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XVII. On the Maintenance of Vibrations by Forces of Double Frequency, and on the Propagation of Waves through a Medium endowed with a Periodic Structure. By Lord Rayleigh, Sec. R. S., Professor of Natural Philosophy in the Royal Institution*.

THE nature of the question to be first considered may be best explained by a paragraph from a former paper $\dagger$, in which the subject was briefly treated. "There is also another kind of maintained vibration which, from one point of view, may be regarded as forced, inasmuch as the period is imposed from without, but which differs from the kind just referred to (ordinary forced vibrations) in that the imposed periodic variations do not tend directly to displace the body from its configuration of equilibrium. Probably the bestknown example of this kind of action is that form of Melde's experiment in which a fine string is maintained in transverse vibration by connecting one of its extremities with the vibrating prong of a massive tuning-fork, the direction of motion of the point of attachneent being parallel to the length of the string $\ddagger$. The effect of the motion is to render the tension of the string periodically variable; and at first sight there is nothing to cause the string to depart from its equilibrium condition of straightness. It is known, however, that under these circumstances the equilibrium position may become unstable, and that the string may settle down into a state of permanent and

[^0]Phil. Mag. S. 5. Vol. 24. No. 147. August 1887. L
vigorous vibration whose period is the double of that of the point of attachment"*. Other examples of acoustical interest are mentioned in the paper.

My attention was recalled to the subject by Mr. Glaisher's Address to the Astronomical Society $\dagger$, in which he gives an interesting account of the treatment of mathematically similar questions in the Lunar Theory by Mr. Hill $\ddagger$ and by Prof. Adams§. The analysis of Mr. Hill is in many respects incomparably more complete than that which I had attempted; but his devotion to the Lunar Theory leads the author to pass by many points of great interest which arise when his results are applied to other physical questions.

By a suitable choice of the unit of time, the equation of motion of the vibrating body may be put into the form

$$
\begin{equation*}
\frac{d^{2} w}{d t^{2}}+2 k \frac{d w}{d t}+\left(\Theta_{0}+2 \Theta_{1} \cos 2 t\right) w=0 ; . \tag{1}
\end{equation*}
$$

where $k$ is a positive quantity, which may usually be treated as small, representing the dissipative forces. $\left(\Theta_{0}+2 \Theta_{1} \cos 2 p t\right)$ represents the coefficient of restitution, which is here regarded as subject to a small imposed periodic variation of period $\pi$. Thus $\Theta_{0}$ is positive, and $\Theta_{1}$ is to be treated as relatively small.

The equation to which Mr. Hill's researches relate is in one respect less general than (1), and in another more general. It omits the dissipative term proportional to $k$; but, on the other hand, as the Lunar Theory demands, it includes terms proportional to $\cos 4 t, \cos 6 t, \& c$. Thus

$$
\begin{equation*}
\frac{d^{2} w}{d t^{2}}+\left(\Theta_{0}+2 \Theta_{1} \cos 2 t+2 \Theta_{2} \cos 4 t+\ldots\right) w=0 ; \tag{2}
\end{equation*}
$$

or

$$
\begin{equation*}
\frac{d^{2} w}{d t^{2}}+\Theta w=0 \tag{3}
\end{equation*}
$$

where

$$
\begin{equation*}
\Theta=\Sigma_{n} \Theta_{n} e^{2 i n t}, . \tag{4}
\end{equation*}
$$

$n$ being any integer, and $i$ representing $\sqrt{ }(-1)$. In the present investigation $\Theta_{-n}=\Theta_{n}$.

* "See Tyndall's 'Sound,' 3rd. ed. ch. iii. § 7, where will also be found a general explanation of the mode of action."
$\dagger$ Monthly Notices, Feb. 1887.
$\ddagger$ "On the Part of the Motion of the Lunar Perigee which is a Function of the Mean Motions of the Sun and Moon," Acta Mathematica, 8:1, 1886. Mr. Hill's work was first published in 1877.
§"On the Motion of the Moon's Node, in the case when the orbits of the Sun and Moon are supposed to have no Eccentricities, and when their Mutual Inclination is supposed to be indefinitely small." Monthly Notices, Nov. 1877.

It will be convenient to give here a sketch of Mr. Hill's method and results. Remarking that when $\Theta_{1}, \Theta_{2}$, \&c. vanish, the solution of (3) is

$$
\begin{equation*}
w=\mathrm{K} e^{i c t}+\mathrm{K}^{\prime} e^{-i e t}, \tag{5}
\end{equation*}
$$

where $K, K^{\prime}$ are arbitrary constants, and $c=\sqrt{ }\left(\Theta_{0}\right)$, he shows that in the general case we may assume as a particular solution

$$
\begin{equation*}
w=\Sigma_{n} b_{n} e^{i c t+2 i n t}, \tag{6}
\end{equation*}
$$

the value of $c$ being modified by the operation of $\Theta_{1}, \& c$., and the original term $b_{0} \epsilon^{i c t}$ being accompanied by subordinate terms corresponding to the positive and negative integral values of $n$.

