partial X_j} + \gamma \nabla^2 \dot{U}_i, \quad \dots\dots(13)$$

18 Differing from Ref [52], the local stresses in our model enter dissipative force balanced
 19 equations via the chain rule of functional differentiation of free energy with respect to
 20 global displacement gradients. By numerical solving Eqs. (10), (12) and (13), the
 21 spatiotemporal evolution of displacements, strains and grain orientations are obtained.
 22 Finally, the viscous term drives the system to the mechanical equilibrium state.

23 **2.3. Numerical Implementation**

24 Our simulations were carried out using a Fast Fourier Transform (FFT)-based
 25 spectral method under periodic boundary conditions in a 256×256 grid with 5 grain

1 orientations of 0° , 7.5° , 15° , 22.5° and 30° ($=\theta_{max}$), respectively (Fig. 1-a). For the
2 formation of the polycrystalline structure, we used the parameters, $a_2=-1$, $a_3=-1$, $a_4=1$,
3 and $a_c=2$. k_{grain} was adjustable to produce appropriate configuration. Since we took a
4 Fe-Pd ferroelastic alloy as an example in our simulation, the following materials
5 parameters were chosen based on the experimental results of elastic constants: $A_1 =$
6 333.91 GPa, $A_{20} = 11.5$ GPa, $A_3 = 282$ GPa, $A_4 = -1.7 \cdot 10^3$ GPa, $T_m = 295$ K and T_c
7 $= 270$ K [50,54-55]. Note that the temperature dependence of the elastic constant A_2 in
8 experiments and linear fitting was well represented by the parameter $A_2 = A_{20} \frac{T - T_c}{T_m - T_c}$,
9 while the other elastic parameters are constant with temperature for simplicity. A_6 was
10 determined from A_{20} , A_4 , and quenching temperature T , satisfying the constraints of
11 Landau polynomial for first-order transformation [56]. The value of the gradient
12 coefficient was set to $g=3.0 \cdot 10^{-8}$ N [52,57] based on microstructural observations,
13 while the dissipation coefficient was estimated as 0.015 N s/m² [57]. Based on these
14 parameters, the interface energy density of full twinned martensites can be estimated
15 around 0.5 J/m² from multi-wells degenerated Landau free energy near the critical
16 point*.

17 **If the viscous term is removed, the conservation equation of motion utilized in our simulation describes a
physical picture in which the decrease of local free energy in Landau potential triggers the formation of the
habit planes and/or twin boundaries during the martensitic nucleation and drives the interface propagation
during martensite growth. In fact, the existence of a viscous term minimizes the finite kinetic energy density.*

18 The interface energy density in our simulation (in Subsection 3.1) has the correct order
19 of magnitude, consistent with theoretical estimations and first principles calculations
20 [58-59]. To tackle the numerical instability, both the materials and the simulation
21 parameters were subjected to a normalization [60], wherein the spatial and energetic
22 variables were rescaled by introducing the normalization factors $d_0=7 \cdot 10^{-9}$ m and f_0
23 $\sim 10^{10}$ J, respectively; such that $\tilde{x} = x/d_0$, and $\tilde{A}_i = A_i/f_0$. The time variable was
24 rescaled as $\tilde{t} = t/t_0 = t/\sqrt{\rho d_0^2/f_0}$ and the rescaled viscosity is $\tilde{\gamma} = \gamma/(d_0 \sqrt{f_0 \rho})$. At
25 the beginning of the simulation, the random fluctuations of displacements ζ_{u_i} obtained
26 from a Gaussian noise were introduced. The mean value and correlation of fluctuations

1 satisfy

$$2 \quad \langle \zeta_{u_i}(\mathbf{r}, t) \rangle = 0, \dots\dots(14)$$

$$3 \quad \langle \zeta_{u_i}(\mathbf{r}, t) \zeta_{u_j}(\mathbf{r}', t') \rangle = 2\gamma k_B T \rho \delta(\mathbf{r} - \mathbf{r}') \delta(t - t') \dots\dots(15)$$

