



Engineering Lattice Metamaterials – Simulation and Experimental Validation

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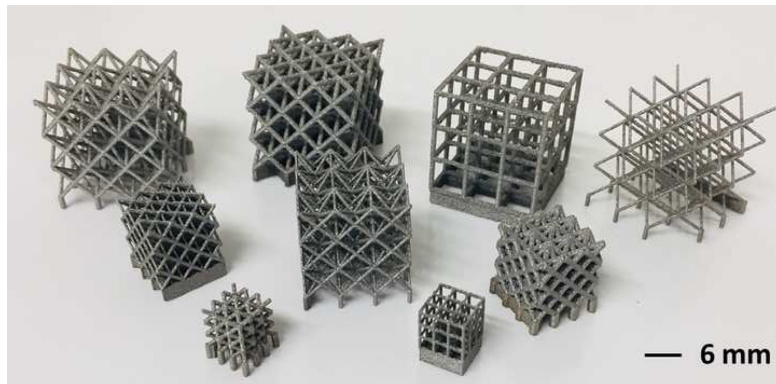


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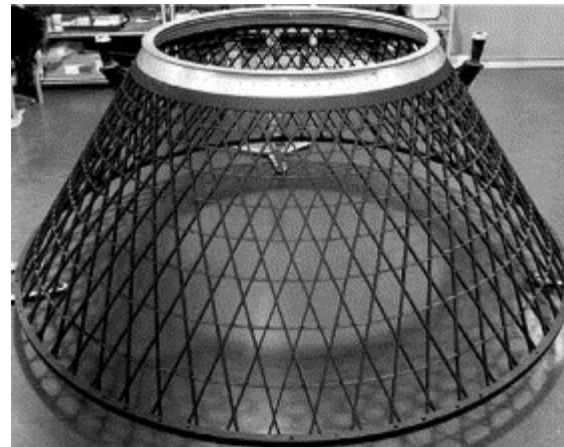
MEBioSys, Brno 2025

Motiviation – Lattice Metamaterials

- Slender lattices
- High strength to density ratio
- Allow for tailoring towards desired properties
 - Auxetic metamaterials
 - Bi-stable metamaterials
- Huge potential for optimization



B. Hanks, et al, Additive Manufacturing, Vol. 35, 101301, 2020

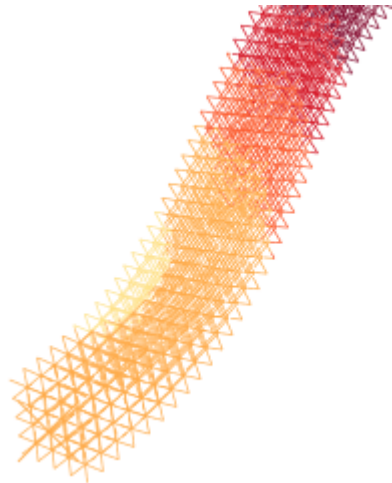


V.V. Vasiliev, A.F. Razin, Compos. Struct., Vol. 76, 182–189, 2006

Modeling Concepts

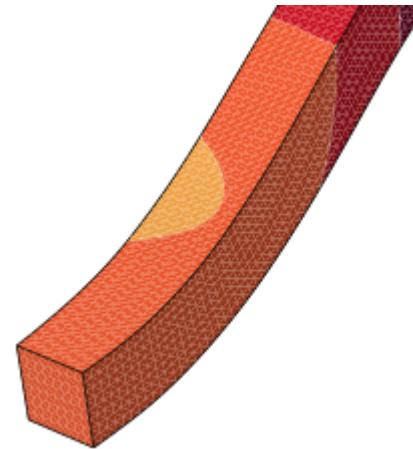
Discrete Models

- Each lattice member resolved
- Detailed geometric model
- Load introduction?
- Computational demanding
- Local phenomena can be captured in detail



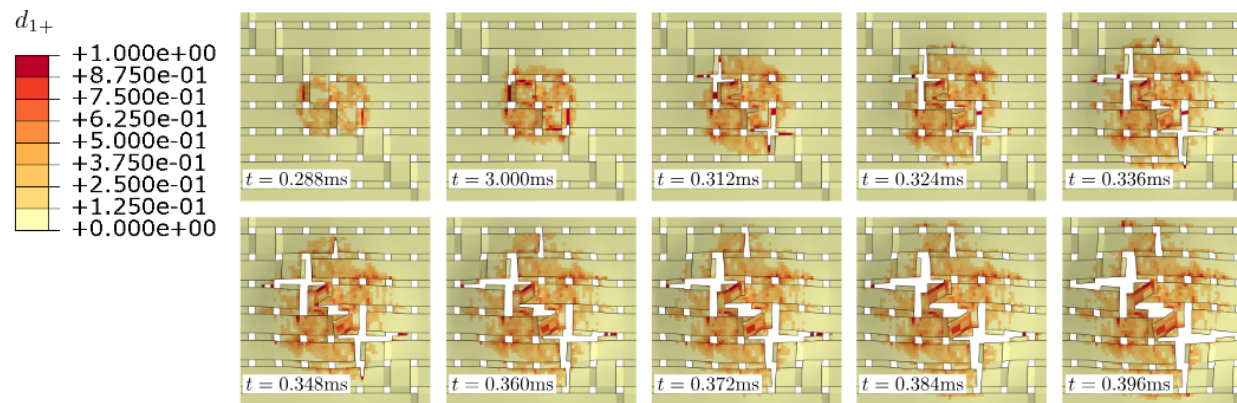
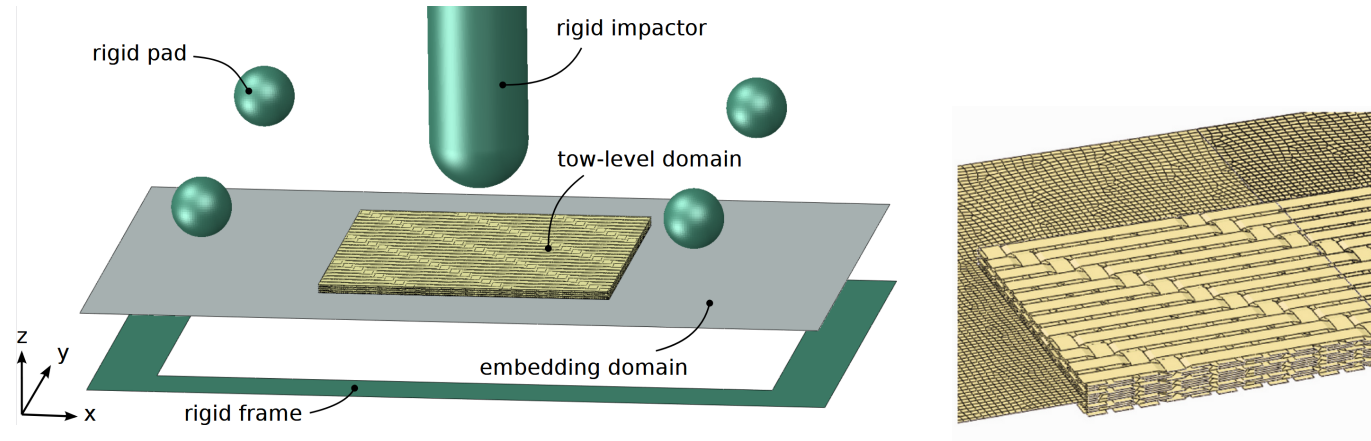
Continuum Models

