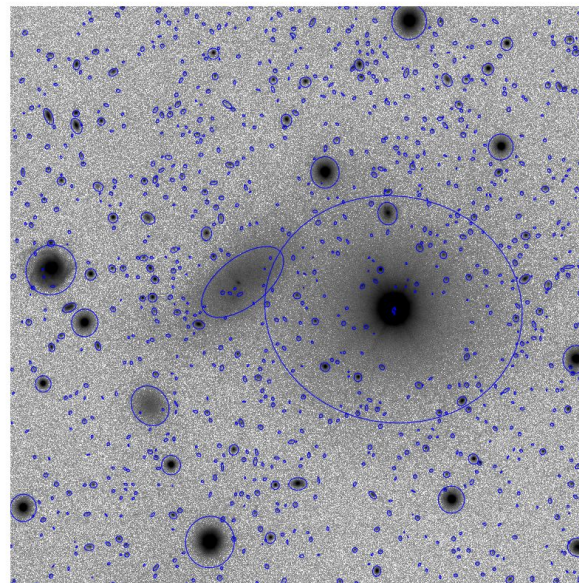
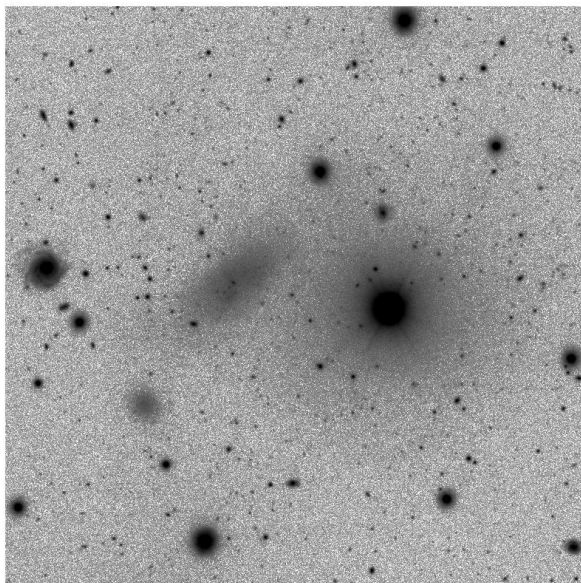


# Automated searches for low surface brightness galaxies in wide area surveys



Daniel J. Prole

Supervisors: J. I. Davies (Cardiff), Michael Hilker & Remco van der Burg (ESO)

# Scientific Interest

## The Ultra-diffuse galaxy (UDG):

Milky way sized (effective radii  $> 1.5$  Kpc)

Stellar masses more like dwarfs ( $M_* \sim 10^7 M_\odot$ )

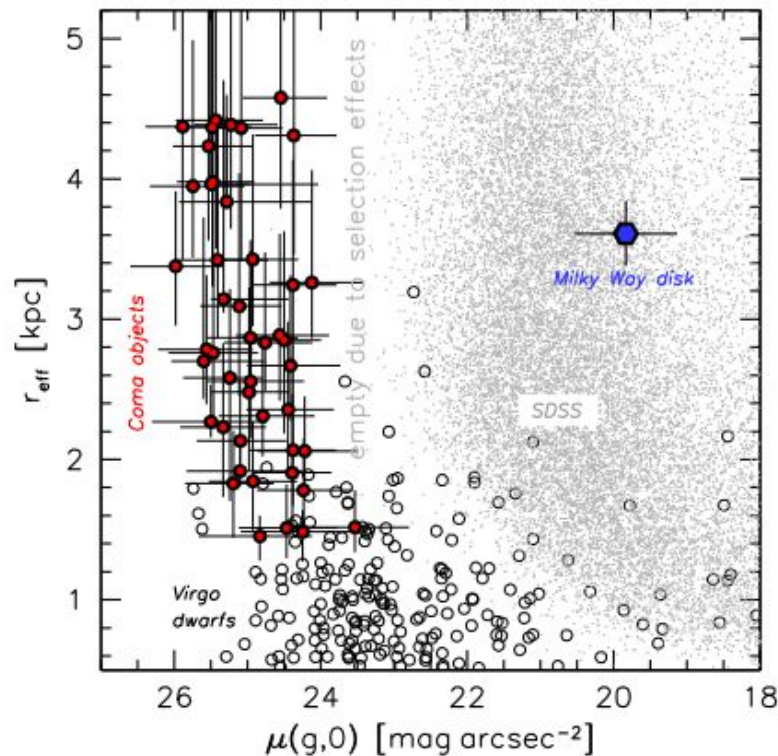
Abundant in high-density environments

## UDG formation mechanisms:

“Failed L\*” galaxies (van Dokkum et al. +15)

High-spin dwarfs (Amorisco & Loeb +16)

Tidal formation (Carleton et al. +18)



Van Dokkum et al. (2015)

