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# *Article* **Generalized Neutrosophic Soft Expert Set for Multiple-Criteria Decision-Making**

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**Abstract:** Smarandache defined a neutrosophic set to handle problems involving incompleteness, indeterminacy, and awareness of inconsistency knowledge, and have further developed it neutrosophic soft expert sets. In this paper, this concept is further expanded to generalized neutrosophic soft expert set (GNSES). We then define its basic operations of complement, union, intersection, AND, OR, and study some related properties, with supporting proofs. Subsequently, we define a GNSES-aggregation operator to construct an algorithm for a GNSES decision-making method, which allows for a more efficient decision process. Finally, we apply the algorithm to a decision-making problem, to illustrate the effectiveness and practicality of the proposed concept. A comparative analysis with existing methods is done and the result affirms the flexibility and precision of our proposed method.

**Keywords:** aggregation operator; complement; intersection; membership; neutrosophic soft set

### **1. Introduction**

For a proper description of objects in an uncertain and ambiguous environment, indeterminate and incomplete information has to be properly handled. Intuitionistic fuzzy sets were introduced by Atanassov [\[1\]](#page-16-0), followed by Molodtsov on soft sets [\[2\]](#page-16-1) and neutrosophy logic [\[3\]](#page-16-2) and neutrosophic sets [\[4\]](#page-16-3) were introduced by Smarandache. The term neutro-sophy means knowledge of neutral thought and this neutral represents the main distinction between fuzzy and intuitionistic fuzzy logic and a set. At present, work on the soft set theory is progressing rapidly. Various operations and applications of soft sets have been developed rapidly, including the possibility of fuzzy soft set [\[5\]](#page-16-4), soft multiset theory [\[6\]](#page-16-5), multiparameterized soft set [\[7\]](#page-16-6), soft intuitionistic fuzzy sets [\[8\]](#page-16-7), Q-fuzzy soft sets [\[9–](#page-16-8)[11\]](#page-16-9), multi Q-fuzzy sets [\[12–](#page-16-10)[14\]](#page-16-11), N-soft set [\[15\]](#page-16-12), Hesitant N-soft set [\[16\]](#page-16-13), and Fuzzy N-soft set [\[17\]](#page-16-14), thereby, opening avenues to genetic applications [\[18](#page-16-15)[,19\]](#page-16-16). Later, Maji [\[20\]](#page-16-17) have introduced a more generalized concept—which is a combination of neutrosophic sets and soft sets—and have studied its properties. Alhazaymeh and Hassan [\[21,](#page-16-18)[22\]](#page-16-19) have studied the concept of vague soft set, which were later extended to vague soft expert set theory [\[23](#page-16-20)[,24\]](#page-16-21), bipolar fuzzy soft expert set [\[25\]](#page-16-22), and multi Q-fuzzy soft expert set [\[26\]](#page-16-23). ¸Sahin et al. [\[27\]](#page-16-24) introduced neutrosophic soft expert sets, while Al-Quran and Hassan [\[28](#page-17-0)[,29\]](#page-17-1) extended it further to neutrosophic vague soft expert set. Neutrosophic set theory has also been applied to multiple attribute decision-making [\[30](#page-17-2)[–32\]](#page-17-3). Fuzzy modelling has long been widely applied to physical problems, which include intuitionistic hesitant fuzzy [\[33\]](#page-17-4), t-concept lattices [\[34\]](#page-17-5), fuzzy operators [\[35\]](#page-17-6), medical image retrieval [\[36\]](#page-17-7), and artificial bee colony [\[37\]](#page-17-8) and multi criteria decision making [\[38](#page-17-9)[,39\]](#page-17-10). Neutrosophic sets have also gained traction with recent publications on neutrosophic triplets [\[40](#page-17-11)[,41\]](#page-17-12), Q-neutrosophic soft relations [\[42\]](#page-17-13), Q-neutrosophic soft sets [\[43\]](#page-17-14), and Q-neutrosophic soft expert set [\[44\]](#page-17-15).

This paper anticipates the neutrosophic set discussions to handle problems involving incompleteness, indeterminacy, and awareness of inconsistency of knowledge, which is further developed to neutrosophic soft expert sets. We intend to extend the discussion further, by proposing the concept of generalized neutrosophic soft expert set (GNSES) and its basic operations of complement, union, intersection, AND, and OR, along with a definition of GNSES-aggregation operator, to construct an algorithm of a GNSES decision method. Finally we provide an application of the constructed algorithm to solve a decision-making problem.

#### **2. Preliminaries**

In this section, we review the basic definitions of a neutrosophic set, neutrosophic soft set, soft expert sets, neutrosophic soft expert sets, and neutrosophic parametrized (NP)-aggregation operator, which are required as preliminaries.

**Definition 1.** *[\[4\]](#page-16-3) Let U be a universe of discourse, with a generic element in U denoted by u, then a neutrosophic (NS) set A is an object having the form*

$$
A = \{ < u : T_A(u), I_A(u), F_A(u) > u \in U \}
$$

*where the functions T, I, F: U*→ *]* <sup>−</sup>*0, 1<sup>+</sup> [ define, respectively, the degree of membership (or Truth), the degree of indeterminacy, and the degree of non-membership (or Falsehood) of the element*  $u \in U$  *to the set A with the condition.*

$$
^{-0} \leq T_A(u) + I_A(u) + F_A(u) \leq 3^+
$$

**Definition 2.** [\[20\]](#page-16-17) Let *U* be an initial universe set and *E* be a set of parameters. Consider  $A \subseteq E$ . Let  $NS(U)$ *denote the set of all neutrosophic sets of U. The collection* (*F*, *A*) *is termed to be the neutrosophic soft set over U, where F is a mapping given by*  $F : A \rightarrow NS(U)$ .

**Definition 3.** *[\[23\]](#page-16-20) U is an initial universe, E is a set of parameters, X is a set of experts (agents), and*  $O = \{agree = 1, disagree = 0\}$  *a* set of opinions. Let  $Z = E \times X \times O$  and  $A \subseteq Z$ . A pair  $(F, A)$  is called a *soft expert set over U*, where *F is a mapping given by*  $F : A \rightarrow P(U)$  *where*  $P(U)$  *denoted the power set of U*.

**Definition 4.** *[\[27\]](#page-16-24) A pair* (*F*, *A*) *is called a neutrosophic soft expert set over U, where F is a mapping given by*  $F: A \rightarrow P(U)$  *where*  $P(U)$  *denotes the power neutrosophic set of U.* 

**Definition 5.** [\[27\]](#page-16-24) The complement of a neutrosophic soft expert set  $(F, A)$  is denoted by  $(F, A)^c$ , and is defined as  $(F, A)^c = (F^c, \neg A)$  where  $F^c = \neg A \rightarrow P(U)$  is a mapping given by  $F^c(x)$  = neutrosophic soft expert complement with  $T_{F^c(x)} = F_{F(x)}$ ,  $I_{F^c(x)} = I_{F(x)}$ ,  $F_{F^c(x)} = T_{F(x)}$ .

**Definition 6.** [\[27\]](#page-16-24) The agree-neutrosophic soft expert set  $(F, A)_1$  over  $U$  is a neutrosophic soft expert subset of (*F*, *A*) defined as

$$
(F, A)_1 = \{F_1(m) : m \in E \times X \times \{1\}\}.
$$

**Definition 7.** [\[27\]](#page-16-24) The disagree-neutrosophic soft expert set  $(F, A)_0$  over U is a neutrosophic soft expert subset *of* (*F*, *A*), defined as

$$
(F, A)_0 = \{F_0(m) : m \in E \times X \times \{0\}\}.
$$

**Definition 8.** *[\[27\]](#page-16-24) Let* (*H*, *A*) *and* (*G*, *B*) *be two neutrosophic soft expert sets (NSESs) over the common universe U. Then the union of*  $(H, A)$  *and*  $(G, B)$  *is denoted by*  $\H(H, A) \cup \H(G, B)$ ", and is defined by

 $(H, A)$   $\stackrel{\sim}{\cup}$   $(G, B)$  =  $(K, C)$ , where  $C = A ∪ B$  and the truth-membership, indeterminacy-membership, *and falsity-membership of* (*K*, *C*) *are as follows:*

$$
T_{K(e)}(m) = \begin{cases} T_{H(e)}(m), & if e \in A - B \\ T_{G(e)}(m), & if e \in B - A \end{cases}
$$

$$
I_{K(e)}(m) = \begin{cases} I_{H(e)}(m), & if e \in A - B \\ T_{H(e)}(m), T_{G(e)}(m)), & if e \in A \cap B \end{cases}
$$

$$
I_{K(e)}(m) = \begin{cases} I_{H(e)}(m), & if e \in B - A \\ T_{H(e)}(m), & if e \in A \cap B \end{cases}
$$

$$
F_{K(e)}(m) = \begin{cases} F_{H(e)}(m), & if e \in A - B \\ F_{G(e)}(m), & if e \in B - A \end{cases}
$$

$$
F_{G(e)}(m), & if e \in B - A \end{cases}
$$

$$
min(F_{H(e)}(m), F_{G(e)}(m)), if e \in A \cap B
$$

**Definition 9.** *[\[27\]](#page-16-24) Let* (*H*, *A*) *and* (*G*, *B*) *be two NSESs over the common universe U. Then the intersection* of  $(H, A)$  and  $(G, B)$  is denoted by " $(H, A) \cap (G, B)$ " and is defined by  $(H, A) \cap (G, B) = (K, C)$ , where *C* = *A* ∩ *B and the truth-membership, indeterminacy-membership, and falsity-membership of* (*K*, *C*) *are as follows:*  $\Delta$ 

$$
T_{K(e)}(m) = \min\left(T_{H(e)}(m), T_{G(e)}(m)\right)
$$

$$
I_{K(e)}(m) = \frac{I_{H(e)}(m) + I_{G(e)}(m)}{2}
$$

$$
F_{K(e)}(m) = \max\left(F_{H(e)}(m), F_{G(e)}(m)\right), \text{ if } e \in A \cap B.
$$

