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# An Overview of Lidar-Assisted Control PART III

#### Main questions today

- ➤ How can we obtain useful information for controls from lidar systems? → Part I
- ➤ How can these signals be used to improve wind turbine control? → Part II
- What are practical considerations when implementing lidar-assisted control in the field? → Part III

### Controls Advanced Research Turbines (CARTs)



Photo by Andy Scholbrock, NREL

- ~40 meter rotor diameter
- Heavily instrumented
  - Dedicated met mast
  - Strain gauges
  - Accelerometers

- ~37 meter hub height
- ~600 kW rated power
- Numerous lidar field campaigns
- Can be run in a downwind configuration

### Lidar Assisted Yaw Control – Bias Correction



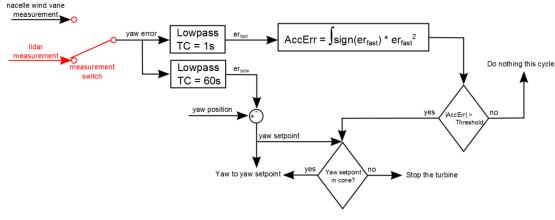


Photo by Lee Jay Fingersh, NREL

### Lidar Assisted Yaw Control – Bias Correction

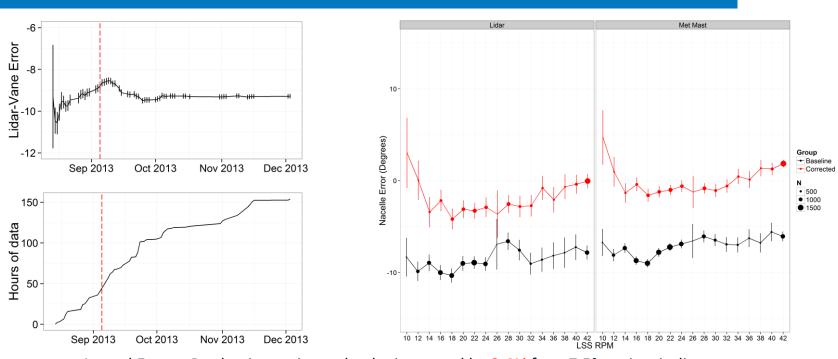


 $AccErr = \int sign(er_{fast}) * er_{fast}^{2}$ TC = 1sDo nothing this cycle precompute AccErrl > vaw setpoint Yaw setpoint Stop the turbine

Lowpass

Photo by Lee Jay Fingersh, NREL

### Lidar Assisted Yaw Control – Bias Correction



Annual Energy Production estimated to be increased by 2.4% for a 7.5° static misalignment

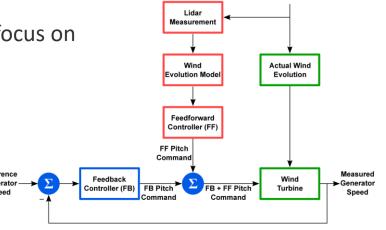
P. A. Fleming, A. K. Scholbrock, A. Jehu, S. Davoust, E. Osler, A. D. Wright, and A. Clifton, "Field-test results using a nacelle-mounted lidar for improving wind turbine power capture by reducing yaw misalignment," Journal of Physics: Conference Series, vol. 524, no. 1, 2014.

## Feedforward blade pitch control

- Wind Measurement  $\rightarrow$  Filter Measurement  $\rightarrow$  FF Pitch Control
  - Filter out high frequency content of wind
  - Control generator speed for low frequency
  - De-tune conventional feedback control to focus on higher frequency turbine loading controls

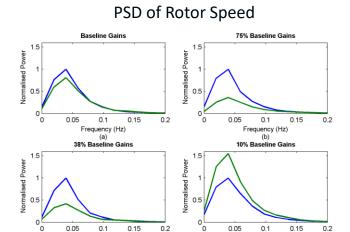


Photo by David Schlipf, SWE



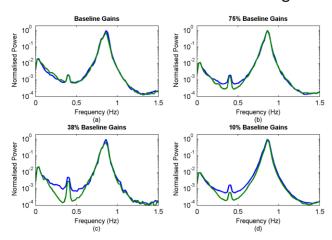
### Feedforward blade pitch control

Frequency (Hz)



Frequency (Hz)

#### PSD of Tower Fore-Aft Bending



Blue – Baseline feedback only control Green – Lidar assisted feedback/feed-forward control

# **Practical Considerations from Field Testing**

#### Visibility/Hard Targets



Environment



Photo by Andy Scholbrock, NREL

Static/Dynamic Alignment



Photo by Mark Murphy, NREL

# **Practical Considerations from Field Testing**

#### Visibility/Hard Targets



Environment



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Static/Dynamic Alignment



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### Certification of Lidar Assisted Control

- Yaw controller changes
  - Loads considerations
- Feedforward Pitch Control
  - Loss of lidar signal
  - Fallback controller
  - Turbine derating
- Process needs to exist for lidar assisted control to have industrial adoption



Photo by Andy Scholbrock, NREL

# Field Testing LAC Summary

- Wind turbine yaw alignment can be improved using lidars over conventional nacelle vanes
- Feedforward controller can be used to regulate rated rotor speed in region III
- Feedback controller can be tuned for loads reduction
- Yaw alignment and feedforward control can be done in tandem
- Practical considerations of visibility, environment, and alignment need to be accounted for
- Certification process needed to ensure robust turbine operation



Photo by Dennis Schroeder, NREI

# Thank you for your time



Photo by Andy Scholbrock, NREL

