

IMAGE ANALYSIS OF HYPERSPECTRAL DATA USING MATHEMATICAL MORPHOLOGY

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TUTORIAL WHISPERS 2014

24-27 June 2014, Lausanne, Switzerland



1 Introduction

2 Spatial information from MM

- Basic tools
- Remote sensing tools
- Advanced tools
- Extension to multivalued images

3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROIS-03

5 Conclusions

1 Introduction

2 Spatial information from MM

- Basic tools
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3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSI-03

5 Conclusions

History

- | | | |
|-------------|---|------------------------------|
| 2001 | M. Pesaresi & J.A. Benediktsson: | Morphological Profile |
| 2003 | J.A. Benediktsson, M. Pesaresi & K. Arnason: | Morphological Profile |
| 2005 | J.A. Benediktsson, J. A. Palmason & J. Sveinsson: | Extended MP |
| 2009 | M. Fauvel, J. Chanussot & J.A. Benediktsson: | Kernel PCA based EMP |
| 2010 | M. Dalla Mura, J.A. Benediktsson, Waske & L. Bruzzone: | Attribute Profile |
| 2011 | M. Dalla Mura, A. Villa, J.A. Benediktsson & L. Bruzzone: | ICA based AP |
| 2014 | WHISPERS Tutorial! | |

VHR Hyperspectral Images: Urban Area



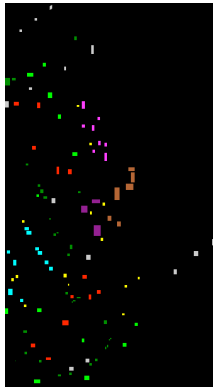
ROSIS: 1.5 m/pixel - 115 spectral channels - 430 nm, 860 nm.

- Spatial resolution: Lower than 2.5 meter by pixel
- Spectral resolution: More than 100 spectral channels (up to 4096!)

Classification



Original Data



Ground-truth

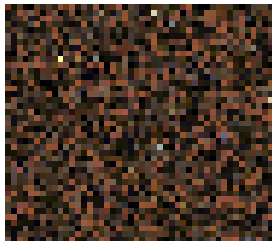


Thematic Map

Classification: A pattern recognition approach

1. Feature extraction: One vector of attributes extracted for every pixels
2. Pattern recognition algorithms: Support Vectors Machines ...

Why spatial information? 1/2

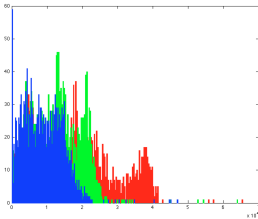
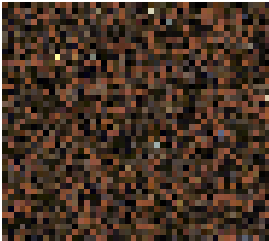


oooooooooooooooooooo

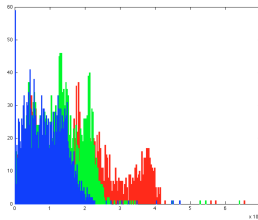
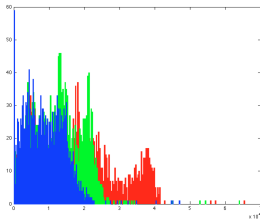
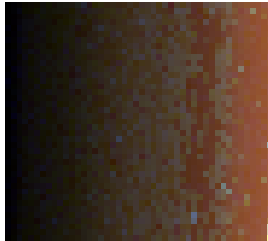
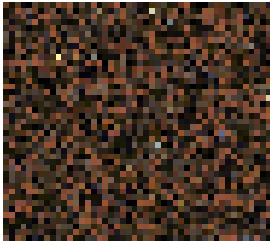
oooooo

