

Star-Hexagon Transformer Supported UPQC

Yash Pal, A.Swarup and Bhim Singh

Abstract—A new topology of unified power quality conditioner (UPQC) is proposed for different power quality (PQ) improvement in a three-phase four-wire (3P-4W) distribution system. For neutral current mitigation, a star-hexagon transformer is connected in shunt near the load along with three-leg voltage source inverters (VSIs) based UPQC. For the mitigation of source neutral current, the uses of passive elements are advantageous over the active compensation due to ruggedness and less complexity of control. In addition to this, by connecting a star-hexagon transformer for neutral current mitigation the over all rating of the UPQC is reduced. The performance of the proposed topology of 3P-4W UPQC is evaluated for power-factor correction, load balancing, neutral current mitigation and mitigation of voltage and currents harmonics. A simple control algorithm based on Unit Vector Template (UVT) technique is used as a control strategy of UPQC for mitigation of different PQ problems. In this control scheme, the current/voltage control is applied over the fundamental supply currents/voltages instead of fast changing APFs currents/voltages, thereby reducing the computational delay. Moreover, no extra control is required for neutral source current compensation; hence the numbers of current sensors are reduced. The performance of the proposed topology of UPQC is analyzed through simulations results using MATLAB software with its Simulink and Power System Block set toolboxes.

Keywords—Power-factor correction, Load balancing, UPQC, Voltage and Current harmonics, Neutral current mitigation, Star-hexagon transformer.

I. INTRODUCTION

THE AC distribution systems are facing severe PQ problems such as high reactive power burden, voltage and current harmonics, poor power-factor, voltage sag, swells and voltage dip etc. There are various reasons behind this; some of these are increasing use of non-linear and poor-power factor loads at commercial, industrial and domestic purposes. Different devices such as rectifiers, inverters, adjustable speed drives, computer power supplies, furnaces and traction drives lead to non-linear current waveforms and hence degrade the quality of power. The quality degradation leads to low power-factor, low efficiency, overheating of transformers and so on [1]. In addition to this the load on a 3P-4W distribution system hardly found balanced. Because of this there is an excessive neutral current of fundamental and as well harmonic frequencies in the neutral conductor [2-3]. The power quality at the distribution system is limited by various standards [4-5] lay down by different agencies. Under the present deregulated

power market, adherence to different power quality standards has become a figure of merit for the utilities.

Custom Power Devices (CPDs) has been reported as a remedy for improving the quality and reliability of electric power distribution systems. D-statcom[6], DVR[7] and UPQC[8-15] are mainly three CPDs. The D-statcom is a shunt device, which mitigates current based distortions, while DVR is a series device, which is responsible for voltage based distortions. The UPQC is a combination of shunt and series APFs, which can provide balance, distortion-free and constant magnitude power to the sensitive load. In addition to this, it restricts the harmonic, unbalance, and reactive power demanded by the load and hence make the overall power distribution system more reliable and healthy [8-15].

Different topologies of 3P-4W UPQC are reported in literature for neutral current compensation along with other PQ problems. Some of these are three-leg VSI with split capacitor[9], three-single phase VSI[12], four-leg VSI[10],[14], current source inverter [15] etc. In case of split capacitor topology an extra control loop is required to maintain a zero voltage error difference between both the capacitor voltages, while three-single phase VSIs topology is bulky in nature, hence not attractive. Out of these reported topologies, the four-leg VSI topology is most popular, but has the disadvantages of greater number of semiconductor switches, complexity of control, etc.

Different applications of star-hexagon transformer are reported in literature [16-17]. For the mitigation of source neutral current, the uses of passive elements are advantageous over the active compensation due to ruggedness and less complexity of control. For the mitigation of source neutral current along with other current based distortions, the integration of readily available three-leg VSI with star-hexagon transformer has been reported in literature for three-phase four-wire D-Statcom[6]. Unfortunately, the performance of the star-hexagon transformer for neutral current mitigation is affected to an extent under distorted or unbalanced source voltages, which is very common in practice. As the UPQC takes care of both voltage and current based distortions simultaneously; hence the integration of star-hexagon transformer for neutral current compensation with UPQC is more justified.

