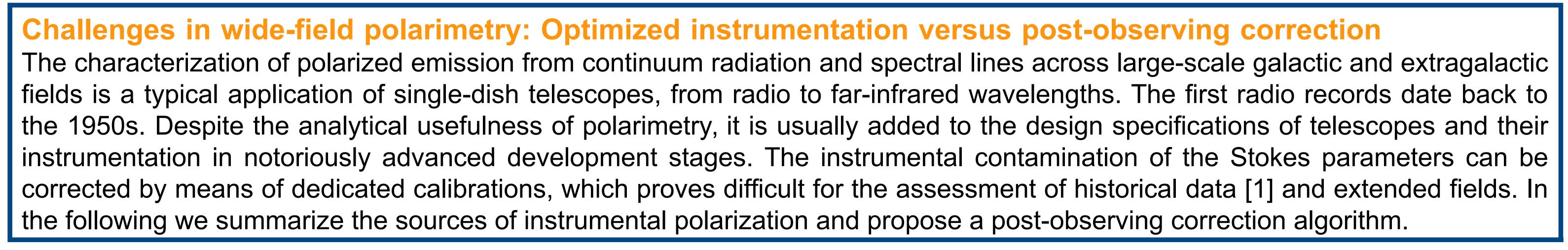
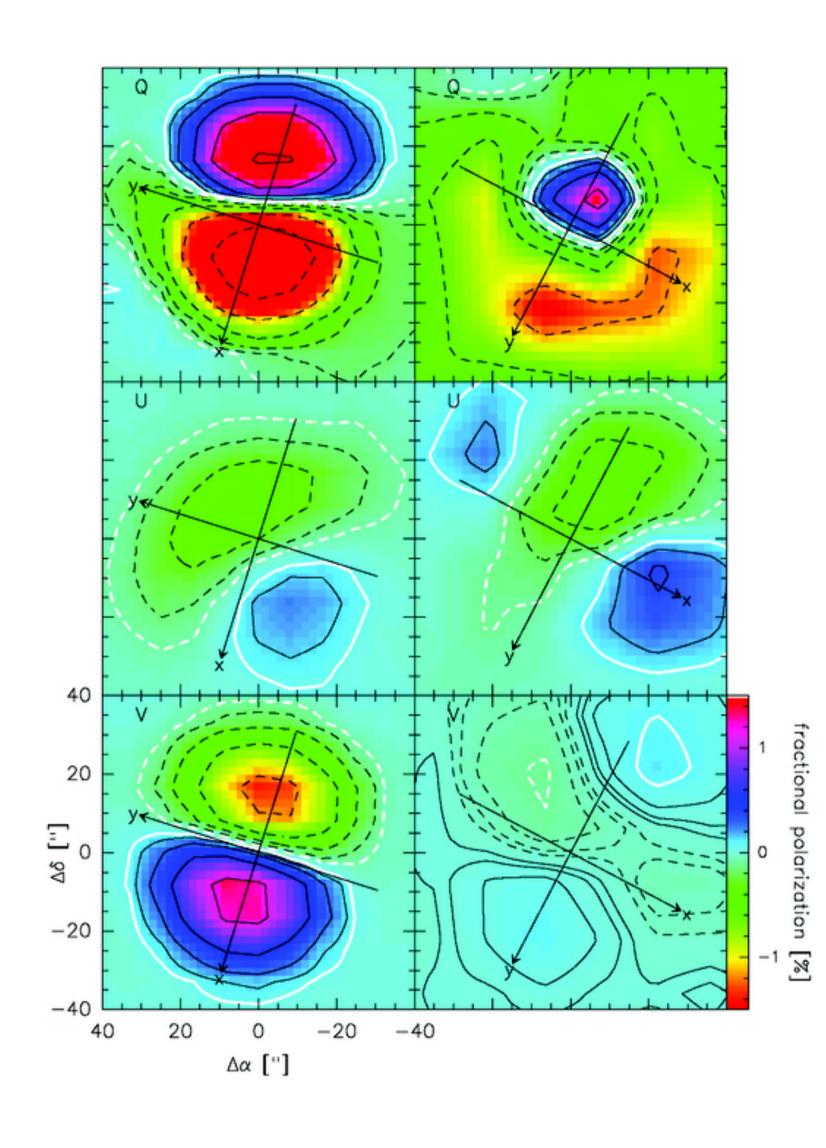
