

Ground-based synthetic aperture radar interferometry for deformation monitoring: a case study at Geheyan Dam, China

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Abstract. Full coverage and continuous deformation information retrieval are key aspects for dam health diagnosis. Ground-based synthetic aperture radar (GB-SAR) interferometry is used for the remote monitoring of the Geheyan Dam, China. Although the monitoring of a dam with ground-based interferometry is not an innovation, specific issues have been found out in the case study discussed due to the large dimension of the monitored structure. More than 400 images were used for interferogram generation. Radar signals reflected from the dam were carefully analyzed: a sort of tunneling effect caused by multireflection is observed, and deformations caused by water level and temperature variations were detected during a six-day monitoring campaign. Radar monitoring results were compared to the data recorded by plummets installed in the dam. The agreement between the displacements retrieved from interferometric data and the plummets demonstrates the capability of GB-SAR for deformation monitoring, with the advantage of large area coverage.

Keywords: ground-based radar; interferometry; dam; deformation.

1 Introduction

To monitor the health-state of a dam, the detection and estimate of small deformations are crucial. Pointwise deformation measurement techniques, such as the Global Positioning System, leveling, and plummet, are usually employed for data collection. These sparsely distributed points are used to describe the movement of the entire dam, and deformation details might be overlooked due to the lack of points, especially when the dimension of the monitored structure is large. Furthermore, these field data collection activities are labor intensive and, in some situations, even unsafe. Terrestrial laser scanning allows capturing dense 3-D point clouds with a high degree of automation, but the accuracy and effectiveness of this technique strongly decreases with sensor to target distance and with adverse atmospheric conditions.

Ground-based synthetic aperture radar (GB-SAR) for deformation monitoring has consolidated in the last decade as a tool able to provide displacement maps with high spatial and temporal resolution and accuracy in different situations.^{1,2} It is a radar-based terrestrial remote sensing imaging system that exploits the interferometric capability of centimeter wavelength microwaves to obtain submillimeter to millimeter deformation estimates.³ Although not widespread as spaceborne SAR interferometry, GB-SAR interferometry has proven to be a reliable remote sensing tool.

The GB-SAR technique has been used to monitor a wide range of deformation phenomena, such as volcanoes,⁴ landslides,^{5,6} and glaciers,⁷ and open-pit mine monitoring,⁸ and also for topographic mapping.^{9,10} The use of GB-SAR for dam deformation monitoring dates back to 1999¹¹ and was further demonstrated by Alba et al.¹² The dams' front profiles monitored in both cases are relatively small and flat, with easily interpreted backscattering properties.

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In this work, a dam with a large complex front profile is monitored. The dam here monitored has been already surveyed in a previous study,¹³ but with a different geometry, from a shorter range and for 8 h only. Xing et al.¹³ focused on the environmental effects affecting the radar acquisition, even though the limited range and short temporal duration of the monitoring reduce the influence of atmospheric propagation with respect to the case analyzed in this paper. In this paper, different behaviors of radar signals reflected from different parts of the structure are analyzed, aimed at estimating deformations during a longer lapse, and from a large distance. The main results of the monitoring in this paper consist of deformation time series covering more than 120 h, where the influence of daily atmospheric fluctuations is detected and corrected. The outcomes are compared with daily plummet measurements to assess the reliability of the proposed approach. The relationship between the behavior of deformation along time and the reservoir water level and temperature variation occurred during the period surveyed are analyzed.

2 GB-SAR Deformation Monitoring

2.1 GB-SAR System

The GB-SAR is a monitoring system mainly composed of the following four separate modules: (1) a radar sensor able to transmit and receive microwave signals, (2) a mechanical scanning rail, 2-m long in the case at hand, along which the sensor moves providing synthetic aperture imaging,³ (3) a laptop for data acquisition and processing, and (4) a power supply module that allows continuous measurements. Many types of GB-SAR systems have been developed in the last decades. A review of the GB-SAR system used in this work can be found in Ref. 14. All the applications of this technique need to carefully deal with the atmospheric artifacts, which are the main source of error in GB-SAR interferometry.¹⁵ Atmospheric phase screen (APS) studies and related solutions have been proposed by different authors. In Sec. 3, where the data processing chain and strategy are described, this issue will be addressed.

Figure 1 shows a general view of the IBIS-L GB-SAR system marketed by IDS Ingegneria dei Sistemi SpA, which was used for data collection in the Geheyan Dam area.

2.2 GB-SAR Interferometry for Deformation Monitoring

Ground-based radar interferometry is based on the same principles as satellite interferometry. SAR interferometry exploits the phase difference between two temporally separated SAR observations; the observed phase of each pixel of an SAR image contains information about its distance from the GB-SAR sensor. If decorrelation is negligible, an interferogram can be generated using two SAR acquisitions by computing the phase difference between these two images. The differential phase obtained is, in the simplest case, proportional to the variation of the line-of-sight (LOS) distance. With respect to satellite SAR interferometry, where each image is acquired from a different position (due to the orbit constraints) introducing a spatial baseline,¹⁶ in the case of ground-based observations, the radar is maintained in the same position, i.e., with zero baseline. Assuming that the dielectric characteristic of the pixels of the SAR image remain unchanged between two SAR acquisitions, the interferogram generated reveals the displacement

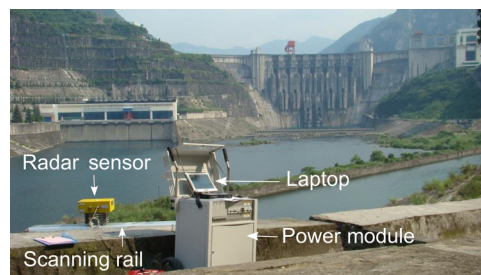


Fig. 1 IBIS-L system installed at Geheyan Dam area.

