

Manufacturing process Digital-Twin-oriented introduction to Octave



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Purpose

- The purpose of the current presentation is to introduce Octave tool to the ones interested in the concept of digital twin and/or cognitive automation.
- This presentation has been created under the framework EIT Manufacturing Project M-NEST-RIS.
- It is considered as an educational product and its price is equal to 0 Euros.
- Material herein can be reproduced given that the source is mentioned.







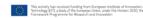


Preparation

- Download Octave
- https://www.gnu.org/software/octave/download

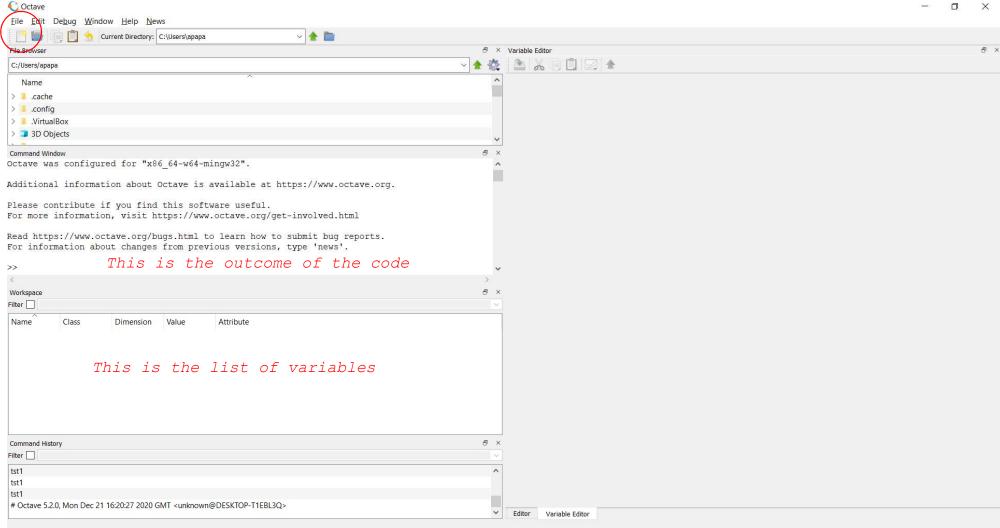








New project











Writing and executing code

- Procedural coding one line runs after the other
- First Run requires saving the code file as text









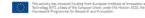


The path folder refers to a folder in the PC where all the related codes that are required for our code to run exist.

One can change this path folder temporarily, or include the folder where they saved their code in the load path, an ensemble of such folders.









Types of Variables

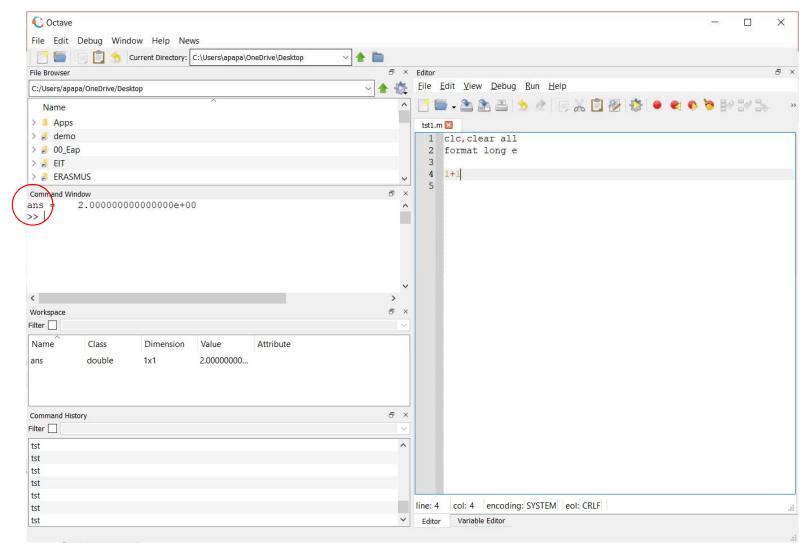
• All variables can be considered to be complex matrices





