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A SURVEY OF PROACTIVE AND REACTIVE PROTOCOLS IN MOBILE AD HOC NETWORKS

Aruna Devi. P*, K. Karthikeyan

*Research Scholar, Ph.D (Computer Science) Dr.SNS Rajalakshmi College of Arts and Science, Coimbatore-49

Head, Dept of Computer Science Government Arts and Science College Karambakudi

DOI:

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ABSTRACT

Mobile Ad Hoc Network (MANET) is one of wireless communication with a collection of more than one device or nodes or terminals which contain network capability that communicate with each other. A Mobile ad-hoc network is set of different types of movable nodes and consists of mobile platforms which are free to move randomly. MANET can be deployed at low cost in variety of application and it contains different types of routing protocols which are classified under the category of proactive (Table driven Protocols) and reactive protocols (ondemand). Nodes can directly communicate to all other nodes within the broadcast communication. If node could not have direct communication then they can act as intermediate node to communicate with other nodes. This paper focus on the survey of proactive and reactive routing protocols namely DSDVR, CGSR, GSR, WRP and DSR, AODV, TORA respectively.

INTRODUCTION

A Mobile Ad hoc Network is wireless mobile nodes that dynamically self-organize in arbitrary manner. Mobile ad hoc networks are group of wireless networks, which consists of large number of mobile nodes. Nodes in MANETs can link and go off the network dynamically. There is no fixed infrastructure and centralized administration in this type of networks. Nodes can be interconnected through wireless interface. Sometimes Mobile ad-hoc networks are also known as short-lived networks. This is a new form of network and might be able to provide services at any places where it is not possible. Flexibility is the advantages of Mobile adhoc network it means people want to communicate anywhere at any time. A MANET is a collection of wireless nodes that exchange information without using any predefined infrastructure. Each device called router in a MANET is free to move independently in any direction at any time.

Figure: 1



Example for Mobile Ad hoc Network

CHALLENGES IN MANETS

Autonomous and infrastructureless - No centralized supervision is available to manage the different mobile nodes operation.

Dynamic Network topology- Nodes are mobile and can be connected dynamically in an arbitrary manner. Links of the network varies based on the proximity of one node to another node.



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Device heterogeneity - Identifying relevant new nodes and informing about their existence Bandwidth constrained

Variable capacity links - Wireless links have considerably lower capability than the wired links.

Limited resources- Mobile nodes contain limited battery constraints.

Network scalability - Scalability is defined as whether the network is able to accept the level of service if it contains large number of nodes.

Limited substantial security- Flexibility implies higher security risks Such as peer-to- peer network architecture. Eavesdropping, spoofing and denial-of-service attacks, Traffic analysis should be considered.

Poor communication Quality- This is an inbuilt problem of wireless networks caused by several error result in declining of the received signal.

Adhoc addressing - Challenges in normal addressing scheme.

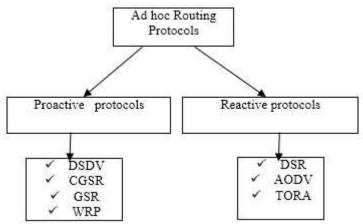
Network configuration- The whole ad hoc infrastructure is dynamic.

Topology protection- Information can be changed among nodes in ad hoc is a major challenge.

OVERVIEW OF PROACTIVE AND REACTIVE PROTOCOLS

The routing protocols for ad hoc networks can be divided into two categories: Table-driven protocols (proactive) and on-demand protocols (reactive). They differ from each other so they obtain the routing information. The table driven protocols habitually maintain the routing table of the whole network whereas the on-demand protocols maintains information of only active paths to the destination nodes.

Figure: 2



Different types of Ad hoc Routing Protocols

Proactive protocols

Destination-sequenced distance vector routing (DSDV)

The DSDV protocol is a routing algorithm that focuses on finding the shortest paths. This protocol is based on the Bellman-Ford algorithm to find the routes with enhancement. Every mobile node maintains a table which consists of all the existing destinations, the number of hops required to reach each destination, and a sequence number in a table form. The purpose of sequence number is to distinguish between old nodes and new ones in the destination. DSDV is suitable for small networks. If there is a link failure in one of the node will change the metric value to infinity and broadcast the message.

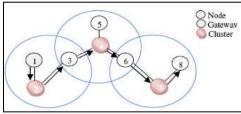


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Cluster head Gateway Switch Routing (CGSR)

The Cluster head Gateway Switch Routing is also a table driven routing protocol. In this protocol the packet cannot be openly sent to the destination instead cluster heads are used for routing. The portable devices will be grouped to form a cluster. The combination is based on the range and each cluster is controlled by cluster head. Then each cluster head is connected to gateway and form a hierarchical structure. All the portable devices will maintain two types of table namely cluster member and routing.

Figure -3



Example for CGSR

Global State Routing (GSR)

Global State Routing (GSR) is almost the same as Destination-sequenced distance vector routing, because it deals with link state routing .The aim is to reduce the flooding of routing messages. In this algorithm each node consists of a distance table, a neighbor list, a topology table, a next hop table. The distance table contains the shortest path to each destination node. The routing messages will be created for each link when link changes. There is a updating of topology table when it receives routing message. After that it updates sequence number stored in the table and it then reconstructs its routing table and broadcasts the packets to its neighbors. The neighbor list of a node consists of the list of its neighbors. The next hop table includes the next hop details to which the packets to be send.