- Homogeneous solid
- Effective response
- Material Parameters?
- Computationally efficient
- Local phenomena not/partly captured



Modeling Concepts

Combined Approaches – e.g. embedding approach



Overview

- Discrete Models
- Continuum Modeling
- Summary

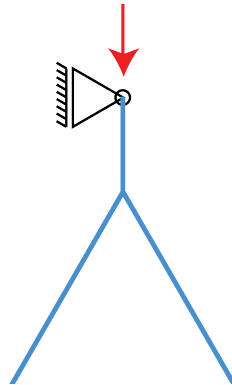
Overview

- **Discrete Models**
 - Modeling
 - Examples
- **Continuum Modeling**
- **Summary**

Modeling

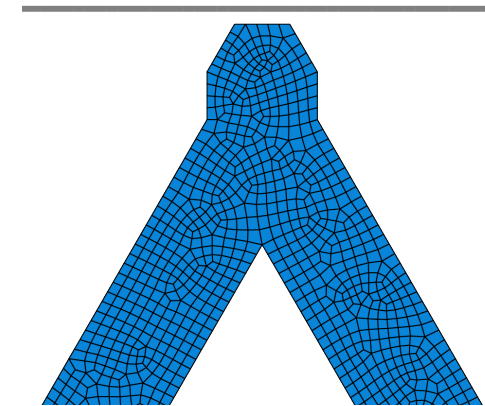
Beam Element Models

- Lattice members discretized with beam elements
- How to represent
 - material aggregation at nodes?
 - material nonlinearities?
 - boundary conditions / load introduction?
 - geometric imperfections?
- Computationally efficient
- Postprocessing

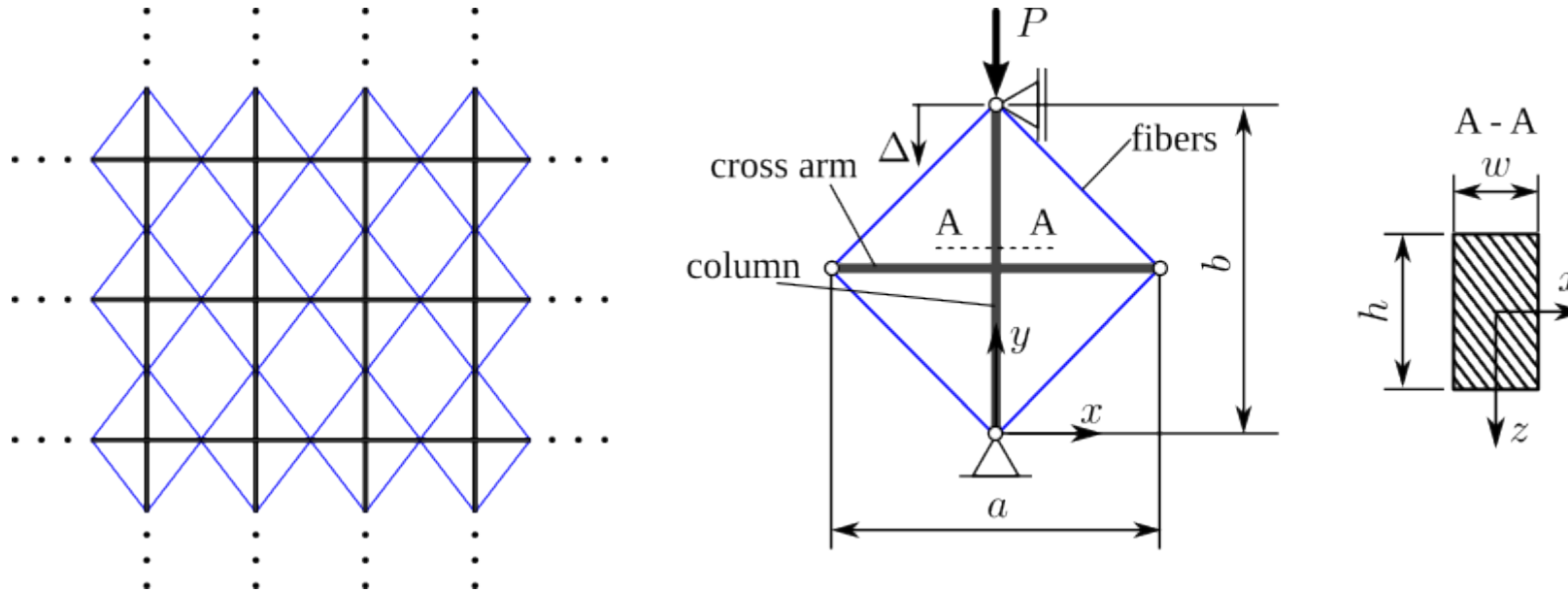


Continuum Element Models

- Lattice members discretized using continuum elements
- Discretization is trade off between
 - required elements over the strut thickness.
 - computational resources.
- Computationally more demanding