4 More details of the model and of the numerical implementation can be found in Refs.
5 [53,60-61].

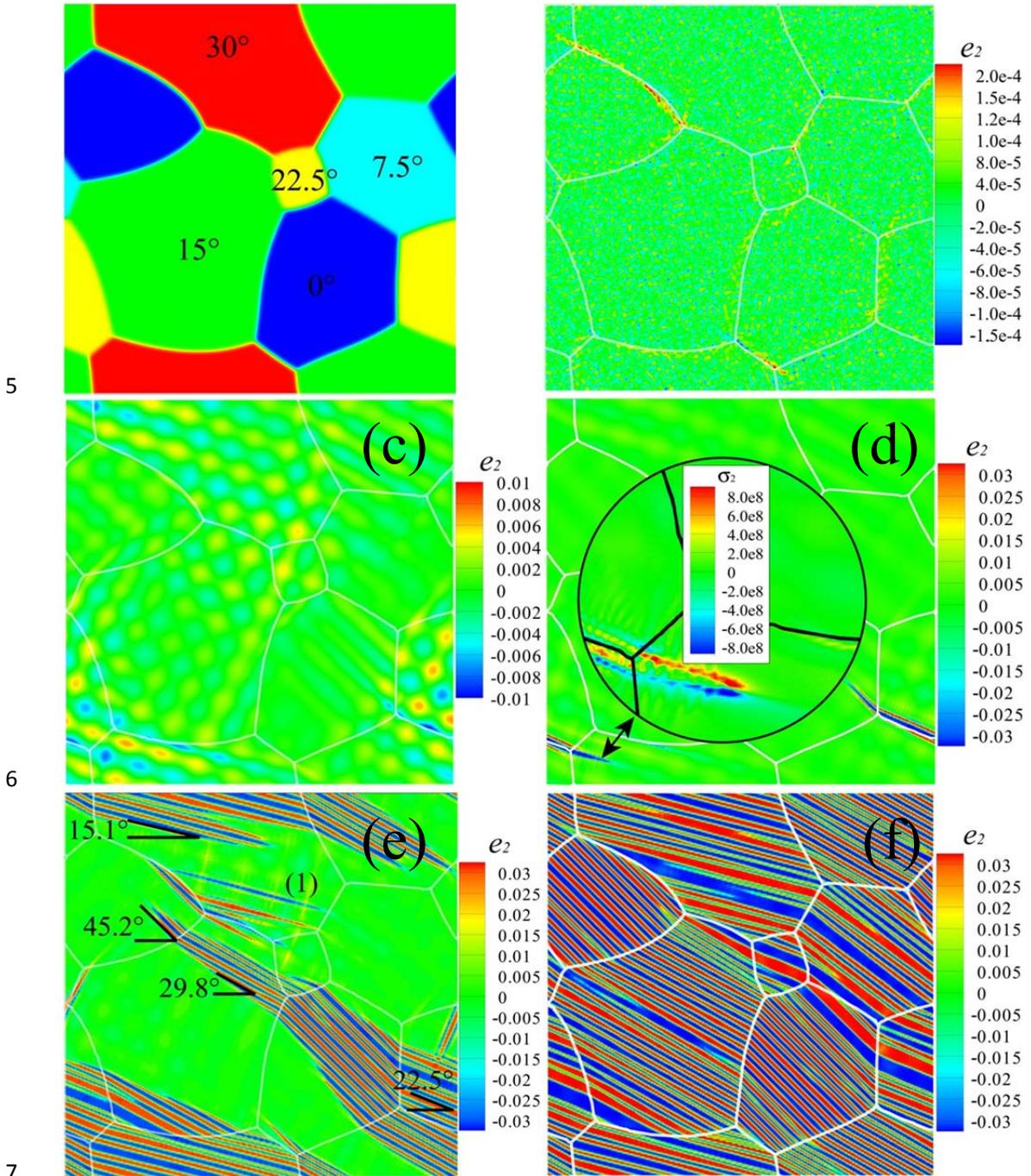
6 **3. Results and Discussion**

7 The martensitic nucleation and the relevant microstructure evolution are obtained
8 from the simulations under the conditions of (1) different applied stresses at a fixed
9 temperature, (two cases of martensitic nucleation under applied stresses of 50 MPa and
10 500 MPa are selected as the examples to be discussed in detail), (2) different
11 temperatures with a constant applied stress, and (3) the combination of varying stresses
12 and temperatures. These external processing conditions interacting with intrinsic MT
13 energy lead to different scenarios of martensitic nucleation.

