

RULE NORMALIZATION

In this section, we present the normalization function, **NORM**, which converts an original SLEEC DSL rule to a set of normalized SLEEC DSL rules. The original SLEEC DSL rule follows the syntax: **when** $e \wedge p$ **then** $resp$ where e is an event symbol, p is a proposition and $resp$ is a response. A response is one of the following:

- (1) **not** e **within** t
- (2) e **within** t
- (3) e **within** t **otherwise** $resp$
- (4) $resp_1$ **unless** $ptextbf(then resp_2)?$ where the expression $(*)?$ indicates $*$ is optional.

Let an original SLEEC DSL rule " $r_o = \text{when } (e \wedge p) \text{ then response}$ " be given. The result of normalizing r_o is the set of normalized rules $= \{ \text{when } e \text{ then } \bigvee_{cob} \mid \bigvee_{cob} \in \text{NORM}(resp, p) \}$ where the normalization function **NORM** is defined in Fig. 7. Given a response $resp$, **NORM** flattens $resp$ into a set of obligation chains by traversing the

nested structure of $resp$ top-down, and then merges the normalization results bottom-up. Note that in a nested response, a chain of *unless* is left associative (e.g., $A \text{ unless } B \text{ unless } C$ is equivalent as $((A \text{ unless } B) \text{ unless } C)$), and *otherwise* has a higher precedence than *unless* by default (e.g., $A \text{ unless } B \text{ otherwise } C$ is equivalent to $A \text{ unless } (B \text{ otherwise } C)$). **NORM** also records and recursively distributes the triggering condition p to each case. The set of obligation chains returned by **NORM** can then be turned into a set of normalized rules by disturbing the triggering event e to them.

COROLLARY 1. For any original SLEEC rule with n syntax tokens, the size of the normalized SLEEC rule is $O(n)$

Example 20. Consider the original SLEEC rule r_o shown in Fig. 8. Applying the normalization function **NORM** on r_o yields two normalized rules r_{n1} and r_{n2} shown in Fig. 8.

The semantics of the normalized SLEEC DSL is shown in Fig. 9.

$$\text{NORM}(resp, p) = \begin{cases} \{p \Rightarrow e \text{ within } t\} & \text{if } resp = e \text{ within } t \\ \{p \Rightarrow \text{not } e \text{ within } t\} & \text{if } resp = \text{not } e \text{ within } t \\ \text{NORM}(resp_1, p \text{ and not } p') \cup \text{NORM}(resp_2, p \text{ and } p') & \text{if } resp = resp_1 \text{ unless } p' \text{ then } resp_2 \\ \text{NORM}(resp_1, p \text{ and not } p') & \text{if } resp = resp_1 \text{ unless } p' \\ \{ \text{NORM}(e \text{ within } t, p) \text{ otherwise } \bigvee_{cob} \mid \bigvee_{cob} \in \text{NORM}(resp_2, \top) \} & \text{if } r_{op} = e \text{ within } t \text{ otherwise } resp_2 \end{cases}$$

Figure 7: Function **NORM** takes $resp$ and p and returns a set of normalized pseudo-rules.

$$\begin{array}{c} \text{Original SLEEC Rule} \\ r_o = \text{when } e_1 \text{ and } p_1 \text{ then } e_2 \text{ within } t_1 \text{ otherwise } (e_3 \text{ within } t_2 \text{ unless } p_3 \text{ then } e_4 \text{ within } t_3) \\ \hline \text{Normalized SLEEC Rules} \\ r_{n1} = \text{when } e_1 \text{ then } (p_1 \Rightarrow (e_2 \text{ within } t_1)) \text{ otherwise } (\text{not } p_3 \Rightarrow e_3 \text{ within } t_2) \\ r_{n2} = \text{when } e_1 \text{ then } (p_1 \Rightarrow (e_2 \text{ within } t_1)) \text{ otherwise } (p_3 \Rightarrow e_4 \text{ within } t_3) \end{array}$$

Figure 8: An example of SLEEC Rule normalization. Given an original SLEEC rule r_o , applying function **NORM** yields two normalized rules r_{n1} and r_{n2} .

$$\begin{array}{ll} \sigma \models_i p & \text{iff } \mathbb{M}_i(p) \\ \sigma \models_i e \text{ within } t & \text{iff } \exists j \in [i, n]. (e \in \mathcal{E}_j \wedge \delta_j \in [\delta_i, \delta_i + \mathbb{M}_j(t)]) \\ \sigma \models_i^J e \text{ within } t & \text{iff } \delta_j = \delta_i + \mathbb{M}_i(t) \wedge \forall j' \in [i, j] (e \notin \mathcal{E}_{j'}) \\ \sigma \models_i \text{not } e \text{ within } t & \text{iff } \exists j (\sigma \models_i^J e \text{ within } t) \\ \sigma \models_i^J \text{not } e \text{ within } t & \text{iff } \sigma \models e \text{ within } t \wedge \forall j' \in [i, j] (\sigma \models_i^J e \text{ within } t) \\ \sigma \models_i (p \Rightarrow ob) & \text{iff } \sigma \models_i p \Rightarrow \sigma \models_i ob \\ \sigma \models_i^J (p \Rightarrow ob) & \text{iff } \sigma \models_i \text{not } p \wedge \sigma \models_i^J ob \\ \sigma \models_i cob^+ \text{ otherwise } \bigvee_{cob} & \text{iff } \sigma \models_i cob^+ \vee \exists j (\sigma \models_i^J cob^+ \wedge \sigma \models_j \bigvee_{cob}) \\ \sigma \models_i^J cob^+ \text{ otherwise } \bigvee_{cob} & \text{iff } \exists j' \in [i, j] (\sigma \models_i^{J'} cob^+ \wedge \sigma \models_{j'} \bigvee_{cob}) \\ \sigma \models \text{when } e \text{ and } p \text{ then } \bigvee_{cob} & \text{iff } \forall i \in [1, n] ((e \in \mathcal{E}_i \wedge \mathbb{M}_i(p)) \Rightarrow \sigma \models_i \bigvee_{cob}) \\ \sigma \models \text{not } \bigvee_{cob} & \text{iff } \exists j (\sigma \models_j^J \bigvee_{cob}) \\ \sigma \models \text{exists } e \text{ and } p \text{ while } \bigvee_{cob} & \text{iff } \exists i \in [1, n] (e \in \mathcal{E}_i \wedge \mathbb{M}_i(p) \wedge \sigma \models_i \bigvee_{cob}) \\ \sigma \models \text{exists } e \text{ and } p \text{ while not } \bigvee_{cob} & \text{iff } \exists i \in [1, n] (e \in \mathcal{E}_i \wedge \mathbb{M}_i(p) \wedge \sigma \models_i \text{not } \bigvee_{cob}) \end{array}$$

Figure 9: Semantics of normalized SLEEC DSL defined over trace $\sigma = (\mathcal{E}_1, \mathbb{M}_1, \delta_1) \dots (\mathcal{E}_n, \mathbb{M}_n, \delta_n)$.