

# Compressodynamics

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# 1 Introduction

This document presents the development of Compressodynamics and outlines the logical progression from earlier frameworks to the present formulation.

## 2 Foundations

### 2.1 Initial Sequence

The development began with FCI, which emphasised that physical content is not lost when systems change form. This later revealed itself as belonging to the observer pathway. RCFT then provided a non-observer description based on resonance and structural behaviour. Continued refinement isolated compression and decompression of the medium as the essential mechanisms.

### 2.2 Compression and Decompression

$$\boxed{\text{Compression} \leftrightarrow \mathcal{C} > 0} \quad \boxed{\text{Decompression} \leftrightarrow \mathcal{C} < 0}$$

A formal definition of  $\mathcal{C}$  will be introduced later.

## 3 Reconsidering Discarded Concepts

The approach developed here will likely be disregarded by many readers, as it reintroduces elements that were removed from mainstream physics more than a century ago. The prevailing view has treated certain discarded ideas as permanently resolved. Once a concept is excluded, it is often assumed that it cannot be reconsidered without contradicting established frameworks.

This reaction is understandable, but not necessarily justified. A concept may have been rejected for reasons that applied only to a specific historical formulation, not to the underlying idea itself. In this case, what was abandoned was a rigid and mechanically inadequate version of a physical medium, not the possibility of a medium in general. The rejection became structural, even though it depended on assumptions that no longer apply.

For more than three decades, key areas of physics have shown limited progress regarding the foundations of space, vacuum behaviour, and the unification of forces. When a field remains unchanged over such a timespan, it becomes reasonable to re-examine earlier assumptions. The purpose is not to restore old models, but to evaluate whether the reasoning that dismissed them still holds under modern understanding.

A simple starting point can be drawn from the binary analogy underlying the FCI work. If a physical structure exists, it cannot be treated as equivalent to the absence of structure. In binary terms, a structure corresponds to 1, not 0. Treating the underlying medium as a 0 state leads to contradictions: a system with mechanical behaviour, tension, waves, limits, and curvature cannot

simultaneously be defined as having no substance. This discrepancy motivates a renewed examination of the medium as a physical entity rather than an absence.

Reconsidering this point does not conflict with established results. It only questions an assumption that has remained untested for decades and may no longer be adequate. The following sections develop this reconsideration in a structured and physical manner.

### **3.1 Historical Constraint on Doctor Einstein’s Approach**

Doctor Einstein’s early work did not begin with the assumption that the physical background was empty. On the contrary, several of his initial ideas implied the presence of a continuous medium with definable properties. However, the scientific context of the early twentieth century imposed constraints that shaped the direction of his final formulations.

The experimental results available at the time, particularly the Michelson–Morley measurement, were interpreted as ruling out the form of medium then under consideration. That medium was assumed to be rigid, stationary, and mechanically incompatible with the observed invariance of light speed. Under these assumptions, maintaining the existence of a medium seemed logically untenable.

Doctor Einstein was therefore placed in a position where the most consistent option was to remove the medium entirely from the formulation. This decision resolved the immediate conflict with the data of the period, but it also eliminated the possibility of exploring a more general form of medium that did not share the rigid properties of the one that had been discarded.

It is important to recognise that this constraint was historical rather than conceptual. Nothing in Doctor Einstein’s final equations strictly prohibits a medium; they only exclude the specific version that was already disproven. Modern understanding of materials, fields, and continuous systems no longer requires the assumptions that invalidated the earlier model. For this reason, it is reasonable to reconsider the medium in a broader and more flexible form, consistent with present-day knowledge.

The intention here is not to contradict Doctor Einstein’s work, but to recognise that his removal of the medium may have reflected the limitations of the models available at the time rather than the limitations of the idea itself.

### **3.2 Interpretive Adjustment Rather Than Predictive Revision**

The direction taken in this document does not alter the predictions obtained from Doctor Einstein’s equations. The empirical successes of general relativity remain intact. The purpose here is to reconsider the physical interpretation assigned to the mathematical structures, not to modify the results they produce.

Doctor Einstein’s formulation uses the stress-energy tensor as the source term for curvature. In Compressodynamics, the same geometric equations are used, but the source term is reinterpreted as the compression state of a continuous medium. This adjustment changes the conceptual view of what

the equations represent, while leaving the numerical outcomes consistent with established tests.

The distinction is therefore one of interpretation rather than prediction. The curvature described by the Einstein tensor remains the same, but the mechanism assigned to it is shifted from an abstraction to a physical process. This approach maintains compatibility with observation while providing a different underlying description of what the mathematics refers to.

### 3.3 Clarifying Points That General Relativity Left Open

Changing the interpretation of the source term in Doctor Einstein's equations from an abstract quantity to the physical compression state of a continuous medium does not alter any of the verified predictions. However, this change provides clear explanations for several elements that originally remained without a physical mechanism. The reinterpretation gives sense to aspects of the framework that general relativity accepted mathematically but did not resolve structurally.

The following points become physically coherent under the medium-based view:

1. **Curvature as a physical effect.** The geometry of spacetime gains a mechanical basis, arising from gradients in compression rather than from a purely abstract relation.
2. **The behaviour of the vacuum.** The vacuum is no longer treated as a region without properties; it becomes a continuous medium capable of supporting tension, waves, and limits.
3. **Propagation limits.** The finite speed of light acquires a physical cause, determined by the stiffness and response of the medium, rather than being imposed as a postulate.
4. **The absence of singularities.** Traditional general relativity permits unbounded curvature. A compressible medium does not. The medium provides natural density limits that remove the need for singular behaviour.
5. **Black hole structure.** Instead of a geometric discontinuity, a black hole becomes a state of maximum compression, consistent with continuous physical behaviour.
6. **Gravitational attraction.** Attraction arises from converging regions of the medium, avoiding the need for an abstract notion of curvature acting without mechanism.
7. **Repulsion and expansion.** Decompression offers a physical basis for repulsive behaviour and large-scale expansion, without introducing new fields for that purpose.

