

# INFORMATION, INCENTIVES AND AIR QUALITY: NEW EVIDENCE FROM MACHINE LEARNING PREDICTIONS

GARESC CONFERENCE

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## STYLIZED FACT 1: RAMPANT DATA MANIPULATION

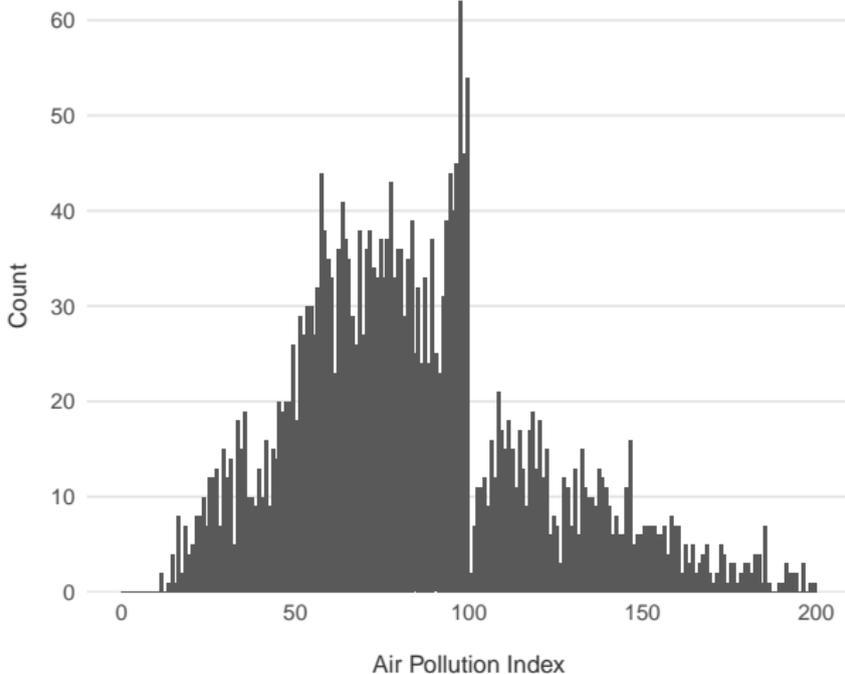
- Anecdotal evidence: *The Ministry of Environmental Protection inspected 8,500 businesses in Beijing and surrounding areas and found that over 3,100 factories had tampered with their emission monitoring equipment and altered reported data*<sup>1</sup>
- Statistical evidence: Local government officials also manipulate air quality data to satisfy targets assigned by the central government

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<sup>1</sup>Source: Caixin Global News Article

# STYLIZED FACT 1: RAMPANT DATA MANIPULATION

Figure 1: Histogram of Reported Air Pollution Index in Beijing, 2005–2013



## STYLIZED FACT 2: RECENT IMPROVEMENT IN DATA QUALITY

- Recent surge in investments in monitoring equipments in China that amount to approximately **0.95 billion USD** in just 2015 (Clean Air Act incurred approximately 65 billion USD in 30 years).
- Much more stringent regulations on maintaining the fidelity of air quality data:
  - Require **real-time hourly data** to be **automatically** publicized on data center websites and mobile apps
  - Employees at local environmental protection bureaus cannot have keys to monitoring stations<sup>2</sup>

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<sup>2</sup>Source: Jinchu News Article

# TESTABLE HYPOTHESIS

## Testable Hypothesis

Does building national monitoring stations reduce information asymmetry between central and local regulators, incentivize local regulators to reduce emission, and thus improve air quality?

### Institutional Context:

- Lack of any  $PM_{2.5}$  information before 2012
- Intensive inter-jurisdiction competition for political promotion
- In 2013, the central government signed separate “contracts” with provincial leaders promising reduction in ambient  $PM_{2.5}$  levels of up to 25% in five years