oooo

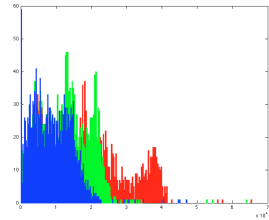
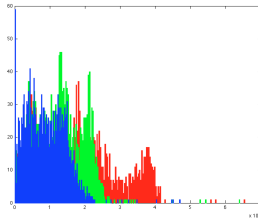
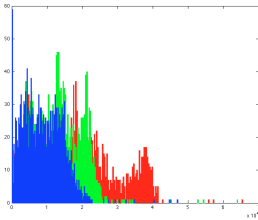
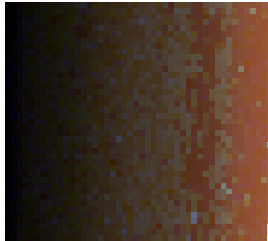
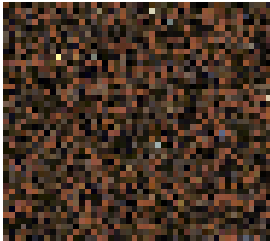
Why spatial information? 1/2



Why spatial information? 1/2



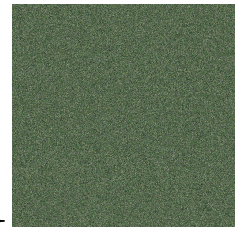
Why spatial information? 1/2



Why spatial information? 2/2



Random permutation
of the spatial position
of the pixels



Spectral classification

Same classification !!

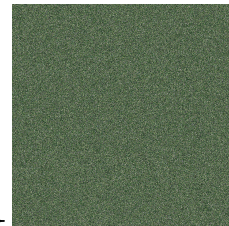
Spectral classification

Need to incorporate information from the spatial domain

Why spatial information? 2/2



Random permutation
of the spatial position
of the pixels



Spectral classification

Same classification !!

Spectral classification

Need to incorporate information from the spatial domain

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- Advanced tools
- Extension to multivalued images

3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSIS-03

5 Conclusions

1 Introduction

2 Spatial information from MM

- Basic tools
 - Remote sensing tools
 - Advanced tools
 - Extension to multivalued images

3 Classification

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- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSIS-03

5 Conclusions

Dilation and Erosion

Definition (Image)

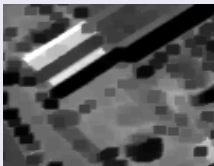
$$f : \mathcal{D}_f \subset \mathbb{Z}^d \rightarrow \{0, \dots, f_{\max}\}$$

$$f^c = f_{\max} - f$$



Definition (Erosion)

$$\epsilon_B(f) = \bigwedge_{b \in B} f_{-b}$$

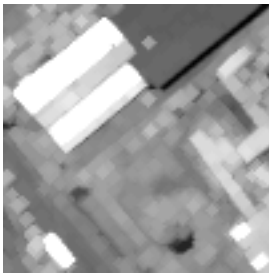


Definition (Dilation)

$$\delta_B(f) = \bigvee_{b \in B} f_{-b}$$



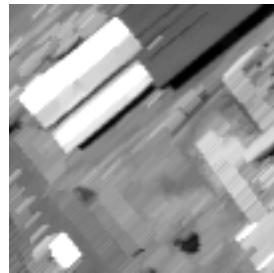
Effect of the structuring element B



0	0	1	0	0
0	1	1	1	0
1	1	1	1	1
0	1	1	1	0
0	0	1	0	0



1	1	1
1	1	1
1	1	1

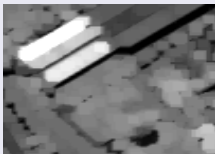


0	0	0	0	1
0	0	0	1	0
0	0	1	0	0
0	1	0	0	0
1	0	0	0	0

Opening and Closing

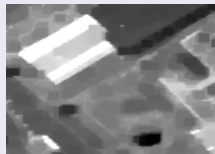
Definition (Opening)

$$\gamma_B(f) = \delta_B \circ \epsilon_B(f)$$



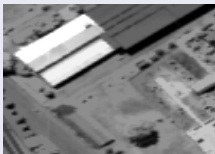
Definition (Closing)

$$\phi_B(f) = \epsilon_B \circ \delta_B(f)$$



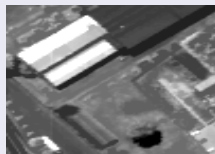
Definition (Opening by reconstruction)