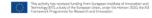




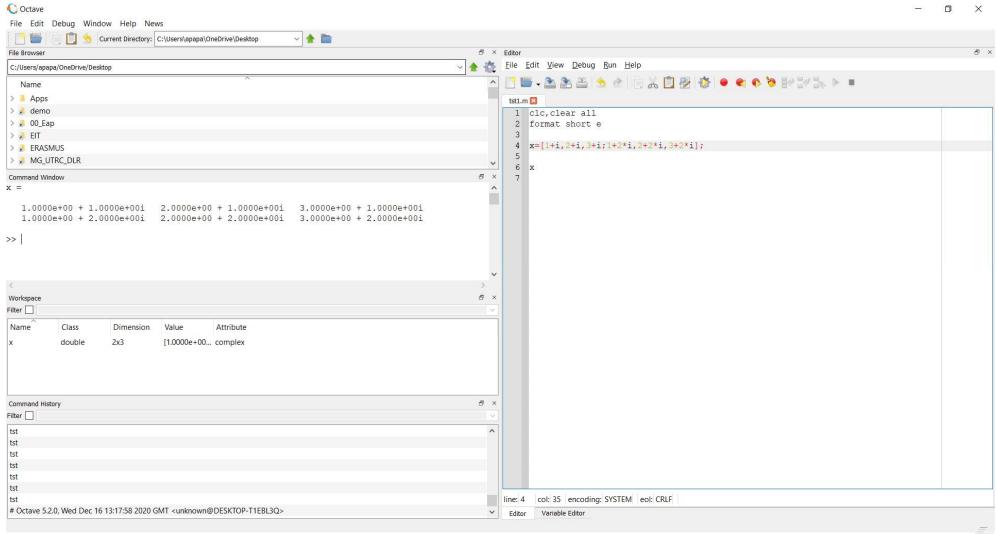




















Types of Operations

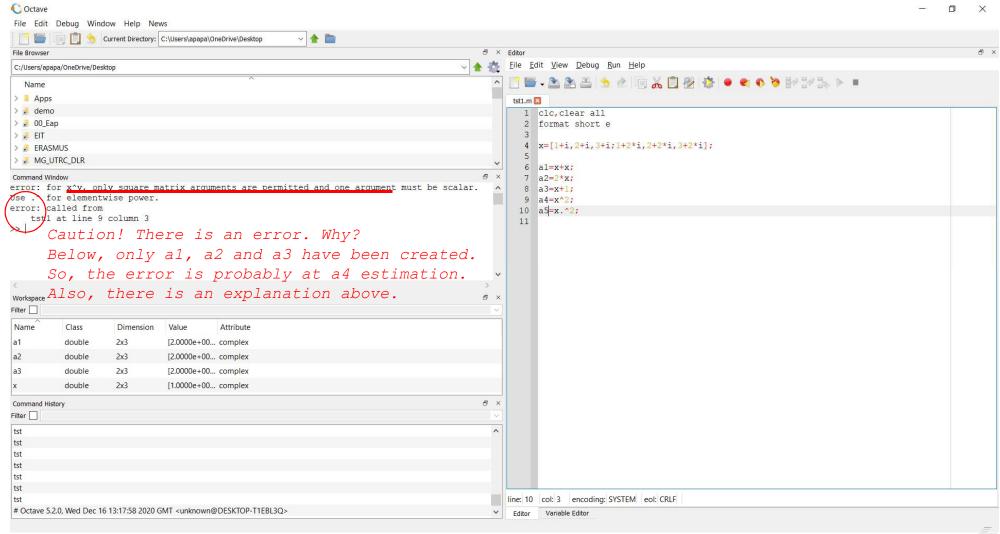
- All kinds of operations are supported
- For matrices, check operator .* against operator * and .^ against ^









