



Efficient boundary condition estimation for continuous casting machinery

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Reduced Order Modelling, Simulation and
Optimization of Coupled Systems
(ROMSOC)



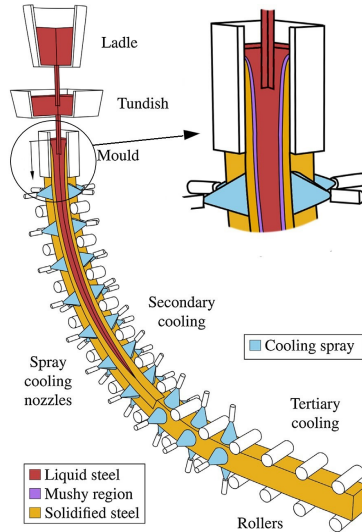
Strobl, October 15, 2019



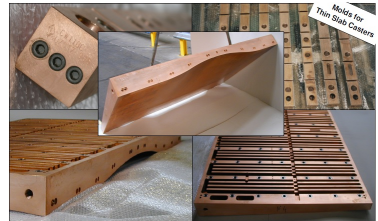
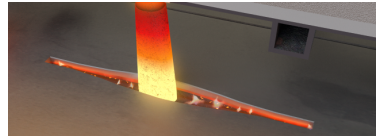
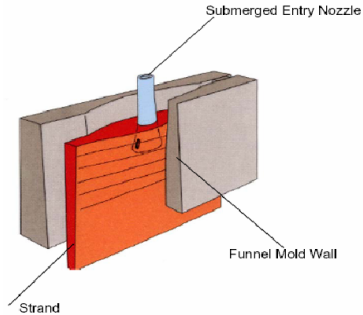
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https://www.danieli.com/en/flat_products_43_2.htm

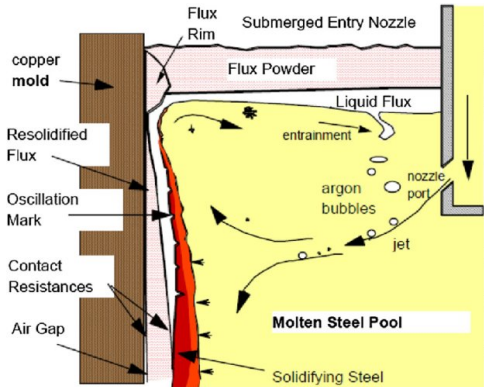


Credits: Klimes et al.



- ▶ Copper plates
- ▶ Cooled by water flowing in channels

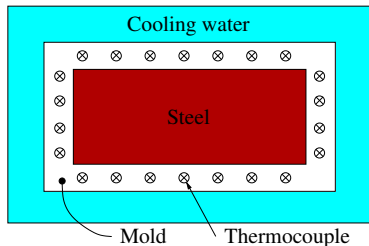
Credits: Carl Schreiber GmbH Neunkirchen, Pprime



Credits: Zhou et al.

Mold issues:

- ▶ Steel sticking to the mold
- ▶ Solid skin braking
- ▶ Cracks



Section of the mold

The casting is mainly controlled by changing the **casting speed**

Information available:

- ▶ Temperature measurements inside the mold
- ▶ Cooling water temperature increase
- ▶ Liquid steel level

Temperatures measurements

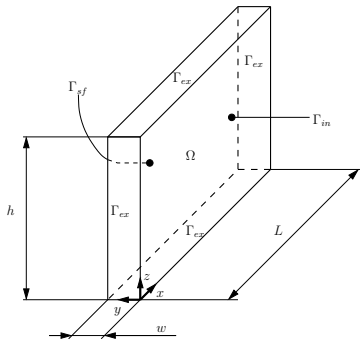


Computation of **heat flux** at the steel-mold interface in
real-time

1 Full Order Inverse Problem

- Alifanov's Regularization
- Levenberg-Marquardt method

2 Reduced Order Inverse Problem



Mold model

Given $k \in \mathbb{R}^+$, $h \in \mathbb{R}^+$, $g \in L^2(\Gamma_{in})$ and $T_f \in L^2(\Gamma_{in})$. Find T such that

