

GENERAL THEORY OF NATURAL EQUIVALENCES

BY

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Introduction. The subject matter of this paper is best explained by an example, such as that of the relation between a vector space L and its “dual”

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or “conjugate” space $T(L)$. Let L be a finite-dimensional real vector space, while its conjugate $T(L)$ is, as is customary, the vector space of all real valued linear functions t on L . Since this conjugate $T(L)$ is in its turn a real vector space with the same dimension as L , it is clear that L and $T(L)$ are isomorphic. But such an isomorphism cannot be exhibited until one chooses a definite set of basis vectors for L , and furthermore the isomorphism which results will differ for different choices of this basis.

For the iterated conjugate space $T(T(L))$, on the other hand, it is well known that one can exhibit an isomorphism between L and $T(T(L))$ *without* using any special basis in L . This exhibition of the isomorphism $L \cong T(T(L))$ is “natural” in that it is given *simultaneously* for *all* finite-dimensional vector spaces L .

This simultaneity can be further analyzed. Consider two finite-dimensional vector spaces L_1 and L_2 and a linear transformation λ_1 of L_1 into L_2 ; in symbols

$$(1) \quad \lambda_1: L_1 \rightarrow L_2.$$

This transformation λ_1 induces a corresponding linear transformation of the second conjugate space $T(L_2)$ into the first one, $T(L_1)$. Specifically, since each element t_2 in the conjugate space $T(L_2)$ is itself a mapping, one has two transformations

$$L_1 \xrightarrow{\lambda_1} L_2 \xrightarrow{t_2} R;$$

their product $t_2\lambda_1$ is thus a linear transformation of L_1 into R , hence an element t_1 in the conjugate space $T(L_1)$. We call this correspondence of t_2 to t_1 the mapping $T(\lambda_1)$ *induced* by λ_1 ; thus $T(\lambda_1)$ is defined by setting $[T(\lambda_1)]t_2 = t_2\lambda_1$, so that

$$(2) \quad T(\lambda_1): T(L_2) \rightarrow T(L_1).$$

In particular, this induced transformation $T(\lambda_1)$ is simply the identity when λ_1 is given as the identity transformation of L_1 into L_1 . Furthermore the transformation induced by a product of λ 's is the product of the separately induced transformations, for if λ_1 maps L_1 into L_2 while λ_2 maps L_2 into L_3 , the definition of $T(\lambda)$ shows that

$$T(\lambda_2\lambda_1) = T(\lambda_1)T(\lambda_2).$$

The process of forming the conjugate space thus actually involves two different operations or functions. The first associates with each space L its conjugate space $T(L)$; the second associates with each linear transformation λ between vector spaces its induced linear transformation $T(\lambda)$ ⁽¹⁾.

(1) The two different functions $T(L)$ and $T(\lambda)$ may be safely denoted by the same letter T because their arguments L and λ are always typographically distinct.

A discussion of the “simultaneous” or “natural” character of the isomorphism $L \cong T(T(L))$ clearly involves a simultaneous consideration of all spaces L and all transformations λ connecting them; this entails a simultaneous consideration of the conjugate spaces $T(L)$ and the induced transformations $T(\lambda)$ connecting them. Both functions $T(L)$ and $T(\lambda)$ are thus involved; we regard them as the component parts of what we call a “functor” T . Since the induced mapping $T(\lambda_1)$ of (2) reverses the direction of the original λ_1 of (1), this functor T will be called “contravariant.”

The simultaneous isomorphisms

$$\tau(L): L \rightleftharpoons T(T(L))$$

compare two covariant functors; the first is the identity functor I , composed of the two functions

$$I(L) = L, \quad I(\lambda) = \lambda;$$

the second is the iterated conjugate functor T^2 , with components

$$T^2(L) = T(T(L)), \quad T^2(\lambda) = T(T(\lambda)).$$

For each L , $\tau(L)$ is constructed as follows. Each vector $x \in L$ and each functional $t \in T(L)$ determine a real number $t(x)$. If in this expression x is fixed while t varies, we obtain a linear transformation of $T(L)$ into R , hence an element y in the double conjugate space $T^2(L)$. This mapping $\tau(L)$ of x to y may also be defined formally by setting $[[\tau(L)]x]t = t(x)$.

The connections between these isomorphisms $\tau(L)$ and the transformations $\lambda: L_1 \rightarrow L_2$ may be displayed thus:

$$\begin{array}{ccc} L_1 & \xrightarrow{\tau(L_1)} & T^2(L_1) \\ I(\lambda) \downarrow & & \downarrow T^2(\lambda) \\ L_2 & \xrightarrow{\tau(L_2)} & T^2(L_2) \end{array}$$

The statement that the two possible paths from L_1 to $T^2(L_2)$ in this diagram are in effect identical is what we shall call the “naturality” or “simultaneity” condition for t ; explicitly, it reads

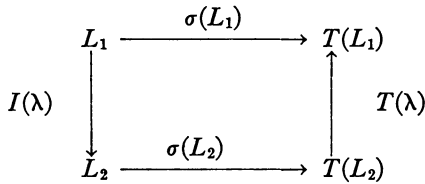
$$(3) \quad \tau(L_2)I(\lambda) = T^2(\lambda)\tau(L_1).$$

This equality can be verified from the above definitions of $t(L)$ and $T(\lambda)$ by straightforward substitution. A function t satisfying this “naturality” condition will be called a “natural equivalence” of the functors I and T^2 .

On the other hand, the isomorphism of L to its conjugate space $T(L)$ is a comparison of the covariant functor I with the contravariant functor T . Suppose that we are given simultaneous isomorphisms

$$\sigma(L): L \rightleftarrows T(L)$$

for each L . For each linear transformation $\lambda: L_1 \rightarrow L_2$ we then have a diagram



The only “naturality” condition read from this diagram is $\sigma(L_1) = T(\lambda)\sigma(L_2)\lambda$. Since $\sigma(L_1)$ is an isomorphism, this condition certainly cannot hold unless λ is an isomorphism of L_1 into L_2 . Even in the more restricted case in which $L_2 = L_1 = L$ is a single space, there can be no isomorphism $\sigma: L \rightarrow T(L)$ which satisfies this naturality condition $\sigma = T(\lambda)\sigma\lambda$ for every nonsingular linear transformation λ (²). Consequently, with our definition of $T(\lambda)$, there is no “natural” isomorphism between the functors I and T , even in a very restricted special case.

Such a consideration of vector spaces and their linear transformations is but one example of many similar mathematical situations; for instance, we may deal with groups and their homomorphisms, with topological spaces and their continuous mappings, with simplicial complexes and their simplicial transformations, with ordered sets and their order preserving transformations. In order to deal in a general way with such situations, we introduce the concept of a *category*. Thus a category \mathfrak{A} will consist of abstract elements of two types: the objects A (for example, vector spaces, groups) and the mappings α (for example, linear transformations, homomorphisms). For some pairs of mappings in the category there is defined a product (in the examples, the product is the usual composite of two transformations). Certain of these mappings act as identities with respect to this product, and there is a one-to-one correspondence between the objects of the category and these identities. A category is subject to certain simple axioms, so formulated as to include all examples of the character described above.

Some of the mappings α of a category will have a formal inverse mapping in the category; such a mapping α is called an equivalence. In the examples quoted the equivalences turn out to be, respectively, the isomorphisms for vector spaces, the homeomorphisms for topological spaces, the isomorphisms for groups and for complexes, and so on.

Most of the standard constructions of a new mathematical object from given objects (such as the construction of the direct product of two groups,

(²) For suppose σ had this property. Then $(x, y) = [\sigma(x)]y$ is a nonsingular bilinear form (not necessarily symmetric) in the vectors x, y of L , and we would have, for every $\lambda, (x, y) = [\sigma(x)](y) = [T(\lambda)\sigma\lambda x]y = [\sigma\lambda x]\lambda y = (\lambda x, \lambda y)$, so that the bilinear form is left invariant by every nonsingular linear transformation λ . This is clearly impossible.

the homology group of a complex, the Galois group of a field) furnish a function $T(A, B, \dots) = C$ which assigns to given objects A, B, \dots in definite categories $\mathfrak{A}, \mathfrak{B}, \dots$ a new object C in a category \mathfrak{C} . As in the special case of the conjugate $T(L)$ of a linear space, where there is a corresponding induced mapping $T(\lambda)$, we usually find that mappings α, β, \dots in the categories $\mathfrak{A}, \mathfrak{B}, \dots$ also induce a definite mapping $T(\alpha, \beta, \dots) = \gamma$ in the category \mathfrak{C} , properly acting on the object $T(A, B, \dots)$.

These examples suggest the general concept of a functor T on categories $\mathfrak{A}, \mathfrak{B}, \dots$ to a category \mathfrak{C} , defined as an appropriate pair of functions $T(A, B, \dots), T(\alpha, \beta, \dots)$. Such a functor may well be covariant in some of its arguments, contravariant in the others. The theory of categories and functors, with a few of the illustrations, constitutes Chapter I.

The natural isomorphism $L \rightarrow T^2(L)$ is but one example of many natural equivalences occurring in mathematics. For instance, the isomorphism of a locally compact abelian group with its twice iterated character group, most of the general isomorphisms in group theory and in the homology theory of complexes and spaces, as well as many equivalences in set theory in general topology satisfy a naturality condition resembling (3). In Chapter II, we provide a general definition of equivalence between functors which includes these cases. A more general notion of a transformation of one functor into another provides a means of comparing functors which may not be equivalent. The general concepts are illustrated by several fairly elementary examples of equivalences and transformations for topological spaces, groups, and Banach spaces.

The third chapter deals especially with groups. In the category of groups the concept of a subgroup establishes a natural partial order for the objects (groups) of the category. For a functor whose values are in the category of groups there is an induced partial order. The formation of a quotient group has as analogue the construction of the quotient functor of a given functor by any normal subfunctor. In the uses of group theory, most groups constructed are obtained as quotient groups of other groups; consequently the operation of building a quotient functor is directly helpful in the representation of such group constructions by functors. The first and second isomorphism theorems of group theory are then formulated for functors; incidentally, this is used to show that these isomorphisms are "natural." The latter part of the chapter establishes the naturality of various known isomorphisms and homomorphisms in group theory⁽³⁾.

The fourth chapter starts with a discussion of functors on the category of partially ordered sets, and continues with the discussion of limits of direct and inverse systems of groups, which form the chief topic of this chapter.

⁽³⁾ A brief discussion of this case and of the general theory of functors in the case of groups is given in the authors' note, *Natural isomorphisms in group theory*, Proc. Nat. Acad. Sci. U.S.A. vol. 28 (1942) pp. 537-543.

After suitable categories are introduced, the operations of forming direct and inverse limits of systems of groups are described as functors.

In the fifth chapter we establish the homology and cohomology groups of complexes and spaces as functors and show the naturality of various known isomorphisms of topology, especially those which arise in duality theorems. The treatment of the Čech homology theory utilizes the categories of direct and inverse systems, as discussed in Chapter IV.

The introduction of this study of naturality is justified, in our opinion, both by its technical and by its conceptual advantages.

In the technical sense, it provides the exact hypotheses necessary to apply to both sides of an isomorphism a passage to the limit, in the sense of direct or inverse limits for groups, rings or spaces⁽⁴⁾. Indeed, our naturality condition is part of the standard isomorphism condition for two direct or two inverse systems⁽⁵⁾.

The study of functors also provides a technical background for the intuitive notion of naturality and makes it possible to verify by straightforward computation the naturality of an isomorphism or of an equivalence in all those cases where it has been intuitively recognized that the isomorphisms are indeed "natural." In many cases (for example, as in the above isomorphism of L to $T(L)$) we can also assert that certain known isomorphisms are in fact "unnatural," relative to the class of mappings considered.

In a metamathematical sense our theory provides general concepts applicable to all branches of abstract mathematics, and so contributes to the current trend towards uniform treatment of different mathematical disciplines. In particular, it provides opportunities for the comparison of constructions and of the isomorphisms occurring in different branches of mathematics; in this way it may occasionally suggest new results by analogy.

The theory also emphasizes that, whenever new abstract objects are constructed in a specified way out of given ones, it is advisable to regard the construction of the corresponding induced mappings on these new objects as an integral part of their definition. The pursuit of this program entails a simultaneous consideration of objects and their mappings (in our terminology, this means the consideration not of individual objects but of categories). This emphasis on the specification of the type of mappings employed gives more insight into the degree of invariance of the various concepts involved. For instance, we show in Chapter III, §16, that the concept of the commutator subgroup of a group is in a sense a more invariant one than that of the center,

(4) Such limiting processes are essential in the transition from the homology theory of complexes to that of spaces. Indeed, the general theory developed here occurred to the authors as a result of the study of the admissibility of such a passage in a relatively involved theorem in homology theory (Eilenberg and MacLane, *Group extensions and homology*, Ann. of Math. vol. 43 (1942) pp. 757–831, especially, p. 777 and p. 815).

(5) H. Freudenthal, *Entwicklung von Räumen und ihren Gruppen*, Compositio Math. vol. 4 (1937) pp. 145–234.

which in its turn is more invariant than the concept of the automorphism group of a group, even though in the classical sense all three concepts are invariant.

The invariant character of a mathematical discipline can be formulated in these terms. Thus, in group theory all the basic constructions can be regarded as the definitions of co- or contravariant functors, so we may formulate the dictum: The subject of group theory is essentially the study of those constructions of groups which behave in a covariant or contravariant manner under induced homomorphisms. More precisely, group theory studies functors defined on well specified categories of groups, with values in another such category.

This may be regarded as a continuation of the Klein Erlanger Programm, in the sense that a geometrical space with its group of transformations is generalized to a category with its algebra of mappings.

CHAPTER I. CATEGORIES AND FUNCTORS

1. Definition of categories. These investigations will deal with aggregates such as a class of groups together with a class of homomorphisms, each of which maps one of the groups into another one, or such as a class of topological spaces together with all their continuous mappings, one into another. Consequently we introduce a notion of "category" which will embody the common formal properties of such aggregates.

From the examples "groups plus homomorphisms" or "spaces plus continuous mappings" we are led to the following definition. A *category* $\mathfrak{A} = \{A, \alpha\}$ is an aggregate of abstract elements A (for example, groups), called the *objects* of the category, and abstract elements α (for example, homomorphisms), called *mappings* of the category. Certain pairs of mappings $\alpha_1, \alpha_2 \in \mathfrak{A}$ determine uniquely a product mapping $\alpha = \alpha_2 \alpha_1 \in \mathfrak{A}$, subject to the axioms C1, C2, C3 below. Corresponding to each object $A \in \mathfrak{A}$ there is a unique mapping, denoted by e_A or by $e(A)$, and subject to the axioms C4 and C5. The axioms are:

C1. *The triple product $\alpha_3(\alpha_2\alpha_1)$ is defined if and only if $(\alpha_3\alpha_2)\alpha_1$ is defined. When either is defined, the associative law*

$$\alpha_3(\alpha_2\alpha_1) = (\alpha_3\alpha_2)\alpha_1$$

holds. This triple product will be written as $\alpha_3\alpha_2\alpha_1$.

C2. *The triple product $\alpha_3\alpha_2\alpha_1$ is defined whenever both products $\alpha_3\alpha_2$ and $\alpha_2\alpha_1$ are defined.*

DEFINITION. A mapping $e \in \mathfrak{A}$ will be called an *identity* of \mathfrak{A} if and only if the existence of any product $e\alpha$ or βe implies that $e\alpha = \alpha$ and $\beta e = \beta$.

C3. *For each mapping $\alpha \in \mathfrak{A}$ there is at least one identity $e_1 \in \mathfrak{A}$ such that αe_1*

is defined, and at least one identity $e_2 \in \mathfrak{A}$ such that $e_2\alpha$ is defined.

C4. The mapping e_A corresponding to each object A is an identity.

C5. For each identity e of \mathfrak{A} there is a unique object A of \mathfrak{A} such that $e_A = e$.

These two axioms assert that the rule $A \rightarrow e_A$ provides a one-to-one correspondence between the set of all objects of the category and the set of all its identities. It is thus clear that the objects play a secondary role, and could be entirely omitted from the definition of a category. However, the manipulation of the applications would be slightly less convenient were this done.

LEMMA 1.1. For each mapping $\alpha \in \mathfrak{A}$ there is exactly one object A_1 with the product $\alpha e(A_1)$ defined, and exactly one A_2 with $e(A_2)\alpha$ defined.

The objects A_1, A_2 will be called the *domain* and the *range* of α , respectively. We also say that α acts on A_1 to A_2 , and write

$$\alpha: A_1 \rightarrow A_2 \text{ in } \mathfrak{A}.$$

Proof. Suppose that $\alpha e(A_1)$ and $\alpha e(B_1)$ are both defined. By the properties of an identity, $\alpha e(A_1) = \alpha$, so that axioms C1 and C2 insure that the product $e(A_1)e(B_1)$ is defined. Since both are identities, $e(A_1) = e(A_1)e(B_1) = e(B_1)$, and consequently $A_1 = B_1$. The uniqueness of A_2 is similarly established.

LEMMA 1.2. The product $\alpha_2\alpha_1$ is defined if and only if the range of α_1 is the domain of α_2 . In other words, $\alpha_2\alpha_1$ is defined if and only if $\alpha_1: A_1 \rightarrow A_2$ and $\alpha_2: A_2 \rightarrow A_3$. In that case $\alpha_2\alpha_1: A_1 \rightarrow A_3$.

Proof. Let $\alpha_1: A_1 \rightarrow A_2$. The product $e(A_2)\alpha_1$ is then defined and $e(A_2)\alpha_1 = \alpha_1$. Consequently $\alpha_2\alpha_1$ is defined if and only if $\alpha_2 e(A_2)\alpha_1$ is defined. By axioms C2 and C1 this will hold precisely when $\alpha_2 e(A_2)$ is defined. Consequently $\alpha_2\alpha_1$ is defined if and only if A_2 is the domain of α_2 so that $\alpha_2: A_2 \rightarrow A_3$. To prove that $\alpha_2\alpha_1: A_1 \rightarrow A_3$ note that since $\alpha_1 e(A_1)$ and $e(A_3)\alpha_2$ are defined the products $(\alpha_2\alpha_1)e(A_1)$ and $e(A_3)(\alpha_2\alpha_1)$ are defined.

LEMMA 1.3. If A is an object, $e_A: A \rightarrow A$.

Proof. If we assume that $e(A): A_1 \rightarrow A_2$ then $e(A)e(A_1)$ and $e(A_2)e(A)$ are defined. Since they are all identities it follows that $e(A) = e(A_1) = e(A_2)$ and $A = A_1 = A_2$.

A "left identity" β is a mapping such that $\beta\alpha = \alpha$ whenever $\beta\alpha$ is defined. Axiom C3 shows that every left identity is an identity. Similarly each right identity is an identity. Furthermore, the product ee^1 of two identities is defined if and only if $e = e^1$.

If $\beta\gamma$ is defined and is an identity, β is called a *left inverse* of γ , γ a *right inverse* of β . A mapping α is called an *equivalence* of \mathfrak{A} if it has in \mathfrak{A} at least one left inverse and at least one right inverse.

LEMMA 1.4. *An equivalence α has exactly one left inverse and exactly one right inverse. These inverses are equal, so that the (unique) inverse may be denoted by α^{-1} .*

Proof. It suffices to show that any left inverse β of α equals any right inverse γ . Since $\beta\alpha$ and $\alpha\gamma$ are both defined, $\beta\alpha\gamma$ is defined, by axiom C2. But $\beta\alpha$ and $\alpha\gamma$ are identities, so that $\beta = \beta(\alpha\gamma) = (\beta\alpha)\gamma = \gamma$, as asserted.

For equivalences α, β one easily proves that α^{-1} and $\alpha\beta$ (if defined) are equivalences, and that

$$(\alpha^{-1})^{-1} = \alpha, \quad (\alpha\beta)^{-1} = \beta^{-1}\alpha^{-1}.$$

Every identity e is an equivalence, with $e^{-1} = e$.

Two objects A_1, A_2 are called *equivalent* if there is an equivalence α such that $\alpha: A_1 \rightarrow A_2$. The relation of equivalence between objects is reflexive, symmetric and transitive.

2. Examples of categories. In the construction of examples, it is convenient to use the concept of a subcategory. A subaggregate \mathfrak{A}_0 of \mathfrak{A} will be called a *subcategory* if the following conditions hold:

- 1°. If $\alpha_1, \alpha_2 \in \mathfrak{A}_0$ and $\alpha_2\alpha_1$ is defined in \mathfrak{A} , then $\alpha_2\alpha_1 \in \mathfrak{A}_0$.
- 2°. If $A \in \mathfrak{A}_0$, then $e_A \in \mathfrak{A}_0$.
- 3°. If $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} with $\alpha \in \mathfrak{A}_0$, then $A_1, A_2 \in \mathfrak{A}_0$.

Condition 1° insures that \mathfrak{A}_0 is "closed" with respect to multiplication in \mathfrak{A} ; from conditions 2° and 3° it then follows that \mathfrak{A}_0 is itself a category. The intersection of any number of subcategories of \mathfrak{A} is again a subcategory of \mathfrak{A} . Note, however, that an equivalence $\alpha \in \mathfrak{A}_0$ of \mathfrak{A} need not remain an equivalence in a subcategory \mathfrak{A}_0 , because the inverse α^{-1} may not be in \mathfrak{A}_0 .

For example, if \mathfrak{A} is any category, the aggregate \mathfrak{A}_e of all the objects and all the equivalences of \mathfrak{A} is a subcategory of \mathfrak{A} . Also if \mathfrak{A} is a category and S a subclass of its objects, the aggregate \mathfrak{A}_s consisting of all objects of S and all mappings of \mathfrak{A} with both range and domain in S is a subcategory. In fact, every subcategory of \mathfrak{A} can be obtained in two steps: first, form a subcategory \mathfrak{A}_s ; second, extract from \mathfrak{A}_s a subaggregate, consisting of all the objects of \mathfrak{A}_s and a set of mappings of \mathfrak{A}_s which contains all identities and is closed under multiplication.

The category \mathfrak{S} of all sets has as its objects all sets $S^{(*)}$. A mapping σ of \mathfrak{S} is determined by a pair of sets S_1 and S_2 and a many-one correspondence between S_1 and a subset of S_2 , which assigns to each $x \in S_1$ a corresponding element $\sigma x \in S_2$; we then write $\sigma: S_1 \rightarrow S_2$. (Note that any deletion of elements from S_1 or S_2 changes the mapping σ .) The product of $\sigma_2: S_2^1 \rightarrow S_3$ and $\sigma_1: S_1 \rightarrow S_2$ is defined if and only if $S_2^1 = S_2$; this product then maps S_1 into S_3 by the usual

(*) This category obviously leads to the paradoxes of set theory. A detailed discussion of this aspect of categories appears in §6, below.

composite correspondence $(\sigma_2\sigma_1)x = \sigma_2(\sigma_1x)$; for each $x \in S_1$ ⁽⁷⁾. The mapping e_S corresponding to the set S is the identity mapping of S onto itself, with $e_Sx = x$ for $x \in S$. The axioms C1 through C5 are clearly satisfied. An equivalence $\sigma: S_1 \rightarrow S_2$ is simply a one-to-one mapping of S_1 onto S_2 .

Subcategories of \mathfrak{S} include the category of all finite sets S , with all their mappings as before. For any cardinal number M there are two similar categories, consisting of all sets S of power less than m (or, of power less than or equal to m), together with all their mappings. Subcategories of \mathfrak{S} can also be obtained by restricting the mappings; for instance we may require that each σ is a mapping of S_1 onto S_2 , or that each σ is a one-to-one mapping of S_1 into a subset of S_2 .