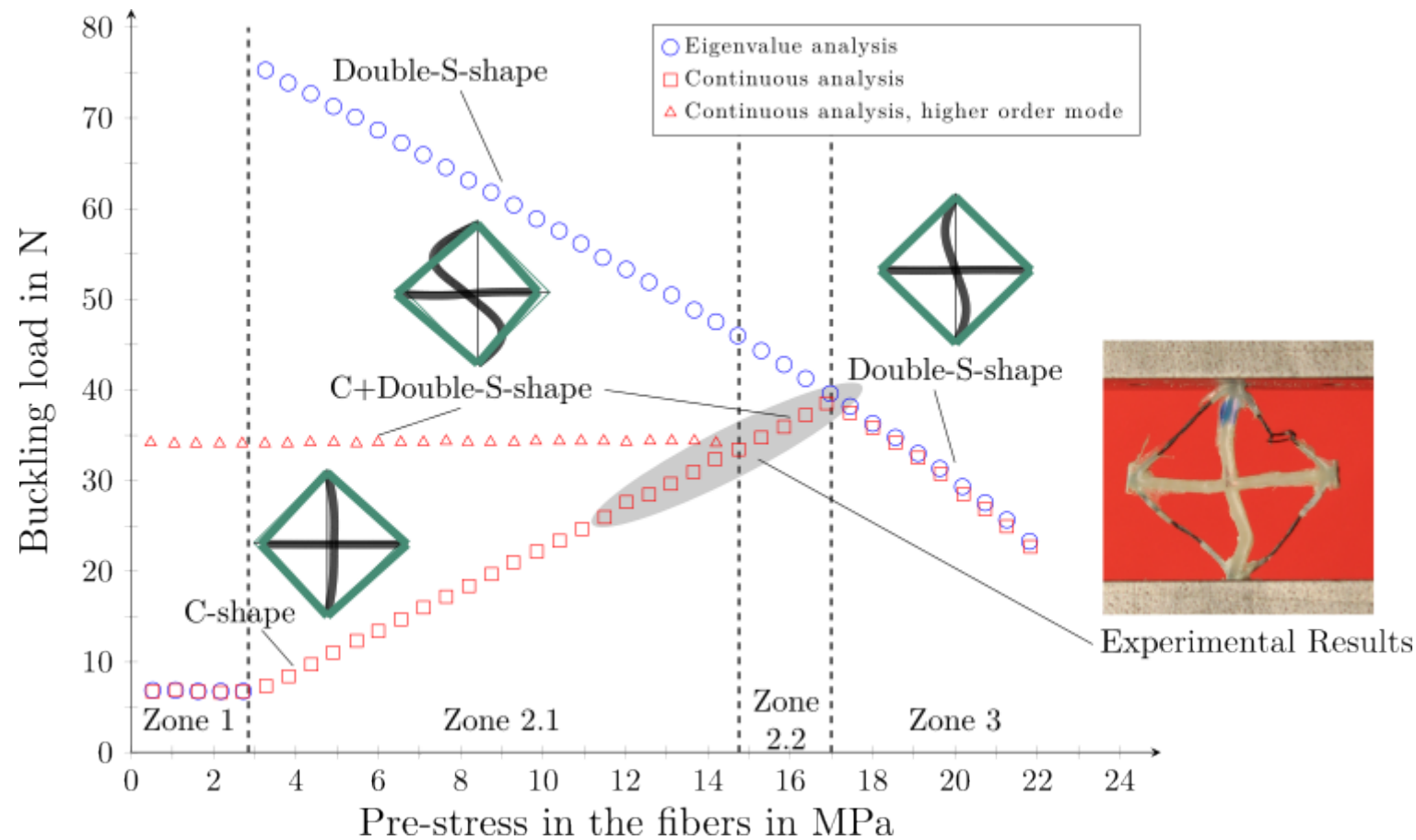


Example – Pre Stressed Lattices



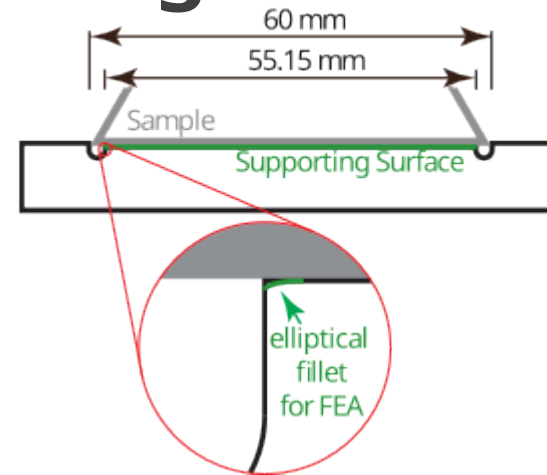
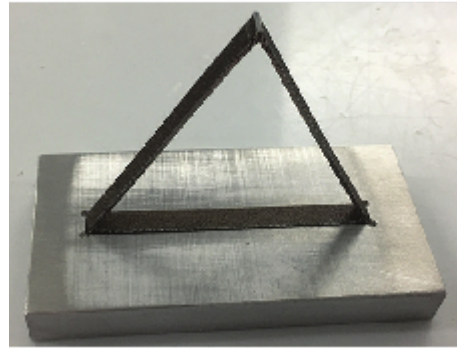
- Fibers are pre-stressed to **increase the buckling load** of the lattice
- Aims:
 - **Proof of concept**
 - Investigate influence of pre-stress on buckling load
- Beam model of single cell, elastic material
- Comparison with experiments

Example – Pre Stressed Lattices



- Pre-stress leads to an increase of the buckling load
- Good agreement with experiments
- Manufacturing of multi-cell arrangements?

Example – Triangular Lattices



- SLM printed cells using stainless steel powder
- Subjected to compressive loading

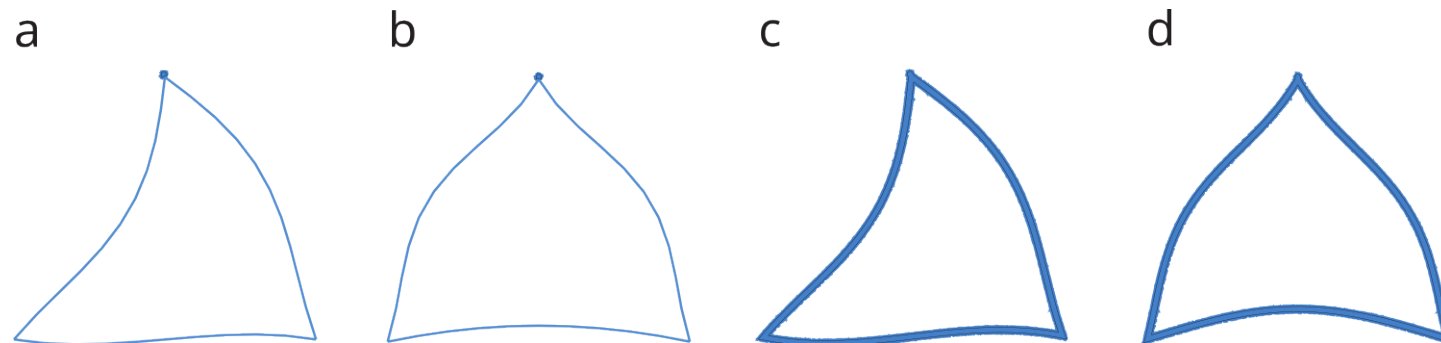
- Modeling with FEM – beam vs. continuum element models
- Elastic-plastic material model, isotropic hardening

B. Werner, O. Červinek, D. Koutný, A. Reisinger, H.E. Pettermann, M. Todt; Int. J. Solids Struct. 236–237, 2022, 111295, <https://doi.org/10.1016/j.ijsolstr.2021.111295>

Example – Triangular Lattices

Linear buckling analysis

- No material nonlinearities
- No friction



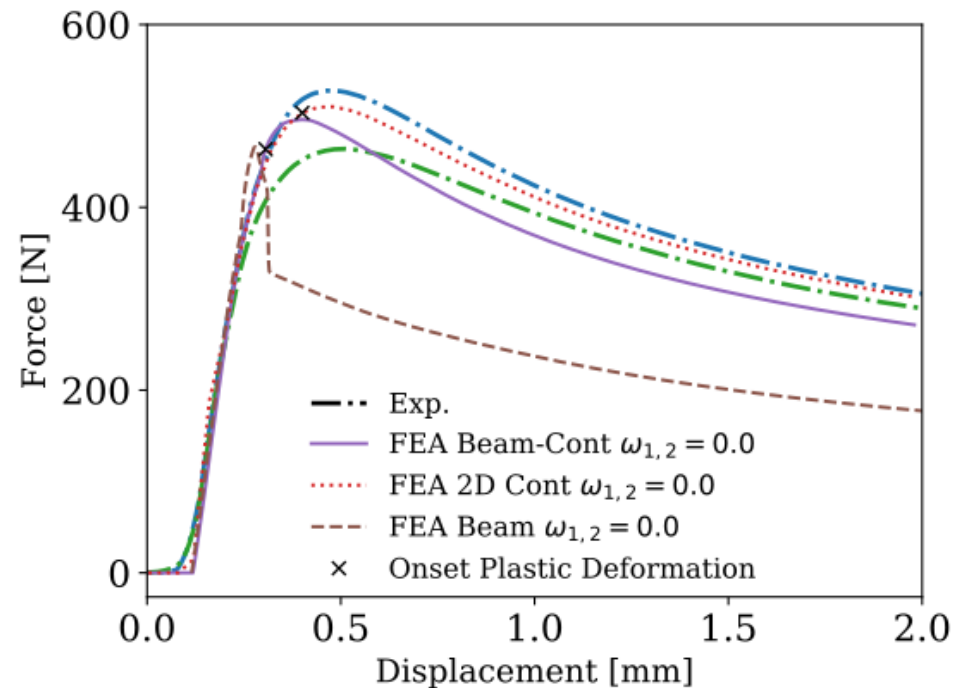
- a & c: mode 1 at approx. 300 N
- b & d: mode 2 at approx. 600 N

Mode 1 should be more likely than mode 2 – experiments tell a different story!