Wireless Routing Protocol (WRP)

WRP is one of the path-finding algorithms and defined as the set of circulated shortest path algorithms, which calculate the paths based on length and hop. Wireless Routing Protocol uses the routing table for each node in the record to complete the routing. It requires each node to operate with four tables namely Distance vector table, Routing table, Link-cost table, Message retransmission list table. Message retransmission list is used to update records which need re-transmission and requires acknowledgement. A node can decide whether to update its routing table after receiving an update message from a neighbor and always it looks for a best path using the new information.

Proactive protocols

Dynamic Source Routing (DSR)

DSR is one type of on-demand routing protocol for ad hoc networks. In DSR the source consist of full routing path in the packets header. The intermediate nodes use this technique to forward packets towards the destination and maintain a route cache table. It is a protocol in which source finds unexpired route to the destination to send the packet. This protocol used in the network with the moderate speed. Routing in DSR can be done using two phases: Route request and Route reply.

Route request

The source sends the information to the destination will create a message as route request by adding its own identification number and broadcasts it in the network.

Route reply

When the destination is reached then it sent a route reply message back to the source. The source can receive multiple replies from multiple paths of the nodes. The source will pick up one of the best path and transmit the packets. If there is a failure while transmitting the packets that is link was broken one of the node will detect it and generate a route error message which will be sent back to the source. Then source will re-established the link for further transmission.



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Ad Hoc On-demand Distance Vector (AODV)

AODV is one type of on-demand routing protocol for ad hoc networks. AODV uses hop-by-hop routing. It maintains routing table entries at each node. In mobile adhoc networks it is known as a source initiated routing protocol .This On-demand Distance Vector algorithm consists of two phases: Route discovery phase, Route maintenance phase. The best feature of AODV is to provide broadcasting, unicasting, and multicasting communication. During route discovery phases it uses a broadcast communication and for reply it uses unicast communication.

Route discovery

The source does not have any route to the destination in its route cache, then it send a route request as RREQ message to the destination node. It specifies for which node it requests the route. The RREQ message consists of a route record which specifies the sequence of nodes. When an intermediate node receives a RREQ message from source then it checks whether the node is already present in the route record or not. If node is present in the record then it drops the message. This is done to prevent from loops. The intermediate node sends the RREQ to the next router according to the route which is specified in the header field. When the destination node receives the RREQ from the source node, it sends back a route reply message (RREP) as a response to the source. Intermediate nodes can also use the route cache to reply to RREQs.

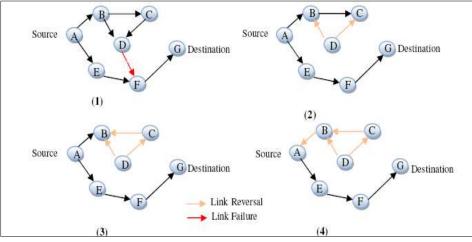
Route maintenance

Route maintenance is maintained when a node detects a broken link. If there is a broken link, node cannot forward a message to next hop but it sends a route error (RERR) message back to the source. When an RERR message is received from broken node it deletes all the links.

Temporally Ordered Routing Algorithm (TORA)

TORA is also a source initiated routing algorithm. It creates multiple routes for any source or destination. The advantage is that route discovery is not required for every modification in the network topology. TORA consists of three basic functions: Route Creation/discovery, Route maintenance, Route erasure. TORA uses three types of packets: Query Packets for creating a route, Update Packets for both creating and maintenance. The route will be found from the source to destination only when a request is made for the transmission between sender and receiver. In this algorithm the source will generate a query packet to broadcast the messages in the network. When the destination is known about an update packet then it will be generated and sent back to the source. The update packet maintains the path information, if more than one update packet is received by the source. It means there are multiple paths to the destination so source has to choose best path available in the network.

Figure-3



TORA: Route maintenance.



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S.NO	PARAMETERS	PROACTIVE PROTOCOL	REACTIVE PROTOCOL
1	Routing Scheme	Table driven	On Demand
2	Routing overhead	High	Low
3	Routing Philosophy	Flat/Hierarchical	Flat
4	Latency	Low due to routing tables	High due to flooding
5	Availability of routing information	Always stored in tables	Available when required
6	Periodic Updates	Yes. Whenever the topology changes	Not needed as route available or Demand
7	Mobility Support	Periodical Updates	Route maintenance
8	Storage Capacity	High ,due to the routing tables	Low generally Depends upon the number of routes

OUTLINE OF PROTOCOLS

Protocol	Advantages	Disadvantages
Proactive	Information is always obtainable. Latency is compact in the network	Overhead is high Routing information is flooded in the whole network
Reactive	Path available when needed overhead is low. Doesn't form any loops.	Latency is improved in the network

CONCLUSION

This paper consists of a number of routing protocols for Mobile Adhoc Network which are broadly classified into Proactive and Reactive Protocols. Proactive routing protocols have a tendency to provide lower latency than that of the on-demand protocols because they maintain tables for all the nodes. But the drawback for such protocols is the extreme routing overhead transmitted which is periodic in nature. In the other hand reactive protocols discover routes only when they are needed, they may still produce a huge amount of traffic when the network or topology changes frequently. Depending on the amount of network traffic and number of flows, the routing protocols could be chosen.

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