

Figure 4-3 defines the geometry for limb scans.

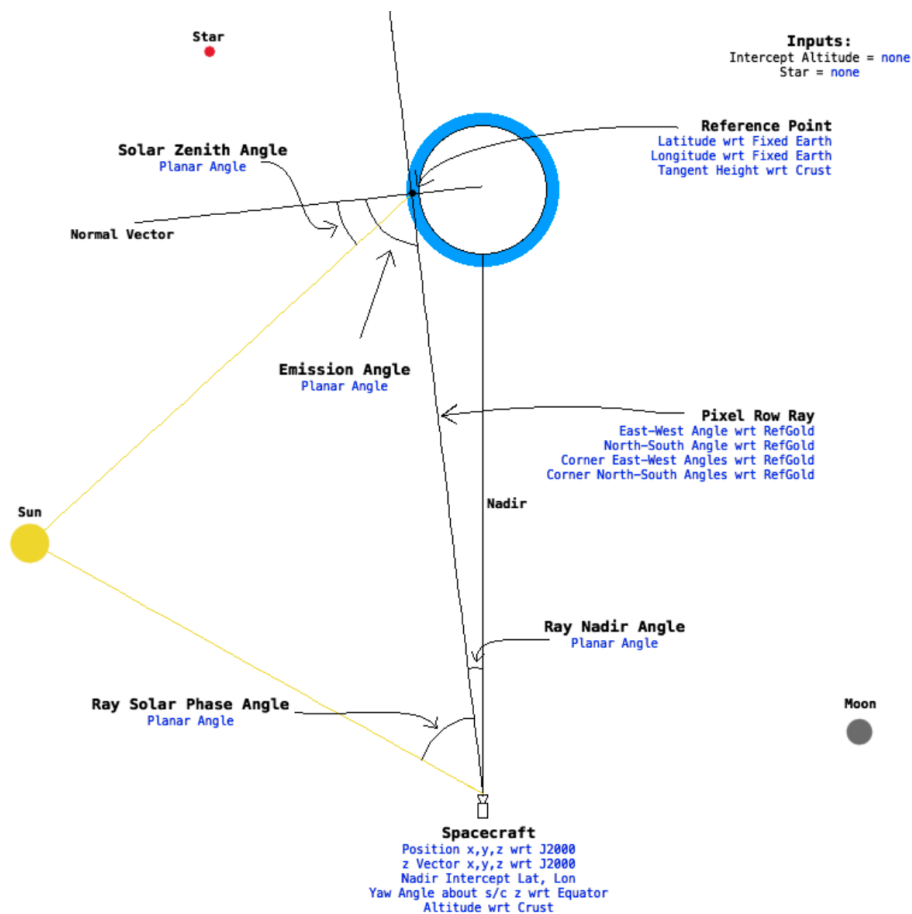


Figure 4-3 Geolocation geometry for limb scan observations.