# POLICY

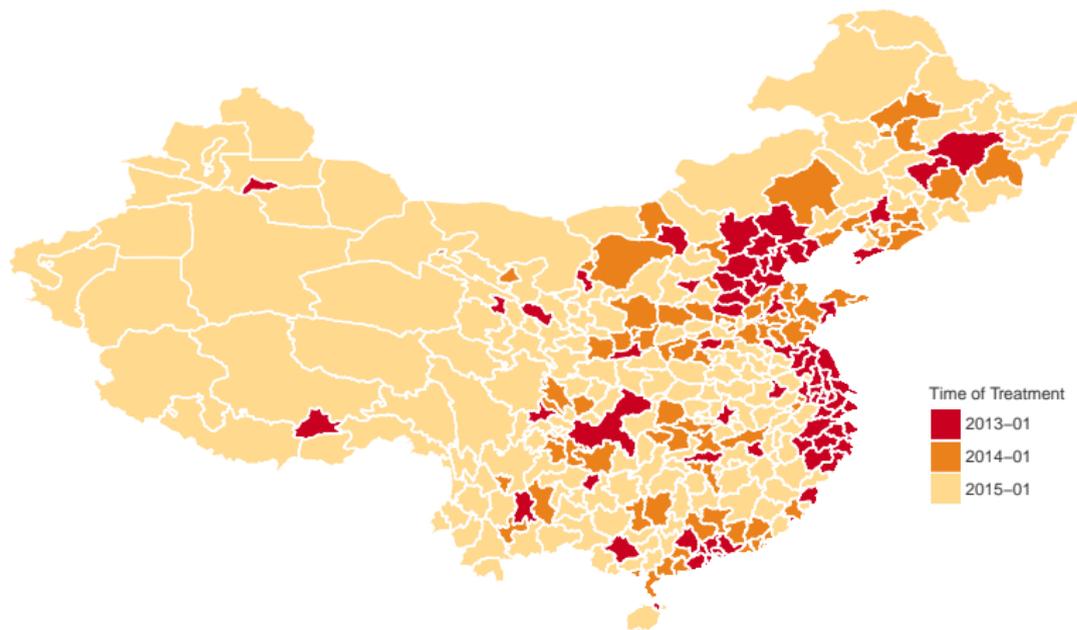
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- **Treatment: Reporting of Fine Particulate Matter (PM<sub>2.5</sub>) monitoring data to the central government.**
- “Contracts” were signed between central and local government to reduce PM<sub>2.5</sub> by a specific target value (ranging from 5% to 25%) by 2017
- The central government imposed the regulation on 74 cities in Jan 2013, over 100 cities in Jan 2014, and the rest in Jan 2015.

# POLICY

Figure 2: Time of Treatment: Dates when Cities Start Reporting PM<sub>2.5</sub> Values

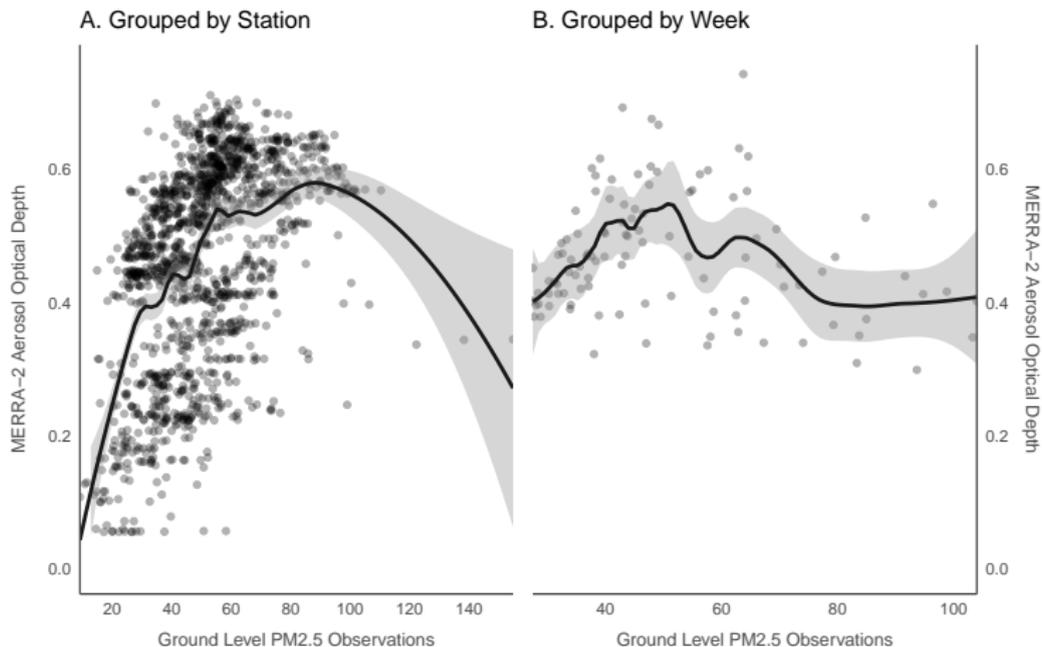


## KEY CONTRIBUTION: DATA

- Challenge: Data did not exist before monitoring stations were built—**pre-treatment data are unavailable**
- Solution: Recent development in **machine learning**, combined with **satellite images** collected by NASA, allows us to reconstruct historical air pollution datasets
- Compared to directly using satellite observations, we recover **ground-level concentrations**, with real welfare and health consequences, whereas raw satellite products report **column concentrations**