15 **3.1 Heterogeneous nucleation under an applied stress of 50 MPa**

16 To examine the MT in the vicinity of grain boundaries, the system was first
17 quenched to $T = 275\text{K}$ ($T_c < T < T_m$), followed by an isothermal simulation under a
18 constant applied stress of $\sigma_{\text{app}} = 50$ MPa. The set temperature is slightly higher than T_c ,
19 which ensures the existence of an energy barrier to describe the nature of first-order
20 MT yet allows a small strain fluctuation to jump over. The sequential process of
21 nucleation and growth of martensite is shown in Fig. 1, where martensite is depicted by
22 the distribution of the deviatoric strain e_2 at different times during the isothermal
23 simulation. The displacement fluctuations give rise to local inhomogeneities of the
24 deviatoric strain at the initial stage of the isothermal simulation that trigger the onset of
25 a fine-scale assembly of cross-hatched tweeds (Fig. 1-b). Differing from single crystals
26 [62], the tweeds exhibit different stretch directions in individual grains. Note that
27 tweeds similar to those in Fig. 1-b can also develop above T_m in the absence of applied
28 stresses. The local distortion of deviatoric strain caused by the local stress field is

1 hence accumulated at the grain boundaries with larger misorientation, as those between
 2 blue and red grains in Fig.1-b, indicating that the free energy minima have been
 3 momentarily shifted toward the grain boundaries due to the synergistic contribution of
 4 the grain boundary energy and the strain gradients.



9 Figure 1. (a) Spatial distribution of the grain orientation angle as indicated in each grain (b)-(f) Martensitic
 10 nucleation and growth in polycrystals, as shown by the deviatoric strain e_2 at 275K under an applied stress $\sigma_{app}=$
 11 50MPa, at time steps of 800, 12000, 92000, 94800 and 104000, respectively. The red and blue domains represent
 12 two martensite variants while the green domain is austenite. The grain boundaries are displayed in white.

1 For $\sigma_{\text{app}} = 50$ MPa, no concentration of deviatoric strain is found in the vicinity of
 2 triple junctions because the strain gradients stemming from individual grain boundaries
 3 cancel each other and lead to a relatively more homogenous strain field at the triple
 4 junction. The fine tweeds inside the grains and deviatoric strain distortion at grain
 5 boundaries are fading away with time, and the system responds to the local stress field
 6 with a metastable microstructure exhibiting a long-range straining pattern (Fig. 1-c),
 7 denominated ‘postcursor’ [63]. The postcursors, modulated partially transformed
 8 martensites, show the same texturing pattern as what the subsequent twins would have.
 9 They arise from a balance between the nonlinearity of transformation energy
 10 represented by the anharmonic terms in Eq. (4) and nonlocality stemming from the
 11 contribution of strain gradients. This modulated metastable equilibrium will be broken
 12 when the reduction of local energy due to the stress released in martensite domains
 13 cannot be compensated by the increase of energy originating from the steeper strain
 14 gradient with respect to the spatial coordinates, and the total energy is progressively
 15 reduced to the stable energetic wells of martensite [63]. Therefore, the postcursors can
 16 play the role of potential embryo of martensite inside the grains, as shown by the
 17 martensite plate marked (1) in Fig.1-e, which grows from an intragranular postcursor.
 18 Simultaneously, the strain distortion at the grain boundary can assist nucleation. If the
 19 grain boundary is parallel to one of the postcursors, the first stable martensite plate will
 20 form preferentially along the grain boundary, as shown in Fig.1-d. As soon as the first
 21 stable martensite plate forms (see the blue variant and the local deviatoric stress
 22 $\sigma_2(\vec{r}) = (\sigma_{xx}(\vec{r}) - \sigma_{yy}(\vec{r}))/\sqrt{2}$ in inset of Fig 1-d), it grows rapidly in length
 23 following the tracks of postcursors due to the large local stress and the curvature at the
 24 tip. When the growing front of the martensite plates crosses the triple junction, the
 25 martensite plate penetrates into the grain and is aligned with the favored orientation.
 26 However, the coarsening of the blue variant in the direction perpendicular to the habit
 27 plane is momentarily arrested by the modified local energy around the plate, and gives
 28 rise to a cascade of pairing red variants, i.e. autocatalysis phenomenon. It should be
 29 noted that branched martensite plates are hardly found due to the limitations of the 2D