$$-k\Delta T(\mathbf{x}) = 0 \text{ on } \mathbf{x} \in \Omega,$$

$$\begin{cases} -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = g(\mathbf{x}) & \text{in } \mathbf{x} \in \Gamma_{in}, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = 0 & \text{in } \mathbf{x} \in \Gamma_{ex}, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = h(T(\mathbf{x}) - T_f(\mathbf{x})) & \text{in } \mathbf{x} \in \Gamma_{sf}. \end{cases}$$

- ▶ T - Mold temperature
- ▶ T_f - Cooling water temperature
- ▶ h - Heat transfer coefficient
- ▶ k - Copper thermal conductivity
- ▶ g - Steel-mold heat flux (**unknown**)

Temperatures measurements



Computation of **heat flux** at the steel-mold interface

Inverse problem

Given the temperature measurements $\tilde{T}(\mathbf{x}_i) \in \mathbb{R}^+$, $i = 1, 2, \dots, M$, find $g(\mathbf{x}) \in L^2(\Gamma_{in})$ which minimizes the functional

$$J[g] = \frac{1}{2} \sum_{i=1}^M [T[g](\mathbf{x}_i) - \tilde{T}(\mathbf{x}_i)]^2,$$

where $T[g](\mathbf{x})$ is solution of the direct problem.

Temperatures measurements



Computation of **heat flux** at the steel-mold interface

Inverse problem

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where $T[g](\mathbf{x})$ is solution of the direct problem.

Ill-posed problem → Requires **regularization**

Regularization techniques:

- ▶ **Alifanov's regularization**
 - Conjugate gradient method applied to the adjoint problem
- ▶ **Levenberg-Marquardt method**
 - Parameterization of the heat flux $g(\mathbf{x}) = \sum_{i=1}^N w_i \gamma_i(\mathbf{x})$

- 1 Set $\mathbf{g}^0(\mathbf{x})$;
- 2 **while** $n \leq nMax$ **do**
- 3 Solve direct problem;
- 4 Compute J ;
- 5 **if** *convergence* **then**
- 6 └ Stop;
- 7 Solve adjoint problem \rightarrow gradient of J, J' ;
- 8
$$\gamma^n = \frac{\int_{\Gamma_{sin}} [J'_{g^n}(\mathbf{x})]^2 dx}{\int_{\Gamma_{sin}} [J'_{g^{n-1}}(\mathbf{x})]^2 dx};$$
- 9 Search direction, $P^n(\mathbf{x}) = J'_{g^n}(\mathbf{x}) + \gamma^n P^{n-1}(\mathbf{x})$;
- 10 Solve sensitivity problem ;
- 11
$$\beta^n = \arg \min_{\beta} J[\mathbf{g}^n - \beta P^n] = \frac{\sum_{i=1}^M \{T[\mathbf{g}^n](\mathbf{x}_i) - \tilde{T}(\mathbf{x}_i)\} \delta T[P^n](\mathbf{x}_i)}{\sum_{i=1}^M (\delta T[P^n](\mathbf{x}_i))^2};$$
- 12 $\mathbf{g}^{n+1} = \mathbf{g}^n - \beta^n P^n$;
- 13 $n = n + 1$;

Adjoint problem

$$\frac{1}{k}\Delta\lambda(\mathbf{x}) + \sum_{i=1}^M (T[\mathbf{g}](\mathbf{x}_i) - \tilde{T}(\mathbf{x}_i))\delta(\mathbf{x} - \mathbf{x}_i) = 0, \text{ on } \Omega,$$
$$\begin{cases} \frac{1}{k}\nabla\lambda(\mathbf{x}) \cdot \mathbf{n} = 0 & \text{in } \Gamma_{in} \cup \Gamma_{ex}, \\ \frac{1}{k}\nabla\lambda(\mathbf{x}) \cdot \mathbf{n} + \frac{1}{k^2}h\lambda(\mathbf{x}) = 0 & \text{in } \Gamma_{sf}. \end{cases}$$

