Non-parametric modeling of microbiome dynamics

with continuous mean-reversible stochastic processes

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Background & Motivation

- Cross-sectional cohorts dominate population-level studies of the human microbiome, but universal patters of microbial community dynamics are less well understood.
- Longitudinal data sets are now rapidly accumulating and there is demand for robust statistical tools that can take into account the low sample sizes, sparse irregular observations, and high levels of unaccounted variation that pose challenges for modeling microbiome dynamics.
- Due to high complexity data generating mechanism are typically not known and inference with mechanistic models such as the generalized Lotka-Volterra equations is unreliable.

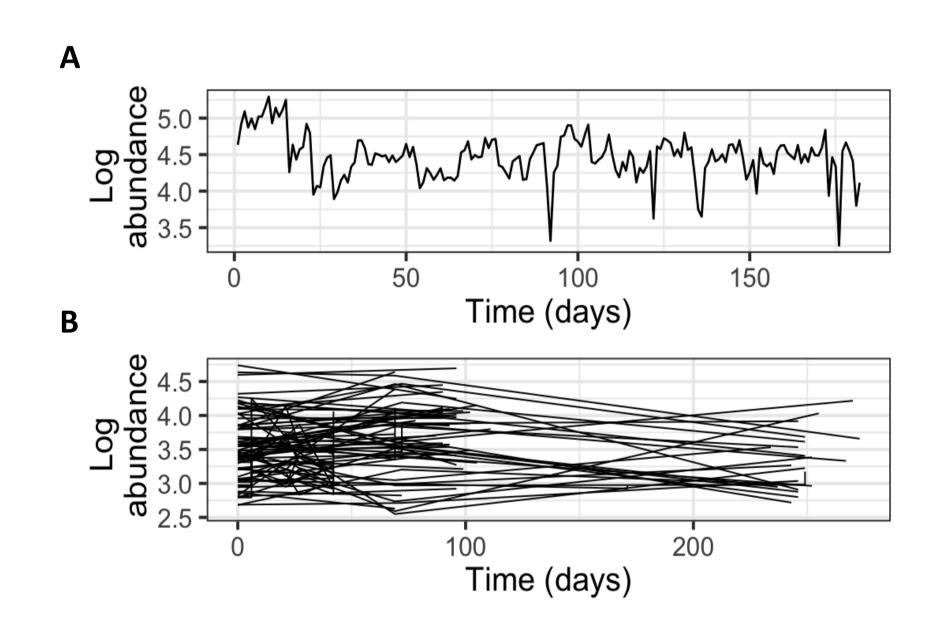
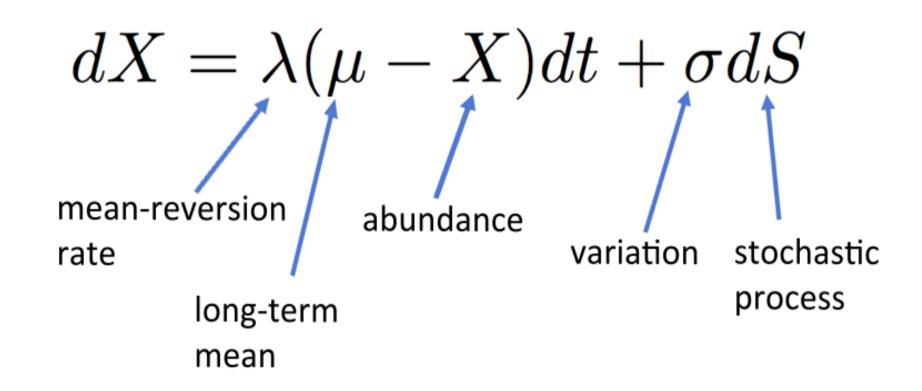


Figure 1. Log abundance levels of *Bacteroides* in A 188 samples from a single subject [1] and **B** 2-5 samples from 78 subjects [2]. Long time series are typically available only for a few subjects. Short or sparse series can be analyzed with multi-level models, if there is a large collection of them.

 Many gut microbes have been reported to have persistent long-term abundance levels [1] (Fig. 1A). The Ornstein-Uhlenbeck process (OUP) can capture key characteristic of such dynamics: location of the stable abundance level, amplitude of stochastic variations and system resilience.