The category \mathfrak{X} of all topological spaces has as its objects all topological spaces X and as its mappings all continuous transformations $\xi: X_1 \rightarrow X_2$ of a space X_1 into a space X_2 . The composition $\xi_2\xi_1$ and the identity e_X are both defined as before. An equivalence in \mathfrak{X} is a homeomorphism (= topological equivalence).

Various subcategories of \mathfrak{X} can again be obtained by restricting the type of topological space to be considered, or by restricting the mappings, say to open mappings or to closed mappings⁽⁸⁾.

In particular, \mathfrak{S} can be regarded as a subcategory of \mathfrak{X} , namely, as that subcategory consisting of all spaces with a discrete topology.

The category \mathfrak{G} of all topological groups⁽⁹⁾ has as its objects all topological groups G and as its mappings γ all those many-one correspondences of a group G_1 into a group G_2 which are homomorphisms⁽¹⁰⁾. The composition and the identities are defined as in \mathfrak{S} . An equivalence $\gamma: G_1 \rightarrow G_2$ in \mathfrak{G} turns out to be a one-to-one (bicontinuous) isomorphism of G_1 to G_2 .

Subcategories of \mathfrak{G} can be obtained by restricting the groups (discrete, abelian, regular, compact, and so on) or by restricting the homomorphisms (open homomorphisms, homomorphisms "onto," and so on).

The category \mathfrak{B} of all Banach spaces is similar; its objects are the Banach spaces B , its mappings all linear transformations β of norm at most 1 of one Banach space into another⁽¹¹⁾. Its equivalences are the equivalences between two Banach spaces (that is, one-to-one linear transformations which preserve

(7) This formal associative law allows us to write $\sigma_2\sigma_1x$ without fear of ambiguity. In more complicated formulas, parentheses will be inserted to make the components stand out.

(8) A mapping $\xi: x_1 \rightarrow x_2$ is *open (closed)* if the image under ξ of every open (closed) subset of X is open (closed) in X_2 .

(9) A *topological group* G is a group which is also a topological space in which the group composition and the group inverse are continuous functions (no separation axioms are assumed on the space). If, in addition, G is a Hausdorff space, then all the separation axioms up to and including regularity are satisfied, so that we call G a *regular topological group*.

(10) By a homomorphism we always understand a continuous homomorphism.

(11) For each linear transformation β of the Banach space B_1 into B_2 , the norm $\|\beta\|$ is defined as the least upper bound $\|\beta b\|$, for all $b \in B_1$ with $\|b\| = 1$.

the norm). The assumption above that the mappings of the category \mathfrak{B} all have norm at most 1 is necessary in order to insure that the equivalences in \mathfrak{B} actually preserve the norm. If one admits arbitrary linear transformations as mappings of the category, one obtains a larger category in which the equivalences are the isomorphisms (that is, one-to-one linear transformations)⁽¹²⁾.

For quick reference, we sometimes describe a category by specifying only the object involved (for example, the category of all discrete groups). In such a case, we imply that the mappings of this category are to be all mappings appropriate to the objects in question (for example, all homomorphisms).

3. Functors in two arguments. For simplicity we define only the concept of a functor covariant in one argument and contravariant in another. The generalization to any number of arguments of each type will be immediate.

Let \mathfrak{A} , \mathfrak{B} , and \mathfrak{C} be three categories. Let $T(A, B)$ be an *object-function* which associates with each pair of objects $A \in \mathfrak{A}$, $B \in \mathfrak{B}$ an object $T(A, B) = C$ in \mathfrak{C} , and let $T(\alpha, \beta)$ be a *mapping-function* which associates with each pair of mappings $\alpha \in \mathfrak{A}$, $\beta \in \mathfrak{B}$ a mapping $T(\alpha, \beta) = \gamma \in \mathfrak{C}$. For these functions we formulate certain conditions already indicated in the example in the introduction.

DEFINITION. The object-function $T(A, B)$ and the mapping-function $T(\alpha, \beta)$ form a *functor* T , covariant in \mathfrak{A} and contravariant in \mathfrak{B} , with values in \mathfrak{C} , if

$$(3.1) \quad T(e_A, e_B) = e_{T(A, B)},$$

if, whenever $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} ,

$$(3.2) \quad T(\alpha, \beta): T(A_1, B_2) \rightarrow T(A_2, B_1),$$

and if, whenever $\alpha_2 \alpha_1 \in \mathfrak{A}$ and $\beta_2 \beta_1 \in \mathfrak{B}$,

$$(3.3) \quad T(\alpha_2 \alpha_1, \beta_2 \beta_1) = T(\alpha_2, \beta_1) T(\alpha_1, \beta_2).$$

Condition (3.2) guarantees the existence of the product of mappings appearing on the right in (3.3).

The formulas (3.2) and (3.3) display the distinction between co- and contravariance. The mapping $T(\alpha, \beta) = \gamma$ induced by α and β acts from $T(A_1, -)$ to $T(A_2, -)$; that is, in the same direction as does α , hence the *covariance* of T in the argument \mathfrak{A} . The induced mapping $T(\alpha, \beta)$ at the same time operates in the direction opposite from that of β ; thus it is *contravariant* in \mathfrak{B} . Essentially the same shift in direction is indicated by the orders of the factors in formula (3.3) (the covariant α 's appear in the same order on both sides; the contravariant β 's appear in one order on the left and in the opposite order on the right). With this observation, the requisite formulas for functors in more arguments can be set down.

According to this definition, the functor T is composed of an object func-

⁽¹²⁾ S. Banach, *Théorie des opérations linéaires*, Warsaw, 1932, p. 180.

tion and a mapping function. The latter is the more important of the two; in fact, the condition (3.1) means that it determines the object function and therefore the whole functor, as stated in the following theorem.

THEOREM 3.1. *A function $T(\alpha, \beta)$ which associates to each pair of mappings α and β in the respective categories \mathfrak{A} , \mathfrak{B} a mapping $T(\alpha, \beta) = \gamma$ in a third category \mathfrak{C} is the mapping function of a functor T covariant in \mathfrak{A} and contravariant in \mathfrak{B} if and only if the following two conditions hold:*

(i) $T(e_A, e_B)$ is an identity mapping in \mathfrak{C} for all identities e_A, e_B of \mathfrak{A} and \mathfrak{B} .

(ii) Whenever $\alpha_2\alpha_1 \in \mathfrak{A}$ and $\beta_2\beta_1 \in \mathfrak{B}$, then $T(\alpha_2, \beta_1)T(\alpha_1, \beta_2)$ is defined and satisfies the equation

$$(3.4) \quad T(\alpha_2\alpha_1, \beta_2\beta_1) = T(\alpha_2, \beta_1)T(\alpha_1, \beta_2).$$

If $T(\alpha, \beta)$ satisfies (i) and (ii), the corresponding functor T is uniquely determined, with an object function $T(A, B)$ given by the formula

$$(3.5) \quad e_{T(A, B)} = T(e_A, e_B).$$

Proof. The necessity of (i) and (ii) and the second half of the theorem are obvious.

Conversely, let $T(\alpha, \beta)$ satisfy conditions (i) and (ii). Condition (i) means that an object function $T(A, B)$ can be defined by (3.5). We must show that if $\alpha: A_1 \rightarrow A_2$ and $\beta: B_1 \rightarrow B_2$, then (3.2) holds. Since $e_{(A_2)}\alpha$ and $\beta e_{(B_1)}$ are defined, the product $T(e_{(A_2)}, e_{(B_1)})T(\alpha, \beta)$ is defined; for similar reasons the product $T(\alpha, \beta)T(e_{(A_1)}, e_{(B_2)})$ is defined.

In virtue of the definition (3.5), the products

$$e(T(A_2, B_1))T(\alpha, \beta), \quad T(\alpha, \beta)e(T(A_1, B_2))$$

are defined. This implies (3.2).

In any functor, the replacement of the arguments A, B by equivalent arguments A', B' will replace the value $T(A, B)$ by an equivalent value $T(A', B')$. This fact may be alternatively stated as follows:

THEOREM 3.2. *If T is a functor on $\mathfrak{A}, \mathfrak{B}$ to \mathfrak{C} , and if $\alpha \in \mathfrak{A}$ and $\beta \in \mathfrak{B}$ are equivalences, then $T(\alpha, \beta)$ is an equivalence in \mathfrak{C} , with the inverse $T(\alpha, \beta)^{-1} = T(\alpha^{-1}, \beta^{-1})$.*

For the proof we assume that T is covariant in \mathfrak{A} and contravariant in \mathfrak{B} . The products $\alpha\alpha^{-1}$ and $\alpha^{-1}\alpha$ are then identities, and the definition of a functor shows that

$$T(\alpha, \beta)T(\alpha^{-1}, \beta^{-1}) = T(\alpha\alpha^{-1}, \beta^{-1}\beta), \quad T(\alpha^{-1}, \beta^{-1})T(\alpha, \beta) = T(\alpha^{-1}\alpha, \beta\beta^{-1}).$$

By condition (3.1), the terms on the right are both identities, which means that $T(\alpha^{-1}, \beta^{-1})$ is an inverse for $T(\alpha, \beta)$, as asserted.

4. Examples of functors. The same object function may appear in various

functors, as is shown by the following example of one covariant and one contravariant functor both with the same object function. In the category \mathfrak{S} of all sets, the "power" functors P^+ and P^- have the object function

$$P^+(S) = P^-(S) = \text{the set of all subsets of } S.$$

For any many-one correspondence $\sigma: S_1 \rightarrow S_2$ the respective mapping functions are defined for any subset $A_1 \subset S_1$ (or $A_2 \subset S_2$) as⁽¹³⁾

$$P^+(\sigma)A_1 = \sigma A_1, \quad P^-(\sigma)A_2 = \sigma^{-1}A_2.$$

It is immediate that P^+ is a covariant functor and P^- a contravariant one.

The cartesian product $X \times Y$ of two topological spaces is the object function of a functor of two covariant variables X and Y in the category \mathfrak{X} of all topological spaces. For continuous transformations $\xi: X_1 \rightarrow X_2$ and $\eta: Y_1 \rightarrow Y_2$ the corresponding mapping function $\xi \times \eta$ is defined for any point (x_1, y_1) in the cartesian product $X_1 \times Y_1$ as

$$\xi \times \eta(x_1, y_1) = (\xi x_1, \eta y_1).$$

One verifies that

$$\xi \times \eta: X_1 \times Y_1 \rightarrow X_2 \times Y_2,$$

that $\xi \times \eta$ is the identity mapping of $X_1 \times Y_1$ into itself when ξ and η are both identities, and that

$$(\xi_2 \xi_1) \times (\eta_2 \eta_1) = (\xi_2 \times \eta_2)(\xi_1 \times \eta_1)$$

whenever the products $\xi_2 \xi_1$ and $\eta_2 \eta_1$ are defined. In virtue of these facts, the functions $X \times Y$ and $\xi \times \eta$ constitute a covariant functor of two variables on the category \mathfrak{X} .

The direct product of two groups is treated in exactly similar fashion; it gives a functor with the set function $G \times H$ and the mapping function $\gamma \times \eta$, defined for $\gamma: G_1 \rightarrow G_2$ and $\eta: H_1 \rightarrow H_2$ exactly as was $\xi \times \eta$. The same applies to the category \mathfrak{B} of Banach spaces, provided one fixes one of the usual possible definite procedures of norming the cartesian product of two Banach spaces.

For a topological space Y and a locally compact (=locally bicomact) Hausdorff space X one may construct the space Y^X of all continuous mappings f of the whole space X into Y ($fx \in Y$ for $x \in X$). A topology is assigned to Y^X as follows. Let C be any compact subset of X , U any open set in Y . Then the set $[C, U]$ of all $f \in Y^X$ with $fC \subset U$ is an open set in Y^X , and the most general open set in Y^X is any union of finite intersections $[C_1, U_1] \cap \dots \cap [C_n, U_n]$.

This space Y^X may be regarded as the object function of a suitable functor, $\text{Map}(X, Y)$. To construct a suitable mapping function, consider any

⁽¹³⁾ Here σA_1 is the set of all elements of S_2 of the form σx for $x \in A_1$, while $\sigma^{-1}A_2$ consists of all elements $x \in S_1$ with $\sigma x \in A_2$. When σ is an equivalence, with an inverse τ , $\tau A_2 = \sigma^{-1}A_2$, so that no ambiguity as to the meaning of σ^{-1} can arise.

continuous transformations $\xi: X_1 \rightarrow X_2, \eta: Y_1 \rightarrow Y_2$. For each $f \in Y_1^{X_2}$, one then has mappings acting thus:

$$X_1 \xrightarrow{\xi} X_2 \xrightarrow{f} Y_1 \xrightarrow{\eta} Y_2,$$

so that one may derive a continuous transformation $\eta f \xi$ of $Y_2^{X_1}$. This correspondence $f \rightarrow \eta f \xi$ may be shown to be a continuous mapping of $Y_1^{X_2}$ into $Y_2^{X_1}$. Hence we may define object and mapping functions "Map" by setting

$$(4.1) \quad \text{Map}(X, Y) = Y^X, \quad [\text{Map}(\xi, \eta)]f = \eta f \xi.$$

The construction shows that

$$\text{Map}(\xi, \eta): \text{Map}(X_2, Y_1) \rightarrow \text{Map}(X_1, Y_2),$$

and hence suggests that this functor is contravariant in X and covariant in Y . One observes at once that $\text{Map}(\xi, \eta)$ is an identity when both ξ and η are identities. Furthermore, if the products $\xi_2 \xi_1$ and $\eta_2 \eta_1$ are defined, the definition of "Map" gives first,

$$[\text{Map}(\xi_2 \xi_1, \eta_2 \eta_1)]f = \eta_2 \eta_1 f \xi_2 \xi_1 = \eta_2(\eta_1 f \xi_2) \xi_1,$$

and second,

$$\text{Map}(\xi_1, \eta_2) \text{Map}(\xi_2, \eta_1)f = [\text{Map}(\xi_1, \eta_2)]\eta_1 f \xi_2 = \eta_2(\eta_1 f \xi_2) \xi_1.$$

Consequently

$$\text{Map}(\xi_2 \xi_1, \eta_2 \eta_1) = \text{Map}(\xi_1, \eta_2) \text{Map}(\xi_2, \eta_1),$$

which completes the verification that "Map," defined as in (4.1), is a functor on $\mathfrak{X}_{lc}, \mathfrak{X}$ to \mathfrak{X} , contravariant in the first variable, covariant in the second, where \mathfrak{X}_{lc} denotes the subcategory of \mathfrak{X} defined by the locally compact Hausdorff spaces.

For abelian groups there is a similar functor "Hom." Specifically, let G be a locally compact regular topological group, H a topological abelian group. We construct the set $\text{Hom}(G, H)$ of all (continuous) homomorphisms ϕ of G into H . The sum of two such homomorphisms ϕ_1 and ϕ_2 is defined by setting $(\phi_1 + \phi_2)g = \phi_1 g + \phi_2 g$, for each $g \in G^{(14)}$; this sum is itself a homomorphism because H is abelian.

Under this addition, $\text{Hom}(G, H)$ is an abelian group. It is topologized by the family of neighborhoods $[C, U]$ of zero defined as follows. Given C , any compact subset of G , and U , any open set in H containing the zero of H , $[C; U]$ consists of all $\phi \in \text{Hom}(G, H)$ with $\phi C \subset U$. With these definitions, $\text{Hom}(G, H)$ is a topological group. If H has a neighborhood of the identity containing no subgroup but the trivial one, one may prove that $\text{Hom}(G, H)$ is locally compact.

(14) The group operation in G, H , and so on, will be written as addition.

This function of groups is the object function of a functor "Hom." For given $\gamma:G_1\rightarrow G_2$ and $\eta:H_1\rightarrow H_2$ the mapping function is defined by setting

$$(4.2) \quad [\text{Hom}(\gamma, \eta)]\phi = \eta\phi\gamma$$

for each $\phi\in\text{Hom}(G_2, H_1)$. Formally, this definition is exactly like (4.1). One may show that this definition (4.2) does yield a continuous homomorphism

$$\text{Hom}(\gamma, \eta):\text{Hom}(G_2, H_1) \rightarrow \text{Hom}(G_1, H_2).$$

As in the previous case, Hom is a functor with values in the category \mathfrak{G}_a of abelian groups, defined for arguments in two appropriate subcategories of \mathfrak{G} , contravariant in the first argument, G , and covariant in the second, H .

For Banach spaces there is a similar functor. If B and C are two Banach spaces, let $\text{Lin}(B, C)$ denote the Banach space of all linear transformations λ of B into C , with the usual definition of the norm of the transformation. To describe the corresponding mapping function, consider any linear transformations $\beta:B_1\rightarrow B_2$ and $\gamma:C_1\rightarrow C_2$ with $\|\beta\|\leq 1$ and $\|\gamma\|\leq 1$, and set, for each $\lambda\in\text{Lin}(B_2, C_1)$,

$$(4.3) \quad [\text{Lin}(\beta, \gamma)]\lambda = \gamma\lambda\beta.$$

This is in fact a linear transformation

$$\text{Lin}(\beta, \gamma):\text{Lin}(B_2, C_1) \rightarrow \text{Lin}(B_1, C_2)$$

of norm at most 1. As in the previous cases, Lin is a functor on \mathfrak{B} , \mathfrak{B} to \mathfrak{B} , contravariant in its first argument and covariant in the second.

In case C is fixed to be the Banach space R of all real numbers with the absolute value as norm, $\text{Lin}(B, C)$ is just the Banach space conjugate to B , in the usual sense. This leads at once to the functor

$$\text{Conj}(B) = \text{Lin}(B, R), \quad \text{Conj}(\beta) = \text{Lin}(\beta, e_R).$$

This is a contravariant functor on \mathfrak{B} to \mathfrak{B} .

Another example of a functor on groups is the tensor product $G \circ H$ of two abelian groups. This functor has been discussed in more detail in our Proceedings note cited above.

5. Slicing of functors. The last example involved the process of holding one of the arguments of a functor constant. This process occurs elsewhere (for example, in the character group theory, Chapter III below), and falls at once under the following theorem.

THEOREM 5.1. *If T is a functor covariant in \mathfrak{A} , contravariant in \mathfrak{B} , with values in \mathfrak{C} , then for each fixed $B\in\mathfrak{B}$ the definitions*

$$S(A) = T(A, B), \quad S(\alpha) = T(\alpha, e_B)$$

yield a functor S on \mathfrak{A} to \mathfrak{C} with the same variance (in \mathfrak{A}) as T .

This “slicing” of a functor may be partially inverted, in that the functor T is determined by its object function and its two “sliced” mapping functions, in the following sense.

THEOREM 5.2. *Let \mathfrak{A} , \mathfrak{B} , \mathfrak{C} be three categories and $T(A, B)$, $T(\alpha, B)$, $T(A, \beta)$ three functions such that for each fixed $B \in \mathfrak{B}$ the functions $T(A, B)$, $T(\alpha, B)$ form a covariant functor on \mathfrak{A} to \mathfrak{C} , while for each $A \in \mathfrak{A}$ the functions $T(A, B)$ and $T(A, \beta)$ give a contravariant functor on \mathfrak{B} to \mathfrak{C} . If in addition for each $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} we have*

$$(5.1) \quad T(A_2, \beta)T(\alpha, B_2) = T(\alpha, B_1)T(A_1, \beta),$$

then the functions $T(A, B)$ and

$$(5.2) \quad T(\alpha, \beta) = T(\alpha, B_1)T(A_1, \beta)$$

form a functor covariant in \mathfrak{A} , contravariant in \mathfrak{B} , with values in \mathfrak{C} .

Proof. The condition (5.1) merely states the equivalence of the two paths about the following square:

$$\begin{array}{ccc}
 T(A_1, B_2) & \xrightarrow{T(\alpha, B_2)} & T(A_2, B_2) \\
 \downarrow T(A_1, \beta) & & \downarrow T(A_2, \beta) \\
 T(A_1, B_1) & \xrightarrow{T(\alpha, B_1)} & T(A_2, B_1)
 \end{array}$$

The result of either path is then taken in (5.2) to define the mapping function, which then certainly satisfies conditions (3.1) and (3.2) of the definition of a functor. The proof of the basic product condition (3.3) is best visualized by writing out a 3×3 array of values $T(A_i, B_j)$.

The significance of this theorem is essentially this: in verifying that given object and mapping functions do yield a functor, one may replace the verification of the product condition (3.3) in two variables by a separate verification, one variable at a time, provided one *also* proves that the order of application of these one-variable mappings can be interchanged (condition (5.1)).

6. Foundations. We remarked in §3 that such examples as the “category of all sets,” the “category of all groups” are illegitimate. The difficulties and antinomies here involved are exactly those of ordinary intuitive *Mengenlehre*; no essentially new paradoxes are apparently involved. Any rigorous foundation capable of supporting the ordinary theory of classes would equally well support our theory. Hence we have chosen to adopt the intuitive standpoint, leaving the reader free to insert whatever type of logical foundation (or absence thereof) he may prefer. These ideas will now be illustrated, with particular reference to the category of groups.

It should be observed first that the whole concept of a category is essentially an auxiliary one; our basic concepts are essentially those of a *functor* and of a natural transformation (the latter is defined in the next chapter). The idea of a category is required only by the precept that every function should have a definite class as domain and a definite class as range, for the categories are provided as the domains and ranges of functors. Thus one could drop the category concept altogether and adopt an even more intuitive standpoint, in which a functor such as "Hom" is not defined over the category of "all" groups, but for each particular pair of groups which may be given. The standpoint would suffice for the applications, inasmuch as none of our developments will involve elaborate constructions on the categories themselves.

For a more careful treatment, we may regard a group G as a pair, consisting of a set G_0 and a ternary relation $g \cdot h = k$ on this set, subject to the usual axioms of group theory. This makes explicit the usual tacit assumption that a group is not just the set of its elements (two groups can have the *same* elements, yet different operations). If a pair is constructed in the usual manner as a certain class, this means that each subcategory of the category of "all" groups is a class of pairs; each pair being a class of groups with a class of mappings (binary relations). Any given system of foundations will then legitimize those subcategories which are allowable classes in the system in question.

Perhaps the simplest precise device would be to speak not of *the* category of groups, but of *a* category of groups (meaning, any legitimate such category). A functor such as "Hom" is then a functor which can be defined for any two suitable categories of groups, \mathfrak{G} and \mathfrak{H} . Its values lie in a third category of groups, which will in general include groups in neither \mathfrak{G} nor \mathfrak{H} . This procedure has the advantage of precision, the disadvantage of a multiplicity of categories and of functors. This multiplicity would be embarrassing in the study of composite functors (§9 below).

One might choose to adopt the (unramified) theory of types as a foundation for the theory of classes. One then can speak of the category \mathfrak{G}_m of all abelian groups of type m . The functor "Hom" could then have both arguments in \mathfrak{G}_m , while its values would be in the same category \mathfrak{G}_{m+k} of groups of higher type $m+k$. This procedure affects each functor with the same sort of typical ambiguity adhering to the arithmetical concepts in the Whitehead-Russell development. Isomorphism between groups of different types would have to be considered, as in the simple isomorphism $\text{Hom}(\mathfrak{Z}, G) \cong G$ (see §10); this would somewhat complicate the natural isomorphisms treated below.