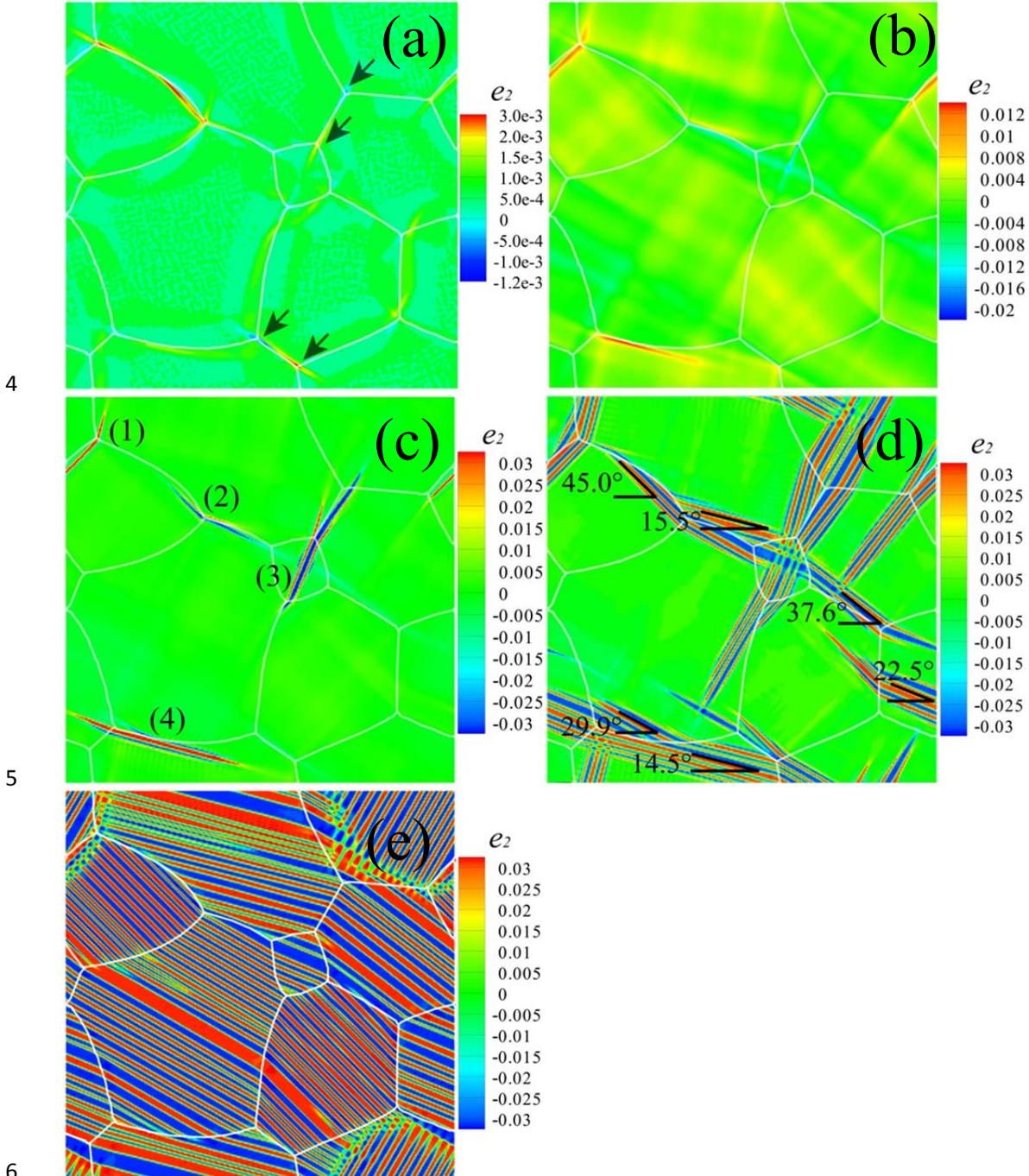
1 model that allows only two different twin-related variants. The branched martensite
2 plates are only found when the grain boundary is located between the orientations of
3 the postcursors in the neighboring grains (see inset in Fig. 3-b). This is different to the
4 richer accommodated patterns consisting of all 24 Kurdjumov–Sachs orientation
5 variants widely observed in the experiments for other Fe-C based alloys [64]. Figure
6 1-f illustrates the morphology of full martensite after long-time simulation. The
7 alternative alignments of twinned red and blue martensites are in agreement with the
8 kink solution of the solitary wave in Ref. [42]. The width and energy density of the
9 twin boundary shown in Fig. 1-f correspond to about 2-3 nm and 0.45J/m^2 , respectively.
10 Although the simulated twin boundary energy density agrees well with that of
11 stationary analysis, the width of the twin boundary in the simulation is three times
12 broader than the several atomic diameters observed from TEM image. It is an inherent
13 consequence of the diffuse interfaces utilized in Landau modeling. In this work, the
14 gradient coefficient was selected by considering a compromise between the twin
15 boundary width and the size of the grains.

