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Topic choice: Sensory and Perceptual Processes

**The Development and Evaluation of Countermeasures  
to Tactile Change Blindness**

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20 **Abstract (250 words)**

21

22 **Objective:** The goal of the present study was to develop and empirically evaluate three  
23 countermeasures to tactile change blindness (where a tactile signal is missed in the presence of a  
24 tactile transient). Each of these countermeasures relates to a different cognitive step involved in  
25 successful change detection.

26 **Background:** To date, change blindness has been studied primarily in vision but there is  
27 limited empirical evidence that the tactile modality may also be subject to this phenomenon. This  
28 raises concerns regarding the robustness of tactile and multimodal interfaces.

29 **Method:** Three countermeasures to tactile change blindness were evaluated in the context  
30 of a highly demanding monitoring task. One countermeasure was proactive (alerting the  
31 participant to a possible change before it occurred) while the other two were adaptive (triggered  
32 after the change upon an observed miss). Performance and subjective data were collected.

33 **Results:** Compared to the baseline condition, all countermeasures improved intramodal  
34 tactile change detection. Adaptive measures resulted in the highest detection rates, specifically  
35 when signal gradation was employed (i.e., when the intensity of the tactile signal was increased  
36 after a miss was observed).

37 **Conclusion:** Adaptive displays can be used to counter the effects of change blindness and  
38 ensure that tactile information is reliably detected. Increasing the tactile intensity after a missed  
39 change appears most promising and was the preferred countermeasure.

40 **Application:** The findings from this study can inform the design of interfaces employing  
41 the tactile modality to support monitoring and attention management in data-rich domains.

42 **Keywords:** Change blindness, tactile information presentation, multimodal interfaces, adaptive

43 displays, signal gradation

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## 50 WORD PRÉCIS

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Three countermeasures to tactile change blindness (the failure to detect a tactile change in the presence of a tactile transient) were evaluated. Signal gradation (increasing the intensity of the tactile signal after a miss) was most effective. Our findings help inform the design of tactile displays in various data-rich domains.

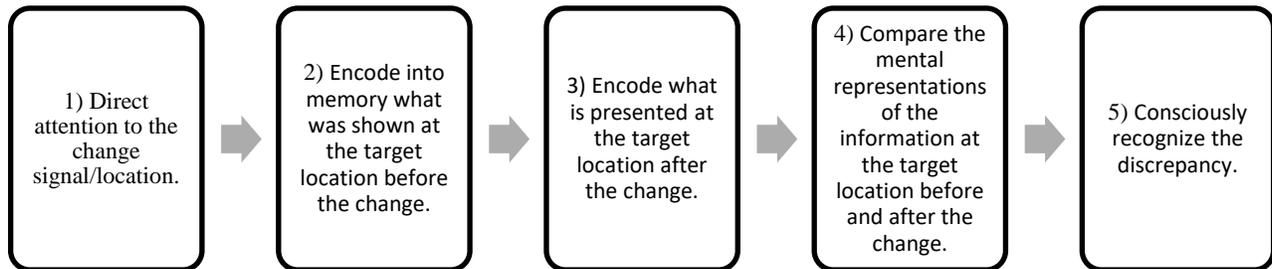
## INTRODUCTION

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Data overload, especially in the visual channel, represents a major challenge in complex data-rich domains (e.g., Sarter, 2000; Sarter, 2007a; Woods, 1995). One promising means of addressing the problem is the introduction of multimodal interfaces which distribute information across multiple sensory channels, primarily vision, audition and touch. This approach has been shown to be effective in offloading the visual channel which is increasingly overburdened in several domains (e.g., aviation or the operating room; Sarter, 2006a, 2006b, 2007a; Ferris & Sarter, 2011). Presenting information via this channel helps support functions such as spatial orienting, navigation tasks, and the communication of complex concepts and messages (Jones & Sarter, 2008; Oviatt, 2003; Sarter, 2002). However, the effectiveness of tactile interfaces may be compromised if their design does not take into consideration limitations of human perception and cognition. One such limitation is a phenomenon called change blindness, where a person misses a signal when it coincides with another event or disruption (i.e., a transient).

To date, the phenomenon has been studied primarily in vision, but there is now also empirical evidence that the tactile modality can be subject to change blindness. For example, a significant performance decrement was observed when subjects had to distinguish between simple vibrotactile patterns from 2-3 tactors (devices that present vibration stimuli to the skin) located across the body in the presence of a vibrotactile mask (vibrotactile stimulation from tactors not related to the pattern of interest; Ferris, Stringfield, & Sarter, 2010; Gallace et al., 2006; Gallace, Tan, & Spence, 2007). Even when the tactile stimuli were presented to the highly touch-sensitive fingertip region, change blindness was elicited in the presence of a tactile transient (Malika, Gallace, Hartcher-O'Brien, Tan, & Spence, 2008). Finally, manual control

75 actions, such as pressing a button or turning a steering wheel, have also been shown to elicit  
76 tactile change blindness (Gallace, Zeeden, Röder, & Spence, 2010). These findings raise  
77 concerns regarding the effectiveness and robustness of tactile and multimodal interfaces. To  
78 address this concern, the present study focuses on the development and evaluation of three  
79 design-based countermeasures to tactile change blindness, which relate to the cognitive steps  
80 involved in successful change detection (Figure 1).



81

82 *Figure 1: Cognitive steps required for successful change detection (Jensen, Yao, Street, &*  
83 *Simons, 2011)*

84

85 The three countermeasures were intended to support various combinations of the first  
86 four steps. Since attention is necessary for change detection (Simons, 2000), all three  
87 countermeasures were designed to direct attention to the change (step 1). The first  
88 countermeasure, “attention guidance,” is proactive: it consists of increasing the frequency (i.e.,  
89 pulse rate) of the tactile cue right **before** a potential change, with the goal to support encoding of  
90 the pre-change cue intensity (step 2). The second and third countermeasures are reactive, i.e.,

91 they are triggered by an observed failure to notice a change. Countermeasure 2 – “signal  
92 gradation” – involves a further increase in the intensity of the tactile signal following a missed  
93 change. The third countermeasure – “direct comparison” – presents the participant with a tactile  
94 signal first at the low (pre-change) and then the high (post-change) intensity, with no interval  
95 separating the two, if a change was missed. This approach is expected to improve detection rates  
96 by supporting relative (as opposed to absolute) judgments and comparisons of cue intensities  
97 before and after a change.

98         The second and third countermeasures represent examples of adaptive information  
99 presentation where the timing and/or nature of a signal or display are adjusted automatically in a  
100 context-sensitive fashion (Sarter, 2007b; Scerbo, 1996; Trumbly, Arnett, & Johnson, 1994). The  
101 need for context-sensitive information presentation has been widely acknowledged (Bennet &  
102 Bennet, 2003; Dorneich et al., 2003; Schmorow & Kruse, 2002). However, no consensus has  
103 been reached on the most appropriate and effective implementation of such flexible information  
104 presentation.