This paper proposes a new topology/structure for 3P4W UPQC, in which a star-hexagon transformer is connected near the load along with readily available three-leg VSI of shunt APF. The hexagon connected secondary winding of the transformer provides a path for the zero sequence fundamental current and harmonics currents and hence mitigates the source neutral current. In addition to this, by connecting a star-hexagon transformer in shunt on the load side, the rating of the UPQC is reduced due to elimination of a fourth leg compared to three-phase four-leg VSI based UPQC. The

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performance of this proposed structure/topology is evaluated for power-factor correction, source neutral current compensation, load balancing, current harmonic mitigation and voltage harmonic mitigation.

Different control strategies reported in the literature to determine the reference values of the voltage and the current of three-phase four-wire UPQC, the most common are the p-q-r theory[9], modified single-phase p-q theory[10], synchronous reference frame(SRF) theory[11], symmetrical component transformation [12], and unit template technique(UTT) [13] etc. Apart from this one cycle control (OCC) [14] (without reference calculation) is also used for the control of three-phase, four-wire UPQC. In this paper a simplified control algorithm based UTT is used as a control scheme for the UPQC system. In this control scheme, the current/voltage control is applied over the fundamental supply currents/voltages instead of fast changing APFs currents/voltages, thereby reducing the computational delay. Moreover, by connecting a star-hexagon transformer on load side, no extra control is required for source neutral current, hence numbers of current sensors are reduced.

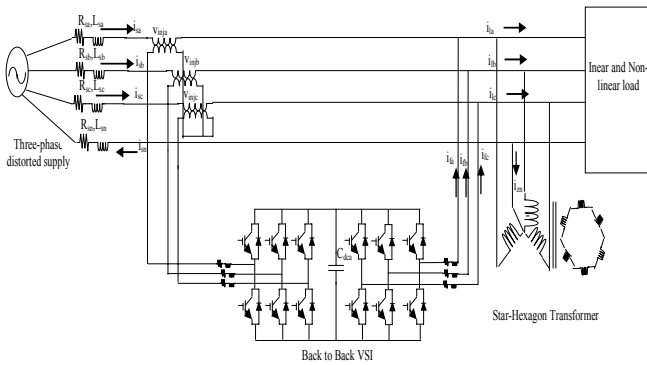


Fig. 1 Detailed Configuration of Proposed 3P-4W UPQC

II. SYSTEM CONFIGURATION AND DESIGN

Fig. 1 shows the proposed topology of 3P-4W UPQC, which is feeding a combination of linear and non-linear unbalanced load. The series and shunt APFs are realized using two readily available three-leg VSIs. The dc link of both APF is connected to a common dc link capacitor. The series APF is connected between the supply and load terminals using three single phase transformers with turn's ratio of 5:1. The primary winding of these transformer are star connected and the secondary windings are connected in series with the three-phase supply. In addition to provide the required injecting voltages, these transformers are used to filter the switching ripple content in the series APF. A small capacity rated R-C filter is connected in parallel with the secondary of each series transformer to eliminate the high switching ripple content in the series APF injected voltage. The voltage source inverters for both the APFs are implemented with Insulated gate Bipolar Transistors (IGBTs). In Fig.1 (i_{sa}, i_{sb}, i_{sc}), (i_{la}, i_{lb}, i_{lc}) and (i_{fa}, i_{fb}, i_{fc}), represent the source currents, load currents and shunt APF currents in phase a, b and c respectively. The source neutral current, load neutral current and neutral current

of the additional connected transformers are represented by i_{sn} , i_{ln} and i_{Tn} , respectively. The injected voltages by the series APF in phase a, b and c is represented by V_{inja} , $V_{inj b}$ and $V_{inj c}$, respectively.

In Fig.1, a star-hexagon transformer is connected in shunt near the load for the mitigation of the source neutral current. The hexagon connected secondary winding of the transformer provides a path for the zero sequence fundamental current and harmonics currents, hence the neutral current is effectively compensated. The load under consideration is a combination of linear and non-linear load. Two single-phase lagging power-factor loads are taken as unbalanced linear load, where as a three-phase diode bridge rectifier with a resistive load on dc side is considered as a non-linear load. The values of the circuit parameters and load under consideration are given in Appendix. The selection criteria of interfacing inductor, dc capacitor, ripple filter and star-hexagon transformer is given in the following section.

