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Deep Learning for Microscopy

Or How to do BioImage Analysis in the era of Deep Learning

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Outline

- What is Bioimage Analysis?
- Image Segmentation.
 - Machine learning-based segmentation.
 - What is Machine Learning?
 - Important concepts and definitions.
 - Shallow Learning.
 - Trainable Weka Segmentation plugin.
 - Deep Learning.
 - Historical view of Artificial Neural Networks.
 - Available tools.



Automatically extract biophysically meaningful information from microscopy images of biological samples.

EU funded action: <u>https://www.cost.eu/actions/CA15124</u> Network of European Bioimage Analysts: <u>www.neubias.org</u>

Slide adapted from Christian Tischer



Fiji: our open-source solution



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Schindelin,

2012

network of europear bioimage analysts

Nature Methods,

Typical analysis pipeline



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network of european bioimage analysts

Image Segmentation

- "Process of partitioning a digital image into multiple segments".
- Typically used to locate **objects** and **boundaries**.





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- More precisely, image segmentation is the process of assigning a label to every pixel in an image such that pixels with the same label share certain visual characteristics.





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Segmentation methods





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Machine learning based segmentation



What is machine learning?

- Technological advances in the last decades have made possible to automate many tasks that required a significant amount of time and repetitive manual work.
- Now technology allows us to work with big data and automate tasks that are not simply mechanical but require a certain degree of intelligence.
- Some tasks are easy for humans but difficult for machines. For example, face recognition, has many challenges:
 - Position, illumination, haircut...
- Some tasks are hard for humans due to the large amount of data to handle.
- Data mining and machine learning techniques have achieved great results in this direction, making intelligent systems an important part of research and business models.



Image via www.vpnsrus.com



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- Assign labels to objects indicating their class.
- Objects represented by a set of measurements or features.





Supervised vs unsupervised learning





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Supervised vs unsupervised learning

• To which class belongs each new point?





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Supervised vs unsupervised learning

- Supervised learning:
 - Data is labeled.
 - Target: build a model or classifier to automatically label novel data \Rightarrow training.
 - If labels are not discrete \Rightarrow regression.
 - Examples:
 - Character or digit recognition (classification).
 - Age estimation (regression).
- Unsupervised learning:
 - Data without labels.
 - Target: model data to discover groups \Rightarrow clustering.









Class, features and dataset

• In machine learning, each sample is represented by a feature vector:

$$x = [x_1, \dots x_n]$$

- Features can be quantitative or qualitative.
- Supervised learning \Rightarrow predefined classes (labels). $U_L = \{u_0, ..., u_{L-1}\}$
 - A sample belongs (usually) to one class only.
 - Each class contains similar samples different to the samples of other classes.
 - Ex.: biopsy classification \Rightarrow 2 classes (tumorous non-tumorous).
- Dataset: $S=\{(x^k,d^k),k=1,...,N\}$
 - Set of pairs sample-class (supervised)
 - Set of samples without class (unsupervised)



• Classifier: function that relates samples to labels:

$$f_{\theta}: x \to d$$

- Some classifiers have two steps:
 - "Soft" decision $y^k = f_{\theta}(x^k)$
 - "Hard" decision \hat{d}
- Training algorithm adjusts classifier parameters θ to minimize a cost or error function.



Classifier evaluation

- How do we evaluate the performance of a classifier?
- How do we compare classifiers?
- Confusion matrix:



Predicted labels

TP: True Positive, **TN**: True Negative, **FP**: False Positive, **FN**: False Negative.

Total number of positive samples: P=TP+FN

Total number of negative samples: N=TN+FP



Performance metrics

True Positive Rate (hit rate, recall, sensitivity)	TP/P	Proportion of positive samples correctly classified
False Positive Rate (False Alarm Rate)	FP/N	Proportion of negative samples incorrectly classified as positive
False Negative Rate	FN/P	Proportion of positive samples incorrectly classified as negative
True Negative Rate (specificity)	TN/N	Proportion of negative samples correctly classified
Precision (Positive Predictive Value)	TP/(TP+FP)	Proportion of samples classified as positive that are really positive
F1 Score	2 x precision x recall / (precision+recall)	Harmonic mean of precision and recall
Error Rate	(FP+FN) / (P+N)	Proportion of samples incorrectly classified
Accuracy	(TP+TN) / (P+N)	Proportion of samples correctly classified



Classifier design

• How many samples we use to build the classifier?





