

1 **Sensitivity of phytoplankton primary production**
2 **estimates to available irradiance under heterogeneous**
3 **sea-ice conditions**

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13 **Key Points:**

- 14 • Phytoplankton primary production under heterogeneous sea ice is highly spatially
15 variable.
- 16 • Transmittance sampled with profiling platforms improves the accuracy of primary
17 production estimates.
- 18 • Upscaling estimates at larger spatial scales using satellite sea-ice concentration further
19 reduced the error.

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Abstract

The Arctic icescape is composed by a mosaic of ridges, hummocks, melt ponds, leads and snow. Under such heterogeneous surfaces, drifting phytoplankton communities are experiencing a wide range of irradiance conditions and intensities that cannot be sampled representatively using single-location measurements. Combining experimentally derived photosynthetic parameters with transmittance measurements acquired at spatial scales ranging from hundreds of meters (using a Remotely Operated Vehicle, ROV) to thousands of meters (using a Surface and Under-Ice Trawl, SUIT), we assessed the sensitivity of water-column primary production estimates to multi-scale under-ice light measurements. Daily primary production calculated from transmittance from both the ROV and the SUIT ranged between 0.004 and 939 mgC m⁻² d⁻¹. Upscaling these estimates at larger spatial scales using satellite-derived sea-ice concentration reduced the variability by 22% (0.004-731 mgC m⁻² d⁻¹). The relative error in primary production estimates was two times lower when combining remote sensing and in situ data compared to ROV-based estimates alone. These results suggest that spatially extensive in situ measurements must be combined with large-footprint sea-ice coverage sampling (e.g., remote sensing, aerial imagery) to accurately estimate primary production in ice-covered waters. Also, the results indicated a decreasing error of primary production estimates with increasing sample size and the spatial scale at which in situ measurements are performed. Conversely, existing estimates of spatially integrated phytoplankton primary production in ice-covered waters derived from single-location light measurements may be associated with large statistical errors. Considering these implications is important for modelling scenarios and interpretation of existing measurements in a changing Arctic ecosystem.

1 Introduction

The Arctic Ocean (AO) icescape is a mosaic composed of sea ice, snow, leads, melt ponds and open water. During the last decades, this AO icescape has been undergoing major changes, including a reduction in extent and thickness (Meier et al., 2014), and an increased drift speed (Kwok, Spreen, & Pang, 2013). A greater frequency of storm events is also making this icescape more prone to deformation (Itkin et al., 2017) and promotes lead formation. Because of the surface heterogeneity of the AO icescape, light transmittance can be highly variable in space, even over short distances (Hancke et al., 2018; Katlein et al., 2015; Nicolaus, Petrich, Hudson, & Granskog, 2013). For example, Perovich, Roesler, and Pegau (1998) showed that sea ice and snow transmittance at 440 nm could vary by a factor of two over horizontal distances of 25 m. The relative contribution of various sea-ice features to under-ice light variability depends on the spatial scale under consideration and has significant implications for their application in physical and ecological studies and also determines the context in which results can be interpreted. For instance, at small scales (< 100 m), local features such as melt ponds and leads have a strong influence on light penetration (Frey, Perovich, & Light, 2011; Katlein, Perovich, & Nicolaus, 2016; Massicotte, Bécu, Lambert-Girard, Leymarie, & Babin, 2018). At larger scales (> 100 m), it was argued that the variability of transmittance is mainly controlled by sea ice thickness (Katlein2015).

Because phytoplankton is exposed to a highly variable light regime while drifting under a spatially heterogeneous, and sometimes dynamic sea-ice surface, single-location irradiance measurements are not representative of the average irradiance experienced by phytoplankton over a large area (Katlein et al., 2016; Lange, Flores, et al., 2017). This is why traditional primary production estimated using in situ incubations at single locations with seawater samples inoculated with ¹⁴C or ¹³C are also not appropriate because they reflect primary production under local light conditions, which is not representative of the range of irradiance experienced by drifting phytoplankton. A better option consists in calculating primary production using daily time series of incident irradiance, sea ice transmittance and in-water vertical attenuation coefficients, combined with photosynthetic parameters determined using

71 photosynthesis vs. irradiance curves (P vs. E curves) measured with incubations of seawater
 72 samples inoculated with ^{14}C . However, this approach requires an adequate description of the
 73 underwater light field, which cannot be characterized using single-location measurements
 74 in a spatially heterogeneous sea ice surface. To better estimate primary production of
 75 phytoplankton under sea ice, the large-area variability in the light field should be adequately
 76 captured.

77 One major challenge in obtaining adequate irradiance estimates under spatially het-
 78 erogeneous sea ice is that observations are often limited to time-consuming single-location
 79 measurements made through boreholes. To overcome this limitation, different underwater
 80 technologies have been developed to study the spatial variability of light transmission un-
 81 der spatially heterogeneous sea-ice surfaces. For the last decade, radiometers have been
 82 attached to remotely operated vehicles (ROV). Small sized ROVs can be deployed through
 83 relatively small holes (< 2 m) to cover areas in the order of a few hundred meters (Ambrose,
 84 von Quillfeldt, Clough, Tilney, & Tucker, 2005; Katlein et al., 2015, 2017; Lund-Hansen et
 85 al., 2018; Nicolaus, Hudson, Gerland, & Munderloh, 2010). Navigating directly under sea
 86 ice, ROVs allow covering various types of sea ice, such as newly formed, ponded and snow-
 87 covered sea ice, as well as pressure ridges (Katlein et al., 2017). More recently, radiometers
 88 have been attached to the Surface and Under Ice Trawl (SUIT). The SUIT is a trawl de-
 89 veloped for sampling meso- and macrofauna in the ice-water interface layer, allowing for
 90 greater spatial coverage on the order of a few kilometers (Flores et al., 2012; Lange, Flores,
 91 et al., 2017; Lange, Katlein, Nicolaus, Peeken, & Flores, 2016).