A. DC Capacitor voltage

The value of the common link DC bus voltage of back to back connected VSIs of the UPQC depends on the instantaneous energy available to the UPQC [18]. For a VSI the DC link voltage is defined as

$$V_{dc} = \frac{2\sqrt{2}V_{LL}}{\sqrt{3}m} \quad (1)$$

where m is the modulation index and V_{LL} is the ac line out voltage of UPQC. Considering modulation index as 1 and for line to line voltage ($V_{LL}=415$ V), the V_{dc} obtained is 677.69 V and is selected as 700 V.

B. DC Bus voltage

The value of dc capacitor (C_{dc}) of back to back connected VSIs of the UPQC depends on the change of DC voltage during increase and decrease of the load. Using the principle of energy conservation, the equation [20] for C_{dc} is as follows

$$\frac{1}{2} C_{dc} \left[(V_{dc}^2) - (V_{dc1}^2) \right] = 3V(\alpha I) t \quad (2)$$

where V_{dc} is the reference dc voltage and V_{dc1} is the minimum voltage level of dc bus, α is the overloading factor, V is the phase voltage, I is the phase current, and t is the time by which the dc bus voltage is to be recovered.

Considering the minimum voltage level of dc the bus, $V_{dc1}=690$ V, $V_{dc}=700$ V, $V=415/\sqrt{3}=239.60$ V, $I=25.40$ A, $t=350\mu s$, $\alpha=1.2$, the calculated value of C_{dc} is 2340 μF . Hence C_{dc} is selected as 3000 μF .

C. AC Inductor

The selection of the ac inductance (L_f) of VSI depends on the current ripple $i_{cr,p-p}$, switching frequency f_s , dc bus voltage (V_{dc}), and L_f is given as [18]

$$L_f = \frac{\sqrt{3}mV_{dc}}{12 \alpha f_s i_{cr(p-p)}} \quad (3)$$

where m is the modulation index and α is the overload factor. Considering, $i_{cr,p-p}=2.5\%$, $f_s=10$ KHz, $m=1$, $V_{dc}=700$ V, $\alpha=1.2$, the L_f value is calculated to be 4.88 mH. A round-off value of L_f of 5 mH is selected in this work.

D. Ripple Filter

A low-pass first-order filter at half the switching frequency is used to filter the high-frequency noise from the injected voltage of series APF. Considering a low impedance of 8.1Ω for the harmonic voltage at half the switching frequency $10\text{ KHz}/2=5\text{ KHz}$, the ripple filter capacitor is designed as $C_f=5\mu\text{F}$. A series resistance (R_f) of 7Ω is included in series with the capacitor (C_f). The impedance is found to be 638Ω at fundamental frequency, which is sufficiently large, and, hence, the ripple filter draws negligible fundamental current.

E. Design of Star-hexagon transformer [6]

The hexagon-connected secondary winding of the star-hexagon transformer provides a path for the zero sequence fundamental currents and hence the source neutral current is mitigated. The connection diagram of star-hexagon transformer is shown in Fig. 2(a), while Fig. 2 (b) shows the phasor diagram.

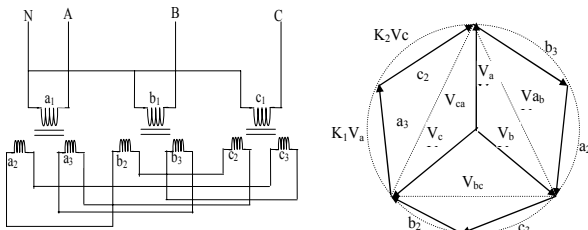


Fig. 2(a) Star-hexagon transformer. (b) Phasor diagram

From the phasor diagram the V_{ca} can be written in terms of phase voltages V_a and V_c are the per equation (4).

$$V_{ca} = K_1 V_a - K_2 V_c \quad (4)$$

where K_1 and K_2 are the fraction of winding in the phases. Considering phase 'a' as reference and putting the values of V_a , V_c and V_{ca} in equation(7), we get the following relationship

$$\sqrt{3}V\angle 30^\circ = K_1 V\angle 0^\circ - K_2 V\angle -120^\circ \quad (5)$$

One gets, $K_1=K_2=1$

For a line to line voltage of 415 V, we get

$$V_a = V_b = V_c = \frac{415}{\sqrt{3}} = 239.6V$$

Hence, three single-phase transformers with turn's ratio 1:1 of rating 5KVA, 240 V/240 V/240 V are selected.