# Scientific Interest: UDG formation

## Open questions:

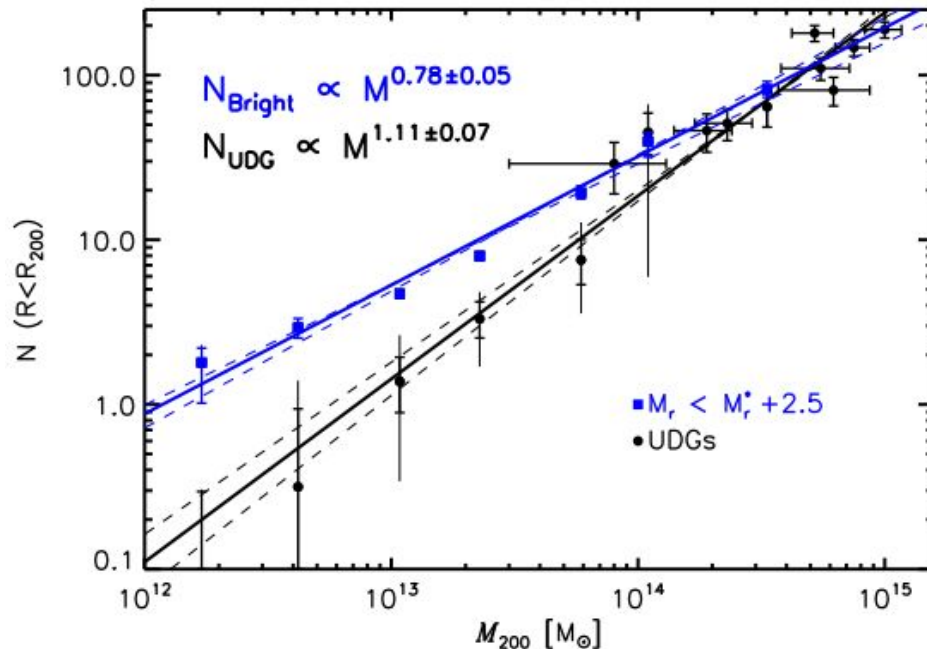
Why are UDGs relatively more abundant in high mass environments?

What are their formation mechanisms?

## Key measurements:

Abundance as a function of environment

Halo mass



Van der Burg et al. (2017)

# Scientific Interest: UDG halo mass

## Kinematic observations:

e.g. 30+ hours on Keck II (van Dokkum et al. +16)

## Weak lensing:

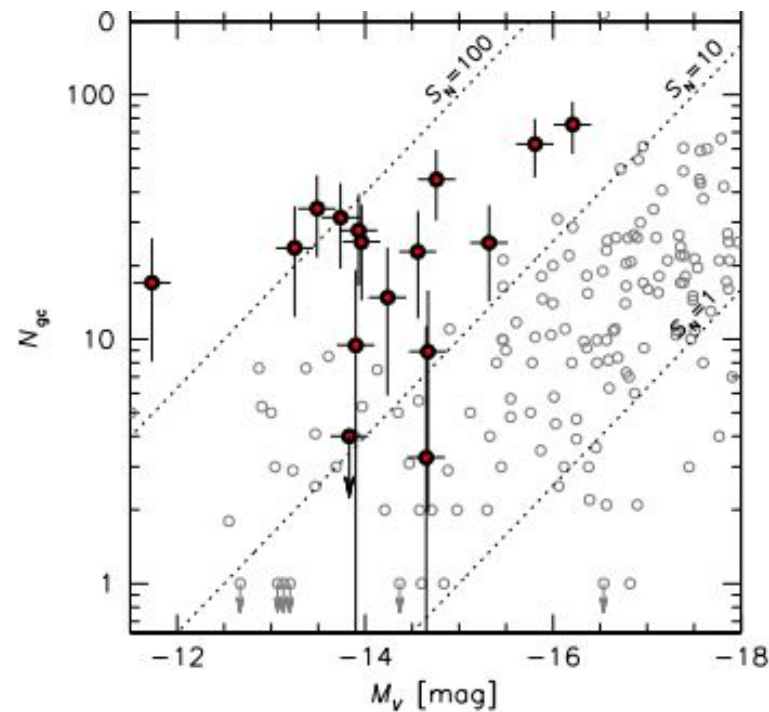
Constraints on *average* mass (Sifon et al. +17)

## Tidal features (e.g. Mowla et al. +17):

Absence in Coma UDGs implies high ML ratios

## Globular cluster systems (e.g. Beasley et al. +16):

Correlation between  $N_{gc}$  and halo mass



van Dokkum et al. 2017

# Science goals & data

LSB galaxies in clusters	Fornax (FDS; Iodice et al. 2016) Hydra (VEGAS; Capaccioli et al. 2015) Virgo (NGVS; Ferrarese et al. 2012)	Size / mass distributions Nucleation fractions Globular cluster populations
UDGs in the field	KiDS (Kuijken et al. 2015) + GAMA (Driver et al. 2011)	Abundance & formation efficiency

ESO Studentship until February 2019

# Detection methods

**Source Extractor** (Bertin & Arnouts 1996)

-Nested sources with multi-threshold deblend

**DeepScan** (Prole et al. 2018)

-Density-based detection of extended LSB structure

**MTObjects** (Teeninga et al. 2016)

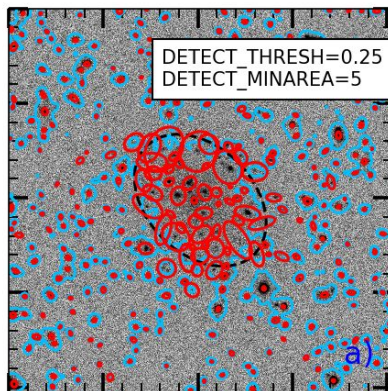
-Max-tree structure with continuous threshold deblend

**ProFound** (Robotham et al. 2018)

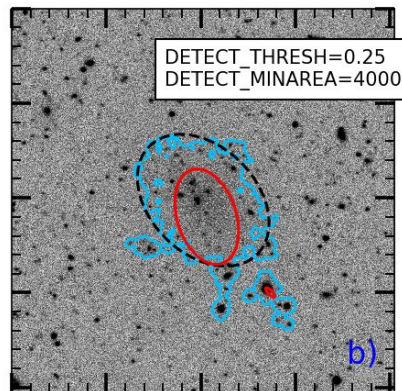
-Watershed deblend + iterative segment dilation



