

# Nanosatellites: The next big chapter in atmospheric tomography

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## Content

- 1. Concept of a dense nanosatellite formation
- 2. Multi-signal combination
  - a) The concept of GNSS tomography
  - b) Results from a case study
  - c) Impact analysis
- 3. Summary



#### **SmallSat Launches**



- In the next decade, 4-5 times more SmallSat launches are expected
- Average costs per nanosatellite launch: <500k €</p>

In-house developed GNSS payload board for nanosatellite missions



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#### Cross-link occultation geometry between four nanosatellites and one GNSS satellite



The concept of GNSS tomography (exemplary for water vapor density  $\rho_w$ )



**Basic function of GNSS tomography** 

$$N = A^{-1} \cdot AEP \implies \rho_w = A^{-1} \cdot PIWV$$

- Setup tomography model (grid/voxel-based or node-based)
- Ray-trace signal paths and determine components of design matrix A

#### Solution of inverse problem

- Pseudo inverse  $A^+ \implies A = U \cdot S \cdot V^T$
- Truncated singular value decomposition (TSVD)

#### The concept of GNSS tomography (exemplary for water vapor density)

Impact of the singular value threshold (s<sub>lim</sub>) on the tomography solution



Differences in N between reference solution and synthetic tomography solution

<u>Goal</u>: Find trade-off between ill-conditioning and over-smoothing





#### Case study: Water vapor inversion layer between 2-4 km altitude



**WRF** (reference) water vapor density ( $\rho_w$ ) field + tangent points of the straight-line RO ray paths through the atmosphere (white lines) - assuming **15 nanosatellite** in one orbit separated by 30 s



Ray-traced **path-integrated water vapour (PIWV)** (visualized for 8 (every 2<sup>nd</sup>) nanosatellites)



#### Tomography solution – A priori field

	#Voxels	First guess	#CubeSats	σ <sub>RO</sub>	$\sigma_{apr}$
Test1a	52 x 41	No	8 (0s,60s,,420s)	1	—
Test1b	52 x 41	StdAtm	8 (0s,60s,,420s)	$0.01g/m^3km$	0.2 <i>wvd</i>
Test1c	52 x 41	SmoothWRF	8 (0s,60s,,420s)	$0.01g/m^3km$	0.2wvd

How sensitive is the tomography solution on the quality of the a priori field?





#### **Tomography solution – Number of satellites**

	#Voxels	First guess	#CubeSats	σ <sub>RO</sub>	$\sigma_{apr}$
Test3a	52 x 41	SmoothWRF	5 (30s,120s,,390s)	$0.01g/m^3km$	0.2 <i>wvd</i>
Test3b	52 x 41	SmoothWRF	8 (0s,60s,,420s)	$0.01g/m^3km$	0.2 <i>wvd</i>
Test3c	52 x 41	SmoothWRF	15 (0s,30s,,420s)	$0.01g/m^3km$	0.2 <i>wvd</i>

How much depends the tomography solution on the number of satellites?

10

9

8

5

3

2





#### **Tomography solution – Spatial resolution**

	#Voxels	First guess	#CubeSats	σ <sub>RO</sub>	$\sigma_{apr}$
Test3a	52 x 41	SmoothWRF	5 (30s,120s,,390s)	$0.01g/m^{3}km$	0.2 <i>wvd</i>
Test3c	137 x 41	SmoothWRF	5 (0s,60s,,420s)	$0.01g/m^{3}km$	0.2 <i>wvd</i>

How good is the spatial resolution of the tomography solution?

10

9

8

6

5

3

2

150

148

22km







#### **Tomography solution – Satellite spacing**

Satellite spacing defines: a) the number of overlapping observations, b) horizontal resolution,
c) temporal resolution, d) height of the lowest layers resolved and e) the area covered

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## Summary

- Nanosatellite technology opens up new possibilities for Earth observation
- Now available: A high-precision GNSS payload board for nanosatellite PNT
- Observation geometry of a dense satellite formation suited for tomographic processing
  - + not dependent on symmetry assumptions
  - + increased horizontal resolution (> 8 km)
- New quality in the reconstruction of atmospheric structures (demostrated for water vapor distribution)



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