III. CONTROL SCHEME OF SERIES APF

A simple control algorithm based on UVT is used to control the series APF of proposed topology. The series is controlled in such a way that it injects voltages ($V_{inj a}$, $V_{inj b}$ and $V_{inj c}$), which cancel out the distortions present in the supply voltages (v_{sa} , v_{sb} and v_{sc}), thus making the voltages at PCC (v_{la} , v_{lb} and v_{lc}) perfectly sinusoidal with the desired amplitude. In other words, the sum of supply voltage and the injected series filter voltage makes the desired voltage at the load terminals. The control strategy for the series APF is shown in Fig. 3. Three-phase distorted supply voltages are sensed and given to

PLL which generates two quadrature unit vectors ($\sin\omega t, \cos\omega t$). The in-phase sine and cosine outputs from the PLL are used to compute the supply in phase, 120° displaced three unit vectors (u_a, u_b, u_c) using eqn.(6) as:

$$\begin{bmatrix} u_a \\ u_b \\ u_c \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} \sin \theta \\ \cos \theta \end{bmatrix} \quad (6)$$

The computed three in-phase unit vectors then multiplied with the desired peak value of the PCC phase voltage (V_{lm}^*), which becomes the three-phase reference PCC voltages as:

$$\begin{bmatrix} v_{la}^* \\ v_{lb}^* \\ v_{lc}^* \end{bmatrix} = V_{lm}^* \begin{bmatrix} u_a \\ u_b \\ u_c \end{bmatrix} \quad (7)$$

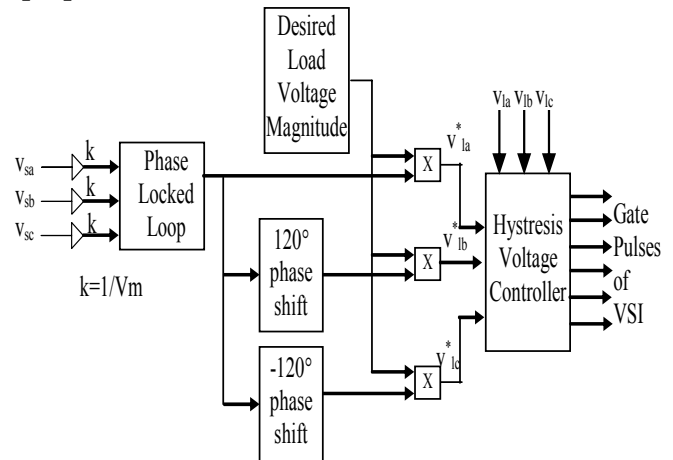


Fig. 3(a) Control Scheme of Series APF

The desired peak value of the PCC voltage under consideration is $338V (=415\sqrt{2}/\sqrt{3})$. The computed voltages from reference voltages from eqn.(2) are then given to the hysteresis voltage controller along with the sensed three phase PCC voltages (v_{la} , v_{lb} and v_{lc}). The output of the hysteresis controller is switching signals to the six switches of the VSI of series APF. The hysteresis controller generates the switching signals such that the voltage at PCC becomes the desired sinusoidal reference voltage. Therefore, the injected voltage across the series transformer through the ripple filter cancels out the harmonics present in the supply voltage.

IV. CONTROL SCHEME OF SHUNT APF

The control algorithm for shunt APF consists of the generation of three-phase reference supply currents (i_{sa}^* , i_{sb}^* and i_{sc}^*) and it is depicted in Fig.4. This algorithm uses supply in-phase, 120° displaced three unit vectors computed in eqn.(3). The amplitude of the reference supply current (I_{sp}^*) is computed from the comparison of average and the reference value of the dc bus voltage of the back to back connected VSIs results in voltage error, which is fed to a proportional integral (PI) controller. The output of the PI controller is taken as the reference amplitude (I_{sp}^*) of the supply currents. The three in-phase reference supply currents are computed by multiplying their amplitude (I_{sp}^*) and in-phase unit current vectors as:

$$\begin{bmatrix} i_{sa}^* \\ i_{sb}^* \\ i_{sc}^* \end{bmatrix} = I_{sp}^* \begin{bmatrix} u_a \\ u_b \\ u_c \end{bmatrix} \quad (8)$$

