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## StuCoSReC

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## Preface

Computer science is now among the most popular study programmes worldwide. We live in a digital age where most industries rely on data and software programmes. From transport infrastructure to public health systems, banking and communications, computer science is everywhere. Technology has made the world better, faster, and more connected. However, it is easy to miss an important component of this exciting success story.
Such development was made possible thanks to the brilliant minds of IT graduates, who took their passion for technology and used it to create ground breaking gadgets and computer programmes. Here in Slovenia, the three public universities share these values and invest heavily in their computer science students. These efforts facilitate collaboration among our departments, resulting in joint events such as this StuCoSRec student conference.

We are proud that, over the past five years, these Student Computer Science Research Conferences have grown in several ways. In this $6^{\text {th }}$ installment, we received 24 full-paper submissions and one abstract submission. Among these, 21 papers were accepted to these proceedings, and 22 talks are scheduled to be presented during the conference, in three parallel sessions. The continued internationalization of our departments is also reflected with the authors of ten full-paper submissions originating from outside of Slovenia.

The conference is dedicated to graduate and undergraduate students of computer science and is therefore free of charge. We gratefully acknowledge the support of the Faculty of Mathematics, Natural Sciences and Information Technologies (University of Primorska).

Matjaž Krnc

## Preface

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# A two-stage heuristic for the university course timetabling problem 

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#### Abstract

This paper presents a two-stage solution method for the curriculum-based university course timetabling problem. First, an initial solution is created using a recursive search algorithm, then its quality is improved with a local search heuristic. This method utilizes a tabu list of forbidden transformations, as well as a destructive step at the end of each iteration. The algorithm is tested on datasets of the 2007 International Timetabling Competition.


## Keywords

University course timetabling; Local search; Heuristic

## 1. INTRODUCTION

Creating the timetable of employees is a crucial task for any organization, and educational institutions are no exceptions. While timetabling problems can sometimes be extremely hard, they are still solved manually in many cases. This process can take a long time, and the efficiency of the resulting timetables is not guaranteed.

There are several different types of timetabling problems that have to be solved in academia, mainly connected to the students or the employees. This paper will cover such a specific problem, namely university course timetabling.

The first section of this paper will introduce the field of course timetabling, and present the curriculum-based university course timetabling problem in detail. After this, we present a two-stage heuristic for the solution of the problem, which is then tested on datasets of the 2007 International

[^0]Timetabling Competition. These instances are based on real world timetables of the University of Udine, Italy.

## 2. COURSE TIMETABLING

Course timetabling is an optimization problem, where resources (courses, rooms, teachers) are allocated to create a timetable that satisfies given constraints. The problem schedules courses and teachers into available time-slots, while trying to avoid the different types of conflicts that can arise. Many variations exist for the course timetabling problem, but the most important ones are the following:

- Curriculum-based Course Timetabling: courses belong to one of several curricula, and courses of the same curriculum cannot be scheduled in overlapping timeslots.
- Post Enrollment based Course Timetabling: the problem also considers the students enrolled to the courses, and introduces several constraints connected to their attendance.
- Examination Timetabling: similar to the general timetabling problem, but considers exam committees instead of teachers, and also deals with the availability of the students for their required exams.

This paper will give a solution algorithm for the curriculumbased course timetabling problem. The following sections will define the problem, present its necessary resources and constraints, and give a short literature overview of the field.

### 2.1 Problem definition

The curriculum-based university course timetabling problem schedules a set $C$ of courses over a horizon of $d$ days to create a timetable. Each day is divided into $s$ time-slots, and a course has to be assigned to one or more consecutive slots (depending on its length). A room has to be selected where the course will take place, and a teacher is also assigned as the instructor. Courses can belong to different curricula, introducing additional constraints to the assignment. Courses of the same curriculum usually cannot overlap, or should be
scheduled close to each other in time. The constraints of the problem belong into two different groups.

Hard constraints should always be respected, and a timetable is not allowed to violate any of them. The most common hard constraints are the following:

- Course assignment: The timetable must contain all courses, and every course has to be assigned to exactly one room, time-slot and teacher.
- Room availability: A given room cannot have more than one assigned course at the same time-slot.
- Teacher availability: A given teacher cannot be assigned to more than one course at the same time-slot.
- Room capacity: A course cannot be scheduled to a room with less capacity than the number of students on the course. Some papers consider this as a soft constraint.
- Teacher availability: Teachers can have time-slots when they are not available. Naturally, no course can be assigned to a teacher at a time-slot where they are not available. Some papers consider this as a soft constraint.

Soft constraints can be violated, but they come with a penalty. The typical soft constraints are the following:

- Compactness: Isolated courses in a curriculum should be avoided. A course is isolated, if no other course of the same curriculum is scheduled in its previous or next time-slot.
- Room stability: Courses of the same curriculum should be assigned to the same room, if possible.
- Minimal number of days: Courses of the same curriculum should be spread out over the week: they should be scheduled to a given $d$ amount of days.
- As it was mentioned above, some of the hard constraint (room capacity, unavailability of teachers) can also be considered as a soft constraint.