8. **Wave propagation.** Gravitational and electromagnetic waves can be understood as structural responses of the medium, giving them a clear physical carrier.
9. **Vacuum energy behaviour.** The medium model provides a structured way to interpret vacuum pressure and the behaviour commonly attributed to dark energy.
10. **Large-scale cosmological expansion.** Decompression of the medium supplies a physical mechanism for expansion, replacing the need to introduce it purely through geometric assumptions.
11. **Origin of repulsive effects.** Diverging regions of the medium generate repulsive behaviour without the need for additional fields or exotic components.
12. **Propagation of gravitational waves.** Compression disturbances travel as waves in the medium, providing a physical carrier for phenomena observed by LIGO and other detectors.
13. **Why gravitational waves travel at the speed of light.** The propagation limit is determined by the stiffness and response rate of the medium, naturally matching the constant  $c$ .
14. **Gravitational time dilation.** Changes in local compression affect the response rate of the medium, giving a mechanical basis for the slowing of clocks in stronger fields.
15. **Absence of infinite curvature.** A compressible medium cannot support unbounded density or tension, providing natural cutoffs that eliminate singularities.
16. **Structure of black hole interiors.** The interior becomes a region of maximum compression rather than a geometric discontinuity, maintaining continuity of physical behaviour.
17. **Stability of event horizons.** The horizon corresponds to a boundary in the medium where compression saturates, producing a stable surface without requiring a singular point.
18. **Evaporation and energy leakage.** Gradual decompression at the boundary provides a mechanism compatible with long-term energy loss, replacing abstract interpretations.
19. **Matter cohesion.** Attraction between particles and stability of condensed phases follow from converging regions of the medium rather than from independent forces.
20. **Surface tension and boundary formation.** Boundaries form where compression gradients stabilize, offering a unified description of droplets, films, and curved interfaces.

21. **Non-uniform thermal behaviour.** Heating and cooling affect the medium by altering local compression rather than acting as standalone causes, explaining materials that expand on cooling or compress under heat.
22. **Why electromagnetic waves require no material carrier.** The medium itself functions as the carrier, eliminating the older assumption that only rigid substances can support wave propagation.
23. **Constraint on maximum propagation speed.** The medium's response rate sets a universal limit, giving a physical origin for the constancy and value of  $c$ .
24. **Relation between pressure and curvature.** Pressure contributes directly to compression, restoring the physical meaning behind its appearance in gravitational equations.
25. **Cosmic flatness.** Balanced compression and decompression across large scales produce near-flat geometry without requiring early-universe fine tuning.
26. **Horizon behaviour in cosmology.** Medium structure provides a continuous link between regions, removing the need for inflation-like mechanisms to explain uniformity.
27. **Vacuum fluctuations as medium responses.** Fluctuations become local variations in compression rather than abstract probabilistic events.
28. **Dark matter-like effects.** Regions with stable compression gradients can reproduce rotation curve behaviour without requiring new particle species.
29. **Unified behaviour of forces.** Interactions emerge from how the medium compresses or decompresses, reducing the number of independent mechanisms required.
30. **Consistency of energy transfer.** All transfers occur through compression change, aligning with the principles reflected in the FCI work.
31. **Continuity of the vacuum.** The medium cannot vanish to a zero state, eliminating gaps between "empty" and "filled" regions and maintaining structural continuity.
32. **Boundaries between phases.** Phase transitions become reorganisations of compression patterns rather than discontinuities imposed by separate laws.
33. **Interpretation of inertial mass.** Resistance to acceleration follows from how firmly a region of the medium is compressed, giving a mechanical meaning to inertia.

34. **Momentum conservation.** Interaction between compressed and decompressed regions provides a physical basis for momentum transfer in closed and open systems.
35. **Behaviour near dense astrophysical objects.** Strong compression gradients explain lensing, time dilation, and orbital dynamics without invoking unobservable singular structures.
36. **Finite energy density of the early universe.** A compressible medium prevents divergence of density, replacing the classical singular Big Bang with a high-compression state.
37. **Large-scale structure formation.** Compression-driven attraction and decompression-driven separation support the emergence of filaments, voids, and cluster boundaries.
38. **Mechanical meaning of curvature.** Curvature becomes the structural response of the medium to compression gradients, giving spacetime geometry a clear physical basis.

### 3.4 Why General Relativity Remains Mechanically Incomplete

The interpretive adjustment introduced in this document does not modify any prediction of Doctor Einstein’s formulation. However, it becomes necessary to clarify why a reinterpretation is required at all. General relativity achieves an elegant and internally consistent description of curvature, but it does not provide the physical mechanism responsible for the behaviour that curvature represents. This omission does not affect the accuracy of the theory’s predictions, yet it leaves several foundational points without a mechanical basis.

General relativity explains how spacetime curves in response to the stress–energy tensor, but it does not describe what spacetime *is*. The equations specify the geometry, not the substance. In this form, curvature is treated as a relation, not as the deformation of a real medium. The absence of a substrate leads to several consequences that remain conceptually unresolved:

1. **Lack of a compressible entity.** The framework predicts behaviours that resemble compression and deformation, but assigns them to geometry rather than to a physical structure. This leaves unanswered what quantity is being compressed or stretched.
2. **Origin of spherical collapse.** Under general relativity, spherical symmetry emerges from the mathematical form of the equations, yet no physical process explains why collapse tends toward radial uniformity or why the preferred configuration distributes tension equally.
3. **Dependence on the stress–energy tensor.** The tensor determines curvature, but its contents are taken as given. General relativity does not explain why pressure, density, and internal stresses influence curvature, only that they do.