**Definition 10.** [\[45\]](#page-17-16) Let  $\Psi_K \in NP$ -soft set. Then an NP-aggregation operator of  $\Psi_K$ , denoted by  $\Psi_K^{agg}$  $_K^{u_{\delta\delta}}$ , is *defined by*

$$
\Psi_K^{agg} = \left\{ \left( \langle u, \mu_K^{agg}, \vartheta_K^{agg}, \omega_K^{agg} \rangle \right) : u \in U \right\},\tag{1}
$$

*which is a neutrosophic set over U,*

$$
\mu_K^{agg}(u) = \frac{1}{|U|} \sum_{e \in E} \mu_K(u) \cdot \lambda f_{K(x)}(u), \mu_K^{agg}: U \to [0, 1]
$$
  
  $u \in U$  (2)

$$
\theta_K^{agg}(u) = \frac{1}{|U|} \sum_{e \in E} \theta_K(u) \Lambda f_{K(x)}(u), \theta_K^{agg}: U \to [0, 1]
$$
\n
$$
u \in U
$$
\n(3)

$$
\omega_K^{agg} = \frac{1}{|U|} \sum_{e \in E} \omega_K(u). \lambda f_{K(x)}(u), \omega_K^{agg}: U \to [0, 1]
$$
  
  $u \in U$  (4)

*and where,*

$$
\lambda f_{K(x)}(u) = \begin{cases} 1, & x \in f_{K(x)}(u), \\ 0, & \text{otherwise,} \end{cases}
$$

*such that* |*U*| *is the cardinality of U*.

#### **3. Generalized Neutrosophic Soft Expert Set**

In this section, we introduce the concept of generalized neutrosophic soft expert set (GNSES) and define some of its properties. Throughout this paper, *U* is an initial universe, *E* is a set of parameters, *X* is a set of experts (agents), and  $O = \{$ agree = 1, disagree = 0 $\}$  a set of opinions. Let  $Z = E \times X \times O$ and *A*  $\subseteq$  *Z* and *u* is a fuzzy set of *A*; that is, *u* : *A*  $\rightarrow$  = [0, 1].

**Definition 11.** A pair  $(F^u, A)$  is called a generalized neutrosophic soft expert set (GNSES) over U, where  $F^u$  is *a mapping given by*

$$
F^u: A \to \mathcal{N}(U) \times
$$

*with*  $\mathcal{N}(U)$  *being the set of all neutrosophic soft expert subsets of U. For any parameter*  $e \in A$ ,  $F(e)$  *is referred as the neutrosophic value set of parameter e, i.e.,*

$$
F(e) = \left\{ \langle u/T_{F(e)}(u), F_{F(e)}(u), F_{F(e)}(u) \rangle \right\},\
$$

*where T*, , *F* : *U* →*]* <sup>−</sup>*0, 1<sup>+</sup> [ are the membership function of truth, indeterminacy, and falsity, respectively, of the element*  $u \in U$ *. For any*  $u \in U$  *and*  $e \in A$ 

$$
-0 \leq T_{F(e)}(u) +_{F(e)} (u) + F_{F(e)}(u) \leq 3^+
$$

In fact,  $F^{\mu}$  is a parameterized family of neutrosophic soft expert sets on *U*, which has the degree of possibility of the approximate value set which is prepresented by *u*(*e*) for each parameter *e*, which can be written as follows:

$$
F^u(e) = \left\{ \left( \frac{u_1}{F(e)(u_1)}, \frac{u_2}{F(e)(u_2)}, \frac{u_3}{F(e)(u_3)}, \cdots, \frac{u_n}{F(e)(u_n)} \right), u(e) \right\}.
$$

**Example 1.** *Suppose that*  $U = \{u_1, u_2, u_3\}$  *is a set of computers and*  $E = \{e_1, e_2, e_3\}$  *is a set of decision parameters.* Let  $X = \{p, q, r\}$  be set of experts. Suppose that

$$
F^{u}(e_{1}, p, 1) = \begin{cases} \left(\frac{u_{1}}{0.4,0.3,0.2}, \frac{u_{2}}{0.5,0.1,0.8}, \frac{u_{3}}{0.5,0.7,0.1}, 0.3\right) \\ \left(\frac{u_{1}}{0.3,0.2,0.5}, \frac{u_{2}}{0.5,0.6,0.2}, \frac{u_{3}}{0.8,0.1,0.4}\right), 0.4\end{cases}
$$
  
\n
$$
F^{u}(e_{1}, r, 1) = \begin{cases} \left(\frac{u_{1}}{0.4,0.3}, \frac{u_{2}}{0.5,0.5,0.5}, \frac{u_{3}}{0.2,0.6,0.5}, 0.8\right) \\ \left(\frac{u_{1}}{0.8,0.4,0.3}, \frac{u_{2}}{0.7,0.3,0.5}, \frac{u_{3}}{0.2,0.6,0.5}\right), 0.8\end{cases}
$$
  
\n
$$
F^{u}(e_{2}, p, 1) = \begin{cases} \left(\frac{u_{1}}{0.4,0.1}, \frac{u_{2}}{0.5,0.1,0.4}, \frac{u_{3}}{0.8,0.6,0.3}, 0.2\right) \\ \left(\frac{u_{1}}{0.6,0.7,0.1}, \frac{u_{2}}{0.8,0.4,0.7}, \frac{u_{3}}{0.8,0.4,0.5}\right), 0.6\end{cases}
$$
  
\n
$$
F^{u}(e_{2}, r, 1) = \begin{cases} \left(\frac{u_{1}}{0.5,0.1,0.8}, \frac{u_{2}}{0.9,0.3,0.6}, \frac{u_{3}}{0.4,0.1,0.7}, 0.5\right) \\ \left(\frac{u_{1}}{0.5,0.1,0.8}, \frac{u_{2}}{0.9,0.3,0.6}, \frac{u_{3}}{0.4,0.1,0.7}\right), 0.5\end{cases}
$$
  
\n
$$
F^{u}(e_{3}, p, 1) = \begin{cases} \left(\frac{u_{1}}{0.4,0.1}, \frac{u_{2}}{0.2,0.5}, \frac{u_{3}}{0.4,0.1}, 0.7\right
$$

*The generalized neutrosophic soft expert set (GNSES) is a parameterized family*  $\{F(e_i), i = 1, 2, ...\}$  *of all neutrosophic sets of U and describes a collection of approximation of an object.*

**Definition 12.** Let  $(F^u, A)$  and  $(G^{\eta}, B)$  be two generalized neutrosophic soft expert sets (GNSESs) over U. *Then* (*F<sup>u</sup>*, *A*) *is said to be a generalized neutrosophic soft expert subset of* (*G<sup>n</sup>*, *B*) *if* 

*i. B* ⊆ *A, and*

*ii.*  $G^{\eta}(\varepsilon)$  *is a generalized neutrosophic soft expert subset*  $F^{\mu}(\varepsilon)$ *, for all*  $\varepsilon \in B$ *,* 

**Example 2.** *Consider Example 1. Suppose that A and B are as follows.*

 $A = \{(e_1, p, 1), (e_2, p, 1), (e_2, q, 0), (e_3, r, 1)\}$  $B = \{(e_1, p, 1), (e_2, p, 1), (e_3, r, 1)\}.$ 

*Since B is a neutrosophic soft expert subset of A, clearly*  $B \subset A$ *. Let*  $(G^{\eta}, B)$  *and*  $(F^{\mu}, A)$  *be defined as follows:*

$$
(F^{u}, A) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.4, 0.3, 0.2}, \frac{u_2}{0.6, 0.1, 0.8}, \frac{u_3}{0.5, 0.7, 0.2} \right), 0.3 \end{bmatrix} \begin{bmatrix} (e_2, p, 1), \left( \frac{u_1}{0.7, 0.3, 0.6}, \frac{u_2}{0.5, 0.1, 0.4}, \frac{u_3}{0.8, 0.6, 0.3} \right), 0.2 \end{bmatrix}, \begin{bmatrix} (e_2, q, 0), \left( \frac{u_1}{0.4, 0.3, 0.6}, \frac{u_2}{0.7, 0.2, 0.5}, \frac{u_3}{0.8, 0.1, 0.4} \right), 0.6 \end{bmatrix}, \begin{bmatrix} (e_3, r, 1), \left( \frac{u_1}{0.4, 0.3}, \frac{u_2}{0.5, 0.3, 0.6}, \frac{u_3}{0.1, 0.4, 0.2} \right), 0.5 \end{bmatrix} \right\}.
$$

$$
(G^{\eta}, B) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.4, 0.3}, \frac{u_2}{0.6, 0.1, 0.8}, \frac{u_3}{0.5, 0.7, 0.2} \right), 0.3 \end{bmatrix}, \begin{bmatrix} (e_2, p, 1), \left( \frac{u_1}{0.7, 0.3, 0.6}, \frac{u_2}{0.5, 0.1, 0.4}, \frac{u_3}{0.8, 0.6, 0.3} \right), 0.2 \end{bmatrix}, \begin{bmatrix} (e_3, r, 1), \left( \frac{u_1}{0.8, 0.4, 0.3}, \frac{u_2}{0.5, 0.3, 0.6}, \frac{u_3}{0.1, 0.4, 0.2} \right), 0.5 \end{bmatrix} \right\}.
$$

*Therefore*  $(G^{\eta}, B) \subseteq (F^{\mu}, A)$ .