92 In a recent study, Massicotte et al. (2018) showed that under spatially heterogeneous sea
 93 ice and snow surfaces, propagating measured surface downward irradiance just below sea ice
 94 $E_d(0^-)$ into the water column using upward attenuation coefficient (K_{L_u}) calculated from
 95 radiance profiles is a better choice compared to the traditional downward vertical attenuation
 96 coefficient (K_{E_d}), because it is less influenced by surface heterogeneity. However, while the
 97 method allows propagation of irradiance to depth from $E_d(0^-)$ more accurately, estimation
 98 of representative $E_d(0^-)$ remains difficult. Both ROV and SUIT aim to better describe the
 99 horizontal variability of $E_d(0^-)$ under heterogeneous sea ice. Since these technologies are
 100 designed to operate at different scales and in different conditions, they are likely to provide
 101 complementary information on the light regime experienced by drifting phytoplankton.

102 In this study, we investigated the spatial variability of light transmittance measured
 103 from these two devices and combined them with satellite-derived sea ice concentrations.
 104 We further used these transmittance data measured at different horizontal spatial scales
 105 to quantify how they influence primary production estimates derived from photosynthetic
 106 parameters. The main objective was to determine if combining multiscale under-ice trans-
 107 mittance observations with photosynthetic parameters, which are derived under a range of
 108 different irradiances, could provide adequate estimates of primary production under sea ice.
 109 This study further aimed at addressing the sensitivity of the phytoplankton to heteroge-
 110 neous irradiance. It provides new guidance on how to derive more representative primary
 111 production estimates under a heterogeneous and changing icescape.

112 2 Materials and Methods

113 2.1 Sampling campaign and study sites

114 Process studies on biological productivity and ecosystem interactions were carried out
 115 north of Spitsbergen during the international Transitions in the Arctic Seasonal Sea Ice Zone
 116 (TRANSISZ) expedition aboard the RV Polarstern (PS92, ARK-XXIX/1) between the 19th
 117 of May and the 26th June of 2015. In total, eight process studies (stations 19 27, 31, 32, 39,
 118 43, 46 and 47) were carried out where the ship was anchored to an ice floe, typically for 36
 119 hours (Figure 1, Table 1). While the ship drifted anchored to ice floe on the port side of the
 120 ship, winch-operated instruments were deployed in the open water on the starboard side.

121 Water samples for P vs. E curves were collected using a CTD/Rosette. On-ice station work
 122 included the deployment of a small observation class ROV under the ice to investigate the
 123 small-scale irradiance variability. Prior to arriving or directly after leaving each ice station,
 124 the SUIT was deployed for larger scale characterization of the under-ice irradiance field.
 125 Due to instrument failure, no SUIT data are available for station 32.

126 2.2 Sea-ice and snow thicknesses and sea-ice concentrations

127 Ground-based multi-frequency electromagnetic induction soundings from a GEM-2
 128 (Geophex Ltd., Raleigh, NC, USA) were used to measure the total thickness of both sea
 129 ice and snow following the ROV survey grid. The snow thickness during GEM-2 surveys
 130 was measured with a Snow-Hydro Magna Probe instrument (SnowHydro LLC, Fairbanks,
 131 Alaska, USA) with a precision of 3 mm (Sturm et al., 2006). The instrument was inserted in
 132 the snow approximately every 2 m. The combined GEM-2 and Magna Probe measurements
 133 started immediately after the ROV light transmission measurements were finished to ensure
 134 that the snow surface was undisturbed. Sea-ice thickness was calculated as the difference
 135 between total snow and -ice thickness and snow depth. The snow thickness displayed in
 136 table 1 is based on ice cores sampled at each station. Sea ice concentration (SIC) data
 137 were obtained from www.meereisportal.de and processed according to algorithms in Spreen,
 138 Kaleschke, and Heygster (2008).

139 2.3 Underwater light measurements

140 2.3.1 ROV measurements

141 ROV observations were taken using similar procedures as presented in Nicolaus and
 142 Katlein (2013) and Katlein et al. (2017) using a V8 Sii ROV (Ocean Modules, Atvidaberg,
 143 Sweden) and RAMSES-ACC-VIS (TriOs GmbH, Rastede, Germany) spectroradiometers
 144 mounted both on the ROV and in a fixed location above the sea-ice surface. The ROV was
 145 deployed through a hole drilled through the ice at a distance of more than 300 m from the
 146 ship. Optical measurements were performed along two perpendicular 100-m transects and
 147 in a push-broom pattern over a 100 m by 100 m area. Spectral downward irradiance (E_d ,
 148 $W m^{-2}$) between 320 and 950 nm was recorded above and below the surface to calculate
 149 spectral light transmittance as the ratio of irradiance transmitted through the snow/ice to
 150 incident irradiance. The sensors were triggered in *burst* mode with the sensors acquiring
 151 data as fast as possible. To account for ROV movement, all data with ROV roll and pitch
 152 angles larger than 10 degrees and with a distance of more than 3 m depth to the ice cover
 153 were rejected from further analysis. To account for light attenuation between the ice-water
 154 interface and the sensor, an exponential function was used to obtain the transmission at the
 155 ice-water interface:

$$156 \quad T(z_{\text{int}}) = \frac{T(z)}{e^{-K_{E_d}(\text{PAR}) \times -z}} \quad (1)$$

157 where $T(z_{\text{int}})$ is the transmittance of the ice and snow at the ice-water interface, $T(z)$ the
 158 photosynthetically available radiation (PAR) transmittance measured by the ROV at depth
 159 z (m) and $K_{E_d}(\text{PAR})$ is the downward diffuse attenuation coefficient of PAR (m^{-1}) calculated
 160 from $E(\text{PAR})$ vertical profiles (equation 2). At each station, at some point during the survey,
 161 the ROV measured a vertical irradiance profile between the surface and at least 20 m depth.
 162 Photosynthetically available radiation downwelling irradiance ($E(\text{PAR}, z)$, $\mu\text{mol m}^{-2} \text{s}^{-1}$),
 163 was calculated as follows:

$$164 \quad E(\text{PAR}, z) = \frac{1}{hc} \frac{1}{N} \int_{400}^{700} \lambda E_d(\lambda, z) d\lambda \quad (2)$$