4. **Singular behaviour at high density.** In strong-field regimes, the equations permit unbounded curvature and infinite density. These singular points indicate the breakdown of the theory’s applicability, suggesting the absence of a regulating mechanism that prevents indefinite compression.
5. **Incompatibility with the vacuum of quantum field theory.** Modern physics recognises that the vacuum possesses structure, fluctuations, and energy density. Treating spacetime as empty—a zero state—conflicts with this understanding. The vacuum cannot be both the foundation of field theory and a region without physical properties.
6. **Absence of a mechanism for expansion and repulsion.** The accelerated expansion of the universe is incorporated through additional terms such as a cosmological constant, but no mechanical process describes what expands or why repulsive behaviour arises at large scales.

These points do not undermine the predictive success of general relativity, but they show that the theory provides a geometric description rather than a physical mechanism. For this reason, the reinterpretation presented in Compressodynamics does not attempt to alter the structure of the Einstein equations. Instead, it supplies the missing mechanical layer: the medium is treated as a continuous, compressible entity whose state determines curvature. The stress–energy tensor is replaced by the compression–decompression tensor  $C_{\mu\nu}$ , and the geometry becomes the structural response of the medium itself. This resolves the conceptual gaps listed above while remaining compatible with all verified predictions of Doctor Einstein’s work

### 3.5 The Flaw in the Historical Rejection: The Case of a Relativistic Medium

The historical dismissal of a physical medium was predicated on a specific, and ultimately limited, assumption: that any such medium must behave as a rigid, stationary substance with a preferred rest frame, thereby generating a detectable “wind” or absolute reference for motion. This assumption, while valid for the nineteenth-century conception of the luminiferous aether, does not constitute a necessary condition for a physical substrate in general.

A simple analogy illustrates this critical point: consider a fish submerged in a vast, calm body of water. The water is unequivocally a physical medium, it transmits pressure, supports wave propagation, and possesses density and compressibility. Yet, the fish cannot perform any self-contained experiment to detect its own uniform motion relative to the water. There is no “water wind” to measure because the medium is dynamically coupled to the observer within it. The medium’s reality is confirmed not by measuring motion through it, but by observing its effects: wave propagation, pressure gradients, and buoyancy forces.

The compression medium proposed in this work is analogous to this. It is not the static, mechanical aether of the nineteenth century, but a dynamic,

relativistic entity whose local state is determined by the energy and matter within it. The null result of the Michelson-Morley experiment does not rule out a medium *in principle*; it only rules out a medium with a *preferred global rest frame*. Our formulation explicitly constructs a medium free of this constraint, where the invariant speed  $c$  emerges naturally as the characteristic propagation speed of compression disturbances, analogous to the speed of sound in a fluid.

This distinction resolves the apparent historical conflict. The rejection a century ago was of a specific, mechanically inadequate model of a medium, not of the underlying concept itself. A relativistic, compressible medium, consistent with all symmetry requirements, remains a viable and physically coherent possibility.

## 4 Spherical Geometry as a Natural Outcome of Compression

When a continuous medium undergoes uniform compression, the resulting configuration tends toward a spherical form. This does not require any added assumptions or external rules; it follows directly from how compression distributes tension and curvature in the simplest possible way.

A sphere is the only shape in which the surface experiences equal curvature in all directions. Under compression, the medium seeks a configuration that minimises internal gradients and distributes the load evenly. The spherical shape achieves this with the least structural inequality. No other geometry offers an equal distribution of compression forces across all directions.

This explains why high-compression systems in nature consistently adopt spherical configurations. Examples include droplets, gas spheres, stars, and the exterior boundary of black holes. Each case reflects the same structural principle: compression drives the system toward the geometry with the most uniform internal response.

The same reasoning extends to orbital paths and field behaviour. Once the medium favours radial symmetry under compression, the resulting structures and trajectories inherit this symmetry. Curvature, flow, and boundary formation all organise themselves around the same central rule: a spherical configuration reduces internal differential stress.

In this sense, the behaviour is not hidden or abstract. It is visible in common physical systems and remains consistent across scales. The preferred geometry appears directly in front of us, in everyday phenomena as well as in astrophysical structures. It is the natural consequence of how a compressible medium responds to uniform pressure.

### 4.1 Spherical Pathways in Natural Structures

Although the underlying medium cannot be observed directly, its influence can be inferred from the organisation of natural structures. When examining the development and complexity of biological species, certain geometric tendencies are consistently present. Many structural features follow spherical or near-spherical

pathways, reflecting the same mechanical principles observed in compressible media outside biology.

Examples include:

- the formation of cells, in which membrane tension produces near-spherical boundaries;
- ocular structures, where pressure uniformity leads to spherical form;
- vascular branching patterns that align with radial distribution laws;
- embryonic development stages that progress through rounded and radially symmetric configurations;
- organ compartments shaped by internal pressure equalisation.

These occurrences are not isolated or incidental. They reflect a general rule: systems subject to uniform or internally balanced forces tend toward spherical or radially organised arrangements, because these geometries minimise differential stress. The consistency of these patterns across biological and non-biological systems suggests a common underlying principle linked to how compression distributes over continuous material.