of the observed surface occurring in the observed period. The displacement associated with a pixel can be recovered using the following simple equation:

$$d_x = \frac{\lambda}{4\pi} \Delta\varphi_x, \quad (1)$$

where λ is the wavelength of the radar sensor and $\Delta\varphi_x$ is the phase difference (interferometric phase) of pixel x . Interferograms can be obtained following two different approaches: by comparing pairs of images acquired at different times separated by the same interval or taking an image as a reference and one acquired at a different increasing time. In the first case used in this data processing, wrapping and decorrelation are reduced.¹¹

In reality, decorrelation caused by geometrical, instrumental, and temporal causes can affect the estimated displacement. Geometrical decorrelation is minimized by installing the GB-SAR system in a stable position on a concrete base. The performances of the radar sensor and the stability of backscattering characteristics of the monitored surface are responsible for maintaining a negligible decorrelation along the whole image acquisition duration.

2.3 Measurement Setup

The Geheyan Dam is located in the Qingjiang River, a tributary of the Yangtze River, surrounded by high mountains on both sides. The climate of the area is subtropical continental, with cold winters and hot and humid summers. The Geheyan Dam is well-known for its singular design: a gravity dam on the lower part and an arch dam on the upper part. The crest elevation is 206 m, the maximum dam elevation from bottom to top is 151 m, and the arc length is 648 m. The overflow section is located at the middle of the dam and has seven surface orifices (the highest at 181.8 m), four middle orifices (the highest at 134 m), and two deep orifices (the highest at 95 m) mounted with radial gates. The orifices dimensions (width \times height) are 12.0 \times 18.2 m, 4.5 \times 6.5 m, and 4.5 \times 6.5 m, respectively. The powerhouse is located on the right bank terrace of the river and a vertical ship lift stands on the left bank.

The IBIS-L system was installed on a concrete stable platform on the left bank terrace at a distance of \sim 1300 m (Figs. 1 and 2). The main parameters of the system are listed in Table 1. 1330 GB-SAR images were collected between July 27 and August 2, 2013, totaling an acquisition period of 5 days, 14 h, and 48 min. These images were acquired in an almost continuous mode, a time interval between image acquisitions of about 5 min, with the exception of some breaks caused by power supply interruptions. Figure 3(a) shows the mean amplitude image with the dam area highlighted by a white rectangle. The pixel selection was based on the amplitude dispersion index (D_A)¹⁷

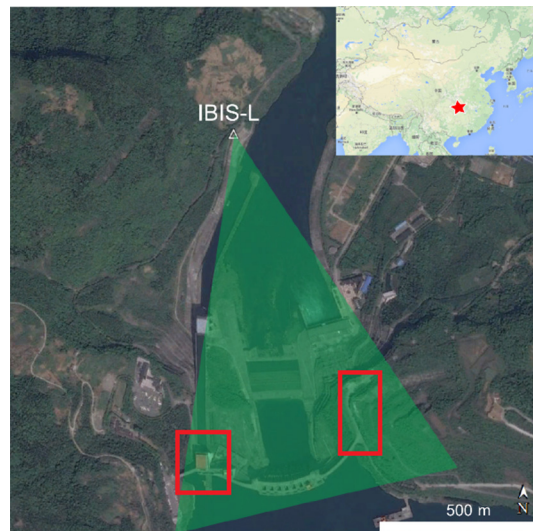


Fig. 2 Geographic location of Geheyan Dam and GB-SAR imaging field of view (green area), the red rectangles marked the area for APS removal.

Table 1 Main parameters of IBIS-L during the Geheyan campaign.

GB-SAR parameters	
Central frequency/wavelength	17.1 GHz/1.75 cm
Length of the synthetic aperture	2 m
Maximum distance from target	1300 m
Range resolution	0.5 m
Azimuth resolution	4.4 mrad
Azimuth resolution at 1200 m	5.3 m