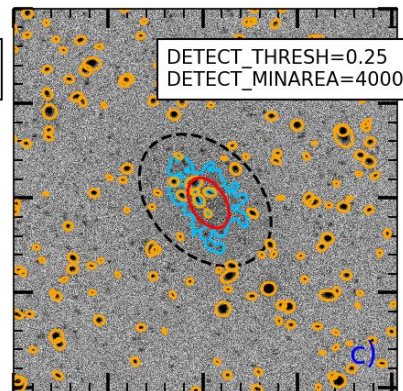
# Detection methods: SExtractor



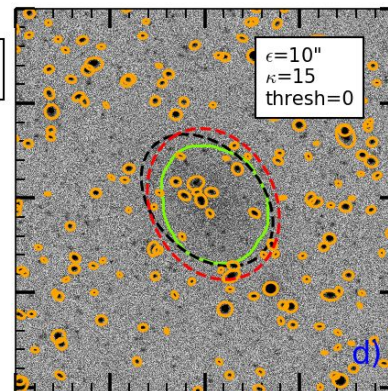
Fragmentation  
("shredding")



Confusion



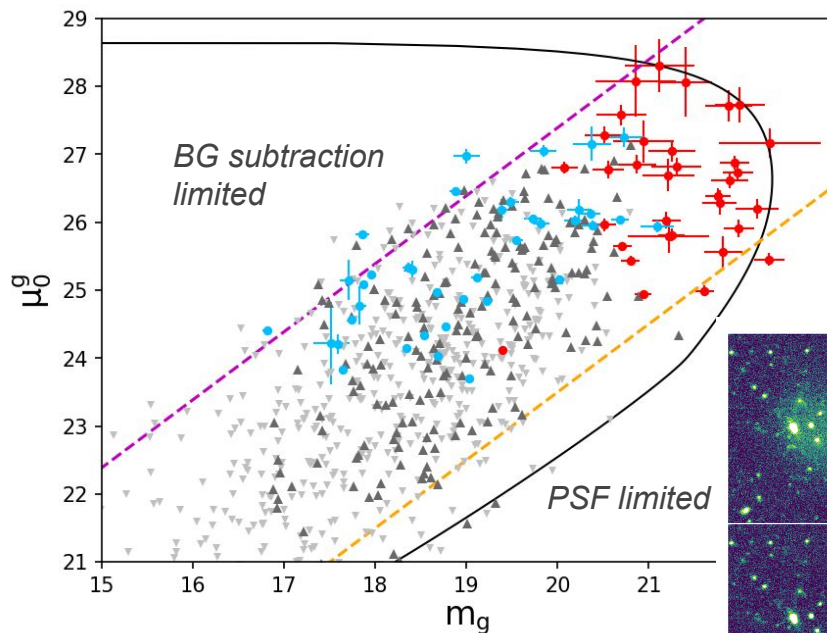
Parameter  
Underestimation



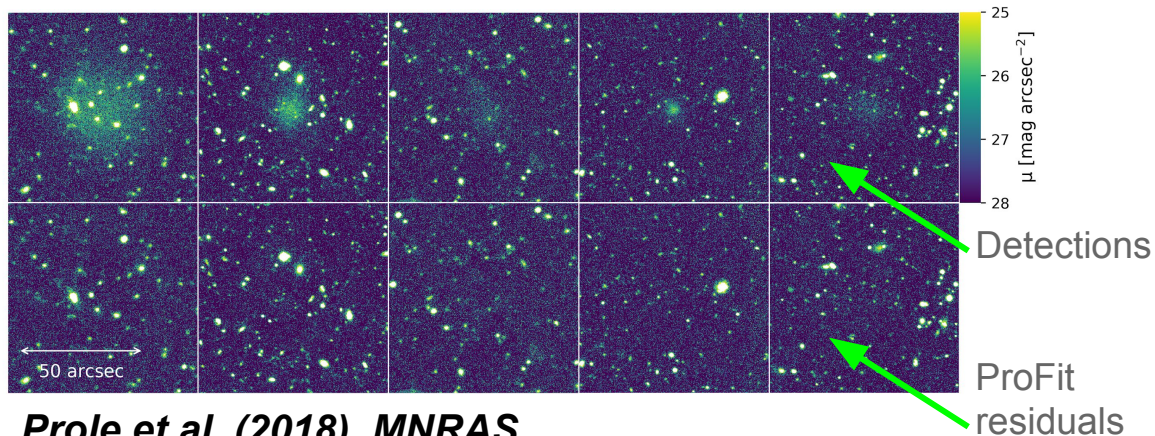
DeepScan

Blue: SExtractor segmentation map  
 Unbroken red: SExtractor FLUX\_RADIUS  
 Orange: Masked

# Detection methods: DeepScan



- 30 new detections over 5 degrees<sup>2</sup> in public NGVS data (red points)
- Stellar masses in range  $10^6$ - $10^7 M_{\odot}$
- Problem of miss-detections

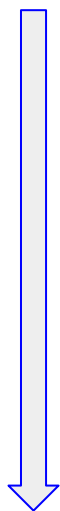


*Prole et al. (2018), MNRAS*

[https://github.com/  
danjampro/DeepScan](https://github.com/danjampro/DeepScan)