165 where h is Planck's constant, describing the energy content of quanta (6.623×10^{-34} J s), c
 166 is the constant speed of light ($299\,792\,458$ m s $^{-1}$), N is Avogadro's number (6.022×10^{23}
 167 mol $^{-1}$) and $E_d(\lambda, z)$ is the measured irradiance at wavelength λ (nm) at depth z . Conversion
 168 from mol to μmol has been done using a factor of 1×10^6 . Note that planar, $E(\text{PAR})$, was
 169 converted to scalar irradiance, $\mathring{E}(\text{PAR})$, using a conversion factor of 1.2 (Toole, Kieber,
 170 Kiene, Siegel, & Nelson, 2003). For each vertical $\mathring{E}(\text{PAR})$ profile, $K_{\mathring{E}_d}(\text{PAR})$ was calculated
 171 by fitting the following equation to the measured irradiance data:

$$172 \quad \mathring{E}(\text{PAR}, z) = \mathring{E}(\text{PAR}, z_{\text{int}}) e^{-K_{\mathring{E}_d}(\text{PAR})z} \quad (3)$$

173 where $\mathring{E}(\text{PAR}, z_{\text{int}})$ is PAR at the ice-water interface and $K_{\mathring{E}_d}(\text{PAR})$ is the diffuse
 174 vertical attenuation coefficient (m $^{-1}$) describing the rate at which $\mathring{E}(\text{PAR})$ decreases with
 175 increasing depth. It is assumed constant for a given station in all our calculations. The
 176 determination coefficients (R^2) of the non-linear fits (equation 3) varied between 0.936 and
 177 0.998.

178 **2.3.2 SUIT measurements**

179 On the SUIT, transmittance (T) and sea ice draft observations were made using a
 180 mounted environmental sensors array that included a RAMSES-ACC irradiance sensor
 181 (Trios, GmbH, Rastede, Germany), a conductivity-temperature-depth probe (CTD; Sea
 182 and Sun Technology, Trappenkamp, Germany), a PA500/6S altimeter (Tritech International
 183 Ltd., Aberdeen, UK), and an Aquadopp acoustic doppler current Profiler (ADCP; Nortek
 184 AS, Rud, Norway). A complete and detailed description of the full sensor array can be
 185 found in David, Lange, Rabe, and Flores (2015) and Lange et al. (2016). Sea ice draft was
 186 calculated from the CTD depth and altimeter measurements of the distance to the ice and
 187 corrected for sensor attitude using the ADCP's pitch and roll measurements according to
 188 Lange et al. (2016). Irradiance above the ice was measured with a RAMSES spectroradiome-
 189 ter mounted on the ship's crow's nest. Consistent with the ROV spectral measurements,
 190 the transmittance was calculated as the ratio of under-ice irradiance to incoming irradiance.
 191 SUIT-mounted downwelling irradiance measurements were acquired every 11 seconds during
 192 the haul. To account for SUIT movement, all data with SUIT roll and pitch angles larger
 193 than 15 degrees were rejected from further analysis. Note that we did not correct for the
 194 light attenuation between the ice-water interface and the sensor because contrary to the
 195 ROV, the SUIT frame is equipped with buoyancy blocks that keep it at the surface in open
 196 water or in contact with the sea ice.

197 **2.4 Incident in-air $\mathring{E}(\text{PAR})$**

198 A CM 11 global radiation pyranometer (Kipp & Zonen, Delft, Netherlands) installed
 199 in the crow's nest onboard the Polarstern was used for measuring incident solar photosyn-
 200 thetically available radiation, ($\mathring{E}(\text{PAR})$, W m $^{-2}$), at 10 minutes intervals. Conversion from
 201 shortwave flux in energy units to $\mathring{E}(\text{PAR})$ in quanta ($\mu\text{mol m}^{-2} \text{s}^{-1}$) was achieved using
 202 a conversion factor of 4.49 (McCree, 1972). Data were then hourly averaged. Calculated
 203 hourly $\mathring{E}(\text{PAR}, 0^+)$ were vertically propagated in the water column between 0 and 40 meters
 204 with 1-meter increments using the following equation:

$$205 \quad \begin{aligned} \mathring{E}(\text{PAR}, z, t) &= \mathring{E}(\text{PAR}, 0^+, t) T(z_{\text{int}}) e^{-K_{\mathring{E}_d}(\text{PAR})z} \\ &= \mathring{E}(\text{PAR}, z_{\text{int}}) e^{-K_{\mathring{E}_d}(\text{PAR})z} \end{aligned} \quad (4)$$

207 where $\mathring{E}(\text{PAR}, 0^+, t)$ is the incident in-air hourly PAR derived from the pyranometer ($\mu\text{mol m}^{-2} \text{s}^{-1}$),
 208 $K_{\mathring{E}_d}(\text{PAR})$ is derived from the ROV (see Table 1 and equation 3), z the water depth (m)

209 and $T(z_{\text{int}})$ the snow and sea ice transmittance estimated using either the ROV or the SUIT
 210 data.

