

# Satellite Computer Vision mit Keras und TensorFlow

Best Practices und Beispiele aus der Forschung

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Mannheim, May 2019



# Why

is satellite computer vision relevant?

# How

does computer vision help remote sensing?

# What

do you need to start?

# Outline

# Why

is satellite computer vision relevant?

→ Theory  
~ 10 minutes

# How

does computer vision help remote sensing?

→ Theory  
→ Code examples in slides  
→ Research results  
~ 25 minutes

# What

do you need to start?

→ Best practices  
→ Links to resources  
~ 5 minutes

# GitHub



jensleitleff/CNN-Sentinel

# Why

is satellite computer vision relevant?

# How

does computer vision help remote sensing?

# What

do you need to start?

1. Why is this talk relevant (for me)?
2. What is satellite CV?
3. How is it applied in today's life?



# Why is this talk relevant (for me)?



## Engineers & scientists

State-of-the-art methods  
Smart data interpretation  
Publishing methods & code



## Similar challenges

Multi-modal data fusion  
Weak & sparse labels  
Curse of dimensionality



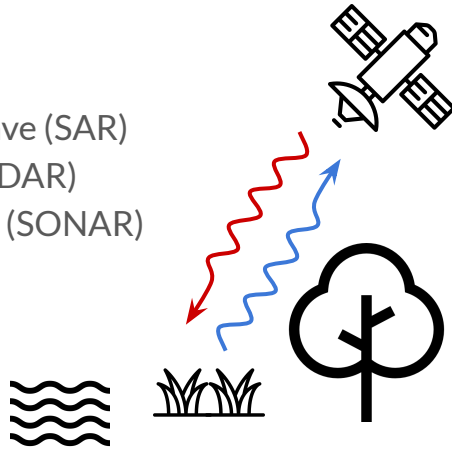
## Relevant data

2D, 3D, time series, GIS  
A lot of free datasets  
Big data & small data

# Remote sensing & satellites

## Active

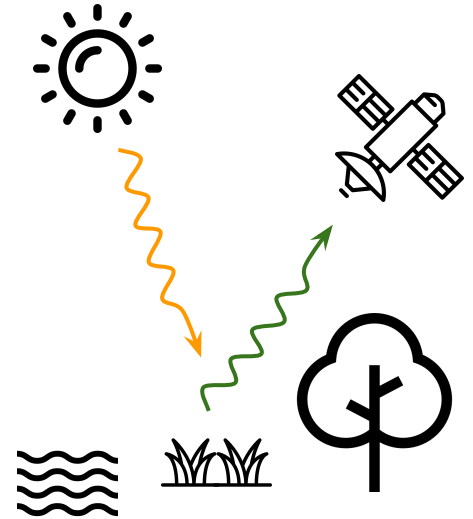
- Microwave (SAR)
- Laser (LIDAR)
- Acoustic (SONAR)



## Passive

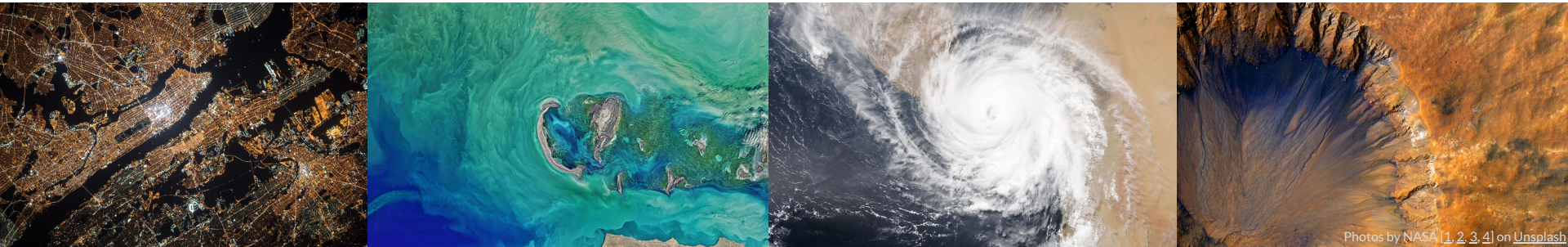
- RGB
- Multispectral

→ Focus of this talk

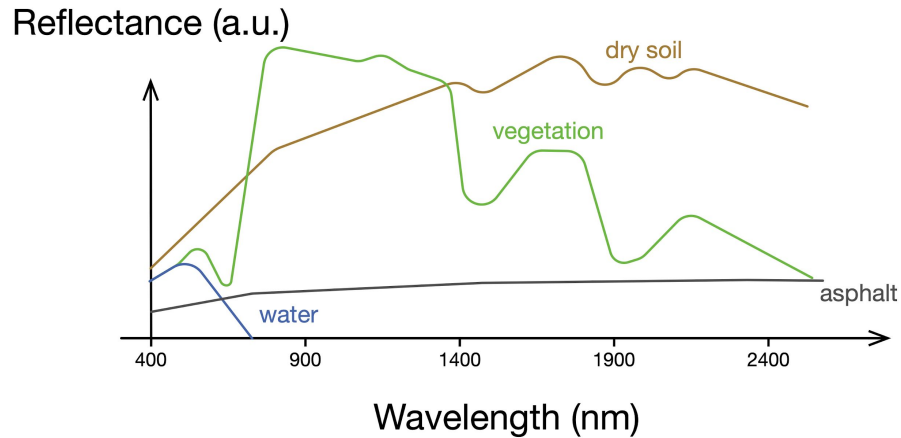


# Applications of satellite remote sensing

- **Meteorology** → weather forecasts, climate research, monitoring of glaciers and sea ice
- **Natural resources** → agriculture, forestry, environmental monitoring, coastal monitoring
- **Geosciences** → mapping, road networks, hydrology
- **Land administration** → land use / cover, building detection
- **Disaster response** → monitoring of natural hazards like wildfires, floods, earthquakes, volcanoes