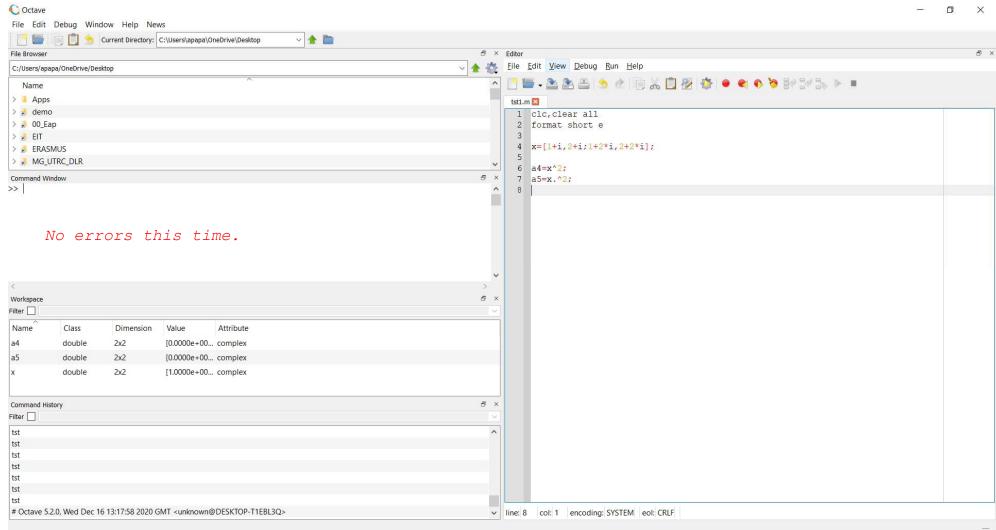




















Elementary Loops

The for loop is supported as per below

For start:step:end

Plotting diagrams is also supported

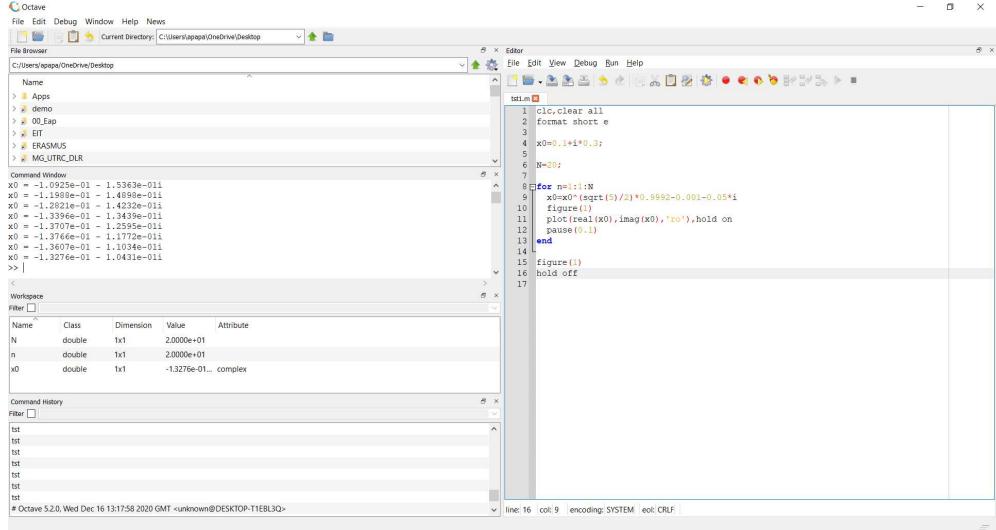
• Example hereafter refers to plotting a sequence in the complex plane



















Conditions & Conditional Loops

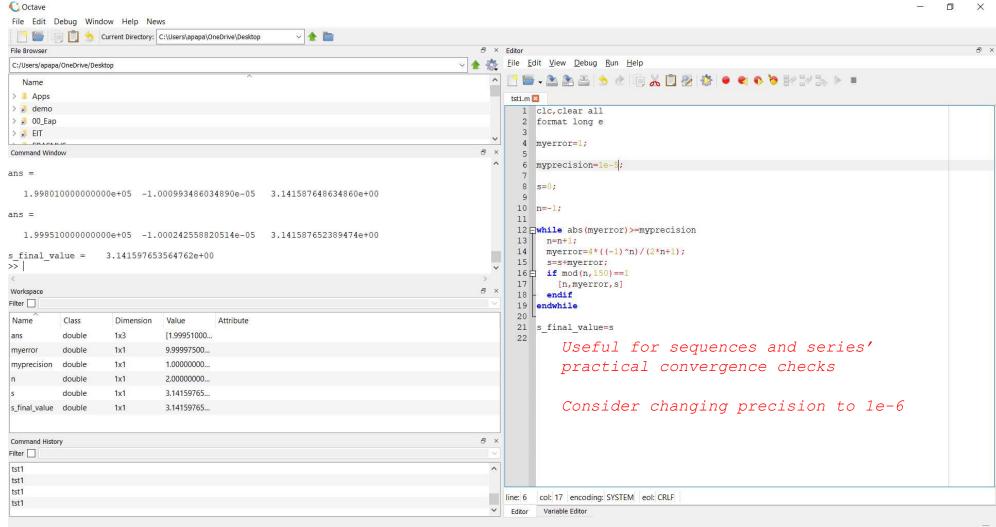
- While a statement is true, something is performed continuously
- If then else statement as per usual
- Example hereafter refers to estimating pi value up to a desired accuracy

