The multiplication by $\Theta$, as given in (4), does not alter the form of (6); and the result of the substitution in the differential equation (3) may be written

$$
\begin{equation*}
(c+2 m)^{2} b_{m}-\Sigma_{n} \Theta_{m-n} b_{n}=0, \ldots \tag{7}
\end{equation*}
$$

which holds for all integral values of $m$, positive and negative. These conditions determine the ratios of all the coefficients $b_{n}$ to one of them, e.g., $b_{0}$, which may then be regarded as the arbitrary constant. They also determine $c$, the main subject of quest. Mr. Hill writes

$$
\begin{equation*}
[n]=(c+2 n)^{2}-\Theta_{0} ; \tag{8}
\end{equation*}
$$

so that the equations take the form
$\ldots+[-2] b_{-2}-\Theta_{1} b_{-1}-\Theta_{2} b_{0}-\Theta_{3} b_{1}-\Theta_{4} b_{2}-\ldots=0$,
$\ldots-\Theta_{1} \quad b_{-2}+[-1] b_{-1}-\Theta_{1} b_{0}-\Theta_{2} \quad b_{1}-\Theta_{3} b_{2}-\ldots=0$,
$\ldots-\Theta_{2} \quad b_{-2}-\Theta_{1} b_{-1}+[0] b_{0}-\Theta_{1} \quad b_{1}-\Theta_{2} b_{2}-\ldots=0$,
$\ldots-\Theta_{3} \quad b_{-2}-\Theta_{2} b_{-1}-\Theta_{1} b_{0}+[-1] b_{1}-\Theta_{1} b_{2}-\ldots=0$,
$\ldots-\Theta_{4} b_{-2}-\Theta_{3} b_{-1}-\Theta_{2} b_{0}-\Theta_{1} b_{1}+[2] b_{2}-\therefore=0$,
The determinant formed by eliminating the $b$ 's from these equations is denoted by $\mathfrak{P}(c)$; so that the equation from which $c$ is to be found is

$$
\mathfrak{D}(c)=0 .
$$

The infinite series of values of $c$ determined by (10) cannot give independent solutions of (3),-a differential equation of the second order only. It is evident, in fact, that the system of equations by which $c$ is determined is not altered if we replace $c$ by $c+2 v$, where $\nu$ is any positive or negative integer. Neither is any change incurred by the substitution of $-c$ for $c$. "It follows that if (10) is satisfied by a root $c=c_{0}$, it will also have, as roots, all the quantities contained in the expression

$$
\pm c_{0}+2 n,
$$

where $n$ is any positive or negative integer or zero. And these are all the roots the equation admits of; for each of the expressions denoted by $[n]$ is of two dimensions in $c$, and may be regarded as introducing into the equation the two roots $2 n+c_{0}$ and $2 n-c_{0}$. Consequently the roots are either all real or all imaginary; and it is impossible that the equation should have any equal root unless all the roots are integral."

On these grounds Mr. Hill concludes that $\mathfrak{D}(c)$ must be such that

$$
\begin{equation*}
\mathfrak{I}(c)=\mathrm{A}\left[\cos (\pi c)-\cos \left(\pi c_{0}\right)\right] \tag{11}
\end{equation*}
$$

identically, where $A$ is some constant independent of $c$; whence on putting $c=0$,

$$
\begin{equation*}
\mathfrak{I}(0)=\mathrm{A}\left[1-\cos \left(\pi c_{0}\right)\right], \tag{12}
\end{equation*}
$$

in which, if we please, $c_{0}$ may be replaced by $c$. The value of A may now be determined by comparison with the particular case $\Theta_{1}=0, \Theta_{2}=0$, \&c., for which of course $c=\sqrt{ } \Theta_{0}$. Thus if $\mathfrak{D}^{\prime}(0)$ denote the special form then assumed, $i$. e. the simple product of the diagonal constituents,

$$
\begin{equation*}
\mathfrak{S}^{\prime}(0)=\mathrm{A}\left[1-\cos \left(\pi \sqrt{ } \Theta_{0}\right)\right] \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{1-\cos (\pi c)}{1-\cos \left(\pi \sqrt{ } \Theta_{0}\right)}=\frac{\sin ^{2}\left(\frac{1}{2} \pi c\right)}{\sin ^{2}\left(\frac{1}{2} \pi \sqrt{ } \Theta_{0}\right)}=\frac{\mathfrak{O}(0)}{\mathfrak{S}^{\prime}(0)} . \tag{14}
\end{equation*}
$$

The fraction $\mathfrak{D}(0) \div \mathfrak{D}^{\prime}(0)$ is denoted by $\mathbf{D}(0)$. It is the determinant formed from the original one by dividing each row by the constituent in the diagonal, so as to reduce all the diagonal constituents to unity, and by making $c$ vanish. Thas

$$
\begin{equation*}
\frac{1-\cos (\pi c)}{1-\cos \left(\pi \sqrt{ } \Theta_{0}\right)}=\square(0), \tag{15}
\end{equation*}
$$

where

The value of $\square(0)$ is calculated for the purposes of the Lunar Theory to a high order of approximation. It will here suffice to give the part which depends upon the squares of $\Theta_{1}, \Theta_{2}$, \&c. Thus

$$
\begin{equation*}
\square(0)=1+\frac{\pi \cot \left(\frac{1}{2} \pi \sqrt{ } \Theta_{0}\right)}{4 \sqrt{ } \Theta_{0}}\left[\frac{\Theta_{1}{ }^{2}}{1-\Theta_{0}}+\frac{\Theta_{2}{ }^{2}}{4-\Theta_{0}}+\frac{\Theta_{3}{ }^{2}}{9-\Theta_{0}}+\ldots\right] . \tag{17}
\end{equation*}
$$