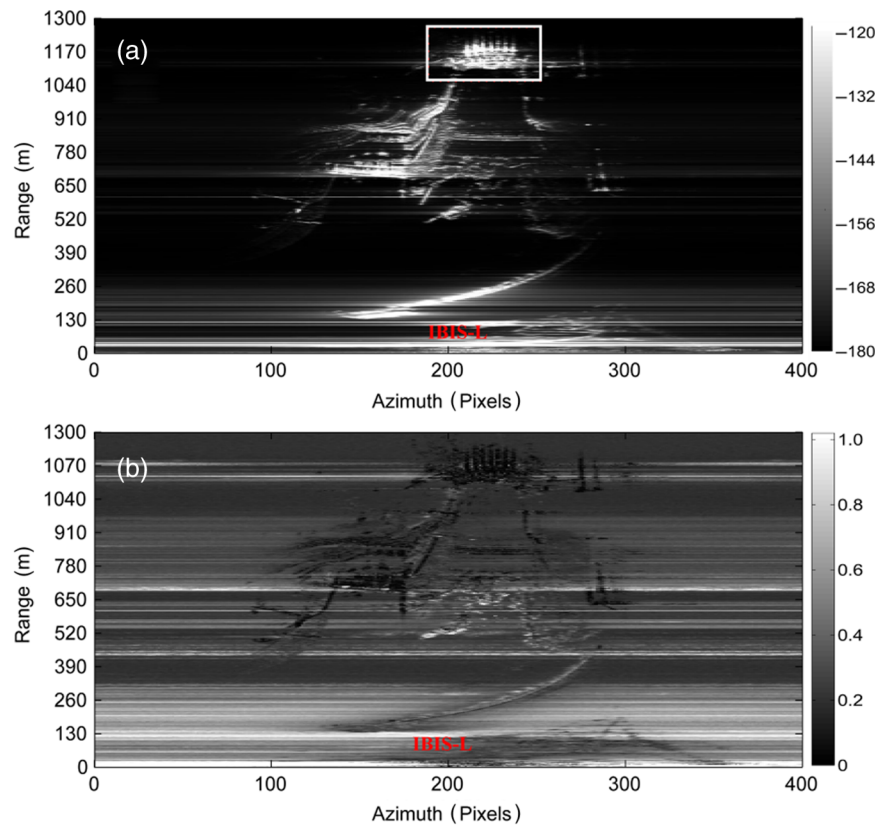


Fig. 3 (a) Mean amplitude in dB with the dam area highlighted by a white rectangle and (b) amplitude dispersion index. Both images are in radar geometry and were calculated using 444 images.

$$D_A = \frac{\sigma_A}{m_A}, \quad (2)$$

where m_A and σ_A are the mean and standard deviation of the amplitude, respectively. D_A of 0.2 was chosen as the threshold. Figure 3(b) shows the amplitude dispersion index where the darker areas are those with lower phase noise.

3 Data Processing Chain and Strategy

The flowchart of the procedure used to estimate deformation is shown in Fig. 4. Each step of the procedure is detailed here:

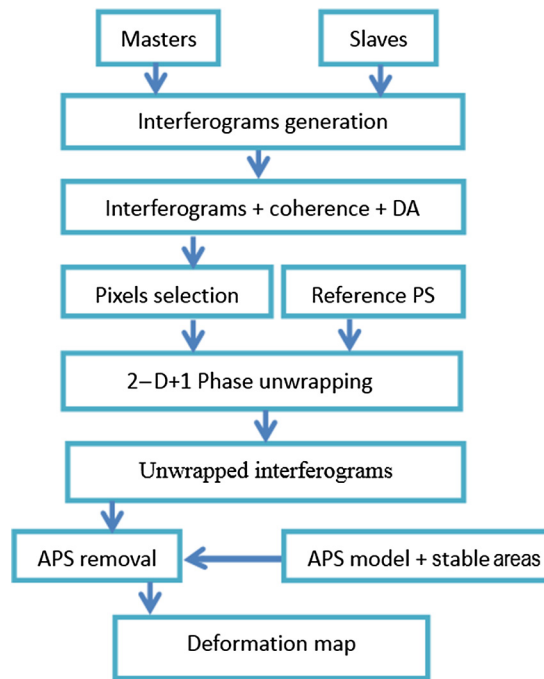


Fig. 4 Flowchart used to estimate deformation on the Geheyen dam campaign.

- GB-SAR image selection: Only 444 images out of 1330 were selected for processing aiming at reducing the computational burden of the huge amount of continuous GB-SAR images acquired. The temporal baseline among images used for analysis is ~ 16 min.
- Interferogram generation: Interferogram formation is obtained according to the following sequence: for the first selected image, the combinations 1-2, 1-3, 1-4, and 1-5 are calculated, for the second selected image, the combinations are 2-3, 2-4, 2-5, 2-6, and so on. In this way, a total of 1766 interferograms is generated. This approach allows checking the quality of the observations.
- Selection of permanent scatters (PS):¹⁶ The spatial coherence between every two consecutive images was first estimated, followed by the calculation of the mean coherence. A threshold of 0.4 was then applied to filter out low coherent areas, such as water and vegetated areas. Finally, a threshold of the amplitude dispersion index lower than 0.2 was implemented as a refinement step. The proposed PS selection strategy greatly reduces the calculation effort and decreases the probability of selecting noisy points located close to high coherent points.
- Phase unwrapping: The “2 + 1-D” phase unwrapping method developed by the Centre Tecnològic de Telecomunicacions de Catalunya (CTTC) in collaboration with the Department of Earth Sciences of the University of Milan was used.¹⁸ The two main steps of the method are: (a) a 2-D spatial phase unwrapping is performed on each interferogram generated and (b) a temporal (1-D) phase unwrapping is carried out on each pixel selected. An advantage of this unwrapping strategy is the ability to detect and correct errors that may exist in the 2-D spatial phase unwrapping stage, reducing the error propagation in subsequent processing steps.
- APS removal: As the APS effects are assumed to be strongly spatially correlated in our procedure, a 2-D quadratic polynomial model presented in Ref. 19 is used for APS estimation. On the basis of the plummets behavior, the points on both sides of the dam are first selected as stable areas to estimate the model parameters (see the two red rectangles marked in Fig. 2). Considering the heavy water vapor affecting those points close to the riverbed, they were not used for APS model estimation. Second, the APS was estimated over selected stable areas by least square adjustment performing an outlier rejection. Finally, the estimated model was used over the unstable area to obtain the APS phase component, which was subsequently subtracted from the original phase to obtain an

APS cleaned phase for the entire set of selected points. The APS removal in terrestrial radar acquisition has been discussed in several papers.²⁰⁻²²

4 Results

4.1 GB-SAR Image Interpretation

Several points were selected to interpret the radar image prior to analyzing and studying the temporal behavior of the dam deformation. Figure 5(a) shows the mean amplitude image calculated using 444 images while a view of the dam from Google Earth[®] is shown in Fig. 5(b). A comparison of both images allows delineating the crest of the dam (marked with a red dashed line). The best way to interpret a GB-SAR image is to obtain the digital surface model (DSM) of

