

MW2 Model

System

Box

- ▶ Orthorombic
- ▶ Dimensions are constants
- ▶ 2D or 3D periodic boundary condition

Species

- ▶ Name
- ▶ Count
- ▶ Mass
- ▶ Charge
 - ▶ point: $\rho_i(r) \equiv q_i \delta(r - r_i)$
 - ▶ gaussian: $\rho_i(r) \equiv Q_i \left(\frac{\eta^2}{\pi} \right) e^{-\eta^2 |r - r_i|^2}$
- ▶ Mobility
 - ▶ mobile: $x, y, z, v_x, v_y, v_z, f_x, f_y, f_z$
 - ▶ fixed: x, y, z

Molecules

- ▶ Name
- ▶ Sites
- ▶ Constraints
 - ▶ bond length constraints (Rattle)
 - ▶ linear molecules
- ▶ Intramolecular harmonic potentials
 - ▶ bond: $V(r_{ij}) = k_0(|r_{ij}| - r_0)^2$
 - ▶ angle: $V(r_i, r_j, r_k) = k_0(|\theta_{ijk}| - \theta_0)^2$

Electrodes

- ▶ Name
- ▶ Sites
- ▶ Potential
- ▶ Minimize energy to compute charges on electrode sites
 - ▶ conjugate gradient algorithm (tolerance, maximum iteration count)
 - ▶ inverse matrix (to be implemented)

Temperature control

- ▶ chained Nose-Hoover thermostat
- ▶ velocities periodic rescaling

Electrostatic Interactions

Coulomb potential

$$V(r_{ij}) = \int_{\mathbb{R}^3} dr' \int_{\mathbb{R}^3} dr'' \frac{\rho_i(r') \rho_j(r'')}{|r_{ij} + r'' - r'|}$$

- ▶ Long range interaction \rightarrow Ewald summation
- ▶ Cut-off for real space sum: r_{cut}
- ▶ Tolerance on real space term minimum magnitude: ϵ_{real}
- ▶ Tolerance on reciprocal space term minimum magnitude: ϵ_{recip}

Lennard-Jones potential

$$V_{ij}(r_{ij}) = 4\epsilon[(\sigma/r_{ij})^{12} - (\sigma/r_{ij})^6]$$

- ▶ Cut-off for all pairs: $V(r > r_c) = 0$
- ▶ Energy is shifted: $\tilde{V}_{ij}(r_{ij}) = V_{ij}(r_{ij}) - V_{ij}(r_c)$
- ▶ Force is not shifted: $F_{ij}(r_{ij}) = -\nabla V_{ij}(r_{ij})$

Born-Mayer potential with Fumi-Tosi parametrisation

$$V(r_{ij}) = Be^{-\eta r_{ij}} - \frac{C}{r_{ij}^6} \left[1 - \sum_{k=0}^6 \frac{d_{dd}^k r_{ij}^k}{k!} e^{-d_{dd} r_{ij}} \right] - \frac{D}{r_{ij}^8} \left[1 - \sum_{l=0}^8 \frac{d_{dq}^l r_{ij}^l}{l!} * e^{-d_{dq} r_{ij}} \right]$$

- Cut-off for all pairs: $V(r > r_c) = 0$

Algorithms

Minimum image distance

```
dx = x_2 - x_1  
scale = floor(dx / a + 0.5_wp)  
dx = dx - a*real(scale,wp)
```

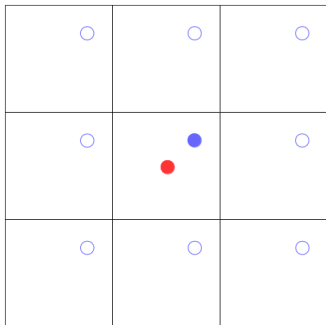


Figure 1: minimum image distance

NVE Time Integration

- ▶ Velocity - Verlet algorithm original formulation
 - ▶ $r(t + dt) = -r(t - dt) + 2r(t) + dt^2 a(t)$
 - ▶ $v(t) = (r(t + dt) - r(t - dt))/2dt$
- ▶ Actual implementation
 - ▶ $v(t + dt/2) = v(t) + \frac{1}{2}dt a(t)$
 - ▶ $r(t + dt) = r(t) + dt v(t + dt/2) + \frac{1}{2}dt^2 a(t)$
 - ▶ $a(t + dt) = m^{-1}f(r(t + dt))$
 - ▶ $v(t + dt) = v(t + dt/2) + \frac{1}{2}dt a(t + dt)$
- ▶ 2nd order centered finite difference method $O(dt^2)$
- ▶ Symmetric, reversible in time and symplectic (energy conservation)