Sensitivity problem

$$-k\Delta\delta T(\mathbf{x}) = 0, \text{ on } \Omega,$$
$$\begin{cases} -k\nabla\delta T(\mathbf{x}) \cdot \mathbf{n} = P^n(\mathbf{x}) & \text{in } \Gamma_{in}, \\ -k\nabla\delta T(\mathbf{x}) \cdot \mathbf{n} = 0 & \text{in } \Gamma_{ex}, \\ -k\nabla\delta T(\mathbf{x}) \cdot \mathbf{n} = h(\delta T(\mathbf{x})) & \text{in } \Gamma_{sf}. \end{cases}$$

$$g(\mathbf{x}) = -x \cdot z \cdot 10^5 \frac{W}{m^2}$$



Finite Volume discretization

$$A\mathbf{T} = \mathbf{b}_g + \mathbf{b}$$



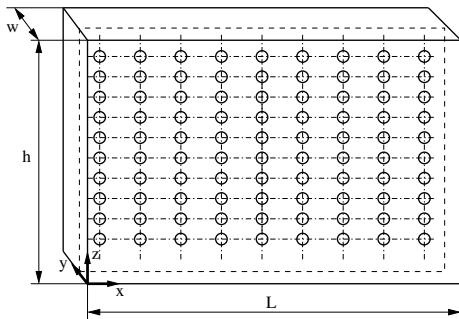
Temperature measurements, \tilde{T}



Inverse problem solver



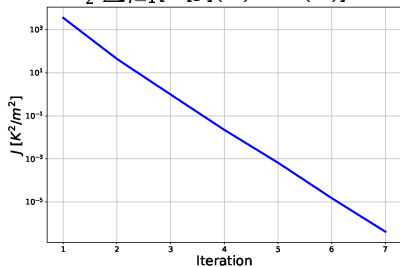
Estimated heat flux, $g(\mathbf{x})$



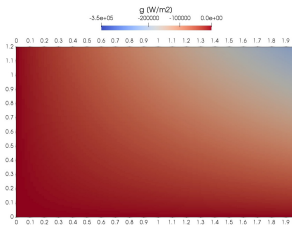
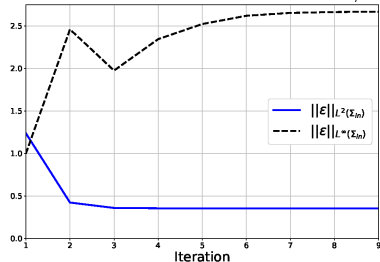
Positions of the thermocouples



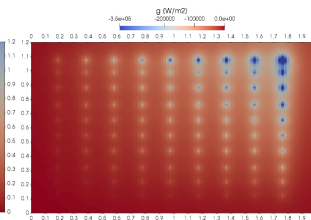
$$J = \frac{1}{2} \sum_{i=1}^M [T[g](x_i) - \tilde{T}(x_i)]^2$$



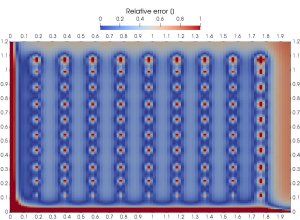
L^2 and L^∞ norm of the relative error, ϵ



