

# A New PyROOT for ROOT 6.22

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PyHEP 2020

ROOT

Data Analysis Framework

<https://root.cern>



- ▶ Introduction: What is PyROOT?
  - Dynamic Python bindings to C++
- ▶ New PyROOT
  - Support for modern C++
  - Interoperability with Python data science libraries
  - Multi-Python builds
  - Docs
- ▶ Future Work
- ▶ Demo

# Introduction

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## Python-C++ bindings

- Access to all C++ from Python (not just for ROOT!)
- Python façade, C++ performance



## Automatic, dynamic

- No static wrapper generation (unlike e.g. SWIG, PyBind11)
- Dynamic Python proxies for C++ entities
- Lazy class/variable lookup



## Powered by the ROOT type system and Cling

- Reflection information, JIT C++ compilation, execution



## Pythonizations

- Make it simpler, more pythonic

## ▶ Automatic bindings + Pythonizations

```
import ROOT  
f = ROOT.TFile('myfile.root')  
t = f.mytree
```

TFile is a (dynamic) Python proxy of a C++ class

f is a (dynamic) Python proxy of a C++ object

Pythonization: access the file content as an attribute



# Dynamic access to C++

▶ JIT compile or load efficient C++, access it right away in Python

```
import ROOT
cpp_code = """
int f(int i) { return i*i; }

class A {
public:
    A() { cout << "Hello PyROOT!" << endl; }
};
"""

# Inject the code in the ROOT interpreter
ROOT.gInterpreter.ProcessLine(cpp_code)

# We find all the C++ entities in Python!
a = ROOT.A() # this prints Hello PyROOT!
x = ROOT.f(3) # x = 9
```

} C++ code we  
want to invoke  
from Python

# New PyROOT

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# New ROOT release, new PyROOT

- ▶ [ROOT 6.22](#) has just been released with a new PyROOT
  - Previously in experimental mode
- ▶ Major revision of PyROOT
  - Support for modern C++
  - Interoperability features
  - More pythonizations
  - Python 2 & 3 in just one build



# The New Structure

**PyROOT**

User API

ROOT Pythonizations

**Cppyy**

Automatic Bindings:  
Proxy Creation,  
Type Conversion  
(Python/C API)

STL  
Pythonizations

**ROOT & Cling**

Reflection Info,  
Execution

ROOT Type System



# Improved C++ support

- ▶ Powered by [cppyy](#)
- ▶ Modern C++: variadic templates, move semantics, lambdas, ...

```
>>> import ROOT
>>> ROOT.gInterpreter.ProcessLine("""
template<typename... myTypes>
int f() { return sizeof...(myTypes); }
""")
0L
>>> ROOT.f['int', 'double', 'void*']()
3
```



# Interoperability with scientific Python

**PyROOT**

**Scientific Python Libraries**

**RDataFrame**

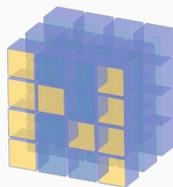
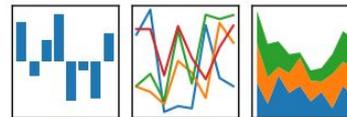
**TTree**

**RVec**

**std::vector**

**pandas**

$$y_{it} = \beta^T x_{it} + \mu_i + \epsilon_{it}$$



**NumPy**



# RDataFrame to NumPy and pandas

- ▶ Efficient computations in C++ powered by RDataFrame, implicit parallelism
- ▶ Convert final dataset to NumPy (and pandas)

```
import ROOT

ROOT.EnableImplicitMT()

df = ROOT.RDataFrame('myTree', 'file.root')

# Perform computations with RDataFrame
np_arrays = df.Filter('x > 0')
               .Define('z', 'x*y')
               .AsNumpy()

# Wrap data with pandas
import pandas
pdf = pandas.DataFrame(np_arrays)
```

← Get dataset columns as NumPy arrays



# C++ containers to NumPy

- ▶ Zero-copy C++ to NumPy array conversion
  - Objects with contiguous data (`std::vector`, `RVec`)
  - Pythonization: tell NumPy about data and shape

```
import ROOT
import numpy as np

vec = ROOT.std.vector['int'](2)
arr = np.asarray(vec) # zero-copy operation
vec[0], vec[1] = 1, 2 ← Memory adopted!

assert arr[0] == 1 and arr[1] == 2 ←
```



# Using Python callables in C++

- ▶ Decorate Python callables to be used from C++, efficiently
  - Automatic wrapper is generated that calls a Numba-jitted version

```
import ROOT

@ROOT.Numba.Declare(['float', 'int'], 'float')
def pypow(x, y):
    return x**y

# Use the callable within an RDataFrame workflow
data = ROOT.RDataFrame('tree', 'file.root')
    .Define('x_pow3', 'Numba::pypow(x, 3)')
    .AsNumpy()
```



## ▶ Single ROOT build for Python 2 & 3

- Eases the transition from Python 2 to 3
- Support Python 2 for as long as the experiments need it

## ▶ How it works

- By default, it will build for both if it finds them in the system
- Hints can be provided to point to specific Python installations
- Building for a single Python version is still possible
- More info [here](#)