$$\gamma_B^r(f) = \text{Rec}_f \circ \epsilon_B(f)$$



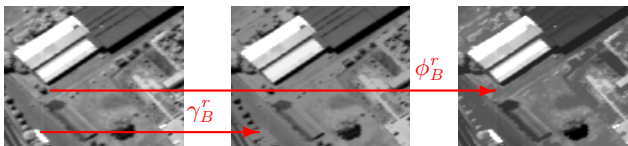
Definition (Closing by reconstruction)

$$\phi_B^r(f) = \text{Rec}_f^* \circ \delta_B(f)$$



Opening and Closing Profile

- For a given B , $\gamma_B^r(f)$ (resp. $\phi_B^r(f)$) indicates which clear (dark) objects fit B .



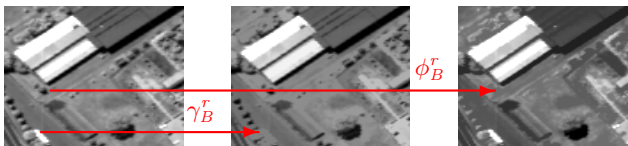
- Applying γ_{B_i} with a set of $\{B_i | B_i \subset B_{i+1}, i \in [1, \dots, n]\}$: **Opening Profile**
- Applying ϕ_{B_i} with a set of $\{B_i | B_i \subset B_{i+1}, i \in [1, \dots, n]\}$: **Closing Profile**

Definition (Granulometry)

A granulometry is a transformation having a size parameter n , and with the following properties: *Anti-extensivity*, *Increasingness* and *Absorption*.

Opening and Closing Profile

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2 Spatial information from MM

- Basic tools
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- Advanced tools
- Extension to multivalued images

3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSIS-03

5 Conclusions

Morphological Profile

Definition (Morphological profile)

The Morphological Profile of size n is a $(2n + 1)$ -dimensional vector such as:

$$\text{MP}(\mathbf{x}) = \left[\text{CP}_n(\mathbf{x}), f(\mathbf{x}), \text{OP}_n(\mathbf{x}) \right].$$



$\text{CP}(\mathbf{x}) \leftarrow \text{ } f(\mathbf{x}) \text{ } \rightarrow \text{OP}(\mathbf{x})$

For a given pixel \mathbf{x} , information include in the $\text{MP}(\mathbf{x})$ are:

- Contrast: Is the structure to which the pixel belongs to darker or lighter than his surrounding neighbors?
- Size: Is the structure to which the pixel belongs to small or big compared to B_i ?

Morphological Profile

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- Size: Is the structure to which the pixel belongs to small or big compared to B_i ?

Derivative of the MP

Definition (Derivative of the Morphological profile)

The Derivative of the Morphological Profile of size n is a $(2n)$ -dimensional vector such as:

$$\text{DMP}(\mathbf{x}) = \left[|\phi_n(\mathbf{x}) - \phi_{n-1}(\mathbf{x})|, \dots, |\gamma_{n-1}(\mathbf{x}) - \gamma_n(\mathbf{x})| \right].$$



1 Introduction

2 Spatial information from MM

- Basic tools
- Remote sensing tools
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- Extension to multivalued images