**Definition 13.** *Two GNSESs*  $(F^u, A)$  *and*  $(G^{\eta}, B)$  *over U are said to be equal if*  $(F^u, A)$  *is a GNSES subset of*  $(G<sup>η</sup>, B)$  and  $(G<sup>η</sup>, B)$  is a GNSES subset of  $(F<sup>u</sup>, A)$ .

**Definition 14.** An agree-GNSESs  $(F^u, A)_1$  over U is a GNSES subset of  $(F^u, A)$  defined as follows.

$$
(F^u, A)_1 = \{F_1(\infty) : \infty \in E \times X \times \{1\}\}.
$$

**Example 3.** *Consider Example 1. The agree-GNSES*  $(F^u, Z)_1$  *over U is* 

$$
(F^{u}, Z)_{1} = \left\{ \begin{bmatrix} (e_{1}, p, 1), \left( \frac{u_{1}}{0.4, 0.3, 0.2}, \frac{u_{2}}{0.6, 0.1, 0.8}, \frac{u_{3}}{0.5, 0.7, 0.2}, \right), 0.3 \end{bmatrix}, \begin{bmatrix} (e_{1}, q, 1), \left( \frac{u_{1}}{0.3, 0.2, 0.5}, \frac{u_{2}}{0.5, 0.6, 0.2}, \frac{u_{3}}{0.8, 0.1, 0.4}, \right), 0.4 \end{bmatrix}, \begin{bmatrix} (e_{1}, r, 1), \left( \frac{u_{1}}{0.8, 0.4, 0.3}, \frac{u_{2}}{0.7, 0.3, 0.5}, \frac{u_{3}}{0.2, 0.6, 0.5}, \right), 0.8 \end{bmatrix}, \begin{bmatrix} (e_{2}, p, 1), \left( \frac{u_{1}}{0.7, 0.3, 0.6}, \frac{u_{2}}{0.5, 0.1, 0.4}, \frac{u_{2}}{0.8, 0.6, 0.3}, \right), 0.2 \end{bmatrix}, \begin{bmatrix} (e_{2}, p, 1), \left( \frac{u_{1}}{0.7, 0.3, 0.6}, \frac{u_{2}}{0.5, 0.1, 0.7}, \frac{u_{3}}{0.5, 0.1, 0.7}, \right), 0.6 \end{bmatrix}, \begin{bmatrix} (e_{2}, r, 1), \left( \frac{u_{1}}{0.5, 0.7, 0.8}, \frac{u_{2}}{0.9, 0.3, 0.6}, \frac{u_{3}}{0.4, 0.1, 0.7}, \right), 0.5 \end{bmatrix}, \begin{bmatrix} (e_{3}, p, 1), \left( \frac{u_{1}}{0.7, 0.3, 0.4}, \frac{u_{2}}{0.5, 0.5, 0.5}, \frac{u_{3}}{0.7, 0.4, 0.6}, \right), 0.4 \end{bmatrix}, \begin{bmatrix} (e_{3}, r, 1), \left( \frac{u_{1}}{0.8, 0.4, 0.3}, \frac{u_{2}}{0.5, 0.3,
$$

**Definition 15.** *A disagree-GNSESs*  $(F^u, A)_0$  *over U is a GNSES subset of*  $(F^u, A)$  *is defined as follows:* 

$$
(F^u, A)_0 = \{F_0(\infty) : \infty \in E \times X \times \{0\}\}.
$$

**Example 4.** *Consider Example 1. The disagree-GNSES*  $(F^u, Z)_0$  *over U is* 

$$
(F^{u}, Z)_{0} = \left\{ \begin{bmatrix} (e_{1}, p, 0), (\frac{u_{1}}{(0.4, 0.1, 0.2}, \frac{u_{2}}{0.7, 0.3, 0.5}, \frac{u_{3}}{0.4, 0.1, 0.6},), 0.1], \\ (e_{1}, q, 0), (\frac{u_{1}}{0.7, 0.3, 0.5}, \frac{u_{2}}{0.6, 0.2, 0.4}, \frac{u_{3}}{0.4, 0.5, 0.1},), 0.3], \\ (e_{1}, r, 0), (\frac{u_{1}}{0.6, 0.4, 0.3}, \frac{u_{2}}{0.7, 0.2, 0.6}, \frac{u_{3}}{0.4, 0.1, 0.3},), 0.2], \\ (e_{2}, p, 0), (\frac{u_{1}}{0.5, 0.1, 0.7}, \frac{u_{2}}{0.4, 0.5, 0.1}, \frac{u_{3}}{0.7, 0.1, 0.4},), 0.2], \\ (e_{2}, q, 0), (\frac{u_{1}}{0.4, 0.3, 0.6}, \frac{u_{2}}{0.7, 0.2, 0.5}, \frac{u_{3}}{0.8, 0.1, 0.4},), 0.6], \\ (e_{2}, r, 0), (\frac{u_{1}}{0.3, 0.2, 0.6}, \frac{u_{2}}{0.4, 0.3, 0.5}, \frac{u_{2}}{0.5, 0.1, 0.4},), 0.4], \\ (e_{3}, p, 0), (\frac{u_{1}}{0.4, 0.3, 0.6}, \frac{u_{2}}{0.5, 0.1, 0.6}, \frac{u_{3}}{0.6, 0.2, 0.5},), 0.5], \\ (e_{3}, q, 0), (\frac{u_{1}}{0.5, 0.2, 0.7}, \frac{u_{2}}{0.8, 0.1, 0.4}, \frac{u_{2}}{0.5, 0.3, 0.4},), 0.2], \\ (e_{3}, r, 0), (\frac{u_{1}}{0.5, 0.4, 0.5}, \frac{u_{2}}{0.6, 0.2, 0.7}, \frac{u_{3}}{0.5, 0.3, 0.4
$$

**Definition 16.** The complement of a GNSES  $(F^u, A)$ , denoted by  $(F^u, A)^c$ , is defined as  $(F^u, A)^c$  =  $(F^{u(c)}, \neg A)$  where  $F^{u(c)}$  :  $\neg A \rightarrow \mathcal{N}(U) \times$  *is a mapping given by* 

$$
F^{u(c)}(\alpha) = \left\{ \begin{array}{c} T_{F(\alpha)^{(c)}} = F_{F(\alpha)}, \\ I_{F(\alpha)^{(c)}} = \overline{1} - F_{(\alpha)}, \\ F_{F(\alpha)^{(c)}} = T_{F(\alpha)}, \\ u^{c}(\alpha) = \overline{1} - u(\alpha) \end{array} \right\} \text{ for each } \alpha \in E.
$$

**Example 5.** *Consider Example 1. By using the definition of GNSES complement, the complement of F <sup>u</sup> denoted by Fu*(*c*) *, is as follows:*

$$
(F^{u(c)}, Z) = \begin{cases} \left[ (-e_1, p, 1), \left( \frac{u_1}{0.2,0.7,0.4}, \frac{u_2}{0.8,0.9,0.6}, \frac{u_3}{0.2,0.3,0.8}, \right), 0.7 \right], \\ \left[ (-e_1, q, 1), \left( \frac{u_1}{0.5,0.8,0.3}, \frac{u_2}{0.2,0.4,0.5}, \frac{u_3}{0.4,0.9,0.8}, \right), 0.6 \right], \\ \left[ (-e_1, r, 1), \left( \frac{u_1}{0.3,0.6,0.8}, \frac{u_2}{0.5,0.7,0.7}, \frac{u_3}{0.3,0.4,0.8}, \right), 0.8 \right], \\ \left[ (-e_2, p, 1), \left( \frac{u_1}{0.6,0.7,0.7}, \frac{u_2}{0.4,0.9,0.5}, \frac{u_3}{0.3,0.4,0.8}, \right), 0.8 \right], \\ \left[ (-e_2, q, 1), \left( \frac{u_1}{0.1,0.3,0.6}, \frac{u_2}{0.7,0.6,0.8}, \frac{u_3}{0.7,0.9,0.5}, \right), 0.4 \right], \\ \left[ (-e_2, r, 1), \left( \frac{u_1}{0.8,0.9,0.5}, \frac{u_2}{0.6,0.7,0.9}, \frac{u_3}{0.7,0.9,0.8}, \right), 0.5 \right], \\ \left[ (-e_3, p, 1), \left( \frac{u_1}{0.2,0.7,0.6}, \frac{u_2}{0.7,0.4,0.5}, \frac{u_3}{0.4,0.9,0.8}, \right), 0.6 \right], \\ \left[ (-e_3, r, 1), \left( \frac{u_1}{0.3,0.6,0.8}, \frac{u_2}{0.6,0.7,0.7}, \frac{u_3}{0.2,0.6,0.1}, \right), 0.5 \right], \\ \left[ (-e_1, p, 0), \left( \frac{u_1}{0.2,0.9,0.4}, \frac{u_2}{0.5,0.8,0.7}, \frac{u_3}{0.1,0.5,0.4}, \
$$