16 ***3.2 Heterogeneous nucleation under an applied stress of 500 MPa***

17 The evolution of microstructure under $\sigma_{\text{app}} = 500\text{ MPa}$ shows similar features (Fig.
18 2-a) at the early stages of the simulation as those for 50 MPa: the tweed pattern
19 develops within the grains and the strain distortions appear at grain boundaries, but
20 both occur more rapidly because of the higher stresses. The accumulation of the
21 deviatoric strain raised by the local stress is supposed to smear out or weaken the effect
22 of postcursors. At the same time, the interplaying of elastic transformation energy and
23 lattice curvature drives the ‘twinned’ strain distortion to split into ‘diploes’ (indicated
24 by the arrows in Fig. 2-a) and to be concentrated at the triple junctions and high angle
25 grain boundaries, both of which serve as the preferential sites for martensitic
26 nucleation and growth, as shown in Fig. 2-b. Three martensite plates (marked (1), (2)
27 and (3) in Fig. 2-c) are nucleated at the triple junctions, and grow into the twins aligned
28 with their optimum martensite orientations in individual grains. For instance, the pairs
29 of needle-like martensites in the grains with the orientation $\theta = 22.5^\circ$ (i.e. the grains in

1 yellow in Fig. 1-a) align along the 67.5° with respect to the horizontal axis of global
 2 reference.

3



7 Figure 2. Martensitic nucleation and growth in polycrystals, as shown by the deviatoric strain e_2 at 275K under an
 8 applied stress $\sigma_{app}=500\text{MPa}$ at time steps of 800 (a), 5200 (b), 6400 (c), 8000 (d), and 28000 (e), respectively. The
 9 red and blue domains represent two martensite variants while the green domain is austenite. The grain boundaries
 10 are displayed in white.

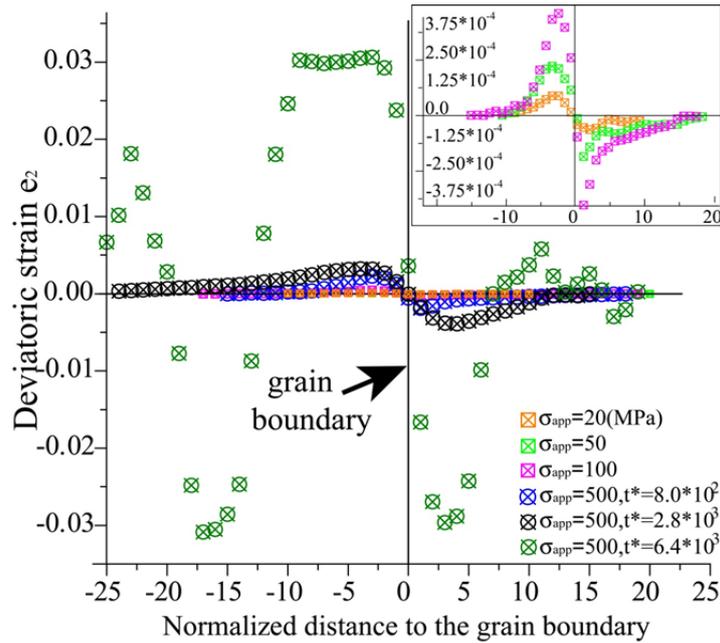
11 A different scenario is found in the twinned martensite plates marked (4) in Fig. 2-c.
 12 They nucleate and grow assisted by the high angle grain boundaries, and the leading

1 plate in red propagates beyond the neighbor triple junction without apparently
2 changing orientation. However, it accommodates itself later to match the surrounding
3 grain misorientation by subtly rotating the residing twin boundary to form the full
4 martensitic morphology (Fig.2-e).

5 ***3.3 The effect of applied stress on heterogeneous nucleation at grain boundaries***