The computed three-phase supply reference currents are compared with the sensed supply currents and are given to a hysteresis current controller to generate the switching signals to the switches of the shunt APF which makes the supply currents follow its reference values. In this control scheme, the current control is applied over the fundamental supply currents instead of the fast changing APF currents, thereby reducing the computational delay. With the integration of star-hexagon transformer, no extra control is required for the mitigation of source neutral current; hence numbers of current sensors are reduced.

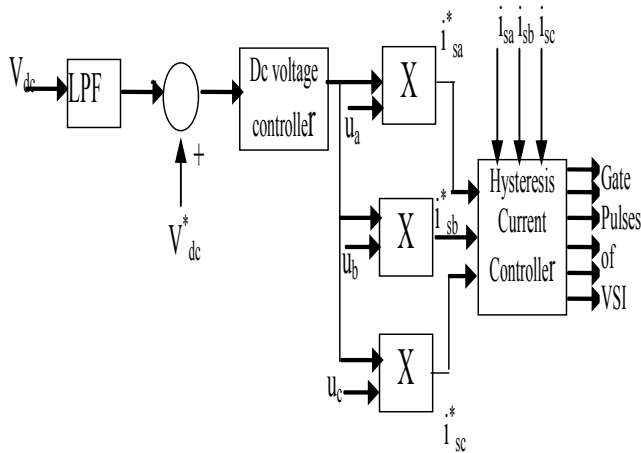


Fig.4 Control Scheme of Shunt APF

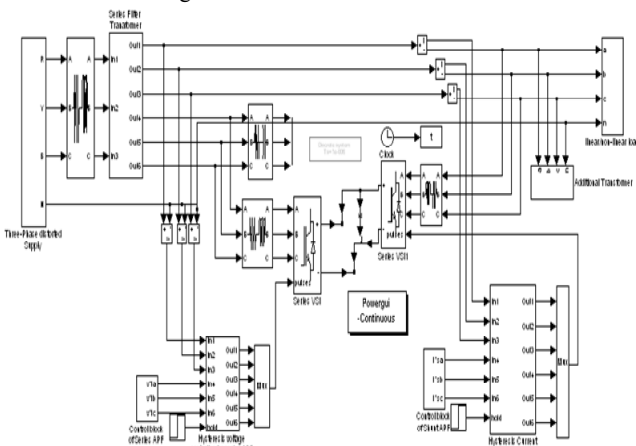


Fig.5 MATLAB model of proposed 3P-4W UPQC

V. RESULTS AND DISCUSSION

The developed model of the proposed UPQC system using MATLAB/SIMULINK environment is shown in Fig.5. The distortion in utility voltage is introduced deliberately by injecting 5th, 7th order voltage harmonics along with the fundamental. The combination of unbalanced linear and non-linear load is considered to verify the effectiveness of UPQC for load balancing, power-factor correction, current harmonic mitigation and neutral current compensation. A lagging load is

considered as a linear load, while a diode bridge rectifier drawing constant dc current is considered as the non-linear load. In order to consider the unbalanced load, two-single phase linear load are connected in phase 'b' and 'c' only. The series transformer, ripple filters and APFs are developed using the Power System Blockset toolbox.

Fig.6 shows the response of a three-phase four-wire UPQC with Star-hexagon transformer at the load side. At t=0.05 sec both the shunt and series APF are switched on simultaneously. It is observed from Fig.6 (d) that the supply currents are balanced and sinusoidal while, the load currents are distorted and unbalanced, as shown in Fig.6(e). It is also observed from the Fig.6(g) that source current and source voltage in phase 'a' are exacting in phase, hence shunt APF is compensating for the reactive power along with load balancing and current harmonic mitigation. Fig.6(i) shows that there is a neutral load current because of the unbalanced load, but the star-hexagon transformer is able to mitigate the neutral current as shown in Fig.6(h). Fig. 6(i) shows the neutral current of the star-hexagon transformer, which is exactly opposite to the load neutral current.

