## **Deep-compression for HEP data**

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## **Motivation**

- There are approximately 1.7 billion events occurring inside the ATLAS detector, each second.
- Storage of these events is limited by the event size and a reduction of the event size will allow for searches that were not previously possible.

#### **Deep-compression**

- Deep compression refers to usage of autoencoders for performing data compression.
- Learn the data distribution by projecting it to a lower-dimension and then reprojecting.
- The idea is to use deep compression for High Energy Physics (HEP) data and check their efficacy.



A typical autoencoder (encoder+decoder) network

## Experiments with 4D data

## Normalization

An important part of training any machine learning algorithm is data preparation and analysis. Hence, we analyse the data distribution of the provided 4 dimensional data containing the parameters: **m**, **p\_t**, **phi** and **eta** when normalized using different normalization methods.



 $m \rightarrow ([log_{10}(m/1000)] + 1)/1.8$ 

## **Experiment details**

To analyze effects of normalization on compression

- trained and tested a simple model latent space of 3
- input 4D data

Ideally, the decompressed 4D data should be same as the input data and hence we train the autoencoder by using a reconstruction loss as the optimization loss function:

MSE = 
$$\frac{1}{N} \sum_{n=1}^{N} \sum_{i=1}^{P} (y_i(\vec{x}_n) - x_{ni})^2$$
,

#### Model description:

The model contains 7 fully-connected layers with 200, 100, 50, 3, 50, 100, 200 nodes and Tanh activation layer after each layer.



## Normalization experiments

Plots of the relative reconstruction error for each compressed variable for the entire test-set:



#### **Observations:**

- High bias in the non-normalised model. pt has low error whereas eta very high reconstruction error.
- Standard normalization has highest error for most of the parameters among the three models
- Custom normalization has better performance for most of the parameters as compared to the others

The custom norm data produced the lowest mean squared error on the test-set and is able to capture correlations among variables in a better way, I chose custom normalization for all further experiments.

Normalization type	MSE on the test-set		
None	0.5181		
Standard	0.01111		
Custom/	0.0007314		

## Different variants of compression network

Next, I tried 2 variants of the autoencoder models that had the same 7 layer autoencoder with similar node configuration as the previous model. The dissimilarity is in the activation layer and batchnorm layer.

- The first model has tanh activation and no batchnorm layer (the base model)
- The second has Leaky Rectified Linear Unit (ReLU) [1] activation and batchnorm [2] after each layer
- The third model has Exponential Linear Unit (ELU) [1] and batchnorm after each layer

Note that the MSE for the test-set is calculated on the custom normalized data, whereas the individual mean relative reconstruction errors are calculated on unnormalized data.

Model	m	pt	phi	eta	MSE on the test-set
Tanh, no BN	0.010748	-0.0001039	0.0007383	0.002638	0.0007314
LeakyReLU, BN	0.004853	-0.001126	0.008089	-0.02475	0.0005750
ELU, BN	0.005528	-0.0007568	-0.003144	-0.0002156	0.0005754

#### Mean of relative reconstruction error

[1] https://en.wikipedia.org/wiki/Rectifier (neural networks) [2] https://en.wikipedia.org/wiki/Batch normalization

## Variants of compression network

Plots of the relative reconstruction error for each compressed variable for the entire test-set:



- LeakyReLU model has moderate performance (based on the variance of relative error and MSE on the test-set).
- Tanh and ELU have comparable performance. Tanh has lower variance and mean for the relative error but ELU has lower MSE.
- Hence ELU model can be said to be the better among by considering both the relative error and MSE, since there is not much difference between ReLU and ELU's MSE for the test-set.