**Proposition 1.** If  $(F^u, A)$  is a generalized neutrosophic soft expert set over U, then

- *1.*  $((F^u, A)^c)^c = (F^u, A)$
- 2.  $((F^u, A)_1)^c = (F^u, A)_0$
- 3.  $((F^u, A)_0)^c = (F^u, A)_1$

**Proof.** (1) From Definition 16, we have  $(F^u, A)^c = (F^{u(c)}, \neg A)$ ,

where  $F^{u(c)}(\infty) = T_{F(\infty)^{(c)}} = F_{F(\infty)}$ ,  $\Gamma_{F(\infty)^{(c)}} = \overline{1} - \Gamma_{F(\infty)}$ ,  $F_{F(\infty)^{(c)}} = T_{F(\infty)}$  and  $u^c(\infty) = \overline{1} - u(\infty)$  for each ∝∈ *E*.

Now  $((F^u, A)^c)^c = ((F^{u(c)})^c, A)$  where

$$
(F^{u(c)})^c(\infty) = \begin{bmatrix} T_{F(\infty)^{(c)}} = F_{F(\infty)} I_{F(\infty)^{(c)}} = \overline{1} - I_{F(\infty)} I_{F(\infty)} \\ F_{F(\infty)^{(c)}} = T_{F(\infty)} I^{u(c)}(\infty) = \overline{1} - u(\infty) \end{bmatrix}^c
$$
  
\n
$$
= \begin{bmatrix} T_{F(\infty)} = F_{F(\infty)^{(c)}} I_{F(\infty)} = \overline{1} - I_{F(\infty)^{(c)}} \\ F_{F(\infty)} = T_{F(\infty)^{(c)}} I^{u(\infty)} = \overline{1} - u^c(\infty) \end{bmatrix}
$$
  
\n
$$
= \overline{1} - (\overline{1} - I_{F(\infty)}) = \overline{1} - (\overline{1} - u(\infty)) = I_{F(\infty)}
$$
  
\n
$$
= u(\infty).
$$

Thus  $((F^u, A)^c)^c$  =  $((F^{u(c)})^c, A) = (F^u, A)$ , for all ∝∈ *E*. The proofs of assertions (2) and (3) are obvious.  $\Box$ 

**Definition 17.** The union of two GNSESs  $(F^u, A)$  and  $(G^{\eta}, B)$  over U, denoted by  $(F^u, A) \overset{\sim}{\cup} (G^{\eta}, B)$ , is the GNSESs  $(H^{\Omega}, C)$ , where  $C = A \cup B$  and the truth-membership, indeterminacy-membership, and falsity-membership of  $(H^\Omega,\mathsf{C})$  are as follows:

$$
T_{H^{\Omega}(e)} = \begin{cases} T_{F^{u}(e)}(m) & \text{if } e \in A - B \\ T_{G^{\eta}(e)}(m) & \text{if } e \in B - A \end{cases}
$$

$$
I_{H^{\Omega}(e)} = \begin{cases} I_{F^{u}(e)}(m), T_{G^{\eta}(e)}(m)) & \text{if } e \in A \cap B \\ I_{F^{u}(e)}(m) & \text{if } e \in A - B \\ I_{G^{\eta}(e)}(m) & \text{if } e \in B - A \end{cases}
$$

$$
F_{H^{\Omega}(e)} = \begin{cases} F_{F^{u}(e)}(m), & \text{if } e \in A - B \\ F_{F^{u}(e)}(m), & \text{if } e \in A - B \\ F_{G^{\eta}(e)}(m) & \text{if } e \in A - B \\ F_{G^{\eta}(e)}(m), & \text{if } e \in B - A \end{cases}
$$

$$
F_{H^{\Omega}(e)} = \begin{cases} F_{F^{u}(e)}(m), & \text{if } e \in B - A \\ F_{F^{u}(e)}(m), F_{G^{\eta}(e)}(m)) & \text{if } e \in A \cap B \end{cases}
$$

 $where \ \Omega(m) = max \Bigl(u_{(e)}(m), \eta_{(e)}(m) \Bigr).$ 

**Example 6.** Suppose that  $(F^u, A)$  and  $(G^{\eta}, B)$  are two GNSESs over U, such that

$$
(F^{u}, A) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.4, 0.3, 0.2}, \frac{u_2}{0.6, 0.1, 0.8}, \frac{u_3}{0.5, 0.7, 0.2} \right), 0.3 \end{bmatrix} \right\}
$$

$$
(e_2, q, 1), \left( \frac{u_1}{0.7, 0.3, 0.6}, \frac{u_2}{0.5, 0.1, 0.4}, \frac{u_3}{0.7, 0.6, 0.3} \right), 0.2 \right],
$$

$$
(e_2, q, 0), \left( \frac{u_1}{0.4, 0.3, 0.6}, \frac{u_2}{0.7, 0.2, 0.5}, \frac{u_3}{0.8, 0.1, 0.4} \right), 0.6 \right\},
$$

$$
(G^{\eta}, B) = \left\{ \begin{bmatrix} (e_3, r, 1), \left( \frac{u_1}{0.8, 0.4, 0.3}, \frac{u_2}{0.5, 0.3, 0.6}, \frac{u_3}{0.1, 0.4, 0.2} \right), 0.5 \end{bmatrix} \right\}.
$$

$$
(G^{\eta}, B) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.6, 0.5, 0.1}, \frac{u_2}{0.8, 0.2, 0.3}, \frac{u_3}{0.9, 0.2, 0.3} \right), 0.1 \end{bmatrix}, \left[ \begin{bmatrix} (e_2, q, 1), \left( \frac{u_1}{0.4, 0.1, 0.2}, \frac{u_2}{0.5, 0.4, 0.7}, \frac{u_3}{0.5, 0.1, 0.7} \right), 0.8 \end{bmatrix} \right\}.
$$

*Then*  $(F^u, A) \cup (G^{\eta}, B) = (H^{\Omega}, C)$  *where* 

$$
(H^{\Omega}, C) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.6, 0.3, 0.1}, \frac{u_2}{0.8, 0.1, 0.3}, \frac{u_3}{0.9, 0.2, 0.2} \right), 0.3 \end{bmatrix}, \begin{bmatrix} (e_2, q, 1), \left( \frac{u_1}{0.6, 0.3, 0.1}, \frac{u_2}{0.8, 0.2, 0.5}, \frac{u_3}{0.7, 0.1, 0.4} \right), 0.4 \end{bmatrix}, \begin{bmatrix} (e_2, q, 0), \left( \frac{u_1}{0.4, 0.3, 0.6}, \frac{u_2}{0.7, 0.2, 0.5}, \frac{u_3}{0.8, 0.1, 0.4} \right), 0.6 \end{bmatrix}, \begin{bmatrix} (e_3, r, 1), \left( \frac{u_1}{0.8, 0.1, 0.2}, \frac{u_2}{0.5, 0.3, 0.2}, \frac{u_3}{0.3, 0.4, 0.2} \right), 0.8 \end{bmatrix} \right\}.
$$

**Proposition 2.** *If*  $(F^u, A)$ ,  $(G^{\eta}, B)$  and  $(H^{\Omega}, C)$  are three GNSESs over U, then

*1.*  $(F^u, A) \overset{\sim}{\cup} (G^{\eta}, B) \overset{\sim}{\cup} (H^{\Omega}, C) = (F^u, A) \overset{\sim}{\cup} ((G^{\eta}, B) \overset{\sim}{\cup} (H^{\Omega}, C)).$ 2.  $(F^u, A) \cup (F^u, A) \subseteq (F^u, A).$ 

**Proof.** (1) We want to prove that

$$
((F^u, A)\overset{\sim}{\cup} (G^{\eta}, B)) \overset{\sim}{\cup} (H^{\Omega}, C) = (F^u, A) \overset{\sim}{\cup} ((G^{\eta}, B) \overset{\sim}{\cup} (H^{\Omega}, C))
$$