105         Gradation – the type of adaptation used for the second countermeasure – consists of  
106 varying over time the salience or intensity of a signal to reflect changes in the urgency of the  
107 associated task or event. This approach has been shown to be highly effective in alarm design.  
108 For instance, Lee, Hoffman, and Hayes (2004) contrasted graded and single-stage tactile  
109 warnings in the context of a driving task as part of a collision warning system. The intensity of  
110 three tactile warnings (vibrations of the seat) changed over time and corresponded to the severity  
111 of the required braking action, i.e., high, medium, or negligible. The authors found that graded  
112 warnings led to an increased time to collision, indicating a greater margin of safety compared to  
113 the single-stage warnings. A similar approach was adopted here by increasing the intensity of the

114 tactile signal following a missed change. Findings from earlier experiments showed that simply  
115 repeating the tactile signals (after a change) at the same intensity is not sufficient to ensure  
116 change detection (Lu & Sarter, 2014).

117 Countermeasure 3 is adaptive in that it is triggered by a failure of the participant to notice  
118 a change in signal intensity. In this case, the tactile signal following the change is applied first at  
119 the low (pre-change) and then the high (post-change) intensity, with no interval separating the  
120 two. The goal here is to support step 4 (in addition to step 1) – the comparison of the information  
121 before and after the change – and to do so without requiring a prolonged retention of a mental  
122 representation of the initial signal. Instead, the participant can make a relative judgment of the  
123 two signals presented side-by-side.

124 The above three countermeasures to tactile change blindness were evaluated in the  
125 context of monitoring multiple sources of simultaneous information in an event-driven setting.  
126 Real-world examples of this task include monitoring of sensor operations, security systems, and  
127 of video feeds from multiple remote vehicles. For the purposes of this study, we focused on the  
128 latter task. Specifically, participants in this study were required to detect two types of targets  
129 while monitoring video feeds from nine Unmanned Aerial Vehicles (UAVs).

130

### 131 **Hypotheses**

132

133 We expected the three countermeasures to have the following effects on participants'  
134 performance and preferences:

135

- 136 1) All three countermeasures were expected to lead to improved performance, compared  
137 to no countermeasure in terms of higher change detection rates (referred to as ‘hit  
138 rates’ from this point on) and better multitasking performance.
- 139 2) Correct rejection rates will be higher with ‘attention guidance’ because this  
140 countermeasure is triggered in advance of a change and prepares the participant for  
141 making a decision.
- 142 3) Of the three countermeasures, the two adaptive displays – signal gradation and direct  
143 comparison – will be preferred over ‘attention guidance’ because direct comparison  
144 will result in some false alarms.

145

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## METHODS

147

### 148 **Participants**

149

150 Twenty undergraduate and graduate students from the University of Michigan  
151 participated in this study (13 males and 7 females; mean age = 22.8, stdev = 2.8). Prior to data  
152 collection, all participants signed an informed consent form approved by the university’s  
153 Institutional Review Board (protocol number: HUM00072207). Participants were required to  
154 possess normal or corrected-to-normal vision, have no known disorders or injuries that may  
155 impair their sense of touch, and have no history of epilepsy (flickering displays may trigger  
156 epileptic seizures).

157

158 **Experimental setup**

159

160 Each participant monitored video feeds from nine UAVs and was responsible for  
161 responding to long-range radar indications in a simulated combat scenario. Long-range  
162 indications were potential targets that could not be seen in a UAV's field of view, but were  
163 detected by the UAV's radar system. The simulation ran on a 20" monitor positioned 30" from  
164 the participant. It displayed nine dynamic UAV feeds (Figure 2).



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166 *Figure 2: Screenshot of nine UAV video feeds on the monitor*

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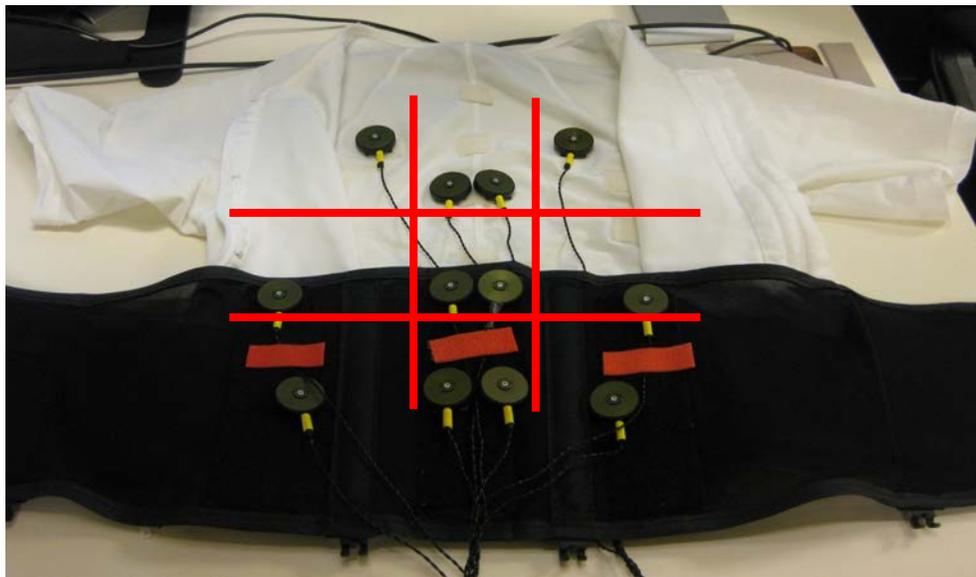
168 **Tactile display**

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170 Twelve C-2 tactors (electromagnetic devices; diameter: 2.97 cm; thickness: 0.76 cm;  
171 Engineering Acoustics, Inc.) applied vibrations to the participant's back to communicate the

172 (potential) presence of a long-range target. The tactors were attached to a vest (a medical  
173 compression garment designed to maintain a consistent pressure on the torso) and belt in a 3x3  
174 array (Figure 3). The location of the tactors mapped to the location of the nine video feeds on the  
175 monitor. Note that three pairs of tactors (as opposed to individual tactors) were placed in the  
176 central column to avoid direct contact with the spine (based on Prinnet, Terhune, & Sarter, 2012).  
177 Also, the tactors in the top row were not aligned vertically to account for the fact that the  
178 participants' shoulder blades would raise the vest slightly, resulting in tactors at the top of the  
179 middle column not being in contact with the person's back.