Another determinant, $\nabla(0)$, is employed by Mr. Hill, the relation of which to $\square(0)$ is expressed by

$$
\begin{equation*}
\nabla(0)=2 \sin ^{2}\left(\frac{1}{2} \pi \sqrt{ } \Theta_{0}\right) \cdot \square(0) ; \tag{18}
\end{equation*}
$$

so that the general solution for $c$ may be written

$$
\begin{equation*}
\cos (\pi c)=1-\nabla(0) \tag{19}
\end{equation*}
$$

Mr. Hill observes that the reality of $c$ requires that $1-\nabla(0)$ should lie between -1 and +1 . In the Lunar Theory this condition is satisfied; but in the application to Acoustics the case of an imaginary $c$ is the one of greater interest, for the vibrations then tend to increase indefinitely.
$\operatorname{Cos}(\pi c)$ being itself always real, let us suppose that $\pi c$ is complex, so that

$$
c=\alpha+i \beta,
$$

where $\alpha$ and $\beta$ are real. Thus

$$
\cos \pi c=\cos \pi \alpha \cos i \pi \beta-\sin \pi \alpha \sin i \pi \beta
$$

and the reality of $\cos \pi c$ requires either (1) that $\beta=0$, or (2) that $\alpha=n, n$ being an integer. In the first case $c$ is real. In the second

$$
\begin{equation*}
\cos \pi c= \pm \cos i \pi \beta=1-\nabla(0) \tag{20}
\end{equation*}
$$

which gives but one (real) value of $\beta$. If $1-\nabla(0)$ be positive,

$$
\begin{equation*}
c= \pm i \beta+2 n ; \tag{21}
\end{equation*}
$$

but if $1-\nabla(0)$ be negative,

$$
\cos \pi c=-\cos i \pi \beta
$$

whence

$$
\begin{equation*}
c= \pm i \beta+2 n+1 . \tag{22}
\end{equation*}
$$

The latter is the case with which we have to do when $\Theta_{0}$, and therefore $c$, is nearly equal to unity; and the conclusion that when $c$ is complex, the real part is independent of $\Theta_{1}, \Theta_{2}$, \&c. is of importance. The complete value of $w$ may then be written

$$
\begin{equation*}
w=e^{\beta t} \sum b_{n} e^{i t(1+2 n)}+e^{-\beta t} \Sigma b^{\prime}{ }_{n} e^{i t(1+2 n)}, . . \tag{2}
\end{equation*}
$$

the ratios of $b_{n}$ and also of $b_{n}{ }^{\prime}$ being determined by (9). After the lapse of a sufficient time, the second set of terms in $e^{-\beta t}$ become insignificant.

In the application of greatest acoustical interest $\Theta_{0}$ (and $c$ ) are nearly equal to unity; so that the free vibrations are performed with a frequency about the half of that introduced by $\Theta_{1}$. In this case the leading equations in (9) are those which involve the small quantities [0] and [-1]; but for the sake of symmetry, it is advisable to retain also the equation containing [1]. If we now neglect $\Theta_{2}$, as well as the $b$ 's whose suffix is numerically greater than unity, we find

$$
\begin{equation*}
\frac{b_{-1}}{\Theta_{1}[1]}=\frac{b_{0}}{[1][-1]}=\frac{b_{1}}{\Theta_{1}[-1]}, \ldots . \tag{24}
\end{equation*}
$$

and

$$
\begin{equation*}
[0][1][-1]-\Theta_{1}^{2}\{[1]+[-1]\}=0 \tag{25}
\end{equation*}
$$

For the sake of distinctness it will be well to repeat here that

$$
[0]=c^{2}-\Theta_{0}, \quad[-1]=(c-2)^{2}-\Theta_{0}, \quad[1]=(c+2)^{2}-\Theta^{0} .
$$

Substituting these values in (25), Mr. Hill obtains

$$
\left(c^{2}-\Theta_{0}\right)\left\{\left(c^{2}+4-\Theta_{0}\right)^{2}-16 c^{2}\right\}-2 \Theta_{1}^{2}\left\{c^{2}+4-\Theta_{0}\right\}=0,
$$

and neglecting the cube of ( $c^{2}-\Theta_{0}$ ), as well as its product with $\Theta_{1}{ }^{2}$,

$$
\left(c^{2}-\Theta_{0}\right)^{2}+2\left(\Theta_{0}-1\right)\left(c^{2}-\Theta_{0}\right)+\Theta_{1}^{2}=0 ;
$$

and from this again

$$
\begin{equation*}
c^{2}=1+\sqrt{ }\left\{\left(\Theta_{0}-1\right)^{2}-\Theta_{1}^{2}\right\} . \tag{26}
\end{equation*}
$$

It appears, therefore, that $c$ is real or imaginary according as $\left(\Theta_{0}-1\right)^{2}$ is greater or less than $\Theta_{1}{ }^{2}$. In the problem of the Moon's apse, treated by Mr. Hill,

$$
\Theta_{0}=1 \cdot 1588439, \quad \Theta_{1}=-0.0570440 ;
$$

and in the corresponding problem of the node, investigated by Prof. Adams,

$$
\begin{aligned}
& \Theta_{0}=1 \cdot 17804,44973,149, \\
& \Theta_{1}=0 \cdot 01261,68354,6 .
\end{aligned}
$$

In both these cases the value of $c$ is real, though of course not to be accurately determined by (26).