Example – Triangular Lattices

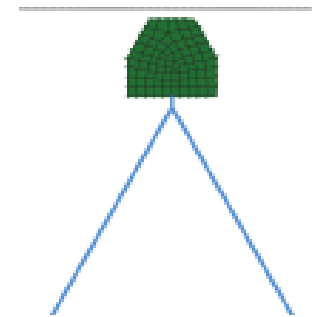
Nonlinear post-buckling analysis

- Beam vs. continuum vs. combined model



Combined Model

Contact area at the top modeled using continuum elements

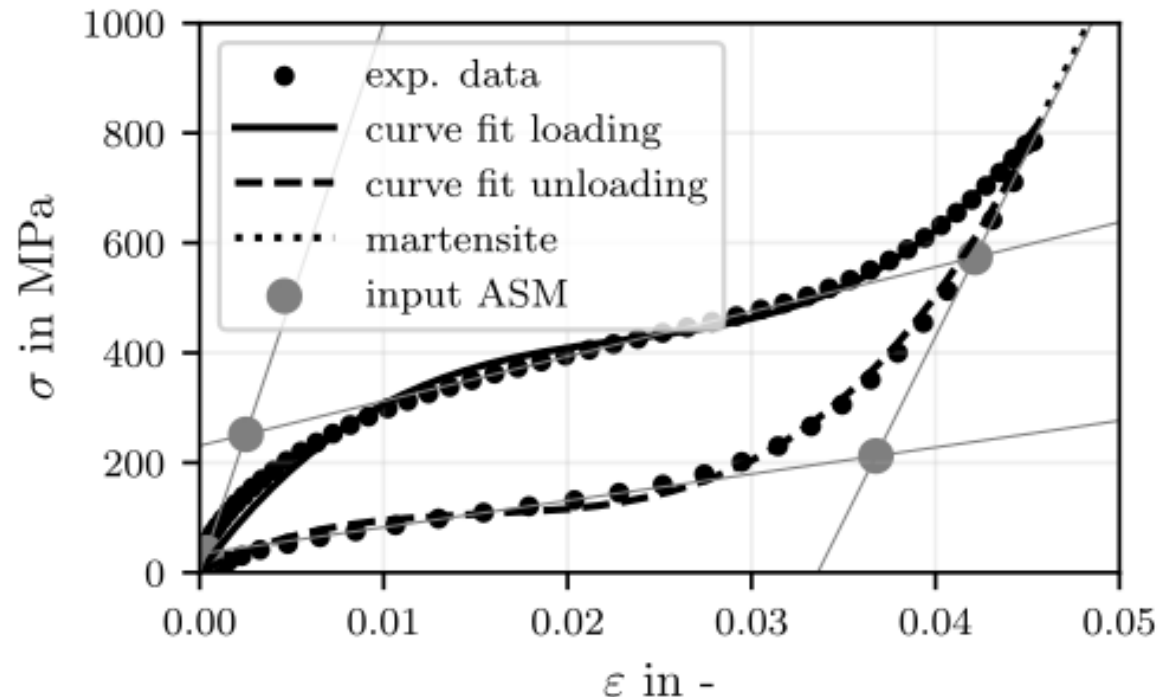


- Friction at top contact point drives structure into mode 2
- Pure beam model is not able to handle this effect

Example – Superelastic Lattices

User Material Model for NiTi 38

- Loading and unloading path using 3rd order polynomials
- Accurate representation of material response
- Available only for uniaxial stress states (beam elements)

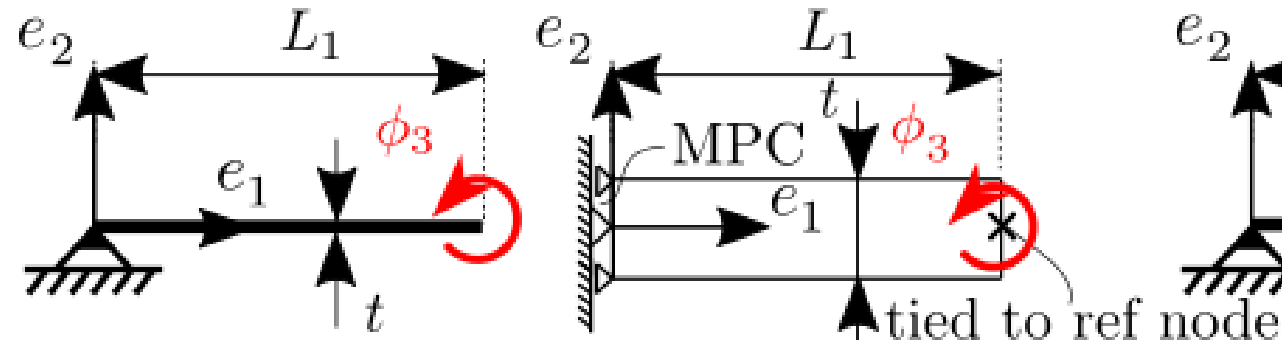


M.M. Schasching, O. Červinek, D. Koutný, H.E. Pettermann,
M. Todt; PAMM 25, 2025, e202400092,
<https://doi.org/10.1002/pamm.202400092>

