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def main():
    Print_Function()
    (x, y, z) = xyz = symbols('x,y,z',real=True)
    (o3d, ex, ey, ez) = Ga.build('e_x e_y e_z', g=[1, 1, 1], coords=xyz)
    grad = o3d.grad
    (u, v) = uv = symbols('u,v',real=True)
    (g2d, eu, ev) = Ga.build('e_u e_v', coords=uv)
    grad_uv = g2d.grad
    v_xyz = o3d.mv('v','vector')
    A_xyz = o3d.mv('A','vector',f=True)
    A_uv = g2d.mv('A','vector',f=True)
    print '#3d orthogonal ($A$ is vector function)'
    print 'A =', A_xyz
    print '%A^{2} =', A_xyz * A_xyz
    print 'grad|A =', grad | A_xyz
    print 'grad*A =', grad * A_xyz
    print 'v|(grad*A) =', v_xyz|(grad*A_xyz)
    print '#2d general ($A$ is vector function)'
    print 'A =', A_uv
    print '%A^{2} =', A_uv * A_uv
    print 'grad|A =', grad_uv | A_uv
    print 'grad*A =', grad_uv * A_uv
    A = o3d.lt('A')
    print '#3d orthogonal ($A,\\;B$ are linear transformations)'
    print 'A =', A
    print r'\f{mat}{A} =', A.matrix()
    print '\\f{\\det}{A} =', A.det()
    print '\\overline{A} =', A.adj()
    print '\\f{\\Tr}{A} =', A.tr()
    print '\\f{A}{e_x^e_y} =', A(ex^ey)
    print '\\f{A}{e_x}^\\f{A}{e_y} =', A(ex)^A(ey)
    B = o3d.lt('B')
    print 'g =', o3d.g
    print '%g^{-1} =', o3d.g_inv

    print 'A + B =', A + B
    print 'AB =', A * B
    print 'A - B =', A - B
    print 'General Symmetric Linear Transformation'
    Asym = o3d.lt('A',mode='s')
    print 'A =', Asym
    print 'General Antisymmetric Linear Transformation'
    Aasym = o3d.lt('A',mode='a')
    print 'A =', Aasym
    print '#2d general ($A,\\;B$ are linear transformations)'
    A2d = g2d.lt('A')
    print 'g =', g2d.g
    print '%g^{-1} =', g2d.g_inv
    print '%gg^{-1} =', simplify(g2d.g * g2d.g_inv)
    print 'A =', A2d
    print r'\f{mat}{A} =', A2d.matrix()
    print '\\f{\\det}{A} =', A2d.det()
    A2d_adj = A2d.adj()
    print '\\overline{A} =', A2d_adj
    print '\\f{mat}{\\overline{A}} =', simplify(A2d_adj.matrix())
    print '\\f{\\Tr}{A} =', A2d.tr()
    print '\\f{A}{e_u^e_v} =', A2d(eu^ev)
    print '\\f{A}{e_u}^\\f{A}{e_v} =', A2d(eu)^A2d(ev)
    B2d = g2d.lt('B')