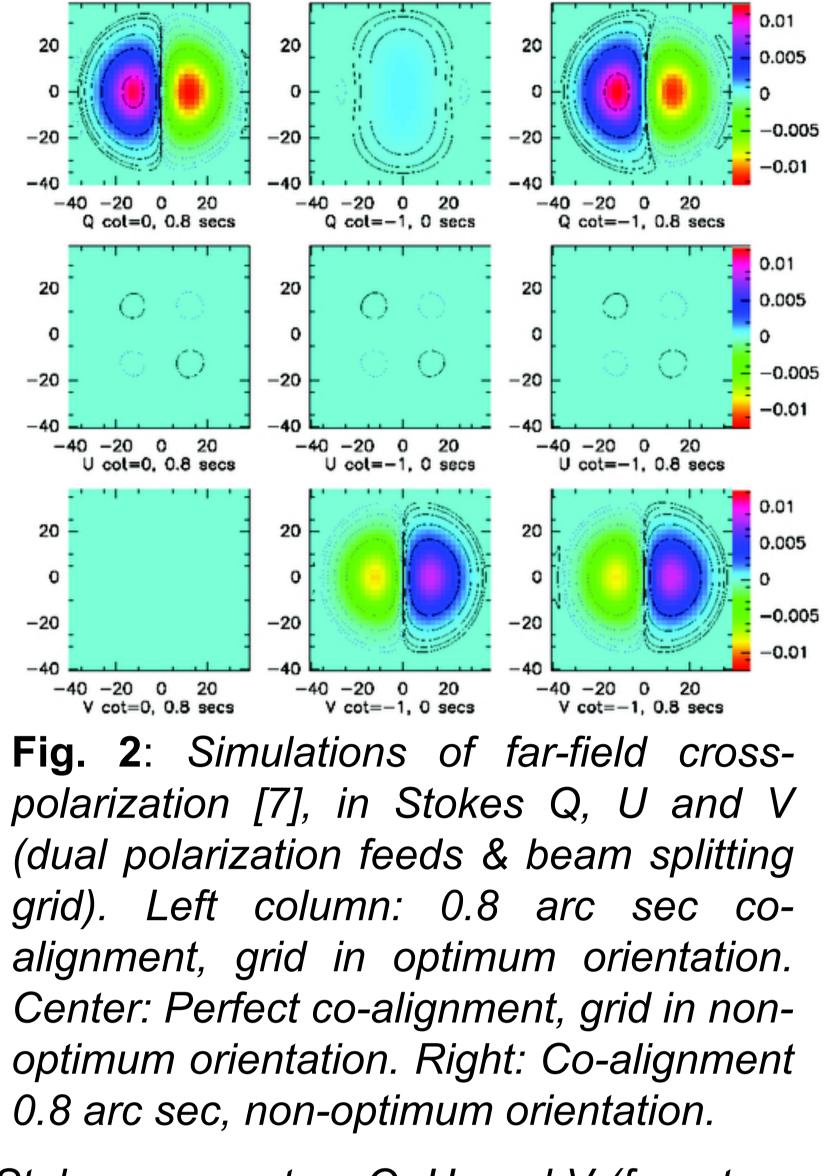