## Execution time and memory allocation

Test-set size: 27945

Hardware for computation: Intel(R) Xeon(R) CPU E5-1620 v4 @ 3.50GHz, 8 cores

Data loading execution time: 0.10674s Data loading memory: 3.668 MBs

Model	Model initialization time (s)	Model load time (s)	Encoding time (s)	Decoding time (s)	Encoding memory alloc (MB)	Decoding memory alloc (MB)
Tanh, no NN	2.5174	0.05932	0.03934	0.02113	0.0024	0.1780
LeakyReLU, BN	2.5903	0.08180	0.12613	0.10033	0.0076	0.2240
ELU, BN	2.4373	0.07940	0.16376	0.15237	0.0064	0.1945

- ELU has exponential component, hence it's runtime is higher
- Tanh also has exponential component, but the batchnorm layer in other two models increases execution time.
- Overall, we can say that a model without the exponential component i.e. with a ReLU activation and without Batch-normalisation should perform the best in terms of execution time

## Experiment with the loss function

- No re-training done for this network, original training from 4D network (MSE)
- Trained another model with the same configuration but with L1 loss

Model details:

- LeakyReLU, Batch Normalization
- Custom-norm, 4D data

#### Variance of relative reconstruction error

Model	m	pt	phi	eta	MSE on the test-set
MSE	0.162	0.0369	1.642	7.206	0.0005750
L1	0.302	0.0203	1.385	2.364	0.01211852

- Since MSE is used as a metric for analysing the test-set error, MSE as a loss function has much less error
- However, the compression performance could be better judged by using the response plots which show the distribution of the relative residual error

## MSE vs L1 - residual plots



Observations:

• No significant difference between the results with two different loss functions

## MSE vs L1 - Correlation plots



Observation:

Higher correlation between pt and m for MSE mean that the relative error of reconstruction for these variables are correlated

## Experiments with 27D data

## Tasks

#### In order to transition to 27D data, we formulated the following tasks:

- Analyse the available data
  - plot the distribution of each variable
  - compare the plots with the plots mentioned in prior experiments (Eric Wullf's thesis, a Masters student who worked on the project earlier)
- Test the available pre-trained model
  - create plots from the pre-trained model
  - compare and validate the published results
- Train the model on the available data
  - create response and correlation plots
  - analyse the performance

## 1. Data distribution - 27D

10<sup>6</sup> 10<sup>5</sup>

Numper of jets 10<sup>3</sup> 10<sup>1</sup> 10<sup>0</sup>

0 250

1000 1250

1500

1750

500

750

We visualize the data distribution for each variable in the training set



## Data distribution - 27D (cont.)



## Data distribution - 27D (cont.)



## 2: Comparison with existing results

Model details for the available results

- LeakyReLU, BN
- Custom-norm, 27D data
- Latent space = 14
- Model
  - o 27-200-200-200-14-200-200-200-27

Model details for the available pre-trained model

- LeakyReLU, BN
- Custom-norm, 27D data
- Latent space = 20
- Model
  - o 27-200-200-200-200-200-200-27



#### Plots for the results from the pre-trained model



#### Observations:

• Performance of the available pretrained seem to be very similar to the existing results

Note:

- The variable N90Constituents was not casted to int for the pre-trained model, which leads to the difference in the output plots
- the axes of the plots are slightly different



#### Plots for the results from the pre-trained model



#### Plots from the available results

#### Plots for the results from the pre-trained model



#### Observations:

• Changes in the latent space dimension changes the correlations

## Overall correlation plot for the pre-trained model

- We can observe that errors for different variables have considerable correlation among themselves
- This gives a glimpse of the ability of the network to compress different variables and also the tradeoff if some variable is focussed more



## 3. Re-training the network on 27D data

Model details:

- LeakyReLU, BN
- Custom-norm
- Latent space = 20
- Model [27, 400, 400, 200, 20, 200, 400, 400, 27]



#### **MSE** on test-set = **7.844e-06**

A comment on the training and validation loss plot - For this particular split and the training settings, the network shows a sharper decrease in the validation loss as compared to the training loss while training. A reason for this could be that the particular split/hyperparameter makes the network learn the data distribution in a better way. An interesting experiment would be to retrain the network with different settings and observe the behaviour.

## Input-output plots for the retrained model



Observations:

• The plots show that a faithful reconstruction for majority of the variables. Since we did not cast the *N90 Constituents* variable, the reconstructed outputs for this variable seems troublesome.