180



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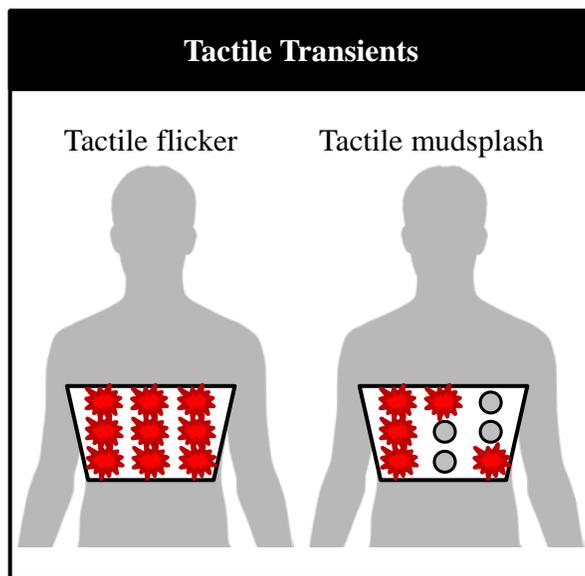
182 *Figure 3:* Tactor vest and belt divided into nine sectors to map to the nine UAV feeds on the  
183 monitor  
184

### 185 **Change blindness transient paradigms: Flicker and mudsplash**

186

187 The flicker and mudsplash paradigms used in this study were modeled after earlier visual  
188 and tactile change blindness studies (Ferris et al., 2010; Rensink, O'Regan, & Clark, 1997). In  
189 the case of a tactile flicker, a vibration (250 Hz, 14 dB) was presented at the same time as the

190 tactile target signal using all nine factor sectors. The tactile mudsplash employed a random  
191 selection of 4 to 6 of the factor sectors at the same intensity (250 Hz, 14 dB; Figure 4).  
192 Participants were told that the transient stimuli represented “bugs” or “interference” from the  
193 UAVs’ environment and to ignore them to the best of their ability. The tactile transients occurred  
194 2, 4, or 5 seconds after the start of a trial and lasted 500 msec.  
195



196

197 *Figure 4: Depiction of the implementation of tactile flickers and tactile mudsplashes*  
198

199 **Tasks**

200

201 Participants had to timeshare between a long-range and a short-range target detection  
202 task. They were instructed that both tasks were of equal importance.

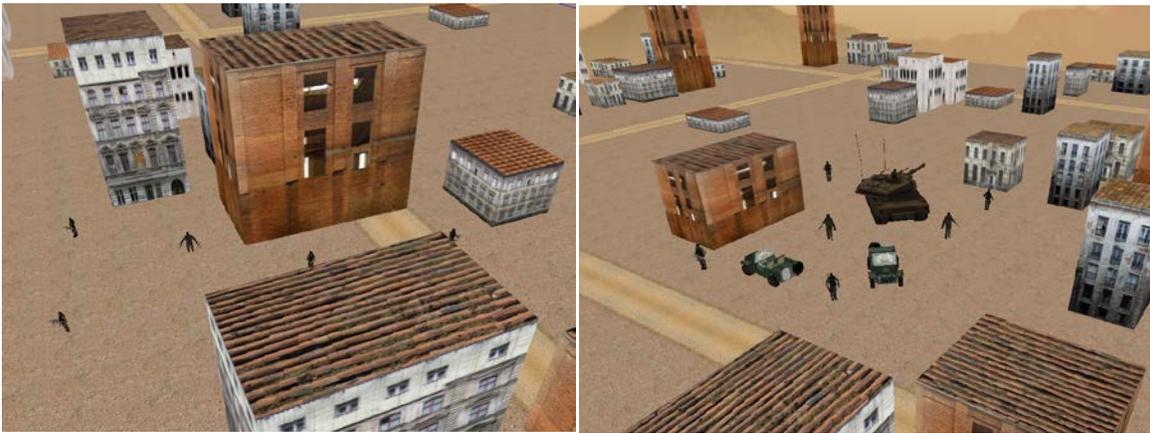
203

204 *Short-range target indications*

205

206 Participants were required to search for short-range targets that appeared in the  
207 highlighted UAV feed. Short-range targets included armed enemy soldiers, tanks, and other  
208 military vehicles (see Figure 5 for examples).

209



210

211 *Figure 5: Examples of short range targets that would require participants to press the ‘tank’*  
212 *button (see Figure 7)*  
213

214

215 *Long-range target indications*

216

217 A trial started when a UAV radar system detected a *potential* long-range target. The  
218 background of the corresponding UAV feed on the monitor was highlighted and the tactor  
219 corresponding to the relevant video feed began pulsing at a low intensity (250 Hz, 5.4 dB) and a  
220 rate of one pulse/750 msec to alert the participant to a possible threat (an example of visual  
221 highlighting is depicted in Figure 6).

222

223



224

225 *Figure 6:* Visual highlighting of screen to direct attention to the UAV feed of interest.  
226 Highlighting extinguished at the completion of each trial.  
227

228 If the potential target was benign ('no change' trial), the tactor continued to pulse at the  
229 low intensity for the entire 8.5-second trial. Otherwise, if the system ultimately deemed the  
230 potential target a threat ('change trial'), the vibration intensity would increase to a higher  
231 intensity (250 Hz, 10.8 dB) two, four, or five seconds after the start of a trial and remained at this  
232 higher intensity for the remainder of the 8.5-second trial. For 'change trials', the transient onset  
233 occurred simultaneously with the change in vibration intensity.

234 Participants used the buttons next to the respective UAV feed on the screen to indicate  
235 whether or not an intensity change had occurred. Pilot testing confirmed that a) visual  
236 highlighting of the relevant video feed did not result in any performance differences for tactile  
237 change detection and b) tactile changes could reliably be perceived, when presented in isolation,  
238 for all tactor locations.

239 To date, very few studies have examined tactile change detection in the context of multi-  
240 tasking (aside from Ferris et al., 2010) but doing so is important because it replicates the  
241 demands experienced by operators in most real world domains.

242

### 243 **Participant response**

244

245 When changes in tactile intensity were detected, participants were instructed to press the  
246 “Target” button on the top right hand corner of the respective UAV feed to indicate to Command  
247 Central the presence of a long-range target. If there was no change in brightness/intensity,  
248 participants were instructed to press the “No Target” button. If participants were unsure whether  
249 or not there was a change, they were instructed to press the “?/Unsure” button (see Figure 7 for  
250 each of the buttons). Participants could make and change their selection any time during the 8.5-  
251 second trial, with the final response being used for data analysis.

252 Since the attention guidance countermeasure was proactive, participants were instructed  
253 to press the target button after a change in tactile cue intensity was actually detected. In the  
254 signal gradation trials, participants were instructed to respond by pressing the ‘target’ button if  
255 they noticed either the initial change from low to medium tactile intensity or the further increase  
256 from medium to high intensity in case of a miss. Similarly, in the direct comparison trials,  
257 participants were told to press the ‘target’ button if they noticed either the original tactile change  
258 or the subsequent direct comparison in case of a miss.

259 For short-range targets, participants had to press the ‘tank’ button on the lower right-hand  
260 side of the video feed.

261



262

263 *Figure 7: One of the nine UAV feeds with associated response buttons labeled*  
264

265 **Countermeasures to tactile change blindness**

266

267 The tactile cues indicating the presence of a long-range target could take the form of  
268 either the above described baseline version, or they were augmented by one of three  
269 countermeasures. These countermeasures were pilot tested to ensure that they could be reliably  
270 detected and accurately interpreted by participants.