$$g(x) = -x \cdot z \cdot 10^5$$

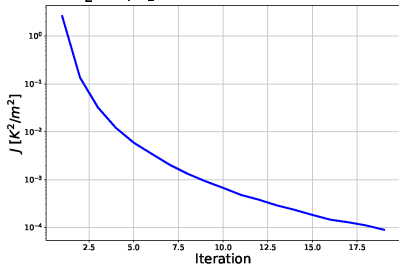


Reconstructed heat flux

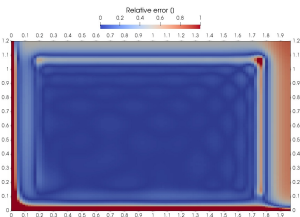
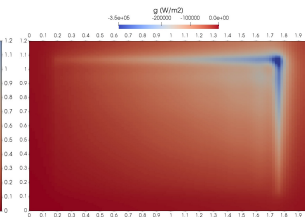
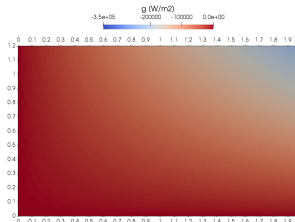
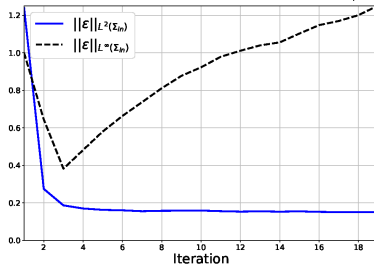


Relative error, ϵ

$$J = \frac{1}{2} \sum_{i=1}^M [T[g](x_i) - \tilde{T}(x_i)]^2$$



L^2 and L^∞ norm of the relative error, ϵ



$$g(x) = -x \cdot z \cdot 10^5$$

Reconstructed heat flux

Relative error, ϵ

Regularization techniques:

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- ▶ **Levenberg-Marquardt method**
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Parameterization of heat flux $g(\mathbf{x}) = \sum_{i=1}^N w_i \gamma_i(\mathbf{x})$

Inverse problem

Given the temperature measurements $\tilde{T}(\mathbf{x}_i) \in \mathbb{R}^+$, $i = 1, 2, \dots, M$, find $\mathbf{w} \in \mathbb{R}^N$ which minimizes the functional

$$J[g] = \frac{1}{2} \sum_{i=1}^M [T[g](\mathbf{x}_i) - \tilde{T}(\mathbf{x}_i)]^2,$$