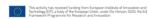


Systemic Approaches

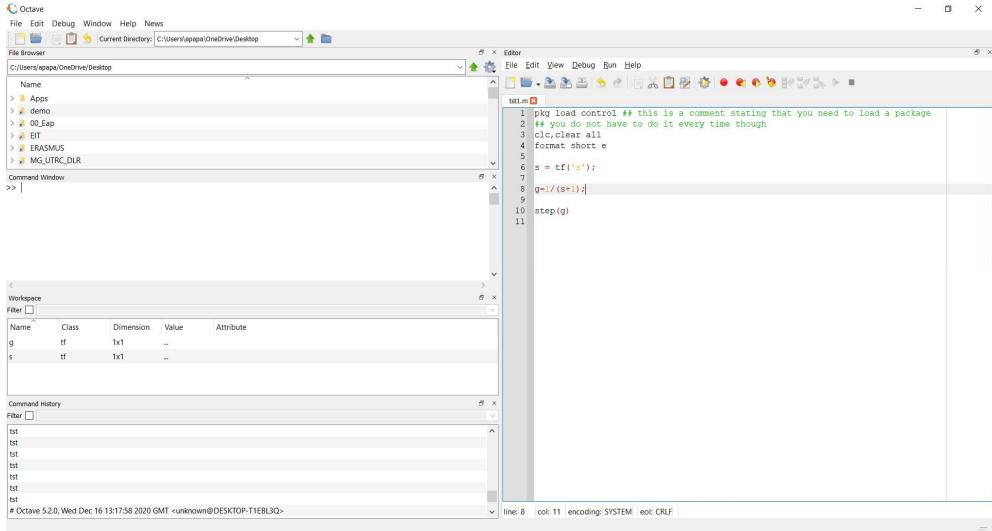
- Transfer functions' definition is supported
- As well as their step responses
- An external package is required to be loaded
- Example hereafter refers to plotting the step response of a first order continuous time system

















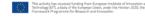


Theoretical modelling

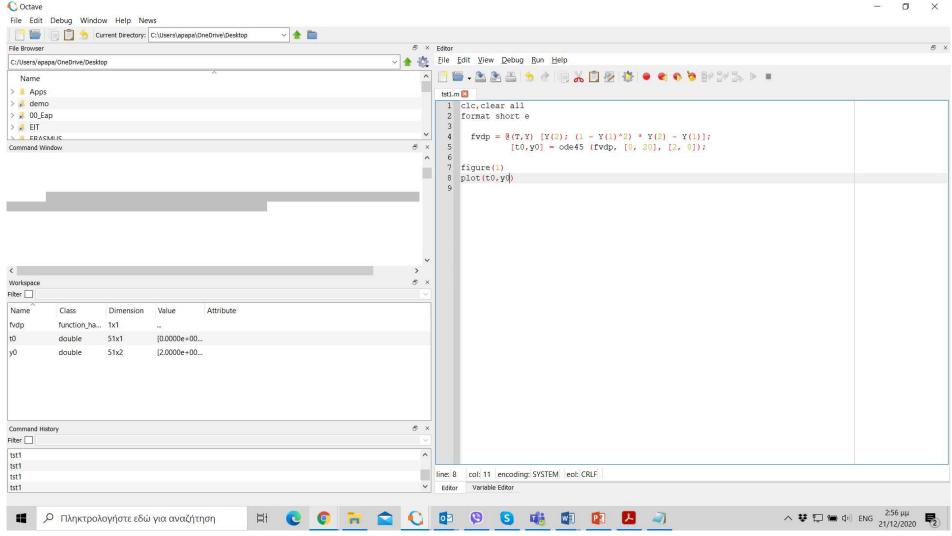
- Numerical solutions for ODEs (and PDEs) can be approximated
- Example hereafter refers to utilizing Runge-Kutta 4-5 method to solve a system of linear differential equations written in its first-order form

