271

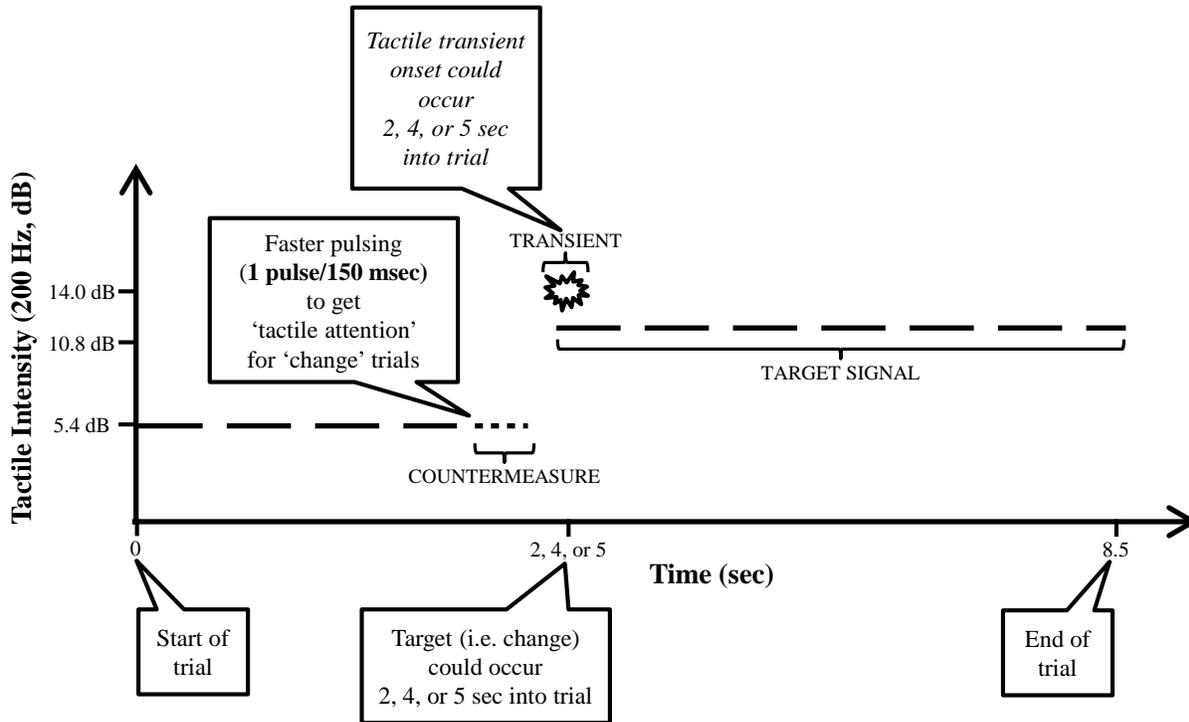
272 *Countermeasure 1: Attention guidance*

273

274 'Attention guidance' was a proactive measure that was employed during both 'change'  
275 and 'no-change trials' (i.e., independent of whether the trial actually involved a change in tactile  
276 intensity or not). The cue consisted of pulses at a rate of 1 pulse/150 msec for two seconds to  
277 prepare the participant for a potential change. Figure 8 provides a depiction of the attention

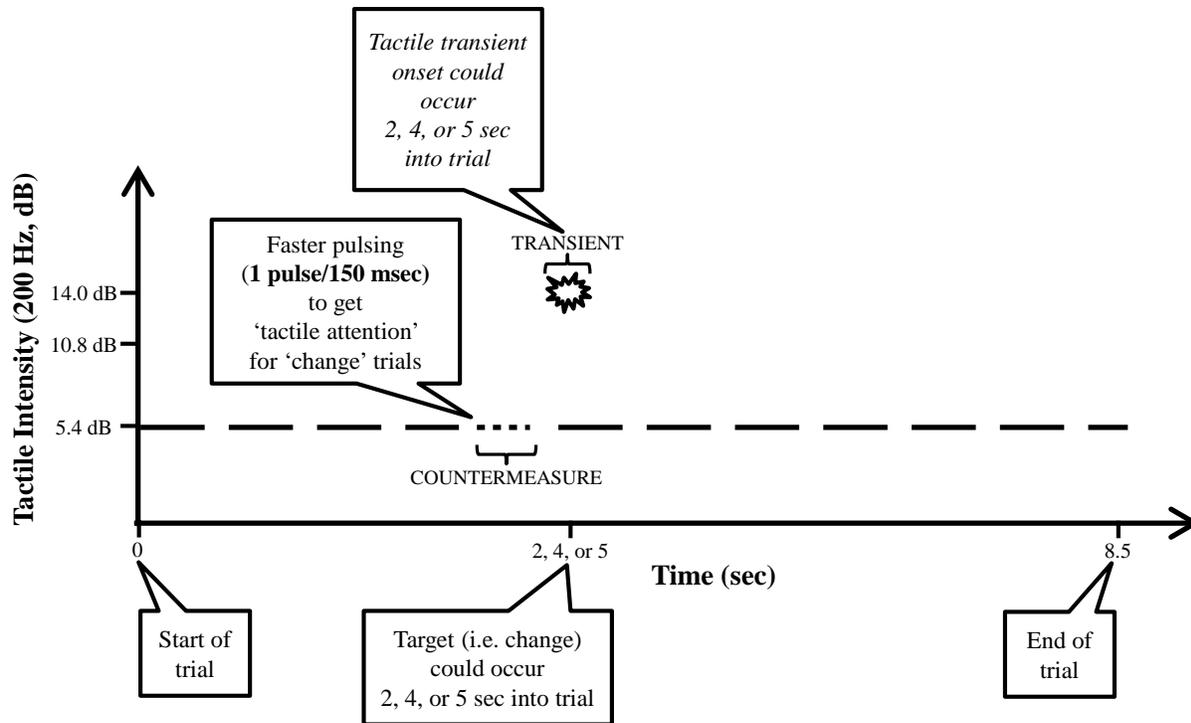
278 guidance cue and its relation to when an intensity change occurred (see Figure 9 for ‘no-change  
279 trials’).

280



282 *Figure 8: Attention guidance for one ‘change trial’ (dashed lines represents onset and duration of*  
283 *the tactile vibrations)*

284



285

286 *Figure 9: Attention guidance for one 'no-change trial' (dashed lines represents onset and*  
 287 *duration of the tactile vibrations)*