One can also choose a set of axioms for classes as in the Fraenkel-von Neumann-Bernays system. A category is then any (legitimate) class in the sense of this axiomatics. Another device would be that of restricting the cardinal number, considering the category of all denumerable groups, of all groups of cardinal at most the cardinal of the continuum, and so on. The subsequent

developments may be suitably interpreted under any one of these viewpoints.

CHAPTER II. NATURAL EQUIVALENCE OF FUNCTORS

7. Transformations of functors. Let T and S be two functors on \mathfrak{A} , \mathfrak{B} to \mathfrak{C} which are *concordant*; that is, which have the same variance in \mathfrak{A} and the same variance in \mathfrak{B} . To be specific, assume both T and S covariant in \mathfrak{A} and contravariant in \mathfrak{B} . Let τ be a function which associates to each pair of objects $A \in \mathfrak{A}$, $B \in \mathfrak{B}$ a mapping $\tau(A, B) = \gamma$ in \mathfrak{C} .

DEFINITION. The function τ is a "natural" transformation of the functor T , covariant in \mathfrak{A} and contravariant in \mathfrak{B} , into the concordant functor S provided that, for each pair of objects $A \in \mathfrak{A}$, $B \in \mathfrak{B}$,

$$(7.1) \quad \tau(A, B): T(A, B) \rightarrow S(A, B) \text{ in } \mathfrak{C},$$

and provided, whenever $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} , that

$$(7.2) \quad \tau(A_2, B_1)T(\alpha, \beta) = S(\alpha, \beta)\tau(A_1, B_2).$$

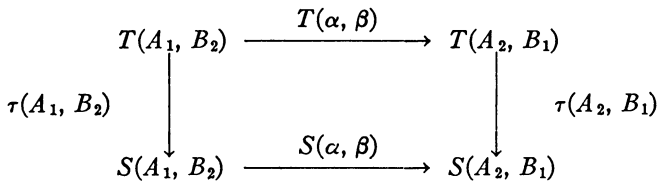
When these conditions hold, we write

$$\tau: T \rightarrow S.$$

If in addition each $\tau(A, B)$ is an equivalence mapping of the category \mathfrak{C} , we call τ a *natural equivalence* of T to S (notation: $\tau: T \rightleftarrows S$) and say that the functors T and S are *naturally equivalent*. In this case condition (7.2) can be rewritten as

$$(7.2a) \quad \tau(A_2, B_1)T(\alpha, \beta)[\tau(A_1, B_2)]^{-1} = S(\alpha, \beta).$$

Condition (7.1) of this definition is equivalent to the requirement that both products in (7.2) are always defined. Condition (7.2) is illustrated by the equivalence of the two paths indicated in the following diagram :



Given three concordant functors T , S and R on \mathfrak{A} , \mathfrak{B} to \mathfrak{C} , with natural transformations $\tau: T \rightarrow S$ and $\sigma: S \rightarrow R$, the product

$$\rho(A, B) = \sigma(A, B)\tau(A, B)$$

is defined as a mapping in \mathfrak{C} , and yields a natural transformation $\rho: T \rightarrow R$. If τ and σ are natural equivalences, so is $\rho = \sigma\tau$.

Observe also that if $\tau: T \rightarrow S$ is a natural equivalence, then the function τ^{-1} defined by $\tau^{-1}(A, B) = [\tau(A, B)]^{-1}$ is a natural equivalence $\tau^{-1}: S \rightarrow T$. Given any functor T on \mathfrak{A} , \mathfrak{B} to \mathfrak{C} , the function

$$\tau_0(A, B) = e_{T(A, B)}$$

is a natural equivalence $\tau_0: T \rightleftharpoons T$. These remarks imply that the concept of natural equivalence of functors is reflexive, symmetric and transitive.

In demonstrating that a given mapping $\tau(A, B)$ is actually a natural transformation, it suffices to prove the rule (7.2) only in these cases in which all except one of the mappings α, β, \dots is an identity. To state this result it is convenient to introduce a simplified notation for the mapping function when one argument is an identity, by setting

$$T(\alpha, B) = T(\alpha, e_B), \quad T(A, \beta) = T(e_A, \beta).$$

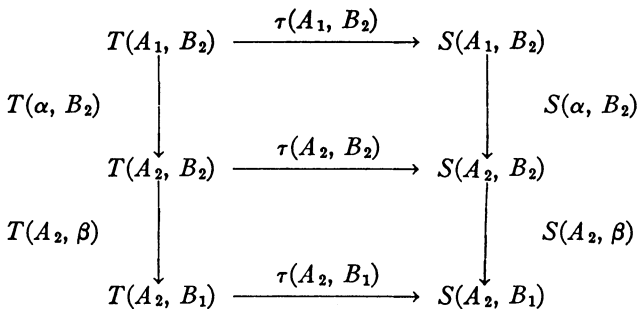
THEOREM 7.1. *Let T and S be functors covariant in \mathfrak{A} and contravariant in \mathfrak{B} , with values in \mathfrak{C} , and let τ be a function which associates to each pair of objects $A \in \mathfrak{A}, B \in \mathfrak{B}$ a mapping with (7.1). A necessary and sufficient condition that τ be a natural transformation $\tau: T \rightarrow S$ is that for each mapping $\alpha: A_1 \rightarrow A_2$ and each object $B \in \mathfrak{B}$ one has*

$$(7.3) \quad \tau(A_2, B)T(\alpha, B) = S(\alpha, B)\tau(A_1, B),$$

and that, for each $A \in \mathfrak{A}$ and each $\beta: B_1 \rightarrow B_2$ one has

$$(7.4) \quad \tau(A, B_1)T(A, \beta) = S(A, \beta)\tau(A, B_2).$$

Proof. The necessity of these conditions is obvious, since they are simply the special cases of (7.2) in which $\beta = e_B$ and $\alpha = e_A$, respectively. The sufficiency can best be illustrated by the following diagram, applying to any mappings $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} :



Condition (7.3) states the equivalence of the results found by following either path around the upper small rectangle, and condition (7.4) makes a similar assertion for the bottom rectangle. Combining these successive equivalences, we have the equivalence of the two paths around the edges of the whole rectangle; this is the requirement (7.2). This argument can be easily set down formally.

8. Categories of functors. The functors may be made the objects of a category in which the mappings are natural transformations. Specifically, given three fixed categories \mathfrak{A} , \mathfrak{B} and \mathfrak{C} , form the category \mathfrak{X} for which the objects are the functors T covariant in \mathfrak{A} and contravariant in \mathfrak{B} , with values in \mathfrak{C} , and for which the mappings are the natural transformations $\tau: T \rightarrow S$. This requires some caution, because we may have $\tau: T \rightarrow S$ and $\tau: T' \rightarrow S'$ for the same function τ with different functors T, T' (which would have the same object function but different mapping functions). To circumvent this difficulty we define a mapping in the category T to be a triple $[\tau, T, S]$ with $\tau: T \rightarrow S$. The product of mappings $[\tau, T, S]$ and $[\sigma, S', R]$ is defined if and only if $S = S'$; in this case it is

$$[\sigma, S, R][\tau, T, S] = [\sigma\tau, T, R].$$

We verify that the axioms C1-C3 of §1 are satisfied. Furthermore we define, for each functor T ,

$$e_T = [\tau_T, T, T], \quad \text{with} \quad \tau_T(A, B) = e_{T(A, B)},$$

and verify the remaining axioms C4, C5. Consequently \mathfrak{X} is a category. In this category it can be proved easily that $[\tau, T, S]$ is an equivalence mapping if and only if $\tau: T \rightleftharpoons S$; consequently the concept of the natural equivalence of functors agrees with the concept of equivalence of objects in the category \mathfrak{X} of functors.

This category \mathfrak{X} is useful chiefly in simplifying the statements and proofs of various facts about functors, as will appear subsequently.

9. Composition of functors. This process arises by the familiar "function of a function" procedure, in which for the argument of a functor we substitute the value of another functor. For example, let T be a functor on $\mathfrak{A}, \mathfrak{B}$ to \mathfrak{C} , R a functor on $\mathfrak{C}, \mathfrak{D}$ to \mathfrak{E} . Then $S = R \otimes (T, I)$, defined by setting

$$S(A, B, D) = R(T(A, B), D), \quad S(\alpha, \beta, \delta) = R(T(\alpha, \beta), \delta),$$

for objects $A \in \mathfrak{A}, B \in \mathfrak{B}, D \in \mathfrak{D}$ and mappings $\alpha \in \mathfrak{A}, \beta \in \mathfrak{B}, \delta \in \mathfrak{D}$, is a functor on $\mathfrak{A}, \mathfrak{B}, \mathfrak{D}$ to \mathfrak{E} . In the argument \mathfrak{D} , the variance of S is just the variance of R . The variance of R in \mathfrak{A} (or \mathfrak{B}) may be determined by the rule of signs (with $+$ for covariance, $-$ for contravariance): variance of S in $\mathfrak{A} =$ variance of R in $\mathfrak{C} \times$ variance of T in \mathfrak{A} .

Composition can also be applied to natural transformations. To simplify the notation, assume that R is a functor in *one* variable, contravariant on \mathfrak{C} to \mathfrak{E} , and that T is covariant in \mathfrak{A} , contravariant in \mathfrak{B} with values in \mathfrak{C} . The composite $R \otimes T$ is then contravariant in \mathfrak{A} , covariant in \mathfrak{B} . Any pair of natural transformations

$$\rho: R \rightarrow R', \quad \tau = T \rightarrow T'$$

gives rise to a natural transformation

$$\rho \otimes \tau: R \otimes T' \rightarrow R' \otimes T$$

defined by setting

$$\rho \otimes \tau(A, B) = \rho(T(A, B))R(\tau(A, B)).$$

Because ρ is natural, $\rho \otimes \tau$ could equally well be defined as

$$\rho \otimes \tau(A, B) = R'(\tau(A, B))\rho(T'(A, B)).$$

This alternative means that the passage from $R \otimes T'(A, B)$ to $R' \otimes T(A, B)$ can be made either through $R \otimes T(A, B)$ or through $R' \otimes T'(A, B)$, without altering the final result. The resulting *composite transformation* $\rho \otimes \tau$ has all the usual formal properties appropriate to the mapping function of the "functor" $R \otimes T$; specifically,

$$(\rho_2 \rho_1) \otimes (\tau_1 \tau_2) = (\rho_2 \otimes \tau_2)(\rho_1 \otimes \tau_1),$$

as may be verified by a suitable 3×3 diagram.

These properties show that the functions $R \otimes T$ and $\rho \otimes \tau$ determine a functor C , defined on the categories \mathfrak{R} and \mathfrak{T} of functors, with values in a category \mathfrak{S} of functors, covariant in \mathfrak{R} and contravariant in \mathfrak{T} (because of the contravariance of R). Here \mathfrak{R} is the category of all contravariant functors R on \mathfrak{C} to \mathfrak{E} , while \mathfrak{S} and \mathfrak{T} are the categories of all functors S and T , of appropriate variances, respectively. In each case, the mappings of the category of functors are natural transformations, as described in the previous section. To be more explicit, the mapping function $C(\rho, \tau)$ of this functor is not the simple composite $\rho \otimes \tau$, but the triple $[\rho \otimes \tau, R \otimes T', R' \otimes T]$.

Since $\rho \otimes \tau$ is essentially the mapping function of a functor, we know by Theorem 3.2 that if ρ and τ are natural equivalences, then $\rho \otimes \tau$ is an equivalence. Consequently, if the pairs R and R' , T and T' are naturally equivalent, so is the pair of composites $R \otimes T$ and $R' \otimes T'$.

It is easy to verify that the composition of functors and of natural transformations is associative, so that symbols like $R \otimes T \otimes S$ may be written without parentheses.

If in the definition of $\rho \otimes \tau$ above it occurs that $T = T'$ and that τ is the identity transformation $T \rightarrow T$ we shall write $\rho \otimes T$ instead of $\rho \otimes \tau$. Similarly we shall write $R \otimes \tau$ instead of $\rho \otimes \tau$ in the case when $R = R'$ and ρ is the identity transformation $R \rightarrow R$.

10. Examples of transformations. The associative and commutative laws for the direct and cartesian products are isomorphisms which can be regarded as equivalences between functors. For example, let X , Y and Z be three topological spaces, and let the homeomorphism

$$(10.1) \quad (X \times Y) \times Z \cong X \times (Y \times Z)$$

be established by the usual correspondence $\tau = \tau(X, Y, Z)$, defined for any

point $((x, y), z)$ in the iterated cartesian product $(X \times Y) \times Z$ by

$$\tau(X, Y, Z)((x, y), z) = (x, (y, z)).$$

Each $\tau(X, Y, Z)$ is then an equivalence mapping in the category \mathfrak{X} of spaces. Furthermore each side of (10.1) may be considered as the object function of a covariant functor obtained by composition of the cartesian product functor with itself. The corresponding mapping functions are obtained by the parallel composition as $(\xi \times \eta) \times \zeta$ and $\xi \times (\eta \times \zeta)$. To show that $\tau(X, Y, Z)$ is indeed a natural equivalence, we consider three mappings $\xi: X_1 \rightarrow X_2$, $\eta: Y_1 \rightarrow Y_2$ and $\zeta: Z_1 \rightarrow Z_2$, and show that

$$\tau(X_2, Y_2, Z_2)[(\xi \times \eta) \times \zeta] = [\xi \times (\eta \times \zeta)]\tau(X_1, Y_1, Z_1).$$

This identity may be verified by applying each side to an arbitrary point $((x_1, y_1), z_1)$ in the space $(X_1 \times Y_1) \times Z_1$; each transforms it into the point $(\xi x_1, (\eta y_1, \zeta z_1))$ in $X_2 \times (Y_2 \times Z_2)$.

In similar fashion the homeomorphism $X \times Y \cong Y \times X$ may be interpreted as a natural equivalence, defined as $\tau(X, Y)(x, y) = (y, x)$. In particular, if X, Y and Z are discrete spaces (that is, are simply sets), these remarks show that the associative and commutative laws for the (cardinal) product of two sets are natural equivalences between functors.

For similar reasons, the associative and commutative laws for the direct product of groups are natural equivalences (or *natural isomorphisms*) between functors of groups. The same laws for Banach spaces, with a fixed convention as to the construction of the norm in the cartesian product of two such spaces, are natural equivalences between functors.

If J is the (fixed) additive group of integers, H any topological abelian group, there is an isomorphism

$$(10.2) \quad \text{Hom}(J, H) \cong H$$

in which both sides may be regarded as covariant functors of a single argument H . This isomorphism $\tau = \tau(H)$ is defined for any homomorphism $\phi \in \text{Hom}(J, H)$ by setting $\tau(H)\phi = \phi(1) \in H$. One observes that $\tau(H)$ is indeed a (bicontinuous) isomorphism, that is, an equivalence in the category of topological abelian groups. That $\tau(H)$ actually is a natural equivalence between functors is shown by proving, for any $\eta: H_1 \rightarrow H_2$, that

$$\tau(H_2) \text{Hom}(e_J, \eta) = \eta \tau(H_1).$$

There is also a second natural equivalence between the functors indicated in (10.2), obtained by setting $\tau'(H)\phi = \phi(-1)$.

With the fixed Banach space R of real numbers there is a similar formula

$$(10.3) \quad \text{Lin}(R, B) \cong B$$

for any Banach space B . This gives a natural equivalence $\tau = \tau(B)$ between

two covariant functors of one argument in the category \mathfrak{B} of all Banach spaces. Here $\tau(B)$ is defined by setting $\tau(B)l=l(1)$ for each linear transformation $l \in \text{Lin}(R, B)$; another choice of τ would set $\tau(B)l=l(-1)$.

For topological spaces there is a distributive law for the functors "Map" and the direct product functor, which may be written as a natural equivalence

$$(10.4) \quad \text{Map}(Z, X) \times \text{Map}(Z, Y) \cong \text{Map}(Z, X \times Y)$$

between two composite functors, each contravariant in the first argument Z and covariant in the other two arguments X and Y . To define this natural equivalence

$$\tau(X, Y, Z): \text{Map}(Z, X) \times \text{Map}(Z, Y) \rightleftharpoons \text{Map}(Z, X \times Y),$$

consider any pair of mappings $f \in \text{Map}(Z, X)$ and $g \in \text{Map}(Z, Y)$ and set, for each $z \in Z$,

$$[\tau(f, g)](z) = (f(z), g(z)).$$

It can be shown that this definition does indeed give the homeomorphism (10.4). It is furthermore natural, which means that, for mappings $\xi: X_1 \rightarrow X_2$, $\eta: Y_1 \rightarrow Y_2$ and $\zeta: Z_1 \rightarrow Z_2$,

$$\tau(X_2, Y_2, Z_1)[\text{Map}(\zeta, \xi) \times \text{Map}(\zeta, \eta)] = \text{Map}(\zeta, \xi \times \eta)\tau(X_1, Y_1, Z_2).$$

The proof of this statement is a straightforward application of the various definitions involved. Both sides are mappings carrying $\text{Map}(Z_2, X_1) \times \text{Map}(Z_2, Y_1)$ into $\text{Map}(Z_1, X_2 \times Y_2)$. They will be equal if they give identical results when applied to an arbitrary element (f_2, g_2) in the first space. These applications give, by the definition of the mapping functions of the functors "Map" and " \times ," the respective elements

$$\tau(X_2, Y_2, Z_1)(\xi f_2 \zeta, \eta g_2 \zeta), \quad (\xi \times \eta)\tau(X_1, Y_1, Z_2)(f_2, g_2)\zeta.$$

Both are in $\text{Map}(Z_1, X_2 \times Y_2)$. Applied to an arbitrary $z \in Z_1$, we obtain in both cases, by the definition of τ , the same element $(\xi f_2 \zeta(z), \eta g_2 \zeta(z)) \in X_2 \times Y_2$.

For groups and Banach spaces there are analogous natural equivalences

$$(10.5) \quad \text{Hom}(G, H) \times \text{Hom}(G, K) \cong \text{Hom}(G, H \times K),$$

$$(10.6) \quad \text{Lin}(B, C) \times \text{Lin}(B, D) \cong \text{Lin}(B, C \times D).$$

In each case the equivalence is given by a transformation defined exactly as before. In the formula for Banach spaces we assume that the direct product is normed by the maximum formula. In the case of any other formula for the norm in a direct product, we can assert only that τ is a one-to-one linear transformation of norm one, but not necessarily a transformation preserving the norm. In such a case τ then gives merely a natural transformation of the functor on the left into the functor on the right.

For groups there is another type of distributive law, which is an equivalence transformation,

$$\text{Hom}(G, K) \times \text{Hom}(H, K) \cong \text{Hom}(G \times H, K).$$

The transformation $\tau(G, H, K)$ is defined for each pair $(\phi, \psi) \in \text{Hom}(G, K) \times \text{Hom}(H, K)$ by setting

$$[\tau(G, H, K)(\phi, \psi)](g, h) = \phi g + \psi h$$

for every element (g, h) in the direct product $G \times H$. The properties of τ are proved as before.

It is well known that a function $g(x, y)$ of two variables x and y may be regarded as a function τg of the first variable x for which the values are in turn functions of the second variable y . In other words, τg is defined by

$$[[\tau g](x)](y) = g(x, y).$$

It may be shown that the correspondence $g \rightarrow \tau g$ does establish a homeomorphism between the spaces

$$Z^{X \times Y} \cong (Z^Y)^X,$$

where Z is any topological space and X and Y are locally compact Hausdorff spaces. This is a "natural" homeomorphism, because the correspondence $\tau = \tau(X, Y, Z)$ defined above is actually a natural equivalence

$$\tau(X, Y, Z) : \text{Map}(X \times Y, Z) \rightleftarrows \text{Map}(X, \text{Map}(Y, Z))$$

between the two composite functors whose object functions are displayed here.

To prove that τ is natural, we consider any mappings $\xi : X_1 \rightarrow X_2, \eta : Y_1 \rightarrow Y_2, \zeta : Z_1 \rightarrow Z_2$, and show that

$$(10.7) \quad \tau(X_1, Y_1, Z_2) \text{Map}(\xi \times \eta, \zeta) = \text{Map}(\xi, \text{Map}(\eta, \zeta))\tau(X_2, Y_2, Z_1).$$

Each side of this equation is a mapping which applies to any element $g_2 \in \text{Map}(X_2 \times Y_2, Z_1)$ to give an element of $\text{Map}(X_1, \text{Map}(Y_1, Z_2))$. The resulting elements may be applied to an $x_1 \in X_1$ to give an element of $\text{Map}(Y_1, Z_2)$, which in turn may be applied to any $y_1 \in Y_1$. If each side of (10.7) is applied in this fashion, and simplified by the definitions of τ and of the mapping functions of the functors involved, one obtains in both cases the same element $\zeta g_2(\xi x_1, \eta y_1) \in Z_2$. Hence (10.7) holds, and τ is natural.

Incidentally, the analogous formula for groups uses the tensor product $G \circ H$ of two groups, and gives an equivalence transformation

$$\text{Hom}(G \circ H, K) \cong \text{Hom}(G, \text{Hom}(H, K)).$$

The proof appears in our Proceedings note quoted in the introduction.

Let D be a fixed Banach space, while B and C are two (variable) Banach

spaces. To each pair of linear transformations λ and μ , with $\|\lambda\| \leq 1$ and $\|\mu\| \leq 1$, and with

$$B \xrightarrow{\lambda} C \xrightarrow{\mu} D,$$

there is associated a composite linear transformation $\mu\lambda$, with $\mu\lambda: B \rightarrow D$. Thus there is a correspondence $\tau = \tau(B, C)$ which associates to each $\lambda \in \text{Lin}(B, C)$ a linear transformation $\tau\lambda$ with

$$[\tau\lambda](\mu) = \mu\lambda \in \text{Lin}(B, D).$$

Each $\tau\lambda$ is a linear transformation of $\text{Lin}(C, D)$ into $\text{Lin}(B, D)$ with norm at most one; consequently τ establishes a correspondence

$$(10.8) \quad \tau(B, C): \text{Lin}(B, C) \rightarrow \text{Lin}(\text{Lin}(C, D), \text{Lin}(B, D)).$$

It can be readily shown that τ itself is a linear transformation, and that $\|\tau(\lambda)\| = \|\lambda\|$, so that τ is an isometric mapping.

This mapping τ actually gives a transformation between the functors in (10.8). If the space D is kept fixed⁽¹⁵⁾, the functions $\text{Lin}(B, C)$ and $\text{Lin}(\text{Lin}(C, D), \text{Lin}(B, D))$ are object functions of functors contravariant in B and covariant in C , with values in the category \mathfrak{B} of Banach spaces. Each $\tau = \tau(B, C)$ is a mapping of this category; thus τ is a natural transformation of the first functor in the second provided that, whenever $\beta: B_1 \rightarrow B_2$ and $\gamma: C_1 \rightarrow C_2$,

$$(10.9) \quad \tau(B_1, C_2) \text{Lin}(\beta, \gamma) = \text{Lin}(\text{Lin}(\gamma, e), \text{Lin}(\beta, e))\tau(B_2, C_1),$$

where $e = e_D$ is the identity mapping of D into itself. Each side of (10.9) is a mapping of $\text{Lin}(B_2, C_1)$ into $\text{Lin}(\text{Lin}(C_2, D), \text{Lin}(B_1, D))$. Apply each side to any $\lambda \in \text{Lin}(B_2, C_1)$, and let the result act on any $\mu \in \text{Lin}(C_2, D)$. On the left side, the result of these applications simplifies as follows (in each step the definition used is cited at the right):

$$\begin{aligned} & \{[\tau(B_1, C_2)] \text{Lin}(\beta, \gamma)\lambda\} \mu \\ &= \{[\tau(B_1, C_2)](\gamma\lambda\beta)\} \mu && \text{(Definition of Lin } (\beta, \gamma)) \\ &= \mu\gamma\lambda\beta && \text{(Definition of } \tau(B_1, C_2)). \end{aligned}$$

The right side similarly becomes

$$\begin{aligned} & \{\text{Lin}(\text{Lin}(\gamma, e), \text{Lin}(\beta, e))[\tau(B_2, C_1)\lambda]\} \mu \\ &= \{\text{Lin}(\beta, e)[\tau(B_2, C_1)\lambda] \text{Lin}(\gamma, e)\} \mu && \text{(Definition of Lin } (—, —)) \\ &= \text{Lin}(\beta, e)\{[\tau(B_2, C_1)\lambda](\mu\gamma)\} && \text{(Definition of Lin } (\gamma, e)) \\ &= \text{Lin}(\beta, e)(\mu\gamma\lambda) && \text{(Definition of } \tau(B_2, C_1)) \\ &= \mu\gamma\lambda\beta && \text{(Definition of Lin } (\beta, e)). \end{aligned}$$

⁽¹⁵⁾ We keep the space D fixed because in one of these functors it appears twice, once as a covariant argument and once as a contravariant one.