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Classifier design

- How many samples we use to build the classifier?
- If we use all samples \Rightarrow overfitting





Train and test

- Divide dataset in two sets:
 - Train: to build the model (~66% of samples)
 - Some models need a validation subset (~10% of training samples).
 - Test: to evaluate the model (~33% of samples)





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k-Fold cross-validation

- Very common alternative.
- Divide dataset of *N* samples in *k* "equal" parts: 1 for test and *k*-1 for train.
- Usual values of *k*: 5 or 10.
- Train/test k times and evaluate based on test labels
- Particular case: *leave-one-out* (*N*-1 for training and 1 for testing).



Source: https://scikit-learn.org/stable/modules/cross_validation.html

Classic classifier design cycle



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Shallow Machine Learning in ImageJ/Fiji

Trainable Weka Segmentation



Trainable segmentation basics

• Transform segmentation problem into pixel classification.



almage anglus

Classification algorithms

- Support Vector Machines (SVM).
- Decision Trees / Random Forests.
- Artificial Neural Networks.



Slide courtesy: Martin Weigert, EPFL Lausanne

learn <u>https://scikit-learn.org/</u>

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What about deep learning?



Linear classifiers: perceptron

• Perceptron (1956): Find a linear classifier f(x) such that





Linear classifiers: perceptron

- Separating two classes A and B
 - y = 1 if the example belongs to A
 - y = 0 if the example belongs to B
- Perceptron algorithm:
 - At iteration k, we consider example x:
 - w(k) = w(k-1) if x is correctly classified
 - w(k) = w(k-1) + (d-y) x otherwise (d: desired output)



• It converges if and only if the examples are linearly separable.





Failures, promises...

- The perceptron (PCP) is a linear machine, so it can learn the AND and OR predicates... but it cannot learn XOR
- Linearly separable problems are very unlikely when sample size >> sample dimension
- But a PCP with one hidden layer can solve XOR
- And a PCP with **two hidden layers** can (essentially) solve any classification or regression problem
- However, there were no algorithms to build (learn) them from a given sample
- This led to the first NN winter (1969) and a concentration of AI efforts in symbolic systems...



Back in business

- We can summarize early work on PCPs by saying that
 - The architecture was right
 - But the training approaches were wrong
- Things change in 1986 with the book: Parallel Distributed Processing. Explorations in the Microstructure of Cognition: Psychological and Biological Models, J.L.
 McClelland, D.E. Rumelhart and the PDP Research Group (G. Hinton among them)
 - Grand title, but learning becomes error minimization (i.e., moves from AI to optimization)
- Multilayer PCPs (MLPs) became highly flexible and very efficient non–linear regression and classification machines.



Multi-layer perceptron architecture

- General organization:
 - 1 input layer, 1 or more hidden layers, 1 output layer
 - Each fully connected with feedforwad processing
- Many layered MLPs define a highly non–linear, weight–depending, transformation
- Learning's goal: minimization of a suitable error function
- Gradient can be easily computed by backpropagation
- This went on strongly until the late 90's when
 - New relevant contributions decrease
 - New competitors appear: Boosting, SVMs,
 Random Forest ⇒ Second Winter of NN.



http://cs231n.github.io/neural-networks-1/



Neural Networks decline

- A nagging issue are deeper MLPs
- One hidden layer MLPs are enough for most applications
- But nobody knew how to train MLPs with three or more hidden layers
- One main obstacle was vanishing gradients: in a 5 layer MLP



Gradients in the last (5-th) layer are nonzero but vanish as we go back towards the first layer

• Inputs cease to have any effect and training stalls



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Golden era: Deep Networks

- First breakthrough around 2007: deep MLP unsupervised pretraining using stacked RBMs (Hinton) or autoencoders (Bengio)
 - Easier fine-tuning afterwards by standard back-propagation
- Floodgates opened: large nets with huge number of weights and new convolutional layers, regularizations, initializations or activations
 - New mood: what was impossible before is now much easier and leads to better results and even major breakthroughs in significant problems
 - New techniques appear ... that are not that different from the old ones
- 2012: the convolutional network AlexNet (Hinton group) wins the ImageNet challenge → the Deep Learning revolution starts.
- 2013: Google hires Geoff Hinton.
- 2014: Facebook hires Yann LeCun (father of the first convolutional network).
- 2018: Turing Award for Hinton, LeCun and Bengio.