Mr. Hill's results are not immediately applicable to the acoustical problem embodied in (1), in consequence of the omission of $k$, representing the dissipation to which all actual vibrations are subject. The inclusion of this term leads, however, merely to the substitution for $(c+2 n)^{2}-\Theta_{0}$ in (8) of

$$
(c+2 n)^{2}-2 i k(c+2 n)-\Theta_{0}
$$

so that the whole operation of $k$ is represented if we write
$(c-i k)$ in place of $c$, and $\left(\Theta_{0}-k^{2}\right)$ in place of $\Theta_{0}$. Accordingly

$$
\begin{equation*}
\cos \pi(c-i k)=1-\nabla^{\prime}(0), \tag{27}
\end{equation*}
$$

$\nabla^{\prime}(0)$ differing from $\nabla(0)$ only by the substitution of $\Theta_{0}-k^{2}$ for $\Theta_{0}$.

If $1-\nabla^{\prime}(0)$ lies between $\pm 1,(c-i k)$ is real, so that

$$
\begin{equation*}
c=i k \pm \alpha+2 n . \tag{28}
\end{equation*}
$$

In this case both solutions are affected with the factor $e^{-k t}$, indicating that whatever the initial circumstances may be, the motion dies away.

It may be otherwise when $1-\nabla^{\prime}(0)$ lies beyond the limits $\pm 1$. In the case of most importance, when $\Theta_{0}$ is nearly equal to unity, $1-\nabla^{\prime}(0)$ is algebraically less than -1 . If

$$
\begin{equation*}
\cos i \pi \beta=-1+\nabla^{\prime}(0), \tag{29}
\end{equation*}
$$

we may write

$$
\begin{equation*}
c=1+i(k \pm \beta)+2 n . \tag{30}
\end{equation*}
$$

Here again both motions die down unless $\beta$ is numerically greater than $k$, in which case one motion dies down, while the other increases without limit. The critical relation may be written

$$
\begin{equation*}
\cos (i \pi k)=-1+\nabla^{\prime}(0) . \tag{31}
\end{equation*}
$$

From (30) we see that, whatever may be the value of $k$, the vibrations (considered apart from the rise or subsidence indicated by the exponential factors) have the same frequency as if $k$, as well as $\Theta_{1}, \Theta_{2}$, \&c. vanished.

Before leaving the general theory it may be worth while to point out that Mr. Hill's method may be applied when the coefficients of $d^{2} w / d t^{2}$ and $d w / d t$, as well as of $w$, are subject to given periodic variations. We may write

$$
\begin{equation*}
\Phi \frac{d^{2} w}{d t^{2}}+\Psi \frac{d w}{d t}+\Theta w=0 \tag{32}
\end{equation*}
$$

where

$$
\begin{equation*}
\Phi=\Sigma \Phi_{n} e^{e^{i n t}}, \quad \Psi=\Sigma \Psi_{n} e^{2 i n t}, \quad \Theta=\Sigma \Theta_{n} e^{2 i n t} . \tag{33}
\end{equation*}
$$

Assuming, as before,

$$
\begin{equation*}
w=\Sigma_{n} b_{n} e^{i c t+2 i n t} \tag{34}
\end{equation*}
$$

we obtain, on substitution, as the coefficient of $e^{i c t+2 i m t}$,

$$
-\Sigma_{n} b_{n}(c+2 n)^{2} \Phi_{m-n}+i \Sigma_{n} b_{n}(c+2 n) \Psi_{m-n}+\Sigma b_{n} \Theta_{m-n}
$$

which is to be equated to zero. The equation for $c$ may still be written

$$
\begin{equation*}
\mathfrak{D}(c)=0, . \tag{35}
\end{equation*}
$$

where
$\mathfrak{D}(c)=\left|\begin{array}{ccccc}\cdot . \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdots[-2,0], & {[-1,-1],} & {[0,-2],} & {[1,-3],} & {[2,-4], \cdots} \\ \cdots[-2,1], & {[-1,0],} & {[0,-1],} & {[1,-2],[2,-3], \ldots} \\ \cdots[-2,2], & {[-1,1],} & {[0,0],} & {[1,-1],[2,-2], \ldots} \\ \cdots[-2,3], & {[-1,2],} & {[0,1],} & {[1,0],} & {[2,-1], \ldots} \\ \cdots[-2,4], & {[-1,3],} & {[0,2],} & {[1,1],} & {[2,0],}\end{array}\right| \cdots(36)$
and

$$
[n, r]=(c+2 n)^{2} \Phi_{r}-i(c+2 n) \Psi_{r}-\Theta_{r} . . .(37)
$$

By similar reasoning to that employed by Mr. Hill we may show that

$$
\begin{aligned}
\mathfrak{D}(c) & =\mathrm{A}\left(\cos \pi c-\cos \pi c_{0}\right) \\
& +\mathrm{B}\left(\sin \pi c-\sin \pi c_{0}\right) \ldots,
\end{aligned}
$$

where A and B are constants independent of $c$; and, further, that

$$
\begin{equation*}
\mathfrak{D}(0)=\mathrm{A}(1-\cos \pi c)-\mathrm{B} \sin \pi c \tag{38}
\end{equation*}
$$