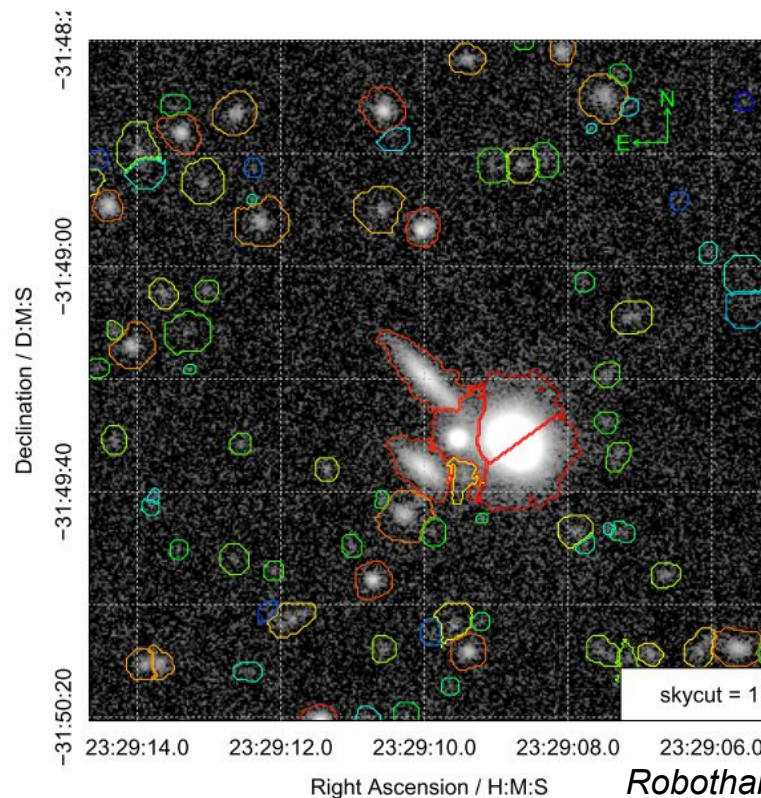


# Detection methods: ProFound



- Sky estimate (mesh)
  - Single detection threshold
  - **Watershed deblend**
  - Sky estimate (mesh)
  - Measure segment stats
  - **Segment dilation**
- } **Iterative**

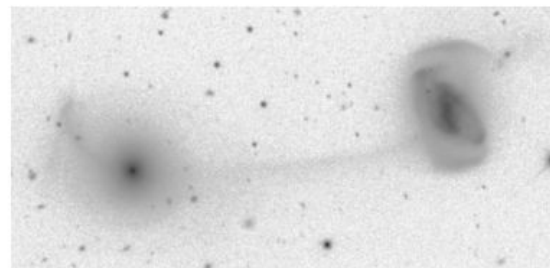
<https://github.com/asgr/ProFound>



*Robotham et al. (2018)*

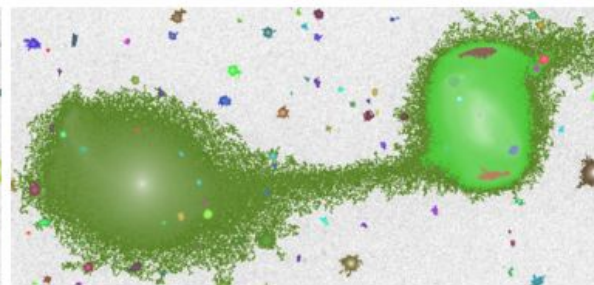
# Detection methods: MTObjects

- Global sky estimate
- **Continuous threshold**
- Statistical attribute filtering
- Max-tree structure  
(**nested sources**)
- Source measurement



SExtractor

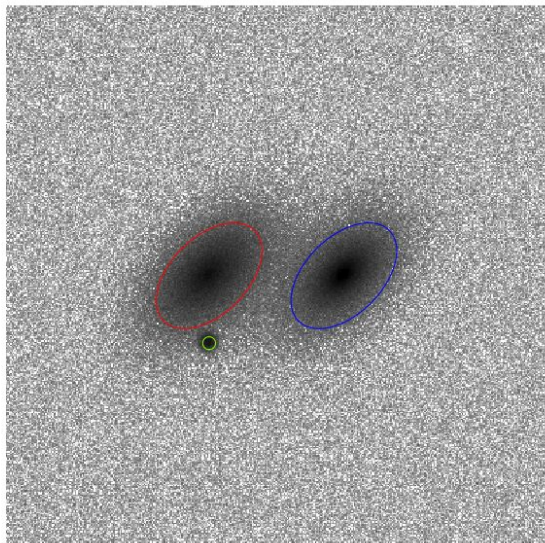
MTObjects



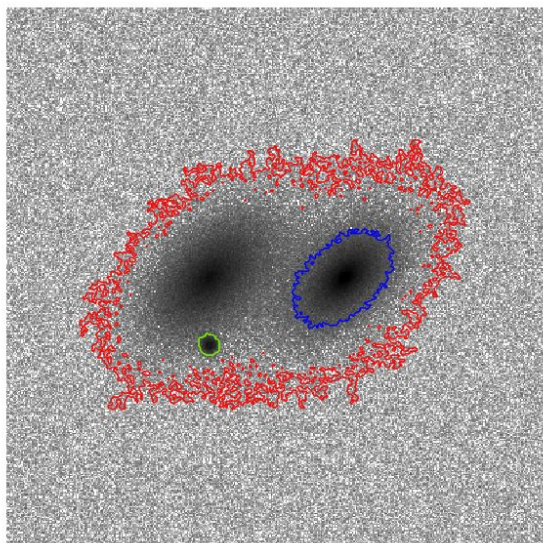
**Under development**

*Teeninga et al. (2016)*

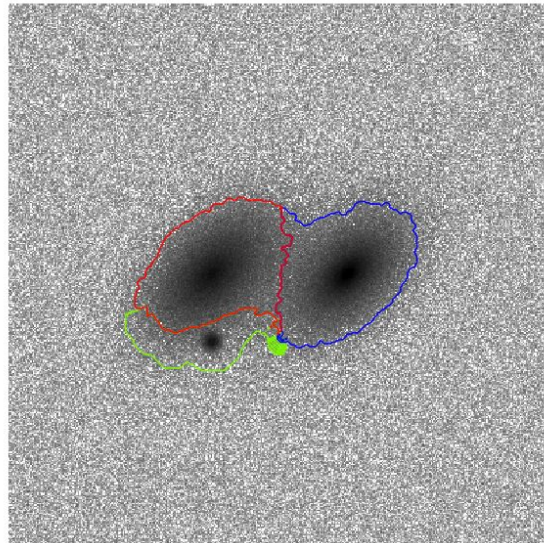
# Detection methods: Comparison



Original



MTOObjects



ProFound

# Which is the best?

... depends on the environment!