Computer “Experiments” on Classical Fluids. I. Thermodynamical Properties of Lennard-Jones Molecules, Loup Verlet, Phys. Rev. 159, 98, 5 July 1967

NVT Time Integration

- ▶ Chained Nosé-Hoover Thermostat

- ▶ $\dot{q}_i = \frac{p_i}{m_i}$

- ▶ $\dot{p}_i = -\frac{\partial V(q)}{\partial q_i} - p_i \frac{p_{\eta_1}}{Q_1}$

- ▶ $\dot{\eta}_i = \frac{p_{\eta_i}}{Q_i}$

- ▶ $\dot{p}_{\eta_1} = \left[\sum_{i=1}^N \frac{p_i^2}{m_i} - NkT \right] - p_{\eta_1} \frac{p_{\eta_2}}{Q_2}$

- ▶ $\dot{p}_{\eta_j} = \left[\frac{p_{\eta_{j-1}}^2}{Q_{j-1}} - kT \right] - p_{\eta_j} \frac{p_{\eta_{j+1}}}{Q_{j+1}}$

- ▶ $\dot{p}_{\eta_M} = \left[\frac{p_{\eta_{M-1}}^2}{Q_{M-1}} - kT \right]$

- ▶ Conserved quantity $H(p, q, \eta, p_\eta) =$

$$V(q) + \sum_{i=1}^N \frac{p_i^2}{2m_i} + \sum_{i=1}^M \frac{p_{\eta_i}^2}{2Q_i} + NkT\eta_1 + \sum_{i=2}^M kT\eta_i$$

- ▶ $Q_1 = NkT/\omega^2$ and $Q_j = kT/\omega^2$ with ω the average “frequency” of the thermostats.

Nosé-Hoover chains: The canonical ensemble via continuous dynamic, G.J. Martyna, M.L. Klein., M. Tuckermann, J. Chem. Phys., Vol. 97, No. 4, 15 August 1992

NVT Time Integration - Implementation

- ▶ $v(t + dt/2) = v(t) + \frac{1}{2}dt(a(t) - v(t) * v_{\eta_1}(t))$
- ▶ $r(t + dt) = r(t) + dt v(t + dt/2) + \frac{1}{2}dt^2 a(t)$
- ▶ $a(t + dt) = m^{-1}f(r(t + dt))$
- ▶ $\eta_i(t + dt) = \eta_i(t) + dt * v_{\eta_i}(t) + \frac{dt^2}{2}a_{\eta_i}(t)$
- ▶ $\tilde{v}^{(0)} = v(t + dt/2) + \frac{1}{2}dt a(t + dt)$
- ▶ $\tilde{v}_{\eta_i}^{(0)} = v_{\eta_i}(t - dt) + 2dt a_{\eta_i}(t)$
- ▶ do k = 1, max_iteration
 - ▶ $\tilde{v}^{(k)} = \frac{1}{1 + \frac{dt}{2} \tilde{v}_{\eta_1}^{(k-1)}} \tilde{v}^{(k-1)}$
 - ▶ $\tilde{a}_{\eta_1}^{(k)} = \frac{1}{Q_1}(\sum_{i=1}^N m_i |\tilde{v}_i^{(k)}|^2 - NkT) - \tilde{v}_{\eta_1}^{(k-1)} * \tilde{v}_{\eta_2}^{(k-1)}$
 - ▶ $\tilde{v}_{\eta_1}^{(k)} = v_{\eta_1}(t) + \frac{dt}{2}(a_{\eta_1}(t) + \tilde{a}_{\eta_1}^{(k)})$
 - ▶ $\tilde{a}_{\eta_i}^{(k)} = \frac{1}{Q_i}(Q_{i-1} \tilde{v}_{\eta_{i-1}}^{(k)} \tilde{v}_{\eta_{i-1}}^{(k)} - kT) - \tilde{v}_{\eta_i}^{(k-1)} \tilde{v}_{\eta_{i+1}}^{(k-1)}$
 - ▶ $\tilde{v}_{\eta_i}^{(k)} = v_{\eta_i}(t) + \frac{dt}{2}(a_{\eta_i}(t) + \tilde{a}_{\eta_i}^{(k)})$
 - ▶ if $(\sum_{i=1}^N m_i |\tilde{v}_i^{(k)} - \tilde{v}_i^{(k-1)}|^2 \leq NkT\epsilon)$ EXIT
- ▶ $v(t + dt) = \tilde{v}^{(k)}$
- ▶ $v_{\eta_i}(t + dt) = \tilde{v}_{\eta_i}^{(k)}$
- ▶ $a_{\eta_i}(t + dt) = \tilde{a}_{\eta_i}^{(k)}$