If all the quantities $\Phi_{r}, \Psi_{r}, \Theta_{r}$ vanish except $\Phi_{0}, \Psi_{0}, \Theta_{0}$, $\mathfrak{T}(0)$ reduces to the diagonal row simply, say $\mathfrak{D}^{\prime}(0)$. Let $c_{1}, c_{2}$ be the roots of

$$
\begin{equation*}
\Phi_{0} \frac{d^{2} w}{d t^{2}}+\Psi_{0} \frac{d w}{d t}+\Theta_{0} w=0 \tag{39}
\end{equation*}
$$

then

$$
\begin{aligned}
\mathfrak{I}^{\prime}(0) & =\mathrm{A}\left(1-\cos \pi c_{1}\right)-\mathrm{B} \sin \pi c_{1} \\
& =\mathrm{A}\left(1-\cos \pi c_{2}\right)-\mathrm{B} \sin \pi c_{2} ;
\end{aligned}
$$

so that the equation for $c$ may be written

$$
\left|\begin{array}{ccc}
\mathfrak{S}(0), & 1-\cos \pi c, & \sin \pi c  \tag{40}\\
\mathfrak{B}^{\prime}(0), & 1-\cos \pi c_{1}, & \sin \pi c_{1}, \\
\mathfrak{D}^{\prime}(0), & 1-\cos \pi c_{2}, & \sin \pi c_{2},
\end{array}\right|=0
$$

In this equation $\mathfrak{D}(0) \div \mathfrak{D}^{\prime}(0)$ is the determinant derived from $\mathfrak{S}(0)$ by dividing each row so as to make the diagonal constituent unity.
If $\ldots \Psi_{-1}, \Psi_{0}, \Psi_{1} \ldots$ vanish (even though $\ldots \Phi_{-1}, \Phi_{0}, \Phi_{1} \ldots$ remain finite), $\mathfrak{D}(c)$ is an even function of $c$, and the coefficient $B$ vanishes in (38). In this case we have simply

$$
\frac{1-\cos \pi c}{1-\cos \pi \sqrt{ } \Theta_{0}}=\frac{\mathfrak{D}(0)}{\mathfrak{D}^{\prime}(0)}
$$

exactly as when $\Phi_{1}, \Phi_{-1}, \Phi_{2}, \Phi_{-2} \ldots$ vanish.

Reverting to (24), we have as the approximate particular solution, when there is no dissipation,

$$
\begin{equation*}
w=\frac{e^{(c-2) i t}}{(c-2)^{2}-\Theta_{0}}+\frac{e^{c i t}}{\Theta_{1}}+\frac{e^{(c+2) i t}}{(c+2)^{2}-\Theta_{0}} . \tag{41}
\end{equation*}
$$

If $c$ be real, the solution may be completed by the addition of a second, found from (41) by changing the sign of $c$. Each of these solutions is affected with an arbitrary constant multiplier. The realized general solution may be written

$$
\begin{align*}
& w=\frac{\mathrm{R} \cos (c-2) t+\mathrm{S} \sin (c-2) t}{(c-2)^{2}-\Theta_{3}} \\
& +\frac{\mathrm{R} \cos c t+\mathrm{S} \sin c t}{\Theta_{1}}+\frac{\mathrm{R} \cos (c+2) t+\mathrm{S} \sin (c+2) t}{(c+2)^{2}-\Theta_{0}}, \tag{42}
\end{align*}
$$

from which the last term may usually be omitted, in consequence of the relative magnitude of its denominator. In this solution $c$ is determined by (26).

When $c^{2}$ is imaginary, we take

$$
\begin{equation*}
4 s^{2}=\Theta_{1}^{2}-\left(\Theta_{0}-1\right)^{2} ; \tag{43}
\end{equation*}
$$

so that

$$
c^{2}=1+2 i s, \quad c=1+i s, \quad c-2=-1+i s .
$$

The particular solution may be written

$$
\begin{equation*}
w=e^{-s t}\left\{\Theta_{1} e^{-i t}+\left(1-\Theta_{0}-2 i s\right) e^{i t}\right\} ; . . \tag{44}
\end{equation*}
$$

or, in virtue of (43),

$$
\begin{equation*}
w=e^{-s t}\left\{\left(1-\Theta_{0}+\Theta_{1}\right) \cos t+2 s \sin t\right\} ; \tag{45}
\end{equation*}
$$

or, again,
$w=e^{-s t}\left\{\sqrt{ }\left(\Theta_{1}+1-\Theta_{0}\right) \cdot \cos t+\sqrt{ }\left(\Theta_{1}-1+\Theta_{0}\right) \cdot \sin t\right\} .$.
The general solution is

$$
\left.\begin{array}{rl}
w & =\operatorname{R} e^{-s t}\left\{\left(1-\Theta_{0}+\Theta_{1}\right) \cos t+2 s \sin t\right\}  \tag{47}\\
& +\operatorname{Se} e^{s t}\left\{\left(1-\Theta_{0}+\Theta_{1}\right) \cos t-2 s \sin t\right\}
\end{array}\right\}
$$

$\mathrm{R}, \mathrm{S}$ being arbitrary multipliers.
One or two particular cases may be noticed. If $\Theta_{0}=1$, $2 s=\Theta_{1}$, and

$$
\left.\begin{array}{rl}
w & =\mathrm{R}^{\prime} e^{-s t}\{\cos t+\sin t\}  \tag{48}\\
& +\mathrm{S}^{\prime} e^{s t}\{\cos t-\sin t\}
\end{array}\right\} .
$$

Again, suppose that

$$
\begin{equation*}
\Theta_{1}^{2}=\left(\Theta_{0}-1\right)^{2} \tag{49}
\end{equation*}
$$

so that $s$ vanishes, giving the transition between the real and
imaginary values of $c$. Of the two terms in (46), one or other preponderates indefinitely in the two alternatives. Thus, if $\Theta_{1}=1-\Theta_{0}$, the solution reduces to $\cos t$; but if $\Theta_{1}=-1+\Theta_{0}$, it reduces to $\sin t$. The apparent loss of generality by the merging of the two solutions may be repaired in the usual way by supposing $s$ infinitely small.