## Example: Land cover



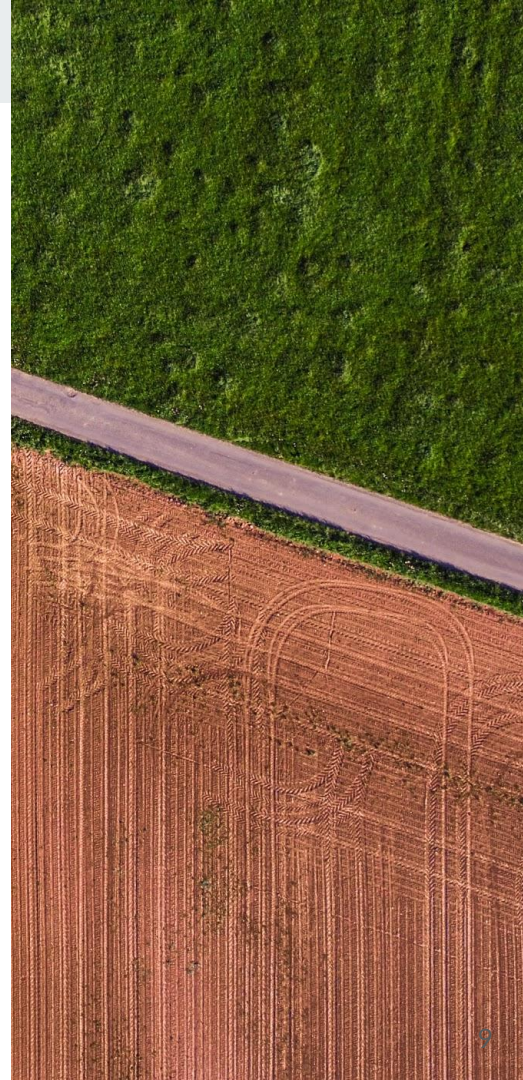
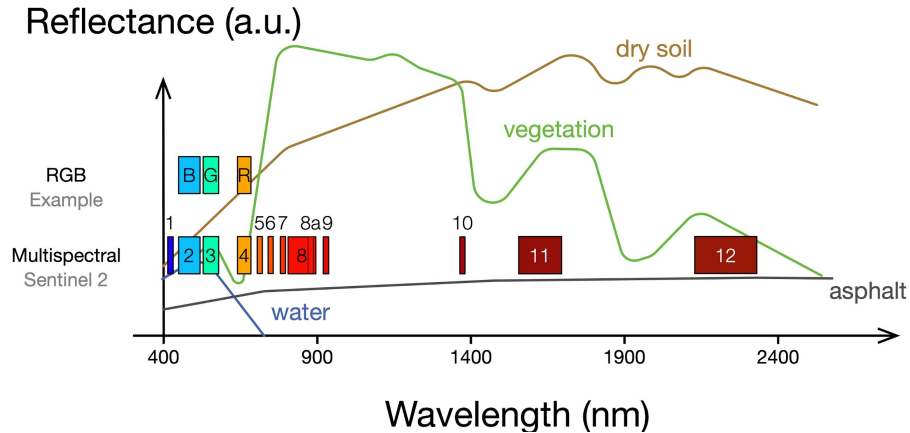
vegetation

asphalt

dry soil



# Example: Land cover & passive satellite





# The Copernicus programme (by ESA)

Launch date	Mission	Objective
2014	Sentinel-1	Radar for land and ocean
2015	Sentinel-2	Vegetation and soil monitoring
2016	Sentinel-3	Marine observation
→ 2023	Sentinel-4	Air quality monitoring
→ 2021	Sentinel-5	Air quality monitoring
→ 2020	Sentinel-6	Atmospheric measurements

# 5 days / world

It takes the Sentinel-2 satellites five days to cover the earth's surface.



# 3.2 TB / day

The Sentinel-2 satellites alone produce images in the size of 3.2 Terabytes per day, 365 days a year.

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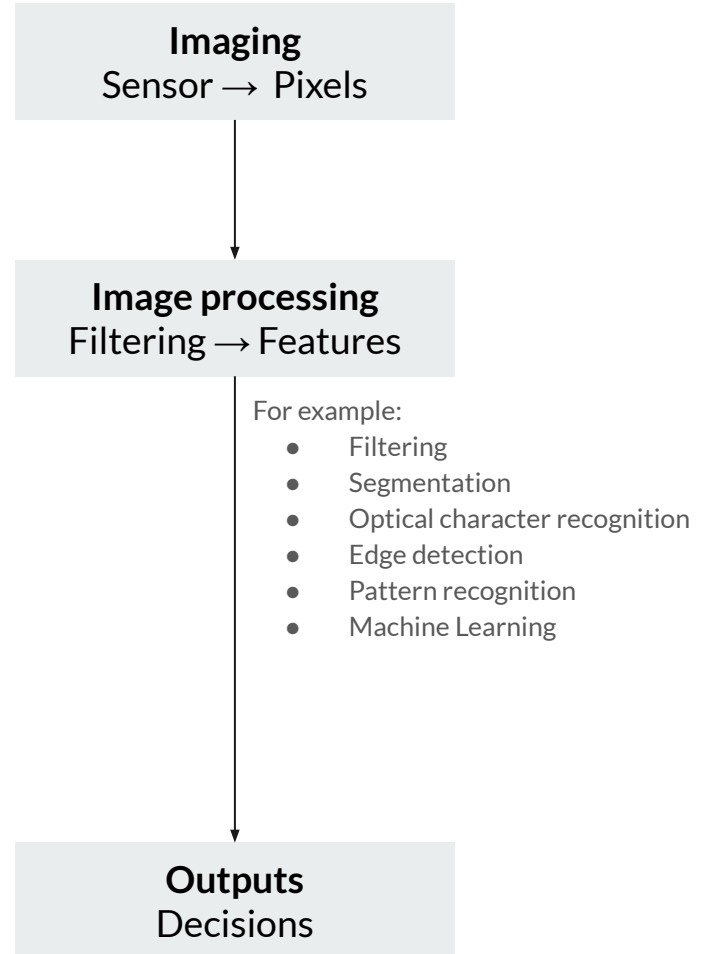
The data of the Sentinel program is free for everyone.  
No matter if commercial or not.  
No matter if European or not.