The objective of the problem is to create a timetable that does not violate any hard constraint, and has a minimum penalty associated to the violations of its soft constraints.

### 2.2 Literature overview

University course timetabling has been researched intensively in the past decades. The problem itself is NP-complete, which was proven by Even et al. [8], and as a result, many different solution methods were considered for its solution. A good overview of these is given by Bettinelli et al. [4] and Babaei et al. [2]. In the following, we will present some the most important of the approaches. An early mathematical model was given by [1], who consider it as a 3-dimensional assignment problem between courses, time-slots and rooms. A more efficient, two-phase mathematical model is presented
by Lach et al. [9], where only courses and time-slots are assigned using a binary variable, and the possible rooms for each time-slot are described by an undirected graph. This approach reduces the model size, and is able to provide solutions for significantly bigger instances.

As mathematical approaches can result in a large model even for relatively small instances, various heuristic methods were also developed for the problem. Different variations of the local search were presented, such as the tabu search of Lü and Hao [10] or the simulated annealing of Bellio et al. [3]. Improved versions of Dueck's Great Deluge algorithm [7] a genetic algorithm with a philosophy close to local search were also been published [5]. Hybrid algorithms with multiple stages are also available, like Müller [11] or Shaker et al. [12], both of which are modifications of the Great Deluge.

## 3. A TWO-STAGE HEURISTIC

In this section, we propose a two-stage heuristic for solving the curriculum-based university course timetabling problem. First, an initial feasible solution is created using a greedy recursive algorithm, then a local search heuristic is utilized to improve its quality.

We apply the following soft constraints from Section 2: Compactness, Room capacity, Room stability, Minimum number of days. The reason for this is that we use the datasets of the Curriculum-based Course Timetabling track of the International Timetabling Competition 2007 (ITC) [6] as evaluation for the method, and this competition also considers the same constraints.

The initial solution is created using a recursive search, which only considers the hard constraints of the problem. The pseudo-code of this can be seen in Algorithm 1.

```
Algorithm 1 Recursive algorithm for initial solution.
Funct recSol(course, node, list)
    if All courses are assigned then
        return TRUE
    end if
    if No more assignment possibilities then
        return FALSE
    end if
    if (course, node) assignment is invalid then
        node \(:=\) next (timeslot,room) pair
        return recSol(course, node, list)
    end if
    if course.teacher is available az node.timeslot then
        list \(\leftarrow\) (course,node) assignment
        node \(:=\) next (timeslot,room) pair
        course \(:=\) next free course
        return recSol(course, node, list)
    else
        node \(:=\) next (timeslot,room) pair
        return recSol(course, node, list)
    end if
```

The function requires 3 input data: the course to be considered (course), the proposed time-slot and room pair (node), and a list of nodes corresponding to the partial solution that is already built (list). Initially, list is empty, and course and
node are randomly chosen. If the assignment of the current course is not possible to this node, then another one is chosen and a recursive call is made. If the course is compatible with the node, and the teacher of the course is also available at the time-slot in question, then the assignment is saved, and the next recursive call will feature a new course. The algorithm terminates if all the courses are assigned, or if there are no more possible nodes to choose from.

As the initial solution is built without considering any soft constraints, it will have a high penalty. A local search method is then used to decrease this penalty by also taking the soft constraints of the problem into consideration. The outline of the algorithm can be seen in Algorithm 2.

```
Algorithm 2 Local search algorithm.
Funct localSearch \((t t, t a b u, n)\)
    \(i:=0\)
    bestSol \(:=t t\)
    while \(n>0\) do
        while foundBetter \(=\) TRUE do
            bestCost \(=\operatorname{cost}(t t)\)
            for Each \(a:=(\) course,timeslot,room \()\) in \(t t\) do
                    for Each \(b:=(\) timeslot,room \()\) in \(t t\) do
                        if \((a, b) \in t a b u\) then
                        CONTINUE
                end if
                neighbor \(:=t t \cdot \operatorname{swap}(a, b)\)
                if neighbor violates hard constraints then
                    CONTINUE
                end if
                if cost(neighbor) < bestNeighCost then
                    bestNeighCost \(:=\operatorname{cost}(\) neighbor \()\)
                    bestNeigh \(:=\) neighbor
                            tabutCand \(:=(b, a)\)
                end if
                    end for
            end for
            if bestNeighCost < bestCost then
                    bestCost \(:=\operatorname{cost}(\) bestNeigh \()\)
                    bestSol \(:=\) bestNeigh
                    \(t a b u \leftarrow t a b u C a n d\)
                    foundBetter := TRUE
            else
                    foundBetter := FALSE
            end if
            if \(i>x\) then
                    tabu(0).erase()
                    \(i:=0\)
            end if
            \(i:=i+1\)
        end while
        destructSearch (bestSol, tabu)
        \(n:=n-1\)
    end while
    return bestSol
```

The input of the algorithm is the $t t$ timetable of assignments from the first stage, the empty list tabu for forbidden neighborhood transformations, and a parameter $n$ that gives the number of destruction steps. The algorithm considers two different neighborhood transformations:

- Swap: The timeslot of a (course, timeslot,room) assignment is swapped with the slot of another assignment.
- Move: A (course,timeslot,room) assignment is moved to another (timeslot,room) position.

