HAPLÓS

Vibrotactile Somaesthetic Technology

for Body Awareness

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How can somatic approaches lead the design of a wearable technology for facilitating somatic learning? We explored this question by taking educational strategies of one somatic approach—the Feldenkrais Method (FM) [2, 5]—and integrating it with artistic research on "somatic costumes... [as] portals of perception" [1] and neuroscientific research on the effects of vibrotactile stimuli on the organization of the sensorimotor cortex [3]. The result was Haplós, a wearable device that aims to develop body awareness through the application of programmable, pleasurable tactile patterns to the skin using small vibratory motors. Table 1 maps how somatic principles from FM were translated into design principles for Haplós. We argue that because Haplós both creates an aesthetic experience as well as facilitates body awareness by heightening proprioceptive sensitivity, it exemplifies what we propose as a somaesthetic [4] technology. Haplós was initially tested in one quasi-experimental workshop involving deception. Using the floor as a "kinesthetic mirror" [5], 8 participants were asked to notice their awareness of their body before and after experiencing Haplós vibrations on only one side. Participants were initially told that the unilateral stimulation was not deliberate and merely due to a technical error. Generally, participants reported feeling more aware of the area of their body that was stimulated, and even reported experiencing more awareness in parts of themselves that were not stimulated but which belonged to the same side laterally. These reports were captured both in verbal reports and through visual representations they created of their perception of their body's contact with the ground (Figure 4). For more details, please refer to the full paper (QR code right) or visit cognovo.eu/project-8.

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| ategies to Haplós | design principles |
| ducational strategies used in the Idenkrais Method for developing body awareness | Related design principles for the technical specifications for and usage of Haplós |
| crease kinesthetic and proprioceptive tivity, first reduce muscular activation in the extensors of the torso by lying wn horizontal [2, 5]. Create a learning nent that affords safe, distraction-free somatic attentiveness. | To increase sensitivity to vibrotactile stimulation, reduce muscular activation in the extensor muscles of the back by supporting the torso through clothing, furniture, or other apparatuses (Figure 1). In addition, Haplós should be used in a quiet room. |
| t with movements of the torso (pelvis- pine-neck), which will likely stimulate ment and sensation in the more distal parts. | Apply vibrotactile stimuli on the midline of the back with emphasis on the upper thoracic spine, since it is a part of the user that they usually do not get to touch and explore themselves. |
| crease the student's ability to perceive subtle differences in kinesthetic and ceptive stimuli by moving just enough that they notice the movement. | Strength and duration of vibrotactile stimulation should be just to enough to draw attention to the vibrated body part. Space vibrotactile motors just at the threshold of two-point tactile discrimination on the torso (2-3 cm) (Figure 2) |
| Ask the student to start with a simple movement, advance to more complex ons of that movement, and then revisit ial movement in order to find the ease of movement | Stimulate the user's skin with structured patterns of vibrotactile stimuli that progress from the simple to the complex, before returning to the initial simple pattern. |
| acilitate self-curiosity and playful self- oration in the student so that they can o their experiences in a value-free way | Present Haplós not as a therapeutic tool but as a playful device. Make the patterns interesting to attend to by programming them to be "musical"—e.g., finding the balance between repetition and variation. |
| the student to move always within the of comfort and ease, resting whenever they feel tired or when they feel their n waning, promoting reorganization in the sensorimotor cortex | Provide users the option to create and change patterns on the fly (Figure 3), and to silence the motors at any time in order not to overstimulate the user. |
| eat a movement several times in order notice differences in sensation as well hen there is a gaps in their kinesthetic awareness | Take advantage of the user's ability to gradually identify and anticipate elements in a pattern by playing a pattern more than once before moving on to a new pattern, in order to train the user to uniquely distinguish the motors from each other |
| dvantage of the bilateral symmetry of y by moving only one side at a time to e differences in sensations that can be bared across midsagittal plane (a "one- sided lesson") [2, 5] | Apply the vibrotactile stimuli on only one side of the torso (see Figure 4). |
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| RSITY | Poster design by Pieter Steyaert (SEADS) |



Figure 1. Haplós attached to a modified, commercially-available back support garment.



Figure 3. Haplós controller and sequencer. Patterns and pattern playback speed can be adjusted on the fly.



Sally Dean, "Amerta Movement and Somatic Costume," in Sarah Whatley, Natalie Garrett Brown, Kirsty Alexander, eds., Attending to movement: Somatic Perspectives on Living in this World (Devon, UK: Triarchy Press, 2015).

[2] Moshe Feldenkrais, Awareness Through Movement; Health Exercises for Personal Growth, 1st ed. (New York, USA: Harper & Row, 1972).

[3] Karin Rosenkranz and John Rothwell, "The Effect of Sensory Input and Attention on the Sensorimotor Organization of the Hand Area of the Human Motor Cortex," Journal of Physiology 561, No. 1 (November 2004), pp. 307-320.

[4] **Richard Shusterman**, Body Consciousness: A Philosophy of Mindfulness and Somaesthetics, (Cambridge; New York: Cambridge Univ. Press, 2008), p. 1.

[5] Frank Wildman, The Busy Person's Guide to Easier Movement: 50 Ways to Achieve a Healthy, Happy, Pain-Free and Intelligent Body, 3rd revised ed. (Berkeley, USA: Feldenkrais Movement Institute, 2006).





Figure 2. Haplós hardware and textile components.



Figure 4. One workshop participant's drawing representing their perception of the contact of their body on the ground before *(left)* and after *(right)*.