# Computer Vision

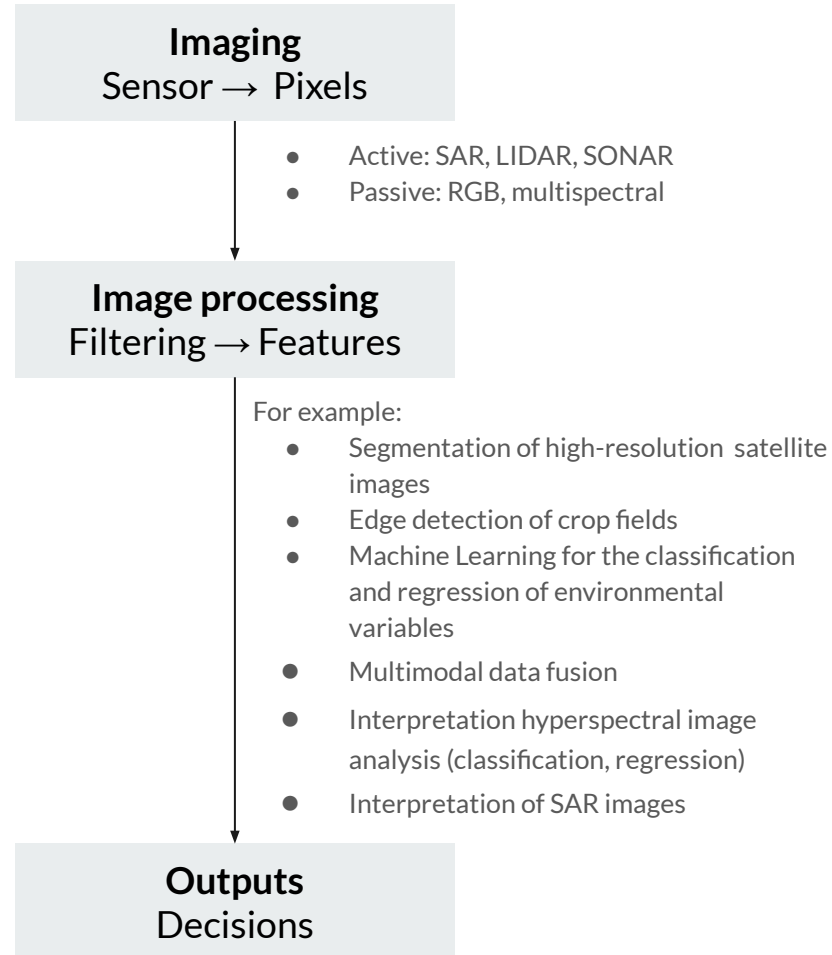
To bridge the gap between pixels  
and “meaning”.





# Computer Vision in Satellite Remote Sensing

To bridge the gap between pixels and “meaning”.



# Why

is satellite computer vision relevant?

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does computer vision help remote sensing?

# What

do you need to start?

1. Learning 2D patterns with CNN
2. Learning 1D & 3D patterns
3. Learning sequences

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# Learning 2D patterns

# The EuroSAT dataset

## Links:

- Introduced in [arXiv:1709.00029](https://arxiv.org/abs/1709.00029)
- Download here: <http://madm.dfki.de/downloads>

## Properties:

- Sentinel-2 satellite images
  - **Raw dataset:** 13 different spectral bands (1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 8a)
  - **RGB dataset:** RGB colors
- 27 000 labeled images
- 10 classes (→ next slide)

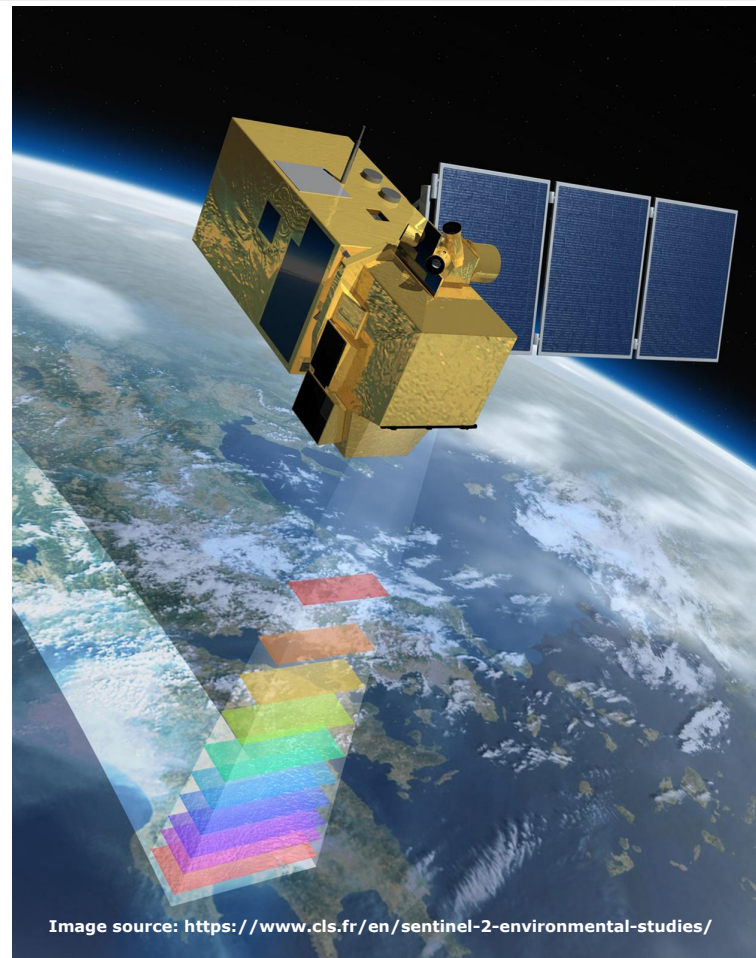


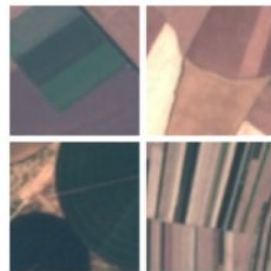
Image source: <https://www.cls.fr/en/sentinel-2-environmental-studies/>