6 In Fig.3, the deviatoric strain as a function of the distance to a high angle grain
7 boundary is plotted for different applied stresses and times at $T = 275$ K. Although the
8 high angle grain boundaries can be intuitively considered analogous to 2D planar
9 defects in Refs [41-42], we must clarify that our modeling has its roots in the
10 dynamical nucleation developed by Clapp [65], Cao [40-41], and Gooding [42], *et al.*
11 The hyperbolic-type profiles of the deviatoric strain are consistent with the analytical
12 results of Cao [41] who introduced a predefined stress field as a martensite embryo for
13 twin. The deviatoric strains raised by the small local stresses rapidly accumulate within
14 the first hundreds of steps (see inset of Fig. 3 with $\sigma_{app} = 20-100$ MPa). However, they
15 are one to two orders of magnitude smaller than the threshold of ‘spinodal strain’ to
16 serve as steady martensite embryos to form stable martensite variants. The strain
17 profile at $\sigma_{app} = 500$ MPa and at time step of 6400 (in the direction perpendicular to the
18 twin plane 4# in Fig. 2-c) exhibits the oscillation between the positive/negative
19 deviatoric strains of two rectangular martensite variants, demonstrating that the local
20 stress has driven the martensitic nuclei into stable plates. Beyond the analytical
21 solution, our results prove that the spatiotemporal evolution is greatly dependent on the
22 strain gradient. In contrast to the predefined stress solution [41], the asymmetry of the
23 profile with $\sigma_{app} = 500$ MPa and at time step of 2800 indicates that the strain distortion
24 is influenced by a curvature driving modulation (through either strain gradients or
25 displacement gradients) and then is concentrated at the triple junctions. As a result,
26 more martensites nucleate at the triple junctions under $\sigma_{app} = 500$ MPa (see martensites
27 1#-3# in Fig. 2-c) than at high angle grain boundaries. All the above findings reveal
28 that intragranular nucleation around grain boundaries prevails over other nucleation
29 modes under small applied stress, whereas nucleation at triple junctions and high angle

1 grain boundaries is the dominant mode under moderate applied stress. These results
 2 support the argument of Clapp [39], who states that high angle grain boundaries are the
 3 favored nucleation sites if the free surface and incoherent grain boundaries are absent.
 4 It should be further emphasized that the triple junctions are more suitable nucleation
 5 sites than high angle grain boundaries in the case of the relative large local stresses.
 6