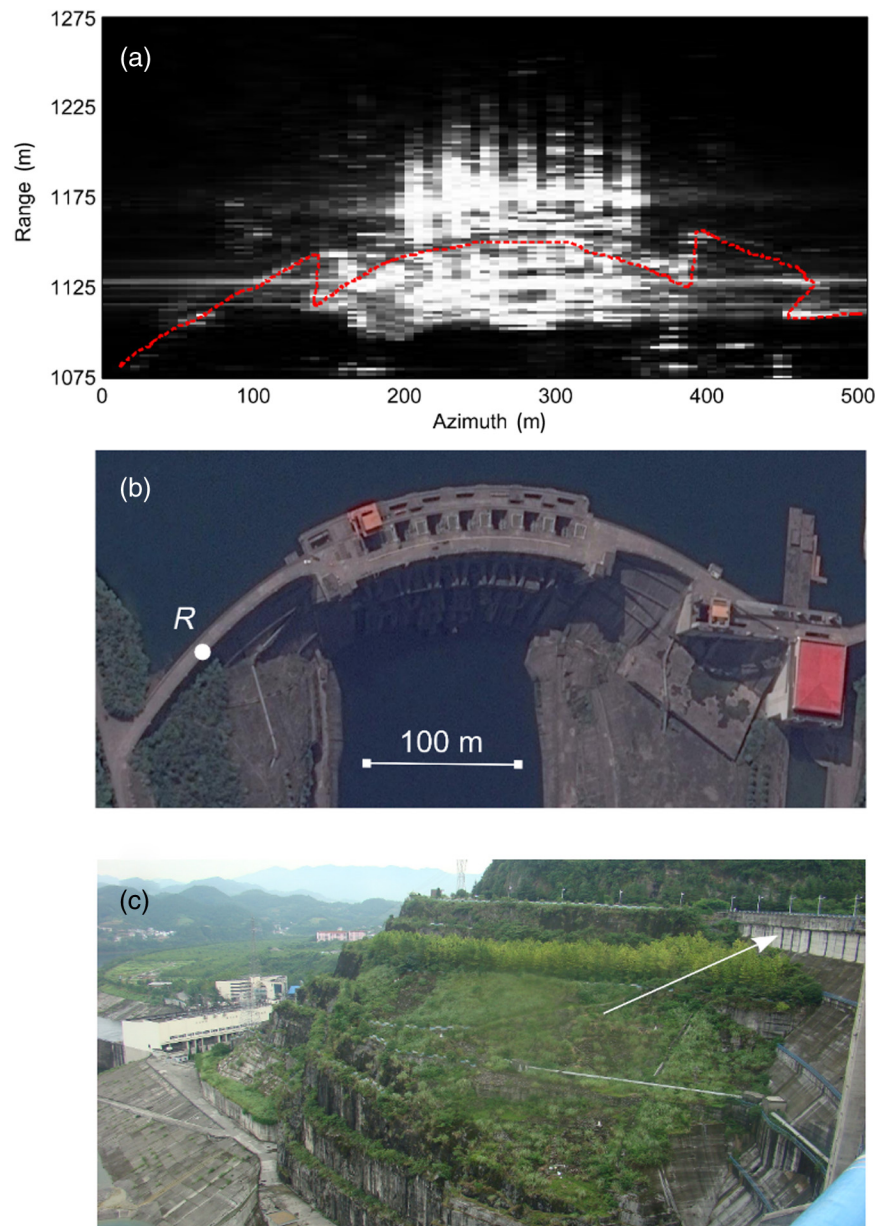


Fig. 5 (a) Zoom of the mean amplitude image obtained from GB-SAR data in radar coordinates. The Y-axis indicates the distance in meters from the GB-SAR. The red dashed line highlights the crest of the dam. (b) View of Geheyan Dam from Google Earth[®]. (c) Picture of the dam with the white arrow indicating the location of the reference point *R*.

the measured area and to geocode the GB-SAR image using this DSM. In this work, a DSM of the dam was not available to assist the interpretation of the GB-SAR image.

As mentioned above, also a GB-SAR can be arranged for DSM generation, but at long distances (>1000 m), the presence of a high APS can compromise the required accuracy.¹⁰

The vertical profile of the dam, as shown in Fig. 6, was then analyzed to better understand the radar response of the other parts of the dam in the GB-SAR images. The numbers next to the triangles indicate the height in meters from the bottom of the dam. The GB-SAR was located at 145 m above sea level, 1145 m from the dam's middle crest, and it illuminated the entire dam. The elevation of the radar antennas was almost horizontal, with a maximum elevation angle of ~ 3 deg for the points located at the top of the dam. Considering the thickness of the dam and its downstream face, the pixels closer to the GB-SAR sensor correspond to the lower part of the dam face.

Another important aspect to take into account is the presence of some orifices in the dam. In fact, the radar signal can enter the dam structure through these orifices and suffer multiple reflections in the tunnel (see the red dashed arrows in Fig. 7). An interpretation of the GB-SAR amplitude map shown in Fig. 5(a) can be proposed considering the role of the multipath fading, based on the following issues: (1) the seven dam orifices agree with the number of distinct "tails" visible in this figure, (2) the orifice width agrees with the pixels response in the amplitude image. The azimuth resolution, at a sensor to target distance of 1200 m, is ~ 5.3 m. Therefore, a 2-3 pixel size in azimuth agrees with the size of the orifices, whose width is 12 m. (3) The depth of the orifices, calculated from the GB-SAR image, is above 80 m, which exceeds the thickness of the dam (41.2 m = 12.5 + 28.7 m, see Fig. 6). An interpretation of this result is that the radar signal is reflected in the hole and, consequently, the sensor to target distance is longer.