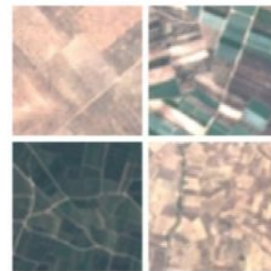
(a) Industrial



(b) Residential



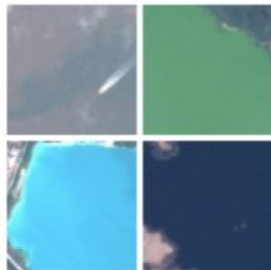
(c) Annual crop



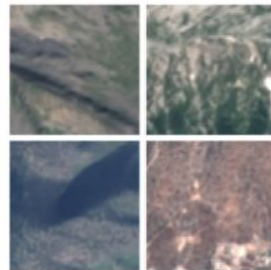
(d) Permanent crop



(e) River



(f) Sea & lake



(g) Herbaceous vegetation



(h) Highway



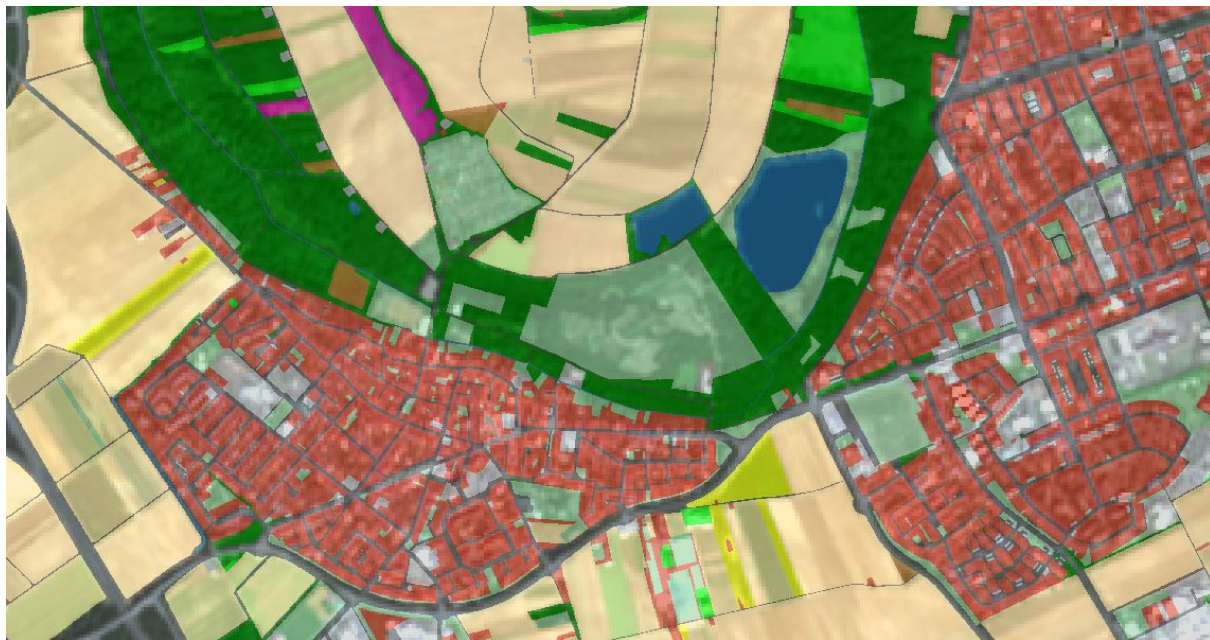
(i) Pasture



(j) Forest

one class per image

# Segmentation training



one class per pixel



## Learning from scratch

1. Network structure with **randomly initialized** weights
2. Training of **complete** network on training dataset

- **slow** convergence
- **lots of** training data necessary
- easily implemented for **every kind** of input data

## Transfer learning

## Learning from scratch

1. Network structure with **randomly initialized** weights
2. Training of **complete** network on training dataset

- **slow** convergence
- **lots of** training data necessary
- easily implemented for **every kind** of input data

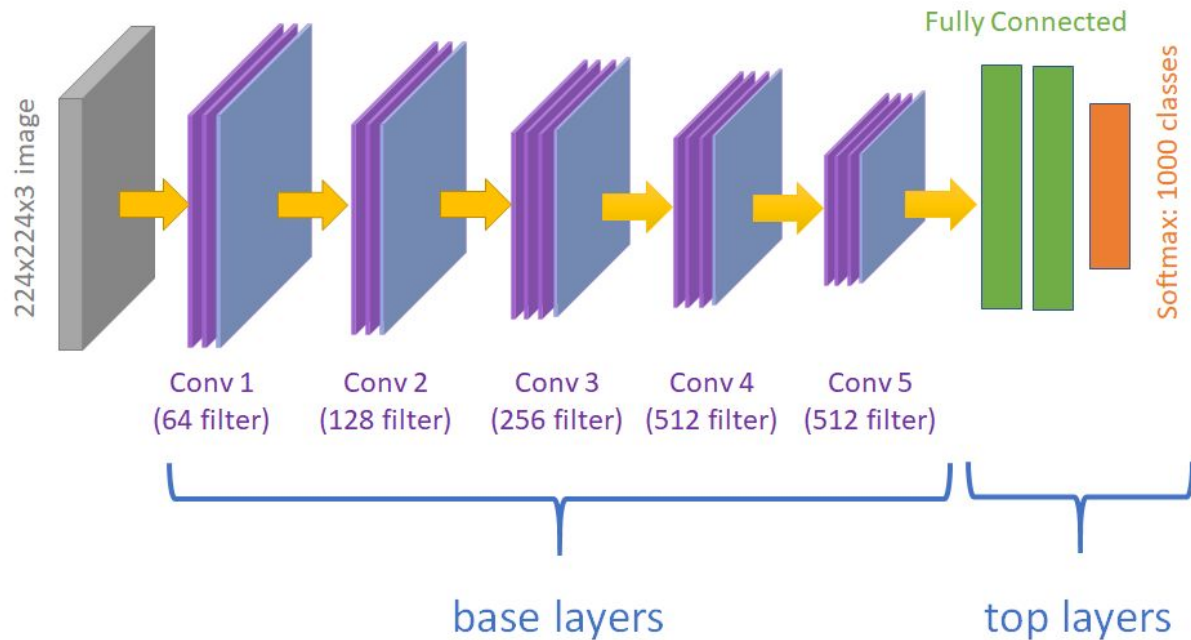
## Transfer learning

1. Network structure with **pretrained** weights
2. Training of **selected** layers on the training dataset (= fine tuning)