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print 'B =', B2d
print 'A + B =', A2d + B2d
print 'AB =', A2d * B2d
print 'A - B =', A2d - B2d
a = g2d.mv('a','vector')
b = g2d.mv('b','vector')
print r'a|\f{\overline{A}}{b}-b|\f{\underline{A}}{a} =',((a|A2d.adj()(b))-(b|A2d(a))).simplify()
m4d = Ga('e_t e_x e_y e_z', g=[1, -1, -1, -1],coords=symbols('t,x,y,z',real=True))
T = m4d.lt('T')
print 'g =', m4d.g
print r'\underline{T} =',T
print r'\overline{T} =',T.adj()
print r'\f{\det}{\underline{T}} =',T.det()
print r'\f{\mbox{tr}}{\underline{T}} =',T.tr()
a = m4d.mv('a','vector')
b = m4d.mv('b','vector')
print r'a|\f{\overline{T}}{b}-b|\f{\underline{T}}{a} =',((a|T.adj()(b))-(b|T(a))).simplify()
coords = (r, th, phi) = symbols('r,theta,phi', real=True)
(sp3d, er, eth, ephi) = Ga.build('e_r e_th e_ph', g=[1, r**2, r**2*sin(th)**2], coords=coords)
grad = sp3d.grad
sm_coords = (u, v) = symbols('u,v', real=True)
smap = [1, u, v] # Coordinate map for sphere of r = 1
sph2d = sp3d.sm(smap,sm_coords,norm=True)
(eu, ev) = sph2d.mv()
grad_uv = sph2d.grad
F = sph2d.mv('F','vector',f=True)
f = sph2d.mv('f','scalar',f=True)
print 'f =',f
print 'grad*f =',grad_uv * f
print 'F =',F
print 'grad*F =',grad_uv * F
tp = (th,phi) = symbols('theta,phi',real=True)
smap = [sin(th)*cos(phi),sin(th)*sin(phi),cos(th)]
sph2dr = o3d.sm(smap,tp,norm=True)
(eth, ephi) = sph2dr.mv()
grad_tp = sph2dr.grad
F = sph2dr.mv('F','vector',f=True)
f = sph2dr.mv('f','scalar',f=True)
print 'f =',f
print 'grad*f =',grad_tp * f
print 'F =',F
print 'grad*F =',grad_tp * F
return

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Code Output: 3d orthogonal (A is vector function)

$$A = A^x \mathbf{e}_x + A^y \mathbf{e}_y + A^z \mathbf{e}_z$$

$$A^2 = (A^x)^2 + (A^y)^2 + (A^z)^2$$

$$\nabla \cdot A = \partial_x A^x + \partial_y A^y + \partial_z A^z$$

$$\nabla A = (\partial_x A^x + \partial_y A^y + \partial_z A^z) + (-\partial_y A^x + \partial_x A^y) \mathbf{e}_x \wedge \mathbf{e}_y + (-\partial_z A^x + \partial_x A^z) \mathbf{e}_x \wedge \mathbf{e}_z + (-\partial_z A^y + \partial_y A^z) \mathbf{e}_y \wedge \mathbf{e}_z$$

$$v \cdot (\nabla A) = (v^y \partial_y A^x - v^y \partial_x A^y + v^z \partial_z A^x - v^z \partial_x A^z) \mathbf{e}_x + (-v^x \partial_y A^x + v^x \partial_x A^y + v^z \partial_z A^y - v^z \partial_y A^z) \mathbf{e}_y + (-v^x \partial_z A^x + v^x \partial_x A^z - v^y \partial_z A^y + v^y \partial_y A^z) \mathbf{e}_z$$

2d general (A is vector function)

$$A = A^u \mathbf{e}_u + A^v \mathbf{e}_v$$

$$A^2 = (e_u \cdot e_u) (A^u)^2 + 2 (e_u \cdot e_v) A^u A^v + (e_v \cdot e_v) (A^v)^2$$

$$\nabla \cdot A = \partial_u A^u + \partial_v A^v$$

$$\nabla A = (\partial_u A^u + \partial_v A^v) + \frac{-(e_u \cdot e_u) \partial_v A^u + (e_u \cdot e_v) \partial_u A^u - (e_u \cdot e_v) \partial_v A^v + (e_v \cdot e_v) \partial_u A^v}{(e_u \cdot e_u)(e_v \cdot e_v) - (e_u \cdot e_v)^2} e_u \wedge e_v$$