Lessons learned from six decades of radio polarimetry

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Sources of cross-polarization

The cross-polarization of an axisymmetric telescope is negligible (for a Huygens source [2] shown by [3], [4],

Fig. 1: *IRAM 30m, beam maps* [7] of the Stokes parameters Q, U, and V (from top to bottom) at 86 GHz in 1999 (left) and 2005 (right, for improved co-alignment and optimal beam-splitting grid orientation). All flux scales are in fractional polarizations (indicated on the lower right), contours are at 0.2%, 0.4%, 0.8%, 1.6%, and 3.2%, negative contours are dashed, thick white contours are at $\pm 0.1\%$. The rotated coordinate crosses show the x- and y-axes of the Nasmyth coordinate system.

including diffraction by [5], [6]). This ideal case is never realized in practice, for various reasons [7]:

•An elevation-dependent deformation of the telescope aperture (from circular to slightly elliptical) introduces a polarization-dependent aperture efficiency.

 Imperfections in the feed horns contribute a few % to the crosspolarization (CP). They are suppressed by a combination of a beam-splitting grid with a mono-mode waveguide, leaving a residual on-axis CP of typically ~1% [8] (also present in orthomode transducers [9]).

•Offsets in the co-alignment of feeds with orthogonal linear or opposite circular polarizations cause extended polarized sidelobes in the far field ("beam squint", Fig. 1).

A de-focus causes a phase error across the aperture plane which is axisymmetric only for a displacement along the optical axis, [10]. With sub-optimal co-alignment this leads to CP [11].
Polarization-sensitive equipment (e.g., a beam-splitting grid) in a divergent beam induces CP for wires in the plane of incidence [12]. If a beam squint is present, this produces a spurious conversion from Stokes I to Stokes V in the far field.

Post-observation removal of cross-polarization

The brightness distribution received from an unpolarized calibrator (Venus, Uranus, Mars if unresolved), fully mapped in all Stokes parameters, allows for the following correction scheme [13]:

B = brightness distribution (intensity), S = flux density, P = point source response.First index: <math>0 = Stokes I, j = 1,2,3: Q, U, V, second index: obj: Object, P: Planet. For j=1,2,3:

Aim: corrected Stokes maps $S_{j,obj} = B_{j,obj} * P_0$ Observations yield $S_{j,obj} = B_{j,obj} * P_0 + B_{0,obj} * P_j$ Model $M_j = S_{0,obj} * B_{j,P} = B_{0,obj} * P_0 * B_{0,P} * P_j$ Correction: $S_{j,obj} * G - M_j$ with $G = P_0 * B_{0,P}$ Apply correction, deconvolve with planetary disk profile.

A demonstration is shown in Fig. 3. While the method preserves the original spatial resolution (Θ_{mb} , the FWHM of the main beam in Stokes I), polarization sidelobes are only corrected on spatial scales $\geq 1.4\Theta_{mb}$, unless a Stokes I map of the target is available with a beam of FWHM $\ll \Theta_{mb}$.

Some imperfections are suppressed by design optimization and accurate adjustments (Figs. 1,2), others remain and show in observations of weakly polarized sources.