When there are dissipative forces, we are to replace $c$ by ( $c-i k$ ), and $\Theta$ by ( $\Theta_{0}-k^{2}$ ); but when $k$ is small the latter substitution may be neglected. Thus, from (26),

$$
\begin{equation*}
c=1+i k+\frac{1}{2} \vee\left\{\left(\Theta_{0}-1\right)^{2}-\Theta_{1}^{2}\right\} . . . . \tag{50}
\end{equation*}
$$

Interest here attaches principally to the case where the radical is imaginary; otherwise the motion necessarily dies down. If, as before,

$$
\begin{gather*}
4 s^{2}=\Theta_{1}{ }^{2}-\left(\Theta_{0}-1\right)^{2},  \tag{51}\\
c=1+i k+i s, \quad c-2=-1+i k+i s, \tag{52}
\end{gather*}
$$

and

$$
w=\frac{e^{(c-2) i t}}{(c-i k-2)^{2}-\Theta_{0}}+\frac{e^{c i t}}{\Theta_{1}},
$$

or

$$
w=e^{-(k+s)}\left\{\Theta_{1} e^{-i t}+\left(1-\Theta_{0}-2 i s\right) e^{i t}\right\},
$$

or

$$
\begin{equation*}
w=\epsilon^{-(k+s) t}\left\{\left(1-\Theta_{0}+\Theta_{1}\right) \cos t+2 s \sin t\right\} . . \tag{53}
\end{equation*}
$$

This solution corresponds to a motion which dies away.
The second solution (found by changing the sign of $s$ ) is

$$
\begin{equation*}
w=e^{(s-k) t}\left\{\left(1-\Theta_{0}+\Theta_{1}\right) \cos t-2 s \sin t\right\} . \tag{54}
\end{equation*}
$$

The motion dies away or increases without limit according as $s$ is less or greater than $k$.

The only case in which the motion is periodic is when $s=k$, or

$$
\begin{equation*}
4 k^{2}=\Theta_{1}^{2}-\left(\Theta_{0}-1\right)^{2} ; \tag{55}
\end{equation*}
$$

and then

$$
\begin{equation*}
w=\left(1-\Theta_{0}-\Theta_{1}\right) \cos t-2 k \sin t . \tag{56}
\end{equation*}
$$

These results, under a different notation, were given in my former paper*.

If $\Theta_{0}=1$, we have by (51), $2 s=\Theta$; and from (53), (54),
$w=\mathrm{R} e^{-(k+s) t}\{\cos t+\sin t\}+\mathrm{S} e^{-(k-s) t}\{\cos t-\sin t\} .$. (57)

[^1]In the former paper some examples were given drawn from ordinary mechanics and acoustics. To these may be added the case of a stretched wire, whose tension is rendered periodically variable by the passage through it of an intermittent electric current. It is probable that an illustration might be arranged in which the vibrations are themselves electrical. $\Theta_{0}$ would then represent the stiffness of a condenser, $\Psi_{0}$ resistance, and $\Phi_{0}$ self-induction. The most practicable way of introducing the periodic term would be by rendering the selfinduction variable with the time $\left(\Phi_{1}\right)$. This could be effected by the rotation of a coil forming part of the circuit.

The discrimination of the real and imaginary values of $c$ is of so much importance, that it is desirable to pursue the approximation beyond the point attained in (26). From (11) we find

$$
\begin{equation*}
\frac{\mathfrak{S}(1)}{\mathfrak{S}^{\prime}(1)}=\frac{1+\cos (\pi c)}{1+\cos \left(\pi \sqrt{ } \Theta_{0}\right)} ; \tag{58}
\end{equation*}
$$

from which, or directly, we see that if $c=1$, corresponding to the transition case between real and imaginary values,

$$
\begin{equation*}
\mathfrak{D}(1)=0 . \tag{59}
\end{equation*}
$$

If, as we shall now suppose, $\Theta_{2}, \Theta_{3} \ldots$ vanish, (59) may be written in the form

$$
\left|\begin{array}{cccccccc}
. & . & . & . & . & .  \tag{60}\\
\ldots .1, & a_{2}, & 1, & 0, & 0, & 0 \ldots \\
\ldots .0, & 1, & a_{1}, & 1, & 0, & 0 \ldots \\
\ldots .0, & 0, & 1, & a_{1}, & 1, & 0 \ldots \\
\ldots .0, & 0, & 0, & 1, & a_{2}, & 1 & \ldots
\end{array}\right|=0, .
$$

where

$$
\begin{equation*}
a_{1}=\frac{\Theta_{0}-1}{\Theta_{1}}, \quad a_{2}=\frac{\Theta_{0}-9}{\Theta_{1}}, \quad a_{3}=\frac{\Theta_{0}-25}{\Theta_{1}}, . \tag{61}
\end{equation*}
$$

The first approximation, equivalent to (26), is found by considering merely the central determinant of the second order involving only $a_{1}$; thus,

$$
\begin{equation*}
a_{1}^{2}-1=0 \tag{62}
\end{equation*}
$$

The second approximation is

$$
\begin{equation*}
a_{2}^{2}\left\{\left(a_{1}-\frac{1}{a_{2}}\right)^{2}-1\right\}=0 \tag{63}
\end{equation*}
$$