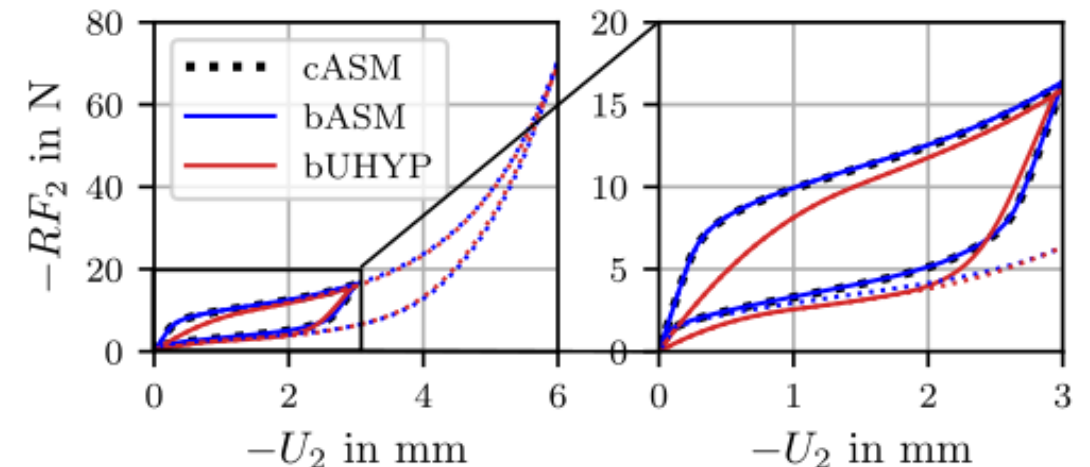
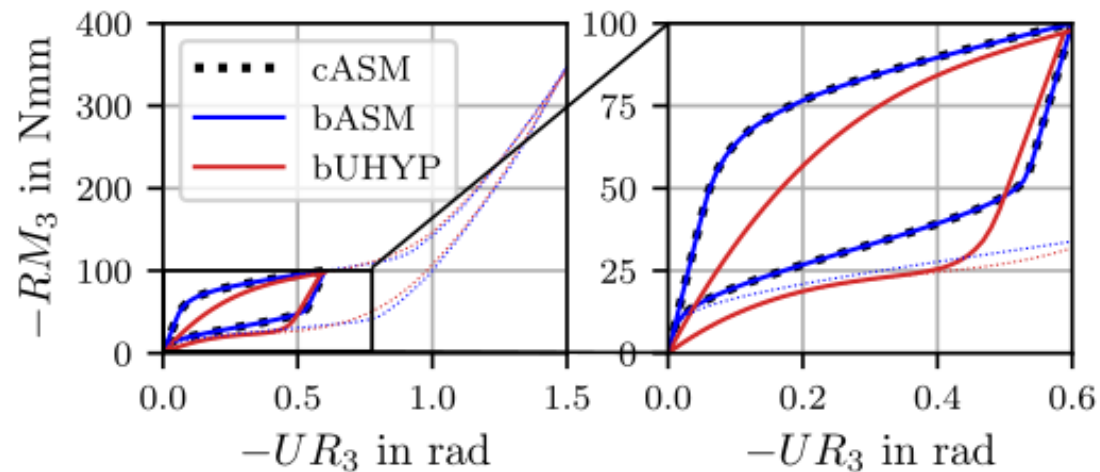
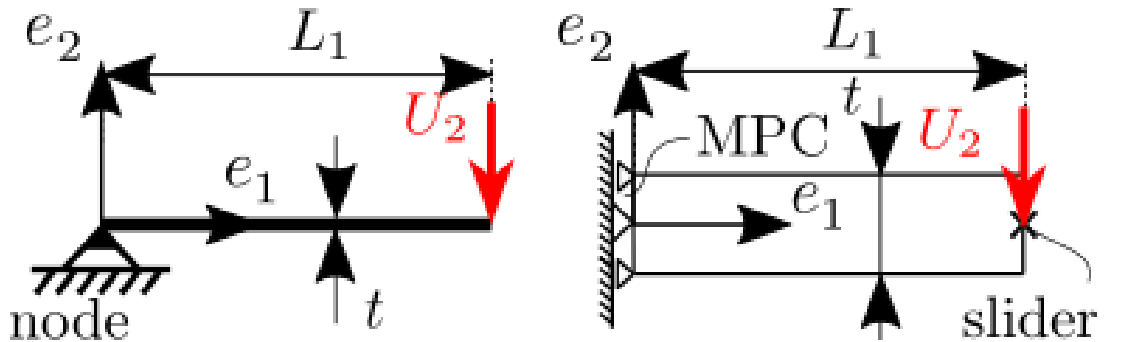
Example – Superelastic Lattices

Beam vs. Continuum Modeling

Pure bending

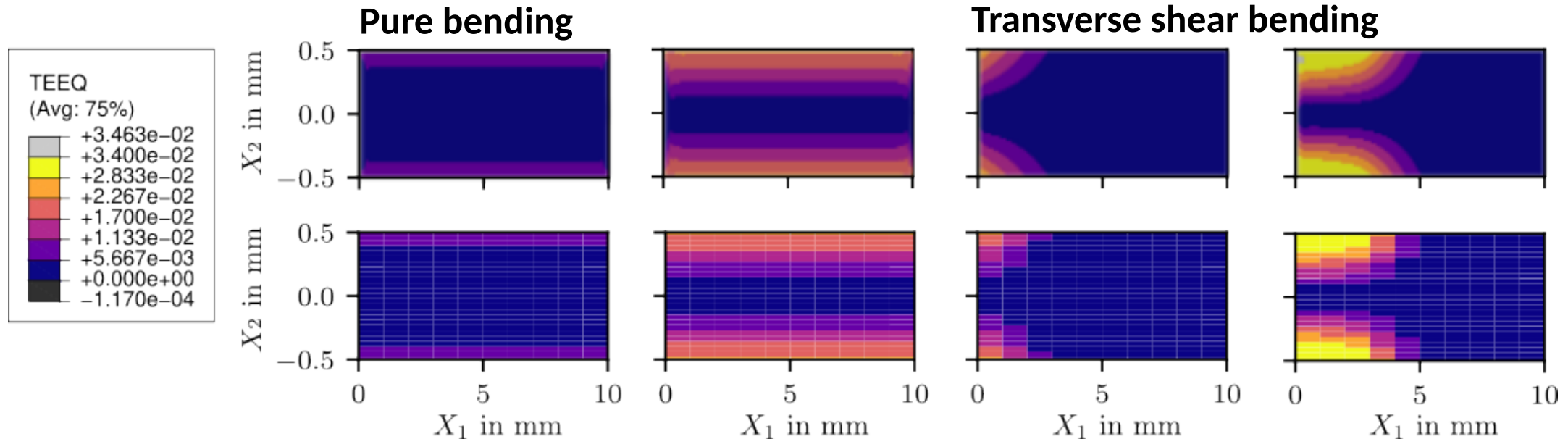


Transverse shear bending



Example – Superelastic Lattices

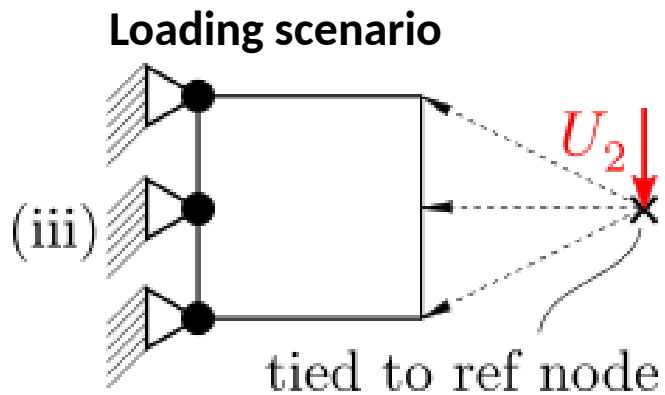
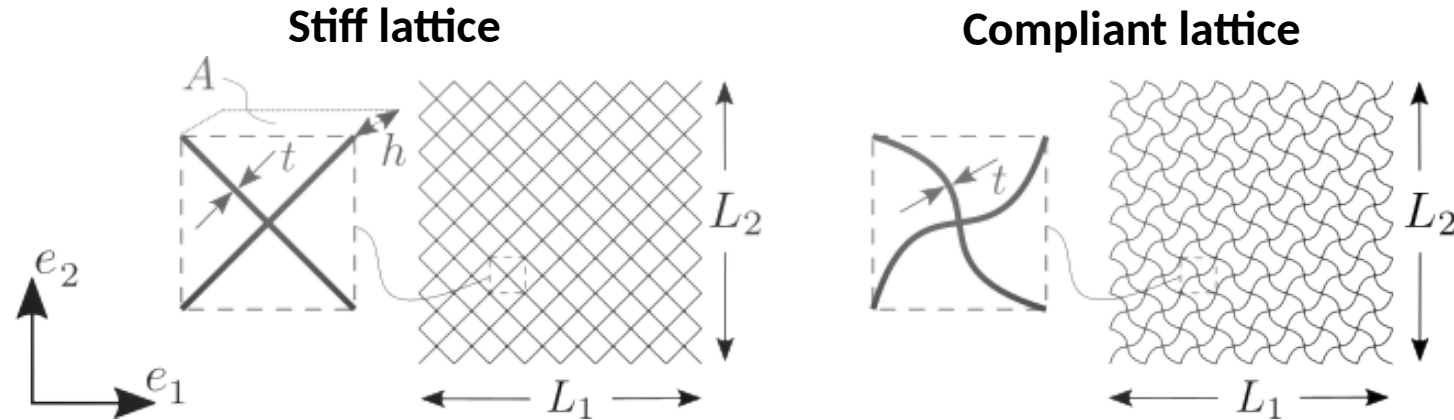
Beam vs. Continuum Modeling