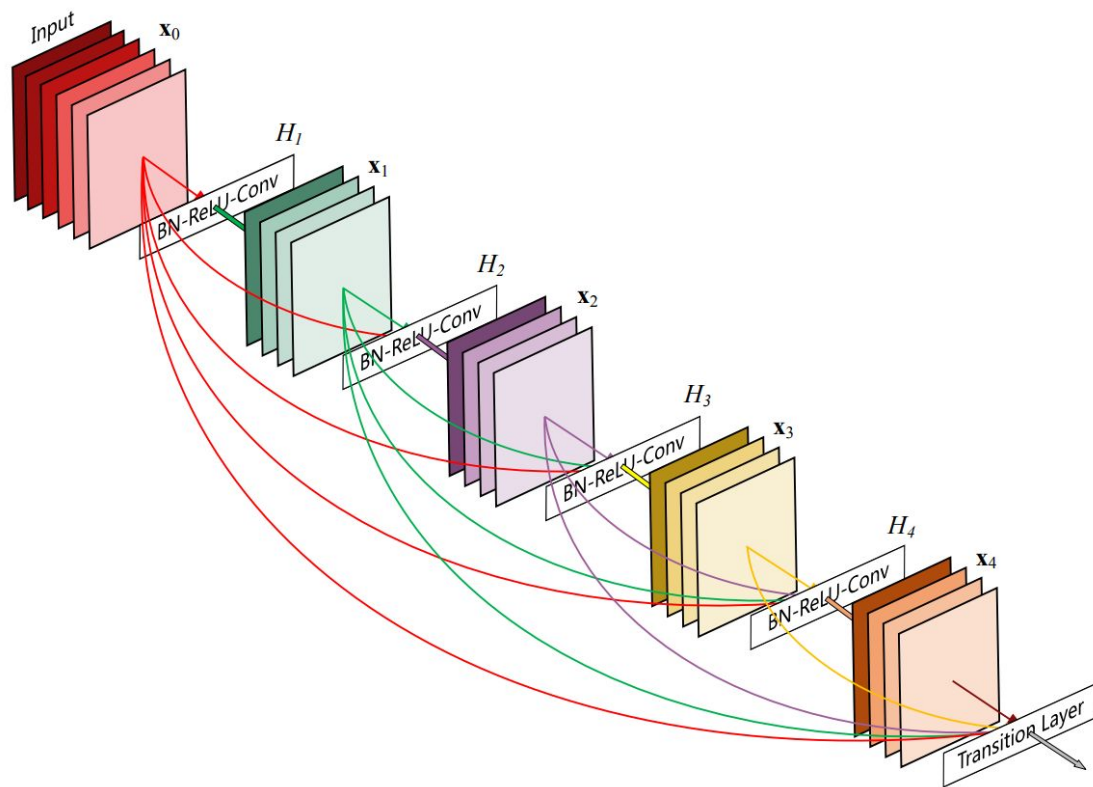
- much **faster** convergence
- **less** training data necessary
- mostly implemented **for RGB**
- modifications for MS necessary

→ Implement for RGB & multispectral

# VGG16 architecture



# DenseNet architecture





# Steps to do

## Training from scratch

1. Initialize network model without top layers
2. define new top layers
3. define data augmentation
4. define callbacks
5. -
6. -
7. -
8. fit model

## Transfer-learning

1. Pretrained network model without top layers
2. define new top layers
3. define data augmentation
4. define callbacks
5. set base layers non trainable
6. fit model (train new top layers)
7. set (some) base layers trainable
8. fit model (fine-tune base and top layers)

## Learning from scratch

```
base_model = VGG(include_top=False,  
                 weights=None,  
                 input_shape=(64, 64, 13))
```

```
# add a global spatial average pooling layer  
top_model = base_model.output  
top_model = GlobalAveragePooling2D()(top_model)  
# let's add a fully-connected layer  
top_model = Dense(2048, activation='relu')(top_model)  
top_model = Dense(2048, activation='relu')(top_model)  
# and a logistic layer  
predictions = Dense(num_classes, activation='softmax')(top_model)  
  
# this is the model we will train  
model = Model(inputs=base_model.input, outputs=predictions)
```

## Transfer learning

```
base_model = VGG(include_top=False,  
                 weights='imagenet',  
                 input_shape=(64, 64, 3))
```

```
# first: train only the top layers  
# i.e. freeze all convolutional layers  
for layer in base_model.layers:  
    layer.trainable = False
```



## Nice tools in Keras I

- Image augmentation

```
# defining ImageDataGenerators
# ... initialization for training
train_datagen = ImageDataGenerator(fill_mode="reflect",
                                    rotation_range=45,
                                    horizontal_flip=True,
                                    vertical_flip=True)
```

- Use image patches  
in directories

```
train_datagen.flow_from_directory(path_to_train,
                                  target_size=(64, 64),
                                  batch_size=batch_size,
                                  class_mode='categorical')
```



## Nice tools in Keras II

- Define some callbacks for training

```
checkpointer = ModelCheckpoint(...)  
earlystopper = EarlyStopping(...)  
tensorboard = TensorBoard(...)
```