The third is

$$
\begin{equation*}
a_{3}^{2}\left\{a_{2}-\frac{1}{a_{3}}\right\}^{2}\left\{\left(a_{1}-\frac{1}{a_{2}-\frac{1}{a_{3}}}\right)^{2}-1\right\}=0, \ldots \tag{64}
\end{equation*}
$$

and so on. The equation (60) is thus equivalent to

$$
\begin{equation*}
a_{1}-\frac{1}{a_{2}-} \frac{1}{a_{3}-} \frac{1}{a_{4}-} \cdots= \pm 1 ; ~ . \tag{65}
\end{equation*}
$$

and the successive approximations are

$$
\begin{equation*}
N_{1}= \pm D_{1}, \quad N_{2}= \pm D_{2}, \tag{66}
\end{equation*}
$$

where

$$
\frac{\mathrm{N}_{1}}{\mathrm{D}_{1}}, \frac{\mathrm{~N}_{2}}{\mathrm{D}_{2}}, \ldots
$$

are the corresponding convergents to the infinite continued fraction*.

In terms of $\Theta_{0}, \Theta_{1}$, the second approximation to the equation discriminating the real and imaginary values of $c$ is

$$
\begin{equation*}
\left(\Theta_{0}-1\right)\left(\Theta_{0}-9\right)-\Theta_{1}{ }^{2}= \pm \Theta_{1}\left(\Theta_{0}-9\right) . \tag{67}
\end{equation*}
$$

One of the most interesting applications of the foregoing analysis is to the case of a laminated medium in which the mechanical properties are periodic functions of one of the coordinates. I was led to the consideration of this problem in connexion with the theory of the colours of thin plates. It is known that old superficially decomposed glass presents reflected tints much brighter, and transmitted tints much purer, than any of which a single transparent film is capable. The laminated structure was proved by Brewster; and it is easy to see how the effect may be produced by the occurrence of nearly similar lamine at nearly equal intervals. Perhaps the simplest case of the kind that can be suggested is that of a stretched string, periodically loaded, and propagating transverse vibrations. We may imagine similar small loads to be disposed at equal intervals. If, then, the wave-length of a train of progressive waves be approximately equal to the double interval between the loads, the partial reflexions from the various loads will all concur in phase, and the result must be a powerful aggregate reflexion, even though the effect of an individual load may be insignificant.

[^2]The general equation of vibration for a stretched string of periodic density is

$$
\begin{align*}
&\left(\rho_{0}+\rho_{1} \cos \frac{2 \pi x}{l}+\rho_{1}^{\prime} \sin \frac{2 \pi x}{l}+\rho_{2} \cos \frac{4 \pi x}{l}\right. \\
&\left.+\rho_{2}{ }^{\prime} \sin \frac{4 \pi x}{l}+\ldots\right) \frac{d^{2} w}{d t^{2}}=\mathrm{T} \frac{d^{2} w}{d x^{2}}, \ldots \tag{68}
\end{align*}
$$

$l$ being the distance in which the density is periodic. We shall suppose that $\rho_{1}{ }^{\prime}, \rho_{2}{ }^{\prime}, \ldots$ vanish, so that the sines disappear, a supposition which involves no loss of generality when we restrict ourselves to a simple harmonic variation of density. If we now assume that $w \propto e^{i p t}$, or $\propto \cos p t$, we obtain

$$
\begin{equation*}
\frac{d^{2} w}{d \xi^{2}}+\left(\Theta_{0}+2 \Theta_{1} \cos 2 \xi+2 \Theta_{2} \cos 4 \xi+\ldots\right) w=0, \ldots \tag{69}
\end{equation*}
$$

where $\xi=\pi x / l$, and

$$
\begin{equation*}
\Theta_{0}=\frac{p^{2} l^{2} \rho_{0}}{\pi^{2} \mathrm{~T}}, \quad 2 \Theta_{1}=\frac{p^{2} l^{2} \rho_{1}}{\pi^{2} \mathrm{~T}}, \text { \&c.; . . } \tag{70}
\end{equation*}
$$

and this is of the form of Mr. Hill's equation (2).
When $c$ is real, we may employ the approximate solutions (41), (44). The latter (with $\xi$ written for $t$ ) gives, when multiplied by $\cos p t$ or $\sin p t$, the stationary vibrations of the system. From (41) we get

$$
\begin{equation*}
w=\frac{\cos [p t+(c-2) \xi]}{(c-2)^{2}-\Theta_{0}}+\frac{\cos [p t+c \xi]}{\Theta_{1}}, \ldots \tag{71}
\end{equation*}
$$

in which, if $c=1$ nearly, the two terms represent waves progressing with nearly equal velocities in the two directions. Neither term gains permanently in relative importance as $x$ is increased or diminished indefinitely.

It is otherwise when the relation of $\Theta_{0}$ to $\Theta_{1}$ is such that $c$ is imaginary. By (44) the solution for $w$, assumed to be proportional to $e^{i p t}$, now takes the form

$$
\left.\begin{array}{rl}
w & =\mathrm{R}^{-s \xi}\left\{\Theta_{1} e^{i(p t-\xi)}+\left(1-\Theta_{0}-2 i s\right) e^{i(p t+\xi)}\right\},  \tag{72}\\
& +\mathrm{S}^{s \xi \xi}\left\{\Theta_{1} e^{i(p t-\xi)}+\left(1-\Theta_{0}+2 i s\right) e^{i(p t+\xi)}\right\} .
\end{array}\right\}
$$

Whatever may be the relative values of $R$ and $S$, the first solution preponderates when $x$ is large and negative, and the second preponderates when $x$ is large and positive. In either extreme case the motion is composed of two progressive waves moving in opposite directions, whose amplitudes are equal in virtue of (43).