# COLUMN CONCENTRATIONS CAPTURE LITTLE TEMPORAL VARIATION

Figure 3: Aerosol Optical Depth and PM<sub>2.5</sub> in China, 2015–2016



## DATA: OVERVIEW

- We feed our machine learning model with **satellite data throughout 2005–2016 as features**, train our model on **2015–2016 ground-level observations**, and use it to predict **2005–2016 ground-level concentrations**, when official data were either non-existent (for  $PM_{2.5}$ ,  $O_3$  and  $CO$ ) or shown to be subject to human manipulation (for  $PM_{10}$ ,  $SO_2$  and  $NO_2$ ).
- We train a different model for every single station amongst about 1500 stations, and drop half of the stations which do not yield satisfactory performance.
- We use **Extreme Gradient Boosting**, which is a variant of Random Forest and a regression-tree-based algorithm. It conducts surrogate splits to do “smart” imputations for observations with missing features.

## DATA: TARGETS AND FEATURES

**Table 1: Targets, Features and Data Sources**

| <b>Targets (2015–2016 for Training, 2014 for Test)</b>   | <b>Dataset</b> | <b>Source</b>     |
|--|----------------|-------------------|
| Monitoring Station Measurements<br>(PM <sub>2.5</sub> , PM <sub>10</sub> , NO <sub>2</sub> , SO <sub>2</sub> , O <sub>3</sub> , CO)<br>Reconstructed Air Pollution Index | AQI            | Harvard Dataverse |
| <b>Features (2005–2016)</b>  | <b>Dataset</b> | <b>Source</b>     |
| Day of Year  |                |                   |
| Aerosol Optical Depth (Aqua and Terra)   | MODIS          | NASA EarthData    |
| SO <sub>2</sub> , NO <sub>2</sub> , O <sub>3</sub> Column Concentrations   | OMI            | NASA EarthData    |
| CO, O <sub>3</sub> and AOD Reanalysis Product  | MERRA2         | NASA EarthData    |
| Temperature, Relative Humidity, Pressure,<br>Eastward and Northward Wind Speed,<br>Planetary Boundary Layer Height   | MERRA2         | NASA EarthData    |

## DATA: PERFORMANCE

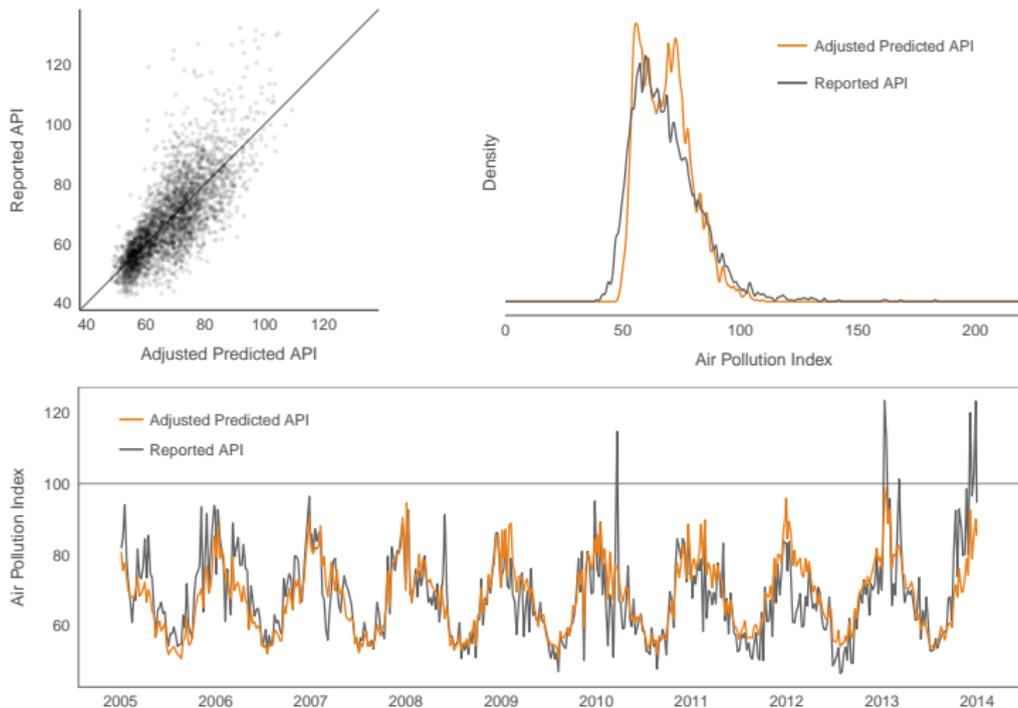
Table 2: Predictive Performance: Cross Validated Weekly  $R^2$