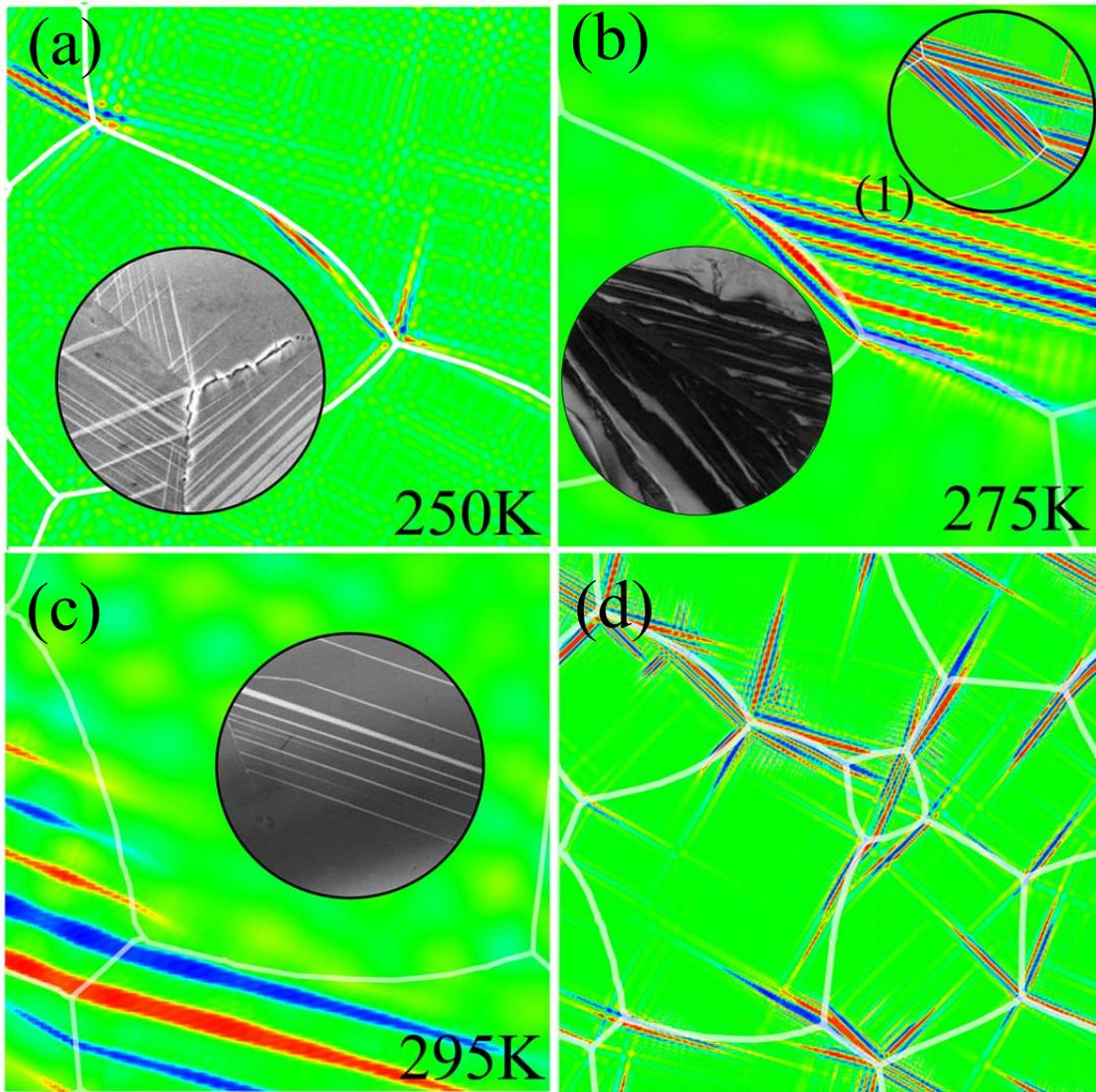


7
 8 Figure 3. Evolution of the deviatoric strain e_2 as a function of the distance to a high angle grain boundaries at the
 9 time step of 800 under different applied stresses $\sigma_{app}=20, 50, 100$ and 500 MPa, respectively, and at later times of
 10 2800 and 6400 steps with $\sigma_{app}=500$ MPa .

11 **3.4 The effect of quenching temperatures on heterogeneous nucleation at grain** 12 **boundaries**

13 The effect of quenching temperatures on the Landau energy landscape and the
 14 transformation pathways is addressed in Fig. 4, which illustrates the morphology of the
 15 principal martensitic plates at different temperatures under $\sigma_{app}=100$ MPa. When
 16 quenching the system to a low temperature $T = 250K < T_c$, the martensite plates prefer
 17 to form and grow at the triple junctions prior to the boost of homogenous
 18 decomposition inside grains. Quenching to $T_c < T = 275 K < T_m$, in contrast, leads to a
 19 diversity of martensitic nucleation sites depending on the localized geometric,
 20 energetic and dynamic conditions, when the stress fields localized at the postcursors,

1 grain boundary and triple junctions are comparable in magnitude. The groups of
2 stripe-like martensites (marked (1) in Fig. 4-b) nucleate to grow intragranularly
3 following the tracks of postcursors. On the contrary, the red variant nucleates at the
4 high angle grain boundary, proceeds along the prestrained postcursors after crossing



5

6

7 Figure 4. Morphology of the initial stabilized martensitic plates in polycrystals undergoing isothermal
8 transformation after quenching to 250K(a), 275K(b) and 295K(c) and continuous cooling at the rate of 0.01K/step
9 from 300K to 100K(d), as shown by the deviatoric strain e_2 under an applied stress $\sigma_{app}=100$ MPa

10 the grain boundary, but leaves with a kink; while the blue martensite plate nucleated at
11 the triple junction and accommodates itself to match the optimal orientations in the
12 neighboring grains. The later morphology at the very high angle grain boundary (see