Modeling the stochastic dynamics

 The Ornstein-Uhlenbeck process is the continuous-time extension of the AR(1) model and is defined with the stochastic differential equation



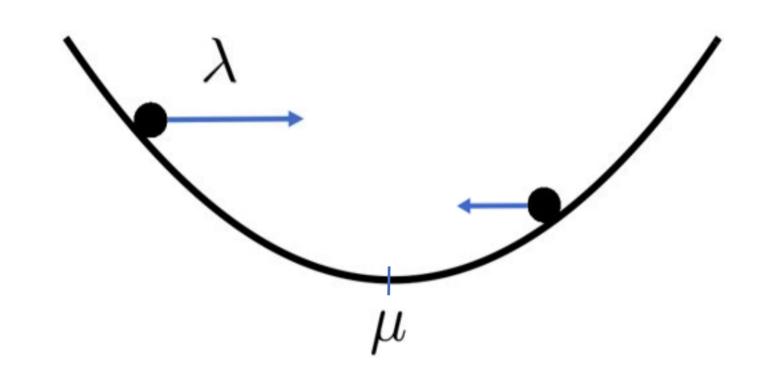
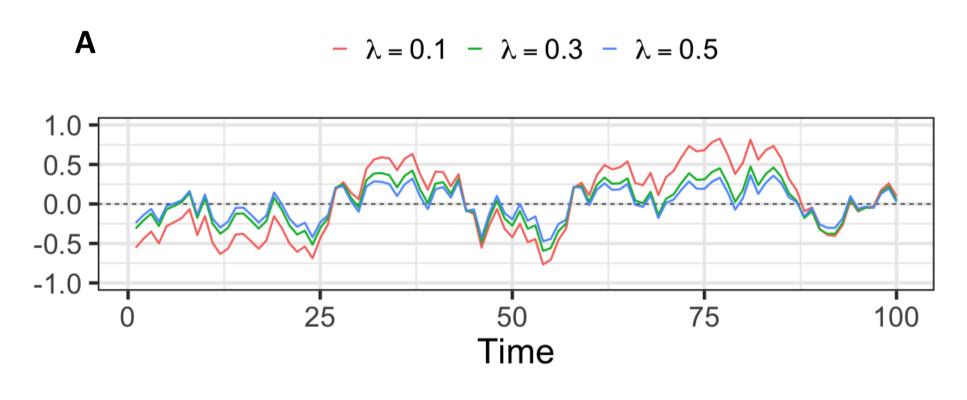


Figure 2. The OUP describes dynamics of a single potential well centered at μ . The mean-reversion rate is determined by λ.

 The OUP generates data resembling real gut microbiome data (Fig. 3A) and parameter inference with Stan [3] is reliable, as long as there are sufficiently many time points (Fig. 3B) [4].



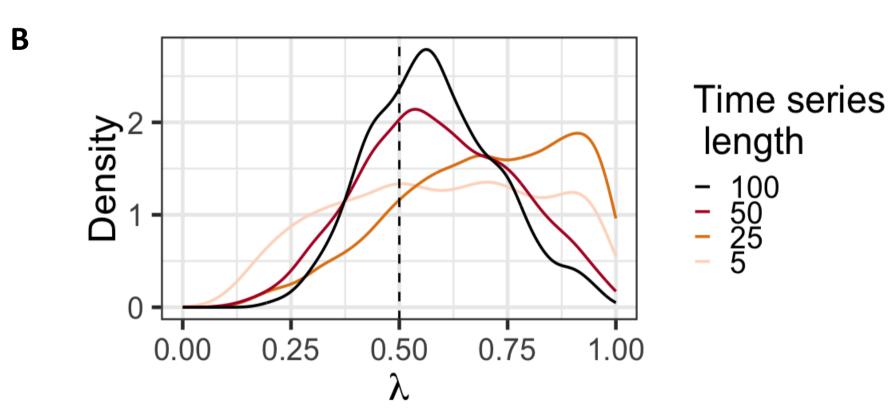


Figure 3. A Simulated OUP time series with $\mu = 0$, $\sigma = 0.5$ and various λ values. **B** Posterior estimates for λ are accurate with sufficient amounts of time points. Similar results are obtained for μ and σ .