Convolutional and pooling layers

- Starting assumption: patterns organized in features having a one, two (or multi) intrinsic dimensional structure
- Basic processing: to apply a *K* x *K* convolutional filter *w* over an image patch x_j as y_j = f (w * x_j + b)
- An M₁ x M₂ input "image" X becomes an (M1 K
 + 1) x (M2 K + 1) output X' = C(X)
- This is followed by a pooling transformation P over L x L patches of X'
 - Possible transforms: averages, max



Image



Convolved Feature

From UFLDL Stanford tutorial



From computersciencewiki.org



Deep Convolutional Networks

- The previous steps are often combined in a Deep Convolutional NN with
 - An initial number of convolutional layers, followed by
 - A number of fully connected inner product layers and, finally
 - A readout layer that yields the NN's response
- A typical architecture for image processing can be



From Convolutional Neural Networks (LeNet) tutorial

• Possibly with connections and weights in the millions



Many computer vision applications





Current situation in Bioimage analysis



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network of europe bioimage analysts

When did it start in the field?



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Advantages of U-Net

- Image processing:
 - Contracting path extracts

high dimension features

 \Rightarrow abstract analysis.

- Expanding path refines the processing.
- Data augmentation applied to medical image processing.



O. Ronneberger, et al., U-Net: Convolutional Networks for Biomedical Image Segmentation, MICCAI 2015.



What do you need?

The problem to solve by machine learning techniques has to be well defined.

Classification: the number of classes has to be determined and their description cannot be ambiguous





Segmentation: the result of any manual annotation when performed twice by an expert, should always coincide.





High enough quality of data.





What do you need?

- To train your own model you need:
 - Technological infrastructure.
 - Graphics processing units (GPU).
 - Cloud computing (Google Colab, Kaggle notebooks, Amazon).
 - Data: Ground Truth (GT) ⇒ manual annotations supervised by experts.
 - GT has to represent the real scenario of the problem.
 - Large enough to train the model and evaluate it.



NVIDIA Quadro P5000





What do you need?

- Data augmentation.
- Patching
 - Geometrical transformations
 - Linear transformations (preserve shape)
 - Rotation
 - Translation
- (!) Non-linear (elastic) transformations (shape changes)
 - Zooming
 - Shearing
- (!) Add artifacts: noise











Original patch

Rotation + Shift

Rotation



Non-linear transformations



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Resources





Instance Segmentation Challenges!



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Biolmage Model Zoo

Advanced AI models in one-click

Integrated with Fiji, ilastik, ImJoy and more Try model instantly with BioEngine Contribute your models via Github Link models to datasets and applications

🚿 Explore the Zoo







be a keyword and press enter

Tags & Filters 🔻

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Current related lab projects



BiaPy: BioImage Analysis Pipelines in Python

Daniel Franco-Barranco (PhD student)













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Wound healing modeling by video prediction

Given a set of initial frames, predict the next frames of a video

Lenka Backovà (PhD student, Biofisika)





Fuskal Herriko

Unibertsitatea

Universidad

del País Vasco

(1) Frame encoding





Encoder

Decoder

(2) Prediction based on 8 initial frames:



Ground truth

Prediction



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Super-resolution deep learning for microscopy

Ivan Hidalgo (former Master student, EHU)











Take home messages

- Machine / Deep Learning is spreading out in the field of Bioimage Analysis.
- Tons of applications if you have:
 - 2D / 3D / ND images, videos...
- and need to do:
 - Classification,
 - detection / segmentation / tracking,
 - super-resolution...
- Drawbacks:
 - Generalization.
 - Interpretability.
 - Computing resources.



https://xkcd.com/1838/







Slides credits and references

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- Selim Aksoy (Bilkent University), "Introduction to Pattern Recognition", CS 551, Fall 2016.
- Deep Networks, J. Dorronsoro, EPS-IIC, UAM.
- Fei-Fei Li & Justin Johnson & Serena Yeung, Stanford, cs231, lecture 11.
- Estibaliz Gómez-de-Mariscal, "Machine learning Deep learning, Applications to Biolmage analysis", SPAOM2018.
- Arrate Muñoz-Barrutia, "deepImageJ, A user-friendly plugin to run deep learning models in ImageJ", SPAOM2019.
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