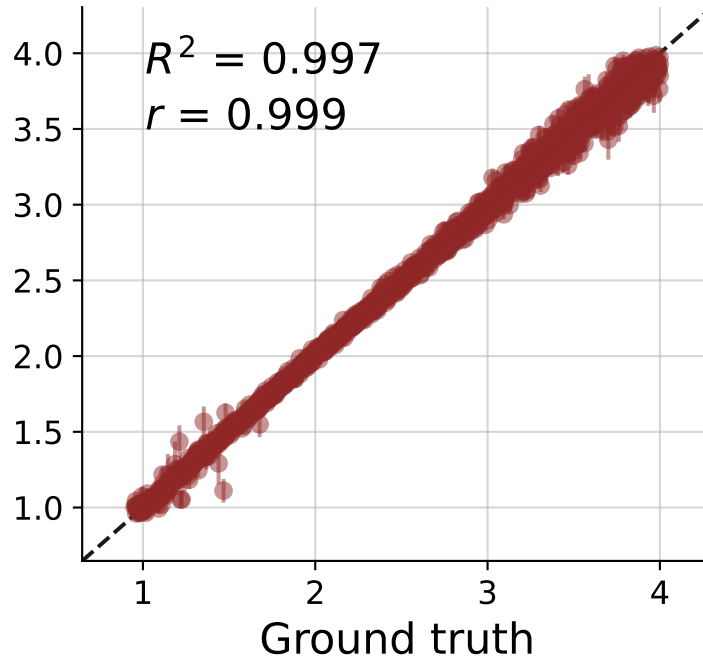
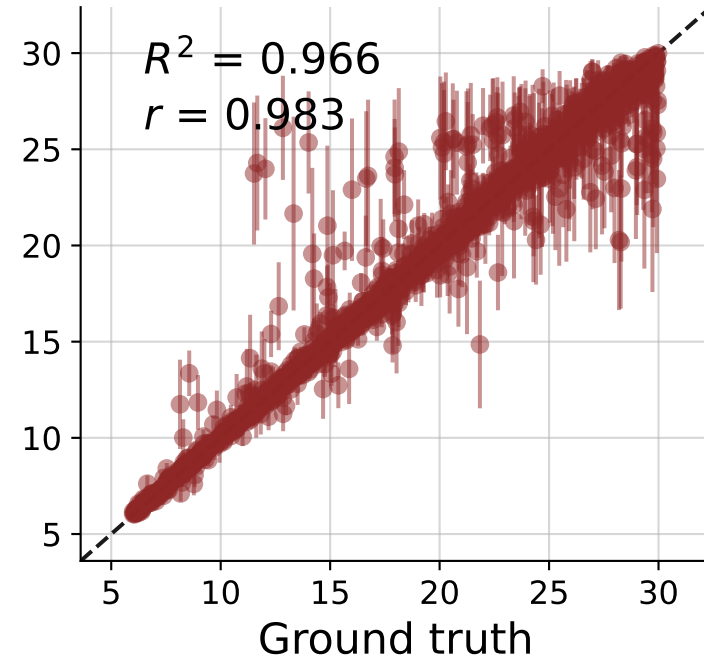


Estimated

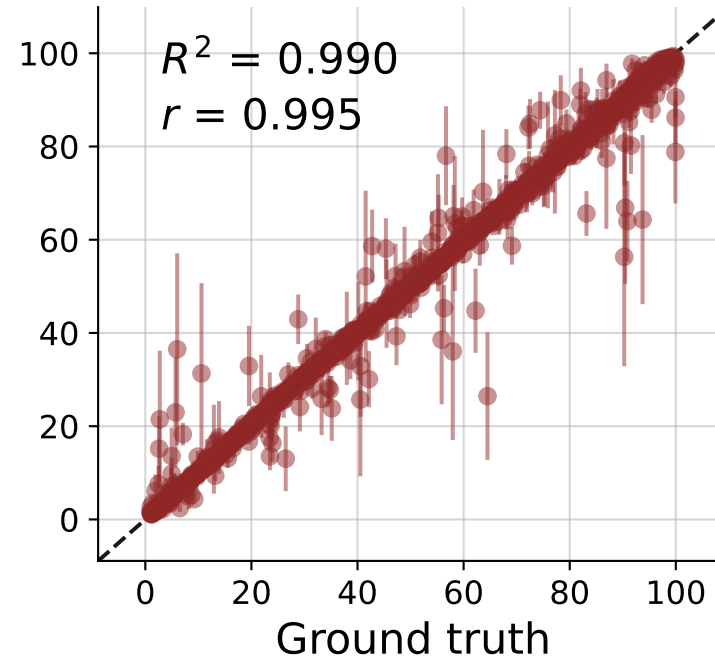
$r_0$



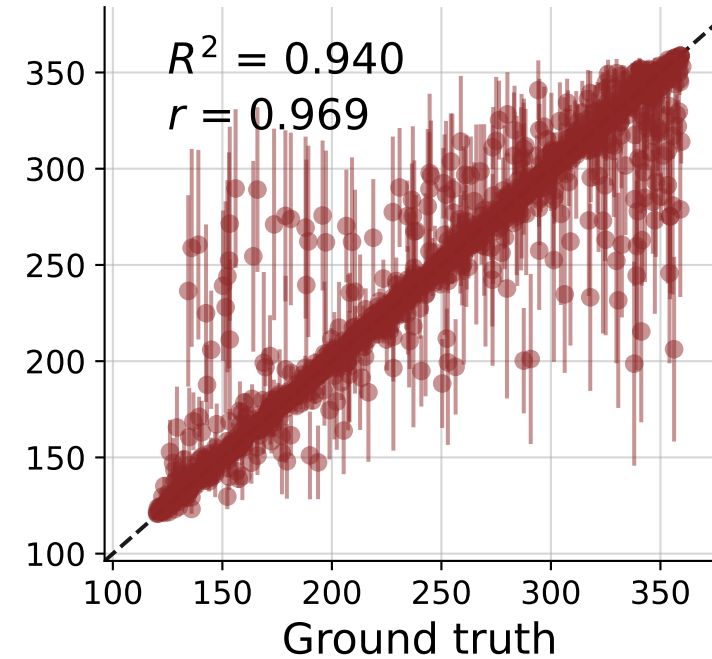
$e_0$



$s_0$



$t_{var}$



$l_0$