By using Definition 17, we consider the case when  $e \in A \cap B$ , as other cases are trivial. We will have

$$
(F^u, A) \widetilde{\cup} (G^{\eta}, B) = \left\{ \left( \begin{array}{c} \max \left( \begin{array}{c} T_{F^u(e)}(m), \\ T_{G^{\eta}(e)}(m) \end{array} \right), \\ u \end{array} \right) \begin{array}{c} \min \left( \begin{array}{c} \text{Im}(x) \\ \text{Im}(F^u(e)(m), \\ \text{Im}(F^u(e)(m)) \end{array} \right), \\ \min \left( \begin{array}{c} \text{Im}(F^u(e)(m), \\ \text{Im}(F^u(e)(m), \\ \text{Im}(F^u(e)(m)) \end{array} \right) \end{array} \right\}, \max \left( \begin{array}{c} u_{(e)}(m), \\ \eta_{(e)}(m) \end{array} \right), u \in U \right\}.
$$

Also consider the case when  $e \in H$ , as the other cases are trivial. We will have

$$
\begin{aligned}\n\left((F^u,A)\ \widetilde{\cup}\ (G^\eta,B)\right)\ \widetilde{\cup}\ (H^{\Omega},C) &= \left\{\begin{pmatrix} u \end{pmatrix} \begin{pmatrix} \max\left(T_{F^u(e)}(m), T_{G^\eta(e)}(m)\right), \\ \min\left(T_{F^u(e)}(m), I_{G^\eta(e)}(m)\right), \\ \min\left(T_{F^u(e)}(m), F_{G^\eta(e)}(m)\right) \end{pmatrix}, \quad \begin{pmatrix} u/T_{H^{\Omega}(e)}(m), I_{H^{\Omega}(e)}(m), F_{H^{\Omega}(e)}(m) \end{pmatrix}, u \in U \end{pmatrix} \right\} \\
&= \left\{\begin{pmatrix} u/T_{F^{\Omega}(e)}(m), T_{F^{\Omega}(e)}(m), F_{G^\eta(e)}(m) \end{pmatrix}, \\ \left(u/T_{F^{\Omega}(e)}(m), I_{F^{\Omega}(e)}(m), F_{F^{\Omega}(e)}(m) \end{pmatrix}, \\ \min\left(T_{G^u(e)}(m), T_{H^\eta(e)}(m)\right), \\ \min\left(T_{G^u(e)}(m), I_{H^\eta(e)}(m)\right), \\ \min\left(T_{G^u(e)}(m), F_{H^\eta(e)}(m)\right) \end{pmatrix} \right\} \begin{pmatrix} u/T_{H^{\Omega}(e)}(m), I_{H^{\Omega}(e)}(m), F_{H^{\Omega}(e)}(m) \end{pmatrix}, u \in U \right\}\n\end{aligned}
$$

(2) The proof is straightforward. $\Box$  **Definition 18.** Let  $(F^u, A)$  and  $(G^{\eta}, B)$  be two GNSESs over a common universe U. Then the intersection of  $(F^u, A)$  and  $(G^{\eta}, B)$  is denoted by  $(F^u, A) \overset{\sim}{\cap} (G^{\eta}, B) = (K^{\delta}, C)$ , where  $C = A \cap B$  and the truth-membership, indeterminacy-membership, and falsity-membership of  $(K^\delta, C)$  are as follows:

$$
T_{K^{\delta}(e)} = \begin{cases} T_{F^u(e)}(m) & if e \in A - B \\ T_{G^{\eta}(e)}(m) & if e \in B - A \end{cases}
$$

$$
I_{K^{\delta}(e)} = \begin{cases} I_{F^u(e)}(m), T_{G^{\eta}(e)}(m) \text{ if } e \in A \cap B \\ I_{F^u(e)}(m) & if e \in A - B \\ \text{I}_{G^{\eta}(e)}(m) & if e \in B - A \end{cases}
$$

$$
F_{K^{\delta}(e)} = \begin{cases} F_{F^u(e)}(m), I_{G^{\eta}(e)}(m) \text{ if } e \in A \cap B \\ F_{G^{\eta}(e)}(m) & if e \in A - B \\ F_{G^{\eta}(e)}(m) & if e \in B - A \end{cases}
$$

$$
F_{K^{\delta}(e)} = \begin{cases} F_{F^u(e)}(m) & if e \in B - A \\ F_{G^{\eta}(e)}(m), F_{G^{\eta}(e)}(m) \text{ if } e \in B - A \end{cases}
$$

 $where \ \delta(m) = min\Bigl(u_{(e)}(m), \eta_{(e)}(m)\Bigr).$ 

**Example 7.** Suppose that  $(F^u, A)$  and  $(G^{\eta}, B)$  are two GNSESs over U, such that

$$
(F^u, A) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.4, 0.3, 0.2}, \frac{u_2}{0.6, 0.1, 0.8}, \frac{u_3}{0.5, 0.7, 0.2}, \right), 0.3 \end{bmatrix}, \\ \begin{bmatrix} (e_2, q, 1), \left( \frac{u_1}{0.7, 0.3, 0.6}, \frac{u_2}{0.5, 0.1, 0.4}, \frac{u_3}{0.7, 0.6, 0.3}, \right), 0.2 \end{bmatrix}, \\ (G^{\eta}, B) = \left\{ \begin{bmatrix} (e_2, q, 0), \left( \frac{u_1}{0.4, 0.3, 0.6}, \frac{u_1}{0.7, 0.2, 0.5}, \frac{u_3}{0.8, 0.1, 0.4}, \right), 0.6 \end{bmatrix} \right\}.
$$

$$
(G^{\eta}, B) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.6, 0.5, 0.1}, \frac{u_2}{0.8, 0.2, 0.3}, \frac{u_3}{0.9, 0.2, 0.3}, \right), 0.1 \end{bmatrix}, \\ \begin{bmatrix} (e_3, r, 1), \left( \frac{u_1}{0.4, 0.1, 0.2}, \frac{u_2}{0.5, 0.4, 0.2}, \frac{u_3}{0.3, 0.6, 0.4}, \right), 0.8 \end{bmatrix} \right\}.
$$

*Then*  $(F^u, A) \overset{\sim}{\cap} (G^{\eta}, B) = (K^{\delta}, C)$  *where* 

$$
\left(K^{\delta}, C\right) = \left\{ \left[ (e_1, p, 1), \left( \frac{u_1}{0.4, 0.3, 0.2}, \frac{u_2}{0.6, 0.1, 0.8}, \frac{u_3}{0.5, 0.2, 0.3}, \right), 0.1 \right] \right\}.
$$

**Proposition 3.** *If*  $(F^u, A)$ ,  $(G^{\eta}, B)$  and  $(H^{\Omega}, C)$  are three GNSESs over U, then

1. 
$$
\left((F^u, A) \overset{\sim}{\cap} (G^{\eta}, B)\right) \overset{\sim}{\cap} (K^{\delta}, C) = (F^u, A) \overset{\sim}{\cap} \left((G^{\eta}, B) \overset{\sim}{\cap} (K^{\delta}, C)\right)
$$
  
2. 
$$
(F^u, A) \overset{\sim}{\cap} (F^u, A) \subseteq (F^u, A).
$$

**Proof.** (1) We want to prove that

$$
((F^u, A) \overset{\sim}{\cap} (G^{\eta}, B)) \overset{\sim}{\cap} (K^{\delta}, C) = (F^u, A) \overset{\sim}{\cap} ((G^{\eta}, B) \overset{\sim}{\cap} (K^{\delta}, C))
$$

By using Definition 18, consider the case when  $e \in A \cap B$ , since other cases are trivial. We have

$$
(F^u, A) \overset{\sim}{\cap} (G^{\eta}, B) = \left\{ \left( u \bigg/ \begin{array}{c} \min\Big( T_{F^u(e)}(m), T_{G^{\eta}(e)}(m) \Big), \\ \min\Big( I_{F^u(e)}(m), I_{G^{\eta}(e)}(m) \Big), \\ \max\Big( F_{F^u(e)}(m), F_{G^{\eta}(e)}(m) \Big) \end{array} \right), \quad \min\Big( u_{(e)}(m), \eta_{(e)}(m) \Big), u \in U \right\}.
$$

Also consider the case when  $e \in K$ , as the other cases are trivial. Then we have

$$
\begin{array}{lcl}\n\left((F^u,A)\stackrel{\sim}{\cap} (G^\eta,B)\right) \stackrel{\sim}{\cap} (K^\delta,C) & = & \left\{\left(u \left/ \begin{array}{c} \min\left(T_{F^u(e)}(m),T_{G^\eta(e)}(m)\right), \\ \min\left(T_{F^u(e)}(m),T_{G^\eta(e)}(m)\right), \\ \max\left(F_{F^u(e)}(m),F_{G^\eta(e)}(m)\right) \end{array}\right)\right. & \left.\left.\left(\begin{array}{c} u/T_{K^\delta(e)}(m),I_{K^\delta(e)}(m),F_{K^\delta(e)}(m)\right), \\ \min\left(u_{(e)}(m),\eta_{(e)}(m),\delta(m)\right), u\in U \end{array}\right.\right\}.\n\end{array}
$$
\n
$$
= & \left\{\left(\begin{array}{c} u/T_{\Gamma^{\Omega}(e)}(m),I_{\Gamma^{\Omega}(e)}(m),F_{\Gamma^{\Omega}(e)}(m)\right), \\ u/T_{\Gamma^{\Omega}(e)}(m),I_{\Gamma^{\Omega}(e)}(m),F_{K^\delta(e)}(m)\right), \\ \max\left(T_{G^u(e)}(m),I_{K^\delta(e)}(m)\right), \\ \max\left(T_{G^u(e)}(m),F_{K^\delta(e)}(m)\right)\right) \end{array}\right\} \min\left(u_{(e)}(m),\eta_{(e)}(m),\delta(m)\right), u\in U\right\}
$$