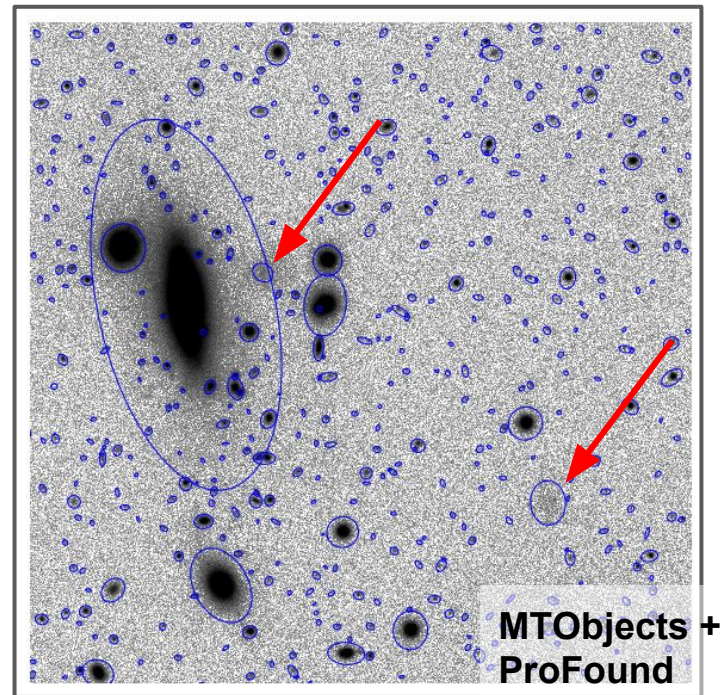
	The Good	The Bad
DeepScan	<ul style="list-style-type: none"> <li>No fragmentation</li> <li>Detection of v. diffuse sources</li> </ul>	<ul style="list-style-type: none"> <li>No nested sources</li> <li>Source confusion</li> </ul>
ProFound	<ul style="list-style-type: none"> <li>Well developed / documented</li> <li>Useful output catalogue</li> </ul>	<ul style="list-style-type: none"> <li>No source nesting</li> <li>Halo fragmentation</li> </ul>
MTOjects	<ul style="list-style-type: none"> <li>Nested sources</li> <li>Extended structure not fragmented</li> </ul>	<ul style="list-style-type: none"> <li>LSB halo confusion</li> <li>Parameter uncertainty for nested sources</li> </ul>

# SG1: Fornax LSB inventory with FDS

Aim to build on by-eye classification of **Venhola et al. (2017)**

Problem of extended LSB halos from bright sources...

- Traditional BG subtraction not optimal
- Need to develop pre-selection and measurement strategies
- Also to define “**metric of success**”



measurement

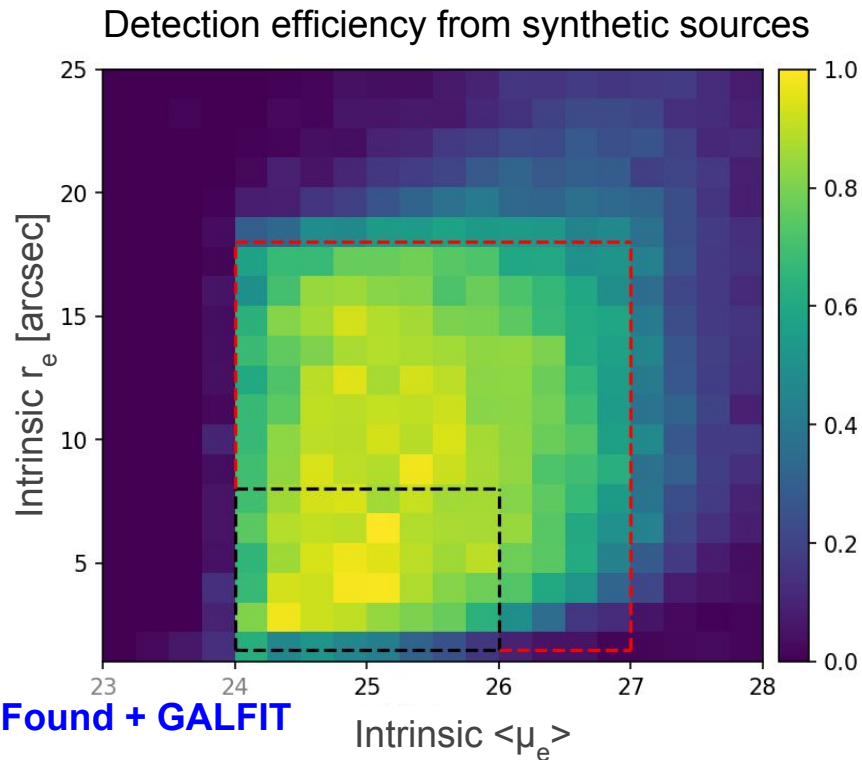
# SG2: UDG field abundance with KiDS

Want to constrain UDG abundance in low-density environments...