211 2.5 Photosynthetic parameters derived from P vs. E curves

212 To calculate photosynthetic parameters (see the next section for a complete description
 213 of these parameters), seawater samples were taken from six depths between 1 and 75 m and
 214 incubated at different irradiance levels in presence of ^{14}C -labelled sodium bicarbonate using
 215 a method derived from Lewis and Smith (1983). Incubations were carried out in a dimly
 216 lit radiation van under the deck to avoid any light stress on the algae. Three replicates of
 217 50 mL samples were inoculated with inorganic ^{14}C ($\text{NaH}^{14}\text{CO}_3$, approximately $2 \mu\text{Ci mL}^{-1}$
 218 final concentration). Exact total activity of added bicarbonate was determined by three
 219 20 μL aliquots of inoculated samples added to 50 μL of an organic base (ethanolamine)
 220 and 6 mL of scintillation cocktail (EcoLumeTM, Costa Mesa, US) into glass scintillation
 221 vials. One mL aliquots of the inoculated sample were dispensed into twenty-eight 7 mL glass
 222 scintillation vials. The samples were cooled to 0°C in thermo-regulated alveoli. Within the
 223 array, the vials were exposed to 28 different irradiance levels provided by separate LEDs
 224 (LUXEON Rebel, Philips Lumileds, USA) from the bottom of each alveolus. Scalar PAR
 225 irradiance was measured in each alveolus prior to the incubation with an irradiance quantum
 226 meter (Walz US-SQS + LI-COR LI-250A, USA) equipped with a 4π spherical collector. For
 227 each measurement, the range of irradiance intensities was selected in order to adequately
 228 capture the initial slope and maximum part of the P vs. E curve. Because this depends
 229 on the in situ growth irradiance, incubation irradiances were modified according to the
 230 depth at which the sample was collected. The maximum irradiance varied between 124 and
 231 $1143 \mu\text{mol photon m}^{-2} \text{ s}^{-1}$. The incubation lasted for 120 minutes and the incubations were
 232 terminated by adding with 50 μL of buffered formalin to each sample. Note that given the
 233 short incubation time, our method for deriving primary production likely provides values
 234 close to gross production (Lewis & Smith, 1983). Thereafter, the aliquots were acidified (250
 235 μL of HCl 50%) in a glove box (radioactive $^{14}\text{CO}_2$ was trapped in a NaOH solution before
 236 opening the glove box) to remove the excess inorganic carbon (three hours, Knap, Michaels,
 237 Close, Ducklow, and Dickson (1996)). In the end, 6 mL of scintillation cocktail was added to
 238 each vial prior to counting in a liquid scintillation counter (Tri-Carb, PerkinElmer, Boston,
 239 USA). The carbon fixation rate was finally estimated according to Parsons, Maita, and Lalli
 240 (1984). Photosynthetic parameters were estimated from P vs. E curves by fitting non-linear
 241 models based on the original definition proposed by Platt, Gallegos, and Harrison (1980)
 242 using equation 5 (parameters are presented in the next section):

$$243 \quad P(z) = (1 - e^{-\alpha(z) \frac{\dot{E}(\text{PAR}, z)}{z}}) \times e^{-\beta(z) \frac{\dot{E}(\text{PAR}, z)}{z}} + P_0 \quad (5)$$

244 2.6 Estimating primary production

245 Two different approaches were used to calculate primary production from estimated
 246 photosynthetic parameters.

247 *Method 1: under-ice only primary production* - This first approach relied on using
 248 $\dot{E}(\text{PAR})$ propagated in the water column only under the ice using the transmittance values
 249 derived from either the ROV or the SUIT, the $K_{\dot{E}_d}(\text{PAR})$ from the ROV and the hourly
 250 incident irradiance from the pyranometer. Primary production was calculated every hour at
 251 each sampling depth using $\dot{E}(\text{PAR}, z, t)$ measurements derived from both ROV and SUIT
 252 transmittance as follows:

$$253 \quad P_{\text{underice}}^{\text{device}}(z, t) = P(z) (1 - e^{-\alpha(z, t) \frac{\dot{E}(\text{PAR}, z, t)}{z}}) \times e^{-\beta(z, t) \frac{\dot{E}(\text{PAR}, z, t)}{z}} \quad (6)$$

254 where $P_{\text{underice}}^{\text{device}}$ device is primary production ($\text{mgC m}^{-3} \text{ h}^{-1}$) calculated using the $\dot{E}(\text{PAR}, z, t)$
 255 from the transmittances measured from a specific device (ROV, $P_{\text{underice}}^{\text{ROV}}$ or SUIT, $P_{\text{underice}}^{\text{SUIT}}$),
 256 P is the photosynthetic rate ($\text{mgC m}^{-3} \text{ h}^{-1}$) at light saturation, α is the photosynthetic effi-
 257 ciency at irradiance close zero ($\text{mgC m}^{-3} \text{ h}^{-1} (\mu\text{mol photon m}^{-2} \text{ s}^{-1})^{-1}$), β is a photoinhibition
 258 parameter (same unit as α). The superscript *device* can be either ROV or SUIT. While fits
 259 allowed a variable intercept (P_0), which tended to be positive, we did not use P_0 in the
 260 primary production computations as we assumed that it was due to methodological issues
 261 (e.g., light absorbed before incubation started). Photosynthetic parameters were linearly
 262 interpolated between 0 and 40 m depth by 1 m increment. Daily primary production
 263 ($\text{mgC m}^{-3} \text{ h}^{-1}$) at each depth was calculated by integrating $P_{\text{underice}}^{\text{device}}(z, t)$ over a 24h period.
 264 Depth-integrated primary production ($\text{mgC m}^{-2} \text{ d}^{-1}$) was then calculated by integrating
 265 daily primary production over the first 40 m of the water column. This depth was chosen
 266 because it roughly coincides with the depth of the euphotic zone.