The meaning of this is that a wave travelling in either
direction is ultimately totally reflected. For example, we may so choose the values of R and S that at the origin of $x$ there is a wave (of given strength) in the positive direction only, and we may imagine that it here passes into a uniform medium, and so is propagated on indefinitely without change. But, in order to maintain this state of things, we have to suppose on the negative side the coexistence of positive and negative waves, which at sufficient distances from the origin are of nearly equal and ever-increasing amplitudes. In order therefore that a small wave may emerge at $x=0$, we have to cause intense waves to be incident upon a face of the medium corresponding to a large negative $x$, of which nearly the whole are reflected.

It is important to observe that the ultimate totality of reflexion does not require a special adjustment between the frequency of the waves and the linear period of the lamination. The condition that $c$ should be imaginary is merely that $\Theta_{1}$ should numerically exceed $\left(1-\Theta_{0}\right)$. If $\lambda$ be the wave-length of the vibration corresponding to $e^{i p t}$ and to density $\rho_{0}$,

$$
\begin{equation*}
\frac{p^{2} \rho_{0}}{\pi^{2} T}=\frac{4}{\lambda^{2}} \tag{73}
\end{equation*}
$$

and thus the limits between real and imaginary values of $c$ are given by

$$
\begin{equation*}
\frac{\lambda^{2}}{4 l^{2}}-1= \pm \frac{\rho_{1}}{2 \rho_{0}} . \tag{74}
\end{equation*}
$$

If $\rho_{1}$ exceeds these limits a train of waves is ultimately totally reflected, in spite of the finite difference between $\frac{1}{2} \lambda$ and $l$ *.

[^3]In conclusion, it may be worth while to point out the application to such a problem as the stationary vibrations of a string of variable density fixed at two points. A distribution of density,

$$
\begin{equation*}
\rho_{0}+\rho_{1} \cos \frac{2 \pi x}{l}+\rho_{2} \cos \frac{4 \pi x}{l}+\ldots . \cdot . \tag{75}
\end{equation*}
$$

is symmetrical with respect to the points $x=0$ and $x=\frac{1}{2} l$, and between those limits is arbitrary. It is therefore possible for a string of this density to vibrate with the points in question undisturbed, and the law of displacement will be
$w=\cos p t\left\{\mathrm{~A}_{1} \sin \frac{2 \pi x}{l}+\mathrm{A}_{2} \sin \frac{4 \pi x}{l}+\mathrm{A}_{3} \sin \frac{6 \pi x}{l}+\ldots\right\}$.
When, therefore, the problem is attacked by the method of Mr. Hill, the value of $c$ obtained by the solution of (69) must be equal to 2. By (15) this requires

$$
\begin{equation*}
\square(0)=0 \text {. } \tag{77}
\end{equation*}
$$

This equation gives a relation between the quantities $\Theta_{0}, \Theta_{1}$, $\Theta_{2}, \ldots$; and this again, by (70), determines $p$, or the frequency ( $p / 2 \pi$ ) of vibration.

Since $\Theta_{0}=4$ nearly, the most important term in (17) is that involving $\Theta_{2}{ }^{2}$. The first approximation to (77) gives

$$
\Theta_{0}=4+\Theta_{2} ;
$$

whence, by (70),

$$
\begin{equation*}
\left(\frac{2 \pi}{p}\right)^{2}=\frac{l^{2}\left(\rho_{0}-\frac{1}{2} \rho_{2}\right)}{\mathrm{T}} . . . . . \tag{78}
\end{equation*}
$$

To this order of approximation the solution may be obtained with far greater readiness by the method given in my work on Sound*; but it is probable that, if the solution were required in a case where the variation of density is very considerable, advantage might be taken of Mr. Hill's determinant
$\square(0)$. There are doubtless other physical problems to which a similar remark would be applicable.

Terling Place, Witham, June 19, 1887.

* 'Theory of Sound,' vol. i. § 140. In comparing the results, it must be borne in mind that the length of the string in ( 78 ) is denoted by $\frac{1}{2} l$.


[^0]:    * Communicated by the Author.
    $\dagger$ "On Maintained Vibrations." Phil. Mag. April 1883, p. 229.
    $\ddagger$ " When the direction of motion is transverse, the case falls under the head of ordinary forced vibrations."

[^1]:    * In consequence of an error of sign, the result for a second approximation there stated is incorrect.

[^2]:    * The relations of determinants of this kind to continued fractions has been studied by Muir (Edinb. Proc. vol. viii.).

[^3]:    * A detailed experimental examination of various cases in which a laminated structure leads to a powerful but highly selected reflexion would be of value. The most frequent examples are met with in the organic world. It has occurred to me that Becquerel's reproduction of the spectrum in natural colours upon silver plates may perhaps be explicable in this manner. The various parts of the film of subchloride of silver with which the metal is coated may be conceived to be subjected, during exposure, to stationary luminous waves of nearly definite wavelength, the effect of which might be to impress upon the substance a periodic structure recurring at intervals equal to half the wave-length of the light; just as a sensitive flame exposed to stationary sonorous waves is influenced at the loops but not at the nodes (Phil. Mag. March 1879, p. 153). In this way the operation of any kind of light would be to produce just such a modification of the film as would cause it to reflect copiously that particular kind of light. I abstain at present from developing this suggestion, in the hope of soon finding an opportunity of making myself experimentally acquainted with the subject.