## 4.2 Interpretation of Soft Magnetism

The term “soft magnetism” was introduced as a descriptive analogy for the behaviour of cohesive regions within the medium. The name does not imply that magnetic forces are involved. Instead, it refers to the observation that certain regions behave as if they possess an alignment tendency similar to that of soft magnetic materials.

In physical terms, the intended meaning is the following:

- regions under compression tend to align their internal structure;
- this alignment increases cohesion and stabilises boundaries;
- neighbouring regions with compatible alignment merge more easily;
- regions with incompatible alignment separate or form distinct domains.

These behaviours are analogous to, but not dependent on, magnetic processes. The analogy serves only as a convenient reference for describing how the medium becomes organised under compression and how cohesive boundaries form. The actual mechanism is mechanical rather than electromagnetic: alignment reflects the way a compressible medium stabilises itself when subjected to internal or external pressure.

This interpretation connects naturally with spherical boundary formation, because alignment under compression encourages configurations that distribute tension evenly. As a result, spherical or radially coordinated structures appear across many systems, from simple droplets to complex biological forms.

### 4.3 Liquids, Compression, and Spherical Pathways

If compression is a fundamental behaviour of the medium, then liquids provide a direct physical example of how matter responds under moderate and uniform compression. Liquids accommodate internal pressure by distributing it evenly, which naturally leads to spherical boundary formation in unconstrained conditions. The spherical form minimises internal stress and allows the system to stabilise with the least structural imbalance.

Liquids also demonstrate another important property: they enable motion and wave propagation with relatively low resistance. Because the internal structure of a liquid is not fixed, compression and decompression can move through it efficiently. Waves, pressure fronts, and boundary adjustments can travel smoothly without the constraints that rigid structures impose.

These characteristics follow directly from the presence of compression in the medium. A spherical configuration reduces differential forces, and the fluid state supports motion and oscillation with minimal internal obstruction. This combination makes liquids one of the clearest demonstrations of how a compressible medium organises itself and how dynamic behaviour is facilitated within it.

### 4.4 Liquids as the Universal Medium of Living Systems

Across all known forms of life, liquids play a central role in sustaining structure and enabling functional behaviour. Whether in simple organisms or complex multicellular systems, a fluid phase is required to permit motion, transport, and the propagation of internal changes.

Every living system relies on fluid environments to carry out essential processes:

- cellular cytoplasm, which maintains internal pressure and allows mechanical and chemical waves to propagate;
- extracellular fluids, which enable transport and structural adjustment between cells;
- blood, lymph, sap, or analogous transport media in larger organisms;
- membrane-bound liquid phases that preserve chemical gradients.

Even organisms that appear structurally dry, such as spores, seeds, or certain extremophiles, retain internal liquid components or rehydrate rapidly when conditions allow. These systems rely on the ability to restore a liquid state in order to resume wave-like behaviour necessary for metabolic activity, signaling, and mechanical responsiveness.

The consistent presence of liquids across all living systems is not incidental. It follows from the fact that liquids support the propagation of pressure and structural waves with minimal internal resistance. This capacity is necessary for coordinated behaviour, for maintaining gradients, and for allowing internal compression changes to translate into functional outcomes. Life depends on the

ability to support and sustain these wave-like processes, and liquids provide the most effective environment for them.

## 5 Thermodynamics in Observer and Non-Observer Terms

Thermodynamics can be described in two distinct ways, depending on whether the focus is on observation or on the underlying physical process.

From the observer pathway, thermodynamics is expressed through the familiar concepts of heat and cold. These terms describe the measurable effect that temperature differences have on systems, and how those differences influence behaviour in a practical sense.

From the non-observer pathway, the same processes reduce to a simpler and more fundamental description: energy entering or leaving a region. Heating corresponds to energy moving into a system, and cooling corresponds to energy moving out of it. This perspective treats thermodynamic behaviour as a change in the internal state of the medium rather than as a change in perception.

Both descriptions refer to the same phenomena, but the non-observer pathway reveals the mechanical basis behind them. Heat and cold are observational labels; the underlying physical action is the transfer of energy in or out of a continuously changing medium.

## 6 The Duality Rule

To interpret thermodynamic behaviour within the medium, it becomes necessary to introduce a guiding principle referred to here as the *duality rule*. This rule states that any process that alters the state of the medium can produce multiple possible responses, depending on the structural conditions present.

In the observer description, heat and cold are treated as opposites. From the non-observer perspective, both represent energy transfer, and their effects on compression depend on how the medium responds. Heat may increase compression when expansion is constrained, but it may also cause decompression in systems where internal bonding relaxes. Cold may increase compression in materials that contract upon cooling, while causing decompression in those that expand when structural spacing increases.

The duality rule is expressed as:

A single action may lead to several responses, but at minimum it separates into opposing directions.

Its operation can be summarised as follows:

- heat can increase compression;
- heat can decrease compression;

- cold can increase compression;
- cold can decrease compression;
- additional intermediate behaviours may occur in complex materials.

The rule is not limited to two outcomes. The number of responses may exceed two when the medium has multiple internal states or structural pathways. However, even in such cases, the behaviour always divides into at least two directions: one that increases compression and one that decreases it. All other outcomes fall between these directions within a broader spectrum.

This structure appears consistently in physical systems, indicating that the duality rule reflects the inherent behaviour of the medium rather than an observational classification.