267 *Method 2: average production under ice and adjacent open waters* - The second ap-
 268 proach consisted of using a mixing model based on sea ice concentration (SIC) derived from
 269 satellite imagery to upscale at a larger spatial scale the estimates of primary production
 270 derived from the ROV and the SUIT. This approach was motivated by the fact that, even
 271 far away from the marginal ice zone, there were often large leads that increased the amount
 272 of light available to drifting phytoplankton and may have contributed to under-ice blooms in
 273 the vicinity as observed by Assmy et al. (2017). To account for this additional light source
 274 available for phytoplankton, primary production was calculated as follows:

$$275 \quad P_{\text{mixing}}^{\text{device}} = \text{SIC} \times P_{\text{underice}}^{\text{device}} + (1 - \text{SIC}) \times P_{\text{openwater}} \quad (7)$$

276 where $P_{\text{mixing}}^{\text{device}}$ is the primary production calculated using the mixing model approach
 277 with the transmittance values from a specific device, SIC is the sea ice concentration aver-
 278 aged over an area of $\approx 350 \text{ km}^2$ (the mean of a 9-pixels square with the station within
 279 the center pixel). $P_{\text{underice}}^{\text{device}}$ is the primary production calculated under ice using transmittance
 280 measurements (equation 6 & method 1 above) and $P_{\text{openwater}}$ the primary production
 281 calculated in open water by using a transmittance of 100%. For the mixing-model based
 282 SUIT-derived primary production, $P_{\text{mixing}}^{\text{SUIT}}$, transmittance observations higher than 10%
 283 were discarded to remove measurements made under very thin ice and in open leads to
 284 avoid accounting twice for open water. In the end, four types of primary production were
 285 considered (2 devices \times 2 approaches, Table 2).

286 2.7 Error on primary production estimates

287 For each of the four scenarios ($P_{\text{mixing}}^{\text{SUIT}}$, $P_{\text{mixing}}^{\text{ROV}}$, $P_{\text{underice}}^{\text{SUIT}}$, $P_{\text{underice}}^{\text{ROV}}$), the average primary
 288 production derived from all the transmittance values was viewed as an adequate description
 289 of the average primary production produced by drifting phytoplankton cells for a given
 290 area. The relative deviation of each individual primary production estimate to the average
 291 primary production over all stations was viewed as the error that one would make when
 292 measuring light at a single location. This relative error was calculated as follows:

$$293 \quad \delta_P^{\text{device}} = \frac{|P^{\text{device}} - \bar{P}^{\text{device}}|}{\bar{P}^{\text{device}}} \times 100 \quad (8)$$

294 where δ_P^{device} is the relative error (%) associated to a specific device (ROV or SUIT),
 295 P^{device} the primary production estimate and \bar{P}^{device} the average primary production of the
 296 device (both in $\text{mgC m}^{-2} \text{ d}^{-1}$).

2.8 Impacts of the number of in situ single-location light measurements on primary production estimates

Because of the sea surface heterogeneity in the field, one needs to carefully choose the number of single-location light measurements in order to obtain representative values of primary production over a given area. Averaging a high number of local measurements is likely to give a better approximation of the average primary production over a given area. However, in the Arctic, it is difficult to sample a high number of uniformly dispersed sampling locations due to logistical constraints. Using primary production estimates derived from the ROV and the SUIT, we calculated how the error would decrease on average when increasing the number of measurements uniformly sampled over a given area. To calculate this error, between 1 and 250 values were randomly drawn from the full distribution of primary production values calculated with individual transmittance data from the ROV or SUIT, and used to calculate average primary production. One can view each of these 250 numerical experiments as possible number of single-location irradiance measurements that one would perform in the field. Each numerical experiment was repeated 100 times to calculate an average and the standard deviation of the absolute difference between a given estimate of primary production and the reference primary production calculated with all transmittance measurements.

2.9 Statistical analysis

All statistical analysis and graphics were carried out with R 3.6.0 (R Core Team, 2019). The non-linear fitting for the P vs. E curves was done using the Levenberg-Marquardt algorithm implemented in the `minpack.lm` R package (Elzhov, Mullen, Spiess, & Bolker, 2013). The code used in this study is available under the GNU GPLv3 licence (<https://github.com/PMassicotte/transsiz>).

3 Results

3.1 Characterization of the sea-ice and snow cover

GEM-2 and Magna Probe surveys along and across the ROV transects showed distinct differences in sea ice and snow thickness between the sampled stations. An overview of the total thickness (i.e., combined snow and ice thickness) is presented in Figure 2A. Overall, the mean ice thickness was 1.01 ± 0.52 m (mean \pm s.d.), the mean snow thickness was 0.32 ± 0.16 m and the mean total thickness was 1.33 ± 0.49 m (Figure 2B). Stations 19 and 47 were characterized by an average total thickness over the ROV transect of approximately 1 m, whereas the average total thickness at station 39 was approximately 2 m. For other stations, average total thickness varied around 1.4 m.

3.2 ROV and SUIT transmittance measurements

A total of 9211 and 817 transmittance measurements distributed over the seven stations were collected from the ROV and SUIT devices, respectively (Figure 3). Transmittance values ranged between 0.001% and 68% for the ROV and between 0.002% and 92% for the SUIT (Figure 3). The transmittances measured by the SUIT were generally higher (mean = 35%) by approximately one order magnitude than those measured with the ROV (mean = 2%). The SUIT measurements were also covering greater ranges of transmittances compared to the ROV. Histograms showed that transmittance generally followed a bimodal distribution (most of the time occurring within the SUIT data) with often one overlapping mode between the ROV and SUIT values (Figure 3).

3.3 Photosynthetically active radiation (PAR)

Incident hourly $\dot{E}(\text{PAR})$, $\dot{E}(\text{PAR}, 0^+, t)$, measured by the pyranometer ranged between 190 and 1400 $\mu\text{mol m}^{-2} \text{s}^{-1}$ (Figure 4). Stations 32 and 39 experienced the highest incident $\dot{E}(\text{PAR}, 0^+, t)$ whereas stations 27 and 43 received the lowest amount of light. Over 24h periods, $\dot{E}(\text{PAR}, z_{\text{int}})$ calculated using SUIT and ROV transmittances ranged between 0.005-1358 and 0.005-1012 $\mu\text{mol m}^{-2} \text{s}^{-1}$ respectively. Due to relatively high attenuation coefficients (Table 1), $\dot{E}(\text{PAR})$ decreased rapidly with depth and generally reached the asymptotic regime at maximum 30 m depth. The PAR diffuse vertical attenuation coefficients, $K_{E_d}^{\circ}(\text{PAR})$, estimated from the ROV vertical profiles varied between 0.07 and 0.59 m^{-1} (Table 1).