3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

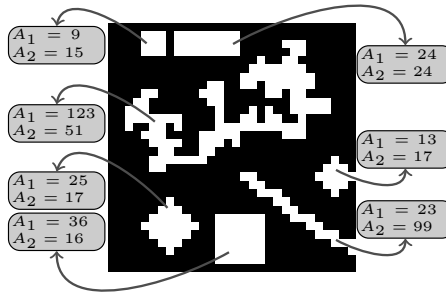
- Data
- Results-ROSIS-03

5 Conclusions

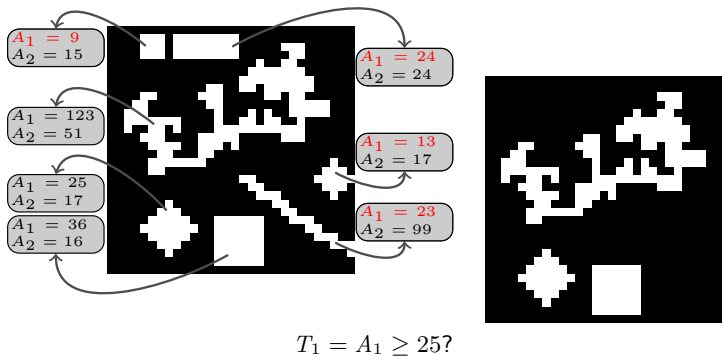
Attribute filters 1/3

- Objects are filtered according to a given attribute (no SE anymore):
 - Area
 - Perimeter
 - Standard deviation
 - Moment of inertia
 - ...
- Combination of attributes are possible !
- Filtering procedure: Attribute filters are based on the following operations:
 - Compute *attribute* for each connected component in the image
 - Keep the components that satisfy the *criterion*.

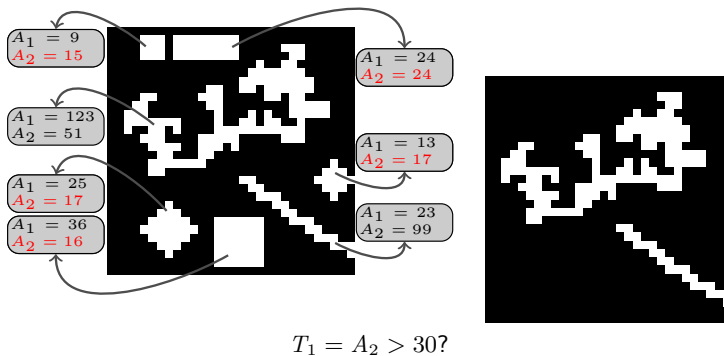
Attribute filters 2/3



Attribute filters 2/3



Attribute filters 2/3



Attribute filters 3/3



Panchromatic image (f)



Filter by rec. $f - \gamma_R^B(f)$ (B : disk radius 7 pixels)



Attribute filter $\gamma^T(f)$ with $T = (R > 0.3) \wedge (I < 0.5) \wedge (50 < A < 5000)$

Attribute filters 3/3



Panchromatic image (f)



Filter by rec. $f - \gamma_R^B(f)$ (B : disk radius 11 pixels)



Attribute filter $\gamma^T(f)$ with $T = (R > 0.3) \wedge (I < 0.5) \wedge (50 < A < 5000)$

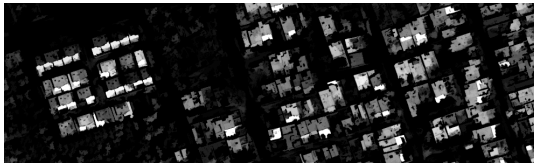
Attribute filters 3/3



Panchromatic image (f)



Filter by rec. $f - \gamma_R^B(f)$ (B : disk radius 15 pixels)



Attribute filter $\gamma^T(f)$ with $T = (R > 0.3) \wedge (I < 0.5) \wedge (50 < A < 5000)$

Attribute filters 3/3



Panchromatic image (f)



Filter by rec. $f - \gamma_R^B(f)$ (B : disk radius 19 pixels)



Attribute filter $\gamma^T(f)$ with $T = (R > 0.3) \wedge (I < 0.5) \wedge (50 < A < 5000)$

1 Introduction

2 Spatial information from MM

- Basic tools
- Remote sensing tools
- Advanced tools
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3 Classification

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4 Experiments

- Data
- Results-ROSIS-03

5 Conclusions

Ordering relation

- MM is based on inf and sup operators
- No unambiguous inf/sup for pixel/vector:

$$\begin{bmatrix} 1 \\ 5 \\ 2 \end{bmatrix} \stackrel{?}{\leq} \begin{bmatrix} 0 \\ 6 \\ 1 \end{bmatrix}$$

- Marginal ordering \Rightarrow by band filtering
- Reduced ordering $\Rightarrow h : \mathbb{R}^d \rightarrow \mathbb{R}$