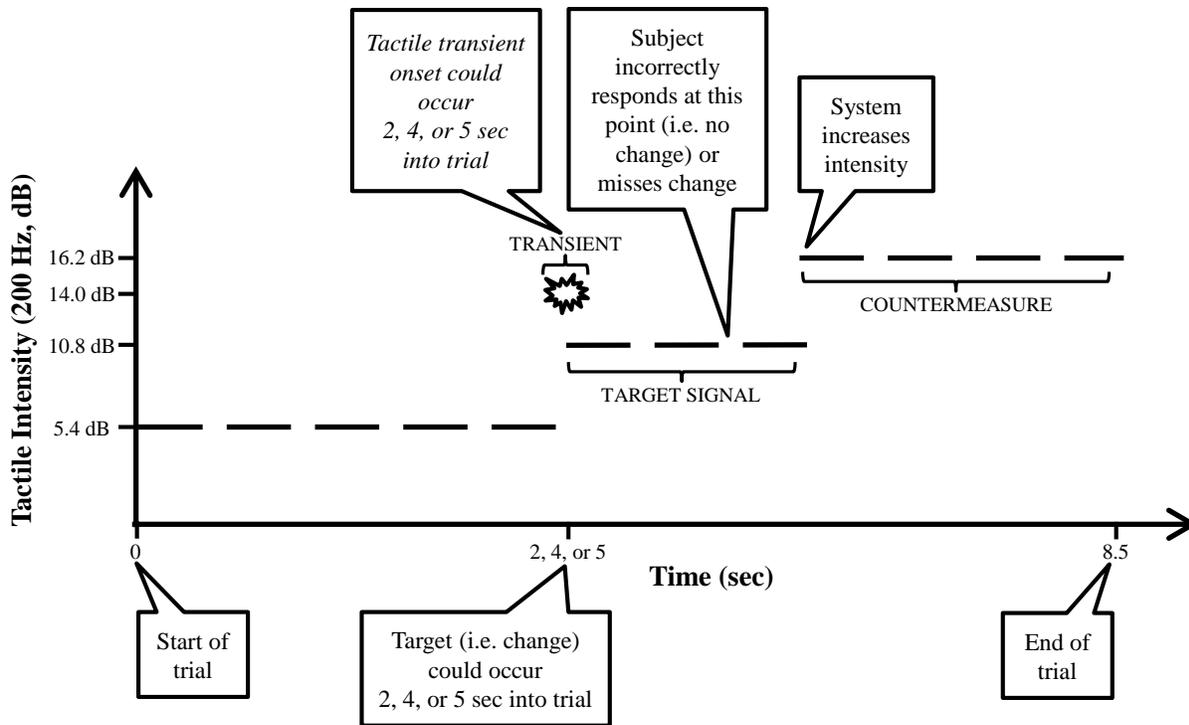
288

289 *Countermeasure 2: Signal gradation*

290

291 The signal gradation countermeasure was adaptive in nature, i.e. it was triggered 1.5 sec  
 292 after a change if the participant responded incorrectly by indicating that there was no change or  
 293 by not responding yet. The increased intensity cue was presented at 250 Hz, 16.2 dB which was  
 294 close to the maximum gain possible for the C-2 tactors. Figure 10 provides a depiction of the  
 295 signal gradation and its relation to the three tactile intensity levels.

296



297

298 *Figure 10: Signal gradation for a 'change trial' (dashed lines represent onset and duration of the*  
 299 *tactile vibrations)*

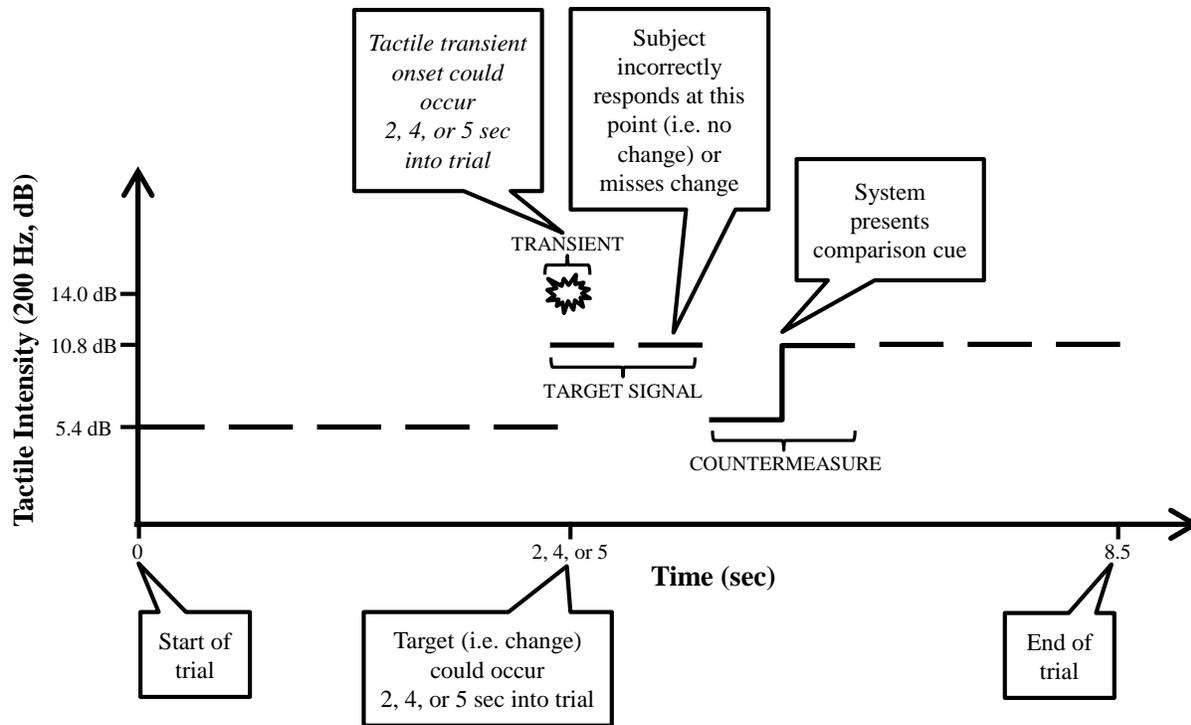
300

301 *Countermeasure 3: Direct comparison*

302

303 Like signal gradation, the direct comparison countermeasure was adaptive and occurred  
 304 1.5 sec after a change if the participant responded incorrectly by indicating that there was no  
 305 change, or by not responding at all. Figure 11 provides a depiction of the direct comparison and  
 306 its relation to the two tactile intensity levels.

307



308

309 *Figure 11: Direct comparison for one ‘change trial’ (dashed lines represents onset and duration*  
 310 *of the tactile vibrations)*

311

312 **Procedure**

313

314 Upon arrival, participants read and signed the consent form. After a brief explanation  
 315 describing the reason for conducting the study, the experimenter described the visual and tactile  
 316 cues, the participants’ tasks, and guided the participants through an interactive demonstration.  
 317 Next, participants completed two 8-minute training sessions which allowed them to practice the  
 318 tactile baseline combinations, i.e. the long-range target change detection task without the  
 319 presence of transients and countermeasures. Upon completion of the training sessions,  
 320 participants were given a demonstration of the tactile transients. Participants were asked to wear  
 321 headphones playing white noise to mask the sound of tactor activation. The participants then

322 completed four blocks of seventy 8.5-second trials: (1) no countermeasure, (2) attention  
323 guidance, (3) signal gradation, and (4) direct comparison.

324 For each countermeasure block, participants were given a demonstration of the  
325 countermeasure before the start of the respective block. The order of the four blocks was  
326 counterbalanced across subjects. After completing all four blocks, participants filled out a  
327 debriefing questionnaire which asked participants to rank in order each of the four tactile  
328 displays in terms of the following cue attributes: supporting change detection, annoyance,  
329 comfort, and overall preference. In total, the experiment lasted two hours.

330

### 331 **Experimental design**

332

333 This study employed an unbalanced nested design. The two main factors were cue-  
334 transient combination (tactile cue only; tactile cue with tactile flicker; tactile cue with tactile  
335 mudsplash) and countermeasure type (no countermeasure, attention guidance, signal gradation,  
336 and direct comparison). The design was unbalanced in that there were an unequal number of  
337 trials for each cue-transient combination. Since this study was interested in overcoming change  
338 blindness, there were more ‘change trials’ (56% of all trials), compared to ‘no-change trials’  
339 (44% trials) in each scenario. A short-range target appeared in 22% of the trials.