- and train ...

```
model.fit_generator(train_generator,...  
                    callbacks=[checkpointer, earlystopper,  
                               tensorboard],  
                    validation_data=validation_generator)
```



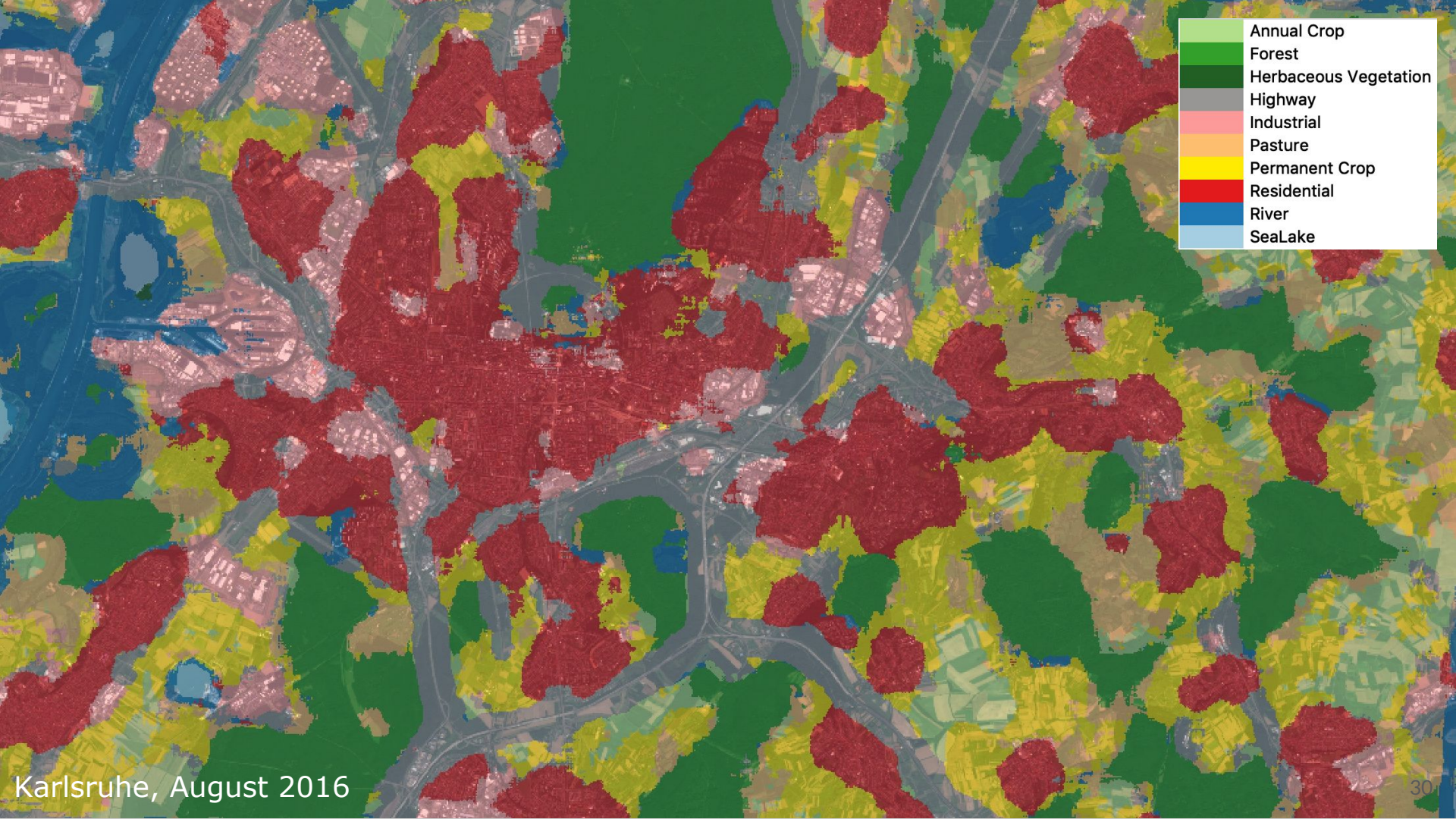
## Additional things in the repository

- in detail notebooks for
  - learning from scratch
  - transfer learning
  - customized data generators
- python scripts for
  - panchromatic data
  - multispectral data
- many additional information about
  - setup an environment
  - data
  - ...