## 6.1 Examples of Duality in Physical Systems

The duality rule appears across many areas of physics and natural behaviour. In each case, a single action can produce multiple outcomes, but the minimum division always separates into two fundamental directions. The following examples illustrate this structure:

1. Heating can increase compression.
2. Heating can decrease compression.
3. Cooling can increase compression.
4. Cooling can decrease compression.
5. Pressure can induce solidification in some materials.
6. Pressure can induce melting in others.
7. Mechanical stress can strengthen a material.
8. Mechanical stress can fracture the same material.
9. Vibration can organise particulate systems.
10. Vibration can disperse them.
11. Rotation can stabilise a structure.
12. Rotation can destabilise it when excessive.
13. Electrical charge can attract matter.
14. Electrical charge can repel matter.
15. Fluid flow can increase structural cohesion.

16. Fluid flow can erode or separate structures.
17. Gravity can cause aggregation of material.
18. Gravity can induce collapse and fragmentation under extremes.
19. Magnetic fields can align domains.
20. Magnetic fields can randomise domains when reversed.
21. Expansion of a material can increase density (in porous systems).
22. Expansion can decrease density in typical solids and liquids.
23. Contraction can strengthen internal bonding.
24. Contraction can weaken bonding when lattice mismatch occurs.
25. Wave input can amplify internal modes.
26. Wave input can dampen modes through destructive interaction.
27. Chemical concentration can accelerate reactions.
28. Chemical concentration can inhibit reactions through saturation.
29. External tension can stabilise membranes.
30. External tension can rupture membranes.
31. Fluid confinement can increase ordering.
32. Fluid confinement can increase disorder under shear.

Although many of these processes admit several intermediate or complex responses, the minimum division always separates along two opposing directions: one that increases compression and one that decreases it. All additional behaviours fall between these limits within a broader spectrum determined by the structure of the medium.

## 7 Compression and Decompression Across Physical Systems

The following examples illustrate how the duality rule appears in physical systems. Each action can lead to multiple outcomes, but the minimum split always separates into an increase or a decrease in compression. All other intermediate behaviours fall between these two directions.

1. Heating increases compression when expansion is prevented (compression  $\uparrow$ ).

2. Heating decreases compression when the material expands freely (compression ↓).
3. Cooling increases compression when the material contracts (compression ↑).
4. Cooling decreases compression in materials that expand upon cooling (compression ↓).
5. Pressure induces solidification in certain substances (compression ↑).
6. Pressure induces melting in systems where internal spacing increases (compression ↓).
7. Mechanical stress strengthens some materials through densification (compression ↑).
8. Mechanical stress fractures materials when structure separates (compression ↓).
9. Vibration compacts granular systems when particles settle (compression ↑).
10. Vibration disperses particles at higher amplitudes (compression ↓).
11. Rotation stabilises structures through radial confinement (compression ↑).
12. Rotation destabilises structures when centrifugal forces dominate (compression ↓).
13. Electric charge attracts opposite charges (compression ↑).
14. Electric charge repels like charges (compression ↓).
15. Fluid flow aligns or compacts suspended structures (compression ↑).
16. Fluid flow erodes boundaries or spreads material (compression ↓).
17. Gravity aggregates matter through convergence (compression ↑).
18. Gravity induces fragmentation in high-energy collisions (compression ↓).
19. Magnetic fields align domains (compression ↑).
20. Magnetic fields disorder domains when reversed or heated (compression ↓).
21. Expansion of porous materials can increase internal density (compression ↑).
22. Expansion of standard solids reduces density (compression ↓).
23. Contraction strengthens bonding when spacing decreases (compression ↑).

24. Contraction weakens bonding when structure is forced out of alignment (compression ↓).
25. Wave input amplifies modes under constructive interaction (compression ↑).
26. Wave input dampens modes under destructive interaction (compression ↓).
27. Increased chemical concentration accelerates reactions through tighter interaction (compression ↑).
28. Increased concentration inhibits reactions when saturation limits contact (compression ↓).
29. External tension stabilises a membrane when it draws structure together (compression ↑).
30. External tension ruptures a membrane when it separates structure (compression ↓).
31. Fluid confinement orders molecular arrangements (compression ↑).
32. Fluid confinement increases disorder when shear dominates (compression ↓).

These examples show that while many systems can exhibit more than two responses, the foundational division always resolves into two directions: an increase in compression or a decrease in compression. Any additional outcomes occupy intermediate positions along this spectrum.

## 7.1 From Doctor Einstein's Equation to the Compression Form

Doctor Einstein's field equation relates spacetime curvature to the stress–energy tensor:

$$\boxed{G_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}} \quad (1)$$

where  $G_{\mu\nu}$  is the Einstein tensor,  $G$  is the gravitational constant,  $c$  is the speed of light, and  $T_{\mu\nu}$  is the stress–energy tensor.

For a continuous medium treated as a relativistic fluid, the usual form of  $T_{\mu\nu}$  is

$$T_{\mu\nu} = \left(\rho + \frac{p}{c^2}\right) u_\mu u_\nu + p g_{\mu\nu} + (\text{viscous and shear terms}), \quad (2)$$

where  $\rho$  is the energy density,  $p$  is the pressure, and  $u^\mu$  is the four–velocity of the fluid.

In Compressodynamics, the same geometric structure is retained, but the source term is reinterpreted in terms of compression and decompression of a

continuous medium. The role of  $T_{\mu\nu}$  is transferred to a *compression–decompression tensor*  $C_{\mu\nu}$ , and the field equation is written as

$$\boxed{G_{\mu\nu} = \lambda C_{\mu\nu}} \quad (3)$$

with  $\lambda$  a coupling constant chosen to reproduce the standard limit,  $\lambda = 8\pi G/c^4$ , when required.