In addition to this, the series APF starts compensating voltage harmonics immediately by injecting out of phase harmonic voltage, making load voltage at load distortion free. The voltage injected by series APF is shown in Fig. 6 (c). Fig. 6(k) shows that during the operation of UPQC dc voltage across the capacitor of back to back VSI is maintained to its reference value. In phase 'c' the THD of load current THD is 15.03%, while the THD of source current is 2.76% as shown in Fig.7 and Fig.8, respectively. The harmonic spectrum of load voltage before compensation is shown in Fig.9, while the harmonic spectrum of load voltage after compensation is shown in Fig.10. The load voltage THD is improved from 7.75% to 1.57 %.

VI. CONCLUSION

The effectiveness of the proposed UPQC topology has been demonstrated for voltage, harmonic elimination, mitigation of current harmonics, load balancing and power-factor correction. Supply currents and load voltage harmonics levels are maintained below IEEE-519 standards under all conditions. The secondary of the star-hexagon transformer connected near the load, in shunt, effectively compensates the source neutral current. By connecting a star-hexagon transformer on the load side, the rating of the UPQC is reduced due to elimination of a fourth leg compared to three-phase four-leg VSI based. In addition to this no extra control is required for the mitigation of neutral current, hence number of current sensors are reduced.

APPENDIX

The system parameters used are as follows:
Supply voltage: 415 V (L-L) RMS, 50Hz.
Supply impedance: 1.5mH, 0. 1Ω.
DC link capacitance value: 3000μF
DC link voltage: 700 V