The occurrence of unexpected phase delay due to propagation and focusing artifacts (side lobe effect) has been already assessed in Ref. 23. The radar response of highly reflective metallic surfaces (orifice in this case), wet surfaces, can electromagnetically dominate less reflective parts (concrete of the dam structure) and also generate side lobes, as visible in the amplitude images [Figs. 3(a) and 5(a)].

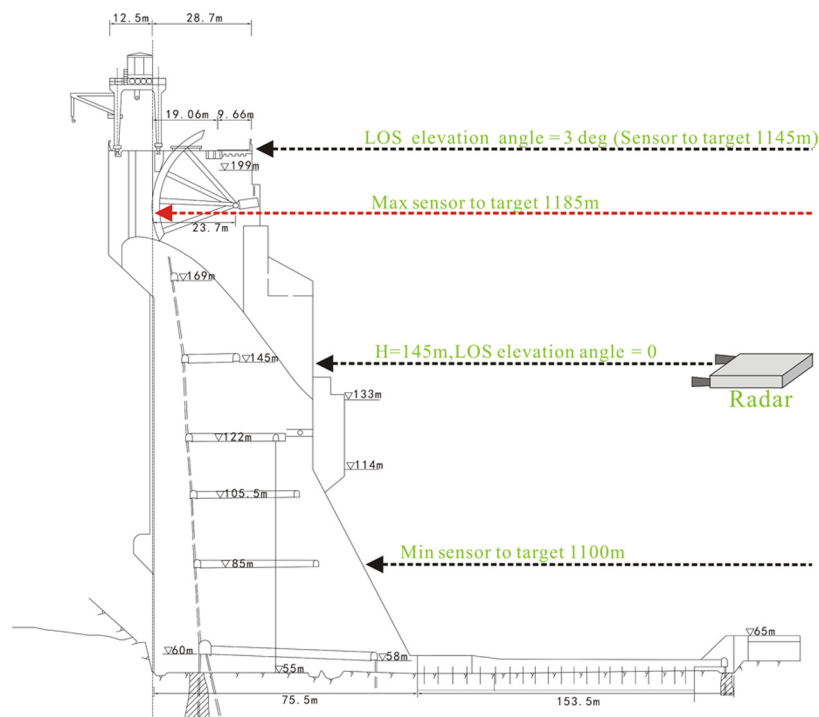


Fig. 6 Profile of the Geheyen Dam indicating the vertical position of the different radar LOS.

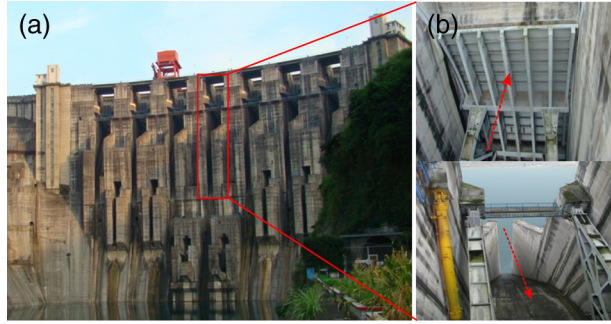


Fig. 7 (a) The dam front face and (b) details of one of the orifices. The red dashed arrows illustrate the main structures affecting the trajectory of the radar signal.

4.2 Deformation Map and Time Series

Considering the dam's plummet measurements, we choose the pixel R as the stable, reference point. Figure 8 shows the mean deformation velocity of all the selected points, and the map can be divided into two main sections using the crest of the dam (marked with a dashed red line) as a boundary: a blue section above and a green section below. The blue color indicates that these points are moving toward the radar, while the green color indicates an almost negligible deformation, i.e., no movement. A light blue strip, where a small deformation occurs toward the GB-SAR, can be clearly identified along the crest of the dam.

Figure 9 shows the time series and the calculated linear regression for points D02, D03, and D04 (Fig. 8) selected as representatives of the right, center, and left part of the crest of the dam, respectively. Despite the low correlation coefficients, which are a result of the presence of periodic fluctuations as detailed in Sec. 5, the deformation velocities can be estimated: -0.17 , -0.21 , and -0.09 mm/d, for D02, D03, and D04, respectively, as shown in Fig. 10 where the daily average deformation measured in these points is shown. Negative values refer to a reduction of the distance, i.e., motion toward the GB-SAR. The deformation behavior on the crest demonstrates that the central part of the dam shows the highest deformation velocity, which decreases progressively toward the sides.

The dam deformation was also measured using plummets during the GB-SAR campaign. Figure 11 shows the position of plummet PL15, installed in the center of the dam, with the heights of the measurement points marked with red numbers. Figure 12 shows the plummet PL15 measured movements (at different heights) toward the GB-SAR location and the reservoir water level variation during the monitoring campaign. The results indicate that the higher the position with respect to the bottom of the dam, the larger the measured deformation. The vertical behavior of the deformation measured by plummet PL15 at different heights is consistent with GB-SAR