- Beam based modelling approach is suitable
- Very good representation of
 - load displacement response
 - spatial evolution of the transformation zones during loading / unloading

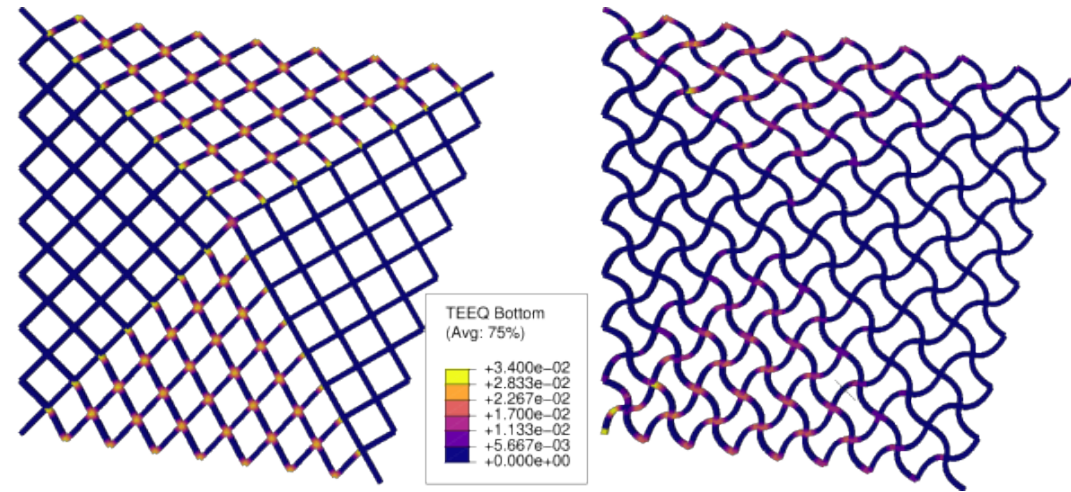
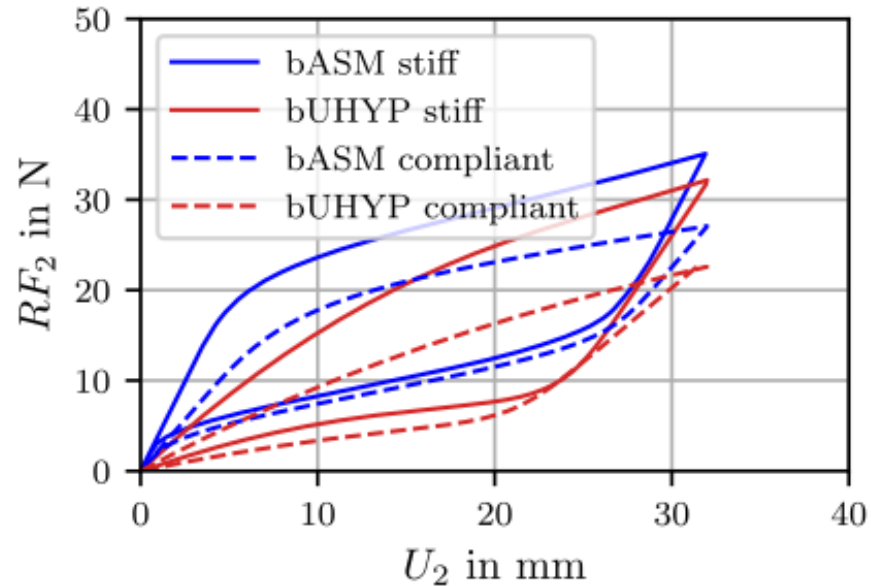
Example – Superelastic Lattices

Simulation of cell structures



$N \times N$	$L_i = L$ in mm	t in mm	$A = Lh$ in mm ²
-			
8x8	80	0.5	80

Example – Superelastic Lattices



- ASM model overestimates the reaction forces for finite structures
- Applicability of ASM model?

Overview

- Discrete Models
- **Continuum Modeling**
 - Micropolar Continuum Model
 - Example
- Summary

Micropolar Continuum Model

Micropolar Theory

- Scenarios where criteria of separation of scales is not met
- Displacement and **additional rotational** DOFs
- Material constants e.g. by energy based homogenization [1,2]

$$\begin{aligned} \underline{\underline{\sigma}} &= \underline{\underline{A}} : \underline{\underline{\varepsilon}} + \underline{\underline{C}} : \underline{\underline{\kappa}} & \text{with} & & \underline{\underline{\varepsilon}} &= \underline{\underline{u}} \otimes \underline{\underline{\nabla}} - \underline{\underline{\phi}} \times \underline{\underline{I}} \\ {}^{\kappa}\underline{\underline{\sigma}} &= \underline{\underline{C}}^T : \underline{\underline{\varepsilon}} + \underline{\underline{B}} : \underline{\underline{\kappa}} & & & \underline{\underline{\kappa}} &= \underline{\underline{\phi}} \otimes \underline{\underline{\nabla}} \end{aligned}$$

$$\underbrace{\begin{bmatrix} [\underline{\underline{\sigma}}] \\ [{}^{\kappa}\underline{\underline{\sigma}}] \end{bmatrix}}_{[\underline{\underline{\sigma}}]} = \underbrace{\begin{bmatrix} [\underline{\underline{A}}] & [\underline{\underline{C}}] \\ [\underline{\underline{C}}]^T & [\underline{\underline{B}}] \end{bmatrix}}_{[\underline{\underline{D}}]} \underbrace{\begin{bmatrix} [\underline{\underline{\varepsilon}}] \\ [\underline{\underline{\kappa}}] \end{bmatrix}}_{[\underline{\underline{\varepsilon}}]}$$

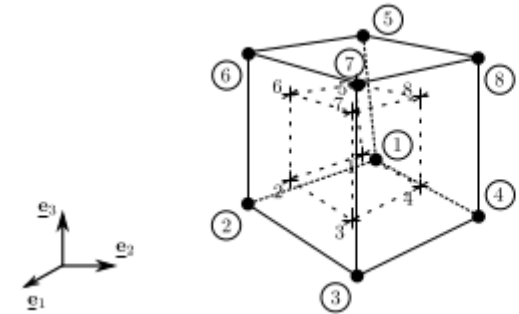
[1] Z.P. Bazant, Int. J. Solids Struct. 8 , 1972, 327–346, [https://doi.org/10.1016/0020-7683\(72\)90093-5](https://doi.org/10.1016/0020-7683(72)90093-5)