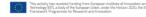


Uncertainty management

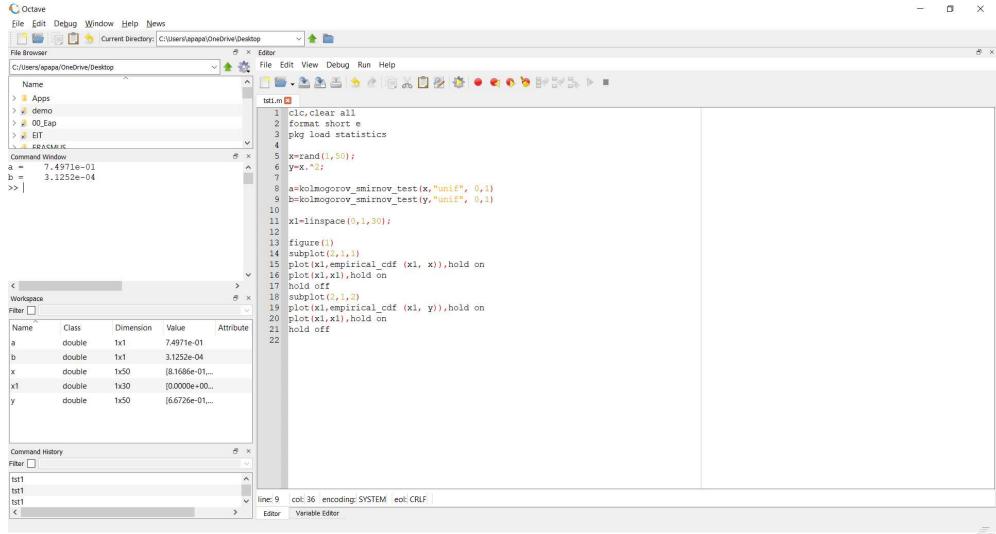
- Statistics' tools are supported
- Example hereafter refers to K-S test for uniform probability density function



















IoT, metrology and control

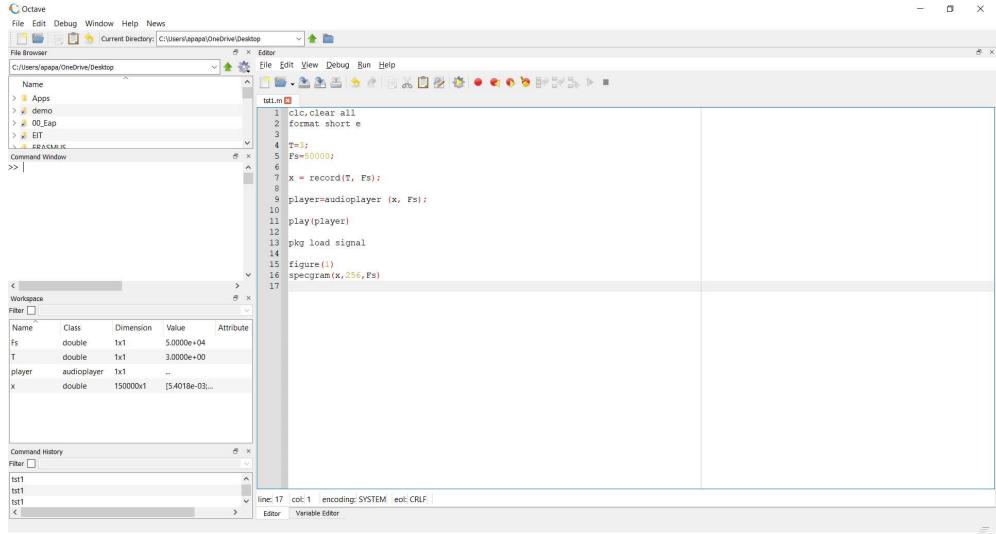
- I/O control is supported
- Example hereafter refers to retrieving data (=signal) from microphone, playing them through the speakers and at the same time visualizing a their spectrogram



















Extra information

- For further information about the current presentation, the concepts in it, or the project, please contact
 - Dr. Panos Stavropoulos, pstavr@lms.mech.upatras.gr





