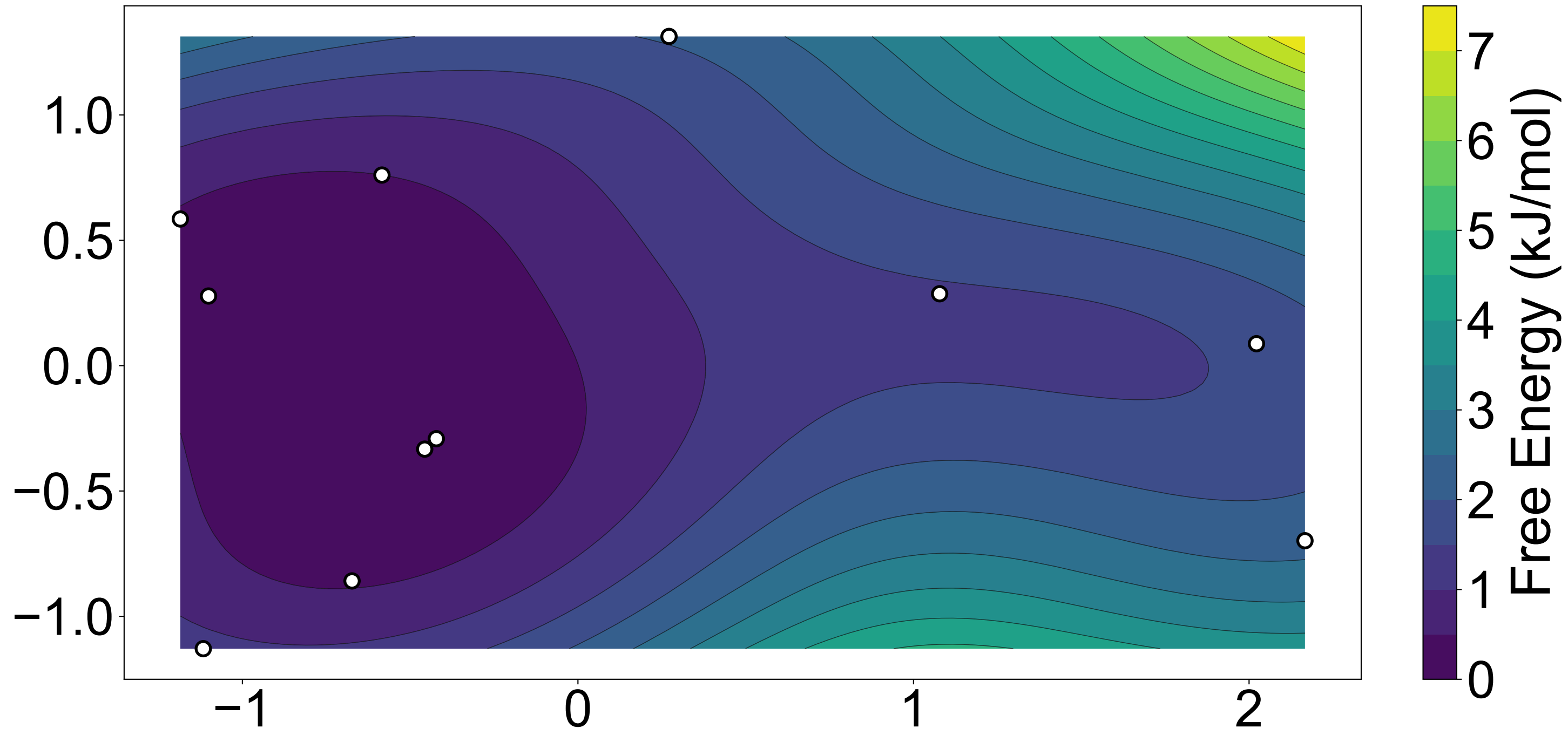


2D projection of trajectory

projection on eigenvector 2 (nm)



projection on eigenvector 1 (nm)