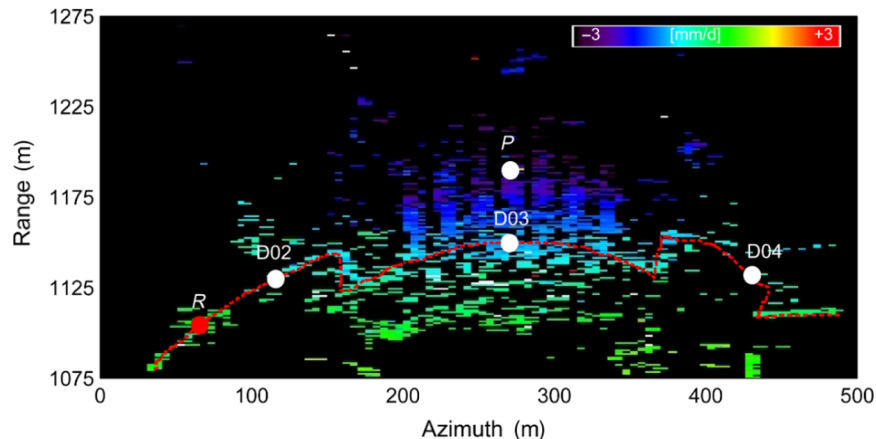


Fig. 8 Mean deformation velocity map. D02, D03, and D04 are points selected on the crest of the dam. R is the stable reference point. P is a point located in one of the orifices of the dam.

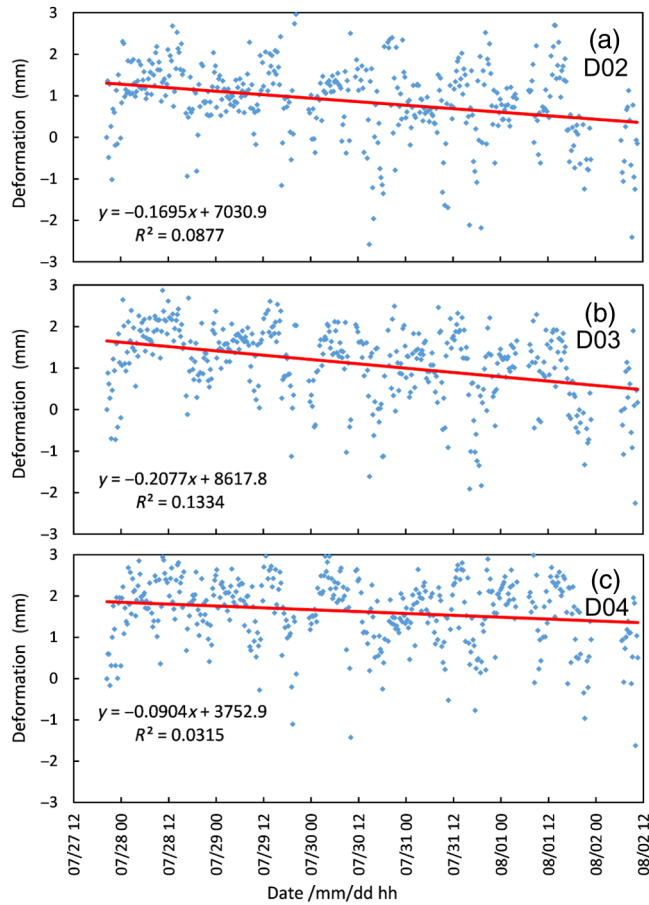


Fig. 9 Deformation time series of the points shown in Fig. 8. The red line indicates the calculated regression line. (a) Point D02, (b) point D03, and (C) point D04.

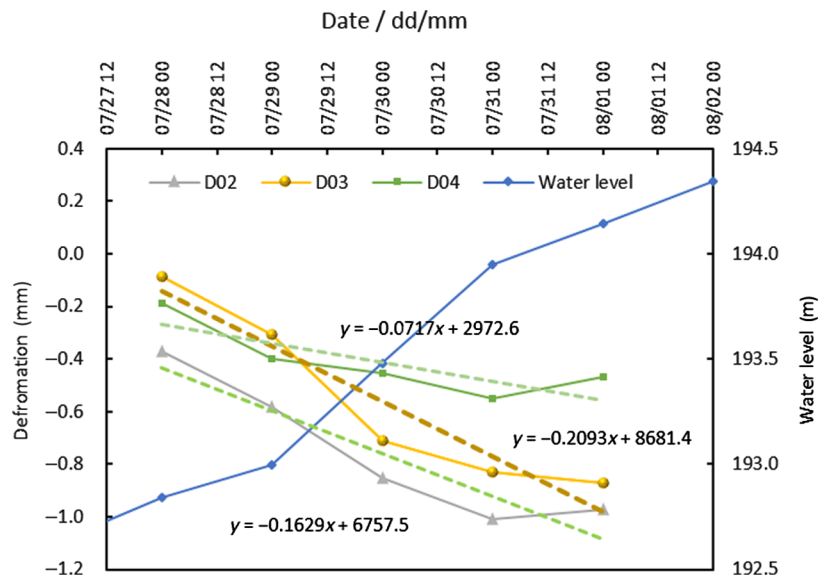


Fig. 10 Daily average deformation measured for points D02, D03, and D04 using the GB-SAR data. The dashed lines indicate the corresponding regression line. The reservoir water level is shown with a solid light blue line.