The medium is described by a four–velocity  $u^\mu$  satisfying

$$u^\mu u_\mu = -1, \quad h_{\mu\nu} = g_{\mu\nu} + u_\mu u_\nu, \quad (4)$$

where  $h_{\mu\nu}$  is the spatial projector orthogonal to  $u^\mu$ . The state of compression is encoded in

$$\theta = \nabla_\mu u^\mu, \quad \mathcal{C} = -\theta, \quad (5)$$

so that  $\mathcal{C} > 0$  corresponds to compression and  $\mathcal{C} < 0$  to decompression.

The compression–decompression tensor is then written as

$$\boxed{C_{\mu\nu} = \rho_c u_\mu u_\nu + p_c h_{\mu\nu} + 2\eta \sigma_{\mu\nu} + \zeta \theta h_{\mu\nu}} \quad (6)$$

where

- $\rho_c$  is the compression density,
- $p_c$  is the compression pressure,
- $\eta$  and  $\zeta$  are shear and bulk response coefficients,
- $\sigma_{\mu\nu}$  is the shear tensor,
- $\theta$  is the expansion/compression scalar defined above.

To separate matter contributions from decompression effects, the compression pressure is decomposed as

$$p_c = p_c^{(\text{matter})} + p_\Phi, \quad p_\Phi = -\alpha \Phi, \quad (7)$$

where  $\Phi$  is a decompression field and  $\alpha$  is a constant. Positive  $\Phi$  reduces effective compression pressure and therefore favours local decompression.

The field  $\Phi$  obeys a dynamical equation coupled to the compression state through  $\theta$ :

$$\boxed{\square\Phi - \frac{dV}{d\Phi} = \kappa \theta} \quad (8)$$

where  $V(\Phi)$  is a potential and  $\kappa$  is a coupling constant. Regions with  $\theta > 0$  (net expansion, decompression) act as sources for  $\Phi$ , while regions with  $\theta < 0$  (net compression) suppress it.

Equations (3), (6), (7), and (8) together represent the transformed version of Doctor Einstein’s field equation, in which the source of curvature is written explicitly in terms of compression and decompression of the medium instead of the traditional stress–energy tensor.

## 7.2 Compression From External Energetic Boundaries

If the medium contains adjacent regions with different vacuum energies or boundary conditions, the interface between these regions experiences a pressure difference. In physical terms, vacuum energy acts as a form of pressure, so a mismatch across a boundary produces a mechanical effect analogous to pressure differences in ordinary continuous media.

Let a region with vacuum pressure  $p_{\text{in}}$  be surrounded by other domains with pressure  $p_{\text{out}}$ . Two basic outcomes follow:

- If  $p_{\text{out}} > p_{\text{in}}$ , the external regions exert an inward force on the boundary. This results in a net compression of the interior region.
- If  $p_{\text{out}} < p_{\text{in}}$ , the interior region exerts an outward force on the boundary. This leads to decompression or expansion.

These outcomes require no additional assumptions beyond established field theory and general relativity. Differences in vacuum pressure across a boundary naturally produce curvature, tension, or displacement of that boundary. The same mechanism appears in models involving domain walls, phase boundaries, and vacuum transitions.

In this context, compression arises because neighbouring domains with higher energetic boundaries act mechanically on our region, forcing its medium inward. Decompression arises when neighbouring domains have lower energetic boundaries and the internal pressure exceeds the external one.

These effects provide a physically consistent means by which large-scale compression and decompression may occur without requiring isolated or self-contained assumptions about the medium.

## 7.3 Limits of Observational Access

Even if neighbouring domains with different energetic boundaries exist, it is not guaranteed that present observational capabilities are sufficient to detect them. Measurements in cosmology are constrained by the observable horizon, limited signal strength, and the fact that observational data must be interpreted through indirect effects rather than direct inspection of remote regions.

Differences in vacuum pressure or boundary conditions may influence the curvature or expansion behaviour of our region without producing signatures that can be isolated with current instruments. Many effects of this type would appear only as broad cosmological trends or could be indistinguishable from other contributions such as dark energy or large-scale structure formation.

Because observations are restricted to signals that reach us from within the causal horizon, any structure beyond this boundary remains inaccessible. As a result, external influences acting through pressure differences at the boundary of our region may be present while remaining observationally silent.

This limitation is not theoretical but practical. The absence of detection does not imply the absence of such structures; it reflects the boundaries of current measurement precision and the inherent restrictions of observational geometry.

## 8 Dynamics of the Compression Medium

The reinterpretation of curvature in terms of compression and decompression suggests that spacetime may be viewed as a continuous medium capable of supporting dynamic behaviour. While the mathematical structure of general relativity remains intact, the physical interpretation may admit a mechanical layer in which compression disturbances propagate, oscillate, and interact with curvature. The following subsections describe one possible way in which such a medium could behave.

### 8.1 Propagation of Compression Disturbances

If the medium possesses finite stiffness and compressibility, then regions in which the scalar compression state changes may generate propagating disturbances. Let  $C = -\theta$  denote the local compression, with small perturbations described by  $\delta C$ . A linear approximation around a background state may lead to a wave-like evolution equation of the form

$$\square \delta C \approx \mathcal{F}(\rho_c, p_c, \eta, \zeta), \quad (9)$$

where  $\rho_c$  and  $p_c$  represent effective compression density and pressure, and  $\eta$  and  $\zeta$  represent possible shear and bulk response coefficients. This structure does not claim a particular microscopic model, but illustrates that a compressible medium could, in principle, support wave propagation in a covariant manner.