Rattle

- ▶ force associated with intramolecular constraints: $g(r(t), v(t))$
- ▶ dynamics with constraints: $a(t) = f(r(t)) + g(r(t), v(t))$
- ▶ time integration:
 - ▶ $v(t + dt/2) = v(t) + \frac{1}{2}dt(a(t) + \tilde{g}_r(t))$
 - ▶ $r(t + dt) = r(t) + dt v(t + dt/2) + \frac{1}{2}dt^2 a(t)$
 - ▶ $v(t + dt) = v(t + dt/2) + \frac{1}{2}dt(a(t + dt) + \tilde{g}_v(t))$
- ▶ $\tilde{g}_r(t)$ and $\tilde{g}_v(t)$ are approximation to $g(r(t), v(t))$ such that $r(t + dt)$ and $v(t + dt)$ satisfy the constraints
 - ▶ $|r_j(t) - r_i(t)|^2 - d_{ij}^2 = 0$
 - ▶ $|v_j(t) - v_i(t)| \cdot |r_j(t) - r_i(t)| = 0$

Rattle: A “Velocity” version of the Shake Algorithm for Molecular Dynamics Calculations, H.C. Andersen, J. Comp. Phys., Vol. 52, 24-34 (1983)

Rattle - Implementation 1st part

Evaluate $\tilde{g}_r(t)$ for each molecule independently

- ▶ $\tilde{v}^{(0)} = v(t) + \frac{1}{2}dt \ a(t)$
- ▶ $\tilde{r}^{(0)} = r(t) + dt \ v^{(0)} + \frac{1}{2}dt^2 \ a(t)$
- ▶ do k = 1, max_iter
 - ▶ do c = 1, num_constraints
 - ▶ if (all constraint are satisfied) exit iteration loop
 - ▶ if $(|\tilde{r}_{ij}^{(k-1)}|^2 - d_{ij}^2 < \epsilon)$ cycle
 - ▶
$$g_r = \frac{|\tilde{r}_{ij}^{(k-1)}|^2 - d_{ij}^2}{2dt(r_{ij}(t) \cdot \tilde{r}_{ij}^{(k-1)})(m_i^{-1} + m_j^{-1})}$$
 - ▶ $\tilde{r}_i^{(k)} = \tilde{r}_i^{(k-1)} + dt g_r m_i^{-1} r_{ij}(t)$
 - ▶ $\tilde{v}_i^{(k)} = \tilde{v}_i^{(k-1)} + g_r m_i^{-1} r_{ij}(t)$
 - ▶ $\tilde{r}_j^{(k)} = \tilde{r}_j^{(k-1)} - dt g_r m_j^{-1} r_{ij}(t)$
 - ▶ $\tilde{v}_j^{(k)} = \tilde{v}_j^{(k-1)} - g_r m_j^{-1} r_{ij}(t)$
 - ▶ end do
- ▶ end do
- ▶ $r(t + dt) = \tilde{r}^{(k)}$
- ▶ $v(t + dt/2) = \tilde{v}^{(k)}$

Rattle - Implementation 2nd part

Evaluate $\tilde{g}_v(t)$ for each molecule independently

- ▶ $\tilde{v}^{(0)} = v(t + dt/2) + \frac{1}{2}dt \ a(t + dt)$
- ▶ do k = 1, max_iter
 - ▶ do c = 1, num_constraints
 - ▶ if (all constraint are satisfied) exit iteration loop
 - ▶ if $(r_{ij} \cdot \tilde{v}_{ij}^{(k-1)} < \epsilon)$ cycle
 - ▶
$$g_v = \frac{r_{ij} \cdot \tilde{v}_{ij}^{(k-1)}}{|r_{ij}|^2 * (m_i^{-1} + m_j^{-1})}$$
 - ▶ $\tilde{v}_i^{(k)} = \tilde{v}_i^{(k-1)} + g_v m_i^{-1} r_{ij}(t + dt)$
 - ▶ $\tilde{v}_j^{(k)} = \tilde{v}_j^{(k-1)} - g_v m_j^{-1} r_{ij}(t + dt)$
 - ▶ end do
- ▶ end do
- ▶ $v(t + dt) = \tilde{v}^{(k)}$