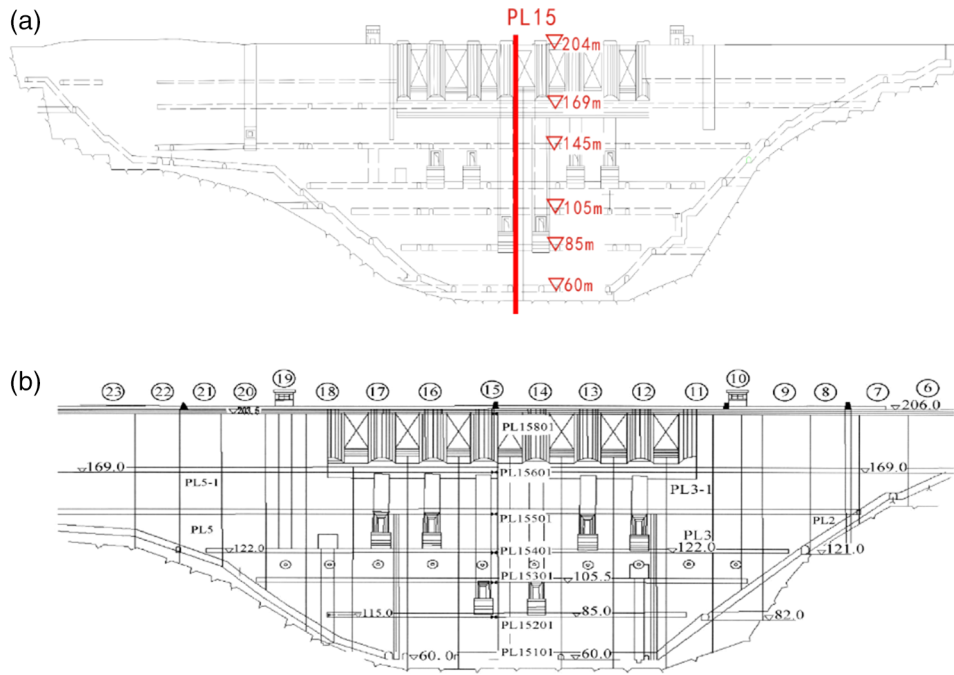


Fig. 11 (a) Vertical profile of the Geheyan Dam indicating the position of plummet PL15, depicted by a red line. The numbers indicate the measurement height. (b) Same view with detailed location of all the installed plummets.

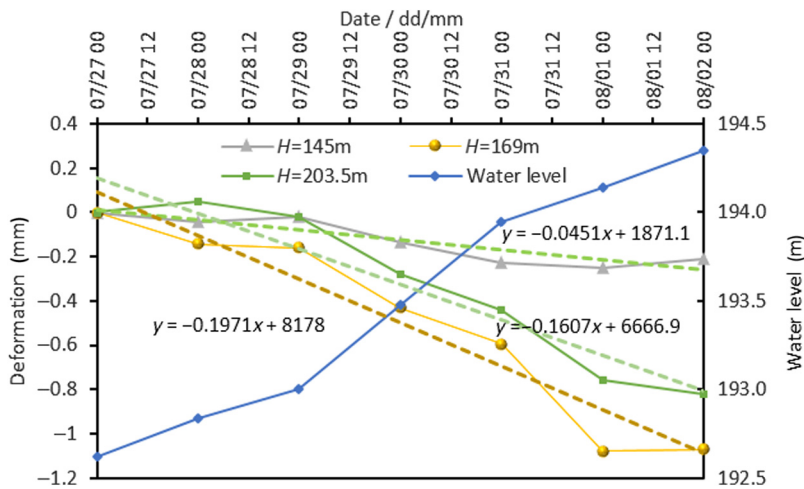


Fig. 12 Deformation showing movement of the dam toward the GB-SAR measured by plummet PL15 at different heights compared with the reservoir water level during the monitoring campaign.

measurements (Table 2, the GB-SAR pixels are selected in the dam center by scaling the height) and the deformation expected when the water reservoir changes. The upper part of the dam shows the highest deformation velocity, which decreases progressively toward the lower part.

It is reasonable that the deformation velocities measured at the dam increase with height. The results shown in Fig. 13 were filtered (moving average with a window size of 9). Time series obtained at the center of the crest of the dam and inside surface orifices are compared, and they indicate that the deformation measured inside and outside the dam at the same height differs. The main interpretation of these results can be summarized as follows. The deformation measured using GB-SAR at the crest of the dam shows good agreement with that measured by plummet PL15 (the purple triangles). Both filtered time series show a cycle of one day, where the

Table 2 Deformation rate at the center of the dam measured by PL15 and GB-SAR.

Point	PL15 (mm/d)	GB-SAR (mm/d)
PL15 at $H = 145$ m	-0.05	-0.08
PL15 at $H = 169$ m	-0.16	-0.18
PL15 at $H = 203$ m	-0.20	-0.21