340

341 **Dependent measures**

342

343 The dependent measures were accuracy (detection of a change (i.e., target present and  
344 target button selected) and correct rejection when there was no change (i.e., target not present  
345 and no target button selected), multitasking performance, and participant preferences.

346

347 **RESULTS**

348

349 Repeated measures linear models (GLM formulation in SPSS 16.0) were used to identify  
350 main and interaction effects. For significant effects, two-tailed Fisher’s LSD post-hoc tests were  
351 performed to determine differences between means. Display preference was analyzed using a  
352 nonparametric Friedman test; a Bonferroni correction was performed for multiple pairwise  
353 comparisons.

354

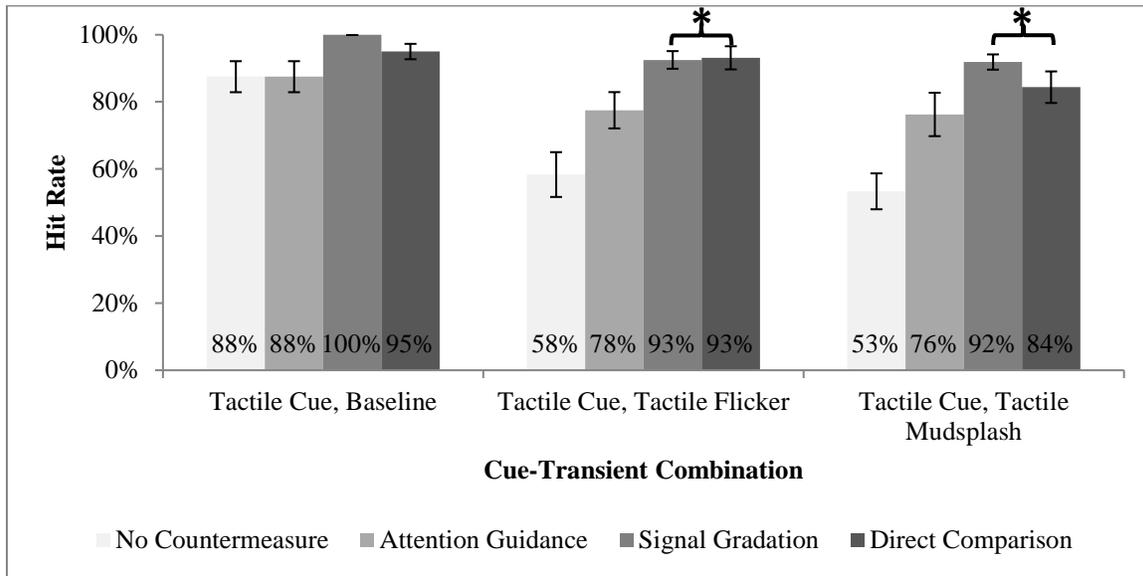
355 **Hit rate**

356

357 There was a significant effect of cue-transient combination ( $F(2,18) = 8.62, p = .002$ ),  
358 with hit rates being significantly higher in the ‘tactile, baseline’ combination compared to other  
359 intramodal tactile combinations (Figure 12). There was also a significant effect of  
360 countermeasure type ( $F(3,17) = 18.26, p < .001$ ), with post hoc tests showing that hit rates were  
361 the highest for signal gradation (hit rate = 95%) and direct comparison (91%), followed by  
362 attention guidance (81%,  $p < .029$  for both pairwise comparisons). Performance was worst with  
363 no countermeasure (66%;  $p = .004$ ). Finally, there was a cue-transient

364 combination\*countermeasure type interaction ( $F(6,14) = 3.27, p = .032$ ), such that in the  
 365 presence of tactile transients, signal gradation and direct comparison had the highest hit rates,  
 366 followed by attention guidance, and lastly no countermeasure.

367



368

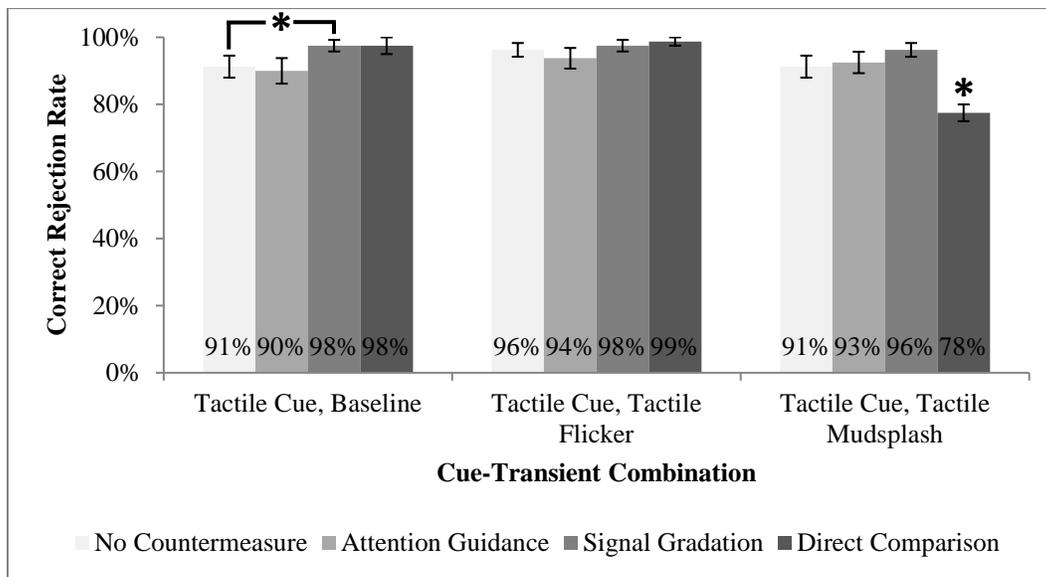
369 *Figure 12: Hit rate for the intramodal tactile cue-transient combinations for ‘change trials’*  
 370 *(error bars represent standard error; \* represent significant countermeasures; countermeasures*  
 371 *grouped by brackets are not significantly different from each other)*  
 372

373 **Correct rejection rate**

374

375 There was a significant effect of cue-transient combination ( $F(2,18) = 8.02, p = .003$ )  
 376 with correct rejection rates for the tactile mudsplash cases being significantly lower than for the  
 377 tactile flicker trials (94%,  $p = .001$ ; Figure 13). There was also a significant effect of  
 378 countermeasure type ( $F(3,17) = 4.30, p < .001$ ), with correct rejection rates being the highest for  
 379 signal gradation (correct rejection = 97%), and significantly higher than direct comparison and  
 380 no countermeasure, but not attention guidance (92%;  $p < .029$  for both pairwise comparisons).