(2) The proof is straightforward.  $\Box$ 

**Proposition 4.** *If*  $(F^u, A)$ *,*  $(G^{\eta}, B)$  and  $(K^{\delta}, C)$  are three GNSESs over U. Then

1. 
$$
\left((F^u, A) \overset{\sim}{\cup} (G^{\eta}, B)\right) \overset{\sim}{\cap} (K^{\delta}, C) = \left((F^u, A) \overset{\sim}{\cap} (K^{\delta}, C)\right) \overset{\sim}{\cup} \left((G^{\eta}, B) \overset{\sim}{\cap} (K^{\delta}, C)\right).
$$
  
2. 
$$
\left((F^u, A) \overset{\sim}{\cap} (G^{\eta}, B)\right) \overset{\sim}{\cup} (K^{\delta}, C) = \left((F^u, A) \overset{\sim}{\cup} (K^{\delta}, C)\right) \overset{\sim}{\cap} \left((G^{\eta}, B) \overset{\sim}{\cup} (K^{\delta}, C)\right).
$$

**Proof.** The proofs can be easily obtained from Definitions 17 and 18.  $\Box$ 

**Definition 19.** If  $(F^u, A)$  and  $(G^{\eta}, B)$  are two GNSESs over U, then " $(F^u, A)$  AND  $(G^{\eta}, B)$ " denoted by  $(F^u, A) \wedge (G^{\eta}, B)$ , is defined by

$$
(F^u, A) \wedge (G^{\eta}, B) = (H^{\Omega}, A \times B)
$$

*such that,*  $H^{\Omega}(\alpha,\beta)$  =  $F^{\mu}(\alpha) \cap G^{\eta}(\beta)$  and the truth-membership, indeterminacy-membership, and falsity-membership of  $(H^{\Omega}, A \times B)$  are as follows.

$$
T_{H^{\Omega}(\alpha,\beta)}(m) = min\left(T_{F^u(\alpha)}(m), T_{G^{\eta}(\beta)}(m)\right),
$$
  
\n
$$
I_{H^{\Omega}(\alpha,\beta)}(m) = min\left(I_{F^u(\alpha)}(m), I_{G^{\eta}(\beta)}(m)\right),
$$
  
\n
$$
F_{H^{\Omega}(\alpha,\beta)}(m) = max\left(F_{F^u(\alpha)}(m), F_{G^{\eta}(\beta)}(m)\right)
$$

 $and \ \Omega(m) = min\Bigl(u_{(e)}(m), \eta_{(e)}(m)\Bigr)$  ,  $\forall \alpha \in A, \forall \beta \in B.$ 

**Example 8.** Suppose that  $(F^u, A)$  and  $(G^{\eta}, B)$  are two GNSESs over U, such that

$$
(F^u, A) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.2, 0.3, 0.5}, \frac{u_2}{0.4, 0.1, 0.2}, \frac{u_3}{0.6, 0.3, 0.7}, \right), 0.4 \end{bmatrix}, \begin{bmatrix} (e_3, r, 0), \left( \frac{u_1}{0.5, 0.2, 0.1}, \frac{u_2}{0.6, 0.3, 0.7}, \frac{u_3}{0.2, 0.1, 0.8}, \right), 0.3 \end{bmatrix} \right\}
$$

$$
(G^{\eta}, B) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.3, 0.2, 0.6}, \frac{u_2}{0.6, 0.3, 0.2}, \frac{u_3}{0.8, 0.1, 0.2}, \right), 0.5 \end{bmatrix}, \begin{bmatrix} (e_2, q, 0), \left( \frac{u_1}{0.1, 0.3, 0.5}, \frac{u_2}{0.7, 0.1, 0.6}, \frac{u_3}{0.4, 0.3, 0.6}, \right), 0.6 \end{bmatrix} \right\}.
$$

*Then*  $(F^u, A) \wedge (G^{\eta}, B) = (H^{\Omega}, A \times B)$  *where* 

$$
(H^{\Omega}, A \times B) = \left\{ \left[ (e_1, p, 1), (e_1, p, 1) \left( \frac{u_1}{0.2, 0.2, 0.6}, \frac{u_2}{0.4, 0.1, 0.2}, \frac{u_3}{0.6, 0.1, 0.7}, \right), 0.4 \right], \left. \left[ (e_1, p, 1), (e_2, q, 0), \left( \frac{u_1}{0.1, 0.3, 0.5}, \frac{u_2}{0.4, 0.1, 0.6}, \frac{u_3}{0.4, 0.3, 0.7}, \right), 0.4 \right], \left. \left[ (e_3, r, 0), (e_1, p, 1), \left( \frac{u_1}{0.3, 0.2, 0.6}, \frac{u_2}{0.6, 0.3, 0.7}, \frac{u_3}{0.2, 0.1, 0.8}, \right), 0.3 \right], \left. \left[ (e_3, r, 0), (e_2, q, 0), \left( \frac{u_1}{0.1, 0.2, 0.5}, \frac{u_2}{0.6, 0.1, 0.7}, \frac{u_3}{0.2, 0.1, 0.8}, \right), 0.3 \right] \right\}.
$$

**Definition 20.** If  $(F^u, A)$  and  $(G^{\eta}, B)$  are two GNSESs over U, then " $(F^u, A)$  OR  $(G^{\eta}, B)$ " denoted by  $(F^u, A) \vee (G^{\eta}, B)$ , is defined by

$$
(F^u, A) \vee (G^{\eta}, B) = (K^{\delta}, A \times B)
$$

 $\mathsf{such\;\;that\;\;}\, \mathsf{K}^{\delta}(\alpha,\beta) \;\;\;= \;\;\;\;\; \mathsf{F}^{\mathsf{u}}(\alpha) \, \cup \, \mathsf{G}^{\eta}(\beta) \;\; \text{and \;\;the \;\; truth-membership, \;\; indeterminacy-membership,}$ and falsity-membership of  $\left(K^\delta, A \times B \right)$  are as follows.

$$
T_{K^{\delta}(\alpha,\beta)}(m) = max(T_{F^u(\alpha)}(m), T_{G^{\eta}(\beta)}(m)),
$$
  
\n
$$
I_{K^{\delta}(\alpha,\beta)}(m) = min(I_{F^u(\alpha)}(m), I_{G^{\eta}(\beta)}(m)),
$$
  
\n
$$
F_{K^{\delta}(\alpha,\beta)}(m) = min(F_{F^u(\alpha)}(m), F_{G^{\eta}(\beta)}(m))
$$

 $and \ \delta(m) = max\Bigl(u_{(e)}(m), \eta_{(e)}(m)\Bigr)$  ,  $\forall \alpha \in A, \forall \beta \in B.$ 

**Example 9.** Suppose that  $(F^u, A)$  and  $(G^{\eta}, B)$  are two GNSESs over U, such that

$$
(F^u, A) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.2, 0.3, 0.5}, \frac{u_2}{0.4, 0.1, 0.2}, \frac{u_3}{0.6, 0.3, 0.7}, \right), 0.4 \\ (e_3, r, 0), \left( \frac{u_1}{0.5, 0.2, 0.1}, \frac{u_2}{0.6, 0.3, 0.7}, \frac{u_3}{0.2, 0.1, 0.8}, \right), 0.3 \end{bmatrix} \right\}
$$

$$
(G^{\eta}, B) = \left\{ \begin{bmatrix} (e_1, p, 1), \left( \frac{u_1}{0.3, 0.2, 0.6}, \frac{u_2}{0.6, 0.3, 0.2}, \frac{u_3}{0.8, 0.1, 0.2}, \right), 0.5 \\ (e_2, q, 0), \left( \frac{u_1}{0.1, 0.3, 0.5}, \frac{u_2}{0.7, 0.1, 0.6}, \frac{u_3}{0.4, 0.3, 0.6}, \right), 0.6 \end{bmatrix} \right\}.
$$

*Then*  $(F^u, A) \vee (G^{\eta}, B) = (K^{\delta}, A \times B)$  *where* 

$$
(K^{\delta}, A \times B) = \left\{ \left[ (e_1, p, 1), (e_1, p, 1) \left( \frac{u_1}{0.3,0.2,0.5}, \frac{u_2}{0.6,0.1,0.2}, \frac{u_3}{0.8,0.1,0.2}, \right), 0.5 \right], \\ \left[ (e_1, p, 1), (e_2, q, 0), \left( \frac{u_1}{0.2,0.3,0.5}, \frac{u_2}{0.7,0.1,0.2}, \frac{u_3}{0.6,0.3,0.6}, \right), 0.6 \right], \\ \left[ (e_3, r, 0), (e_1, p, 1), \left( \frac{u_1}{0.5,0.2,0.1}, \frac{u_2}{0.7,0.3,0.6}, \frac{u_3}{0.8,0.1,0.2}, \right), 0.5 \right], \\ \left[ (e_3, r, 0), (e_2, q, 0), \left( \frac{u_1}{0.5,0.2,0.1}, \frac{u_2}{0.7,0.1,0.6}, \frac{u_3}{0.4,0.1,0.6}, \right), 0.6 \right] \right\}.
$$

**Proposition 5.** Let  $(F^u, A)$  and  $(G^{\eta}, B)$  be GNSESs over U. Then

*1.*  $((F^u, A) \wedge (G^{\eta}, B))^{c} = (F^u, A)^{c} \vee (G^{\eta}, B)^{c}$ 2.  $((F^u, A) \vee (G^{\eta}, B))^c = (F^u, A)^c \wedge (G^{\eta}, B)^c$ 

**Proof.** The proofs can be easily obtained from Definitions 16, 19 and 20. $\Box$ 

#### **4. GNSES-Aggregation Operator**

In this section, we define a GNSES-aggregation operator of a GNSES to construct a decision method by which approximate functions of a soft expert set are combined to produce a neutrosophic set that can be used to evaluate each alternative.