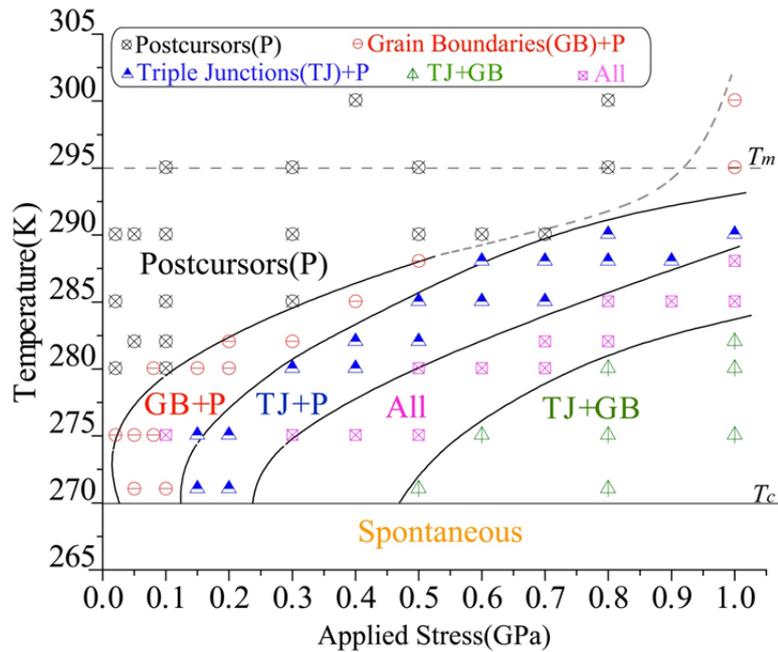
1 the top-right inset in Fig. 4-b) is consistent with the coarse lenticular martensites
2 observed in Fe-based materials [64]. On quenching to $T = T_m = 295\text{K}$, the morphology
3 exhibits a heterogeneous structure containing austenite-martensite alternated stripes in
4 the grains (Fig. 4-c). This process takes place via the nucleation and growth relying on
5 the preexisting postcursors with a morphology much like the stress-induced martensite
6 at room temperature ($>T_m$) for certain cubic-to-monoclinic II shape memory alloys [66].
7 Note that since the symmetry breaking of cubic-to-monoclinic II MT contains the
8 elements of cubic-to-tetragonal, a specific 2D projection of the microstructure of the
9 monoclinic II martensites in a fine wire sample could sustain the lamella features in
10 tetragonal martensites [67]. The formation of a single martensite variant in equilibrium
11 with the austenite is energetically allowed at T_m , and even at higher temperature, if the
12 local stress is above a threshold. Nevertheless, it is constrained by geometrical
13 compatibility in 3D bulk materials. So far, our simulations have demonstrated that the
14 martensitic nucleation modes (sites) are sensitive to the quenching temperature. The
15 primary nucleation sites vary from triple junctions to high angle grain boundaries to
16 postcursors as the quenching temperature increases. Thus, it can be inferred that a
17 continuous cooling to a lower temperature is perfectly adequate to yield the formation
18 of stable martensite plates at the triple junctions, as proven in Fig. 4d.

19 ***3.5 Phase diagram of nucleation modes***

20 Most of the discoveries by our simulations can be summarized in the phase diagram of
21 the Fe-Pd ferroelastics presented in Fig. 5. The phase diagram looks similar to a
22 conventional TTT diagram, and conveys the information about the principally favored
23 mode of martensitic nucleation under particular combination of quenching temperature
24 and applied stress. It is still noteworthy that the nucleation and growth of martensite is
25 actually governed by the local stresses rather than by the applied stress. However, the
26 applied stresses can be easily used to control processing in an industrial environment.
27 The phase diagram manifests that nucleation at the postcursors dominates at high
28 quenching temperatures. As the quenching temperature decreases or the applied stress
29 increases, nucleation at the postcursors is replaced by four distinct mixed modes,

1 namely, grain boundary + postcursor, triple junction + postcursor, hybrid (i.e. all sorts
 2 of nucleation sites are possible) and triple junction + grain boundary. Only the
 3 postcursors can lead by themselves to the development of a nucleation site, while the
 4 grain boundaries and triple junctions have to cooperate to become viable nucleation
 5 sites, see Fig.5. It is worth pointing out that our results have been obtained assuming
 6 that the material was elastic and continuous. Thus, other aspects associated with grain
 7 boundary nucleation such as plasticity, incoherent interfaces and defect cores have not
 8 been considered. The incorporation of these issues into the simulation will be
 9 necessary to include more physics in the model and enhance the predictive capabilities
 10 of this strategy.

11



12

13 Figure 5. Phase diagram of the nucleation modes of martensite in the Fe-Pd ferroelastic polycrystals.

14

15 4. Conclusion

16 In summary, we investigate the dynamical nucleation of martensite in polycrystals
 17 by means of LR dynamics and Landau energetics. Avoiding the detail of the defect
 18 cores, the simulations capture the heterogeneous processes of dynamical martensitic
 19 nucleation under the local stress field, and are able to predict the phase diagram of

1 martensitic nucleation. With the example of Fe-Pd ferroelastic polycrystals, the phase
2 diagram illustrates that postcursors, high angle grain boundaries and triple junctions
3 serve as the preferential heterogeneous nucleation sites depending on the loading and
4 cooling conditions. The information, presented in the form of a phase diagram like Fig.
5 5, specify how the quenching temperature and applied stress conditions can be
6 combined to activate particular mechanisms of martensitic nucleation and growth,
7 leading to complex microstructures in order to meet microstructural design goals.

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