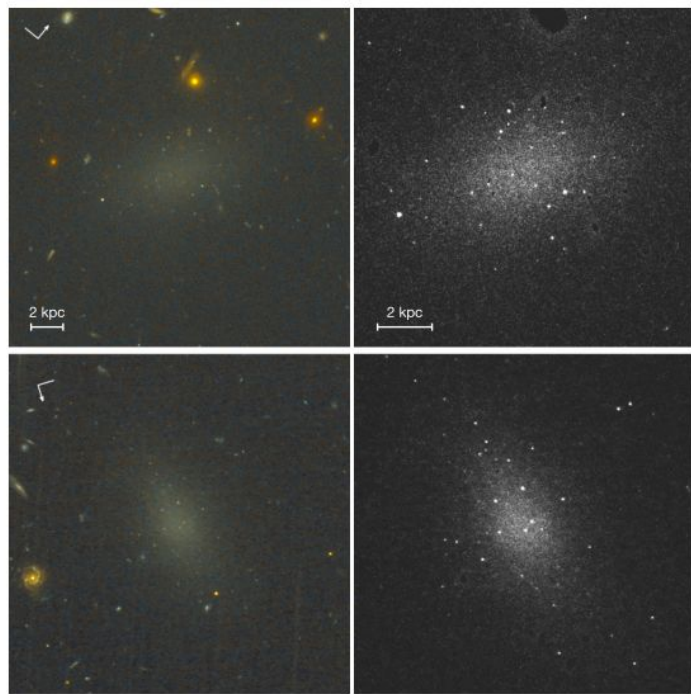
→ Need an observational sample of isolated sources

Why KiDS?

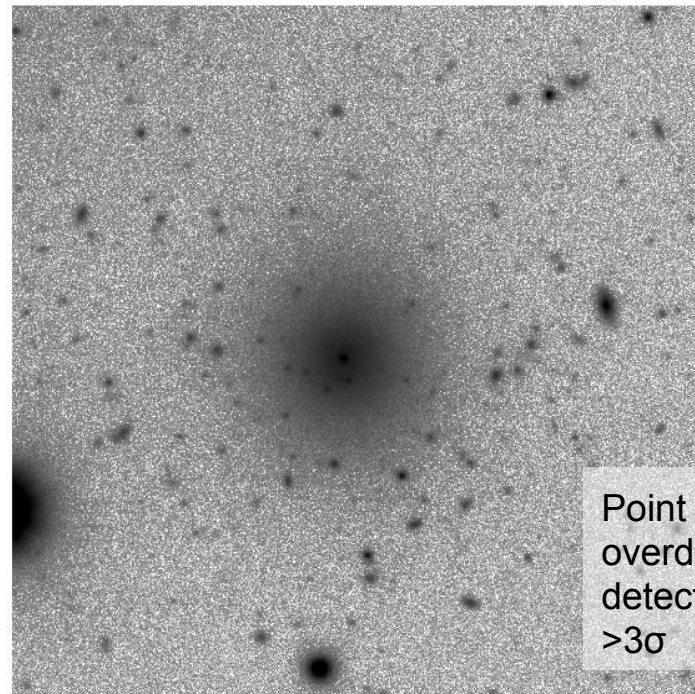
- Wide area, GAMA overlap
- Background subtracted, masks and weight maps



# SG3: Fornax UDG globular clusters

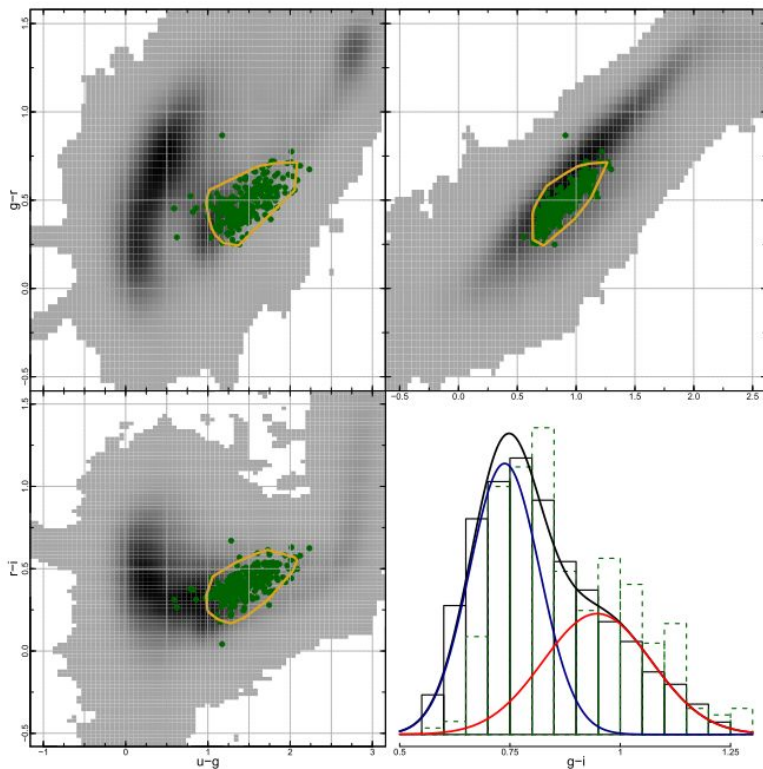


*Coma UDGs with HST (van Dokkum et al. 2017)*



*A Fornax UDG in FDS (r)*

# SG3: Fornax UDG globular clusters



+PCA Colour selection based on FDS training set (D'Abrusco et al. 2016)