Ewald summation - Definitions

- ▶ point charge distribution: $\rho_i(r) \equiv q_i \delta(r - r_i)$
- ▶ gaussian charge distribution: $\rho_i(r) \equiv Q_i \left(\frac{\eta^2}{\pi} \right) e^{-\eta^2 |r - r_i|^2}$
- ▶ l_x, l_y, l_z : box length dimension
- ▶ r_c : cut-off radius for real space interaction
- ▶ ϵ_{real} : tolerance parameter for real space sum convergence
- ▶ ϵ_{recip} : tolerance parameter for reciprocal space sum convergence
- ▶ α : Ewald gaussian smearing width (do not confuse with η !)
 - ▶ $\alpha = \frac{\sqrt{(-\log(\epsilon_{\text{real}} * r_c))}}{r_c}$
- ▶ $\vec{k} = (\frac{2\pi k_x}{a}, \frac{2\pi k_y}{b}, \frac{2\pi k_z}{c})$: reciprocal space vector
- ▶ k_c : cut-off radius for reciprocal space vector
 - ▶ $k_c = \sqrt{(-\log(\epsilon_{\text{recip}}))} 4\alpha^2$
 - ▶ $k[\text{xyz}]_{\text{max}} = \text{floor}(k_c * l[\text{xyz}] / (2\pi))$

Ewald summation - Point charge distribution

► 3D PBC

- $$U_{sr} = \frac{1}{2} \sum_{i,j} q_i q_j \sum'_{\vec{n}} \frac{\text{erfc}(\alpha |\vec{r}_{ij} + \vec{n}|)}{|\vec{r}_{ij} + \vec{n}|}$$
- $$U_{lr} = \frac{1}{ab} \sum_{i,j} q_i q_j \sum_{\vec{k} \neq \vec{0}} \frac{\cos(\vec{k} \cdot \vec{r}_{ij})}{|\vec{k}|^2} e^{-\frac{|\vec{k}|^2}{4\alpha^2}}$$
- $$U_{self} = -\frac{\alpha}{\sqrt{\pi}} \sum_i q_i^2$$

► 2D PBC

- $$U_{sr} = \frac{1}{2} \sum_{i,j} q_i q_j \sum'_{\vec{n}} \frac{\text{erfc}(\alpha |\vec{r}_{ij} + \vec{n}|)}{|\vec{r}_{ij} + \vec{n}|}$$
- $$U_{lr} = \frac{1}{ab} \sum_{i,j} q_i q_j \sum_{\vec{k} \neq \vec{0}} \int_{-\infty}^{\infty} du \frac{\cos(\vec{k} \cdot \vec{\xi}_{ij} + u z_{ij})}{|\vec{k}|^2 + u^2} e^{-\frac{|\vec{k}|^2 + u^2}{4\alpha^2}}$$
- $$U_{k=0} = -\frac{\sqrt{\pi}}{ab} \sum_{i,j} q_i q_j \left(\frac{e^{-\frac{z_{ij}^2 \alpha^2}{2}}}{\alpha} + \sqrt{\pi} |z_{ij}| \text{erf}(\alpha |z_{ij}|) \right)$$
- $$U_{self} = -\frac{\alpha}{\sqrt{\pi}} \sum_i q_i^2$$

Ewald summation - Gaussian charge distribution

► 3D PBC

- $$U_{sr} = \frac{1}{2} \sum_{i,j} Q_i Q_j \sum'_{\vec{n}} \frac{(\text{erfc}(\alpha |\vec{r}_{ij} + \vec{n}|) - \text{erfc}(\eta_{ij} |\vec{r}_{ij} + \vec{n}|))}{|\vec{r}_{ij} + \vec{n}|}$$
- $$U_{lr} = \frac{1}{ab} \sum_{i,j} Q_i Q_j \sum_{\vec{k} \neq \vec{0}} \frac{\cos(\vec{k} \cdot \vec{r}_{ij})}{|\vec{k}|^2} e^{-\frac{|\vec{k}|^2}{4\alpha^2}}$$
- $$U_{\text{self}} = \frac{1}{\sqrt{\pi}} \sum_i Q_i^2 \left(\frac{\eta_i}{\sqrt{2}} - \alpha \right)$$