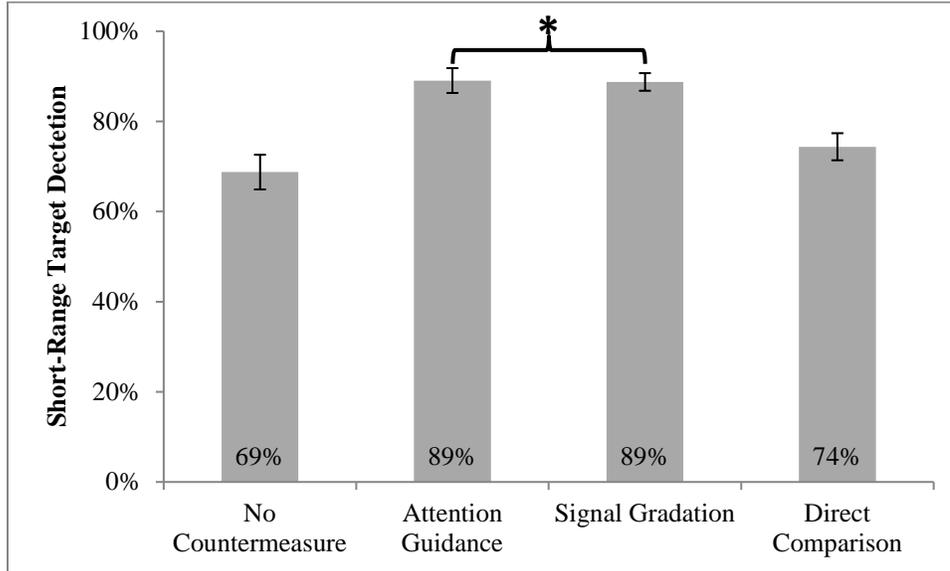
381 Finally, there was a cue-transient combination\*countermeasure type interaction ( $F(6,14) = 10.25$ ,  
 382  $p < .001$ ). Post hoc tests showed that for the ‘tactile cue, baseline’ combination, the rejection  
 383 rates for signal gradation (98%) were significantly higher than no countermeasure (91%;  $p =$   
 384  $.021$ ) and for the ‘tactile cue, tactile mudsplash’ combination and rejection rates were  
 385 significantly lower for the direct comparison, compared to all other countermeasures ( $p < .001$   
 386 for all pairwise comparisons).  
 387



388  
 389 *Figure 13: Correct rejection rates for the intramodal tactile cue-transient combinations for ‘no-*  
 390 *change trials’ (error bars represent standard error; \* represent significant and/or significance*  
 391 *between countermeasures)*  
 392

393 **Multitasking performance**

394  
 395 Figure 14 shows that attention guidance and signal gradation resulted in significantly  
 396 higher short-range detection rates compared to when there was no countermeasure and with the  
 397 direct comparison countermeasure ( $p < .05$  for both pairwise comparisons).



399

400 *Figure 14:* Short-range target detection rates for each tactile display type (bars represent standard  
 401 error; \* represent significant countermeasures; countermeasures grouped by brackets are not  
 402 significantly different from each other)  
 403

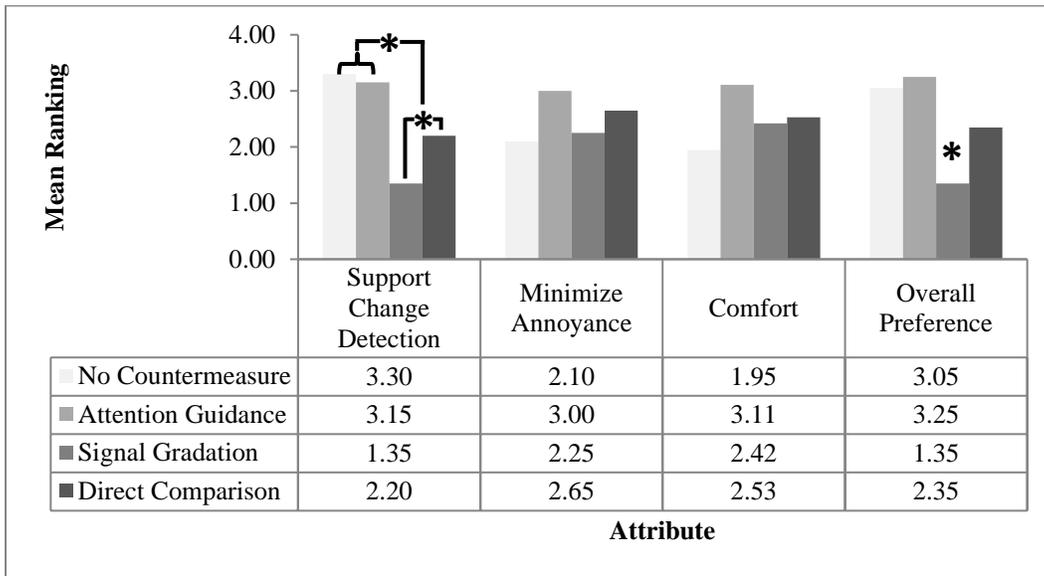
#### 404 **Subjective rankings of tactile displays**

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406 Rankings differed significantly with respect to how well the countermeasures supported  
 407 change detection ( $\chi^2(3) = 29.70, p < .001$ ). Signal gradation was ranked the highest (mean  
 408 ranking = 1.35), followed by the direct comparison (2.20), attention guidance (3.15), and no  
 409 countermeasure (3.30; Figure 15). Signal gradation was also ranked significantly higher than the  
 410 attention guidance ( $p < .001$ ), and both the signal gradation and direct comparison were ranked  
 411 significantly higher than the baseline condition ( $p < .001$  and  $p = .042$ , respectively). There was  
 412 also a significant difference in overall countermeasure preference ( $\chi^2(3) = 26.52, p < .001$ ).  
 413 Again, signal gradation was ranked the highest (mean ranking = 1.35), followed by the direct  
 414 comparison (2.35), no countermeasure (3.05), and direct comparison (3.25). The signal gradation

415 was also ranked significantly higher than the attention guidance and baseline ( $p < .001$  for both  
 416 pairwise comparisons). Rankings did not differ with respect to annoyance ( $\chi^2(3) = 5.940, p =$   
 417  $.115$ ) and comfort ( $\chi^2(3) = 7.737, p = .052$ ).

418



419

420 *Figure 15: Mean rankings of each countermeasure for each attribute (with a ranking of 1 being*  
 421 *the most favored and 4 being the least favored; \* represent significant and/or significance*  
 422 *between countermeasures; countermeasures grouped by brackets are not significantly different*  
 423 *from each other)*

424

425

## DISCUSSION

426

427 The goal of this study was to design and evaluate three countermeasures to intramodal  
 428 tactile change blindness. The phenomenon has been demonstrated in earlier studies (e.g, Auvray  
 429 et al., 2008; Ferris et al., 2010; Gallace et al., 2006) and raises concerns about the robustness of  
 430 tactile and multimodal displays (e.g., Lu, 2014; Lu & Sarter, 2014) which are increasingly  
 431 introduced in a wide range of domains.