# Summary

	Science	Data	Tool
Field UDG abundance	Formation efficiency	KiDS + GAMA	ProFound
LSBGs/UDGs in Clusters	Spatial distributions	FDS + NGVS	MTOjects
GC systems of UDGs	Halo masses	FDS	ProFound

## To do:

Refine detection + **measurement** algorithms

Define “**metric of success**” for meaningful algorithm comparisons

# Quality control

## Completeness / detection efficiency:

Fraction of sources with  $\langle \mu_e \rangle$ , re that are detected **AND** recovered in final sample

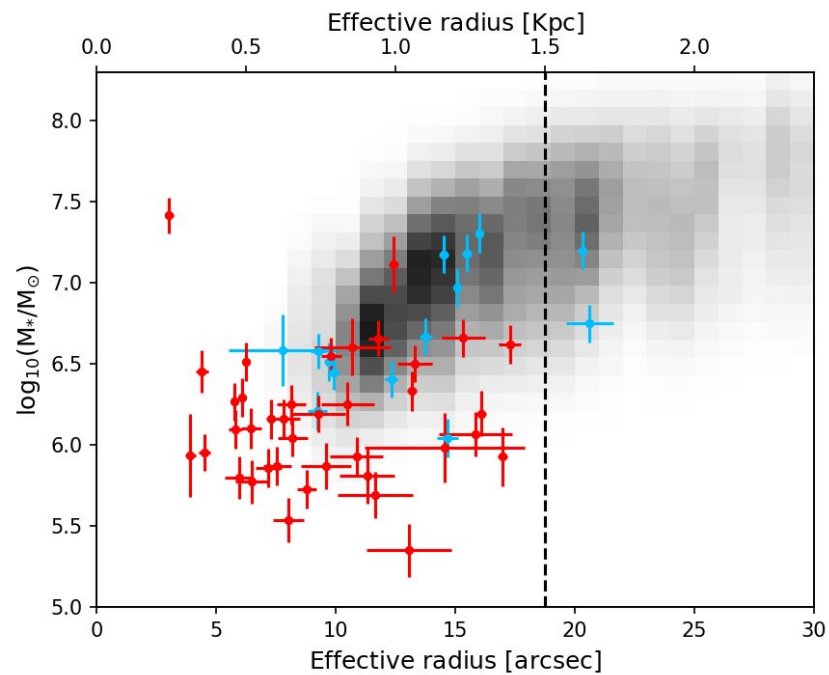
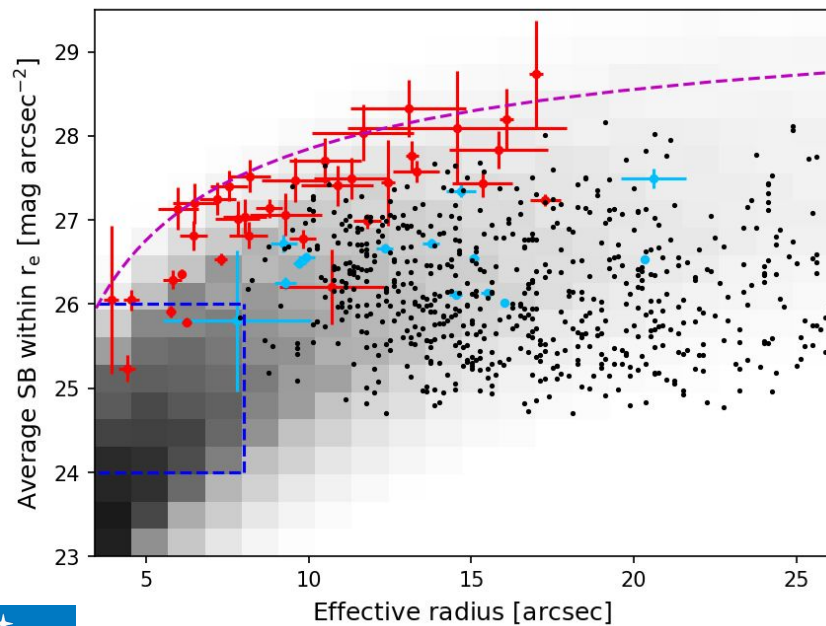
Can be measured with synthetic source injections