3d orthogonal (A, B are linear transformations)

$$A = \begin{Bmatrix} L(e_x) = A^{xx}e_x + A^{xy}e_y + A^{xz}e_z \\ L(e_y) = A^{yx}e_x + A^{yy}e_y + A^{yz}e_z \\ L(e_z) = A^{zx}e_x + A^{zy}e_y + A^{zz}e_z \end{Bmatrix}$$

$$mat(A) = \begin{bmatrix} A^{xx} & A^{xy} & A^{xz} \\ A^{yx} & A^{yy} & A^{yz} \\ A^{zx} & A^{zy} & A^{zz} \end{bmatrix}$$

$$\det(A) = A^{zx}(A^{xy}A^{yz} - A^{xz}A^{yy}) - A^{zy}(A^{xx}A^{yz} - A^{xz}A^{yx}) + A^{zz}(A^{xx}A^{yy} - A^{xy}A^{yx})$$

$$\overline{A} = \begin{Bmatrix} L(e_x) = A^{xx}e_x + A^{yx}e_y + A^{zx}e_z \\ L(e_y) = A^{xy}e_x + A^{yy}e_y + A^{zy}e_z \\ L(e_z) = A^{xz}e_x + A^{yz}e_y + A^{zz}e_z \end{Bmatrix}$$

$$\text{Tr}(A) = A^{xx} + A^{yy} + A^{zz}$$

$$A(e_x \wedge e_y) = (A^{xx}A^{yy} - A^{xy}A^{yx})e_x \wedge e_y + (A^{xx}A^{yz} - A^{xz}A^{yx})e_x \wedge e_z + (A^{xy}A^{yz} - A^{xz}A^{yy})e_y \wedge e_z$$

$$A(e_x) \wedge A(e_y) = (A^{xx}A^{yy} - A^{xy}A^{yx})e_x \wedge e_y + (A^{xx}A^{yz} - A^{xz}A^{yx})e_x \wedge e_z + (A^{xy}A^{yz} - A^{xz}A^{yy})e_y \wedge e_z$$

$$g = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$g^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A + B = \begin{Bmatrix} L(e_x) = (A^{xx} + B^{xx})e_x + (A^{xy} + B^{xy})e_y + (A^{xz} + B^{xz})e_z \\ L(e_y) = (A^{yx} + B^{yx})e_x + (A^{yy} + B^{yy})e_y + (A^{yz} + B^{yz})e_z \\ L(e_z) = (A^{zx} + B^{zx})e_x + (A^{zy} + B^{zy})e_y + (A^{zz} + B^{zz})e_z \end{Bmatrix}$$

$$AB = \begin{Bmatrix} L(e_x) = (A^{xx}B^{xx} + A^{yx}B^{xy} + A^{zx}B^{xz})e_x + (A^{xy}B^{xx} + A^{yy}B^{xy} + A^{zy}B^{xz})e_y + (A^{xz}B^{xx} + A^{yz}B^{xy} + A^{zz}B^{xz})e_z \\ L(e_y) = (A^{xx}B^{yx} + A^{yx}B^{yy} + A^{zx}B^{yz})e_x + (A^{xy}B^{yx} + A^{yy}B^{yy} + A^{zy}B^{yz})e_y + (A^{xz}B^{yx} + A^{yz}B^{yy} + A^{zz}B^{yz})e_z \\ L(e_z) = (A^{xx}B^{zx} + A^{yx}B^{zy} + A^{zx}B^{zz})e_x + (A^{xy}B^{zx} + A^{yy}B^{zy} + A^{zy}B^{zz})e_y + (A^{xz}B^{zx} + A^{yz}B^{zy} + A^{zz}B^{zz})e_z \end{Bmatrix}$$

$$A - B = \begin{Bmatrix} L(e_x) = (A^{xx} - B^{xx})e_x + (A^{xy} - B^{xy})e_y + (A^{xz} - B^{xz})e_z \\ L(e_y) = (A^{yx} - B^{yx})e_x + (A^{yy} - B^{yy})e_y + (A^{yz} - B^{yz})e_z \\ L(e_z) = (A^{zx} - B^{zx})e_x + (A^{zy} - B^{zy})e_y + (A^{zz} - B^{zz})e_z \end{Bmatrix}$$