► 2D PBC

- $$U_{sr} = \frac{1}{2} \sum_{i,j} Q_i Q_j \sum'_{\vec{n}} \frac{(\text{erfc}(\alpha |\vec{r}_{ij} + \vec{n}|) - \text{erfc}(\eta_{ij} |\vec{r}_{ij} + \vec{n}|))}{|\vec{r}_{ij} + \vec{n}|}$$
- $$U_{lr} = \frac{1}{ab} \sum_{i,j} Q_i Q_j \sum_{\vec{k} \neq \vec{0}} \int_{-\infty}^{\infty} du \frac{\cos(\vec{k} \cdot \vec{\xi}_{ij} + u z_{ij})}{|\vec{k}|^2 + u^2} e^{-\frac{|\vec{k}|^2 + u^2}{4\alpha^2}}$$
- $$U_{k=0} = -\frac{\sqrt{\pi}}{ab} \sum_{i,j} Q_i Q_j \left(\frac{e^{-z_{ij}^2 \alpha^2}}{\alpha} + \sqrt{\pi} |z_{ij}| \text{erf}(\alpha |z_{ij}|) \right)$$
- $$U_{\text{self}} = \frac{1}{\sqrt{\pi}} \sum_i Q_i^2 \left(\frac{\eta_i}{\sqrt{2}} - \alpha \right)$$

Ewald summation - Mixed system

- ▶ 3D PBC

- ▶
$$U_{sr} = \sum_{i,j} q_i Q_j \sum_{\vec{n}} \frac{(\operatorname{erfc}(\alpha|\vec{r}_{ij} + \vec{n}|) - \operatorname{erfc}(\eta_j|\vec{r}_{ij} + \vec{n}|))}{|\vec{r}_{ij} + \vec{n}|}$$

- ▶
$$U_{lr} = \frac{2}{ab} \sum_{i,j} q_i Q_j \sum_{\vec{k} \neq \vec{0}} \frac{\cos(\vec{k} \cdot \vec{r}_{ij})}{|\vec{k}|^2} e^{-\frac{|\vec{k}|^2}{4\alpha^2}}$$

- ▶ 2D PBC

- ▶
$$U_{sr} = \sum_{i,j} q_i Q_j \sum_{\vec{n}} \frac{(\operatorname{erfc}(\alpha|\vec{r}_{ij} + \vec{n}|) - \operatorname{erfc}(\eta_j|\vec{r}_{ij} + \vec{n}|))}{|\vec{r}_{ij} + \vec{n}|}$$

- ▶
$$U_{lr} = \frac{2}{ab} \sum_{i,j} q_i Q_j \sum_{\vec{k} \neq \vec{0}} \int_{-\infty}^{\infty} du \frac{\cos(\vec{k} \cdot \vec{r}_{ij} + uz_{ij})}{|\vec{k}|^2 + u^2} e^{-\frac{|\vec{k}|^2 + u^2}{4\alpha^2}}$$

- ▶
$$U_{k=0} = -\frac{2\sqrt{\pi}}{ab} \sum_{i,j} q_i Q_j \left(\frac{e^{-z_{ij}^2 \alpha^2}}{\alpha} + \sqrt{\pi} |z_{ij}| \operatorname{erf}(\alpha |z_{ij}|) \right)$$

Constant potential energy minimization

- ▶ Equipotential constraint: $\frac{\partial U_c}{\partial Q_{ie}} = V_e$
- ▶ $U_T = U - \sum_{e=1}^{N_{\text{elec}}} \sum_{i=1}^{N_e} V_e Q_{ie} \Rightarrow \frac{\partial U_T}{\partial Q_{ie}} = 0$
- ▶ $U_T = \frac{1}{2} Q^T A Q - Q^T b + c$
 - ▶ $\frac{1}{2} Q^T A Q = U_{c_{gg}}$
 - ▶ $Q^T b = Q^T V - U_{c_{pg}}$
 - ▶ $c = U_{c_{pp}} + \text{other interactions}$
- ▶ Solve $AQ = b$
 - ▶ matrix inversion: compute coefficient of A^{-1} (not yet implemented)
 - ▶ iterative algorithm: Conjugate Gradient

Put it all together

- ▶ $t = 0$
- ▶ initialize system (runtime.inpt)
- ▶ initialize position (data.inpt)
- ▶ initialize velocity (data.inpt or random distribution)
- ▶ compute charge on electrodes
- ▶ compute forces on mobile species
- ▶ Begin MD loop
 - ▶ update velocities and positions
 - ▶ if (NVT) update species' and thermostats's positions and velocities
 - ▶ if (molecule with constraints) apply 1st part of rattle
 - ▶ compute charge on electrodes at $t + dt$
 - ▶ compute forces on mobile species at $t + dt$
 - ▶ Update velocities for the second half-step
 - ▶ if (molecule with constraints) apply 2nd part of rattle
 - ▶ if (NVT) iteratively update species and thermostat velocities
 - ▶ output
 - ▶ $t = t + dt$
- ▶ End MD loop

Missing features

To request the addition of a feature, create an issue on the gitlab:

<https://gitlab.maisondelasimulation.fr/amarinla/mw2/issues>