 The OUP can equivalently be formulated as a stochastic process with covariance

$$K = \frac{\sigma^2}{\lambda} e^{-\lambda \Delta t}$$

• With multiple time series we can use a hierarchically extended model with individual parameters $\theta = \lambda_i$, μ_i , σ_i for each series and hyperparameters φ and -priors [5]. The posterior density is

$$p(\theta, \phi|X) \propto \prod_{i=1}^{N} \left[\text{MVT}_n(X_i|\nu, \mu_i, K_i) \right] p(\theta|\phi) p(\phi)$$

Results & Conclusions

 Simulations show that our implementation of the hierachical model with partially pooled parameters is able to recover more accurate estimates for all parameters compared to the non-pooled model (Fig. 4).

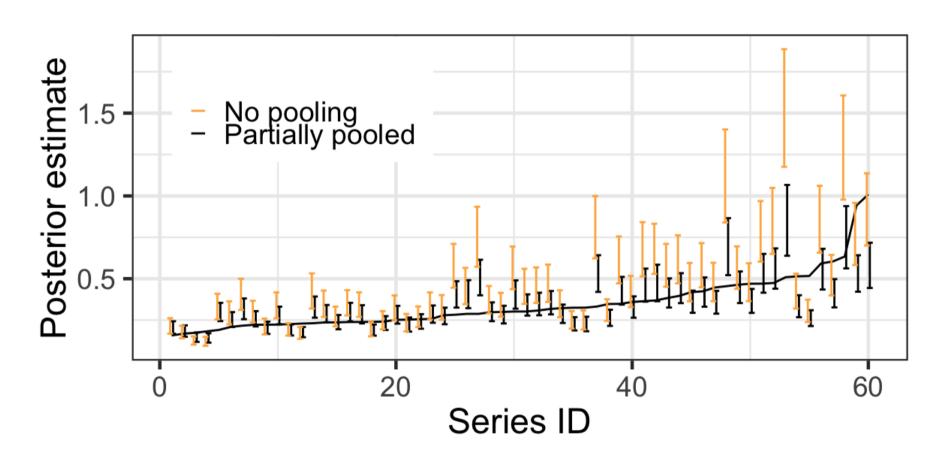


Figure 4. Simulation values of σ (solid line) and posterior 50% interquartile ranges from partially pooled (black bars) and unpooled (orange bars) models.

Ongoing research

 The standard OUP-type processes can be extended to multivariate models of microbiome composition, potentially including multiple stable states, to ultimately characterize the entire dynamic landscape of the gut ecosystem.

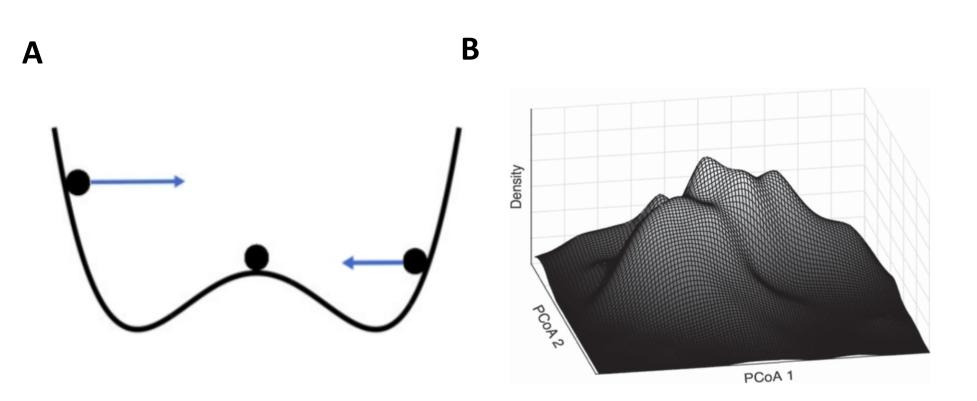


Figure 5. A Double well potential that could be used to model transitions between alternative stable states. **B** Variation in population frequency across alternative community types [6].

For preprint [7] and source code, check our research homepage:

https://openresearchlabs.github.io



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Tipping elements.

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