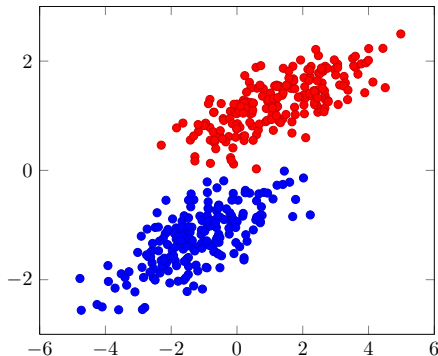
$$\mathbf{x} \mapsto h(x)$$

Principal Component Analysis

- $h(\mathbf{x}) = \langle \mathbf{x}, \mathbf{v}_m \rangle$ such as \mathbf{v}_m is the m^{th} principal component of the spectral data
- \mathbf{v}_m is computed as the eigenvector corresponding to the m^{th} largest eigenvalue of the covariance matrix of the spectral data

$$\lambda_m \mathbf{v}_m = \Sigma \mathbf{v}_m$$

- The number of retained PCs correspond to a certain percentage of the cumulative variance

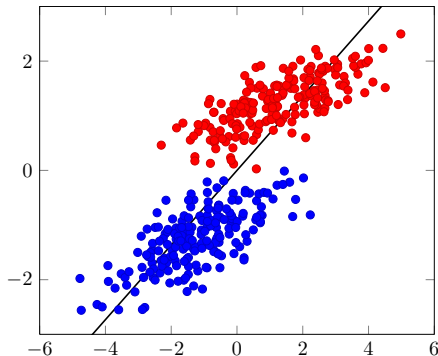


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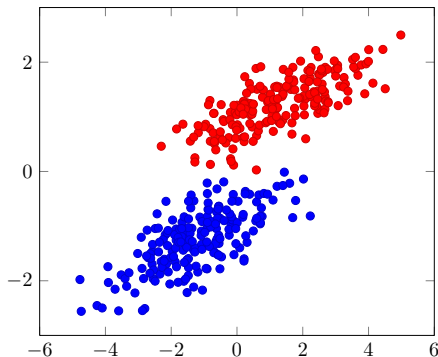


Linear Discriminant Analysis

- $h(\mathbf{x}) = \langle \mathbf{x}, \mathbf{v}_l \rangle$ such as \mathbf{v}_l maximizes the separability of the classes
- \mathbf{v}_l is computed by solving the generalized eigenvalue problem

$$\lambda_l \mathbf{S}_w \mathbf{v}_l = \mathbf{S}_b \mathbf{v}_l$$

where $\mathbf{S}_w = \sum \Sigma_c$ and $\mathbf{S}_b = \sum (\mu_c - \mu)(\mu_c - \mu)^T$

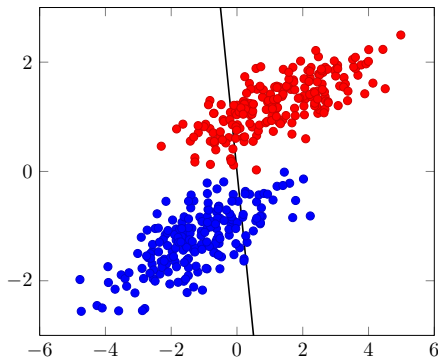


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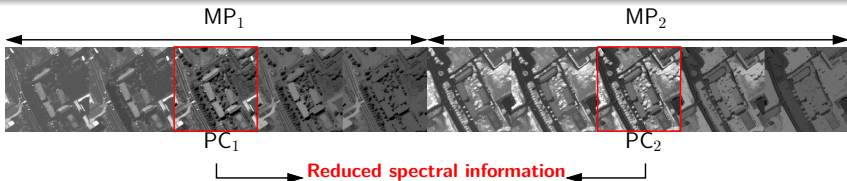


Extended Morphological Profile

Definition (Extended Morphological Profile - EMP)

The EMP of size $n \times p$ is a $(2n + 1)p$ -dimensional vector made of the MP build with the p first principal components:

$$\text{EMP}(\mathbf{x}) = [\text{MP}_1(\mathbf{x}), \dots, \text{MP}_p(\mathbf{x})].$$