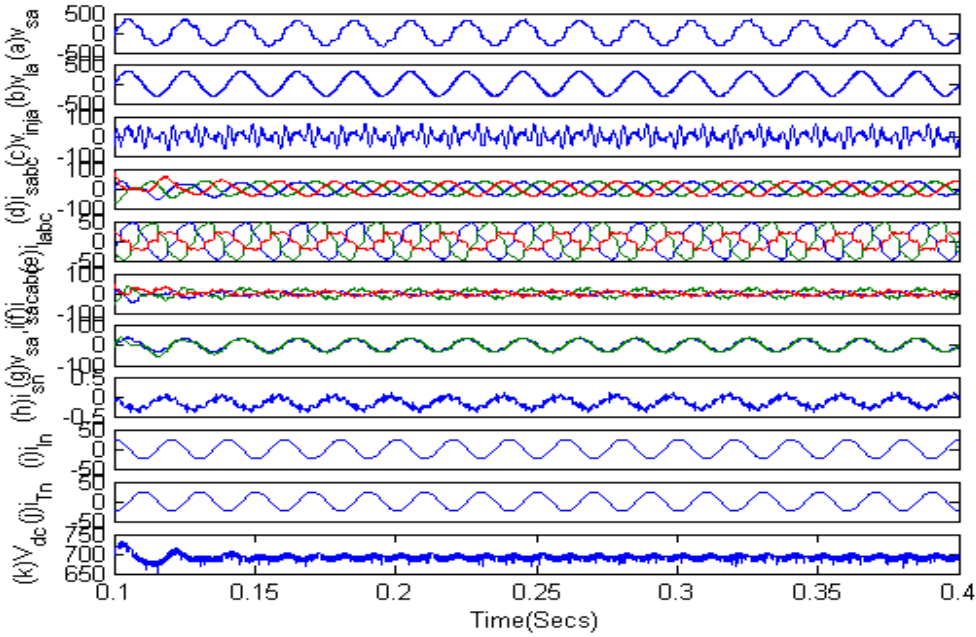


Fig.6. Performance of Proposed 3P-4W UPQC

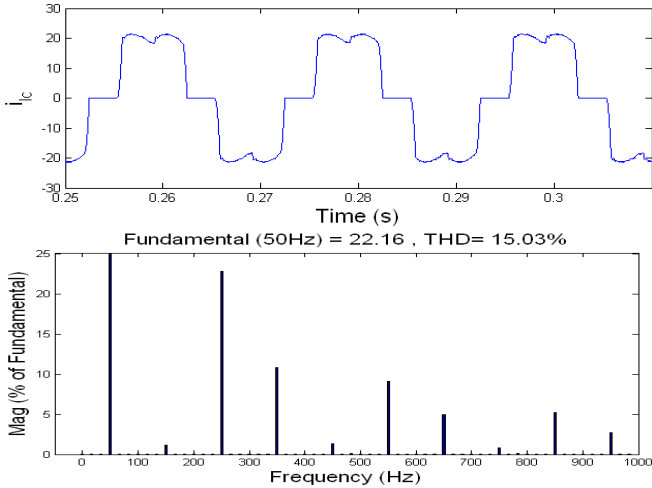


Fig.7 Load current and its harmonic spectrum

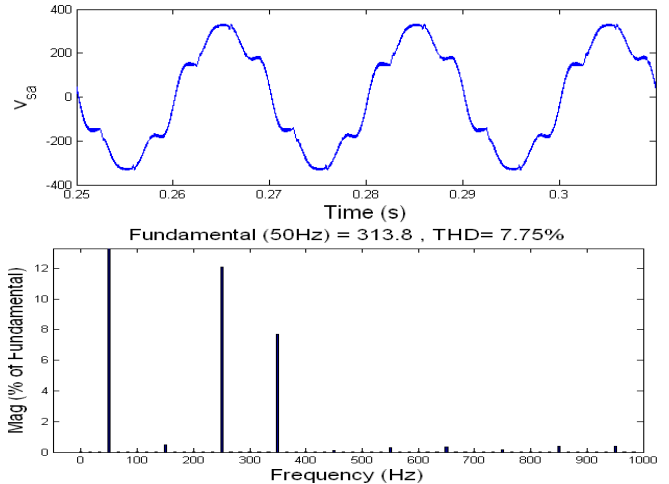


Fig.9 Supply voltage and its harmonic spectrum

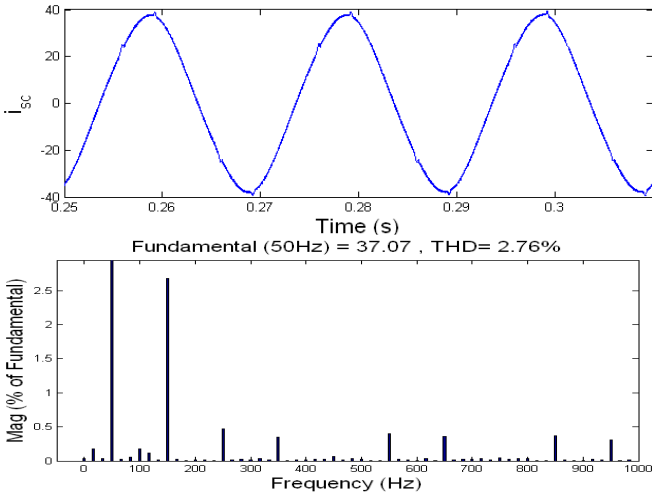


Fig.8 Supply current and its harmonic spectrum

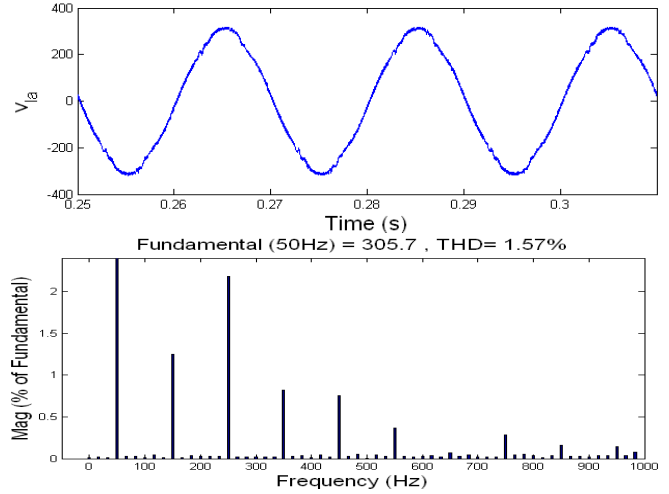


Fig.10 PCC voltage and its harmonic spectrum

Ripple filter: 7Ω , $5\mu\text{F}$

$K_p=2$, $K_i=2$

Transformer: 250MVA, 58KV/12KV

Linear load: 12KW, 8KVar lagging load in phase 'a' and 'b'

Non-Linear load: Three-Phase Rectifier Load $R=15$ on dc side.

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