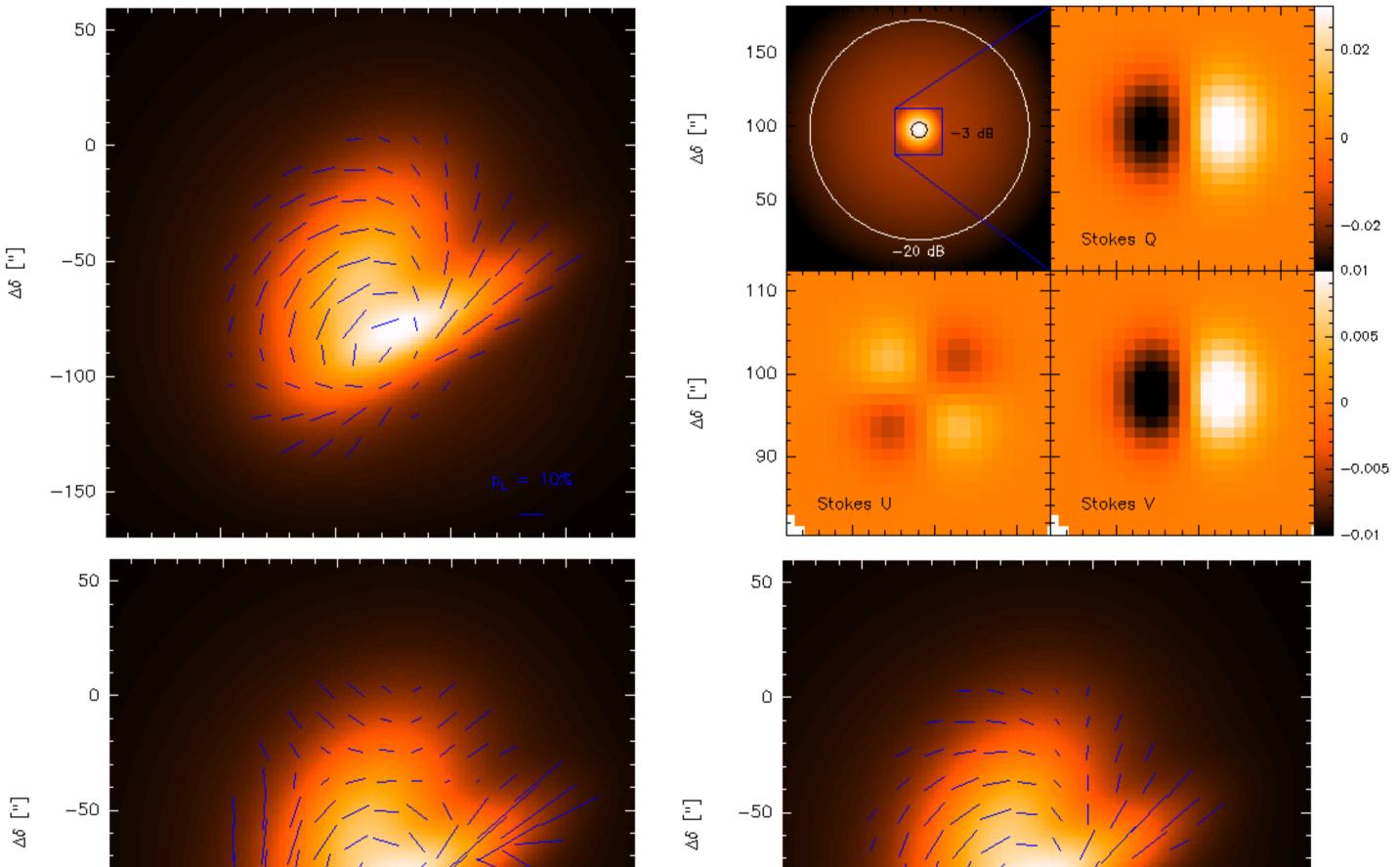


Fig. 3: Simulation of the deconvolution of a sky-plane projected magnetic dipole field (top left) from the instrumental leakage of Stokes I into Stokes Q, U and V (top right). The bottom panels show the observed (left) and the restored, intrinsic polarization (right).

-100 - 100

Conclusions

Provided that the instrumental cross polarization is sufficiently well known even under various observing conditions, the intrinsic, polarized brightness distribution of the target can be restored with a dedicated algorithm [13]. This correction is particularly useful for wide-field observations, but requires additional calibration measurements which, depending on the instrumentation, may prove substantial and involved. Including high-fidelity polarimetry in the design specifications for radio telescopes and their instrumentation is therefore desirable. Under a more general perspective this may also improve sensitivity and observing efficiency.

References: [1] Robishaw T. 2008, PhD thesis. [2] Koffman I. 1966, ITAP 14, 37. [3] Hanfling J. 1970, ITAP 18, 392. [4] Safak M. ea. 1976, IEEE Trans. AP-24, 497. [5] Minnett H.C. ea 1968, Proc.IEE 115, 1419. [6] Thomas B. 1976, Elec..Let. 12, 218. [7] Thum C. ea. 2008, PASP 120, 777. [8] Agudo, I. ea 2018, MNRAS in press. [9] Sievers A. ea. 2015, IRAM Report. [10] Baars, J.W.M. 2007, Springer ASSL 348. [11] Wiesemeyer H. ea. 2011, A&A 528, A11. [12] Chu T.S. ea. 1975, BellSys Tech..Journ. 54, 1665. [13] Wiesemeyer H. ea. PASP 126, 1027.