GeneralSymmetricLinearTransformation

$$A = \begin{Bmatrix} L(e_x) = A^{xx}e_x + A^{xy}e_y + A^{xz}e_z \\ L(e_y) = A^{xy}e_x + A^{yy}e_y + A^{yz}e_z \\ L(e_z) = A^{xz}e_x + A^{yz}e_y + A^{zz}e_z \end{Bmatrix}$$

GeneralAntisymmetricLinearTransformation

$$A = \begin{Bmatrix} L(e_x) = A^{xy}e_y + A^{xz}e_z \\ L(e_y) = -A^{xy}e_x + A^{yz}e_z \\ L(e_z) = -A^{xz}e_x - A^{yz}e_y \end{Bmatrix}$$

2d general (A, B are linear transformations)

$$g = \begin{bmatrix} (e_u \cdot e_u) & (e_u \cdot e_v) \\ (e_u \cdot e_v) & (e_v \cdot e_v) \end{bmatrix}$$

$$g^{-1} = \begin{bmatrix} \frac{(e_u \cdot e_u)(e_v \cdot e_v)^2 - (e_u \cdot e_v)^2(e_v \cdot e_v)}{(e_u \cdot e_u)^2(e_v \cdot e_v)^2 - 2(e_u \cdot e_u)(e_u \cdot e_v)^2(e_v \cdot e_v) + (e_u \cdot e_v)^4} & \frac{-(e_u \cdot e_u)(e_u \cdot e_v)(e_v \cdot e_v) + (e_u \cdot e_v)^3}{(e_u \cdot e_u)^2(e_v \cdot e_v)^2 - 2(e_u \cdot e_u)(e_u \cdot e_v)^2(e_v \cdot e_v) + (e_u \cdot e_v)^4} \\ \frac{-(e_u \cdot e_u)(e_u \cdot e_v)(e_v \cdot e_v) + (e_u \cdot e_v)^3}{(e_u \cdot e_u)^2(e_v \cdot e_v)^2 - 2(e_u \cdot e_u)(e_u \cdot e_v)^2(e_v \cdot e_v) + (e_u \cdot e_v)^4} & \frac{(e_u \cdot e_u)^2(e_v \cdot e_v) - (e_u \cdot e_u)(e_u \cdot e_v)^2}{(e_u \cdot e_u)^2(e_v \cdot e_v)^2 - 2(e_u \cdot e_u)(e_u \cdot e_v)^2(e_v \cdot e_v) + (e_u \cdot e_v)^4} \end{bmatrix}$$

$$gg^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$F = F^u \boldsymbol{e}_u + F^v \boldsymbol{e}_v$$

$$\boldsymbol{\nabla} F = \left(\frac{F^u}{\tan(u)} + \partial_u F^u + \frac{\partial_v F^v}{\sin(u)} \right) + \left(\frac{F^v}{\tan(u)} + \partial_u F^v - \frac{\partial_v F^u}{\sin(u)} \right) \boldsymbol{e}_u \wedge \boldsymbol{e}_v$$

$$f=f$$

$$\boldsymbol{\nabla} f = \partial_\theta f \boldsymbol{e}_\theta + \frac{\partial_\phi f}{\sin(\theta)} \boldsymbol{e}_\phi$$

$$F = F^\theta \boldsymbol{e}_\theta + F^\phi \boldsymbol{e}_\phi$$

$$\boldsymbol{\nabla} F = \left(\frac{F^\theta}{\tan(\theta)} + \partial_\theta F^\theta + \frac{\partial_\phi F^\phi}{\sin(\theta)} \right) + \left(\frac{F^\phi}{\tan(\theta)} + \partial_\theta F^\phi - \frac{\partial_\phi F^\theta}{\sin(\theta)} \right) \boldsymbol{e}_\theta \wedge \boldsymbol{e}_\phi$$