where $T[g](\mathbf{x})$ is solution of

$$-k\Delta T(\mathbf{x}) = 0 \text{ on } \mathbf{x} \in \Omega,$$

$$\begin{cases} -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = \sum_{i=1}^N w_i \gamma_i(\mathbf{x}) & \text{in } \mathbf{x} \in \Gamma_{in}, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = 0 & \text{in } \mathbf{x} \in \Gamma_{ex}, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = h(T(\mathbf{x}) - T_f(\mathbf{x})) & \text{in } \mathbf{x} \in \Gamma_{sf}. \end{cases}$$

```

1 Set  $\mathbf{w}^0$ ;
2 while  $n \leq nMax$  do
3   Solve direct problem;
4   Compute  $J$ ;
5   if convergence then
6     Stop;
7   Compute the Jacobian,  $\mathcal{J}$  ;
8   Solve  $[(\mathcal{J}^n)^T \mathcal{J}^n - s^n I] \delta \mathbf{w}^n = -(\mathcal{J}^n)^T \mathbf{R}^n$  ;
9   Update weights  $\mathbf{w}^{n+1} = \mathbf{w}^n + \delta \mathbf{w}^n$  ;
10   $n = n + 1$ ;

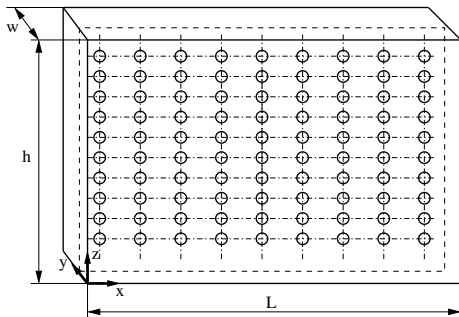
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► $\mathcal{J}_{ij} = \frac{\partial T_i[\mathbf{w}]}{\partial w_j}$

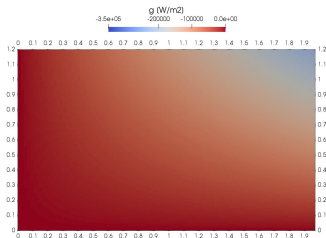
► s - Regularization factor

Basis functions $\gamma_i(\mathbf{x})$ are Gaussian Radial Basis Functions centered at the projection of the thermocouples on the boundary Γ_{in}

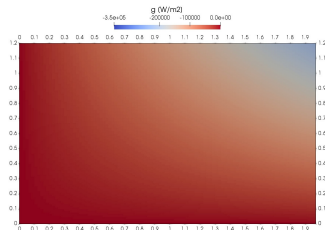
$$\gamma_i(\mathbf{x}) = e^{-\alpha^2 r_i(\mathbf{x})^2}$$



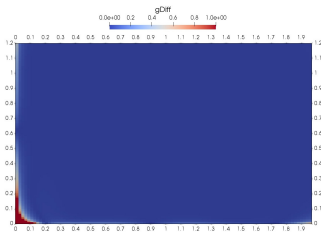
Positions of the thermocouples



$$g(x) = -x \cdot z \cdot 10^5$$



Reconstructed heat flux



Relative error, ϵ

- ▶ Approx. **40 seconds** required for the solution
- ▶ For **real time computation** the we have to reduce the computation time to less than 1 second
- ▶ We use **Reduced Basis Method** to reduced the cost of solving the direct problem

1 Full Order Inverse Problem

- Alifanov's Regularization
- Levenberg-Marquardt method

2 Reduced Order Inverse Problem

Parameterized PDE

Direct problem

$$\begin{cases} -k\Delta T(\mathbf{x}) = 0 & \text{on } \mathbf{x} \in \Omega, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = \sum_{i=1}^N w_i \gamma_i(\mathbf{x}) & \text{in } \mathbf{x} \in \Gamma_{in}, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = 0 & \text{in } \mathbf{x} \in \Gamma_{ex}, \\ -k\nabla T(\mathbf{x}) \cdot \mathbf{n} = h(T(\mathbf{x}) - T_f(\mathbf{x})) & \text{in } \mathbf{x} \in \Gamma_{sf}. \end{cases}$$

The parameters are the weights \mathbf{w}

POD-Galerkin approach