3.4 Estimated primary production

Daily areal primary production derived from photosynthetic parameters and transmittance values ranged between 0.004 and 939 $\text{mgC m}^{-2} \text{d}^{-1}$ for P_{underice} and between 0.004 and 731 $\text{mgC m}^{-2} \text{d}^{-1}$ for P_{mixing} (Figure 5). In ROV-based estimates, daily areal primary production calculated using the two different approaches (P_{underice} and P_{mixing}) generally showed consistency especially when SIC was high. At stations 19 and 27, greater differences between P_{underice} and P_{mixing} were observed in ROV-based estimates due to lower sea ice concentrations (Table 1) which allowed for a greater weight of $P_{\text{openwater}}$ on the calculations. In SUIT-based estimates, mean daily P_{underice} values were higher than P_{mixing} values at stations 19, 39 and 43, similar at stations 27, 46 and 47, and lower at station 31 (Figure 5). The 10% transmittance threshold used to filter out SUIT-based data explains why mean values of daily P_{underice} can be lower than those of based on ROV measurements. The differences between the two approaches in SUIT data were related to the varying proportions of thin ice and open water during SUIT hauls, which were reflected in the P_{underice} estimates. Overall, both ROV- and SUIT based estimates agreed well with each other when the mixing approach (P_{mixing}) was applied.

3.5 Error on primary production estimates

Figure 6 shows the distributions of the relative errors around the calculated average of areal primary production (see black dots in Figure 5). Overall, the absolute relative errors (δ_P) were distributed over a range covering four orders of magnitude, between 0.1% and 1000% which corresponds to an absolute primary production error varying between 0.0001 and 640 $\text{mgC m}^{-2} \text{d}^{-1}$. The lowest absolute errors (average $\approx 50\%$) were associated with primary production estimates made using the mixing model approach (P_{mixing}). Larger absolute errors were made with P_{underice} derived from only using ROV (mean = 88%) and the SUIT (mean = 71%) transmittances.

3.6 Impacts of the number of in situ light measurements on primary production estimates

Figure 7 shows the average relative error that one would make when averaging light measurements performed at a number of random locations varying between 1 and 250. The variability around the means also decreased with increasing number of observations (shaded areas in Figure 7). The greatest relative mean error ($\approx 60\text{-}100\%$) occurred when only one primary production estimate was randomly selected from the distributions. The number of randomly selected observations to reach mean relative errors of 10%, 15%, 20% and 25% are presented in Table 3. Overall, about 25% the number of observations were needed to reach those targets when sampling from the distribution for P_{mixing} compared to the distribution of P_{underice} . Additionally, the number of observations required when using the SUIT transmittance to derive primary production estimation was also about 25% of the number of corresponding ROV-based measurements to reach the same error threshold.

4 Discussion

4.1 Primary production under heterogeneous sea ice

Vertically-integrated net primary production in the Arctic is known to be highly variable in both time and space (Hill, Ardyna, Lee, & Varela, 2018; Matrai et al., 2013). For example, primary production in the central Arctic Ocean estimated using photosynthetic parameters was found to vary between 18 and 308 mgC m⁻² d⁻¹ in ice-free waters, and between 0.1 and 232 mgC m⁻² d⁻¹ in ice-covered waters (Fernández-Méndez et al., 2015). Our primary production estimates generally fall within these ranges, although our highest values (731 - 939 mgC m⁻² d⁻¹) are roughly twice as high. There are many factors such as season, cloudiness, sea ice and snow, nutrient concentration, temperature and phytoplankton community composition that can influence such variability. In a modeling exercise, Popova et al. (2010) found that shortwave light radiation and the maximum depth of winter mixing (which determine the amount of nutrients available for summer primary production) explained more than 80% of the spatial variability of primary production in the Arctic. In our approach, the impact of light history, nutrients, temperature, and community composition are implicit in photosynthetic parameters and chl a concentration obtained in this study. The instantaneous effect of light variations is explicit and the main focus of this study.

4.2 Multi-scale spatial variability of light transmittance

In the context of obtaining meaningful measurements of transmittance to accurately estimate E0(PAR, 0-), one challenge is to define the spatial extent at which light should be sampled. Based on a spatial autocorrelation analysis conducted in the central Arctic ocean, it was determined that transmittance values were uncorrelated (i.e., randomly spatially distributed) to each other after a horizontal lag distance of 65 m (Lange, Katlein, et al., 2017). This range is much smaller than the distance covered by drifting phytoplankton over a 24h period. Water currents around Svalbard have been found to vary between 0.14 and 0.21 m s⁻¹ at this time of the year (Meyer et al., 2017). Such speeds are in the same order of magnitude as the average sea ice drift speeds of 0.10 m s⁻¹ observed during the expedition. On daily timescales, ice-motion is generally decoupled from Ocean currents and is rather driven by inertial oscillations and wind stress (Park & Stewart, 2016). This corresponds to a relative ice-water displacement varying between 3.5 and 18 km over a 24h period which is much greater than the scale of the spatial variability of transmittance, as well as the scale of most typical ice floes in this area. Under such a large area, drifting phytoplankton is experiencing a wide range of irradiance conditions that can be hardly characterized by a single-location light measurement. Our results showed that at medium spatial scales, the ROV and the SUIT are able to characterize the local sea-ice variability on the scale of one or a few individual ice floes. However, these technologies do not adequately capture the spatial variability that originate from larger scale features such as open water areas nor large leads that can increase the amount of light available to drifting phytoplankton (Assmy et al., 2017). Thus at larger spatial scales, satellite-derived information, such as SIC or lead cover products can provide important information on the panarctic context. Such information allows to upscale the estimates of primary production derived from the ROV and the SUIT to a larger spatial scale. Our results showed that using a simple mixing model (equation 7), combining both in-situ transmittance measurements and SIC, can be used to upscale observations acquired “locally” to larger scales. This approach reduced the relative error by approximately a factor of two when spatially integrating devices such as ROVs or SUIT are used to measure transmittance (Figure 5). Furthermore, this error was lower when using in-situ measurements acquired on a larger spatial scale using the SUIT. This strengthens the idea that one needs to characterize the light field over an area as large as reasonably possible so the true irradiance variability is captured.