| Target Variable   | Overall $R^2$ | Station-Specific $R^2$ Percentiles |      |      |      |      |
|-------------------|---------------|------------------------------------|------|------|------|------|
|                   |               | 5%                                 | 10%  | 50%  | 90%  | 95%  |
| API               | 0.82          | 0.38                               | 0.42 | 0.54 | 0.68 | 0.72 |
| PM <sub>10</sub>  | 0.80          | 0.37                               | 0.40 | 0.52 | 0.66 | 0.70 |
| PM <sub>2.5</sub> | 0.87          | 0.42                               | 0.46 | 0.57 | 0.70 | 0.73 |
| O <sub>3</sub>    | 0.92          | 0.54                               | 0.56 | 0.69 | 0.84 | 0.86 |
| SO <sub>2</sub>   | 0.86          | 0.19                               | 0.24 | 0.48 | 0.76 | 0.81 |
| NO <sub>2</sub>   | 0.85          | 0.34                               | 0.39 | 0.56 | 0.71 | 0.74 |
| CO                | 0.92          | 0.16                               | 0.21 | 0.43 | 0.69 | 0.73 |

**Notes:** (i) We use 5-fold cross validation on training data to obtain predicted and true value pairs. (ii) We include only half of all the stations.

# DATA: PERFORMANCE

Figure 4: Comparing Predicted and Reported Air Pollution Index in China



# EMPIRICAL STRATEGY: EVENT STUDY

$$Y_{iwy} = \alpha_i + \beta_{wy} + \sum_{k \in [-10, 4] \setminus \{-8, -1\}} \tau_k 1\{K_{iwy} = k\} + \epsilon_{iwy} \quad (1)$$

- Each  $i$  indicates one monitoring station;
- Each  $t$  indicates one week;
- $K_{iwy}$  is the year relative to treatment;
- $Y_{i,t}$  is average weekly air pollution levels;
- $\epsilon_{i,t}$  is clustered at the city level.