# Multi-Python builds: CMSSW

- ▶ CMSSW users are now able to use PyROOT from both Python 2 & 3

```
[etejedor@lxplus CMSSW_11_1_ROOT6_X_2020-04-27-2300]$ python2
Python 2.7.15+ (default, Mar 24 2020, 13:10:41)
>>> import ROOT
```

```
[etejedor@lxplus CMSSW_11_1_ROOT6_X_2020-04-27-2300]$ python3
Python 3.8.2 (default, Mar 24 2020, 13:29:26)
>>> import ROOT
```



- ▶ A [new ROOT website](#) has been recently published!
- ▶ The website includes a [PyROOT manual](#)
  - User interface
  - Interactive graphics
  - Jupyter notebooks
  - ... and more!
- ▶ Docs for pythonizations will be in the [reference guide](#)

The screenshot shows the ROOT Data Analysis Framework website. The header includes the ROOT logo and navigation links: About, Install, Get Started, Forum & Help, Manual, News, Contribute, For Developers, and a search icon. The main content area features a large banner image of a particle detector with the text "ROOT: analyzing petabytes of data, scientifically." Below the banner, there are two buttons: "Learn more" and "Install v6.22/00". A row of four icons with labels below them: "Get Started" (arrow pointing to a document), "Reference" (book icon), "Forum & Help" (speech bubble), and "Gallery" (bar chart). Below this, there are three columns of text. The first column is titled "v-1" and discusses the framework's use in scientific analyses. The second column is titled with a globe icon and discusses the high-performance software being written in C++. The third column is titled with a dollar sign and underscore icon and discusses the C++ interpreter and Python integration.

# Summary & Future Work

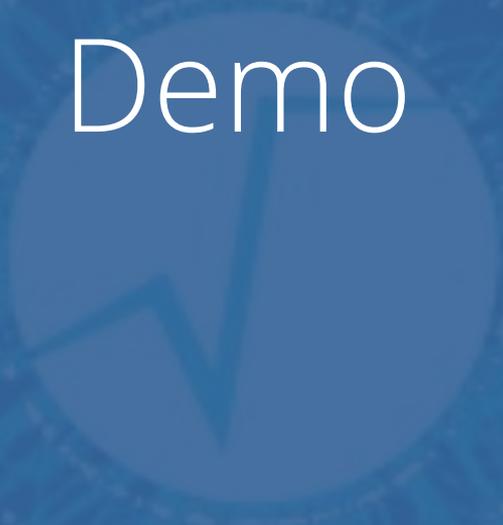
ROOT

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- ▶ ROOT 6.22 comes with new PyROOT
  - Modern, pythonic, interoperable
  - Support for Python 2 & 3 in the same installation
- ▶ Find [here](#) how to install it
- ▶ Future work
  - Installation in standard Python directories
  - API for user-defined pythonizations
  - Extend RDataFrame Python programming model



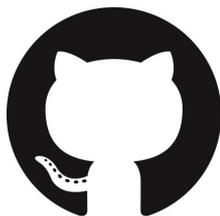
# Demo

# ROOT

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- ▶ Notebooks hosted on GitHub and interactively accessible via binder



- ▶ Alternative: Install ROOT locally in under 5 minutes
  - Powered by conda and thanks to Chris Burr, Enrico Guiraud and Henry Schreiner
  - [Link to instructions](#)

# Backup Slides

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# C++ support: move semantics

## ▶ Support for rvalue reference parameters

```
>>> import ROOT
>>> ROOT.gInterpreter.ProcessLine(
'void myfunction(std::vector<int>&& v) {
    for (auto i : v) std::cout << i << " ";
}')
0L
>>> v = ROOT.std.vector['int'](range(10))
>>> ROOT.myfunction(ROOT.std.move(v))
0 1 2 3 4 5 6 7 8 9
>>> ROOT.myfunction(ROOT.std.vector['int'](range(10)))
0 1 2 3 4 5 6 7 8 9
```



# RDataFrame to NumPy and pandas

```
# Run input pipeline with C++ performance that can process TBs of data
```

```
df = ROOT.RDataFrame('tree', 'file.root')  
    .Filter('pT_j0 > 30')  
    .Define('r_j0', 'sqrt(eta_j0*eta_j0 + phi_j0*phi_j0)')
```

```
# Read out final selection with defined variables as NumPy arrays
```

```
col_dict = df.AsNumpy(['r_j0', 'eta_j0', 'phi_j0'])  
print(col_dict)
```

```
{'r_j0': ndarray([0.26,1.,4.45]), 'eta_j0': ndarray(0.1,-1.,2.1), 'phi_j0': ndarray([-0.5,0.,0.2])}
```

```
# Wrap data with pandas
```

```
p = pandas.DataFrame(col_dict)  
print(p)
```

```
   r_j0  eta_j0  phi_j0  
0  0.26   0.1   -0.5  
1  1.0   -1.0    0.0  
2  4.45   2.1    0.2
```



- ▶ Read a TTree into a NumPy array
  - Branches of arithmetic types

```
myTree # Contains branches x and y of type float

# Convert to numpy array and apply numpy methods
myArray = myTree.AsMatrix()
m = np.mean(myArray, axis = 0)

# Read only specific branches, specify output type
xAsInts = myTree.AsMatrix(columns = ['x'], dtype = 'int')
```



# User-defined pythonizations

- ▶ **User Pythonizations:** allow ROOT users to define pythonizations for their own classes
  - Lazily executed

```
@pythonization('MyCppClass')  
def my_pythonizor_function(klass):  
    # Inject new behaviour in the class  
    klass.some_attr = ...
```

Python proxy of the class