[3] R.S. Kumar, D.L. McDowell, Int. J. Solids Struct. 41, 7399–7422, 2004, <https://doi.org/10.1016/j.ijsolstr.2004.06.038>

Micropolar Continuum Model

FEM Implementation

- Geometric nonlinear behavior – large rotations
- Stiffness matrix via finite differences of perturbed residuals [3]
- FEM implementation as 3D user element

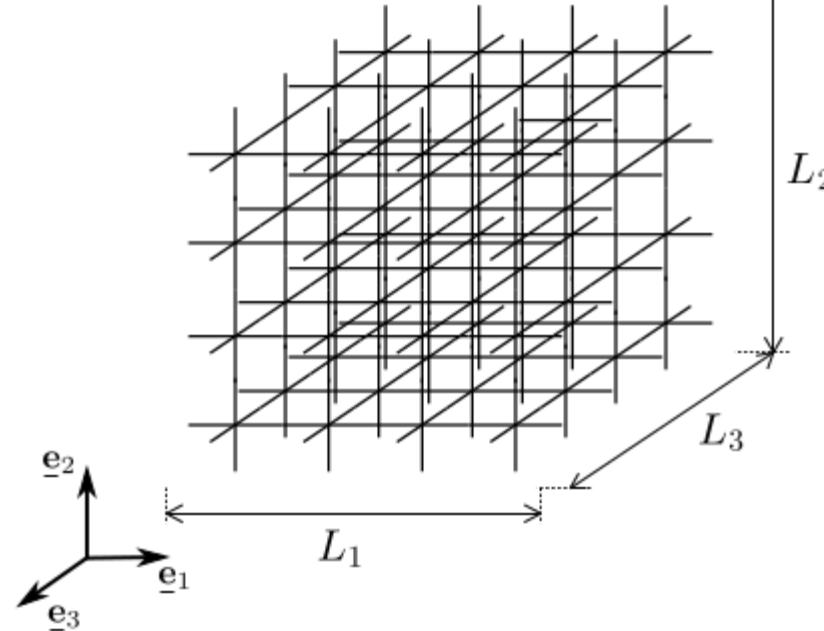
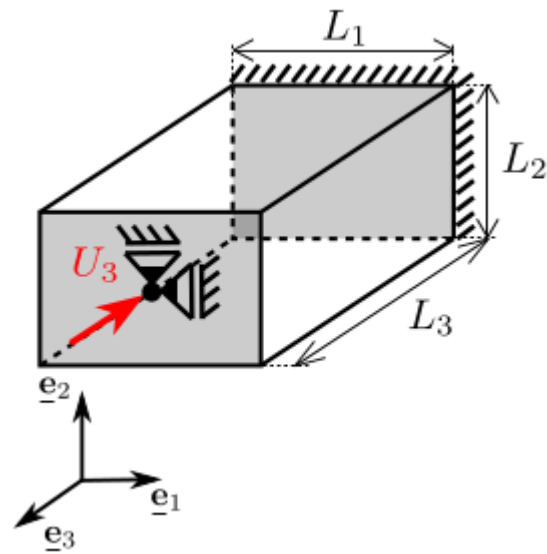


$$\begin{aligned} \check{\underline{\underline{T}}} &= \underline{\underline{A}} : \underline{\underline{E}} + \underline{\underline{C}} : \underline{\underline{\kappa}} \quad \text{with} \quad \underline{\underline{E}} = \underline{\underline{R}}^T \underline{\underline{F}} - \underline{\underline{I}} \\ {}^\kappa \check{\underline{\underline{T}}} &= \underline{\underline{C}}^T : \underline{\underline{E}} + \underline{\underline{B}} : \underline{\underline{\kappa}} \quad \underline{\underline{\kappa}} = \text{axl}(\underline{\underline{R}}^T \frac{\partial \underline{\underline{R}}}{\partial X_k}) \otimes \underline{\underline{E}}_k = -\frac{1}{2} \underline{\underline{\epsilon}} : (\underline{\underline{R}}^T \cdot \text{Grad}_{\underline{\underline{R}}}(\underline{\underline{R}})) \end{aligned}$$

$$[\underline{\underline{K}}_{\text{T};IJ}^{(k)}] = \left. \frac{\partial r_{iI}}{\partial y_{jJ}} \right|_k \approx \left. \frac{r_{iI}([\underline{\underline{y}}_J] + \vartheta[\underline{\underline{e}}_j]) - r_{iI}([\underline{\underline{y}}_J] - \vartheta[\underline{\underline{e}}_j])}{2\vartheta} \right|_k$$

[3] S. Bauer et al., Comput. Methods Appl. Mech. Eng. 199, 2010, 2643–2654, <https://doi.org/10.1016/j.cma.2010.05.002>

Example – Lattice Beam Buckling

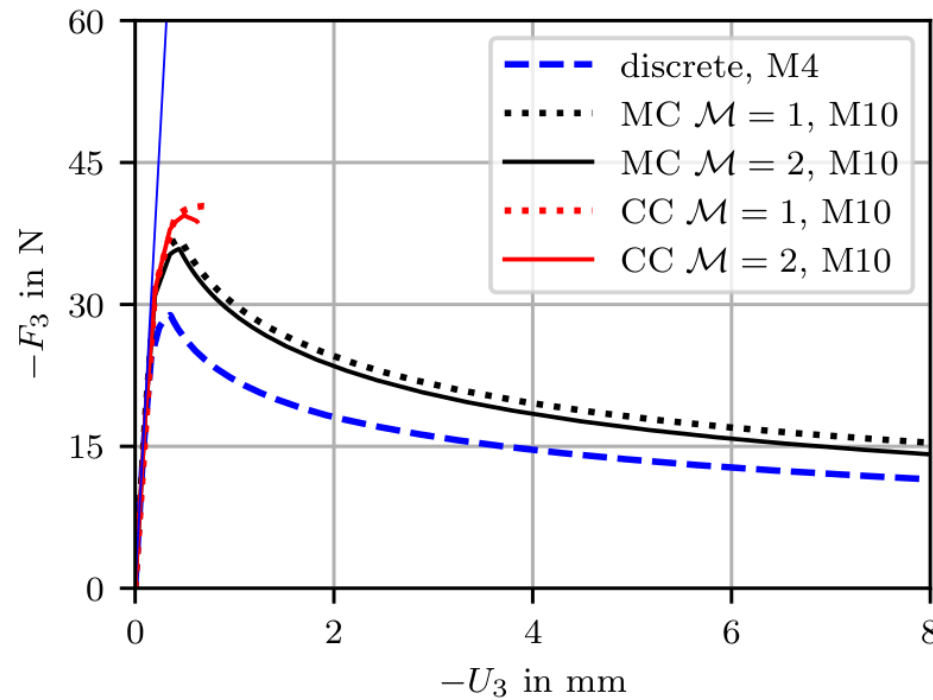


$L_1 = L_2$ in mm	L_3 in mm	l in mm	r in mm	$N_1 \times N_2 \times N_3$ (/)
4.0	80.0	1.0	1./20.0	4x4x80
8.0	160.0	1.0	1./20.0	8x8x160