# GitHub

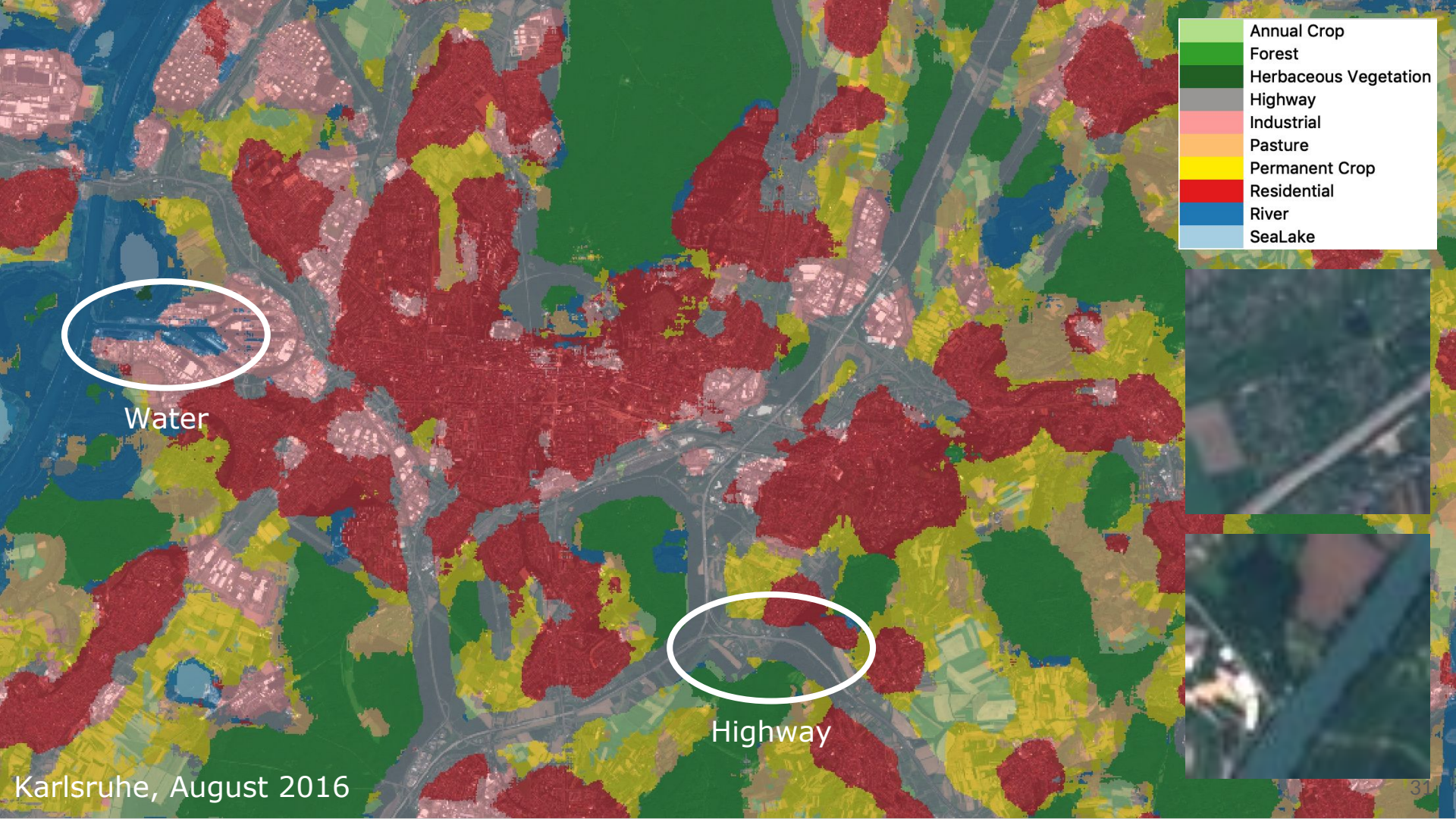


jensleitloff/CNN-Sentinel



Karlsruhe, August 2016







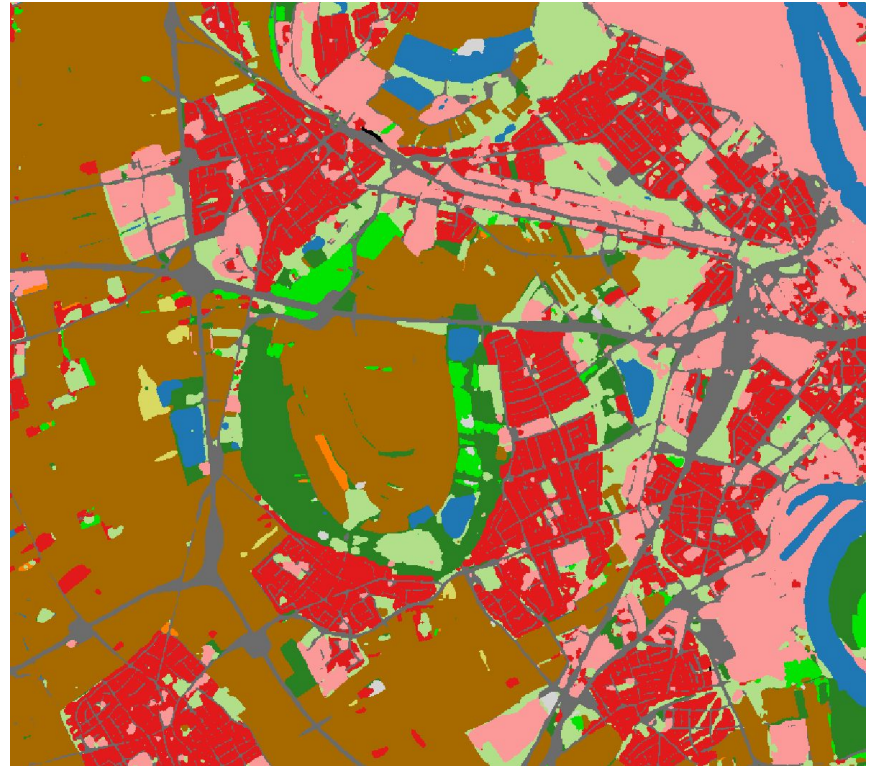




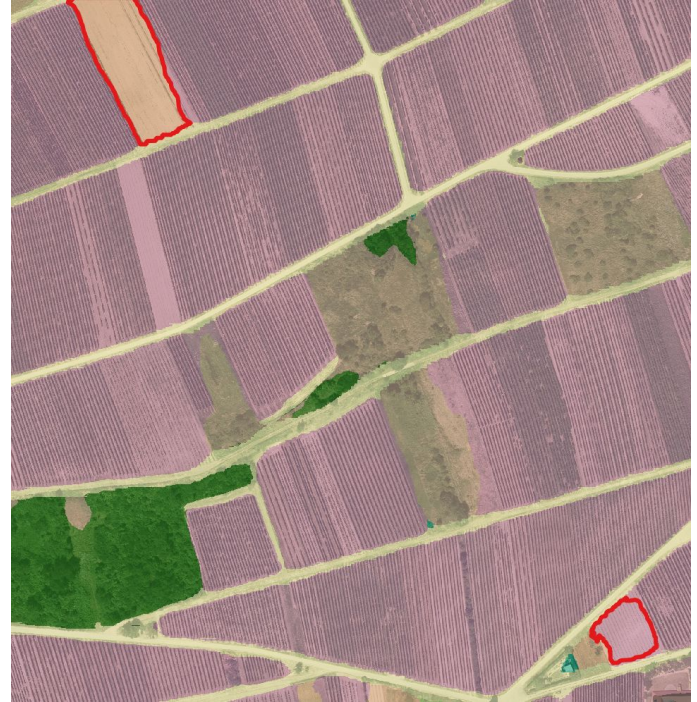
Ludwigshafen, August 2015



Results from project with LVerGeo Rheinland-Pfalz



Results with image segmentation



Klassifikation 20cm



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# Learning 1D & 3D patterns

## Learning sequences



# Other convolution approaches

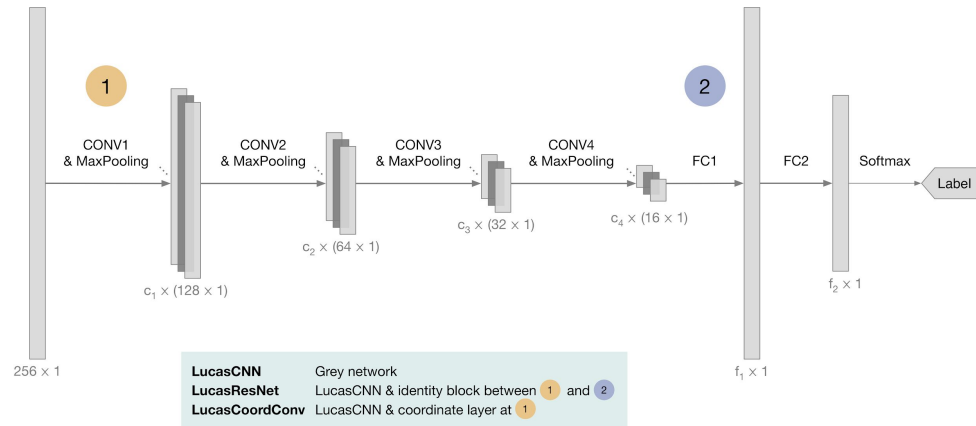
Convolution approaches:

- No convolution
- 1D convolution over spectral dimension
- 2D convolution over spatial dimension → this talk
- 3D convolution over spectral & spatial dimension
- 3D convolution over temporal & spatial dimension

Review paper: [arXiv:1710.03959](https://arxiv.org/abs/1710.03959)



# Learning 1D patterns with CNNs



- Paper will be presented in June 2019
- [Code](#) available on GitHub
- Free soil texture [dataset](#)
- Hyperspectral → more features than multispectral
- 1D convolution over the spectral dimension

Felix M. Riese and Sina Keller, "Soil Texture Classification with 1D Convolutional Neural Networks based on Hyperspectral Data," 2019, Accepted at Geospatial Week 2019 in Enschede (NL). Available: [arXiv:1901.04846](#)



# Learning 3D patterns with CNNs

- 3D convolution over **spatial** & **spectral** dimension
  - spatial dimension → earth surface (cf. [Learning 2D patterns](#))
  - spectral dimension → making use of multi-/hyperspectral data (cf. [Learning 1D patterns with CNNs](#))
- 3D convolution over **spatial** & **temporal** dimension
  - temporal dimension → learn from temporal changes, e.g. crop

# Learning sequences



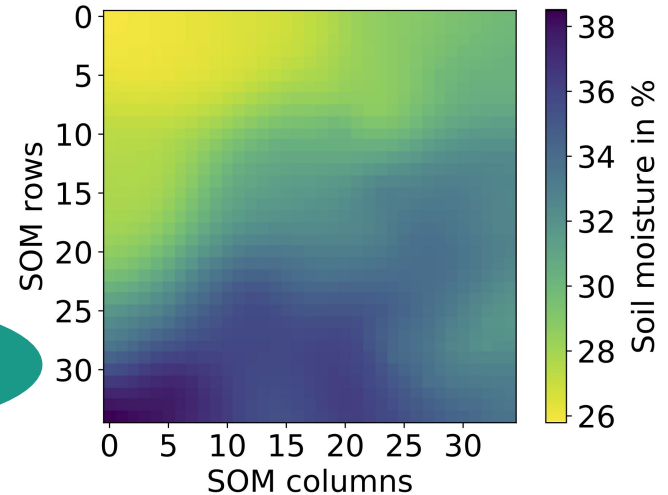
- Temporal changes → learning sequences
- Recurrent neural networks, LSTM → Rußwurm, Körner ([arXiv:1802.02080](https://arxiv.org/abs/1802.02080))