The process examines all possible neighborhood moves for a given timetable, and applies the one with the smallest penalty. If the resulting timetable is better than the currently stored best one, then it becomes the new best solution, and the neighborhood move that was used to produce this solution is saved to the tabu list of forbidden moves.

If a local optimum is found, the algorithm switches to the destructSearch phase. In this phase, a set number of neighborhood moves are applied to the solution, strictly decreasing the quality with each step. After this destruction phase, the local search part of the algorithm is executed again, searching for a new local optimum, while also using the existing tabu list to avoid certain transformations. The number of these destruction steps is given by the parameter $n$ in the input.

## 4. TEST RESULTS

As it was mentioned in the previous Section, the algorithm was tested on the instances of the 2007 International Timetabling Competition. These instances are based on real-life input from the University of Udine. The competition provided three sets of input: Early, Late and Hidden datasets. Due to space limitations, we will only present the first two of these datasets. The most important information about these can be seen in Table 1.

Table 1: Input characteristics

| Inst. | Day | Slot | Room | Course | Curr. | Unav. |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Early Datasets |  |  |  |  |  |  |
| Comp01 | 5 | 6 | 6 | 30 | 14 | 53 |
| Comp02 | 5 | 5 | 16 | 82 | 70 | 513 |
| Comp03 | 5 | 5 | 16 | 72 | 68 | 382 |
| Comp04 | 5 | 5 | 18 | 79 | 57 | 396 |
| Comp05 | 6 | 6 | 9 | 54 | 139 | 771 |
| Comp06 | 5 | 5 | 18 | 108 | 70 | 632 |
| Comp07 | 5 | 5 | 20 | 131 | 77 | 667 |
| Late Datasets |  |  |  |  |  |  |
| Comp08 | 5 | 5 | 18 | 86 | 61 | 478 |
| Comp09 | 5 | 5 | 18 | 76 | 75 | 405 |
| Comp10 | 5 | 5 | 18 | 115 | 67 | 694 |
| Comp11 | 5 | 9 | 5 | 30 | 13 | 94 |
| Comp12 | 6 | 6 | 11 | 88 | 150 | 1368 |
| Comp13 | 5 | 5 | 19 | 82 | 66 | 468 |
| Comp14 | 5 | 5 | 17 | 85 | 60 | 486 |

For each instance, the table gives the number of days, timeslots per day, rooms, courses, curricula and unavailability constraints for the teachers. The following penalty values were used for the soft constraints:

- Compactness: Every isolated course is worth 2 ponts.
- Roomy capacity: The capacity of a room can be violated, but every student above the capacity is worth 1 point.
- Room stability: If lectures of a course are scheduled into more than one room, then the penalty for each room beyond the first is 1 point.
- Minimum number of days: If a course is scheduled on less days than the minimum required number, 5 penalty points are given for missing each day.

Test results of the algorithm are presented in Table 2. The algorithm was executed ten times for each instance, and the rounded average of these solutions is give by the table. The destructive search ran for 30 steps in each iteration.

| Table 2: Test results |  |
| :--- | :--- | :--- |
| Instance Runningtime Penalty <br> Early Datasets   <br> Comp01 32s 51 <br> Comp02 16M26s 328 <br> Comp03 9M16s 314 <br> Comp04 8M25s 348 <br> Comp05 7M32s 423 <br> Comp06 14M54s 503 <br> Comp07 15M46s 592 <br> Late Datasets   <br> Comp08 10M31s 361 <br> Comp09 12M3s 285 <br> Comp10 16M17s 536 <br> Comp11 43s 37 <br> Comp12 11M4s 525 <br> Comp13 9M42s 331 <br> Comp14 7 M 32 s 434 |  |

The table presents the total running time of both stages for each instance, as well as the total penalty of the best achieved solution. It can be seen from the results that while the running times are acceptable, the penalties in some cases are a bit high. This means that there is still room for the improvement of the algorithm.

## 5. CONCLUSIONS AND FUTURE WORK

In this paper, we examined the curriculum-based university course timetabling problem, and developed a two-stage heuristic algorithm for its solution. This algorithm uses a greedy recursive approach to construct an initial solution, then increases its quality with the help of a local search method. While the local search itself is not fully a tabu search algorithm, it utilizes a tabu list to store forbidden transformations. A destructive step is also executed to escape local optima at the end of each iteration.

The algorithm was tested on the datasets of the 2007 International Timetabling Competition. While feasible solutions were found for all instances, both their running time and quality can be improved. We would like to implement faster approaches for creating the initial solution, as well as implementing a proper tabu search algorithm instead of the current local search.

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