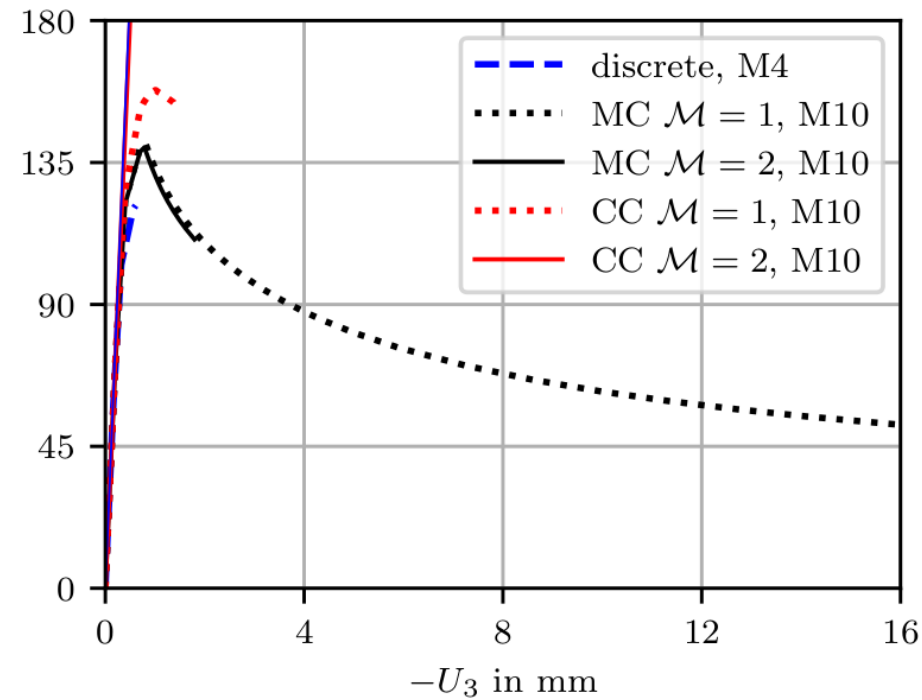
with $E_S = 120000$ in MPa, $\nu_S = 0.3$

Example – Lattice Beam Buckling

4x4x80



8x8x160



- Critical load slightly overestimated
- Unstable post-buckling response captured with MC model

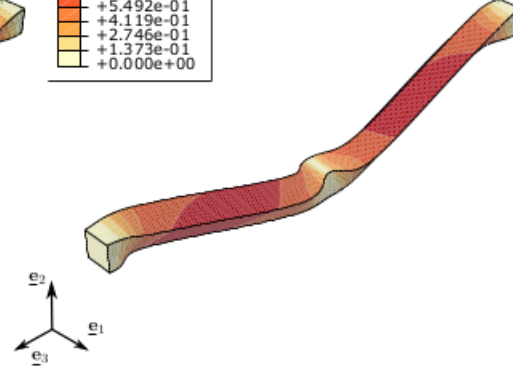
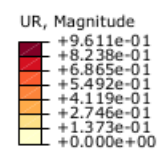
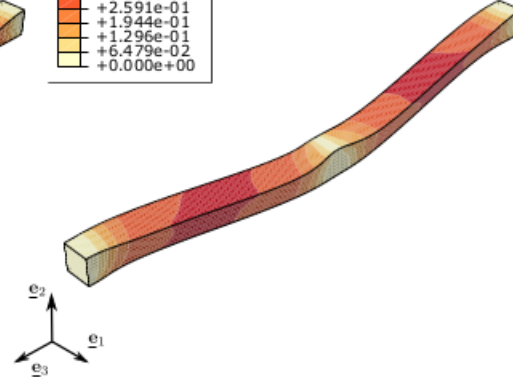
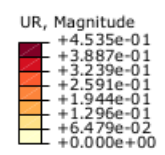
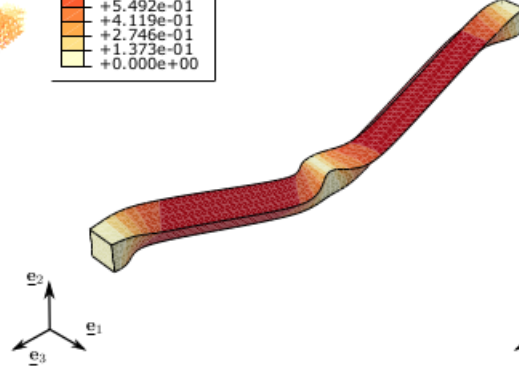
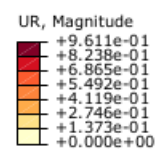
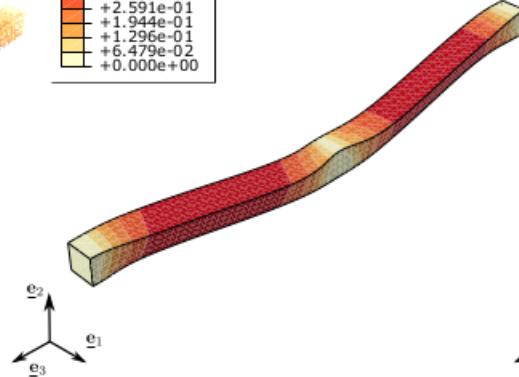
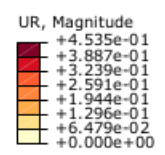
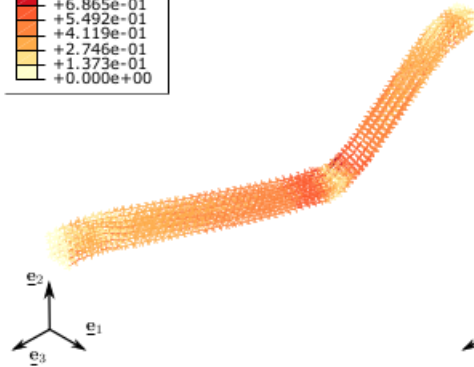
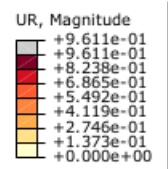
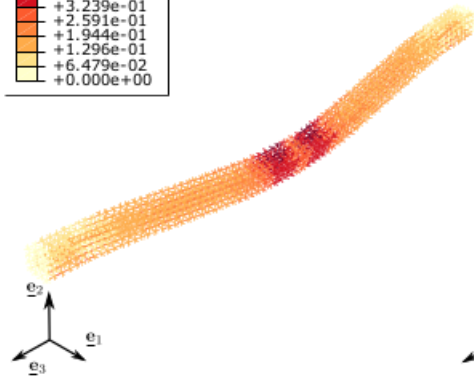
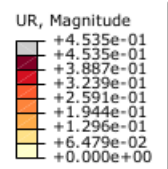
Example – Lattice Beam Buckling

rotation magnitude

discrete

MC $\mathcal{M} = 1$

MC $\mathcal{M} = 2$



- Results for 2 different discretizations
- Good agreement for displacements and rotations
- Model still needs further improvement in terms of computational efficiency

Overview

- Discrete Models
- Continuum Modeling
- **Summary**

Summary

- There exists no “one-fits-all” model
- Model has to be appropriate for the questions asked
 - It has to be **built correctly**
 - It has to be able to **capture the underlying physics**
- Validation against experiments or more sophisticated models necessary
 - Experiments should be mappable to a model.
 - Effect of boundary conditions has to be addressed.
- Interpretation of results always under consideration of the modeling assumptions

Acknowledgement



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BAANG

- **for your attention!**