# One more thing: SUSI

Supervised Self-organ/zing maps in Python

- Self-organizing maps for unsupervised **and** supervised learning
- Code and usage in **scikit-learn style**
- Example applications
  - 2D visualization of high-dimensional data
  - Classification and regression on small datasets
- [Code](#) and [paper](#) freely available

see talk by Oliver Zeigermann today



Source: [felixriese/susi](https://felixriese.github.io/susi/)

# Why

is satellite computer vision relevant?

# How

does computer vision help remote sensing?

# What

do you need to start?

1. Best practices from research
2. Starting point with satellite CV



# Best practices

## Basics

- Use existing frameworks like **Keras**
- Make use of **build-in functions** like
  - data augmentation generators
  - callbacks
- Try **established architectures** and try **pre-trained** networks to reduce training time
- **Big data** beats data cleaning
- Measure error on training **and** test subset
- Training **strategy**:
  1. Training of estimator on small dataset until training error is 0
  2. Implementation of regularization, e.g. dropout, batch-normalization, ...



# Best practices

Further reading

Recommended resources:

- [CPVR 2014 Talk by Marc'Aurelio Ranzato](#)
- “Visualizing and Understanding Convolutional Networks” by M. D. Zeiler and R. Fergus, 2013, [arXiv:1311.2901](#)
- Coursera Deep Learning Specialization part 3: [Structuring Machine Learning Projects](#) by deeplearning.ai

# Starting point with satellite CV

## GitHub



jensleitloff/CNN-Sentinel

- Requirements (Versions ...)
- Environment setup (Conda ...)
- Code for
  - setting up the data
  - CNN transfer learning RGB & MS
  - CNN learning-from-scratch RGB & MS
- How to download Sentinel-2 data
- Links to more datasets





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**Thank you for your attention!**

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