**Definition 21.** Let  $Y_A \in GNSESS$ . Then a GNSES-aggregation operator of  $Y_A$ , denoted by  $Y_A^{agg}$ *A* , *is defined by*

$$
Y_A^{agg} = \left\{ \langle \left( u, T_A^{agg}(u), I_A^{agg}(u), F_A^{agg}(u) \right) \rangle : u \in U \right\},\tag{5}
$$

*which is a GNSES over U*,

$$
T_A^{agg}: U \to [0,1], \quad T_A^{agg}(u) = \frac{1}{|U|} \sum_{\ell \in E} e_{\ell} F_{A}(u) . \mu,
$$
  
  $u \in U$  (6)

$$
F_A^{agg}: U \to [0,1], \ F_A^{agg}(u) = \frac{1}{|U|} \sum_{\ell \in E} e_{\ell} F_A(u) . \mu,
$$
  
  $u \in U$  (7)

$$
I_A^{agg}: U \to [0,1], \ I_A^{agg}(u) = \frac{1}{|U|} \sum_{\ell \in E} \bigg[ I_A(u). \mu,
$$
\n
$$
u \in U
$$
\n(8)

*where* |*U*| *is the cardinality of U and µ is defined below*

$$
\mu = \frac{1}{n} \sum_{i=1}^{n} \mu(e_i). \qquad (e_i, i = 1, 2, 3, \dots, n). \tag{9}
$$

**Definition 22.** Let  $Y_A \in GNSESs$ ,  $Y_A^{agg}$ *A be the corresponding GNSES aggregation operator. Then a reduced fuzzy set of* Υ *agg A is a fuzzy set over U*, *denoted by*

$$
Y_A^{agg} = \left\{ \frac{\tau Y_A^{agg}(u)}{u} : u \in U \right\},\tag{10}
$$

*where*  $\tau Y^{agg}_A$  $\int_A^{agg}(u) : U \to [0,1]$  and  $u_i = \left|T_{A_i}^{agg}\right|$  $\frac{G}{A_i}$ <sup>*agg*</sup></sup> $- F_{A_i}$ <sup>*agg*</sup>  $I_{A_i}^{agg} - I_{A_i}^{agg}$ *Ai*   .

## <span id="page-12-0"></span>**5. An Application of Generalized Neutrosophic Soft Expert Set**

In this section, we present an application of generalized neutrosophic soft expert set theory in a decision-making problem. Based on Definitions 21 and 22, we constructed an algorithm for the GNSES decision-making method as follows.

**Step 1**—Choose a feasible subset of the set of parameters.

**Step 2**—Construct the GNSES tables for each opinion (agree, disagree) of experts.

**Step 3**—Compute the aggregation operator GNSES  $Y_A^{agg}$  $\frac{dS}{A}$  of  $Y_A$  and the reduced fuzzy set  $T_{A_i}^{a g g}$ *Ai* , *F agg Ai* , *I agg Ai* of Υ *agg* "88 .<br>А

**Step 4**—Score $(u_I)$  = maxagree $(u_i)$  – mindisagree $(u_i)$ .

**Step 5—Choose** the element of  $u_i$  that has maximum score. This will be the optimal solution.

**Example 10.** *Suppose a company needs to employ a worker, which is to be decided by a few experts. The employee has to be chosen from five potential workers,*  $U = \{u_1, u_2, u_3, u_4, u_5\}$ . *Suppose there are four parameters*  $E = \{e_1, e_2, e_3, e_4\}$  *where the parameters*  $e_i$  ( $i = 1, 2, 3, 4$ ) *stand for "education," "age," "capability" and* 

"experience", respectively. Let  $X = \{p, q, r\}$  be a set of experts. After a serious discussion, the experts construct *the following generalized neutrosophic soft expert set.*

**Step 1**—Choose a feasible subset of the set of parameters

$$
(F^{\mu},Z) = \begin{cases} \left[ (e_1, p, 1), \left( \frac{u_1}{0.2,0.3,0.4}, \frac{u_2}{0.8,0.2,0.5}, \frac{u_3}{0.4,0.2,0.3}, \frac{u_4}{0.4,0.2,0.3}, \frac{u_4}{0.5,0.3,0.5}, \frac{u_3}{0.4,0.2,0.3}, \frac{u_4}{0.5,0.3,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.2,0.4}, \frac{u_6}{0.5,0.2,0.4}, \frac{u_7}{0.5,0.2,0.5}, \frac{u_7}{0.3,0.1,0.6}, \frac{u_7}{0.5,0.3,0.1}, \frac{u_8}{0.5,0.2,0.5}, \frac{u_4}{0.3,0.1,0.6}, \frac{u_7}{0.4,0.3,0.2}, \frac{u_8}{0.5,0.2,0.5}, \frac{u_9}{0.3,0.1,0.6}, \frac{u_9}{0.4,0.3,0.2}, \frac{u_1}{0.4,0.3,0.2}, \frac{u_1}{0.4,0.3,0.2}, \frac{u_1}{0.4,0.3,0.5}, \frac{u_2}{0.5,0.3,0.4}, \frac{u_3}{0.2,0.4,0.5}, \frac{u_5}{0.5,0.3,0.4}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.3,0.4}, \frac{u_5}{0.5,0.2,0.5}, \frac{u_5}{0.5,0.3,0.4}, \frac{u_5}{0.5,0.3,0.4}, \frac{u_5}{0
$$

<span id="page-13-0"></span>**Step 2**—Construct the GNSES tables for each opinion (agree, disagree) of experts, as shown in Tables [1](#page-13-0) and [2.](#page-14-0)

**Table 1.** Agree-GNSES.

$u_1$	$u_2$	$u_3$	$u_4$	$u_{5}$	μ
0.2, 0.3, 0.4	0.8, 0.2, 0.6	0.6, 0.3, 0.5	0.4, 0.2, 0.3	0.6.0.3.0.1	0.7
0.6.0.2.0.3	0.4, 0.2, 0.5	0.3, 0.4, 0.1	0.7, 0.3, 0.6	0.5.0.2.0.4	0.8
0.2, 0.4, 0.6	0.7, 0.4, 0.2	0.4, 0.1, 0.2	0.8, 0.4, 0.3	0.7, 0.3, 0.4	0.3
0.2, 0.3, 0.6	0.7.0.1.0.5	0.4.0.2.0.8	0.9.0.2.0.4	0.3.0.4.0.6	0.6
0.3, 0.1, 0.4	0.2, 0.1, 0.5	0.4, 0.2, 0.3	0.4, 0.2, 0.3	0.7.0.2.0.5	0.6
0.1, 0.3, 0.6	0.7, 0.3, 0.1	0.6, 0.2, 0.5	0.3, 0.1, 0.6	0.4.0.3.0.2	0.4
0.4, 0.2, 0.6	0.5, 0.3, 0.6	0.6, 0.2, 0.7	0.8, 0.2, 0.4	0.6.0.2.0.3	0.4
0.5, 0.2, 0.1	0.2, 0.3, 0.4	0.4, 0.1, 0.5	0.6, 0.3, 0.2	0.7, 0.3, 0.4	0.6
0.3, 0.5, 0.1	0.6, 0.2, 0.5	0.1, 0.4, 0.2	0.5, 0.2, 0.3	0.4.0.3.0.2	0.2
0.6, 0.3, 0.5	0.7, 0.3, 0.6	0.5, 0.3, 0.4	0.2, 0.1, 0.3	0.6.0.2.0.5	0.5
0.3, 0.6, 0.5	0.6, 0.2, 0.5	0.2, 0.1, 0.4	0.5, 0.3, 0.2	0.4.0.1.0.5	0.5
0.5.0.2.0.1	0.6, 0.3, 0.5	0.2, 0.5, 0.3	0.5, 0.1, 0.4	0.3.0.2.0.5	0.3

