



# Hybrid Consensus Networks for Scalable and Secure Internet of Vehicles

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### Introduction



Level - 0	Level - 1	Level - 2	Level - 3	Level - 4	Level - 5
DRIVER	FEET OFF	HANDS OFF	EYES OFF	MIND OFF	PASSENGER
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No Assistance	Assisted	Partially Automated	Highly Automated	Fully Automated	Autonomous
Human	Transfer of responsibility				Machine





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#### Introduction

#### **Benefits of IoV**

- Reduce traffic congestion
- Reduce pollution
- Increase road safety
- Improve accessibility
- Reduce Stress









### Motivation

 Vehicular networks connect CAVs to each other and to various infrastructure elements via multiple types of V2X communications.









## Blockchain and PDL

- Blockchain technology as a distributed ledger, provides an effective framework that guarantees transparency, security, and decentralization in untrusted environment.
- Originally designed for a public decentralized network, but customized as a Permissioned Distributed Ledger (PDL) to address privacy concerns.
- PDLs are **scalable** and particularly well-suited for IoV applications, which require **low latency**, and secure data exchange.







- IoV applications demand **low-latency** processing to enable real-time decision-making and ensure timely responses to critical events.
- PDL consensus mechanism leads to data processing and validation delays!
- VEC servers -> wired consensus networks
- CAVs computation capability -> ETSI propose -> wireless consensus network (WCN)
- CAVs mobility, interference and signal loss -> Challenge





# Hybrid consensus network (HCN)

- Multi-layer VEC framework
- Parked CAV as pseudo stationary VEC
- Leveraging CAV's computation power







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#### DPoT (Delegated Proof of Trust)









## DPoT (Delegated Proof of Trust)

#### Trust score calculation:

- Communication and Computation reliability
- Increasing transmission power
- Computing on high clock frequency
- Energy sustainability concerns raised by ETSI
- A balance between reliability and energy consumption









#### Anonymous group signature









- We present a novel consensus network, HCN, architecture that integrates parked CAVs into a multi-layer VEC framework.
- HCN leverages the computational capabilities of parked CAVs while adhering to ETSI guidelines.
- Our goal is to enhance the scalability and performance of PDLs for IoV applications.
- We aim to improve reliability and real-time processing in PDL-based IoV networks while enhancing security and privacy.







# THANK YOU!