Our study confirms our earlier hypothesis that estimating primary production from photosynthetic parameters and transmittance measured at a single location does not provide

440 a representative description of the spatial variability of the primary production occurring
 441 under a heterogeneous sea surface (Figure 6, Figure 7). Depending on the scale at which
 442 transmittance was measured, it was found that deriving primary production from photo-
 443 synthetic parameters using under-ice profile measurements alone would produce on average
 444 relative errors varying between 47% and 88% (Figure 6). In contrast, much lower errors
 445 (25%) were made when primary production estimates were upscaled using satellite-derived
 446 SIC (P_{mixing}). For stations with lower SIC (stations 19, 27, 31 and 39), primary production
 447 estimates were more constrained around the average (Figure 4) because $P_{\text{openwater}}$ had a
 448 greater weight in the calculation of P_{mixing} (see equation 7). For stations 43, 46 and 47
 449 where SIC was 100%, the spread around the mean was higher because only P_{underice} was
 450 contributing to the calculation of P_{mixing} . These results suggest that using a distribution
 451 of measured transmittances allows calculating a more representative transmittance average
 452 for a given area, but also provides additional knowledge on its spatial variability.

453 Although our results indicate that it is necessary to properly characterize the light field
 454 under the heterogeneous sea surface, the physiological state of the phytoplankton community
 455 under the sea ice surface also plays a major role on the sensitivity of the estimates to in-
 456 coming irradiance. An important parameter of the physiological state of the phytoplankton
 457 community is the light-saturated photosynthesis regime, E_k an index of photoadaptation.
 458 If a phytoplankton community was adapted to extremely low light intensity, as example,
 459 variations in the surface light field would have reduced impacts on the estimates because
 460 phytoplankton primary production might be systematically light-saturated. In this study,
 461 the average E_k was 65.2 ± 55.3 (range = 18.0 - 409.5) $\mu\text{mol m}^{-2} \text{s}^{-1}$, whereas the average of
 462 all estimates of mean daily, under-ice irradiance made from ROV and SUIT measurements
 463 was 12.6 ± 7.6 (range = 3.0 - 26.4) $\mu\text{mol m}^{-2} \text{s}^{-1}$. Since the latter were generally much lower
 464 than E_k , phytoplankton were able to respond strongly to variability in the under-ice light
 465 field and take advantage of increased irradiance in occasional leads. This setting underscores
 466 the importance of taking into account a mixture of sea ice cover and open water, for the
 467 estimation of primary production. However, the seasonal degree of photoadaptation of the
 468 phytoplankton communities and their ability to adjust rapidly to a variable light field still
 469 remains to be evaluated.

470 **4.3 Influence of the number of sampling locations on primary production** 471 **estimation**

472 As with any scientific expedition in remote environments such as the Arctic, careful
 473 planning is needed to find the right balance between the sampling effort and the sufficient
 474 amount of acquired information to study a particular phenomenon. Our results suggested
 475 that errors made by estimating primary production using photosynthetic parameters de-
 476 creased exponentially with increasing number of transmittance measurements (Figure 7).
 477 Depending on the extent of the spatial scale at which transmittance is measured (order of
 478 meters for the ROV, order of kilometers for the SUIT) and the targeted error thresholds
 479 (10%, 15%, 20% or 25%), a number of light measurements varying between four and 359
 480 were sufficient to reasonably capture the spatial variability of sea ice transmittance to de-
 481 rive average primary production estimates over a given area. This shows, that local primary
 482 production estimated from just a single or even a handful of light observations has limited
 483 value. However, further seasonal and regional studies are needed to fully capture the vari-
 484 ability of photosynthetic parameters, which are not fully accounted for within the primary
 485 production derived from the presented spring study.

486 **4.4 Implications for Arctic primary production estimates**

487 It is known that the annual primary production in the ice-covered Arctic is among
 488 the lowest of all oceans worldwide, because both light and limited nutrient availability are
 489 the main constraining factors for phytoplankton growth under the ice. In a changing Arc-
 490 tic icescape, efforts have been devoted to better understand how phytoplankton primary

491 production is responding to increasing light availability (Fernández-Méndez et al., 2015;
 492 Vancoppenolle et al., 2013). Many studies have been conducted in the vicinity of an ice
 493 edge to characterize primary production occurring under the ice sheet (Arrigo et al., 2012,
 494 2014; Mundy et al., 2009). However, in such studies, due to logistical constraints, the under-
 495 water light field was often characterized by a limited number of light measurements. Other
 496 approaches, based on 24h ship-board incubations performed under incident light, have pro-
 497 vided local estimates that were simply scaled to an assessment of percent ice-cover in the
 498 vicinity of the ship (Gosselin, Levasseur, Wheeler, Horner, & Booth, 1997; Mei et al., 2003;
 499 Smith, 1995). Therefore, depending on whether light is measured under bare ice or in open
 500 water, the estimated primary production is either under- or overestimated. Different ap-
 501 proaches based on remote sensing techniques and modelling have been used to reduce the
 502 uncertainties associated with estimates derived from local in-situ measurements. However,
 503 in an ecosystem model intercomparison study, Jin et al. (2016) showed that under-ice pri-
 504 mary production was very sensitive to the light availability computed by atmospheric and
 505 sea ice models, reinforcing the need to develop new integrative strategies to adequately char-
 506 acterize the light field at large scale under heterogeneous sea ice surfaces. Our results show
 507 that upscaling primary production estimates derived from fine-scale local measurements us-
 508 ing SIC derived from satellite imagery allowed reducing the error at larger spatial scales.
 509 Furthermore, it was found that even when SIC was high ($> 95\%$), the use of a mixing-model
 510 approach helped to obtain better estimates (Figure 5).