we have to sample the parameter space



Reduction of the parameter space, i.e. the dimension of \mathbf{w}

Experimental measurements from a real mold, $\tilde{T}_i, i = 1, 2, \dots, M$



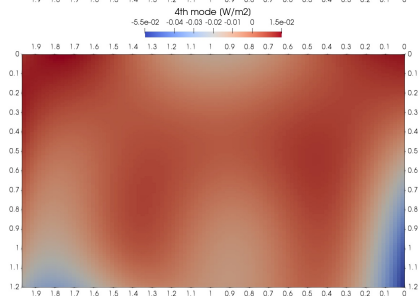
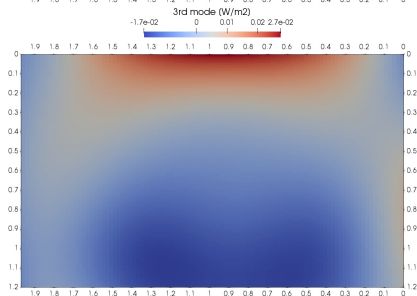
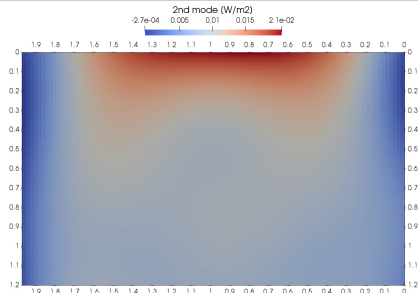
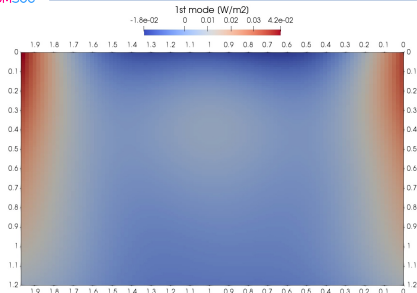
Solve inverse problem, obtain $g(\mathbf{x})$ for each set of measurements



Perform a Proper Orthogonal Decomposition (POD) on the obtained set of
heat flux, $g(\mathbf{x})$



Use the first few modes, $\gamma_r(\mathbf{x}), r = 1, 2, \dots, R$, as basis for the heat flux,
 $g(\mathbf{x}) = \sum_{r=1}^R w_r \gamma_r(\mathbf{x})$



- Having reduced the number of parameters, we can sample the parameter space and obtain a set of solutions of the direct problem (snapshots)

$$\mathbb{V}_T = \text{span}(\mathbf{T}_1, \mathbf{T}_2, \dots, \mathbf{T}_S)$$

- POD on solution space to obtain orthonormal basis ϕ

$$\mathbb{V}_T = \text{span}(\phi_1, \phi_2, \dots, \phi_S),$$

- Select the first few modes to have a reduced basis spaces $\mathbb{V}_{T_{RB}}$

$$\mathbb{V}_{T_{RB}} = \text{span}(\phi_1, \phi_2, \dots, \phi_{N_r}), N_r \ll N_h$$

- Approximation of full order fields by linear combinations of the modes

$$T \approx \sum_{i=1}^{N_r} T_{r_i} \phi_i$$

- Galerkin projection of the full order model on the reduced basis

$$L := \begin{bmatrix} | & & | \\ \phi_1 & \dots & \phi_{N_r} \\ | & & | \end{bmatrix} \in \mathbb{R}^{N_h \times N_r}, \mathbf{T} = L\mathbf{T}_r$$

Full order, N_h unknowns

$$A\mathbf{T} = \mathbf{b}_g + \mathbf{b}$$

↓

$$L^T A L \mathbf{T}_r = L^T \mathbf{b}_g + L^T \mathbf{b}_T$$

↓

Reduced order, N_r unknowns

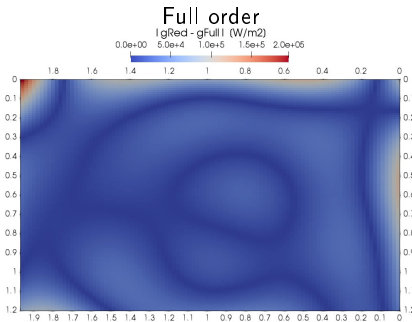
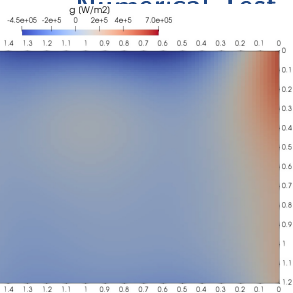
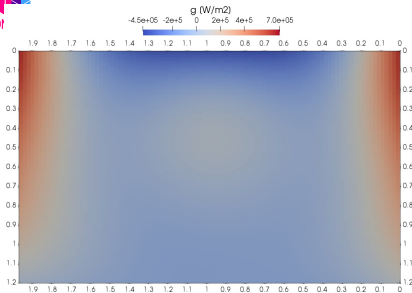
$$A_r \mathbf{T}_r = L^T G \mathbf{w} + \mathbf{b}_r = G_R \mathbf{w} + \mathbf{b}_r$$

Offline

- ▶ Solve full order inverse problem with meaningful set of experimental measurements
- ▶ Perform POD on **heat flux** samples
- ▶ Compute snapshot for direct problem
- ▶ POD on snapshot set
- ▶ Assemble A_r, G_r, \mathbf{b}_r

Online

- ▶ Use Levenberg-Marquardt Regularization



Reduced order

Computational cost of the online phase
 ≈ 2 seconds

Error

Conclusions

- Implemented full order methodology
- Developed reduced method for inverse problem

Future Work

- Error estimate
- Move to Bayesian approach
- Study noise on input

Thank you