The identity of these two results shows that τ is indeed a natural transformation of functors.

In the special case when D is the space of real numbers, $\text{Lin}(C, D)$ is simply the conjugate space $\text{Conj}(C)$. Thus we have the natural transformation

$$(10.10) \quad \tau(B, C): \text{Lin}(B, C) \rightarrow \text{Lin}(\text{Conj } C, \text{Conj } B).$$

A similar argument for locally compact abelian groups G and H yields a natural transformation

$$(10.11) \quad \tau(G, H): \text{Hom}(G, H) \rightarrow \text{Hom}(\text{Ch } H, \text{Ch } G).$$

In the theory of character groups it is shown that each $\tau(G, H)$ is an isomorphism, so (10.11) is actually a natural isomorphism. The well known isomorphism between a locally compact abelian group G and its twice iterated character group is also a natural isomorphism

$$\tau(G): G \rightleftarrows \text{Ch}(\text{Ch } G)$$

between functors⁽¹⁶⁾. The analogous natural transformation

$$\tau(B): B \rightarrow \text{Conj}(\text{Conj } B)$$

for Banach spaces is an equivalence only when B is restricted to the category of reflexive Banach spaces.

11. Groups as categories. Any group G may be regarded as a category \mathfrak{G}_G in which there is only one object. This object may either be the set G or, if G is a transformation group, the space on which G acts. The mappings of the category are to be the elements γ of the group G , and the product of two elements in the group is to be their product as mappings in the category. In this category every mapping is an equivalence, and there is only one identity mapping (the unit element of G). A covariant functor T with one argument in \mathfrak{G}_G and with values in (the category of) the group H is just a homomorphic mapping $\eta = T(\gamma)$ of G into H . A natural transformation τ of one such functor T_1 into another one, T_2 , is defined by a single element $\tau(G) = \eta_0 \in H$. Since η_0 has an inverse, every natural transformation is automatically an equivalence. The naturality condition (7.2a) for τ becomes simply $\eta_0 T_1(\gamma) \eta_0^{-1} = T_2(\gamma)$. Thus the functors T_1 and T_2 are naturally equivalent if and only if T_1 and T_2 , considered as homomorphisms, are conjugate.

Similarly, a contravariant functor T on a group G , considered as a category, is simply a "dual" or "counter" homomorphism ($T(\gamma_2 \gamma_1) = T(\gamma_1) T(\gamma_2)$).

A ring R with unity also gives a category, in which the mappings are the elements of R , under the operation of multiplication in R . The unity of the ring is the only identity of the category, and the units of the ring are the equivalences of the category.

⁽¹⁶⁾ The proof of naturality appears in the note quoted in footnote 3.

12. Construction of functors as transforms. Under suitable conditions a mapping-function $\tau(A, B)$ acting on a given functor $T(A, B)$ can be used to construct a new functor S such that $\tau: T \rightarrow S$. The case in which each τ is an equivalence mapping is the simplest, so will be stated first.

THEOREM 12.1. *Let T be a functor covariant in \mathfrak{A} , contravariant in \mathfrak{B} , with values in \mathfrak{C} . Let S and τ be functions which determine for each pair of objects $A \in \mathfrak{A}$, $B \in \mathfrak{B}$ an object $S(A, B)$ in \mathfrak{C} and an equivalence mapping*

$$\tau(A, B): T(A, B) \rightarrow S(A, B) \quad \text{in } \mathfrak{C}.$$

Then S is the object function of a uniquely determined functor S , concordant with T and such that τ is a natural equivalence $\tau: T \rightleftharpoons S$.

Proof. One may readily show that the mapping function appropriate to S is uniquely determined for each $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} by the formula

$$S(\alpha, \beta) = \tau(A_2, B_1)T(\alpha, \beta)[\tau(A_1, B_2)]^{-1}.$$

The companion theorem for the case of a transformation which is not necessarily an equivalence is somewhat more complicated. We first define mappings cancellable from the right. A mapping $\alpha \in \mathfrak{A}$ will be called cancellable from the right if $\beta\alpha = \gamma\alpha$ always implies $\beta = \gamma$. To illustrate, if each "formal" mapping is an actual many-to-one mapping of one set into another, and if the composition of formal mappings is the usual composition of correspondences, it can be shown that every mapping α of one set *onto* another is cancellable from the right.

THEOREM 12.2. *Let T be a functor covariant in \mathfrak{A} and contravariant in \mathfrak{B} , with values in \mathfrak{C} . Let $S(A, B)$ and $S(\alpha, \beta)$ be two functions on the objects (and mappings) of \mathfrak{A} and \mathfrak{B} , for which it is assumed only, when $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} , that*

$$S(\alpha, \beta): S(A_1, B_2) \rightarrow S(A_2, B_1) \quad \text{in } \mathfrak{C}.$$

If a function τ on the objects of \mathfrak{A} , \mathfrak{B} to the mappings of \mathfrak{C} satisfies the usual conditions for a natural transformation $\tau: T \rightarrow S$; namely that

$$(12.1) \quad \tau(A, B): T(A, B) \rightarrow S(A, B) \quad \text{in } \mathfrak{C},$$

$$(12.2) \quad \tau(A_2, B_1)T(\alpha, \beta) = S(\alpha, \beta)\tau(A_1, B_2),$$

and if in addition each $\tau(A, B)$ is cancellable from the right, then the functions $S(\alpha, \beta)$ and $S(A, B)$ form a functor S , concordant with T , and τ is a transformation $\tau: T \rightarrow S$.

Proof. We need to show that

$$(12.3) \quad S(e_A, e_B) = e_{S(A, B)},$$

$$(12.4) \quad S(\alpha_2\alpha_1, \beta_2\beta_1) = S(\alpha_2, \beta_1)S(\alpha_1, \beta_2).$$

Since T is a functor, $T(e_A, e_B)$ is an identity, so that condition (12.2) with $A_1 = A_2$, $B_1 = B_2$ becomes

$$\tau(A, B) = S(e_A, e_B)\tau(A, B).$$

Because $\tau(A, B)$ is cancellable from the right, it follows that $S(e_A, e_B)$ must be the identity mapping of $S(A, B)$, as desired.

To consider the second condition, let $\alpha_1: A_1 \rightarrow A_2$, $\alpha_2: A_2 \rightarrow A_3$, $\beta_1: B_1 \rightarrow B_2$ and $\beta_2: B_2 \rightarrow B_3$, so that $\alpha_2\alpha_1$ and $\beta_2\beta_1$ are defined. By condition (12.2) and the properties of the functor T ,

$$\begin{aligned} S(\alpha_2\alpha_1, \beta_2\beta_1)\tau(A_1, B_3) &= \tau(A_3, B_1)T(\alpha_2\alpha_1, \beta_2\beta_1) \\ &= \tau(A_3, B_1)T(\alpha_2, \beta_1)T(\alpha_1, \beta_2) \\ &= S(\alpha_2, \beta_1)\tau(A_2, B_2)T(\alpha_1, \beta_2) \\ &= S(\alpha_2, \beta_1)S(\alpha_1, \beta_2)\tau(A_1, B_3). \end{aligned}$$

Again because $\tau(A_1, B_3)$ may be cancelled on the right, (12.4) follows.

13. Combination of the arguments of functors. For n given categories $\mathfrak{A}_1, \dots, \mathfrak{A}_n$, the cartesian product category

$$(13.1) \quad \mathfrak{A} = \prod_i \mathfrak{A}_i = \mathfrak{A}_1 \times \mathfrak{A}_2 \times \dots \times \mathfrak{A}_n$$

is defined as a category in which the objects are the n -tuples of objects $[A_1, \dots, A_n]$, with $A_i \in \mathfrak{A}_i$, the mappings are the n -tuples $[\alpha_1, \dots, \alpha_n]$ of mappings $\alpha_i \in \mathfrak{A}_i$. The product

$$[\alpha_1, \dots, \alpha_n][\beta_1, \dots, \beta_n] = [\alpha_1\beta_1, \dots, \alpha_n\beta_n]$$

is defined if and only if each individual product $\alpha_i\beta_i$ is defined in \mathfrak{A}_i , for $i = 1, \dots, n$. The identity corresponding to the object $[A_1, \dots, A_n]$ in the product category is to be the mapping $[e(A_1), \dots, e(A_n)]$. The axioms which assert that the product \mathfrak{A} is a category follow at once. The natural correspondence

$$(13.2) \quad P(A_1, \dots, A_n) = [A_1, \dots, A_n],$$

$$(13.3) \quad P(\alpha_1, \dots, \alpha_n) = [\alpha_1, \dots, \alpha_n]$$

is a covariant functor on the n categories $\mathfrak{A}_1, \dots, \mathfrak{A}_n$ to the product category. Conversely, the correspondences given by "projection" into the i th coordinate,

$$(13.4) \quad Q_i([A_1, \dots, A_n]) = A_i, \quad Q_i([\alpha_1, \dots, \alpha_n]) = \alpha_i,$$

is a covariant functor in one argument, on \mathfrak{A} to \mathfrak{A}_i .

It is now possible to represent a functor covariant in any number of argu-

ments as a functor in one argument. Let T be a functor on the categories $\mathfrak{A}_1, \dots, \mathfrak{A}_n, \mathfrak{B}$, with the same variance in \mathfrak{A}_i as in \mathfrak{A}_1 ; define a new functor T^* by setting

$$T^*([A_1, \dots, A_n], B) = T(A_1, \dots, A_n, B),$$

$$T^*([\alpha_1, \dots, \alpha_n], \beta) = T(\alpha_1, \dots, \alpha_n, \beta).$$

This is a functor, since it is a composite of T and the projections Q_i of (13.4); its variance in the first argument is that of T in any A_i . Conversely, each functor S with arguments in $\mathfrak{A}_1 \times \dots \times \mathfrak{A}_n$ and \mathfrak{B} can be represented as $S = T^*$, for a T with $n+1$ arguments in $\mathfrak{A}_1, \dots, \mathfrak{A}_n, \mathfrak{B}$, defined by

$$T(A_1, \dots, A_n, B) = S([A_1, \dots, A_n], B) = S(P(A_1, \dots, A_n), B),$$

$$T(\alpha_1, \dots, \alpha_n, \beta) = S([\alpha_1, \dots, \alpha_n], \beta) = S(P(\alpha_1, \dots, \alpha_n), \beta).$$

Again T is a composite functor. These reduction arguments combine to give the following theorem.

THEOREM 13.1. *For given categories $\mathfrak{A}_1, \dots, \mathfrak{A}_n, \mathfrak{B}_1, \dots, \mathfrak{B}_m, \mathfrak{C}$, there is a one-to-one correspondence between the functors T covariant in $\mathfrak{A}_1, \dots, \mathfrak{A}_n$, contravariant in $\mathfrak{B}_1, \dots, \mathfrak{B}_m$, with values in \mathfrak{C} , and the functors S in two arguments, covariant in $\mathfrak{A}_1 \times \dots \times \mathfrak{A}_n$ and contravariant in $\mathfrak{B}_1 \times \dots \times \mathfrak{B}_m$, with values in the same category \mathfrak{C} . Under this correspondence, equivalent functors T correspond to equivalent functors S , and a natural transformation $\tau: T_1 \rightarrow T_2$ gives rise to a natural transformation $\sigma: S_1 \rightarrow S_2$ between the functors S_1 and S_2 corresponding to T_1 and T_2 respectively.*

By this theorem, all functors can be reduced to functors in two arguments. To carry this reduction further, we introduce the concept of a "dual" category.

Given a category \mathfrak{A} , the dual category \mathfrak{A}^* is defined as follows. The objects of \mathfrak{A}^* are those of \mathfrak{A} ; the mappings α^* of \mathfrak{A}^* are in a one-to-one correspondence $\alpha \rightleftharpoons \alpha^*$ with the mappings of \mathfrak{A} . If $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} , then $\alpha^*: A_2 \rightarrow A_1$ in \mathfrak{A}^* . The composition law is defined by the equation

$$\alpha_2^* \alpha_1^* = (\alpha_1 \alpha_2)^*,$$

if $\alpha_1 \alpha_2$ is defined in \mathfrak{A} . We verify that \mathfrak{A}^* is a category and that there are equivalences

$$(\mathfrak{A}^*)^* \cong \mathfrak{A}, \quad \prod_i \mathfrak{A}_i^* \cong (\prod_i \mathfrak{A}_i)^*.$$

The mapping

$$D(A) = A, \quad D(\alpha) = \alpha^*$$

is a contravariant functor on \mathfrak{A} to \mathfrak{A}^* , while D^{-1} is contravariant on \mathfrak{A}^* to \mathfrak{A} .

Any contravariant functor T on \mathfrak{A} to \mathfrak{C} can be regarded as a covariant

functor T^* on \mathfrak{A}^* to \mathfrak{C} , and vice versa. Explicitly, T^* is defined as a composite

$$T^*(A) = T(D^{-1}(A)), \quad T^*(\alpha^*) = T(D^{-1}(\alpha^*)).$$

Hence we obtain the following reduction theorem.

THEOREM 13.2. *Every functor T covariant on $\mathfrak{A}_1, \dots, \mathfrak{A}_n$ and contravariant on $\mathfrak{B}_1, \dots, \mathfrak{B}_m$ with values in \mathfrak{C} may be regarded as a covariant functor T' on*

$$\left(\prod_i \mathfrak{A}_i \right) \times \left(\prod_j \mathfrak{B}_j^* \right)$$

with values in \mathfrak{C} , and vice versa. Each natural transformation (or equivalence) $\tau: T_1 \rightarrow T_2$ yields a corresponding transformation (or equivalence) $\tau': T'_1 \rightarrow T'_2$.

CHAPTER III. FUNCTORS AND GROUPS

14. Subfunctors. This chapter will develop the fashion in which various particular properties of groups are reflected by properties of functors with values in a category of groups. The simplest such case is the fact that subgroups can give rise to “subfunctors.” The concept of subfunctor thus developed applies with equal force to functors whose values are in the category of rings, spaces, and so on.

In the category \mathfrak{G} of all topological groups we say that a mapping $\gamma': G'_1 \rightarrow G'_2$ is a *submapping* of a mapping $\gamma: G_1 \rightarrow G_2$ (notation: $\gamma' \subset \gamma$) whenever $G'_1 \subset G_1$, $G'_2 \subset G_2$ and $\gamma'(g_1) = \gamma(g_1)$ for each $g_1 \in G'_1$. Here $G'_1 \subset G_1$ means of course that G'_1 is a subgroup (not just a subset) of G_1 .

Given two concordant functors T' and T on \mathfrak{A} and \mathfrak{B} to \mathfrak{G} , we say that T' is a subfunctor of T (notation: $T' \subset T$) provided $T'(A, B) \subset T(A, B)$ for each pair of objects $A \in \mathfrak{A}$, $B \in \mathfrak{B}$ and $T'(\alpha, \beta) \subset T(\alpha, \beta)$ for each pair of mappings $\alpha \in \mathfrak{A}$, $\beta \in \mathfrak{B}$. Clearly $T' \subset T$ and $T \subset T'$ imply $T = T'$; furthermore this inclusion satisfies the transitive law. If T' and T'' are both subfunctors of the same functor T , then in order to prove that $T' \subset T''$ it is sufficient to verify that $T'(A, B) \subset T''(A, B)$ for all A and B .

A subfunctor can be completely determined by giving its object function alone. The requisite properties for this object function may be specified as follows:

THEOREM 14.1. *Let the functor T covariant in \mathfrak{A} and contravariant in \mathfrak{B} have values in the category \mathfrak{G} of groups, while T' is a function which assigns to each pair of objects $A \in \mathfrak{A}$ and $B \in \mathfrak{B}$ a subgroup $T'(A, B)$ of $T(A, B)$. Then T' is the object function of a subfunctor of T if and only if for each $\alpha: A_1 \rightarrow A_2$ in \mathfrak{A} and each $\beta: B_1 \rightarrow B_2$ in \mathfrak{B} the mapping $T(\alpha, \beta)$ carries the subgroup $T'(A_1, B_2)$ into part of $T'(A_2, B_1)$. If T' satisfies this condition, the corresponding mapping function is uniquely determined.*

Proof. The necessity of this condition is immediate. Conversely, to prove

the sufficiency, we define for each α and β a homomorphism $T'(\alpha, \beta)$ of $T'(A_1, B_2)$ into $T'(A_2, B_1)$ by setting $T'(\alpha, \beta)g = T(\alpha, \beta)g$, for each $g \in T'(A_1, B_2)$. The fact that T' satisfies the requisite conditions for the mapping function of a functor is then immediate, since T' is obtained by "cutting down" T .

The concept of a subtransformation may also be defined. If T, S, T', S' are concordant functors on $\mathfrak{A}, \mathfrak{B}$ to \mathfrak{G} , and if $\tau: T \rightarrow S$ and $\tau': T' \rightarrow S'$ are natural transformations, we say that τ' is a *subtransformation* of τ (notation: $\tau' \subset \tau$) if $T' \subset T, S' \subset S$ and if, for each pair of arguments $A, B, \tau'(A, B)$ is a submapping of $\tau(A, B)$. Any such subtransformation of τ may be obtained by suitably restricting both the domain and the range of τ . Explicitly, let $\tau: T \rightarrow S$, let $T' \subset T$ and $S' \subset S$ be such that for each $A, B, \tau(A, B)$ maps the subgroup $T'(A, B)$ of $T(A, B)$ into the subgroup $S'(A, B)$ of $S(A, B)$. If then $\tau'(A, B)$ is defined as the homomorphism $\tau(A, B)$ with its domain restricted to the subgroup $T'(A, B)$ and its range restricted to the subgroup $S'(A, B)$, it follows readily that τ' is indeed a natural transformation $\tau': T' \rightarrow S'$.

Let τ be a natural transformation $\tau: T \rightarrow S$ of concordant functors T and S on \mathfrak{A} and \mathfrak{B} to the category \mathfrak{G} of groups. If T' is a subfunctor of T , then the map of each $T'(A, B)$ under $\tau(A, B)$ is a subgroup of $S(A, B)$, so that we may define an object function

$$S'(A, B) = \tau(A, B)[T'(A, B)], \quad A \in \mathfrak{A}, B \in \mathfrak{B}.$$

The naturality condition on τ shows that the function S' satisfies the condition of Theorem 14.1; hence $S' = \tau T'$ gives a subfunctor of S , called the τ -transform of T' . Furthermore there is a natural transformation $\tau': T' \rightarrow S'$, obtained by restricting τ . In particular, if τ is a natural equivalence, so is τ' .

Conversely, for a given $\tau: T \rightarrow S$ let S'' be a subfunctor of S . The inverse image of each subgroup $S''(A, B)$ under the homomorphism $\tau(A, B)$ is then a subgroup of $T(A, B)$, hence gives an object function

$$T''(A, B) = \tau(A, B)^{-1}[S''(A, B)], \quad A \in \mathfrak{A}, B \in \mathfrak{B}.$$

As before, this is the object function of a subfunctor $T'' \subset T$ which may be called the inverse transform $\tau^{-1}S'' = T''$ of S'' . Again, τ may be restricted to give a natural transformation $\tau'': T'' \rightarrow S''$. In case each $\tau(A, B)$ is a homomorphism of $T(A, B)$ onto $S(A, B)$, we may assert that $\tau(\tau^{-1}S'') = S''$.

Lattice operations on subgroups can be applied to functors. If T' and T'' are two subfunctors of a functor T with values in G , we define their meet $T' \cap T''$ and their join $T' \cup T''$ by giving the object functions,

$$\begin{aligned} [T' \cap T''](A, B) &= T'(A, B) \cap T''(A, B), \\ [T' \cup T''](A, B) &= T'(A, B) \cup T''(A, B). \end{aligned}$$

We verify that the condition of Theorem 14.1 is satisfied here, so that these object functions do uniquely determine corresponding subfunctors of T . Any

lattice identity for groups may then be written directly as an identity for the subfunctors of a fixed functor T with values in \mathfrak{G} .

15. **Quotient functors.** The operation of forming a quotient group leads to an analogous operation of taking the “quotient functor” of a functor T by a “normal” subfunctor T' . If T is a functor covariant in \mathfrak{A} and contra-variant in \mathfrak{B} , with values in \mathfrak{G} , a *normal subfunctor* T' will mean a subfunctor $T' \subset T$ such that each $T'(A, B)$ is a normal subgroup of $T(A, B)$, while a *closed* subfunctor T' will be one in which each $T'(A, B)$ is a closed subgroup of the topological group $T(A, B)$. If T' is a normal subfunctor of T , the quotient functor $Q = T/T'$ has an object function given as the factor group,

$$Q(A, B) = T(A, B)/T'(A, B).$$

For homomorphisms $\alpha:A_1 \rightarrow A_2$ and $\beta:B_1 \rightarrow B_2$ the corresponding mapping function $Q(\alpha, \beta)$ is defined for each coset⁽¹⁷⁾ $x + T'(A_1, B_2)$ as

$$Q(\alpha, \beta)[x + T'(A_1, B_2)] = [T(\alpha, \beta)x] + T'(A_2, B_1).$$

We verify at once that Q thus gives a uniquely defined homomorphism,

$$Q(\alpha, \beta):Q(A_1, B_2) \rightarrow Q(A_2, B_1).$$

Before we prove that Q is actually a functor, we introduce for each $A \in \mathfrak{A}$ and $B \in \mathfrak{B}$ the homomorphism

$$\nu(A, B):T(A, B) \rightarrow Q(A, B)$$

defined for each $x \in T(A, B)$ by the formula

$$\nu(A, B)(x) = x + T'(A, B).$$

When $\alpha:A_1 \rightarrow A_2$ and $\beta:B_1 \rightarrow B_2$ we now show that

$$Q(\alpha, \beta)\nu(A_1, B_2) = \nu(A_2, B_1)T(\alpha, \beta).$$

For, given any $x \in T(A_1, B_2)$, the definitions of ν and Q give at once

$$\begin{aligned} Q(\alpha, \beta)[\nu(A_1, B_2)(x)] &= Q(\alpha, \beta)[x + T'(A_1, B_2)] \\ &= [T(\alpha, \beta)(x)] + T'(A_2, B_1) \\ &= \nu(A_2, B_1)[T(\alpha, \beta)(x)]. \end{aligned}$$

Notice also that $\nu(A, B)$ maps $T(A, B)$ onto the factor group $Q(A, B)$, hence is cancellable from the right. Therefore, Theorem 12.2 shows that $Q = T/T'$ is a functor, and that ν is a natural transformation $\nu:T \rightarrow T/T'$. We may call ν the natural transformation of T onto T/T' .