- Fusion of morphological and spectral features

1 Introduction

2 Spatial information from MM

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- Advanced tools
- Extension to multivalued images

3 Classification

- Support Vectors Machines
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4 Experiments

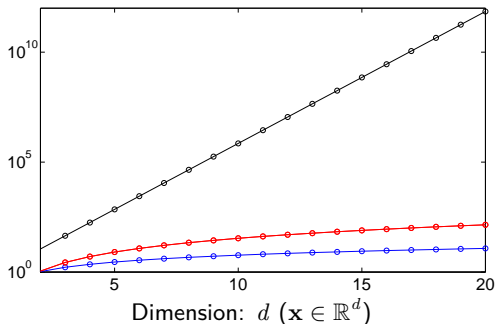
- Data
- Results-ROSI-03

5 Conclusions

High dimensional data

- Number of samples for *accurate* classification:

Linear	\gg	d
Quadratic	\gg	d^2
Non-parametric	\gg	$\exp(d)$



- Hyperspectral data: $d > 100$

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- Advanced tools
- Extension to multivalued images

3 Classification

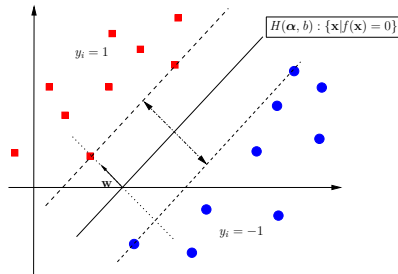
- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSI-03

5 Conclusions

Principle



■ Training set: $\mathcal{S} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_\ell, y_\ell)\} \in \mathbb{R}^n \times \{-1; 1\}$

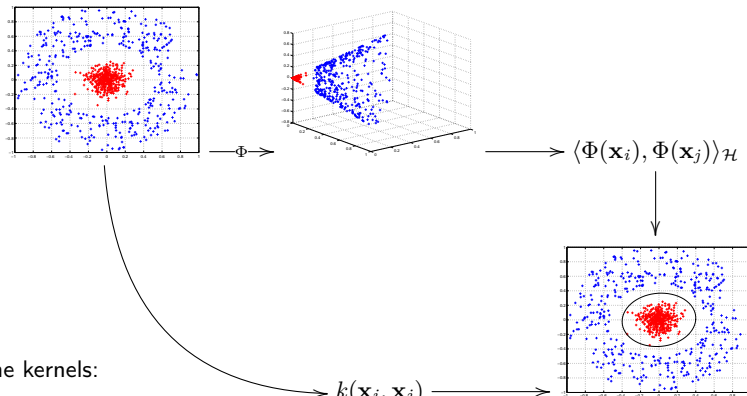
■ Learn a function $f(\mathbf{z}) = \text{sgn} \left(\sum_{i=1}^{\ell} \alpha_i k(\mathbf{z}, \mathbf{x}_i) + b \right)$

■ Solve:

$$\begin{aligned} \max_{\alpha} g(\alpha) &= \sum_{i=1}^{\ell} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{\ell} \alpha_i \alpha_j y_i y_j k(\mathbf{x}_i, \mathbf{x}_j) \\ \text{subject to} & \quad 0 \leq \alpha_i \leq C \text{ and } \sum_{i=1}^{\ell} \alpha_i y_i = 0 \end{aligned}$$

Kernel trick

- Kernel function k : semi-definite positive $k(\mathbf{x}_i, \mathbf{x}_j) = \langle \Phi(\mathbf{x}_i), \Phi(\mathbf{x}_j) \rangle_{\mathcal{H}}$

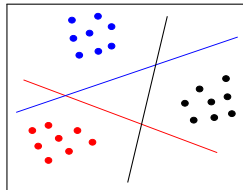


- Some kernels:

