



Performance optimizations for the atmospheric tomography problem of extremely large telescopes on real-time hardware

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Reduced Order Modelling, Simulation and
Optimization of Coupled Systems
(ROMSOC)



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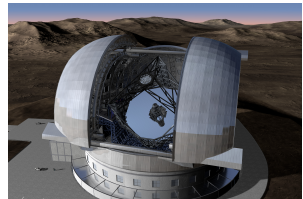


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- 1 Introduction
- 2 Solvers for atmospheric tomography
- 3 Performance analysis
- 4 Implementation on RTC hardware

- planned to be the world's largest optical/near-infrared telescope
 - built by the European Southern Observatory (ESO)
 - in the Atacama desert, Chile
 - with a primary mirror of 39 m
- ⇒ highly efficient algorithms to achieve an excellent image quality

- **adaptive optics:**
compensate optical distortions in the atmosphere
- **atmospheric tomography:**
reconstruction of the turbulent layers from sensor measurements



Credit: ESO

- **goal:** reconstruct turbulent layers ϕ from measurements s
- mathematical problem formulation:

$$s = A\phi$$

inverse problem \Rightarrow requires regularization

- **approach:** Bayesian framework and maximum a-posteriori estimate

$$(A^T C_\eta^{-1} A + C_\phi^{-1})\phi = A^T C_\eta^{-1} s$$

where C_ϕ and C_η are the covariance matrices of layers ϕ and noise η

Challenges:

- computationally very expensive operations
- to be solved in real-time (500 Hz)

\Rightarrow **need an efficient solver**

We want to solve:

$$(A^T C_\eta^{-1} A + C_\phi^{-1})\phi = A^T C_\eta^{-1} s$$

Soft Real Time (SRT):

Compute the reconstruction matrix by inverting the left-hand-side operator:

$$R := (A^T C_\eta^{-1} A + C_\phi^{-1})^{-1} A^T C_\eta^{-1}$$

Hard Real Time (HRT):

Apply matrix vector multiplication to get mirror commands:

$$\phi = R \cdot s$$

We want to solve:

$$(A^T C_\eta^{-1} A + C_\phi^{-1})\phi = A^T C_\eta^{-1} s$$

Use clever transformations - dual domain discretization:

$$(\mathbf{W}^{-T} \hat{A}^T C_\eta^{-1} \hat{A} \mathbf{W}^{-1} + \alpha D)c = \mathbf{W}^{-T} \hat{A}^T C_\eta^{-1} s$$

- \mathbf{W} is a mapping between finite element and wavelet domain
- \hat{A} discretized in the bilinear domain
- D is a diagonal approximation of C_ϕ^{-1} in the wavelet domain

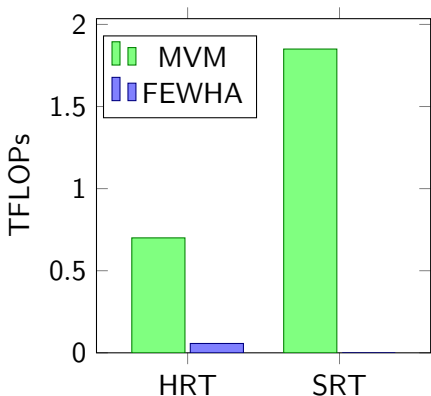
Hard Real Time (HRT): iterative approach to compute c

⇒ Preconditioned Conjugate Gradient Method

[2] M. Yudytskiy, T. Helin, R. Ramlau, A finite element - wavelet hybrid algorithm for atmospheric tomography

- first light instrument of the ELT
- collaboration with Microgate (responsible for RTC design)

number of layers:	6
number of wavefront sensors:	6
number of measurements per sensor:	9 600
number of modes per layer:	5 000
number of wavelets scales per layer:	128x128 or 64x64
number of PCG iterations for FEWHA:	4
hard real time:	2 ms
soft real time:	360 s
size of MVM matrix:	30 000 × 57 600
size of FEWHA matrix:	32 768 × 57 600

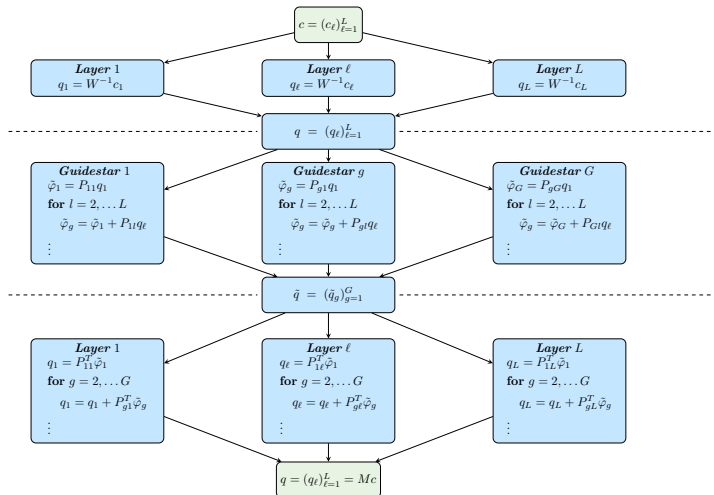


Memory Usage:

	MVM	FEWHA
HRT	3GB	15MB
SRT	50GB	-
	53GB	15MB

single precision floating point numbers

- ⇒ FEWHA **12 times faster** than the MVM for hard real time
- ⇒ FEWHA has **no additional soft real time** computational load
- ⇒ matrix free → saves a lot of memory and FLOPs



[3] B.Stadler, R. Biasi, R. Ramlau, Feasibility of standard a novel solvers for atmospheric tomography

One node of Radon1 HPC cluster of RICAM

- equipped with two 8-core Xeon E5-2630v3, 2.4Ghz
- **parallelization:**
OpenMP, Intel TBB and SSE
- **optimization:**
 - number of cores/threads (6 / 12)
 - vectorization
 - memory management

NVIDIA Tesla V100 GPU

- 5120 CUDA Cores, 1.2 GHz max. blocks per SM: 32 max. threads per block: 1024
- **parallelization:**
CUDA 10.1
- **optimization:**
 - number of threads/blocks
 - memory management
 - concurrent kernel execution
 - avoid transfer GPU - CPU

⇒ **2.3ms for FEWHA**

⇒ **10ms for FEWHA**

- ⇒ for FEWHA the CPU is a lot faster than the GPU
- ⇒ but for MVM the GPU is faster

Possible reasons:

- CPU has a faster clock (2.4 GHz vs. 1.2 GHz)
- memory bounded algorithm → faster memory access on CPU (Caches)
- dimension of the problem is too small
 - local parallelization of operators:
 - matrix-free implementation → over max. 128x128
 - global parallelization:
 - number of 6 layers or 6 wavefront sensors
- maybe other...

Thank you!

- [1] *B. L. Ellerbroek and C. R. Vogel, Inverse problems in astronomical adaptive optics.*
- [2] *M. Yudytskiy and T. Helin and R. Ramlau, Finite element-wavelet hybrid algorithm for atmospheric tomography.*
- [3] *B. Stadler, R. Biasi, R. Ramlau, Feasibility of standard and novel solvers for atmospheric tomography.*



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	GPU	CPU
Discrete Wavelet Transform	0.15	0.08
Bilinear Interpolation	0.08	0.015
Shack-Hartmann Operator	0.02	0.004
Diagonal Matrix	0.08	0.02