In particular, if the functor T has its values in the category of regular topological groups, while T' is a *closed* normal subfunctor of T , the quotient

⁽¹⁷⁾ For convenience in notation we write the group operations (commutative or not) with a plus sign.

functor T/T' has its values in the same category of groups, since a quotient group of a regular topological group by a *closed* subgroup is again regular.

To consider the behavior of quotient functors under natural transformations we first recall some properties of homomorphisms. Let $\alpha:G\rightarrow H$ be a homomorphism of the group G into H , while $\alpha':G'\rightarrow H'$ is a submapping of α , with G' and H' normal subgroups of G and H , respectively, and ν and μ are the natural homomorphisms $\nu:G\rightarrow G/G'$, $\mu:H\rightarrow H/H'$. Then we may define a homomorphism $\beta:G/G'\rightarrow H/H'$ by setting $\beta(x+G')=\alpha x+H'$ for each $x\in G$. This homomorphism is the only mapping of G/G' into H/H' with the property that $\beta\nu=\mu\alpha$, as indicated in the figure

$$\begin{array}{ccc} G & \xrightarrow{\alpha} & H \\ \nu \downarrow & & \downarrow \mu \\ G/G' & \xrightarrow{\beta} & H/H' \end{array}$$

We may write $\beta=\alpha/\alpha'$. The corresponding statement for functors is as follows.

THEOREM 15.1. *Let $\tau:T\rightarrow S$ be a natural transformation between functors with values in \mathfrak{G} ; and let $\tau':T'\rightarrow S'$ be a subtransformation of τ such that T' and S' are normal subfunctors of T and S , respectively. Then the definition $\rho(A, B)=\tau(A, B)/\tau'(A, B)$ gives a natural transformation $\rho=\tau/\tau'$,*

$$\rho:T/T' \rightarrow S/S'.$$

Furthermore, $\rho\nu=\mu\tau$, where ν is the natural transformation $\nu:T\rightarrow T/T'$ and μ is the natural transformation $\mu:S\rightarrow S/S'$.

Proof. This requires only the verification of the naturality condition for ρ , which follows at once from the relevant definitions.

The “kernel” of a transformation appears as a special case of this theorem. Let $\tau:T\rightarrow S$ be given, and take S' to be the identity-element subfunctor of S ; that is, let each $S'(A, B)$ be the subgroup consisting only of the identity (zero) element of $S(A, B)$. Then the inverse transform $T'=\tau^{-1}S'$ is by §14 a (normal) subfunctor of T , and τ may be restricted to give the natural transformation $\tau':T'\rightarrow S'$. We may call T' the kernel functor of the transformation τ . Theorem 15.1 applied in this case shows that there is then a natural transformation $\rho:T/T'\rightarrow S$ such that $\rho=\tau\nu$. Furthermore each $\rho(A, B)$ is a one-to-one mapping of the quotient group $T(A, B)/T'(A, B)$ into $S(A, B)$. If in addition we assume that each $\tau(A, B)$ is an open mapping of $T(A, B)$ onto $S(A, B)$, we may conclude, exactly as in group theory, that ρ is a natural equivalence.

16. Examples of subfunctors. Many characteristic subgroups of a group

may be written as subfunctors of the identity functor. The (covariant) identity functor I on \mathfrak{G} to \mathfrak{G} is defined by setting

$$I(G) = G, \quad I(\gamma) = \gamma.$$

Any subfunctor of I is, by Theorem 14.1, determined by an object function

$$T(G) \subset G$$

such that whenever γ maps G_1 homomorphically into G_2 , then $\gamma[T(G_1)] \subset T(G_2)$. Furthermore, if each $T(G)$ is a normal subgroup of G , we can form a quotient functor I/T .

For example, the commutator subgroup $C(G)$ of the group G determines in this fashion a normal subfunctor of I . The corresponding quotient functor $(I/C)(G)$ is the functor determining for each G the factor commutator group of G (the group G made abelian).

The center $Z(G)$ does not determine in this fashion a subfunctor of I , because a homomorphism of G_1 into G_2 may carry central elements of G_1 into non-central elements of G_2 . However, we may choose to restrict the category \mathfrak{G} by using as mappings only homomorphisms of one group onto another. For this category, Z is a subfunctor of I , and we may form a quotient functor I/Z .

Thus various types of subgroups of G may be classified in terms of the degree of invariance of the "subfunctors" of the identity which they generate. This classification is similar to, but not identical with, the known distinction between normal subgroups, characteristic subgroups, and strictly characteristic subgroups of a single group⁽¹⁸⁾. The present distinction by functors refers not to the subgroups of an individual group, but to a definition yielding a subgroup for each of the groups in a suitable category. It includes the standard distinction, in the sense that one may consider functors on the category with only one object (a single group G) and with mappings which are the inner automorphisms of G (the subfunctors of I =normal subgroups), the automorphisms of G (subfunctors=characteristic subgroups), or the endomorphisms of G (subfunctors=strictly characteristic subgroups).

Still another example of the degree of invariance is given by the automorphism group $A(G)$ of a group G . This is a functor A defined on the category \mathfrak{G} of groups with the mappings restricted to the isomorphisms $\gamma: G_1 \rightarrow G_2$ of one group onto another. The mapping function $A(\gamma)$ for any automorphism σ_1 of G_1 is then defined by setting

$$[A(\gamma)\sigma_1]g_2 = \gamma\sigma_1\gamma^{-1}g_2, \quad g_2 \in G_2.$$

The types of invariance for functors on \mathfrak{G} may thus be indicated by a table, showing how the mappings of the category must be restricted in order to make the indicated set function a functor:

⁽¹⁸⁾ A subgroup S of G is characteristic if $\sigma(S) \subset S$ for every automorphism σ of G , and strictly (or "strongly") characteristic if $\sigma(S) \subset S$ for every endomorphism of G .

<i>Functor</i>	<i>Mappings $\gamma: G_1 \rightarrow G_2$</i>
$C(G)$	Homomorphisms into,
$Z(G)$	Homomorphisms onto,
$A(G)$	Isomorphisms onto.

For the subcategory of \mathcal{G} consisting of all (additive) abelian groups there are similar subfunctors: 1°. G_0 , the set of all elements of finite order in G ; 2°. G_m , the set of all elements in G of order dividing the integer m ; 3°. mG , the set of all elements of the form mg in G . The corresponding quotient functors will have object functions G/G_0 (the "Betti group" of G), G/G_m , and G/mG (the group G reduced modulo m).

17. The isomorphism theorems. The isomorphism theorems of group theory can be formulated for functors; from this it will follow that these isomorphisms between groups are "natural."

The "first isomorphism theorem" asserts that if G has two normal subgroups G_1 and G_2 with $G_2 \subset G_1$, then G_1/G_2 is a normal subgroup of G/G_2 , and there is an isomorphism τ of $(G/G_2)/(G_1/G_2)$ to G/G_1 . The elements of the first group (in additive notation) are cosets of cosets, of the form $(x + G_2) + G_1/G_2$, and the isomorphism τ is defined as

$$(17.1) \quad \tau[(x + G_2) + G_1/G_2] = x + G_1.$$

This may be stated in terms of functors as follows.

THEOREM 17.1. *Let T_1 and T_2 be two normal subfunctors of a functor T with values in the category of groups. If $T_2 \subset T_1$, then T_1/T_2 is a normal subfunctor of T/T_2 and the functors*

$$(17.2) \quad T/T_1 \quad \text{and} \quad (T/T_2)/(T_1/T_2)$$

are naturally equivalent.

Proof. We assume that the given functor T depends on the usual typical arguments A and B . Since $(T_1/T_2)(A, B)$ is clearly a normal subgroup of $(T/T_2)(A, B)$, a proof that T_1/T_2 is a normal subfunctor of T/T_2 requires only a proof that each $(T_1/T_2)(\alpha, \beta)$, is a submapping of the corresponding $(T/T_2)(\alpha, \beta)$ for any $\alpha: A_1 \rightarrow A_2$ and $\beta: B_1 \rightarrow B_2$. To show this, apply $(T_1/T_2) \cdot (\alpha, \beta)$ to a typical coset $x + T_2(A_1, B_2)$. Applying the definitions, one has

$$\begin{aligned} (T_1/T_2)(\alpha, \beta)[x + T_2(A_1, B_2)] &= T_1(\alpha, \beta)(x) + T_2(A_2, B_1) \\ &= T(\alpha, \beta)(x) + T_2(A_2, B_1) \\ &= (T/T_2)(\alpha, \beta)[x + T_2(A_1, B_2)], \end{aligned}$$

for $T_1(\alpha, \beta)$ was assumed to be a submapping of $T(\alpha, \beta)$.

The asserted equivalence (17.2) is established by setting, as in (17.1),

$$\tau(A, B)\{[x + T_2(A, B)] + (T_1/T_2)(A, B)\} = x + T_1(A, B).$$

The naturality proof then requires that, for any mappings $\alpha: A_1 \rightarrow A_2$ and $\beta: B_1 \rightarrow B_2$,

$$\tau(A_2, B_1)S(\alpha, \beta) = (T/T_1)(\alpha, \beta)\tau(A_1, B_2),$$

where $S = (T/T_2)/(T_1/T_2)$. This equality may be verified mechanically by applying each side to a general element $[x + T_2(A_1, B_2)] + (T_1/T_2)(A_1, B_2)$ in the group $S(A_1, B_2)$.

The theorem may also be stated and proved in the following equivalent form.

THEOREM 17.2. *Let T' and T'' be two normal subfunctors of a functor T with values in the category G of groups. Then $T' \cap T''$ is a normal subfunctor of T' and of T , $T'/T' \cap T''$ is a normal subfunctor of $T/T' \cap T''$, and the functors*

$$(17.3) \quad T/T' \quad \text{and} \quad (T/T' \cap T'')/(T'/T' \cap T'')$$

are naturally equivalent.

Proof. Set $T_1 = T'$, $T_2 = T' \cap T''$.

The second isomorphism theorem for groups is fundamental in the proof of the Jordan-Hölder Theorem. It states that if G has normal subgroups G_1 and G_2 , then $G_1 \cap G_2$ is a normal subgroup of G_1 , G_2 is a normal subgroup of $G_1 \cup G_2$, and there is an isomorphism μ of $G_1/G_1 \cap G_2$ to $G_1 \cup G_2/G_2$. (Because G_1 and G_2 are normal subgroups, the join $G_1 \cup G_2$ consists of all "sums" $g_1 + g_2$, for $g_i \in G_i$, so is often written as $G_1 \cup G_2 = G_1 + G_2$.) For any $x \in G_1$, this isomorphism is defined as

$$(17.4) \quad \mu[x + (G_1 \cap G_2)] = x + G_2.$$

The corresponding theorem for functors reads:

THEOREM 17.3. *If T_1, T_2 are normal subfunctors of a functor T with values in G , then $T_1 \cap T_2$ is a normal subfunctor of T_1 , and T_2 is a normal subfunctor of $T_1 \cup T_2$, and the quotient functors*

$$(17.5) \quad T_1/(T_1 \cap T_2) \quad \text{and} \quad (T_1 \cup T_2)/T_2$$

are naturally equivalent.

Proof. It is clear that both quotients in (17.5) are functors. The requisite equivalence $\mu(A, B)$ is given, as in (17.4), by the definition

$$\mu(A, B)[x + (T_1(A, B) \cap T_2(A, B))] = x + T_2(A, B),$$

for any $x \in T_1(A, B)$. The naturality may be verified as before.

From these theorems we may deduce that the first and second isomorphism theorems yield natural isomorphisms between groups in another and more specific way. To this end we introduce an appropriate category \mathfrak{G}^* . An object of \mathfrak{G}^* is to be a triple $G^* = [G, G', G'']$ consisting of a group G and two

of its normal subgroups. A mapping $\gamma: [G_1, G_1', G_1''] \rightarrow [G_2, G_2', G_2'']$ of \mathfrak{G}^* is to be a homomorphism $\gamma: G_1 \rightarrow G_2$ with the special properties that $\gamma(G_1') \subset G_2'$ and $\gamma(G_1'') \subset G_2''$. It is clear that these definitions do yield a category \mathfrak{G}^* . On this category \mathfrak{G}^* we may define three (covariant) functors with values in the category \mathfrak{G} of groups. The first is a "projection" functor,

$$P([G, G', G'']) = G, \quad P(\gamma) = \gamma;$$

the others are two normal subfunctors of P , which may be specified by their object functions as

$$P'([G, G', G'']) = G', \quad P''([G, G', G'']) = G''.$$

Consider now the first isomorphism theorem, in the second form,

$$(17.6) \quad G/G' \cong (G/(G' \cap G''))/(G'/(G' \cap G'')).$$

If we set $G^* = [G, G', G'']$, the left side here is a value of the object function of the functor, P/P' , and the right side is similarly a value of $(P/P' \cap P'')/(P'/P' \cap P'')$. Theorem 17.2 asserts that these two functors are indeed naturally equivalent. Therefore, the isomorphism (17.6) is itself natural, in that it can be regarded as a natural isomorphism between the object functions of suitable functors on the category \mathfrak{G}^* .

The second isomorphism theorem

$$(G' \cup G'')/G'' \cong G'/(G' \cap G'')$$

is natural in a similar sense, for both sides can be regarded as object functions of suitable (covariant) functors on \mathfrak{G}^* .

It is clear that this technique of constructing a suitable category \mathfrak{G}^* could be used to establish the naturality of even more complicated "isomorphism" theorems.

18. Direct products of functors. We recall that there are essentially two different ways of defining the direct product of two groups G and H . The "external" direct product $G \times H$ is the group of all pairs (g, h) with $g \in G, h \in H$, with the usual multiplication. This product $G \times H$ contains a subgroup G' , of all pairs $(g, 0)$, which is isomorphic to G , and a subgroup H' isomorphic to H . Alternatively, a group L with subgroups G and H is said to be the "internal" direct product $L = G \times H$ of its subgroups G and H if $gh = hg$ for every $g \in G, h \in H$ and if every element in L can be written uniquely as a product gh with $g \in G, h \in H$. The intimate connection between the two types of direct products is provided by the isomorphism $G \times H \cong G \times H$ and by the equality $G \times H = G' \times H'$, where $G' \cong G, H' \cong H$.

As in §4, the *external* direct product can be regarded as a covariant functor on \mathfrak{G} and \mathfrak{G} to \mathfrak{G} , with object function $G \times H$, and mapping function $\gamma \times \eta$, defined as in §4.

Direct products of functors may also be defined, with the same distinction

between “external” and “internal” products. We consider throughout functors covariant in a category \mathfrak{A} , contravariant in \mathfrak{B} , with values in the category \mathfrak{G}_0 of discrete groups. If T_1 and T_2 are two such functors, the external direct product is a functor $T_1 \times T_2$ for which the object and mapping functions are respectively

$$(18.1) \quad (T_1 \times T_2)(A, B) = T_1(A, B) \times T_2(A, B),$$

$$(18.2) \quad (T_1 \times T_2)(\alpha, \beta) = T_1(\alpha, \beta) \times T_2(\alpha, \beta).$$

If $T'_1(A, B)$ denotes the set of all pairs $(g, 0)$ in the direct product $T_1(A, B) \times T_2(A, B)$, T'_1 is a subfunctor of $T_1 \times T_2$, and the correspondence $g \rightarrow (g, 0)$ provides a natural isomorphism of T_1 to T'_1 . Similarly T_2 is naturally isomorphic to a subfunctor T'_2 of $T_1 \times T_2$.

On the other hand, let S be a functor on $\mathfrak{A}, \mathfrak{B}$ to \mathfrak{G}_0 with subfunctors S_1 and S_2 . We call S the *internal* direct product $S_1 \times S_2$ if, for each $A \in \mathfrak{A}$ and $B \in \mathfrak{B}$, $S(A, B)$ is the internal direct product $S_1(A, B) \times S_2(A, B)$. From this definition it follows that, whenever $\alpha: A_1 \rightarrow A_2$ and $\beta: B_1 \rightarrow B_2$ are given mappings and $g_i \in S_i(A_i, B_i)$ are given elements ($i=1, 2$), then, since $S_i(\alpha, \beta) \subset S(\alpha, \beta)$,

$$S(\alpha, \beta)g_1g_2 = [S_1(\alpha, \beta)g_1][S_2(\alpha, \beta)g_2].$$

This means that the correspondence τ defined by setting $[\tau(A_1, B_2)](g_1g_2) = g_2$ is a natural transformation $\tau: S \rightarrow S_2$. Furthermore this transformation is idempotent, for $\tau(A_1, B_2)\tau(A_1, B_2) = \tau(A_1, B_2)$.

The connection between the two definitions is immediate; there is a natural isomorphism of the internal direct product $S_1 \times S_2$ to the external product $S_1 \times S_2$; furthermore any external product $T_1 \times T_2$ is the internal product $T'_1 \times T'_2$ of its subfunctors $T'_1 \cong T_1, T'_2 \cong T_2$.

There are in group theory various theorems giving direct product decompositions. These decompositions can now be classified as to “naturalness.” Consider for example the theorem that every finite abelian group G can be represented as the (internal) direct product of its Sylow subgroups. This decomposition is “natural”; specifically, we may regard the Sylow subgroup $S_p(G)$ (the subgroup consisting of all elements in G of order some power of the prime p) as the object function of a subfunctor S_p of the identity. The theorem in question then asserts in effect that the identity functor I is the internal direct product of (a finite number of) the functors S_p . This representation of the direct factors by functors is the underlying reason for the possibility of extending the decomposition theorem in question to infinite groups in which every element has finite order.

On the other hand consider the theorem which asserts that every finite abelian group is the direct product of cyclic subgroups. It is clear here that the subgroups cannot be given as the values of functors, and we observe that in this case the theorem does not extend to infinite abelian groups.

As another example of non-naturality, consider the theorem which asserts that any abelian group G with a finite number of generators can be represented as a direct product of a free abelian group by the subgroup $T(G)$ of all elements of finite order in G . Let us consider the category \mathfrak{G}_{af} of all discrete abelian groups with a finite number of generators. In this category the "torsion" subgroup $T(G)$ does determine the object function of a subfunctor $T \subset I$. However, there is no such functor giving the complementary direct factor of G .

THEOREM 18.1. *In the category \mathfrak{G}_{af} there is no subfunctor $F \subset I$ such that $I = F \times T$, that is, such that, for all G ,*

$$(18.3) \quad G = F(G) \times T(G).$$

Proof. It suffices to consider just one group, such as the group G which is the (external) direct product of the additive group of integers and the additive group of integers mod m , for $m \neq 0$. Then no matter which free subgroup $F(G)$ may be chosen so that (18.3) holds for this G , there clearly is an isomorphism of G to G which does not carry F into itself. Hence F cannot be a functor.

This result could also be formulated in the statement that, for any G with $G \neq T(G) \neq (0)$, there is no decomposition (18.3) with $F(G)$ a (strongly) characteristic subgroup of G . In order to have a situation which cannot be reformulated in this way, consider the closely related (and weaker) group theoretic theorem which asserts that for each G in \mathfrak{G}_{af} there is an isomorphism of $G/T(G)$ into G . This isomorphism cannot be natural.

THEOREM 18.2. *For the category \mathfrak{G}_{af} there is no natural transformation, $\tau: I/T \rightarrow I$, which gives for each G an isomorphism $\tau(G)$ of $G/T(G)$ into a subgroup of G .*

This proof will require consideration of an infinite class of groups, such as the groups $G_m = J \times J_{(m)}$ where J is the additive group of integers and $J_{(m)}$ the additive group of integers, modulo m . Suppose that $\tau(G): G/T(G) \rightarrow G$ existed. If $\mu(G): G \rightarrow G/T(G)$ is the natural transformation of G into $G/T(G)$ the product $\sigma(G) = \tau(G)\mu(G)$ would be a natural transformation of G into G with kernel $T(G)$. For each of the groups G_m with elements $(a, b_{(m)})$ for $a \in J$, $b_{(m)} \in J_{(m)}$, this transformation $\sigma_m = \sigma(G_m)$ must be a homomorphism with kernel $J_{(m)}$, hence must have the form

$$\sigma_m(a, b_{(m)}) = (r_m a, (s_m a)_{(m)}),$$

where r_m and s_m are integers. Now consider the homomorphism $\gamma: G_m \rightarrow G_m$ defined by setting $\gamma(a, b_{(m)}) = (0, b_{(m)})$. Since σ_m is natural, we must have $\sigma_m \gamma = \gamma \sigma_m$. Applying this equality to an arbitrary element we conclude that $s_m \equiv 0 \pmod{m}$. Next consider $\delta: G_m \rightarrow G_m$ defined by $\delta(a, b_{(m)}) = (0, a_{(m)})$. The

condition $\sigma_m \delta = \delta \sigma_m$ here gives $r_m \equiv 0 \pmod{m}$, so that we can write $r_m = mt_m$. Therefore for each m

$$\sigma_m(a, b_{(m)}) = (mt_m a, 0).$$

Now consider two groups G_m, G_n with a homomorphism $\beta: G_m \rightarrow G_n$ defined by setting $\beta(a, b_{(m)}) = (a, 0_{(n)})$. The naturality condition $\sigma_n \beta = \beta \sigma_m$ now gives $mt_m = nt_n$. If we hold m fixed and allow n to increase indefinitely, this contradicts the fact that mt_m is a finite integer. The proof is complete.

It may be observed that the use of an infinite number of distinct groups is essential to the proof of this theorem. For any subcategory of \mathfrak{G}_{af} containing only a finite number of groups, Theorem 18.2 would be false, for it would be possible to define a natural transformation $\tau(G)$ by setting $[\tau(G)]_g = kg$ for every g , where the integer k is chosen as any multiple of the order of all the subgroups $T(G)$ for G in the given category.

The examples of "non-natural" direct products adduced here are all examples which mathematicians would usually recognize as not in fact natural. What we have done is merely to show that our definition of naturality does indeed properly apply to cases of intuitively clear non-naturality.

19. Characters⁽¹⁹⁾. The character group of a group may be regarded as a contravariant functor on the category \mathfrak{G}_{lca} of locally compact regular abelian groups, with values in the same category. Specifically, this functor "Char" may be defined by "slicing" (see §5) the functor Hom of §4 as follows. Let P be the (fixed) topological group of real numbers modulo 1, define "Char" by setting

$$(19.1) \quad \text{Char } G = \text{Hom}(G, P), \quad \text{Char } \gamma = \text{Hom}(\gamma, e_P).$$

Given $g \in G$ and $\chi \in \text{Char } G$ it will be convenient to denote the element $\chi(g)$ of P by (χ, g) . Using this terminology and the definition of Hom we obtain for $\gamma: G_1 \rightarrow G_2, \chi \in \text{Char } G_2$ and $g_1 \in G_1$,

$$(19.2) \quad (\text{Char } (\gamma)\chi, g) = (\chi, \gamma g).$$

As mentioned before (§10) the familiar isomorphism $\text{Char}(\text{Char } G) \cong G$ is a natural equivalence.