511 Based on our results, different strategies can be easily adopted to obtain the best possi-
 512 ble estimates of primary production under spatially heterogeneous sea ice surfaces. Firstly,
 513 one should acquire a sufficient number of P vs. E curves under different nutrient conditions
 514 that are representative for the region under investigation. Secondly, one should measure
 515 light transmittance or irradiance at a spatial scale fine enough to capture the horizontal
 516 variability that is meaningful for the studied process. The number of measurements should
 517 be chosen as a function of the sampling method and a reasonable degree of error (Figure 7,
 518 Table 3). Nowadays, this can be relatively easily achieved using ROV, SUIT or autonomous
 519 underwater vehicles (AUV). Secondly, under heterogeneous sea ice surface, one should use
 520 extinction coefficients derived from upward radiance (L_u) measurements to propagate PAR
 521 in the water column because it is less influenced by the geometric effects of sea ice surface
 522 compared to downward irradiance (Katlén et al., 2016; Massicotte et al., 2018). Finally,
 523 local measurements can be upscaled at higher spatial scale using remote-sensing data such
 524 as sea-ice concentration.

525 5 Conclusions

526 Advances in underwater technologies have made it easier to characterize surface trans-
 527 mittance over large areas even under dense sea ice. Our results show that combining pho-
 528 tosynthetic parameters measured in laboratory experiments with spatially representative
 529 transmittance values sampled with under-ice profiling platforms can significantly improve
 530 the accuracy of primary production estimates under heterogeneous sea surfaces. A good way
 531 forward to sample the under-ice light field on a large enough scale without the inherent biases
 532 of the ROV and SUIT deployment techniques would be the use of long-range autonomous
 533 underwater vehicles. Furthermore, upscaling in-situ measurements at larger scales using
 534 remote sensing data becomes necessary when the spatial scale of the studied process (e.g., a
 535 phytoplankton bloom) is greater than that which is realistically possible to measure in the
 536 field. This emphasizes the need for spatially integrated observation approaches to charac-
 537 terize the light field in ice-covered regions in order to provide more representative primary
 538 production estimates for the Arctic.

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564 6 Figures captions

Figure 1. Locations of the ice stations sampled during the Transsiz expedition north of Svalbard. The dots reflect the drift of the ship while anchored to an ice floe.

Figure 2. (A) Spatial overview of the total thickness (snow + ice) at each station. (B) Boxplots showing the variability and the contribution of the snow and the ice to the total thickness. Note that only total thickness is available at stations 46 and 47 due to instrument failure.

Figure 3. Density plots showing the distribution of transmittance values measured by the ROV and the SUIT devices. Dashed lines represent the 10% transmittance threshold used to filter out SUIT transmittance used in the mixing models. Numbers on top of the gray boxes identify the stations. Top-left numbers in each facet show the number of observations.

Figure 4. Incident hourly photosynthetic active radiation, $\overset{\circ}{E}(\text{PAR}, 0^+, t)$, measured at each station with a pyranometer installed onboard the ship. Numbers on top of the gray boxes identify the stations.

Figure 5. Violin plots of primary production calculated from ROV and SUIIT transmittance data. For SUIIT data, mixing models were calculated using only transmittance $\leq 10\%$ (see Figure 3) whereas the under ice models were calculated using all transmittance data. Black dots inside the violin plots indicate the average primary production. Numbers on top of the gray boxes identify the stations and satellite-derived sea ice concentrations.

Figure 6. Distributions of the relative errors corresponding to the absolute deviation of each individual primary estimations from the average (see equation 7 for details). The red dashed lines and the numbers on the left indicate the mean errors.

Figure 7. Average relative errors based on the number of single-spot measurements that one would make when averaging samples randomly sampled over a given area (black dots). The shaded gray areas represent the standard deviation around the mean. The means and standard deviations were calculated from 100 randomly chosen replicates.

7 Tables

Station	Date	Latitude (N)	Longitude (E)	Water depth (m)	Snow thickness (m)	SIC (%)	$K_d(PAR)$ (m^{-1})
19	2015-05-28	81.17	19.13	-377	0.20	71	0.59
27	2015-05-31	81.39	17.59	-876	0.27	96	0.25
31	2015-06-03	81.62	19.43	-1963	0.36	97	0.22
39	2015-06-11	81.92	13.46	-1589	0.18	99	0.15
43	2015-06-15	82.21	7.59	-804	0.20	100	0.14
46	2015-06-17	81.89	9.73	-906	0.10	100	0.07
47	2015-06-19	81.35	13.61	-2171	0.14	100	0.17

Table 1. Physical characteristics of the seven stations sampled during the TRANSSIZ campaign of 2015.

Symbol	Description
$P_{\text{openwater}}$	Primary production estimated using 100% transmittance.
$P_{\text{underice}}^{\text{ROV}}$	Primary production estimated using underice transmittance values measured by the ROV.
$P_{\text{mixing}}^{\text{ROV}}$	Primary production estimated using a mixing model approach combining underice transmittance values measured by the ROV and satellite-derived SIC.
$P_{\text{underice}}^{\text{SUIT}}$	Primary production estimated using underice transmittance values measured by the SUIT.
$P_{\text{underice}}^{\text{SUIT}}$	Primary production estimated using a mixing model approach combining underice transmittance values measured by the SUIT and satellite-derived SIC.

Table 2. Descriptions of the symbols used to identify the four types of primary production modeled in this study.

Model	Relative error threshold			
	10%	15%	20%	25%
$PP_{\text{mixing}}^{\text{ROV}}$	99	46	26	16
$PP_{\text{underice}}^{\text{ROV}}$	359	166	90	60
$PP_{\text{mixing}}^{\text{SUIT}}$	27	13	7	5
$PP_{\text{underice}}^{\text{SUIT}}$	86	40	23	15

Table 3. Number of measurements needed to reach various relative error thresholds.

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