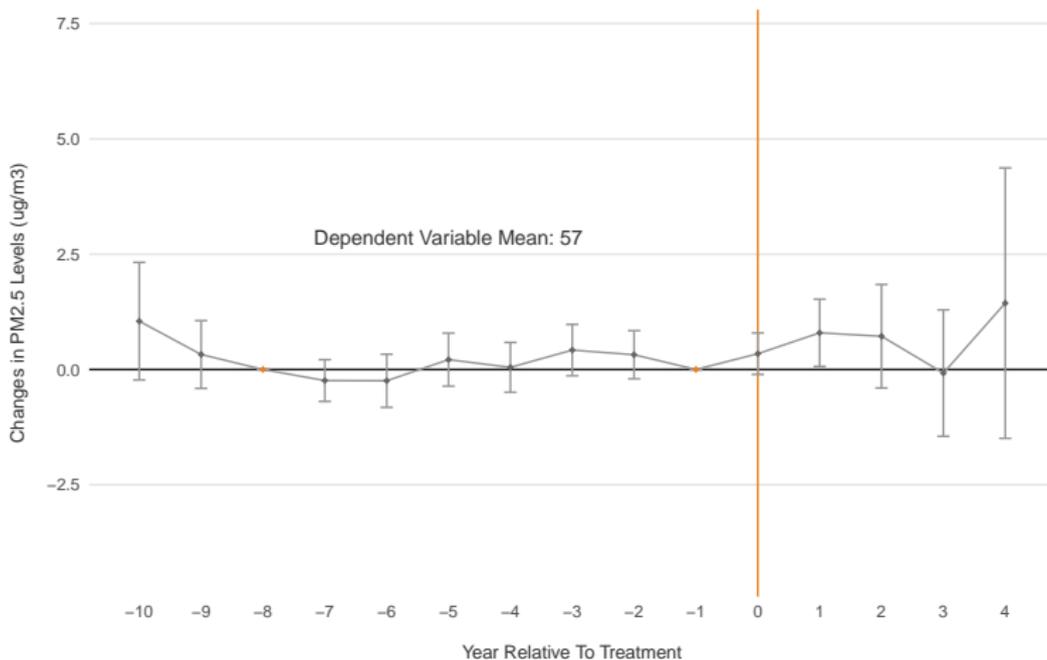
## EMPIRICAL STRATEGY: STRUCTURAL BREAK

$$Y_{iwy} = \alpha_{iw} + \beta_y + \tau_j 1\{K_{iwy} \geq j\} + \epsilon_{iwy} \quad (2)$$

- Each  $i$  indicates one monitoring station;
- Each  $w$  indicates one week, each  $y$  indicates one year;
- $K_{iwy}$  is the year relative to treatment;
- $j \in [-8, 2]$  is the placebo or actual treatment time;
- $Y_{iwy}$  is average weekly air pollution levels;
- $\epsilon_{iwy}$  is clustered at the city level.