The functor "Char" can be compounded with other functors. Let T be any functor covariant in \mathfrak{A} , contravariant in \mathfrak{B} , with values in \mathfrak{G}_{lca} . The composite functor $\text{Char } T$ is then defined on the same categories \mathfrak{A} and \mathfrak{B} but is contravariant in \mathfrak{A} and covariant in \mathfrak{B} . Let S be any closed subfunctor of T . Then for each pair of objects $A \in \mathfrak{A}, B \in \mathfrak{B}$, the closed subgroup $S(A, B) \subset T(A, B)$ determines a corresponding subgroup $\text{Annih } S(A, B)$ in $\text{Char } T(A, B)$; this annihilator is defined as the set of all those characters $\chi \in \text{Char } T(A, B)$ with $(\chi, g) = 0$ for each $g \in S(A, B)$. This leads to a closed

⁽¹⁹⁾ General references: A. Weil, *L'integration dans les groupes topologiques et ses applications*, Paris, 1938, chap. 1; S. Lefschetz, *Algebraic topology*, Amer. Math. Soc. Colloquium Publication, vol. 27, New York, 1942, chap. 2.

subfunctor $\text{Annih } (S; T)$ of the functor $\text{Char } T$, determined by the object function

$$[\text{Annih } (S; T)](A, B) = \text{Annih } S(A, B) \text{ in } \text{Char } T(A, B).$$

It is well known that

$$\begin{aligned} \text{Char } [T(A, B)/S(A, B)] &= \text{Annih } S(A, B), \\ \text{Char } S(A, B) &= \text{Char } T(A, B)/\text{Annih } S(A, B). \end{aligned}$$

These isomorphisms in fact yield natural equivalences

$$(19.3) \quad \sigma: \text{Annih } (S; T) \rightleftharpoons \text{Char } (T/S),$$

$$(19.4) \quad \tau: \text{Char } T/\text{Annih } (S; T) \rightleftharpoons \text{Char } S.$$

For example, to prove (19.4) one observes that each $\chi \in \text{Char } T(A, B)$ may be restricted to give a character $\tau_0(A, B)\chi$ of $S(A, B)$ by setting

$$(19.5) \quad (\tau_0(A, B)\chi, h) = (\chi, h), \quad h \in S(A, B).$$

This gives a homomorphism

$$\tau_0(A, B): \text{Char } T(A, B) \rightarrow \text{Char } S(A, B)$$

with kernel $\text{Annih } S(A, B)$. This homomorphism τ_0 will yield the required isomorphism τ of (19.4); by Theorem 15.1 a proof that τ_0 is natural will imply that τ is natural.

To show τ_0 natural, consider any mappings $\alpha: A_1 \rightarrow A_2$ and $\beta: B_1 \rightarrow B_2$ in the argument categories of T . Then $\gamma = T(\alpha, \beta)$ maps $T(A_1, B_2)$ into $T(A_2, B_1)$, while $\delta = S(\alpha, \beta)$ is a submapping of γ . The naturality requirements for τ_0 is

$$(19.6) \quad (\text{Char } \delta)\tau_0(A_2, B_1) = \tau_0(A_1, B_2) \text{Char } \gamma.$$

Each side is a homomorphism of $\text{Char } T(A_2, B_1)$ into $\text{Char } S(A_1, B_2)$. If the left-hand side be applied to an element $\chi \in \text{Char } T(A_2, B_1)$, and the resulting character of $S(A_1, B_2)$ is then applied to an element h in the latter group, we obtain

$$(\text{Char } \delta(\tau_0(A_2, B_1)\chi), h) = (\tau_0(A_2, B_1)\chi, \delta h) = (\chi, \delta h)$$

by using the definition (19.2) of $\text{Char } \delta$ and the definition (19.5) of τ_0 . If the right-hand side of (19.6) be similarly applied to χ and then to h , the result is

$$(\tau_0(A_1, B_2)((\text{Char } \gamma)\chi), h) = ((\text{Char } \gamma)\chi, h) = (\chi, \gamma h).$$

Since $\delta \subset \gamma$, these two results are equal, and both τ_0 and τ are therefore natural.

The proof of naturality for (19.3) is analogous.

If R is a closed subfunctor of S which is in turn a closed subfunctor of T , both of these natural isomorphisms may be combined to give a single natural isomorphism

$$(19.7) \quad \rho: \text{Char } (S/R) \Leftrightarrow \text{Annih } (S; T)/\text{Annih } (R; T).$$

CHAPTER IV. PARTIALLY ORDERED SETS AND PROJECTIVE LIMITS

20. **Quasi-ordered sets.** The notions of functors and their natural equivalences apply to partially ordered sets, to lattices, and to related mathematical systems. The category \mathfrak{Q} of all quasi-ordered sets⁽²⁰⁾ has as its objects the quasi-ordered sets P and as its mappings $\pi: P_1 \rightarrow P_2$ the order preserving transformations of one quasi-ordered set, P , into another. An equivalence in this category is thus an isomorphism in the sense of order.

An important subcategory of \mathfrak{Q} is the category \mathfrak{Q}_d of all directed sets⁽²¹⁾. One may also consider subcategories which are obtained by restricting both the quasi-ordered sets and their mappings. For example, the category of lattices has as objects all those partially ordered sets which are lattices and as mappings those correspondences which preserve both joins and meets. Alternatively, by using these mappings which preserve only joins, or those which preserve only meets, we obtain two other categories of lattices.

The category \mathfrak{S} of sets may be regarded as a subcategory of \mathfrak{Q} , if each set S is considered as a (trivially) quasi-ordered set in which $p_1 < p_2$ in S means that $p_1 = p_2$. The category \mathfrak{W} of well-ordered sets is another subcategory of \mathfrak{Q} . These categories provide a basis for applying the study of functors to cardinal and ordinal arithmetic. Specifically, the general theory of arithmetic of partially ordered sets, as developed recently by Birkhoff⁽²²⁾, can be viewed as the construction of a large number of functors (cardinal power, ordinal power, and so on) defined on suitable subcategories of \mathfrak{Q} , together with a collection of natural equivalences and transformations between these functors⁽²³⁾.

The construction of the category \mathfrak{Q} of all quasi-ordered sets is not the only such interpretation of partial order. It is also possible to regard the elements of a *single* quasi-ordered set P as the objects of a category; with this device, one can represent an inverse or a direct system of groups (or of spaces) as a functor on P .

If a quasi-ordered set P be regarded as a category \mathfrak{C}_P , the objects of the category are the elements $p \in P$ and the mappings are the pairs $\pi = (p_2, p_1)$ of elements $p_i \in P$ such that $p_1 < p_2$. To each object p we assign the pair $e_p = (p, p)$ as the corresponding identity mapping, while the product $(p_3, p'_2) (p_2, p_1)$ of two mappings of \mathfrak{C}_P is defined if and only if $p'_2 = p_2$ and is in this case the mapping (p_3, p_1) . The axioms C1 to C5 for a category are readily

⁽²⁰⁾ A *quasi-ordered set* P is a set of elements p_1, p_2, \dots with a reflexive and transitive binary relation $p_1 < p_2$ between the elements. If, in addition, the antisymmetric law $(p_1 < p_2$ and $p_2 < p_1$ imply $p_1 = p_2)$ holds, P is a *partially ordered set*.

⁽²¹⁾ A quasi-ordered set P is *directed* if for each pair of elements $p_1, p_2 \in P$ there exists a $p_3 \in P$ with $p_1 < p_3, p_2 < p_3$.

⁽²²⁾ Garrett Birkhoff, *Generalized arithmetic*, Duke Math. J. vol. 9 (1942) pp. 283-302.

⁽²³⁾ Note, however, that the ordinary cardinal sum of two sets A and B does not give rise to a functor, because the definition applies only when the sets A and B are disjoint.

verified, and it develops that the only identities are the pairs (p, p) , that the equivalence mappings of \mathfrak{C}_P are the pairs (p_2, p_1) with $p_1 < p_2$ and $p_2 < p_1$ and that any pair (p_2, p_1) with $p_1 < p_2$ is a mapping $(p_2, p_1): p_1 \rightarrow p_2$. It further follows that any two mappings $\pi_1: p_1 \rightarrow p_2$ and $\pi_2: p_1 \rightarrow p_2$ of this category which have the same range and the same domain are necessarily equal. Conversely any given category \mathfrak{C} which has the property that any two mappings π_1 and π_2 of \mathfrak{C} with the same range and the same domain are equal is isomorphic to the category \mathfrak{C}_P for a suitable quasi-ordered set P . In fact, P can be defined to be the set of all objects C of the category \mathfrak{C} with $C_1 < C_2$ if and only if there is in \mathfrak{C} a mapping $\gamma: C_1 \rightarrow C_2$.

Consider now two quasi-ordered sets P and Q , with their corresponding categories \mathfrak{C}_P and \mathfrak{C}_Q . A covariant (contravariant) functor T on \mathfrak{C}_P with values in \mathfrak{C}_Q is determined uniquely by an order preserving (reversing) mapping t of P into Q . Specifically, each such correspondence t is the object function $t(p) = q$ of a functor T , for which the corresponding mapping function is defined as $T(p_2, p_1) = (tp_2, tp_1)$ (or, in case t is order-reversing, as (tp_1, tp_2)). Each functor T of one variable can be obtained in this way.

21. Direct systems as functors. Let D be a directed set. If for every $d \in D$ a discrete group G_d is defined and for every pair $d_1 < d_2$ in D a homomorphism

$$(21.1) \quad \phi_{d_2, d_1}: G_{d_1} \rightarrow G_{d_2}$$

is given such that $\phi_{d, d}$ is the identity and that

$$(21.2) \quad \phi_{d_3, d_1} = \phi_{d_3, d_2} \phi_{d_2, d_1} \quad \text{for } d_1 < d_2 < d_3$$

then we say that the groups $\{G_d\}$ and the homomorphisms $\{\phi_{d_2, d_1}\}$ constitute a direct system of groups indexed by D .

Let us now regard the directed set D as a category. For every object $d \in D$ define

$$T(d) = G_d.$$

For every mapping $\delta = (p_2, p_1)$ in D define

$$T(\delta) = T(d_2, d_1) = \phi_{d_2, d_1}.$$

Conditions (21.1) and (21.2) imply that T is a covariant functor on D with values in the category \mathfrak{G}_0 of discrete groups. Conversely any such functor gives rise to a unique direct system. Consequently the terms "direct system of groups indexed by the directed set D " and "covariant functor on D to \mathfrak{G}_0 " may be regarded as synonyms.

With each direct system of groups T there is associated a discrete limit group $G = \text{Lim.} T$ defined as follows. The elements of the limit group G are pairs (g, d) for $g \in T(d)$; two elements (g_1, d_1) and (g_2, d_2) are considered equal if and only if there is an index d_3 with $d_1 < d_3$, $d_2 < d_3$ and with $T(d_3, d_1)g_1 = T(d_3, d_2)g_2$. The sum is defined by setting $(g, d) + (g', d) = (g + g', d)$; since

the set D is directed, this provides for the addition of any two pairs in G . For a fixed $d \in D$ one may also consider the homomorphisms, called projections, $\lambda(d): T(d) \rightarrow G$ defined by setting

$$(21.3) \quad \lambda(d)g = (g, d)$$

for $g \in T(d)$. Clearly

$$(21.4) \quad \lambda(d_1) = \lambda(d_2)T(d_2, d_1) \quad \text{for } d_1 < d_2.$$

To treat this limit group, we enlarge the given directed set D by adjoining one new element ∞ , ordered by the specification that $d < \infty$ for each $d \in D$. This enlarged directed set D_∞ also determines a category containing D as a subcategory, with new mappings (∞, d) for each $d \in D$. Let now T be any covariant functor on D to \mathfrak{G}_0 (that is, any direct system of groups indexed by D). We define an extension T_∞ of the object function of T by setting

$$(21.5) \quad T_\infty(\infty) = \text{Lim}_\rightarrow T = G,$$

the limit group of the given directed system T , and we similarly extend the mapping function of T by letting T_∞ , for a new mapping (∞, d) , be the corresponding projection of $T(d)$ into the limit group

$$(21.6) \quad T_\infty(\infty, d) = \lambda(d).$$

Condition (21.5) implies that T_∞ is indeed a covariant function on D_∞ with values in \mathfrak{G}_0 . The properties of the limit group may be described in terms of this extended functor T_∞ .

THEOREM 21.1. *Let D be a directed set and T a covariant functor on D (regarded as a category) to \mathfrak{G}_0 . Then the limit group G of the direct system T and the projections of each group $T(d)$ into this limit determine as in (21.5) and (21.6) an extension of T to a covariant functor T_∞ on D_∞ to \mathfrak{G}_0 . If S_∞ is any other extension of T to a covariant functor on D_∞ to \mathfrak{G}_0 , there is a unique natural transformation $\sigma: T_\infty \rightarrow S_\infty$ such that each $\sigma(d)$ with $d \neq \infty$ is the identity.*

Proof. We have already seen that T_∞ is a covariant functor on D_∞ to \mathfrak{G}_0 , extending T . Let now S_∞ be any other functor extending T . Since $S(d_2, d_1) = T(d_2, d_1)$ for $d_2 < d_1$ in D , it follows from the functor condition on S_∞ that

$$(21.7) \quad S_\infty(\infty, d_2)T(d_2, d_1) = S_\infty(\infty, d_1).$$

We define a homomorphism

$$\sigma(\infty): T_\infty(\infty) \rightarrow S_\infty(\infty)$$

by setting $\sigma(\infty)(g, d) = S_\infty(\infty, d)g$ for every element $(g, d) \in T_\infty(\infty) = \text{Lim}_\rightarrow T$. Condition (21.7) implies that $\sigma(\infty)$ is single-valued. If we now set $\sigma(d)$ to be the identity mapping $T_\infty(d) \rightarrow S_\infty(d)$ for $d \neq \infty$, we have the desired transformation $\sigma: T_\infty \rightarrow S_\infty$.

The extension T_∞ and hence the limit group $G = T_\infty(\infty)$ of the given direct system is completely determined by the property given in the last sentence of the theorem. In fact if T'_∞ is any other extension of T with the same property as T_∞ , there will exist transformations $\sigma: T_\infty \rightarrow T'_\infty$ and $\sigma': T'_\infty \rightarrow T_\infty$. Then $\rho = \sigma'\sigma: T_\infty \rightarrow T_\infty$ with $\rho(d)$ the identity whenever $d \neq \infty$. It follows that

$$\rho(\infty)\lambda(d) = \rho(\infty)T(\infty, d) = T(\infty, d)\rho(d) = T(\infty, d) = \lambda(d)$$

and therefore for every (g, d) in G we get

$$\rho(\infty)(g, d) = \rho(\infty)\lambda(d)g = \lambda(d)g = (g, d).$$

Hence $\rho(\infty)$ is the identity and σ is a natural equivalence $\sigma: T_\infty \rightarrow T'_\infty$. In this way the limit group of a direct system of groups can be defined up to an isomorphism by means of such extensions of functors. This indicates that the concept (but not necessarily the existence) of direct "limits" could be set up not only for groups, but also for objects of any category.

THEOREM 21.2. *If T_1 and T_2 are two covariant functors on the directed category D with values in \mathfrak{G}_0 , and τ is a natural transformation $\tau: T_1 \rightarrow T_2$, there is only one extension τ_∞ of τ which is a natural transformation $\tau_\infty: T_{1\infty} \rightarrow T_{2\infty}$ between the extended functors on D_∞ . When τ is a natural equivalence so is τ_∞ .*

Proof. The naturality condition for τ , when applied to any mapping (d_2, d_1) with $d_1 < d_2$ in the directed set D reads

$$(21.8) \quad \tau(d_2)T_1(d_2, d_1) = T_2(d_2, d_1)\tau(d_1).$$

Given any element (g_1, d) of the limit group $T_{1\infty}(\infty) = \text{Lim}_\rightarrow T_1$ we define

$$(21.9) \quad \omega(g_1, d) = (\tau(d)g_1, d) \in \text{Lim}_\rightarrow T_2 = T_{2\infty}(\infty).$$

Condition (21.8) implies that this definition of ω gives a result independent of the special representation (g_1, d) chosen for the limit element. Hence we get a homomorphism

$$\omega: T_{1\infty}(\infty) \rightarrow T_{2\infty}(\infty).$$

In virtue of (21.6) and (21.3), the definition (21.9) becomes

$$(21.10) \quad \omega T_{1\infty}(\infty, d) = T_{2\infty}(\infty, d)\tau(d).$$

This means simply that by setting $\tau_\infty(d) = \tau(d)$, $\tau_\infty(\infty) = \omega$ we get an extension of τ which is still natural and which gives a transformation $\tau_\infty: T_{1\infty} \rightarrow T_{2\infty}$. Since the naturality condition (21.10) is equivalent with (21.9) which completely determines the value of $\tau_\infty(\infty)$, the requisite uniqueness follows. In particular, if τ is an equivalence, each $\tau(d)$ is an isomorphism "onto," hence it follows that $\omega = \tau_\infty(\infty)$ is also an isomorphism onto, and is an equivalence. This is just a restatement of the known theorem that "isomorphic" direct systems determine isomorphic limit groups.

THEOREM 21.3. *If T is a direct system of groups indexed by a directed set D , while H is a fixed discrete group, regarded as a (constant) covariant functor on D to \mathfrak{G}_0 , then for each natural transformation $\tau: T \rightarrow H$ there is a unique homomorphism τ_0 of the limit group $\text{Lim}_\rightarrow T$ into H with the property that $\tau(d) = \tau_0 \lambda(d)$ for each $d \in D$, where $\lambda(d)$ is the projection of $T(d)$ into $\text{Lim}_\rightarrow T$.*

Proof. This follows from the preceding theorem and from the remark that H_∞ is also a constant functor on D_∞ to \mathfrak{G}_0 .

22. Inverse limits as functors. Let D be a directed set. If for every $d \in D$ a topological group G_d is defined and for every pair $d_1 < d_2$ in D a homomorphism

$$(22.1) \quad \phi_{d_2, d_1}: G_{d_2} \rightarrow G_{d_1}$$

is given such that $\phi_{d, d}$ is the identity and that

$$(22.2) \quad \phi_{d_3, d_1} = \phi_{d_2, d_1} \phi_{d_3, d_2} \quad \text{for } d_1 < d_2 < d_3$$

then we say that the groups $\{G_d\}$ and the homomorphisms $\{\phi_{d_2, d_1}\}$ constitute an inverse system of groups indexed by D .

If we now regard D as a category, and define as before

$$(22.3) \quad T(d) = G_d$$

for every object d in D , and

$$(22.4) \quad T(\delta) = T(d_2, d_1) = \phi_{d_2, d_1}$$

for every mapping $\delta = (d_2, d_1)$ in D , it is clear that T is a contravariant functor on D with values in the category \mathfrak{G} of topological groups. Conversely any such functor may be regarded as an inverse system of groups.

With each inverse system of groups T there is associated a limit group $G = \text{Lim}_\leftarrow T$ defined as follows. An element of G is a function $g(d)$ which assigns to each element $d \in D$ an element $g(d) \in T(d)$, in such wise that these elements "match" under the mappings; that is, such that $T(d_2, d_1)g(d_2) = g(d_1)$ whenever $d_1 < d_2$. The sum of $g_1 + g_2$ is defined as $(g_1 + g_2)(d) = g_1(d) + g_2(d)$. This limit group G is assigned a topology, in known fashion, by treating G as a subgroup of the direct product of the groups $T(d)$, with the usual direct product topology. For fixed d , the (continuous) projection $\mu(d)$ of the limit group G into $T(d)$ is defined by setting $[\mu(d)]g = g(d)$, for $g \in G$.

Again we may consider the extended category D_∞ and define the extension T_∞ of T by setting

$$(22.5) \quad T_\infty(\infty) = G, \quad T_\infty(\infty, d) = \mu(d).$$

As before the following theorem can be established:

THEOREM 22.1. *Let D be a directed set and T a contravariant functor on D (regarded as a category) to \mathfrak{G} . Then the limit group G of the inverse system T*

and the projections of this limit group into each group $T(d)$ determine as in (22.5) an extension of T to a contravariant functor T_∞ on D_∞ to \mathfrak{G} . If S_∞ is any other extension of T to a contravariant functor on D_∞ to \mathfrak{G} , there is a unique natural transformation $\sigma: S_\infty \rightarrow T_\infty$ such that each $\sigma(d)$ with $d \neq \infty$ is the identity.

As before we can also verify that the second half of the theorem determines the extended functor T_∞ to within a natural equivalence, and therefore it determines the limit group to within an isomorphism.

The following two theorems may also be proved as in the preceding section.

THEOREM 22.2. *If T_1 and T_2 are two contravariant functors on the directed category D with values in \mathfrak{G} , and τ is a natural transformation $\tau: T_1 \rightarrow T_2$, there is only one extension τ_∞ of τ which is a natural transformation $\tau_\infty: T_{1\infty} \rightarrow T_{2\infty}$ between the extended functors on D_∞ . When τ is a natural equivalence so is τ_∞ .*

THEOREM 22.3. *If T is an inverse system of groups indexed by the directed set D , while K is a fixed topological group regarded as a (constant) contravariant functor on D to \mathfrak{G} , then for each natural transformation $\tau: T \rightarrow K$ there is a unique homomorphism $\tau_0: \text{Lim}_\leftarrow T \rightarrow K$ such that $\tau_0 = \tau(d)\lambda(d)$ for each $d \in D$.*

The preceding discussion carries over to inverse systems of spaces, by a mere replacement of the category of topological groups \mathfrak{G} by the category of topological spaces \mathfrak{X} .

23. The categories “Dir” and “Inv.” The process of forming a direct or inverse limit of a system of groups can be treated as a functor “Lim $_+$ ” or “Lim $_-$ ” which operates on an appropriately defined category. Thus the functor “Lim $_+$ ” will operate on any direct system T defined on any directed set D . Consequently we define a category “Dir” of directed systems whose objects are such pairs (D, T) . Here we may regard D itself as a category and T as a covariant functor on D to \mathfrak{G}_0 . To introduce the mappings of this category, observe first that each order preserving transformation R of a directed set D_1 into another such set D_2 will give for each direct system T_2 of groups indexed by D_2 an induced direct system indexed by D_1 . Specifically, the induced direct system is just the composite $T_2 \otimes R$ of the (covariant) functor R on D_1 to D_2 and the (covariant) functor T_2 on D_2 to \mathfrak{G}_0 . Given two objects (D_1, T_1) and (D_2, T_2) of Dir, a mapping

$$(R, \rho): (D_1, T_1) \rightarrow (D_2, T_2)$$

of the category Dir is a pair (R, ρ) composed of a covariant functor R on D_1 to D_2 and a natural transformation

$$\rho: T_1 \rightarrow T_2 \otimes R$$

of T_1 into the composite functor $T_2 \otimes R$.

To form the product of two such mappings

$$(23.1) \quad (R_1, \rho_1):(D_1, T_1) \rightarrow (D_2, T_2), \quad (R_2, \rho_2):(D_2, T_2) \rightarrow (D_3, T_3)$$

observe first that the functors T_2 and $T_3 \otimes R_2$ on D_2 to \mathcal{G}_0 can be compounded with the functor R_1 on D_1 to D_2 , and hence that the given transformation $\rho_2:T_2 \rightarrow T_3 \otimes R_2$ can be compounded with the identity transformation of R_1 into itself, just as in §9.

The result is a composite transformation

$$(23.2) \quad \rho_2 \otimes R_1:T_2 \otimes R_1 \rightarrow T_3 \otimes R_2 \otimes R_1$$

which assigns to each object $d_1 \in D_1$ the mapping $[\rho_2 \otimes R_1](d_1) = \rho_2(R_1 d_1)$ of $T_2(R_1 d_1)$ into $T_3 \otimes R_2(R_1 d_1)$. The transformations (23.2) and $\rho_1:T_1 \rightarrow T_2 \otimes R_1$ yield as in §9 a composite transformation $\rho_2 \otimes R_1 \otimes \rho_1:T_1 \rightarrow T_3 \otimes R_2 \otimes R_1$. We may now define the product of two given mappings (23.1) to be

$$(R_2, \rho_2)(R_1, \rho_1) = (R_2 \otimes R_1, \rho_2 \otimes R_1 \otimes \rho_1).$$

With these conventions, we verify that \mathfrak{Dir} is a category. Its identities are the pairs (R, ρ) in which both R and ρ are identities; its equivalences are the pairs (R, ρ) in which R is an isomorphism and ρ a natural equivalence.