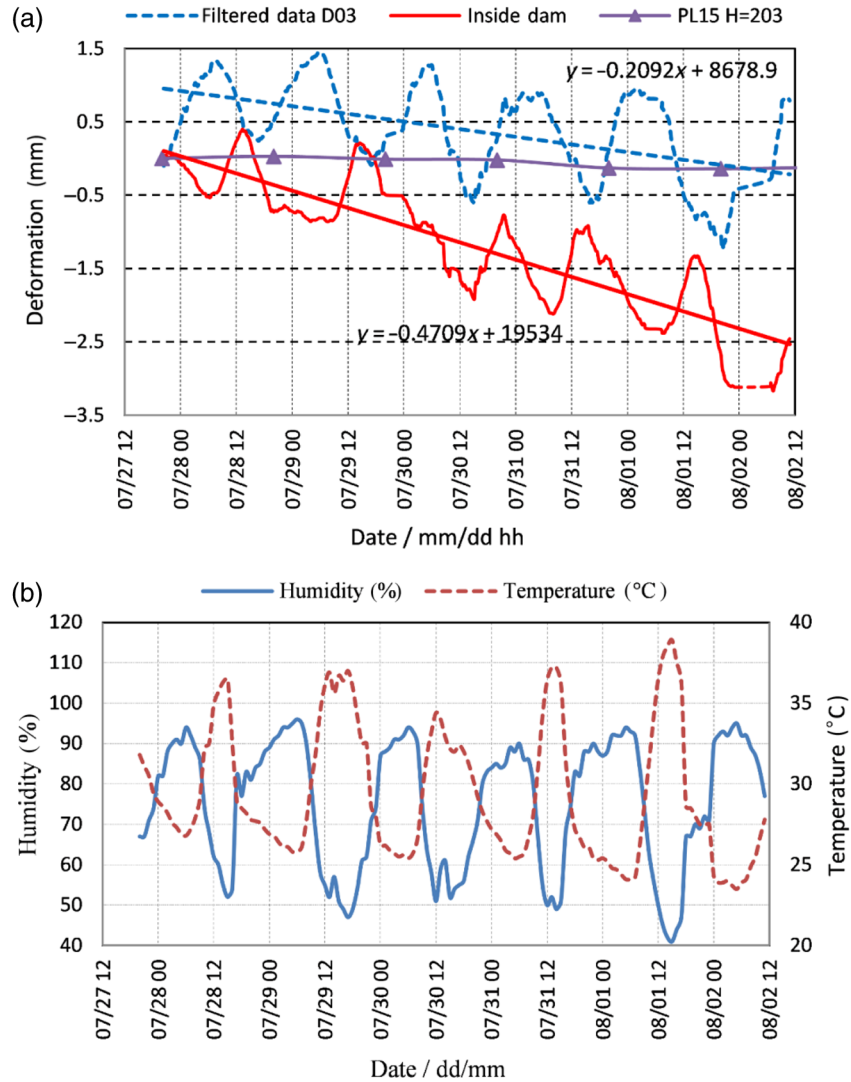


Fig. 13 (a) Deformation time series measured by the GB-SAR at the crest of the dam (D03) and inside one of the orifices (point P shown in Fig. 8). The blue dashed line is the deformation time series at point D03, before (oscillating line) and after filtering (straight line); the red line represents the deformation at point P , before (oscillating line) and after filtering (straight line); the purple line with triangles refers to the deformation measured by PL15 (at height 203 m). (b) Local air temperature (red dashed line) and relative humidity (blue) measured during the GB-SAR campaign.

amplitude ranges between 1 and 1.5 mm. The deformation velocity in the orifice (-0.47 mm/d) displays the same trend but it is more than twice that at the crest (-0.21 mm/d). Reasonable explanations for these results might be the following: (1) the temporal trend of deformation shows a one day periodic variation which demonstrates there is still residual deformation associated with environmental elements, residual APS, and the different thermal expansions of the

reference point and of the measured points between the reference point and the measured points are good explanation of the cyclic changes. However, with several days of continuous observations, the estimate of the velocity could be improved, (2) different amplitudes and opposite peaks and troughs may be caused by different atmospheric patterns inside and outside the dam. As stated in Ref. 14, at Ku band, 1% change of humidity can result in 2-mm radar LOS change in a target–sensor distance of 1000 m, hence, 20% humidity difference inside the orifice (40 m) causes 1.6-mm LOS distance change. In high humidity areas, especially in a mountainous area, it is difficult to completely remove the difference of APS inside and outside the structure of the dam, and (3) GB-SAR multireflections are present in the orifices, making the apparent distance sensor to target longer. The reflecting signals are also probably affected by the metal gates, which are influenced by water pressure. Consequently, the gates have a larger magnitude of deformation, as they are not only affected by the dam deformation but also by the distortion caused by the water pressure on the gates. For this reason, a correct interpretation of the GB-SAR data requires an accurate understanding of the amplitude image, a more challenging issue when measurements are taken from long distances, with low azimuth resolution and substantial atmospheric effects.

5 Conclusions

The results of a GB-SAR monitoring campaign carried out from more than 1.2 km far from and aimed at monitoring a large and geometrically complex dam, Geheyan, China, is discussed in this paper. More than 400 GB-SAR images acquired during ~5 days have been used for interferogram generation. Complex radar signals reflected from the dam have been carefully analyzed by considering the geometry of the sensor and the targets. A 2-D polynomial model has been used for APS estimation and correction. Mean deformation velocities at the main section of the dam have been estimated and compared with plummet measurements. The results show that the maximum deformation velocity estimated by SAR interferometry at the center of the crest of the dam is around -0.2 mm/d, in agreement with the measurements of plummets mounted in the dam. Meanwhile, the dam deformation time series are correlated with the reservoir water level during the monitoring campaign. The APS correction applied to interferometric data was mostly satisfactory, except in areas where the atmospheric humidity is very high, and the residual APS clearly shows a one-day periodicity, which does not jeopardize the estimation of deformation velocity over the entire duration of the campaign. The case at hand shows that, due to the large distance radar-dam and the size of the monitored structure, a careful interpretation of the SAR amplitude image is required to associate the deformation behavior of the backscattering inside the discontinuities present in the dam (i.e., the orifices) to avoid an overestimation of the deformation rate. These scatters display similar deformation characteristics as that of the dam front profile, but the deformation velocity can be twice that at the crest of the dam. This difference can be related to the radar signal propagation at the orifices, where the deformation of the metal gates is not only affected by the dam structure but also by the direct pressure of the water contained in the reservoir and the complex variation of the atmospheric parameters. The need to carefully analyze the occurrence of spurious phase shifts in the presence of metal structure and the side-lobes role in radar backscattering in complex GB-SAR scenario seems to agree with assessments of a recent paper.²³

Acknowledgments

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