432           The experiment confirmed the occurrence of intramodal tactile change blindness  
433 (Gallace, Tan, & Spence, 2006). All three countermeasures significantly improved change  
434 detection performance, compared to the baseline condition. Overall, the two adaptive  
435 countermeasures, i.e. signal gradation and direct comparison, were most beneficial in terms of  
436 aiding change detection. Both attention guidance and signal gradation resulted in an increase in  
437 correct rejections but likely for different reasons. In the former case, the countermeasure  
438 provided support in no-change trials. With signal gradation, on the other hand, a number of  
439 participants indicated that the strategy they adopted was to press the ‘no target’ button for every  
440 trial and then switch their selection when they detected a change or one of the countermeasures.  
441 That way, participants could leave their initial response until the extremely salient signal  
442 gradation countermeasure was triggered. Direct comparisons were not as effective for  
443 supporting correct rejections, especially in the case of tactile mudsplashes. In the debrief,  
444 feedback from participants revealed that only half of them perceived this countermeasure as  
445 intended (i.e., equal duration at low and high intensity) which may have led to an increased  
446 number of false alarms.

447           When considering both hit rates and correct rejections, overall accuracy was highest  
448 with signal gradation, followed by direct comparison. One likely reason for the success of these  
449 adaptive measures is that they served as error feedback to participants. Attention guidance  
450 prepared participants for a potential change but still required participants to play an active role  
451 in monitoring and making a decision. Signal gradation and direct comparison, on the other  
452 hand, indicated that an actual change had been missed and thus served as a safe recovery  
453 mechanism. This may have allowed participants to disengage, to an extent, from the task and  
454 rely on the countermeasure. This interpretation is in line with earlier observations that the

455 greater the reliability of a system, the more likely operators are to rely and potentially ‘over-  
456 rely’ on the technology (Parasuraman et al., 2007). In this study, the participants’ reliance on  
457 the system may be attributed to the fact the automation was designed to appear “trustworthy”  
458 based on the design guidelines suggested by Lee & See (2007). The adaptive measures used: 1)  
459 were based on a simple algorithm invoked in response to an overt operator response and 2)  
460 provided immediate results to the operators. For less reliable systems, the participants’ strategy  
461 could result in problems and different countermeasures would need to be developed based on  
462 real-time assessments of workload or visual attention to mitigate potential over-reliance (Giang  
463 et al., 2010; Parasuraman & Wickens, 2008).

464         The superior performance benefits associated with the two adaptive measures suggest  
465 that the various cognitive steps involved in change detection may not be of equal importance or  
466 may not be equally likely to break down. Specifically, the early step of encoding the target,  
467 which was addressed by the attention guidance measure, may be less critical. Another reason  
468 why attention guidance was less effective than the other countermeasures may be its particular  
469 implementation. The effectiveness of this approach drastically decreased in the presence of  
470 tactile flicker and mudsplash, compared to no transient. This suggests that attention guidance  
471 may have overwhelmed the participants with the occurrence of three tactile signals – attention  
472 guidance, tactile change, and tactile transient – all in close temporal proximity to one another.

473         The direct comparison was successful in preventing tactile change blindness, which can  
474 be explained by the fact that it supported relative judgments. Previous work has shown better  
475 performance with relative judgments, which involve a reduced load on memory compared to  
476 absolute judgments (Perreault & Cao, 2006). However, it is important to note that correct  
477 rejection rates for direct comparisons was lowest when compared to all other countermeasures,

478 including no countermeasure. This may be due to the fact that the direct comparison was similar  
479 to a gradual change paradigm, i.e., a continuous rather than discrete change over time (Simons,  
480 2000). The inability to detect gradual changes has been demonstrated mainly in vision, but there  
481 is evidence that people also have difficulty detecting gradual tactile changes (Ferris et al., 2010).  
482 The gradual attribute of the direct comparison may have made it difficult to discern when there  
483 was a change.

484         The superior performance observed with signal gradation, followed by direct  
485 comparison, is also reflected in participants' overall preference for these two countermeasures,  
486 which was based almost exclusively on how much each measure supported change detection.  
487 Comfort and annoyance seem to have had little impact on which countermeasure participants  
488 liked, although the rankings were similar to the overall preference. Subjective rankings of the  
489 adaptive measures showed that attention guidance was the least preferred method. This may be  
490 due to 30% of the participants feeling that it was more difficult to attend to the tactile cues  
491 because the tactile attention guidance created data overload in that channel. Another 15% of  
492 participants noted that, although attention guidance provided better support for change detection  
493 than the baseline, its benefit was nullified in the presence of tactile transients. Thus, attention  
494 guidance may have contributed to tactile clutter – which, according to previous literature, can  
495 reduce the effectiveness of tactile signals (van Erp, 2002; van Erp, Veltman, van Veen, &  
496 Orving, 2003).

497         In the absence of transients, the findings support using the sense of touch for  
498 communication and guiding attention (Geldard, 1957, 1960; Jones & Sarter, 2008). Potential  
499 applications include supporting monitoring/surveillance/vigilance tasks, such as military  
500 operations (e.g. as part of UAV control), healthcare (e.g. tele-ICUs), process and quality

501 control, and in the future, automated driving. The majority of the literature to date has shown  
502 the benefits of the tactile channel, but little work has focused on the limitations of this channel.  
503 The findings here highlight a major limitation – the inability to reliably attend to concurrent  
504 streams of tactile stimuli. This may suggest that tactile stimuli are best presented serially as  
505 detection accuracy was best without transients and with the adaptive countermeasures when  
506 transients were present. This also may suggest that unexpected vibrations could potentially  
507 interfere with the ability to detect, differentiate, and appropriately respond to tactile signals.

508 Further work needs to explore more effective design and implementation of these  
509 countermeasures to improve accuracy under various contexts and situations. One open question  
510 and potential concern with this approach is whether people will experience cue fatigue from the  
511 8.5 sec tactile signals and the highest signal intensities over longer periods of time, especially if  
512 they are used to support continuous monitoring tasks (Ferris et al., 2010; McLanders,  
513 Santomauro, Tran, & Sanderson, 2014). It will also be critical to ensure that people perceive the  
514 signal the same way it was intended by the designer and to minimize the risk of creating tactile  
515 clutter. Overall, the results show the promise of adaptive displays, but more work needs to  
516 consider how to best integrate adaptive design principles, particularly when the system is less  
517 reliable.

518

519

### **KEY POINTS**

520

- 521 • Three types of tactile displays – one proactive and two adaptive measures – were developed  
522 to counter the effects of tactile change blindness and evaluated in the context of monitoring  
523 multiple Unmanned Aerial Vehicle (UAV) video feeds.

- 524 • All tactile countermeasures improved performance compared to the baseline in terms of hit  
525 rate, with the two adaptive measures (signal gradation and direct comparison) resulting in the  
526 highest tactile change detection. The success of these adaptive countermeasures may be due  
527 to the fact they served as error feedback to participants and were context-sensitive, triggering  
528 only when the participants responded incorrectly.
- 529 • Increasing the salience of the tactile signal after a miss with the signal gradation  
530 countermeasure was best when considering hit rates, correct rejections, and participant  
531 preference. It is recommended that increasing the saliency of the tactile signal be used as a  
532 means to counter tactile change blindness.
- 533 • The attention guidance countermeasure – which increased tactile pulse rate **before** any  
534 potential change – resulted in the highest correct rejection rates. However, this  
535 countermeasure was the least preferred display as participants indicated it caused an overload  
536 of tactile information.
- 537

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