The effect of fixing the directed set D in the objects (D, T) of the category \mathfrak{Dir} is to restrict \mathfrak{Dir} to the subcategory which consists of all direct systems of groups indexed by D (that is, the category of all covariant functors on D to \mathcal{G}_0 , as defined in §8).

We shall now define Lim_\rightarrow as a covariant functor on \mathfrak{Dir} with values in \mathcal{G}_0 . For each object (D, T) of \mathfrak{Dir} we define $\text{Lim}_\rightarrow(D, T)$ to be the group obtained as the direct limit of the direct system of groups T indexed by the directed set D . Given a mapping

$$(23.3) \quad (R, \rho):(D_1, T_1) \rightarrow (D_2, T_2) \quad \text{in } \mathfrak{Dir}$$

we define the mapping function of Lim_\rightarrow ,

$$(23.4) \quad \text{Lim}_\rightarrow(R, \rho):\text{Lim}_\rightarrow(D_1, T_1) \rightarrow \text{Lim}_\rightarrow(D_2, T_2),$$

as follows. An element in the limit group $\text{Lim}(D_1, T_1)$ is a pair (g_1, d_1) with $d_1 \in D_1, g_1 \in T_1(d_1)$. For each such element define $\phi(g_1, d_1)$ to be the pair $(\rho(d_1)g_1, R d_1)$. Since $\rho(d_1)$ maps $T_1(d_1)$ into $T_2(R d_1)$ we have $\rho(d_1)g_1$ in $T_2(R d_1)$, so that the resulting pair is indeed in the limit group $\text{Lim}_\rightarrow(D_2, T_2)$. The mapping ϕ carries equal pairs into equal pairs, and yields the requisite homomorphism (23.4). We verify that Lim_\rightarrow , defined in this manner, is a covariant functor on \mathfrak{Dir} to \mathcal{G}_0 .

Alternatively, the mapping function of this functor " Lim_\rightarrow " can be obtained by extensions of mappings to the directed sets $D_{1\infty}, D_{2\infty}$ (with ∞ added), defined as in §21. Given the mapping (R, ρ) of (23.3), first extend the given objects of \mathfrak{Dir} to obtain new objects $(D_{1\infty}, T_{1\infty})$ and $(D_{2\infty}, T_{2\infty})$. The given functor R on D_1 to D_2 can also be extended by setting $R_\infty(\infty) = \infty$; this

gives a functor R_∞ on $D_{1\infty}$ to $D_{2\infty}$. Furthermore, Theorem 21.2 asserts that the transformation $\rho: T_1 \rightarrow T_2 \otimes R$ has then a unique extension $\rho_\infty: T_{1\infty} \rightarrow T_{2\infty} \otimes R_\infty$. All told, we have a new mapping

$$(R_\infty, \rho_\infty): (D_{1\infty}, T_{1\infty}) \rightarrow (D_{2\infty}, T_{2\infty})$$

in \mathfrak{Dir} . In particular, when ρ_∞ is applied to the new element ∞ of $D_{1\infty}$, it yields a homomorphism of the limit group of T_1 into the limit group of $T_2 \otimes R$. On the other hand, R determines a homomorphism R^\sharp of the limit group of $T_2 \otimes R$ into the limit group of T_2 ; explicitly, for (g_1, d_1) in the first limit group, the image $R^\sharp(g_1, d_1)$ is the element (g_1, Rd_1) in the second limit group. The requisite mapping function of the functor " Lim_∞ " is now defined by setting

$$\text{Lim}_\infty(R, \rho) = R^\sharp(\rho_\infty(\infty)).$$

In a similar way we define the category \mathfrak{Inb} . The objects of \mathfrak{Inb} are pairs (D, T) where D is a directed set and T is an inverse system of topological groups indexed by D (that is, T is a contravariant functor on D to \mathfrak{G}). The mappings in \mathfrak{Inb} are pairs (R, ρ)

$$(R, \rho): (D_1, T_1) \rightarrow (D_2, T_2)$$

where R is a covariant functor on D_2 to D_1 (that is, an order preserving transformation of D_2 into D_1) and ρ is a natural transformation of the functors

$$\rho: T_1 \otimes R \rightarrow T_2$$

both contravariant on D_2 to \mathfrak{G} . The product of two mappings

$$(R_1, \rho_1): (D_1, T_1) \rightarrow (D_2, T_2), \quad (R_2, \rho_2): (D_2, T_2) \rightarrow (D_3, T_3)$$

is defined as

$$(R_2, \rho_2)(R_1, \rho_1) = (R_1 \otimes R_2, \rho_2 \otimes \rho_1 \otimes R_2)$$

where $\rho_1 \otimes R_2$ is the transformation

$$\rho_1 \otimes R_2: T_1 \otimes R_1 \otimes R_2 \rightarrow T_2 \otimes R_2$$

induced (as in §9) by

$$\rho_1: T_1 \otimes R_1 \rightarrow T_2.$$

With these conventions, we verify that \mathfrak{Inb} is a category.

We shall now define Lim_∞ as a covariant functor on \mathfrak{Inb} with values in \mathfrak{G} . For each object (D, T) in \mathfrak{Inb} we define $\text{Lim}_\infty(D, T)$ to be the inverse limit of the inverse system of groups T indexed by the directed set D . Given a mapping

$$(23.5) \quad (R, \rho): (D_1, T_1) \rightarrow (D_2, T_2) \text{ in } \mathfrak{Inb}$$

we define the mapping function of Lim_∞

$$(23.6) \quad \text{Lim}_{\leftarrow} (R, \rho) : \text{Lim}_{\leftarrow} (D_1, T_1) \rightarrow \text{Lim}_{\leftarrow} (D_2, T_2)$$

as follows. Each element of $\text{Lim}_{\leftarrow} (D_1, T_1)$ is a function $g(d_1)$ with values $g(d_1) \in T_1(d_1)$, for $d_1 \in D_1$, which match properly under the projections in T_1 . Now define a new function h , with

$$h(d_2) = \rho(d_2)g(Rd_2), \quad d_2 \in D_2;$$

it is easy to verify that h is an element of the limit group $\text{Lim} (D_2, T_2)$. The correspondence $g \rightarrow h$ is the homomorphism (23.6) required for the definition of the mapping function of Lim_{\leftarrow} . One may verify that this definition does yield a covariant functor Lim_{\leftarrow} on the category \mathfrak{Snb} to \mathfrak{G} .

The mapping function of Lim_{\leftarrow} may again be obtained by first extending the given mapping (23.5) to

$$(R_{\infty}, \rho_{\infty}) : (D_{1\infty}, T_{1\infty}) \rightarrow (D_{2\infty}, T_{2\infty}) \text{ in } \mathfrak{Snb}.$$

In particular, when the extended transformation ρ_{∞} is applied to the element ∞ of $D_{1\infty}$, we obtain a homomorphism of the limit group of $T_1 \otimes R$ into the limit group of T_2 . On the other hand, the covariant functor R on D_2 to D_1 determines a homomorphism R^* of the limit group of (D_1, T_1) into the limit group of $(D_2, T_1 \otimes R)$; explicitly, for each function $g(d_1)$ in the first limit group, the image $h = R^*g$ in the second limit group is defined by setting $h(d_2) = g(Rd_2)$ for each $d_2 \in D_2$. The mapping function of the functor “ Lim_{\leftarrow} ” is now $\text{Lim}_{\leftarrow} (R, \rho) = \rho_{\infty}(\infty)R^*$.

24. The lifting principle. Let Q be a functor whose arguments and values are groups, while T is any direct or inverse system of groups. If the object function of Q is applied to each group $T(d)$ of the given system, while the mapping function of Q is applied to each projection $T(d_1, d_2)$ of the given system, we obtain a new system of groups, which may be called $Q \otimes T$. If Q is covariant, T and $Q \otimes T$ are both direct or both inverse, while if Q is contravariant, $Q \otimes T$ is inverse when T is direct, and vice versa.

Actually this new system $Q \otimes T$ is simply the composite of the functor T with the functor Q (see §9). We may regard this composition as a process which “lifts” a functor Q whose arguments and values are groups to a functor Q_L whose arguments and values are direct (or inverse) systems of groups. We may then regard the lifted functor as one acting on the categories \mathfrak{Dir} and \mathfrak{Snb} , as the case may be. In every case, the lifted functor has its object and mapping functions given formally by the equations (in the “cross” notation for composites)

$$(24.1) \quad Q_L(D, T) = (D, Q \otimes T), \quad Q_L(R, \rho) = (R, Q \otimes \rho).$$

This formula includes the following four cases:

- (I) Q covariant on \mathfrak{G}_0 to \mathfrak{G}_0 ; Q_L covariant on \mathfrak{Dir} to \mathfrak{Dir} .
- (II) Q contravariant on \mathfrak{G}_0 to \mathfrak{G} ; Q_L contravariant on \mathfrak{Dir} to \mathfrak{Snb} .

(III) Q covariant on \mathfrak{G} to \mathfrak{G} ; Q_L covariant on \mathfrak{Snb} to \mathfrak{Snb} .

(IV) Q contravariant on \mathfrak{G} to \mathfrak{G}_0 ; Q_L contravariant on \mathfrak{Snb} to \mathfrak{Dir} .

For illustration, we discuss case (II), in which Q is given contravariant on \mathfrak{G}_0 to \mathfrak{G} . The object function of Q_L , as defined in the first equation of (24.1), assigns to each object (D, T) of the category \mathfrak{Dir} a pair $(D, Q \otimes T)$. Since T is covariant on D to \mathfrak{G}_0 and Q contravariant on \mathfrak{G}_0 to \mathfrak{G} , the composite $Q \otimes T$ is contravariant on D to \mathfrak{G} , so that $Q \otimes T$ is an inverse system of groups, and the pair $(D, Q \otimes T)$ is an object of \mathfrak{Snb} . On the other hand, given a mapping

$$(R, \rho): (D_1, T_1) \rightarrow (D_2, T_2) \text{ in } \mathfrak{Dir},$$

with $\rho: T_1 \rightarrow T_2 \otimes R$, the composite transformation $Q \otimes \rho$ is obtained by applying the mapping function of Q to each homomorphism $\rho(d_1): T_1(d_1) \rightarrow T_2 \otimes R(d_1)$, and this gives a transformation $Q \otimes \rho: Q \otimes T_2 \otimes R \rightarrow Q \otimes T_1$. Thus the mapping function of Q_L , as defined in (24.1), does give a mapping $(R, Q \otimes \rho): (D_2, Q \otimes T_2) \rightarrow (D_1, Q \otimes T_1)$ in the category \mathfrak{Snb} . We verify that Q_L is a contravariant functor on \mathfrak{Dir} to \mathfrak{Snb} .

Any natural transformation $\kappa_1: Q \rightarrow P$ induces a transformation on the lifted functors, $\kappa_L: Q_L \rightarrow P_L$, obtained by composition of the transformation κ with the identity transformation of each T , as

$$\kappa_L(D, T) = (D, \kappa \otimes T).$$

If κ is an equivalence, so is this "lifted" transformation.

Just as in the case of composition, the operation of "lifting" can itself be regarded as a functor "Lift," defined on a suitable category of functors Q . In all four cases (I)-(IV), this functor "Lift" is covariant.

In all these cases the functor Q may originally contain any number of additional variables. The lifted functor Q_L will then involve the same extra variables with the same variance. With proper caution the lifting process may also be applied simultaneously to a functor Q with two variables, both of which are groups.

25. Functors which commute with limits. Certain operations, such as the formation of the character groups of discrete or compact groups, are known to "commute" with the passage to a limit. Using the lifting operation, this can be formulated exactly.

To illustrate, let Q be a covariant functor on \mathfrak{G}_0 to \mathfrak{G}_0 , and Q_L the corresponding covariant lifted functor on \mathfrak{Dir} to \mathfrak{Dir} , as in case (I) of §24. Since Lim_\rightarrow is a covariant functor on \mathfrak{Dir} to \mathfrak{G}_0 , we have two composite functors

$$\text{Lim}_\rightarrow \otimes Q_L \text{ and } Q \otimes \text{Lim}_\rightarrow,$$

both covariant on \mathfrak{Dir} to \mathfrak{G}_0 . There is also an explicit natural transformation

$$(25.1) \quad \omega_1: \text{Lim}_\rightarrow \otimes Q_L \rightarrow Q \otimes \text{Lim}_\rightarrow,$$

defined as follows. Let the pair (D, T) be a direct system of groups in the

category \mathfrak{Dir} , and let $\lambda(d)$ be the projection

$$\lambda(d): T(d) \rightarrow \text{Lim}_\rightarrow T, \quad d \in D.$$

Then, on applying the mapping function of Q to λ , we obtain the natural transformation

$$Q\lambda(d): QT(d) \rightarrow Q[\text{Lim}_\rightarrow T].$$

Theorem 21.3 now gives a homomorphism

$$\omega_I(T): \text{Lim}_\rightarrow [Q \otimes T] \rightarrow Q[\text{Lim}_\rightarrow T],$$

or, exhibiting D explicitly, a homomorphism

$$\omega_I(D, T): \text{Lim } Q_L(D, T) \rightarrow Q[\text{Lim}_\rightarrow (D, T)].$$

We verify that ω_I , so defined, satisfies the naturality condition.

Similarly, to treat case (II), consider a contravariant functor Q on \mathfrak{G}_0 to \mathfrak{G} and the lifted functor Q_L on \mathfrak{Dir} to \mathfrak{Inb} . We then construct an explicit natural transformation

$$(25.2) \quad \omega_{II}: Q \otimes \text{Lim}_\rightarrow \rightarrow \text{Lim}_\leftarrow \otimes Q_L$$

(note the order !), defined as follows. Let the pair (D, T) be in \mathfrak{Dir} , and let $\lambda(d)$ be the projection

$$\lambda(d): T(d) \rightarrow \text{Lim}_\rightarrow T, \quad d \in D.$$

On applying Q , we get

$$Q\lambda(d): Q[\text{Lim}_\rightarrow T] \rightarrow QT(d).$$

The Theorem 22.3 for inverse systems now gives a homomorphism

$$\omega_{II}(D, T): Q[\text{Lim}_\rightarrow (D, T)] \rightarrow \text{Lim}_\leftarrow Q_L(D, T).$$

In the remaining cases (III) and (IV) similar arguments give natural transformations

$$(25.3) \quad \omega_{III}: Q \otimes \text{Lim}_\leftarrow \rightarrow \text{Lim}_\leftarrow \otimes Q_L,$$

$$(25.4) \quad \omega_{IV}: \text{Lim}_\rightarrow \otimes Q_L \rightarrow Q \otimes \text{Lim}_\leftarrow.$$

DEFINITION. The functor Q defined on groups to groups is said to commute (more precisely to ω -commute) with Lim if the appropriate one of the four natural transformations ω above is an equivalence.

In other words, the proof that a functor Q commutes with Lim requires only the verification that the homomorphisms defined above are isomorphisms. The naturality condition holds in general!

To illustrate these concepts, consider the functor C which assigns to each discrete group G its commutator subgroup $C(G)$, and consider a direct system T of groups, indexed by D . Then the lifted functor Q (case (I) of §24) applied

to the pair (D, T) in \mathfrak{Dir} gives a new direct system of groups, still indexed by D , with the groups $T(d)$ of the original system replaced by their commutator subgroups $CT(d)$, and with the projections correspondingly cut down. It may be readily verified that this functor does commute with Lim .

Another functor Q is the subfunctor of the identity which assigns to each discrete abelian group G the subgroup $Q(G)$ consisting of those elements $g \in G$ such that there is for each integer m an $x \in G$ with $mx = g$ (that is, of those elements of G which are divisible by every integer), Q is a covariant functor with arguments and values in the subcategory G_{0a} of discrete abelian groups. The lifted functor Q_L will be covariant, with arguments and values in the subcategory \mathfrak{Dir}_a of \mathfrak{Dir} , obtained by restricting attention to abelian groups. This functor Q clearly does not commute with Lim , since one may represent the additive group of rational numbers as a direct limit of cyclic groups Z for which each subgroup $Q(Z)$ is the group consisting of zero alone.

The formation of character groups gives further examples. If we consider the functor Char as a contravariant functor on the category \mathfrak{G}_{0a} of discrete abelian groups to the category \mathfrak{G}_{ca} of compact abelian groups, the lifted functor Char_L will be covariant on the appropriate subcategory of \mathfrak{Dir} to \mathfrak{Inb} as in case (II) of §24. This lifted functor Char_L applied to any direct system (D, T) of discrete abelian groups will yield an inverse system of compact abelian groups, indexed by the same set D . Each group of the inverse system is the character group of the corresponding group of the direct system, and the projections of the inverse system are the induced mappings.

On the other hand, there is a contravariant functor Char on \mathfrak{G}_{ca} to \mathfrak{G}_{0a} . In this case the lifted functor Char_L will be contravariant on a suitable subcategory of \mathfrak{Inb} with values in \mathfrak{Dir} , just as in case (III) of §24. Both these functors Char commute with Lim .

CHAPTER V. APPLICATIONS TO TOPOLOGY⁽²⁴⁾

26. Complexes. An abstract complex K (in the sense of W. Mayer) is a collection

$$\{C^q(K)\}, \quad q = 0, \pm 1, \pm 2, \dots,$$

of free abelian discrete groups, together with a collection of homomorphisms

$$\partial^q: C^q(K) \rightarrow C^{q-1}(K)$$

called boundary homomorphisms, such that

$$\partial^q \partial^{q+1} = 0.$$

By selecting for each of the free groups C^q a fixed basis $\{\sigma_i^q\}$ we obtain a complex which is substantially an abstract complex in the sense of A. W.

⁽²⁴⁾ General reference: S. Lefschetz, *Algebraic topology*, Amer. Math. Soc. Colloquium Publications, vol. 27, New York, 1942.

Tucker. The σ_i^q will be called q -dimensional cells. The boundary operator ∂ can be written as a finite sum

$$\partial\sigma^q = \sum_{\sigma^{q-1}} [\sigma^q; \sigma^{q-1}] \sigma^{q-1}.$$

The integers $[\sigma^q; \sigma^{q-1}]$ are called incidence numbers, and satisfy the following conditions:

(26.1) Given σ^q , $[\sigma^q; \sigma^{q-1}] \neq 0$ only for a finite number of $(q-1)$ -cells σ^{q-1} .

(26.2) Given σ^{q+1} and σ^{q-1} , $\sum_{\sigma^q} [\sigma^{q+1}; \sigma^q] [\sigma^q; \sigma^{q-1}] = 0$.

Condition (26.1) indicates that we are confronted with an abstract complex of the closure finite type. Consequently we shall define (§27) homologies based on finite chains and cohomologies based on infinite cochains.

Our preference for complexes à la W. Mayer is due to the fact that they seem to be best adapted for the exposition of the homology theory in terms of functors.

Given two abstract complexes K_1 and K_2 , a chain transformation

$$\kappa: K_1 \rightarrow K_2$$

will mean a collection $\kappa = \{\kappa^q\}$ of homomorphisms,

$$\kappa^q: C^q(K_1) \rightarrow C^q(K_2),$$

such that

$$\kappa^{q-1} \partial^q = \partial^q \kappa^q.$$

In this way we are led to the category \mathfrak{K} whose objects are the abstract complexes (in the sense of W. Mayer) and whose mappings are the chain transformations with obvious definition of the composition of chain transformations.

The consideration of simplicial complexes and of simplicial transformations leads to a category \mathfrak{K}_s . As is well known, every simplicial complex uniquely determines an abstract complex, and every simplicial transformation a chain transformation. This leads to a covariant functor on \mathfrak{K}_s to \mathfrak{K} .

27. Homology and cohomology groups. For every complex K in the category \mathfrak{K} and every group G in the category \mathfrak{G}_{0a} of discrete abelian groups we define the groups $C^q(K, G)$ of the q -dimensional chains of K over G as the tensor product

$$C^q(K, G) = G \circ C^q(K),$$

that is, $C^q(K, G)$ is the group with the symbols

$$gc^q, \quad g \in G, c^q \in C^q(K)$$

as generators, and

$$(g_1 + g_2)c^q = g_1c^q + g_2c^q, \quad g(c_1^q + c_2^q) = gc_1^q + gc_2^q$$

as relations.

For every chain transformation $\kappa:K_1 \rightarrow K_2$ and for every homomorphism $\gamma:G_1 \rightarrow G_2$ we define a homomorphism

$$C^q(\kappa, \gamma):C^q(K_1, G_1) \rightarrow C^q(K_2, G_2)$$

by setting

$$C^q(\kappa, \gamma)(g_1c_1^q) = \gamma(g_1)\kappa^q(c_1^q)$$

for each generator $g_1c_1^q$ of $C^q(K_1, G_1)$.

These definitions of $C^q(K, G)$ and of $C^q(\kappa, \gamma)$ yield a functor C^q covariant in \mathfrak{K} and in \mathfrak{G}_{0a} with values in \mathfrak{G}_{0a} . This functor will be called the q -chain functor.

We define a homomorphism

$$\partial^q(K, G):C^q(K, G) \rightarrow C^{q-1}(K, G)$$

by setting

$$\partial^q(K, G)(gc^q) = g\partial c^q$$

for each generator gc^q of $C^q(K, G)$. Thus the boundary operator becomes a natural transformation of the functor C^q into the functor C^{q-1}

$$\partial^q:C^q \rightarrow C^{q-1}.$$

The kernel of this transformation will be denoted by Z^q and will be called the q -cycle functor. Its object function is the group $Z^q(K, G)$ of the q -dimensional cycles of the complex K over G .

The image of C^q under the transformation ∂^q is a subfunctor $B^{q-1} = \partial^q(C^q)$ of C^{q-1} . Its object function is the group $B^{q-1}(K, G)$ of the $(q-1)$ -dimensional boundaries in K over G .

The fact that $\partial^q\partial^{q+1} = 0$ implies that $B^q(K, G)$ is a subgroup of $Z^q(K, G)$. Consequently B^q is a subfunctor of Z^q . The quotient functor

$$H^q = Z^q/B^q$$

is called the q th homology functor. Its object function associates with each complex K and with each discrete abelian coefficient group G the q th homology group $H^q(K, G)$ of K over G . The functor H^q is covariant in \mathfrak{K} and \mathfrak{G}_{0a} and has values in \mathfrak{G}_{0a} .

In order to define the cohomology groups as functors we consider the category \mathfrak{K} as before and the category \mathfrak{G}_a of topological abelian groups. Given a complex K in \mathfrak{K} and a group G in \mathfrak{G}_a we define the group $C^q(K, G)$ of the q -dimensional cochains of K over G as

$$C_q(K, G) = \text{Hom}(C^q(K), G).$$

Given a chain transformation $\kappa: K_1 \rightarrow K_2$ and a homomorphism $\gamma: G_1 \rightarrow G_2$, we define a homomorphism

$$C_q(\kappa, \gamma): C_q(K_2, G_1) \rightarrow C_q(K_1, G_2)$$

by associating with each homomorphism $f \in C_q(K_2, G_1)$ the homomorphism $\bar{f} = C_q(\kappa, \gamma)f$, defined as follows:

$$\bar{f}(c_1^q) = \gamma[f(\kappa^q c_1^q)], \quad c_1^q \in C^q(K_1).$$

By comparing this definition with the definition of the functor Hom , we observe that $C_q(\kappa, \gamma)$ is in fact just $\text{Hom}(\kappa^q, \gamma)$.