<span id="page-14-0"></span>

U	$u_1$	u <sub>2</sub>	$u_3$	$u_4$	$u_{5}$	μ
$(e_1, p)$	0.2, 0.3, 0.4	0.5, 0.3, 0.1	0.6, 0.3, 0.4	0.6, 0.2, 0.4	0.7.0.5.0.6	0.9
$(e_2, p)$	0.7, 0.3, 0.5	0.6, 0.2, 0.4	0.4, 0.3, 0.5	0.3, 0.2, 0.5	0.4, 0.3, 0.5	0.8
$(e_3, p)$	0.6.02.0.4	0.6, 0.1, 0.5	0.5.0.4.0.6	0.8, 0.3, 0.6	0.7.0.2.0.4	0.5
$(e_4, p)$	0.4, 0.2, 0.6	0.5, 0.2, 0.6	0.9, 0.5, 0.1	0.3, 0.2, 0.6	0.4, 0.3, 0.5	0.6
$(e_1, q)$	0.5, 0.1, 0.7	0.4, 0.2, 0.3	0.8, 0.5, 0.4	0.7, 0.3, 0.6	0.5, 0.3, 0.4	0.7
$(e_2,q)$	0.6.0.2.0.4	0.5.0.3.0.7	0.8, 0.1, 0.3	0.2, 0.3, 0.6	0.6.0.2.0.4	0.4
$(e_3, q)$	0.7, 0.1, 0.6	0.4, 0.5, 0.8	0.4, 0.3, 0.5	0.6.0.2.0.5	0.4.0.3.0.5	0.3
$(e_4, q)$	0.3, 0.2, 0.1	0.6, 0.1, 0.5	0.6, 0.2, 0.5	0.8, 0.3, 0.2	0.2, 0.3, 0.4	0.5
$(e_1,r)$	0.3, 0.1, 0.6	0.6, 0.3, 0.7	0.3, 0.2, 0.4	0.8, 0.1, 0.4	0.6.0.4.0.5	0.6
$(e_2,r)$	0.6, 0.3, 0.4	0.5, 0.2, 0.4	0.7, 0.4, 0.5	0.5, 0.2, 0.4	0.4, 0.3, 0.5	0.2
$(e_3,r)$	0.2, 0.3, 0.6	0.7, 0.4, 0.5	0.4.0.2.0.8	0.9.0.1.0.4	0.6.0.3.0.2	0.3
$(e_4,r)$	0.6.0.2.0.5	0.7, 0.1, 0.6	0.5, 0.3, 0.1	0.3, 0.2, 0.6	0.4.0.2.0.5	0.1

**Table 2.** Disagree-GNSES.

**Step 3**—Now calculate the scores of agree  $(u_i)$  by using the data in Table [1,](#page-13-0) to obtain values in Table [3.](#page-14-1) *agg*

$$
T_A^{agg}(p, u_1) = \left(\frac{T_{A1} + T_{A2} + T_{A3} + T_{A4}}{4}\right) \cdot \left(\frac{\mu_1 + \mu_2 + \mu_3 + \mu_4}{4}\right) = \left(\frac{0.2 + 0.6 + 0.2 + 0.2}{4}\right) \cdot \left(\frac{0.7 + 0.8 + 0.3 + 0.6}{4}\right) = 0.18
$$
  

$$
I_A^{agg}(q, u_1) = \left(\frac{I_{A1} + I_{A2} + I_{A3} + I_{A4}}{4}\right) \cdot \left(\frac{\mu_1 + \mu_2 + \mu_3 + \mu_4}{4}\right) = \left(\frac{0.3 + 0.2 + 0.4 + 0.3}{4}\right) \cdot \left(\frac{0.7 + 0.8 + 0.3 + 0.6}{4}\right) = 0.18
$$
  

$$
F_A^{agg}(r, u_1) = \left(\frac{F_{A1} + F_{A2} + F_{A3} + F_{A4}}{4}\right) \cdot \left(\frac{\mu_1 + \mu_2 + \mu_3 + \mu_4}{4}\right) = \left(\frac{0.4 + 0.3 + 0.6 + 0.6}{4}\right) \cdot \left(\frac{0.7 + 0.8 + 0.3 + 0.6}{4}\right) = 0.285
$$
  

$$
u_1 = \left|T_{A_i}^{agg} - F_{A_i}^{agg} - I_{A_i}^{agg}\right| = |0.18 - 0.18 - 0.285| = 0.285.
$$

**Table 3.** Degree table of agree-GNSES.

U	$u_1$	$\mathfrak{u}_2$	$u_3$	$u_{4}$	uп
р		$0.285$ $0.015$ $0.135$ $0.015$			0.09
q	0.18	0.15	0.105	0.12	0.015
r	0.165	0.09	0.24	0.06	0.045

<span id="page-14-1"></span>Now calculate the score of disagree (*ui*) by using the data in Table [2,](#page-14-0) to obtain values in Table [4.](#page-15-0)

$$
T_A^{agg}(p, u_1) = \left(\frac{T_{A1} + T_{A2} + T_{A3} + T_{A4}}{4}\right) \cdot \left(\frac{\mu_1 + \mu_2 + \mu_3 + \mu_4}{4}\right)
$$
  
\n
$$
= \left(\frac{0.2 + 0.7 + 0.6 + 0.4}{4}\right) \cdot \left(\frac{0.9 + 0.8 + 0.5 + 0.6}{4}\right)
$$
  
\n
$$
= 0.3325
$$
  
\n
$$
I_A^{agg}(q, u_1) = \left(\frac{I_{A1} + I_{A2} + I_{A3} + I_{A4}}{4}\right) \cdot \left(\frac{\mu_1 + \mu_2 + \mu_3 + \mu_4}{4}\right)
$$
  
\n
$$
= \left(\frac{0.3 + 0.3 + 0.2 + 0.2}{4}\right) \cdot \left(\frac{0.9 + 0.8 + 0.5 + 0.6}{4}\right)
$$
  
\n
$$
= 0.175
$$
  
\n
$$
F_A^{agg}(r, u_1) = \left(\frac{F_{A1} + F_{A2} + F_{A3} + F_{A4}}{4}\right) \cdot \left(\frac{\mu_1 + \mu_2 + \mu_3 + \mu_4}{4}\right)
$$
  
\n
$$
= \left(\frac{0.4 + 0.5 + 0.4 + 0.6}{4}\right) \cdot \left(\frac{0.9 + 0.8 + 0.5 + 0.6}{4}\right)
$$
  
\n
$$
= 0.3325
$$
  
\n
$$
u_1 = \left|T_{A_i}^{agg} - F_{A_i}^{agg} - I_{A_i}^{agg}\right| = |0.3325 - 0.175 - 0.3325| = 0.175.
$$

U	$u_1$	u <sub>2</sub>	$u_3$	$u_{4}$	$u_{\overline{z}}$
р				$0.175$ $0.035$ $0.1225$ $0.175$ $0.1925$	
a				0.0525 0.2625 0.035 0.1225 0.0875	
r				0.2275 0.1225 0.175 0.0175 0.1575	

**Table 4.** Degree table of disagree-GNSES.

<span id="page-15-0"></span>**Step 4—The final score of**  $u_i$  **is computed as follows.** 



**Step 5**—Score( $u_1$ ) = 0.2325 is the maximum. Hence, the best decision for the experts is to select worker  $u_1$  as the company's employee.

#### **6. Comparison Analysis**

A generalized neutrosophic soft expert model gives more precision, flexibility, and compatibility than the existing neutrosophic models. These are verified by a comparison analysis, using neutrosophic soft expert decision method, with those methods used by Sahin et al. [\[27\]](#page-16-24), Hassan [\[44\]](#page-17-15), and Maji [\[20\]](#page-16-17), as given in Table [5.](#page-15-1) The comparison is done based on the same example as in Section [5.](#page-12-0) The ranking order results obtained are consistent with those in [\[20,](#page-16-17)[27,](#page-16-24)[44\]](#page-17-15).

<span id="page-15-1"></span>**Methods Neutrosophic Soft Set Neutrosophic Soft Expert Set** *Q***-Neutrosophic Soft Expert Set Generalized Neutrosophic Soft Expert Set** Authors Maji [\[20\]](#page-16-17) Sahin et al. [\[27\]](#page-16-24) Hassan et al. [\[44\]](#page-17-15) Proposed Method Domain Universe of discourse Universe of discourse Universe of discourse Universe of discourse  $Co$ -domain  $[0.1]$ <sup>3</sup>  $[0.1]^{3}$  $[0,1]^{3}$  $[0,1]^{3}$ True Yes Yes Yes Yes Falsity Yes Yes Yes Yes Indeterminacy Yes Yes Yes Yes Yes Yes Yes Expert No Yes Yes Yes *Q* No No Yes No Ranking  $u_2 > u_3 > u_1 >$  $u_4 > u_5$  $u_2 > u_2 > u_1 >$  $u_4 > u_5$  $u_3 > u_1 > u_2 >$  $u_4 > u_5$  $u_1 > u_3 > u_2 >$  $u_4 > u_5$ 

**Table 5.** Comparison of neutrosophic soft set to other variants.

#### **7. Conclusions**

We have established the concept of generalized neutrosophic soft expert set (GNSES) as a generalization of NSES. The basic operations of GNSES of complement, union, intersection AND, and OR were defined. Subsequently, a definition of GNSES-aggregation operator was proposed to construct an algorithm of a GNSES decision method. Finally, an application of the constructed algorithm, to solve a decision-making, was provided. This new extension provides a significant contribution to current theories for handling indeterminacy, and it spurs the development of further research and pertinent applications.

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