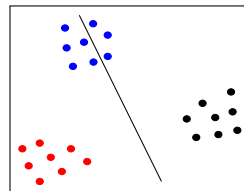
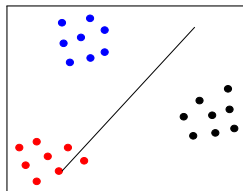
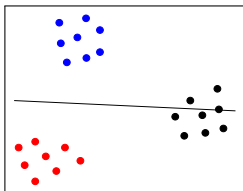
- ★ Linear kernel: $k(\mathbf{x}_i, \mathbf{x}_j) = \langle \mathbf{x}_i, \mathbf{x}_j \rangle_{\mathbb{R}^n}$
- ★ Polynomial kernel: $k(\mathbf{x}_i, \mathbf{x}_j) = (\langle \mathbf{x}_i, \mathbf{x}_j \rangle_{\mathbb{R}^n} + q)^p$
- ★ Gaussian kernel: $k(\mathbf{x}_i, \mathbf{x}_j) = \exp \left(- \frac{\|\mathbf{x}_i - \mathbf{x}_j\|_{\mathbb{R}^n}^2}{2\sigma^2} \right)$

Multiclass problem

■ One versus All: m binary classifiers



■ One versus One: $m(m-1)/2$ classifiers



1 Introduction

2 Spatial information from MM

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- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSIS-03

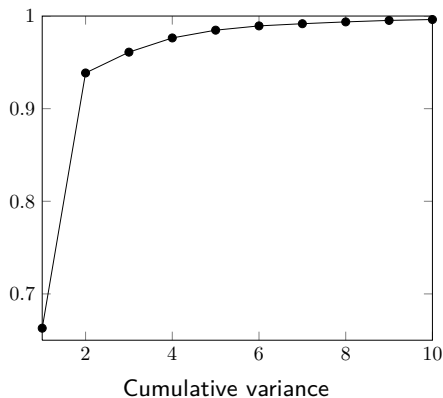
5 Conclusions

EMP

■ Inputs: $\text{EMP}(\mathbf{x})$, $\dim(\text{EMP}(\mathbf{x})) = (2n + 1)p$

■ Parameters:

- ★ Numbers of PCs $\rightarrow p$
- ★ Size of MP $\rightarrow n$
- ★ Hyperparameters



1 Introduction

2 Spatial information from MM

- Basic tools
- Remote sensing tools
- Advanced tools
- Extension to multivalued images

3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSI-03

5 Conclusions

1 Introduction

2 Spatial information from MM

- Basic tools
- Remote sensing tools
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- Extension to multivalued images

3 Classification

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4 Experiments

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- Results-ROSI-03

5 Conclusions

ROSIS-03

University Area, Pavia - Italy

- Airbone
- $[H \ W]=[610 \ 340]$
- 103 channels
- 1.3 m/pixel
- 43 923 referenced samples
- 9 classes : Asphalts, Meadow, Gravel, Tree, Metal Sheet, Bare Soil, Bitumen, Brick and Shadow.



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2 Spatial information from MM

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- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSI-03

5 Conclusions

Quantitative analysis

Let's generate some results!

1 Introduction

2 Spatial information from MM

- Basic tools
- Remote sensing tools
- Advanced tools
- Extension to multivalued images

3 Classification

- Support Vectors Machines
- Classification of spectral-spatial features

4 Experiments

- Data
- Results-ROSI-03

5 Conclusions

Discussion

■ Mathematical Morphology:

- ★ Morphological operators extract relevant spatial features for classification
- ★ Connectivity is a key property
- ★ Extended profiles should be constructed with advance FE algorithms
- ★ The use of attributes profile allows the extraction of relevant spatial features

■ SVM:

- ★ Ability to include additional spatial information
- ★ Robust to the dimensionality

■ Classification:

- ★ Analyst intervention is minimized
- ★ Classification accuracy
- ★ Works with other geographical area

Perspectives

- Supervised or un-supervised FE?
- Best attribute?
- Time processing?

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IMAGE ANALYSIS OF HYPERSPECTRAL DATA USING MATHEMATICAL MORPHOLOGY

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TUTORIAL WHISPERS 2014

24-27 June 2014, Lausanne, Switzerland