## Purity:

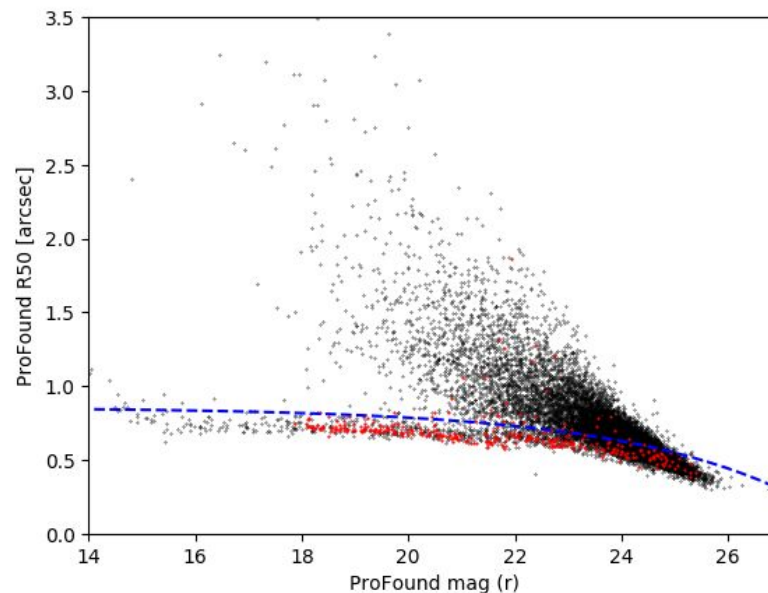
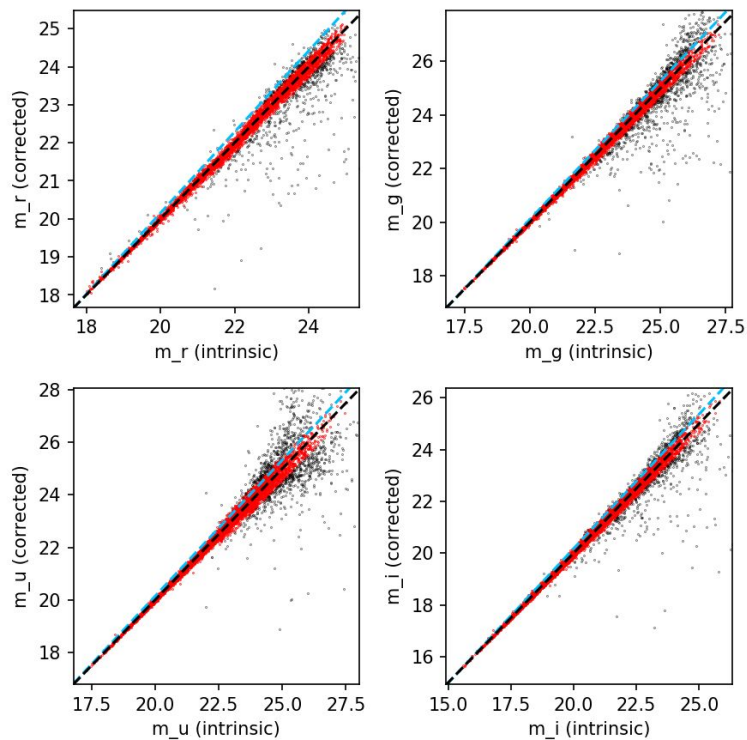
Fraction of sources in sample that have intrinsic  $\langle \mu_e \rangle$ , re meeting selection criteria

Non-trivial to estimate automatically; in clusters can use statistical correction



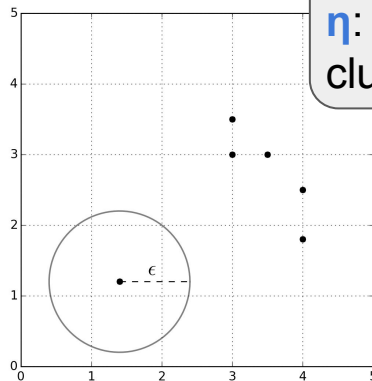
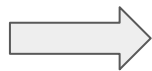
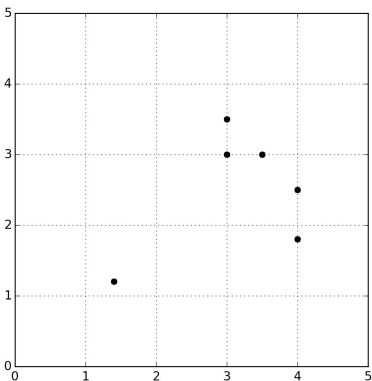


# SG3: Fornax UDG globular clusters

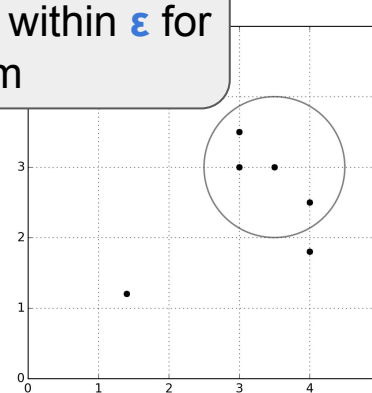
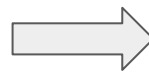


+ PCA Colour selection (D'Abrusco et al. 2016)

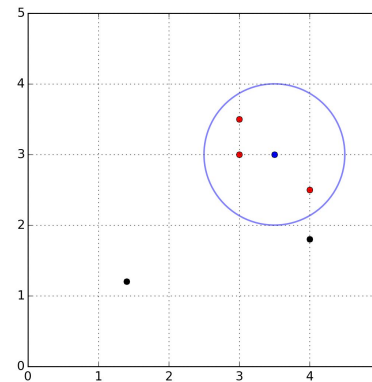
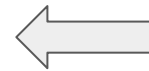
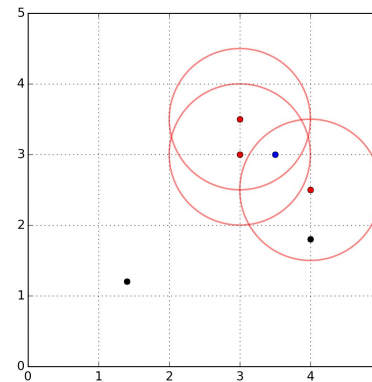
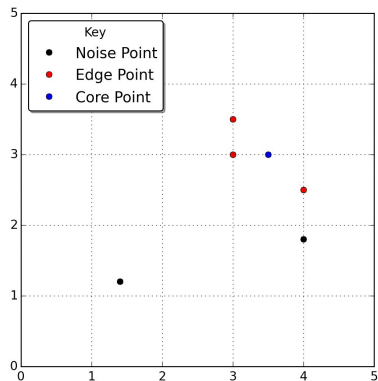
# The DBSCAN algorithm



$\epsilon$ : clustering scale length  
 $\eta$ : min points within  $\epsilon$  for cluster to form



$\epsilon=1$   
 $\eta=3$



*Ester et al.*  
(1996)