### 8.2 Oscillation as Release of Excess Compression

If the medium resists unlimited compression, then any region compressed beyond its preferred equilibrium state might develop restoring gradients. Once the compressive forces are relaxed, the region may oscillate around its equilibrium. This behaviour is typical of compressible systems in classical physics and could provide a possible interpretation of oscillatory phenomena in gravitational systems or in regions where curvature evolves dynamically.

### 8.3 Upper Limit on Propagation Speed

A medium with finite response time may naturally impose an upper limit on the speed at which compression disturbances propagate. If this interpretation is valid, the invariant speed  $c$  may be understood as the maximum rate at which the medium adjusts to changes in compression. This does not alter the structure of relativity but offers a possible physical explanation for why all massless signals share the same propagation speed.

### 8.4 Relation Between Compression and Curvature

If curvature reflects the structural response of the medium to spatial variations in compression, then propagating disturbances in  $C$  would temporarily modify

curvature along their trajectory. This picture could provide a mechanical interpretation of how gravitational waves arise: as moving regions of altered compression influencing the local geometry. While this remains a possible interpretation, the geometric equations themselves continue to govern the dynamics.

## 8.5 Stability of Spherical Configurations

Earlier sections described how systems under uniform compression tend to adopt spherical geometries. From a dynamic perspective, this stability may emerge because nonspherical distortions generate restoring compression gradients. Such gradients could launch waves that redistribute tension until a more symmetric state is achieved. This offers one possible mechanical interpretation for the prevalence of spherical structures in nature.

# 9 Local and Global Compression

The behaviour of the medium may differ significantly when examined at local and cosmological scales. If compression and decompression describe the state of a continuous medium, then it becomes possible that distinct regions settle into different regimes depending on their internal energy, boundary conditions, and background pressure. This distinction may clarify why local structures remain stable and spherical while the universe as a whole appears to undergo large-scale decompression.

## 9.1 Local Stability Through Compression Balance

A local region may reach a stable configuration when the inward and outward components of compression reach equilibrium. In such cases, the medium could be sufficiently compressed to prevent further contraction, yet not so compressed that restoring gradients destabilise the structure. Stars, bound systems, and molecular arrangements may be viewed in this sense: they occupy regions where compression has balanced with internal response forces, resulting in surfaces that minimise differential stress and therefore favour near-spherical configurations.

Within this interpretation, the local medium might behave as a confined domain whose boundaries are maintained by persistent compression gradients. These gradients could serve as a form of structural tension that holds the system together independently of any large-scale decompression occurring elsewhere.

## 9.2 Resistance of Bound Systems to Global Decompression

If the medium allows both compression and decompression, then regions with sufficiently high compression density may resist global changes in the background state. A local system could remain effectively insulated from large-scale behaviour when the internal compression exceeds any external decompressive influence. This does not require additional forces; it follows from the possibility that compression gradients may dominate over weak, uniform decompression fields.

In such a scenario, cosmic expansion need not influence the internal structure of bound systems. Their equilibrium states may be governed entirely by local compression dynamics, allowing them to remain stable even as the surrounding medium relaxes or decompresses on cosmological scales.

### 9.3 Coexistence of Opposing Regimes

The presence of both local compression and large-scale decompression may be understood as the outcome of a medium that supports multiple regimes simultaneously. Regions with high internal compression naturally evolve toward spherical and cohesive configurations, while extended regions of lower compression may evolve toward expansion or reduced curvature.

This coexistence suggests that compression and decompression do not represent mutually exclusive states of the medium, but instead describe different positions along a continuous range of possible behaviours. As a consequence, the medium may support stable, highly compressed structures embedded within a background that tends toward decompression at large scales.

### 9.4 Boundary Effects and Regional Independence

If the medium admits boundaries between regions of differing compression density, then transitions between regimes may be regulated by pressure differences. Local structures might reside within domains where compression density is relatively high, while the surrounding large-scale environment may exist in a decompressive regime. Such boundaries do not need to be sharply defined; gradual transitions could allow regions to evolve largely independently.

This could explain why local dynamics appear governed by familiar compressive behaviour, while cosmological observations indicate large-scale expansion. Different regions may simply occupy different points within the medium's broader range of compression states, each evolving according to internal conditions and the influence of surrounding gradients.

## 10 Constitutive Properties of the Medium

The behaviour of a continuous medium is determined not only by its geometric or dynamic equations but also by the internal relations that connect compression, pressure, flow, and deformation. If the medium underlying curvature possesses physical structure, then it may be characterised by constitutive properties that govern how it responds to changes in compression. These properties need not be fixed universally; they may vary across regimes, densities, or large-scale domains. The purpose of this section is to outline possible constitutive behaviours without assuming a specific microscopic model.

## 10.1 Effective Compression Density and Pressure

A continuous medium may be described by an effective compression density  $\rho_c$  and a corresponding compression pressure  $p_c$ . These quantities need not coincide with classical energy density or thermodynamic pressure, although they may share formal similarities. Instead, they may represent how the medium resists or accommodates changes in its internal state. In regions where  $\rho_c$  is high, the medium may behave as if stiff or resistant to deformation, whereas regions with lower  $\rho_c$  may permit more substantial changes in  $C$ .

The relation between  $\rho_c$  and  $p_c$  could follow an equation of state, possibly of the form

$$p_c = p_c(\rho_c, C), \quad (10)$$

where  $C$  influences how the medium responds locally to compression or decompression. This equation need not be linear; more complex behaviour may arise in strongly compressed regions or near boundaries between domains.

## 10.2 Shear and Bulk Response

If the medium can sustain both volumetric and shear deformations, then its response may involve bulk and shear coefficients. The bulk coefficient may govern how the medium resists uniform compression, while the shear coefficient may determine how it responds to distortional deformations. These responses may play a role in stabilising structures and distributing stresses.