## Input-output plots for the retrained model (cont.)



Observations:

• Similarly in the case of the variables shown here, most of the reconstructions seem good, except for *ActiveArea* and *ActiveArea4vec\_pt* variables as we have not casted the output variables to int.

## 1D response plots for the retrained model



Observations:

• The 1D response plots here show that the distribution of the relative error. We notice that most of the variables are zero centered and have low variance, which depicts that compression model performs fairly well for these variables. 26



0.8

- 0.6

0.4

0.2

Correlation

-0.2

-0.4

-0.6

-0.8

m = 6.3e - 05\*8 21:8

ActiveArea4vec\_m





Apic





## Standard norm vs Custom norm on PhenoML data

• Performance on the test-set

Normalization type	MSE on the test-set
Standard	2.7026193e-05
Custom	8.7358785e-06



## Custom norm on PhenoML data

#### 1D response plots







## Variation in training-set size

MSE on test-set:

- "Full" dataset (500 MB of jets): 2.485e-06 2-3 days, batch size 8k (using the one from before)
  - More requires too much memory to be loaded all at once...
- Half- dataset: 8.735e-06 24h
- Question for later: if we increase the batch size && use the full dataset it should take less time...check E. Wulff's thesis





## Test with atop\_10fb data - events with only jets

Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]

Jets data with custom norm

• Trained on njets\_10fb dataset - containing only jets [number of events?]

Normalization type	MSE on the test-set
atop	2.7047477e-06
Jets	2.4856113e-06

#### atop events with only jets data with custom norm



## Test with atop\_10fb data - events with only jets



Keep all the event, but use only the type of particles == jets in network dataset

## Test with atop\_10fb data - all events but only jet particles

#### Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

Jets data with custom norm

#### Normalization type 2.6954153e-06 atop 2.4856113e-06 Jets

#### Residuals of E Residuals of E Residuals of pt 25000 3500 25000 $Mean = 0.000375 \pm 0.000012$ $Mean = 0.001237 \pm 0.000012$ 3000 $\sigma = 0.003726 \pm 0.000008$ $\sigma = 0.003643 \pm 0.000008$ 20000 20000 2500 15000 2000 15000 1500 10000 10000 1000 5000 5000 500 -0100-0075-0050-0025 0000 0025 0050 0075 0100 -0100-0075-0050-0025 0000 0025 0050 0075 0100 $(E_{out} - E_{ln})/E_{ln}$ $(E_{out} - E_{ln})/E_{ln}$ Residuals of phi Residuals of eta 35000 3500 20000 Mean = -0.000789±0.003765 Mean = -0.000839 ±0.001128 30000 $\sigma = 1.190682 \pm 0.002662$ $\sigma = 0.356568 \pm 0.000797$ 3000 25000 15000 2500 5 20000 5 2000 10000 15000 1500 10000 1000 5000 5000 500 -0.100 -0.075 -0.050 -0.025 0.000 0.025 0.050 0.075 0.100 -0.100 -0.075 -0.050 -0.025 0.000 0.025 0.050 0.075 0.100 -0.100 -0.075 -0.050 -0.025 0.000 0.025 0.050 0.075 0.100

#### all events but only jet particles



1000

1000

000

-0.100 -0.075 -0.050 -0.025 0.000 0.025 0.050 0.075 0.100

MSE on the test-set

## Test with atop\_10fb data - all events but only jet particles



Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets



#### atop data with custom norm



#### Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

Jets data with custom norm

# Normalization typeMSE on the test-setatop6.7475153e-06Jets2.4856113e-06



#### atop data with custom norm



## Test with atopbar\_10fb data

Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets .



#### atopbar data with custom norm



## Test with atopbar\_10fb data

Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

# Normalization typeMSE on the test-setatopbar6.674753e-06Jets2.4856113e-06



## Test with atop\_10fb data



## Test with ttbar\_10fb data - events with only jets

Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

Jets data with custom norm

Normalization type	MSE on the test-set
ttbar	2.915699e-06
Jets	2.4856113e-06

#### ttbar events with only jets data with custom norm



## Test with ttbar\_10fb data - events with only jets



## Test with ttbar\_10fb data - all events but only jet particles

Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

## Normalization typeMSE on the test-setttbar3.0117515e-06Jets2.4856113e-06

#### Jets data with custom norm

#### all events but only jet particles



## Test with ttbar\_10fb data - all events but only jet particles



Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets



#### Jets data with custom norm

10<sup>3</sup> 103 Number of jets 10<sup>1</sup> 10<sup>1</sup> Number of jets 10<sup>1</sup> 10° 10 1.5 2.0 2.5 3.0 3.5 125 150 175 2.00 2.25 2.50 2.75 3.00 pt  $6 \times 10^{2}$  $6 \times 10^{2}$ b of jets 2 × 10<sup>5</sup>  $2 \times 10^{2}$ -0.6 -0.4 -0.2 0.0 0.2 0.4 0.6 -1.0 -0.5 0.0 0.5 1.0 eta phi

#### ttbar data with custom norm

#### Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

# Normalization typeMSE on the test-setttbar8.184939e-06Jets2.4856113e-06

#### Jets data with custom norm

#### ttbar data with custom norm





# Particle distribution plot for different processes in phenoML dataset - SM



# Particle distribution plot for different processes in phenoML dataset - SM



# Particle distribution plot for different processes in phenoML dataset - SM



## Particle distribution plot for different processes in phenoML



## Particle distribution plot for different processes in phenoML





## Particle distribution plot for different processes in phenoML



### Particle distribution plot for different processes in phenoML dataset - BSM



61

1224

e+

1406

e+

Model details:

- LeakyReLU, BN, Custom-norm
- Latent space = 3
- Model [4, 400, 400, 200, 3, 200, 400, 400, 4]
- Trained on njets\_10fb dataset containing only jets

Process	e+	е-	m+	m-	\gamma
stop_02	8.737900e-05	8.628796e-05	9.500347e-05	0.0001134310	1.1838656e-05
gluino_02	6.45536e-05	5.087386e-05	9.127547e-05	7.675688e-05	1.2573055e-05



Mean and std-dev for the residuals of pt





# Testing a chan2a-trained-model on chan3 of DarkMachines data



Model trained on chan2a doesn't converge that well, and performs moderately on jets

### Testing a chan2a-trained-model on chan3 of DarkMachines

data





## **Detailed summary**

- Fixed the GitHub repo by adding missing references to the files
  - Commit links: [ <u>a558e70</u>, <u>8f1253d</u>, <u>0faabf1</u> ]
- Extracted data from ROOT files and created binary (pickle) files for processing
- Plotted the data distribution to validate that the working data is correct
  - Link to the plots
- Created plots from the pre-trained model available to compare and validate the published results (thesis of Eric Wulff)
  - Link to the plots
- Understood the functioning of HTCondor
- Wrote documents (starting-guide) to work on HTCondor
  - Link to the doc

## Detailed summary (cont.)

- Created scripts for
  - Processing and saving the ROOT files [ 0531239 ]
  - Scaling the data by fitting scaling models for each data [ <u>06161dc</u> ]
  - Custom normalising the data [ <u>a93afeb</u> ]

on HTCondor

- Modified and created training scripts for 27D data to run on the GPUs available at HTCondor
  - [<u>f169d01</u>, <u>ef03a0e</u>]
- Checked the training strategy for the 27D model
  - Number of epochs or stopping point was not mentioned anywhere
  - Found that an MSE loss around 1e-6 is sufficient for stopping
  - For custom-normalized data, it corresponds to around 500 epochs @ LR 1e-4

## Detailed summary (cont.)

- Trained the model for 27D [27, 400, 400, 200, 20, 200, 400, 400, 27]
  - scaled data (link to the training summary and models)
  - custom normalized data (link to the training summary and models)
- Checked the training time for the models
  - On an average 3.12 minutes per epoch
  - For 500ep 25:35 hours on a GPU @ batch-size of 8192
- Created plots for the trained models
  - Scaled data (link to the plots)
  - Custom-normalized data (<u>link to the plots</u>)
- Compared L1 with MSE loss for 4D data
  - Link to the plots