The definitions of $C_q(K, G)$ and $C_q(\kappa, \gamma)$ yield a functor C_q contravariant in \mathfrak{R} , covariant in \mathfrak{G}_a , and with values in \mathfrak{G}_a . This functor will be called the q th cochain functor.

The coboundary homomorphism

$$\delta_q(K, G): C_q(K, G) \rightarrow C_{q+1}(K, G)$$

is defined by setting, for each cochain $f \in C_q(K, G)$,

$$(\delta_q f)(c^{q+1}) = f(\partial^{q+1} c^{q+1}).$$

This leads to a natural transformation of functors

$$\delta_q: C_q \rightarrow C_{q+1}.$$

We may observe that in terms of the functor "Hom" we have $\delta_q(K, G) = \text{Hom}(\partial^{q+1}, e_G)$.

The kernel of the transformation δ_q is denoted by Z_q and is called the q -cocycle functor. The image functor of δ_q is denoted by B_{q+1} and is called the $(q+1)$ -coboundary functor. Since $\partial^q \partial^{q+1} = 0$, we may easily deduce that B_q is a subfunctor of Z_q . The quotient-functor

$$H_q = Z_q / B_q$$

is, by definition, the q th cohomology functor. H_q is contravariant in \mathfrak{R} , covariant in \mathfrak{G}_a , and has values in \mathfrak{G}_a . Its object function associates with each complex K and each topological abelian group G the (topological abelian) q th cohomology group $H_q(K, G)$.

The fact that the homology groups are discrete and have discrete coefficient groups, while the cohomology groups are topologized and have topological coefficient groups, is due to the circumstance that the complexes considered are closure finite. In a star finite complex the relation would be reversed.

For "finite" complexes both homology and cohomology groups may be topological. Let \mathfrak{R}_f denote the subcategory of \mathfrak{R} determined by all those complexes K such that all the groups $C^q(K)$ have finite rank. If $K \in \mathfrak{R}_f$ and

G is a topological group, then the group $C^q(K, G) = G \circ C^q(K)$ can be topologized in a natural fashion and consequently $H^q(K, G)$ will be topological. Hence both H^q and H_q may be regarded as functors on \mathfrak{R}_f and \mathfrak{G}_a with values in \mathfrak{G}_a . The first one is covariant in both \mathfrak{R}_f and \mathfrak{G}_a , while the second one is contravariant in \mathfrak{R}_f and covariant in \mathfrak{G}_a .

28. Duality. Let G be a discrete abelian group and $\text{Char } G$ be its (compact) character group (see §19).

Given a chain

$$c^q \in C^q(K, G)$$

where

$$c^q = \sum_i g_i c_i^q, \quad g_i \in G, c_i^q \in C^q(K),$$

and given a cochain

$$f \in C_q(K, \text{Char } G),$$

we may define the Kronecker index

$$KI(f, c^q) = \sum_i (f(c_i^q), g_i).$$

Since $f(c_i^q)$ is an element of $\text{Char } G$, its application to g_i gives an element of the group P of reals reduced mod 1. The continuity of $KI(f, c^q)$ as a function of f follows from the definition of the topology in $\text{Char } G$ and in $C_q(K, \text{Char } G)$.

As a preliminary to the duality theorem, we define an isomorphism

$$(28.1) \quad \tau^q(K, G): C_q(K, \text{Char } G) \rightleftharpoons \text{Char } C^q(K, G),$$

by defining for each cochain $f \in C_q(K, \text{Char } G)$ a character

$$\tau^q(K, G)f: C^q(K, G) \rightarrow P,$$

as follows:

$$(\tau^q f, c^q) = KI(f, c^q).$$

The fact that $\tau^q(K, G)$ is an isomorphism is a direct consequence of the character theory. In (28.1) both sides should be interpreted as object functions of functors (contravariant in both K and G), suitably compounded from the functors C^q , C_q , and Char . In order to prove that (28.1) is natural, consider

$$\kappa: K_1 \rightarrow K_2 \text{ in } \mathfrak{R}, \quad \gamma: G_1 \rightarrow G_2 \text{ in } \mathfrak{G}_{0a}.$$

We must prove that

$$(28.2) \quad \tau^q(K_1, G_1)C_q(\kappa, \text{Char } \gamma) = [\text{Char } C^q(\kappa, \gamma)]\tau^q(K_2, G_2).$$

If now

$$f \in C_q(K_2, G_2), \quad c^q \in C^q(K_1, G_1),$$

then the definition of τ^q shows that (28.2) is equivalent to the identity

$$(28.3) \quad KI(C_q(\kappa, \text{Char } \gamma)f, c^q) = KI(f, C^q(\kappa, \gamma)c^q).$$

It will be sufficient to establish (28.3) in the case when c^q is a generator of $C^q(K_1, G_1)$,

$$c^q = g_1 c_1^q, \quad g_1 \in G_1, c_1^q \in C^q(K_2).$$

Using the definition of the terms involved in (28.3) we have on the one hand

$$\begin{aligned} KI(C_q(\kappa, \text{Char } \gamma)f, g_1 c_1^q) &= ([C_q(\kappa, \text{Char } \gamma)f]_{c_1^q}, g_1) \\ &= (\text{Char } \gamma[f(\kappa c_1^q)]_{g_1}) = (f(\kappa c_1^q), \gamma g_1), \end{aligned}$$

and on the other hand

$$KI(f, C^q(\kappa, \gamma)g_1 c_1^q) = KI(f, (\gamma g_1)(\kappa c_1^q)) = (f(\kappa c_1^q), \gamma g_1).$$

This completes the proof of the naturality of (28.1).

Using the well known property of the Kronecker index

$$KI(f, \partial^{q+1}c^{q+1}) = KI(\delta_q f, c^{q+1}),$$

one shows easily that under the isomorphism τ^q of (28.1)

$$\tau^q[Z_q(K, \text{Char } G)] = \text{Annih } B^q(K, G), \quad \tau^q[B_q(K, \text{Char } G)] = \text{Annih } Z^q(K, G),$$

with "Annih" defined as in §19. Both Annih ($B^q; C^q$) and Annih ($Z^q; C^q$) are functors covariant in K and G ; the latter is a subfunctor of the former, so that τ^q induces a natural isomorphism

$$\sigma^q: Z_q(K, \text{Char } G)/B_q(K, \text{Char } G) \rightleftharpoons \text{Annih } B^q(K, G)/\text{Annih } Z^q(K, G).$$

The group on the left is $H_q(K, \text{Char } G)$. The group on the right is, according to (19.7), naturally isomorphic to $\text{Char } Z^q(K, G)/B^q(K, G)$. All told we have a natural isomorphism:

$$\rho^q: H_q(K, \text{Char } G) \rightleftharpoons \text{Char } H^q(K, G).$$

This is the customary Pontrjagin-type duality between homology and cohomology. Thus we have established the naturality of this duality.

29. Universal coefficient theorems. The theorems of this name express the cohomology groups of a complex, for an arbitrary coefficient group, in terms of the integral homology groups and the coefficient group itself. A quite general form of such theorems can be stated in terms of certain groups of group extensions⁽²⁶⁾; hence we first show that the basic constructions of group extensions may be regarded as functors.

Let G be a topological abelian group and H a discrete abelian group. A factor set of H in G is a function $f(h, k)$ which assigns to each pair h, k of elements in H an element $f(h, k) \in G$ in such wise that

⁽²⁶⁾ S. Eilenberg and S. MacLane, *Group extensions and homology*, Ann. of Math. vol. 43 (1943) pp. 757-831.

$$f(h, k) = f(k, h), \quad f(h, k) + f(h + k, l) = f(h, k + l) + f(k, l),$$

for all h, k , and l in H . With the natural addition and topology, the set of all factor sets f of H in G constitute a topological abelian group $\text{Fact}(G, H)$. If $\gamma: G_1 \rightarrow G_2$ and $\eta: H_1 \rightarrow H_2$ are homomorphisms, we can define a corresponding mapping

$$\text{Fact}(\gamma, \eta): \text{Fact}(G_1, H_2) \rightarrow \text{Fact}(G_2, H_1)$$

by setting

$$[\text{Fact}(\gamma, \eta)f](h_1, k_1) = \gamma f(\eta h_1, \eta k_1)$$

for each factor set f in $\text{Fact}(G_1, H_2)$. Thus it appears that Fact is a functor, covariant on the category \mathfrak{G}_a of topological abelian groups and contravariant in the category \mathfrak{G}_{0a} of discrete abelian groups.

Given any function $g(h)$ with values in G , the combination

$$f(h, k) = g(h) + g(k) - g(h + k)$$

is always a factor set; the factor sets of this special form are said to be transformation sets, and the set of all transformation sets is a subgroup $\text{Trans}(G, H)$ of the group $\text{Fact}(G, H)$. Furthermore, this subgroup is the object function of a subfunctor. The corresponding quotient functor

$$\text{Ext} = \text{Fact}/\text{Trans}$$

is thus covariant in \mathfrak{G}_a , contravariant in \mathfrak{G}_{0a} , and has values in \mathfrak{G}_a . Its object function assigns to the groups G and H the group $\text{Ext}(G, H)$ of the so-called abelian group extensions of G by H .

Since $C_q(K, G) = \text{Hom}(C^q(K), G)$ and since $C^q(K, I) = I \circ C^q(K) = C^q(K)$ where I is the additive group of integers, we have

$$C_q(K, G) = \text{Hom}(C^q(K, I), G).$$

We, therefore, may define a subgroup

$$A_q(K, G) = \text{Annih } Z^q(K, I)$$

of $C_q(K, G)$ consisting of all homomorphisms f such that $f(z^q) = 0$ for $z^q \in Z^q(K, I)$. Thus we get a subfunctor A_q of C_q , and one may show that the coboundary functor B_q is a subfunctor of A_q which, in turn, is a subfunctor of the cocycle functor Z_q . Consequently, the quotient functor

$$Q_q = A_q/B_q$$

is a subfunctor of the cohomology functor H_q , and we may consider the quotient functor H_q/Q_q . The functors Q_q and H_q/Q_q have the following object functions

$$\begin{aligned} Q_q(K, G) &= A_q(K, G)/B_q(K, G), \\ (H_q/Q_q)(K, G) &= H_q(K, G)/Q_q(K, G) \cong Z_q(K, G)/A_q(K, G). \end{aligned}$$

The universal coefficient theorem now consists of these three assertions⁽²⁶⁾:

$$(29.1) \quad Q_q(K, G) \text{ is a direct factor of } H_q(K, G).$$

$$(29.2) \quad Q_q(K, G) \cong \text{Ext}(G, H^{q+1}(K, I)).$$

$$(29.3) \quad H_q(K, G)/Q_q(K, G) \cong \text{Hom}(H^q(K, I), G).$$

Both the isomorphisms (29.2) and (29.3) can be interpreted as equivalences of functors. The naturality of these equivalences with respect to K has been explicitly verified⁽²⁷⁾, while the naturality with respect to G can be verified without difficulty. We have not been able to prove and we doubt that the functor Q_q is a direct factor of the functor H_q (see §18).

30. Čech homology groups. We shall present now a treatment of the Čech homology theory in terms of functors.

By a covering U of a topological space X we shall understand a finite collection:

$$U = \{A_1, \dots, A_n\}$$

of open sets whose union is X . The sets A_i may appear with repetitions, and some of them may be empty. If U_1 and U_2 are two such coverings, we write $U_1 < U_2$ whenever U_2 is a refinement of U_1 , that is, whenever each set of the covering U_2 is contained in some set of the covering U_1 . With this definition the coverings U of X form a directed set which we denote by $C(X)$.

Let $\xi: X_1 \rightarrow X_2$ be a continuous mapping of the space X_1 into the space X_2 . Given a covering

$$U = \{A_1, \dots, A_n\} \in C(X_2),$$

we define

$$C(\xi)U = \{\xi^{-1}(A_1), \dots, \xi^{-1}(A_n)\} \in C(X_1)$$

and we obtain an order preserving mapping

$$C(\xi): C(X_2) \rightarrow C(X_1).$$

We verify that the functions $C(X)$, $C(\xi)$ define a contravariant functor C on the category \mathfrak{X} of topological spaces to the category \mathfrak{D} of directed sets.

Given a covering U of X we define, in the usual fashion, the nerve $N(U)$ of U . $N(U)$ is a finite simplicial complex; it will be treated, however, as an object of the category K_f of §27.

If two coverings $U_1 < U_2$ of X are given, then we select for each set of the covering U_2 a set of the covering U_1 containing it. This leads to a simplicial mapping of the complex $N(U_2)$ into the complex $N(U_1)$ and therefore gives a chain transformation

⁽²⁶⁾ Loc. cit. p. 808.

⁽²⁷⁾ Loc. cit. p. 815.

$$\kappa: N(U_2) \rightarrow N(U_1).$$

This transformation κ will be called a projection. The projection κ is not defined uniquely by U_1 and U_2 , but it is known that any two projections κ_1 and κ_2 are chain homotopic and consequently the induced homomorphisms

$$(30.1) \quad H^q(\kappa, e_G): H^q(N(U_2), G) \rightarrow H^q(N(U_1), G),$$

$$(30.2) \quad H_q(\kappa, e_G): H_q(N(U_1), G) \rightarrow H_q(N(U_2), G)$$

of the homology and cohomology groups do not depend upon the particular choice of the projection κ .

Given a topological group G we consider the collection of the homology groups $H^q(N(U), G)$ for $U \in C(X)$. These groups together with the mappings (30.1) form an inverse system of groups defined on the directed set $C(X)$. We denote this inverse system by $\overline{C}^q(X, G)$ and treat it as an object of the category $\mathfrak{I}nv$ (§23).

Similarly, for a discrete G the cohomology groups $H_q(N(U), G)$ together with the mappings (30.2) form a direct system of groups $\overline{C}_q(X, G)$ likewise defined on the directed set $C(X)$. The system $\overline{C}_q(X, G)$ will be treated as an object of the category $\mathfrak{D}ir$.

The functions $\overline{C}^q(X, G)$ and $\overline{C}_q(X, G)$ will be object functions of functors \overline{C}^q and \overline{C}_q . In order to complete the definition we shall define the mapping functions $\overline{C}^q(\xi, \gamma)$ and $\overline{C}_q(\xi, \gamma)$ for given mappings

$$\xi: X_1 \rightarrow X_2, \quad \gamma: G_1 \rightarrow G_2.$$

We have the order preserving mapping

$$(30.3) \quad C(\xi): C(X_2) \rightarrow C(X_1)$$

which with each covering

$$U = \{A_1, \dots, A_n\} \in C(X_2)$$

associates the covering

$$V = C(\xi)U = \{\xi^{-1}A_1, \dots, \xi^{-1}A_n\} \in C(X_1).$$

Thus to each set of the covering V corresponds uniquely a set of the covering U ; this yields a simplicial mapping

$$\kappa: N(V) \rightarrow N(U),$$

which leads to the homomorphisms

$$(30.4) \quad H^q(\kappa, \gamma): H^q(N(V), G_1) \rightarrow H^q(N(U), G_2),$$

$$(30.5) \quad H_q(\kappa, \gamma): H_q(N(U), G_1) \rightarrow H_q(N(V), G_2).$$

The mappings (30.3)-(30.5) define the transformations

$$\begin{aligned} \bar{C}^q(\xi, \gamma) : \bar{C}^q(X_1, G_1) &\rightarrow \bar{C}^q(X_2, G_2) \quad \text{in } \mathfrak{I}nb, \\ \bar{C}_q(\xi, \gamma) : \bar{C}_q(X_2, G_1) &\rightarrow \bar{C}_q(X_1, G_2) \quad \text{in } \mathfrak{D}ir. \end{aligned}$$

Hence we see that \bar{C}^q is a functor covariant in \mathfrak{X} and in \mathfrak{G}_a with values in $\mathfrak{I}nb$ while \bar{C}_q is contravariant in \mathfrak{X} covariant in \mathfrak{G}_{0a} and has values in $\mathfrak{D}ir$.

The Čech homology and cohomology functors are now defined as

$$\bar{H}^q = \text{Lim}_{\leftarrow} \bar{C}^q, \quad \bar{H}_q = \text{Lim}_{\leftarrow} \bar{C}_q.$$

\bar{H}^q is covariant in \mathfrak{X} and \mathfrak{G}_a and has values in \mathfrak{G}_a , while \bar{H}_q is contravariant in \mathfrak{X} , covariant in \mathfrak{G}_{0a} , and has values in \mathfrak{G}_{0a} . The object functions $\bar{H}^q(X, G)$ and $\bar{H}_q(X, G)$ are the Čech homology and cohomology groups of the space X with the group G as coefficients.

31. Miscellaneous remarks. The process of setting up the various topological invariants as functors will require the construction of many categories. For instance, if we wish to discuss the so-called relative homology theory, we shall need the category \mathfrak{X}_S whose objects are the pairs (X, A) , where X is a topological space and A is a subset of X . A mapping

$$\xi : (X, A) \rightarrow (Y, B) \quad \text{in } \mathfrak{X}_S$$

is a continuous mapping $\xi : X \rightarrow Y$ such that $\xi(A) \subset B$. The category \mathfrak{X} may be regarded as the subcategory of \mathfrak{X}_S , determined by the pairs (X, A) with $A = 0$.

Another subcategory of \mathfrak{X}_S is the category \mathfrak{X}_b defined by the pairs (X, A) in which the set A consists of a single point, called the base point. This category \mathfrak{X}_b would be used in a functorial treatment of the fundamental group and of the homotopy groups.

APPENDIX. REPRESENTATIONS OF CATEGORIES

The purpose of this appendix is to show that every category is isomorphic with a suitable subcategory of the category of sets \mathfrak{S} .

Let \mathfrak{A} be any category. A covariant functor T on \mathfrak{A} with values in \mathfrak{S} will be called a representation of \mathfrak{A} in \mathfrak{S} . A representation T will be called faithful if for every two mappings, $\alpha_1, \alpha_2 \in \mathfrak{A}$, we have $T(\alpha_1) = T(\alpha_2)$ only if $\alpha_1 = \alpha_2$. This implies a similar proposition for the objects of \mathfrak{A} . It is clear that a faithful representation is nothing but an isomorphic mapping of \mathfrak{A} onto some subcategory of \mathfrak{S} .

If the functor T on \mathfrak{A} to \mathfrak{S} is contravariant, we shall say that T is a dual representation. T is then obviously a representation of the dual category \mathfrak{A}^* , as defined in §13.

Given a mapping $\alpha : A_1 \rightarrow A_2$ in \mathfrak{A} , we shall denote the domain A_1 of α by $d(\alpha)$ and the range A_2 of α by $r(\alpha)$. In this fashion we have

$$\alpha : d(\alpha) \rightarrow r(\alpha).$$

Given an object A in \mathfrak{A} we shall denote by $R(A)$ the set of all $\alpha \in \mathfrak{A}$, such that $A = r(\alpha)$. In symbols

$$(I) \quad R(A) = \{ \alpha \mid \alpha \in \mathfrak{A}, r(\alpha) = A \}.$$

For every mapping α in \mathfrak{A} we define a mapping

$$(II) \quad R(\alpha): R(d(\alpha)) \rightarrow R(r(\alpha))$$

in the category \mathfrak{S} by setting

$$(III) \quad [R(\alpha)]\xi = \alpha\xi$$

for every $\xi \in R(d(\alpha))$. This mapping is well defined because if $\xi \in R(d(\alpha))$, then $r(\xi) = d(\alpha)$, so that $\alpha\xi$ is defined and $r(\alpha\xi) = r(\alpha)$ which implies $\alpha\xi \in R(r(\alpha))$.

THEOREM. *For every category \mathfrak{A} the pair of functions $R(A), R(\alpha)$, defined above, establishes a faithful representation R of \mathfrak{A} in \mathfrak{S} .*

Proof. We first verify that R is a functor. If $\alpha = e_A$ is an identity, then definition (III) implies that $[R(\alpha)]\xi = \xi$, so that $R(\alpha)$ is the identity mapping of $R(A)$ into itself. Thus R satisfies condition (3.1). Condition (3.2) has already been verified. In order to verify (3.3) let us consider the mappings

$$\alpha_1: A_1 \rightarrow A_2, \quad \alpha_2: A_2 \rightarrow A_3.$$

We have for every $\xi \in R(A_1)$,

$$[R(\alpha_2\alpha_1)]\xi = \alpha_2\alpha_1\xi = [R(\alpha_2)]\alpha_1\xi = [R(\alpha_2)R(\alpha_1)]\xi,$$

so that $R(\alpha_2\alpha_1) = R(\alpha_2)R(\alpha_1)$. This concludes the proof that R is a representation.

In order to show that R is faithful, let us consider two mappings $\alpha_1, \alpha_2 \in \mathfrak{A}$ and let us assume that $R(\alpha_1) = R(\alpha_2)$. It follows from (II) that $R(d(\alpha_1)) = R(d(\alpha_2))$, and, therefore, according to (I), $d(\alpha_1) = d(\alpha_2)$. Consider the identity mapping $e = e_{d(\alpha_1)} = e_{d(\alpha_2)}$. Following (III), we have

$$\alpha_1 = \alpha_1 e = [R(\alpha_1)]e = [R(\alpha_2)]e = \alpha_2 e = \alpha_2,$$

so that $\alpha_1 = \alpha_2$. This concludes the proof of the theorem.

In a similar fashion we could define a faithful dual representation D of \mathfrak{A} by setting

$$D(A) = \{ \alpha \mid \alpha \in \mathfrak{A}, d(\alpha) = A \}$$

and

$$[D(\alpha)]\xi = \xi\alpha$$

for every $\xi \in D(r(\alpha))$.

The representations R and D are the analogues of the left and right regular representations in group theory.

We shall conclude with some remarks concerning partial order in categories. Most of the categories which we have considered have an intrinsic partial order. For instance, in the categories \mathfrak{S} , \mathfrak{X} , and \mathfrak{G} the concepts of subset, subspace, and subgroup furnish a partial order. In view of (I), $A_1 \neq A_2$ implies that $R(A_1)$ and $R(A_2)$ are disjoint, so that the representation R destroys this order completely. The problem of getting "order preserving representations" would require probably a suitable formalization of the concept of a partially ordered category.

As an illustration of the type of arguments which may be involved, let us consider the category \mathfrak{G}_0 of discrete groups. With each group G we can associate the set $R_1(G)$ which is the set of elements constituting the group G . With the obvious mapping function, R_1 becomes a covariant functor on \mathfrak{G}_0 to \mathfrak{S} , that is, R_1 is a representation of \mathfrak{G}_0 in \mathfrak{S} . This representation is not faithful, since the same set may carry two different group structures. The group structure of G is entirely described by means of a ternary relation $g_1 g_2 = g$. This ternary relation is nothing but a subset $R_2(G)$ of $R_1(G) \times R_1(G) \times R_1(G)$. All of the axioms of group theory can be formulated in terms of the subset $R_2(G)$. Moreover a homomorphism $\gamma: G_1 \rightarrow G_2$ induces a mapping $R_2(\gamma): R_2(G_1) \rightarrow R_2(G_2)$. Consequently R_2 is a subfunctor of a suitably defined functor $R_1 \times R_1 \times R_1$. The two functors R_1 and R_2 together give a complete description of \mathfrak{G}_0 , preserving the partial order.

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