A general form for the medium's response could include terms such as

$$\sigma_{\mu\nu} = \eta S_{\mu\nu}, \quad \theta h_{\mu\nu} = \zeta B_{\mu\nu}, \quad (11)$$

where  $\eta$  and  $\zeta$  represent shear and bulk responses, and  $S_{\mu\nu}$  and  $B_{\mu\nu}$  encode the corresponding deformation modes. These relations do not assume a specific microscopic interpretation; they simply allow for the possibility that the medium exhibits structured internal behaviour.

## 10.3 Compressibility and Response Time

The finite response of the medium may be reflected in an effective compressibility. A highly compressible region could undergo significant deformation under small gradients in  $C$ , whereas a weakly compressible region may respond slowly or minimally. The response time associated with such changes could play a role in limiting the propagation speed of compression disturbances.

If the propagation speed of disturbances approaches  $c$ , this may indicate that the medium possesses an effective stiffness or inertia that limits how quickly compression adjustments occur. This behaviour would be consistent with relativistic propagation constraints without requiring the introduction of a rigid structure.

## 10.4 Nonlinear Behaviour at High Compression

Regions experiencing high compression may exhibit nonlinear constitutive behaviour. Instead of responding proportionally to changes in  $C$ , the medium may undergo threshold effects, saturation, or stiffening. Such behaviour could prevent unbounded compression and may contribute to the avoidance of singular configurations.

This nonlinear response could also influence the evolution of highly compressed systems, potentially affecting how oscillations develop or how boundaries form between regions of differing compression density.

## 10.5 Variation Across Domains

If the medium admits multiple domains or regions with differing compression states, then its constitutive properties may vary across these domains. A region with low background compression density might exhibit different stiffness, response time, or shear behaviour compared to a region where compression is high. These differences may influence how waves propagate, how structures form, and how boundaries evolve.

Such variation does not require fine-tuning; it may arise naturally if the medium can occupy different stable or metastable states across large scales.

# 11 Conclusion

The framework presented here develops a possible mechanical interpretation of curvature, compression, and expansion without altering the established mathematical structure of general relativity. The medium is treated as a continuous entity capable of supporting compression and decompression, and the stress–energy content is reinterpreted as a compression state rather than an abstract source term. This view remains compatible with all verified predictions because the governing equations are unchanged; only the physical interpretation has been shifted.

The behaviour described throughout this document is intended as a consistent possibility rather than a definitive model. It suggests that many features of gravitation, wave propagation, spherical symmetry, boundary formation, and large-scale evolution may arise naturally from the response of a compressible medium. This interpretation could offer a clearer mechanical account of several phenomena that general relativity leaves without explicit mechanism, such as the origin of curvature, the stability of spherical structures, the coexistence of local compression with global expansion, and the existence of propagation limits.

Although this framework proposes a continuous medium, it does not reintroduce the rigid structures once considered incompatible with relativity. Instead, it presents a compressible, relativistic continuum that may coexist with all symmetry requirements of modern physics. Whether such a medium exists, or whether its constitutive behaviour can be derived from a deeper microscopic model, remains an open question.

Several existing theories explore ideas that bear some resemblance to the interpretation offered here. Scalar-field models in cosmology, relativistic hydrodynamics, and approaches that treat spacetime as emergent from underlying degrees of freedom share certain conceptual similarities. However, none of them arrive at precisely the same formulation developed in this document, nor do they recast the Einstein equations explicitly in terms of compression and decompression of a continuous medium. The alignment is partial rather than complete, indicating that this framework occupies a distinct conceptual space.

The development presented here is not intended to be final. It may be extended or refined in several directions, including the mathematical structure of the medium, the behaviour of boundaries between regions of differing compression density, and the evolution of large-scale decompression states. The framework is deliberately open, allowing additional work to explore whether its principles can be connected to quantum descriptions, cosmological observations, or more detailed modelling of dynamic processes. What has been provided is a coherent starting point: a perspective that fits existing data and equations while offering a new way to interpret the physical meaning behind them.

## Author's Reflection

The development of this framework did not arise from a single idea but from a sequence of questions that gradually converged toward a common structure. The earliest work emphasised conservation of physical content and observer-dependent pathways, followed by attempts to describe systems through resonance, structure, and non-observer behaviour. Each line of inquiry introduced a partial element of what now appears, in retrospect, as components of a single underlying concept.

Throughout this progression, the notion of a medium repeatedly re-emerged. In the early history of relativity, Doctor Einstein himself considered the possibility that a continuous medium might be required, while later developments moved away from such interpretations for historical reasons rather than necessity. Revisiting these ideas with modern understanding suggested that a medium could exist without conflicting with the symmetries of relativity or the mathematical form of its equations.

What is notable is that the reinterpretation presented here does not alter the mathematical structure of general relativity. Normally, when the physical meaning of a fundamental equation is changed, the predictive framework must be modified as well. In this case, the opposite occurred: the geometric equations operate exactly as before, while the compression–decompression interpretation provides a possible mechanical layer that fits naturally over them. The continuous medium described here may offer a physical interpretation without requiring any adjustment to the underlying differential structure.

It is unusual for a reinterpretation of a highly constrained mathematical framework to maintain full compatibility with existing predictions while introducing a new conceptual foundation. Yet that appears to be the case here. The reasoning developed through prior work, combined with a return to the idea of a continuous medium, led to an interpretation that remains mathematically

consistent and aligns with observations, despite differing from the standard view. Whether this perspective ultimately proves to be the correct physical description remains open, but the coherence of the structure suggests that the approach may merit further exploration.