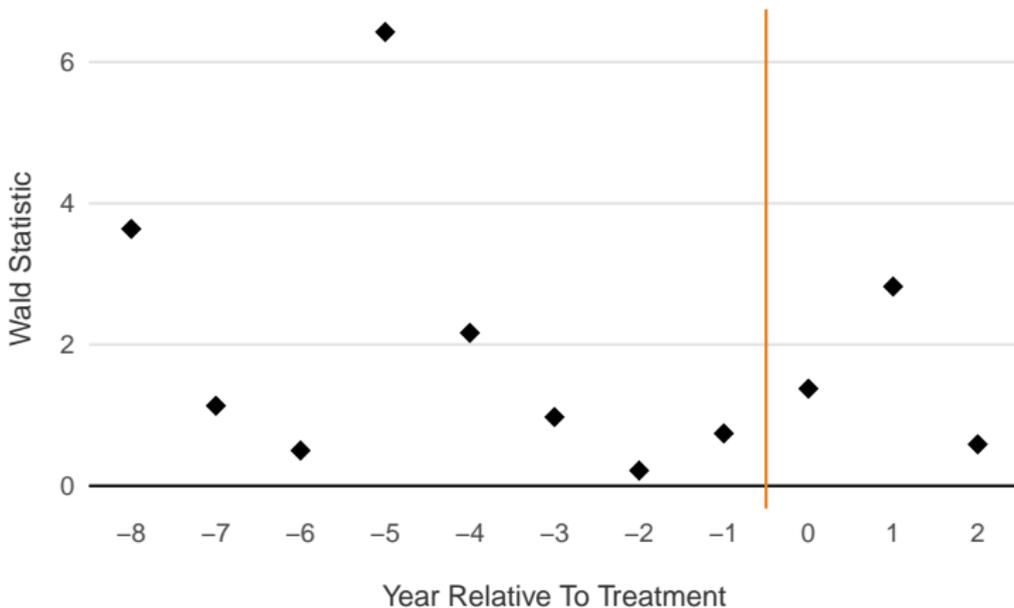
# TREATMENT EFFECTS ARE TIGHTLY BOUNDED AROUND ZERO

Figure 5: Event Study Estimates: PM<sub>2.5</sub> Levels



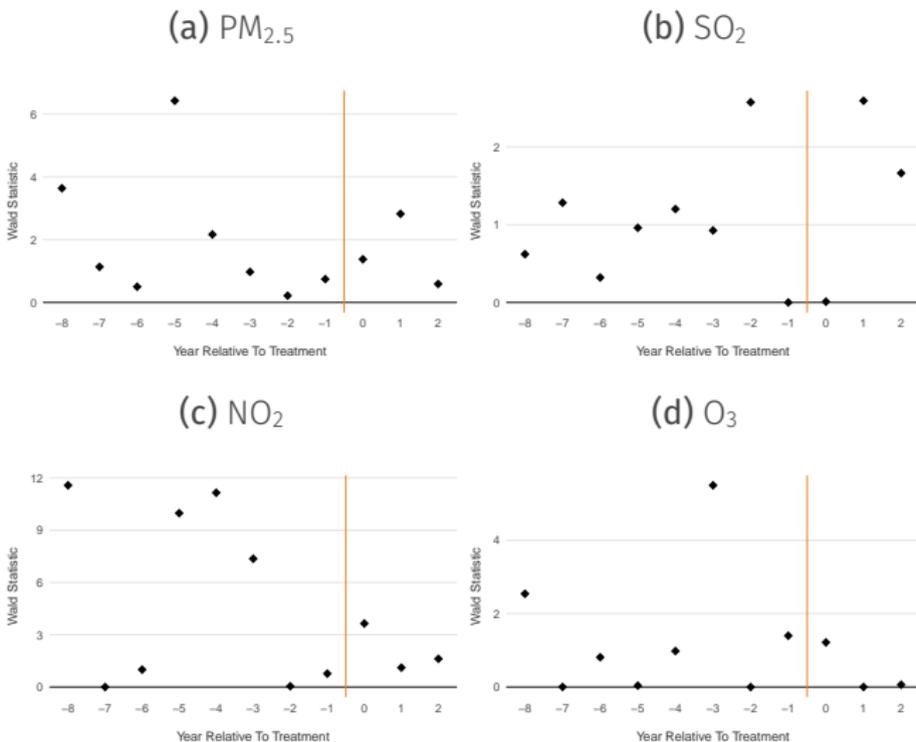
# TREATMENT HAS NO EFFECTS ON AIR QUALITY

Figure 6: Structural Break Estimates: Machine Learning Predictions for  $PM_{2.5}$



# TREATMENT HAS NO EFFECTS ON AIR QUALITY

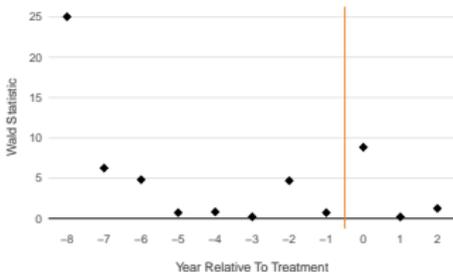
Figure 7: Structural Break Estimates: Machine Learning Predictions



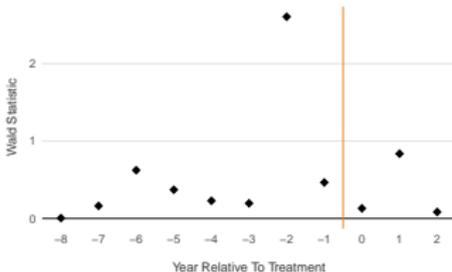
# TREATMENT HAS NO EFFECTS ON AIR QUALITY

Figure 9: Structural Break Estimates: **Satellite Observations**

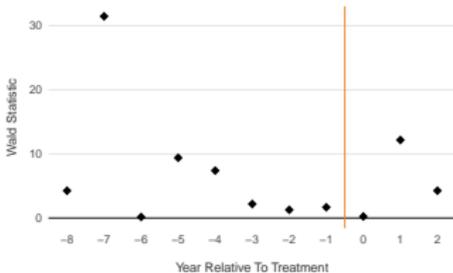
(a) AOD (MERRA2)



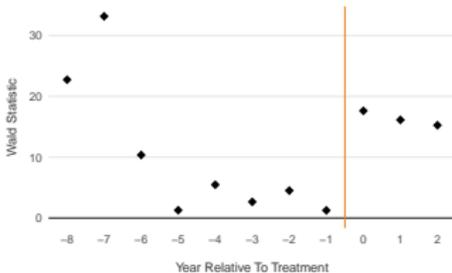
(b) AOD (Terra)



(c) O<sub>3</sub> (Aura)



(d) SO<sub>2</sub> (Aura)



## A CONCEPTUAL MODEL TO RECONCILE RESULTS

Local regulators are evaluated with either **emissions (which may be mis-reported)**

$$\underbrace{b(e+l)}_{\text{benefit of reported emission reduction}} - \underbrace{c(e)}_{\text{cost of effort}} - \underbrace{p(l)}_{\text{punishment for being caught}} \quad (3)$$

or **ambient concentrations**

$$\underbrace{q(e, \epsilon)}_{\text{(air) quality depends on effort but is uncertain}} - \underbrace{c(e)}_{\text{cost of effort}} \quad (4)$$

The relative effectiveness of the two regulations depend on the extent of **information asymmetry**  $p(\cdot)$  and the **uncertainty in ambient concentrations**  $\epsilon$ , conditional on emissions.